# Peach - Computational Intelligence for Python

# API Documentation

# July 28, 2011

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# 1 Package peach

*Peach* is a pure-Python package with aims to implement techniques of machine learning and computational intelligence. It contains packages for

- Neural Networks, including, but not limited to, multi-layer perceptrons and self-organizing maps;
- Fuzzy logic and fuzzy inference systems, including Mamdani-type and Sugeno-type controllers;
- Optimization packages, including multidimensional optimization;
- Stochastic Optimizations, including genetic algorithms, simulated annealing, particle swarm optimization;
- A lot more.

Author: José Alexandre Nalon

Version: 0.1.0

#### 1.1 Modules

```
• fuzzy: This package implements fuzzy logic. Consult:
```

(Section 2, p. 4)

-  ${\bf base}:$  This package implements basic definitions for fuzzy logic

(Section 3, p. 5)

- **cmeans**: Fuzzy C-Means

(Section 4, p. 9)

- **control**: This package implements fuzzy controllers, of fuzzy inference systems.

(Section 5, p. 13)

- defuzzy: This package implements defuzzification methods for use with fuzzy controllers.

(Section 6, p. 24)

- **mf**: Membership functions

(Section 7, p. 27)

- **norms**: This package implements operations of fuzzy logic.

(Section 8, p. 43)

• ga: This package implements genetic algorithms. Consult:

(Section 9, p. 48)

- base: Basic Genetic Algorithm (GA)

(Section 10, p. 49)

- **chromosome**: Basic definitions and classes for manipulating chromosomes

(Section 11, p. 57)

crossover: Basic definitions for crossover operations and base classes.

(Section 12, p. 61)

- **fitness**: Basic definitions and base classes for definition of fitness functions for use with genetic algorithms.

(Section 13, p. 67)

mutation: Basic definitions and classes for operating mutation on chromosomes.
 (Section 14, p. 71)

selection: Basic classes and definitions for selection operator.
 (Section 15, p. 74)

• nn: This package implements support for neural networks. Consult:

Modules Package peach

(Section 16, p. 79)

- af: Base activation functions and base class

(Section 17, p. 80)

- base: Basic definitions for layers of neurons.

(Section 18, p. 100)

- **kmeans**: K-Means clustering algorithm

(Section 19, p. 104)

 - lrules: Learning rules for neural networks and base classes for custom learning. (Section 20, p. 108)

- **mem**: Associative memories and Hopfield network model.

(Section 21, p. 123)

nnet: Basic topologies of neural networks.

(Section 22, p. 128)

• optm: This package implements deterministic optimization methods. Consult:

(Section 23, p. 142)

- base: Basic definitons and base class for optimizers

(Section 24, p. 143)

- linear: This package implements basic one variable only optimizers.

(Section 25, p. 148)

multivar: This package implements basic multivariable optimizers, including gradient and Newton searches.

(Section 26, p. 160)

quasinewton: This package implements basic quasi-Newton optimizers. Newton optimizer is
very efficient, except that inverse matrices need to be calculated at each convergence step. These
methods try to estimate the hessian inverse iteratively, thus increasing performance.

(Section 27, p. 175)

- stochastic (Section 28, p. 185)
- pso: Basic Particle Swarm Optimization (PSO)

(Section 29, p. 187)

acc: Functions to update the velocity (ie, accelerate) of the particles in a swarm.
 (Section 30, p. 188)

- base: This package implements the simple continuous version of the particle swarm optimizer. In this implementation, it is possible to specify, besides the objective function and the first estimates, the ranges of search, which will influence the max velocity of the particles, and the population size. Other parameters are available too, please refer to the rest of this documentation for further details.

(Section 31, p. 192)

• sa: This package implements optimization by simulated annealing. Consult:

(Section 32, p. 198)

- base: This package implements two versions of simulated annealing optimization. One works with numeric data, and the other with a codified bit string. This last method can be used in discrete optimization problems.

(Section 33, p. 199)

 neighbor: This module implements a general class to compute neighbors for continuous and binary simulated annealing algorithms. The continuous neighbor functions return an array with a neighbor of a given estimate; the binary neighbor functions return a bitarray object.

