

$$eq := \text{diff}(u(x), x^2) - 3 \cdot \text{diff}(u(x), x) = 9 \cdot x - 5;$$

$$\frac{d^2}{dx^2} u(x) - 3 \left(\frac{d}{dx} u(x) \right) = 9x - 5 \quad (1)$$

#a

$$sol := \text{dsolve}(eq, u(x));$$

$$u(x) = -\frac{3}{2} x^2 + \frac{1}{3} e^{3x} _C1 + \frac{2}{3} x + _C2 \quad (2)$$

#b

$$f := \text{unapply}(\text{rhs}(sol), x);$$

$$x \rightarrow -\frac{3}{2} x^2 + \frac{1}{3} e^{3x} _C1 + \frac{2}{3} x + _C2$$

$$expr := \text{subs}(_C1 = 0, _C2 = 0, f(x));$$

$$-\frac{3}{2} x^2 + \frac{2}{3} x \quad (4)$$

$$\text{limit}(expr, x = \text{infinity});$$

$$-\infty \quad (5)$$

#c

$$ics := u(0) = 0, D(u)(0) = 1;$$

$$u(0) = 0, D(u)(0) = 1 \quad (6)$$

$$sol := \text{dsolve}(\{eq, ics\}, u(x));$$

$$u(x) = -\frac{3}{2} x^2 + \frac{1}{9} e^{3x} + \frac{2}{3} x - \frac{1}{9} \quad (7)$$

$$expr := \text{rhs}(sol);$$

$$-\frac{3}{2} x^2 + \frac{1}{9} e^{3x} + \frac{2}{3} x - \frac{1}{9} \quad (8)$$

$$\text{evalf}(\text{eval}(expr, x = 2), 6);$$

$$40.0476 \quad (9)$$

#Problem 2

restart :

with(LinearAlgebra) :

$$A := \text{Matrix}([[-2, 0, 0], [0, -1, 1], [0, -1, -1]]);$$

$$\begin{bmatrix} -2 & 0 & 0 \\ 0 & -1 & 1 \\ 0 & -1 & -1 \end{bmatrix} \quad (10)$$

```
#a
Eigenvalues(A);
```

$$\begin{bmatrix} -2 \\ -1 - I \\ -1 + I \end{bmatrix} \quad (11)$$

```
#b
expr := MatrixExponential(t·A);
```

$$\begin{bmatrix} e^{-2t} & 0 & 0 \\ 0 & e^{-t} \cos(t) & e^{-t} \sin(t) \\ 0 & -e^{-t} \sin(t) & e^{-t} \cos(t) \end{bmatrix} \quad (12)$$

```
#c
Map(limit, MatrixExponential(t·A), t=infinity);
```

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad (13)$$

Error, invalid input: VectorCalculus:-limit expects its 1st argument, f, to be of type {algebraic, Vector(algebraic)}, but received Matrix(3, 3, {(1, 1) = exp(-2*t), (1, 2) = 0, (1, 3) = 0, (2, 1) = 0, (2, 2) = exp(-t)*cos(t), (2, 3) = exp(-t)*sin(t), (3, 1) = 0, (3, 2) = -exp(-t)*sin(t), (3, 3) = exp(-t)*cos(t)})

```
#d
f := (x, y, z) → -2·x :
g := (x, y, z) → -y + z :
h := (x, y, z) → -y - z :
```

```
with(linalg) : with(VectorCalculus) :
Jm := Jacobian([f(x, y, z), g(x, y, z), h(x, y, z)], [x, y, z]);
```

$$\begin{bmatrix} -2 & 0 & 0 \\ 0 & -1 & 1 \\ 0 & -1 & -1 \end{bmatrix} \quad (14)$$

```
A := subs([x=0, y=0, z=0], Jm);
```

$$\begin{bmatrix} -2 & 0 & 0 \\ 0 & -1 & 1 \\ 0 & -1 & -1 \end{bmatrix} \quad (15)$$

Eigenvalues(A);

$$\begin{bmatrix} -2 \\ -1 - I \\ -1 + I \end{bmatrix} \quad (16)$$

#Problem 3

restart :