(Section 34, p. 210)

# 2 Package peach.fuzzy

This package implements fuzzy logic. Consult:

base Basic definitions, classes and operations in fuzzy logic;

**mf** Membership functions;

defuzzy Defuzzification methods;

**control** Fuzzy controllers (FIS - Fuzzy Inference Systems), for Mamdani- and Sugeno-type controllers and others;

cmeans Fuzzy C-Means clustering algorithm;

## 2.1 Modules

- base: This package implements basic definitions for fuzzy logic (Section 3, p. 5)
- **cmeans**: Fuzzy C-Means (Section 4, p. 9)
- control: This package implements fuzzy controllers, of fuzzy inference systems. (Section 5, p. 13)
- **defuzzy**: This package implements defuzzification methods for use with fuzzy controllers. (Section 6, p. 24)
- mf: Membership functions (Section 7, p. 27)
- norms: This package implements operations of fuzzy logic. (Section 8, p. 43)

# 3 Module peach.fuzzy.base

This package implements basic definitions for fuzzy logic

## 3.1 Variables

Name	Description
doc	Value:
package	Value: 'peach.fuzzy'

# 3.2 Class FuzzySet

```
object —
numpy.ndarray —
peach.fuzzy.base.FuzzySet
```

Array containing fuzzy values for a set.

This class defines the behavior of a fuzzy set. It is an array of values in the range from 0 to 1, and the basic operations of the logic -- and (using the & operator); or (using the | operator); not (using ~ operator) -- can be defined according to a set of norms. The norms can be redefined using the appropriated methods.

To create a FuzzySet, instantiate this class with a sequence as argument, for example:

### 3.2.1 Methods

And operation as defined by Lofti Zadeh.

And operation is the minimum of the two values. Return Value The result of the and operation.

 $-\mathbf{OR}_{--}(x, y)$ 

Or operation as defined by Lofti Zadeh.

Or operation is the maximum of the two values. Return Value

The result of the or operation.

 $-NOT_{--}(x)$ 

Not operation as defined by Lofti Zadeh.

Not operation is the complement to 1 of the given value, that is, 1 - x. Return Value The result of the not operation.

\_\_**new**\_\_( cls, data)

Allocates space for the array.

A fuzzy set is derived from the basic NumPy array, so the appropriate functions and methods are called to allocate the space. In theory, the values for a fuzzy set should be in the range  $0.0 \le x \le 1.0$ , but to increase efficiency, no verification is made. Return Value

A new array object with the fuzzy set definitions. ( $type=a\ new\ object\ with\ type\ S,\ a\ subtype\ of\ T)$ 

Overrides: object.\_new\_\_

 $\_$ **init** $\_$ (self, data=[])

Initializes the object.

Operations are defaulted to Zadeh norms (max, min, 1-x) Overrides: object.\_\_init\_\_

 $\_$ and $\_$ (self, a)

Fuzzy and (&) operation. Overrides: numpy.ndarray.\_and\_

\_\_or\_\_(self, a)

Fuzzy or (1) operation. Overrides: numpy.ndarray.\_or\_

 $\_$ invert $\_$ (self)

Fuzzy not (~) operation. Overrides: numpy.ndarray.\_\_invert\_\_

### $\mathbf{set\_norm}(\mathit{cls}, f)$

Selects a t-norm (and operation)

Use this method to change the behaviour of the and operation. Parameters

f: A function of two parameters which must return the and of the values.

### $\mathbf{set\_conorm}(\mathit{cls}, f)$

Selects a t-conorm (or operation)

Use this method to change the behaviour of the or operation. Parameters

f: A function of two parameters which must return the or of the values.

# $\mathbf{set\_negation}(\mathit{cls}, f)$

Selects a negation (not operation)

Use this method to change the behaviour of the not operation. **Parameters** 

f: A function of one parameter which must return the not of the value.

# Inherited from numpy.ndarray

```
_abs_(), _add_(), _array_(), _array_wrap_(), _contains_(), _copy_(), _deepcopy_(),
__delitem__(), __delslice__(), __div__(), __divmod__(), __eq__(), __float__(), __floatv__(),
__ge__(), __getitem__(), __getslice__(), __gt__(), __hex__(), __iadd__(), __iand__(), __idiv__(),
__ifloordiv__(), __ilshift__(), __imod__(), __imul__(), __index__(), __int__(), __ior__(),
_ipow_(), _irshift_(), _isub_(), _iter_(), _itruediv_(), _ixor_(), _le_(), _len_(),
_long_(), _lshift_(), _lt_(), _mod_(), _mul_(), _ne_(), _neg_(), _nonzero_(),
_oct_(), _pos_(), _pow_(), _radd_(), _radd_(), _rdiv_(), _rdiv_(), _rdivmod_(), _reduce_(),
_repr_(), _rfloordiv_(), _rlshift_(), _rmod_(), _rmul_(), _ror_(), _rpow_(),
__rrshift__(), __rshift__(), __rsub__(), __rtruediv__(), __rxor__(), __setitem__(), __setslice__(),
_setstate_(), _str_(), _sub_(), _truediv_(), _xor_(), all(), any(), argmax(),
argmin(), argsort(), astype(), byteswap(), choose(), clip(), compress(), conj(), con-
jugate(), copy(), cumprod(), cumsum(), diagonal(), dump(), dumps(), fill(), flat-
ten(), getfield(), item(), itemset(), max(), mean(), min(), newbyteorder(), nonzero(),
prod(), ptp(), put(), ravel(), repeat(), reshape(), resize(), round(), searchsorted(),
setfield(), setflags(), sort(), squeeze(), std(), sum(), swapaxes(), take(), tofile(),
tolist(), tostring(), trace(), transpose(), var(), view()
```

# Inherited from object

```
\label{lem:condition} $$ $\operatorname{local}(), \operatorname{local}(), \operatorname{
```

# 3.2.2 Properties

Name	Description							
Inherited from numpy.ndarre	iy							
T, _array_finalize_, _array_interface_, _array_priority_, _array_struct_,								
base, ctypes, data, dtype, flags, flat, imag, itemsize, nbytes, ndim, real,								
shape, size, strides								
Inherited from object								
_class								

# 4 Module peach.fuzzy.cmeans

Fuzzy C-Means

Fuzzy C-Means is a clustering algorithm based no fuzzy logic.

This package implements the fuzzy c-means algorithm for clustering and classification. This algorithm is very simple, yet very efficient. From a training set and an initial condition which gives the membership values of each example in the training set to the clusters, it converges very fastly to crisper sets.

The initial conditions, ie, the starting membership, must follow some rules. Please, refer to any bibliography about the subject to see why. Those rules are: no example might have membership 1 in every class, and the sum of the membership of every component must be equal to 1. This means that the initial condition is a fuzzy partition of the universe.

### 4.1 Variables

Name	Description
doc	Value:
package	Value: 'peach.fuzzy'

# 4.2 Class FuzzyCMeans

object — peach.fuzzy.cmeans.FuzzyCMeans

Fuzzy C-Means convergence.

Use this class to instantiate a fuzzy c-means object. The object must be given a training set and initial conditions. The training set is a list or an array of N-dimensional vectors; the initial conditions are a list of the initial membership values for every vector in the training set -- thus, the length of both lists must be the same. The number of columns in the initial conditions must be the same number of classes. That is, if you are, for example, classifying in C classes, then the initial conditions must have C columns.

There are restrictions in the initial conditions: first, no column can be all zeros or all ones -- if that happened, then the class described by this column is unnecessary; second, the sum of the memberships of every example must be one -- that is, the sum of the membership in every column in each line must be one. This means that the initial condition is a perfect partition of C subsets.

Notice, however, that no checking is done. If your algorithm seems to be behaving strangely,

try to check these conditions.