#a

with(linalg) : with(Student[LinearAlgebra]) : with(LinearAlgebra) :

f := x → 3.4 · x · (1 − x);

$$x \rightarrow 3.4 x (1 - x) \quad (17)$$

?vector

psi := [];

$$[] \quad (18)$$

x := 0.4;

$$0.4 \quad (19)$$

for i from 1 to 20 do *x := f(x) : psi(i) := x : print(psi(i))* **od:**

0.5104896

0.8496258922

0.4343899006

0.8353640705

0.4676051968

0.8464319608

0.4419486483

0.8385421378

0.4603233513

0.8446475958

0.4461413181

0.8401374244

0.4566422106

0.8436083471

0.4485732329

0.8410079780

0.4546261004

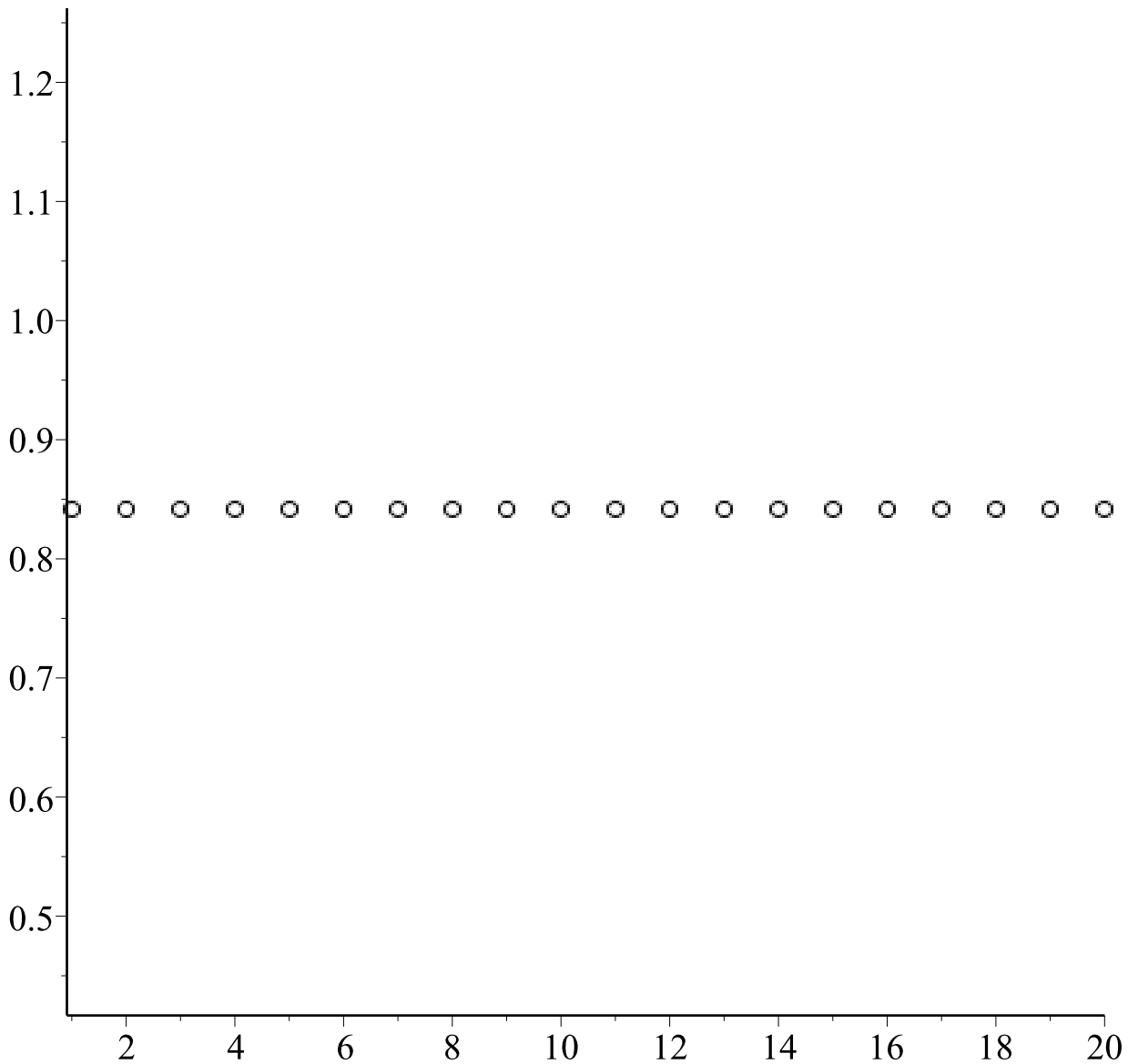
0.8430001112

0.4499931406

0.8414976676

(20)

```
points := [[n, psi(n)]$n = 1..20]; with(plots) : pointplot(points, symbol=circle);
[[1, 0.8414976676], [2, 0.8414976676], [3, 0.8414976676], [4, 0.8414976676], [5,
0.8414976676], [6, 0.8414976676], [7, 0.8414976676], [8, 0.8414976676], [9,
0.8414976676], [10, 0.8414976676], [11, 0.8414976676], [12, 0.8414976676], [13,
0.8414976676], [14, 0.8414976676], [15, 0.8414976676], [16, 0.8414976676], [17,
0.8414976676], [18, 0.8414976676], [19, 0.8414976676], [20, 0.8414976676]]
```



```
#c
with(DETools) :
f := x -> 3.5 * x * (1 - x);
```