#### 4.2.1 Methods

### $_{\rm init\_(self,\ training\_set,\ initial\_conditions,\ m=2.0)}$

Initializes the algorithm. Parameters

training\_set: A list or array of vectors containing the data

to be classified. Each of the vectors in this list *must* have the same dimension, or the algorithm won't behave correctly. Notice that each vector can be given as a tuple — internally, everything is converted to arrays.

initial\_conditions: A list or array of vectors containing the

initial membership values associated to each example in the training set. Each column of this array contains the membership assigned to the corresponding class for that vector. Notice that each vector can be given as a tuple — internally, everything is converted to

arrays.

m: This is the aggregation value. The bigger it

is, the smoother will be the classification. Please, consult the bibliography about the subject. m must be bigger than 1. Its default

value is 2

Overrides: object.\_\_init\_\_

### centers(self)

Given the present state of the algorithm, recalculates the centers, that is, the position of the vectors representing each of the classes. Notice that this method modifies the state of the algorithm if any change was made to any parameter. This method receives no arguments and will seldom be used externally. It can be useful if you want to step over the algorithm. *This method has a colateral effect!* If you use it, the c property (see above) will be modified. **Return Value** 

A vector containing, in each line, the position of the centers of the algorithm.

# membership(self)

Given the present state of the algorithm, recalculates the membership of each example on each class. That is, it modifies the initial conditions to represent an evolved state of the algorithm. Notice that this method modifies the state of the algorithm if any change was made to any parameter. **Return Value** 

A vector containing, in each line, the membership of the corresponding example in each class.

# step(self)

This method runs one step of the algorithm. It might be useful to track the changes in the parameters. Return Value

The norm of the change in the membership values of the examples. It can be used to track convergence and as an estimate of the error.

# \_\_call\_\_(self, emax=1e-10, imax=20)

The \_\_call\_\_ interface is used to run the algorithm until convergence is found.

#### **Parameters**

emax: Specifies the maximum error admitted in the execution of the algorithm. It defaults to 1.e-10. The error is tracked according to the norm returned by the step() method.

imax: Specifies the maximum number of iterations admitted in the execution of the algorithm. It defaults to 20.

### Return Value

An array containing, at each line, the vectors representing the centers of the clustered regions.

# Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

# 4.2.2 Properties

Name	Description
С	
mu	

continued on next page

Name	Description
X	
Inherited from object	
class	

# 4.2.3 Instance Variables

Name	Description
m	The fuzzyness coefficient. Must be bigger than
	1, the closest it is to 1, the smoother the mem-
	bership curves will be.

# 5 Module peach.fuzzy.control

This package implements fuzzy controllers, of fuzzy inference systems.

There are two types of controllers implemented in this package. The Mamdani controller is the traditional approach, where input (or controlled) variables are fuzzified, a set of decision rules determine the outcome in a fuzzified way, and a defuzzification method is applied to obtain the numerical result.

The Sugeno controller operates in a similar way, but there is no defuzzification step. Instead, the value of the output (or manipulated) variable is determined by parametric models, and the final result is determined by a weighted average based on the decision rules. This type of controller is also known as parametric controller.

### 5.1 Variables

Name	Description
doc	Value:
DRASTIC_NORMS	Value: DrasticProduct, DrasticSum,
	ZadehNot
EINSTEIN_NORMS	Value: EinsteinProduct, EinsteinSum,
	ZadehNot
MAMDANI_INFERENCE	Value: MamdaniImplication,
	MamdaniAglutination
PROB_INFERENCE	Value: ProbabilisticImplication,
	ProbabilisticAglutination
PROB_NORMS	Value: ProbabilisticAnd,
	ProbabilisticOr, ProbabilisticNot
ZADEH_NORMS	Value: ZadehAnd, ZadehOr, ZadehNot
package	Value: 'peach.fuzzy'
cos	Value: <ufunc 'cos'=""></ufunc>
exp	Value: <ufunc 'exp'=""></ufunc>
pi	Value: 3.14159265359

### 5.2 Class Controller

object — peach.fuzzy.control.Controller

peach.ruzzy.common.commoner

Known Subclasses: peach.fuzzy.control.Mamdani

Basic Mamdani controller

This class implements a standard Mamdani controller. A controller based on fuzzy logic has a somewhat complex behaviour, so it is not explained here. There are numerous references that can be consulted.