$$x \rightarrow 3.5 x (1 - x) \quad (21)$$

```
x := 0.4;
```

$$0.4 \quad (22)$$

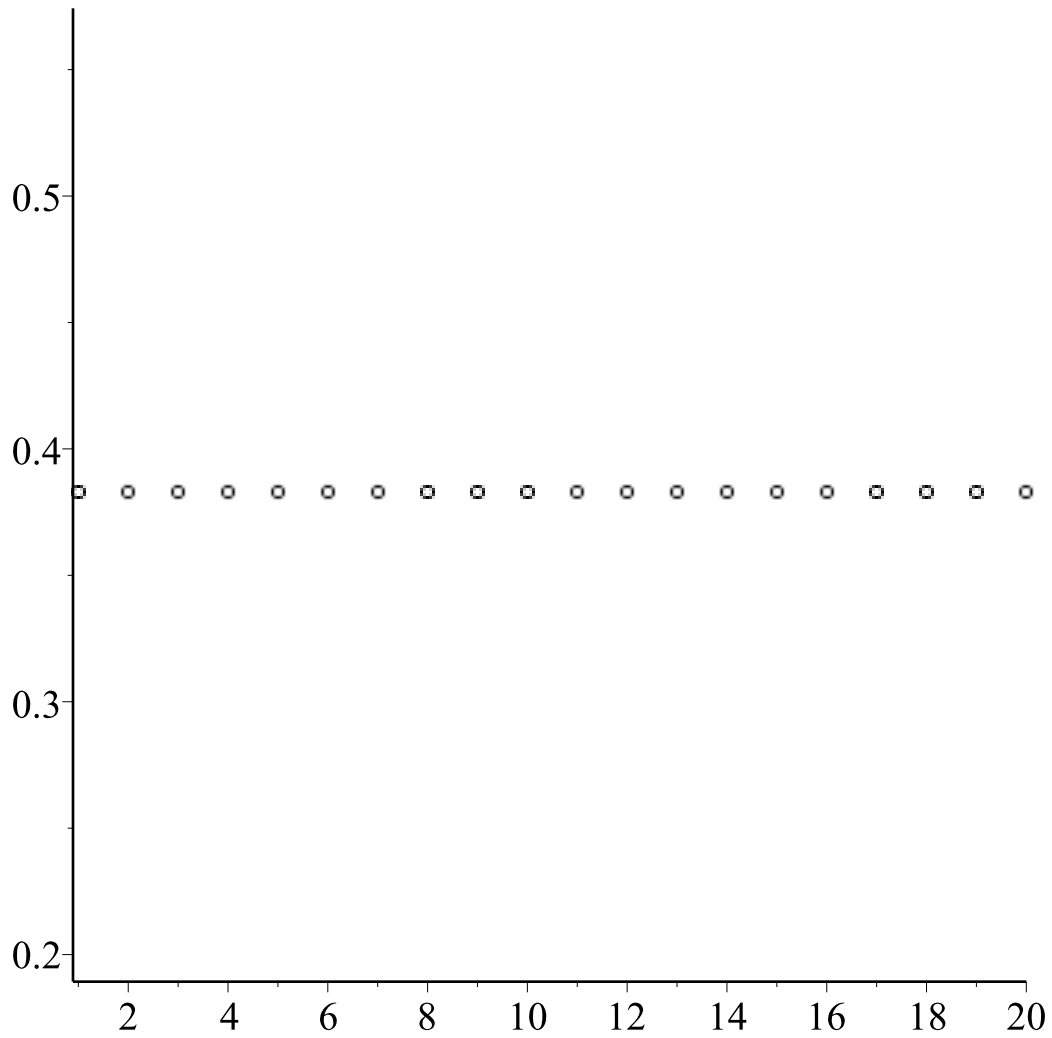
```
for i from 1 to 20 do x := f(x) : psi(i) := x : print(psi(i)) : od;
```

$$0.840$$

0.4704000
0.8719334400
0.3908293067
0.8332861588
0.4862211773
0.8743355044
0.3845552555
0.8283537882
0.4976432643
0.8749805603
0.3828635279
0.8269766644
0.5008019132
0.8749977492
0.3828184083
0.8269396610
0.5008866033
0.8749972490
0.3828197214