It is essential to understand the format that decision rules must follow to obtain correct behaviour of the controller. A rule is a tuple given by:

where mx0 is a membership function of the first input variable, mx1 is a membership function of the second input variable and so on; and my is a membership function or a fuzzy set of the output variable.

Notice that mx's are functions not fuzzy sets! They will be applied to the values of the input variables given in the function call, so, if they are anything different from a membership function, an exception will be raised. Please, consult the examples to see how they must be used.

### 5.2.1 Methods

\_\_init\_\_(self, yrange, rules=[], defuzzy=<function Centroid at 0x9891bfc>, norm=<function ZadehAnd at 0x97d7a3c>, conorm=<function ZadehOr at 0x97d7a74>, negation=<function ZadehNot at 0x97d7aac>, imply=<function MamdaniImplication at 0x97d7bfc>, aglutinate=<function MamdaniAglutination at 0x97d7c34>)

Creates and initialize the controller. Parameters

yrange: The range of the output variable. This must be given as

a set of points belonging to the interval where the output variable is defined, not only the start and end points. It is strongly suggested that the interval is divided in some

(eg.: 100) points equally spaced;

rules: The set of decision rules, as defined above. If none is

given, an empty set of rules is assumed;

defuzzy: The defuzzification method to be used. If none is given,

the Centroid method is used:

norm: The norm (and operation) to be used. Defaults to Zadeh

and.

conorm: The conorm (or operation) to be used. Defaults to

Zadeh or.

negation: The negation (not operation) to be used. Defaults to

Zadeh not.

imply: The implication method to be used. Defaults to

Mamdani implication. aglutinate The aglutination method to be used. Defaults to Mamdani aglutination.

Overrides: object.\_\_init\_\_

### $\mathbf{set\_norm}(self, f)$

Sets the norm (and) to be used.

This method must be used to change the behavior of the and operation of the controller. Parameters

f: The function can be any function that takes two numerical values and return one numerical value, that corresponds to the and result.

# $\mathbf{set\_conorm}(self, f)$

Sets the conorm (or) to be used.

This method must be used to change the behavior of the or operation of the controller. Parameters

f: The function can be any function that takes two numerical values and return one numerical value, that corresponds to the or result.

# $set_negation(self, f)$

Sets the negation (not) to be used.

This method must be used to change the behavior of the **not** operation of the controller. **Parameters** 

f: The function can be any function that takes one numerical value and return one numerical value, that corresponds to the not result.

# $set_implication(self, f)$

Sets the implication to be used.

This method must be used to change the behavior of the implication operation of the controller. **Parameters** 

f: The function can be any function that takes two numerical values and return one numerical value, that corresponds to the implication result.

## $set\_aglutination(self, f)$

Sets the aglutination to be used.

This method must be used to change the behavior of the aglutination operation of the controller. **Parameters** 

f: The function can be any function that takes two numerical values and return one numerical value, that corresponds to the aglutination result.

# add\_rule(self, rule)

Adds a decision rule to the knowledge base.

It is essential to understand the format that decision rules must follow to obtain correct behaviour of the controller. A rule is a tuple must have the following format:

```
((mx0, mx1, \ldots, mxn), my)
```

where mx0 is a membership function of the first input variable, mx1 is a membership function of the second input variable and so on; and my is a membership function or a fuzzy set of the output variable.

Notice that mx's are functions not fuzzy sets! They will be applied to the values of the input variables given in the function call, so, if they are anything different from a membership function, an exception will be raised when the controller is used. Please, consult the examples to see how they must be used.

### add\_table(self, lx1, lx2, table)

Adds a table of decision rules in a two variable controller.

Typically, fuzzy controllers are used to control two variables. In that case, the set of decision rules are given in the form of a table, since that is a more compact format and very easy to visualize. This is a convenience function that allows to add decision rules in the form of a table. Notice that the resulting knowledge base will be the same if this function is used or the add\_rule method is used with every single rule. The second method is in general easier to read in a script, so consider well. Parameters

- 1x1: The set of membership functions to the variable x1, or the lines of the table
- 1x2: The set of membership functions to the variable x2, or the columns of the table
- table: The consequent of the rule where the condition is the line and the column. These can be the membership functions or fuzzy sets.