(23)

points := [[*n*, psi(*n*)]\$*n* = 1 ..20] : with(*plots*) : *pointplot*(*points*, *symbol* = *circle*);



$$\begin{array}{l} \#e \\ x := 0.4; \end{array} \quad \begin{array}{l} 0.4 \end{array} \quad (24)$$

$$f := x \rightarrow 3.5 \cdot x \cdot (1 - x); \quad \begin{array}{l} x \rightarrow 3.5 \, x \, (1 - x) \end{array} \quad (25)$$

$$\text{psi}(1) := \text{evalf}(x, 7); \quad \begin{array}{l} 0.4 \end{array} \quad (26)$$

$$\text{psi}(2) := \text{evalf}(f(x), 7); \quad \begin{array}{l} 0.840 \end{array} \quad (27)$$

$$\text{psi}(3) := \text{evalf}(f(f(x)), 6); \quad \begin{array}{l} 0.470400 \end{array} \quad (28)$$

$$\text{psi}(4) := \text{evalf}(f(f(f(x))), 6); \quad \begin{array}{l} 0.871933 \end{array} \quad (29)$$

$$\text{psi}(5) := \text{evalf}(f(f(f(f(x)))), 6); \quad \begin{array}{l} 0.390831 \end{array} \quad (30)$$

$$\text{psi}(6) := \text{evalf}(f(f(f(f(f(x))))), 6);$$

0.833288

(31)

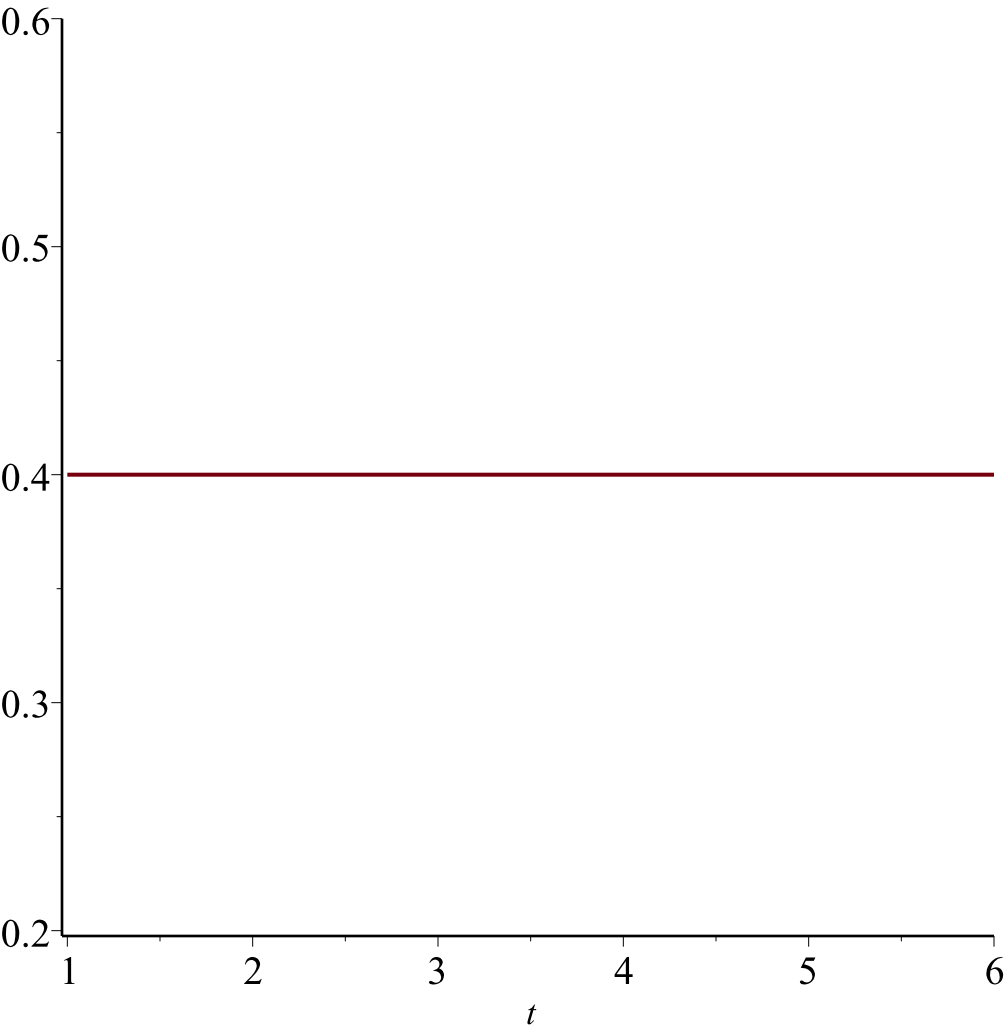
$$\text{psi}(1); \text{psi}(2); \text{psi}(3);$$

0.4

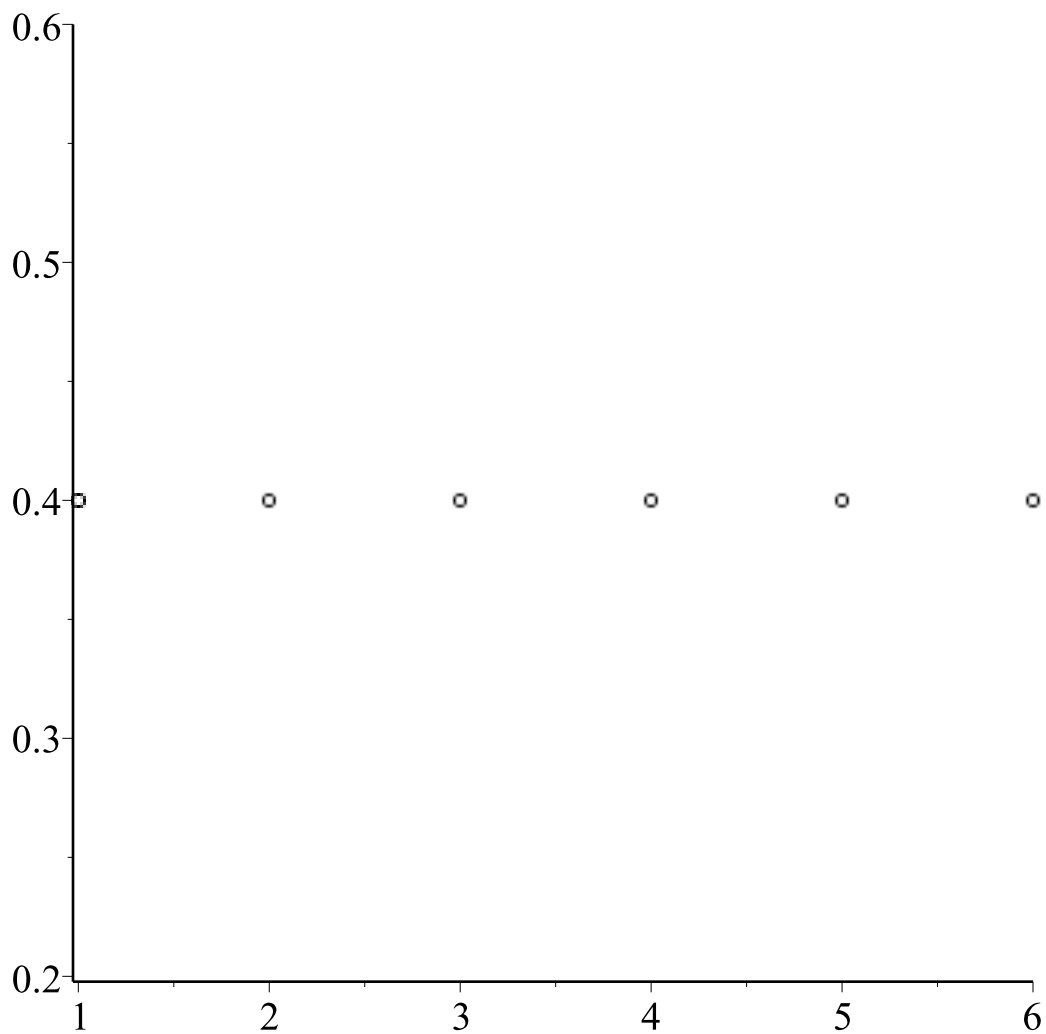
0.840

0.470400

(32)



$$points := [[n, \text{psi}(n)] \$ n = 1 .. 6]; \text{pointplot}(points, symbol = circle);$$



#Problem 4

restart :

#a

a := sqrt(2);

$\sqrt{2}$ (33)

evalf(a² - 2);

0. (34)

#b

b := evalf(sqrt(2), 20);

1.4142135623730950488 (35)

evalf(b² - 2);

-1. 10⁻⁹ (36)

#c

restart :

E1 := sin²(x) + cos²(x);

$E2 := 1;$
 $\sin(x)^2 + \cos(x)^2$
(37)

$x0 := \frac{\text{Pi}}{7};$
 1
(38)

$evalf(eval(E1, x=x0));$
 $\frac{1}{7} \pi$
(39)

$evalf(eval(E2, x=x0));$
 0.9999999999
(40)

$?evalf$
 $1.$
(41)