# eval(self, r, xs)

Evaluates one decision rule in this controller

Takes a rule from the controller and evaluates it given the values of the input variables. **Parameters** 

- r: The rule in the standard format, or an integer number. If r is an integer, then the r th rule in the knowledge base will be evaluated.
- xs: A tuple, a list or an array containing the values of the input variables. The dimension must be coherent with the given rule.

### Return Value

This method evaluates each membership function in the rule for each given value, and and 's the results to obtain the condition. If the condition is zero, a tuple (0.0, None) is returned. Otherwise, the condition is 'imply ed in the membership function of the output variable. A tuple containing (condition, imply) (the membership value associated to the condition and the result of the implication) is returned.

### eval\_all(self, \*xs)

Evaluates all the rules and aglutinates the results.

Given the values of the input variables, evaluate and apply every rule in the knowledge base (with the eval method) and aglutinates the results.

### **Parameters**

xs: A tuple, a list or an array with the values of the input variables.

### Return Value

A fuzzy set containing the result of the evaluation of every rule in the knowledge base, with the results aglutinated.  $\_$ call $\_$ (self, \*xs)

Apply the controller to the set of input variables

Given the values of the input variables, evaluates every decision rule, aglutinates the results and defuzzify it. Returns the response of the controller.

### **Parameters**

xs: A tuple, a list or an array with the values of the input variables.

### Return Value

The response of the controller.

# Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

### 5.2.2 Properties

Name	Description
У	
rules	
Inherited from object	
class	

### 5.3 Class Mamdani

object —
peach.fuzzy.control.Controller —
peach.fuzzy.control.Mamdani

Mandani is an alias to Controller

### 5.3.1 Methods

# Inherited from peach.fuzzy.control.Controller(Section 5.2)

```
_call_(), _init_(), add_rule(), add_table(), eval(), eval_all(), set_aglutination(), set_conorm(), set_implication(), set_negation(), set_norm()
```

## Inherited from object

### 5.3.2 Properties

Name	Description
Inherited from peach.fuzzy.co	ontrol. Controller (Section 5.2)
rules, y	
Inherited from object	
class	

### 5.4 Class Parametric

Known Subclasses: peach.fuzzy.control.Sugeno

Basic Parametric controller

This class implements a standard parametric (or Takagi-Sugeno) controller. A controller based on fuzzy logic has a somewhat complex behaviour, so it is not explained here. There are numerous references that can be consulted.

It is essential to understand the format that decision rules must follow to obtain correct behaviour of the controller. A rule is a tuple given by:

$$((mx0, mx1, ..., mxn), (a0, a1, ..., an))$$

where mx0 is a membership function of the first input variable, mx1 is a membership function of the second input variable and so on; and a0 is the linear parameter, a1 is the parameter associated with the first input variable, a2 is the parameter associated with the second input variable and so on. The response to the rule is calculated by:

$$y = a0 + a1*x1 + a2*x2 + ... + an*xn$$

Notice that mx's are functions not fuzzy sets! They will be applied to the values of the input variables given in the function call, so, if they are anything different from a membership function, an exception will be raised. Please, consult the examples to see how they must be used.

### 5.4.1 Methods

\_\_init\_\_(self, rules=[], norm=<function ProbabilisticAnd at 0x97d7c6c>, conorm=<function ProbabilisticOr at 0x97d7ca4>, negation=<function ProbabilisticNot at 0x97d7cdc>)

Creates and initializes the controller. Parameters

rules: List containing the decision rules for the controller. If

not given, an empty set of decision rules is used.

norm: The norm (and operation) to be used. Defaults to

Probabilistic and.

conorm: The conorm (or operation) to be used. Defaults to

Probabilistic or.

negation: The negation (not operation) to be used. Defaults to

Probabilistic not.

Overrides: object.\_\_init\_\_

# add\_rule(self, rule)

Adds a decision rule to the knowledge base.

It is essential to understand the format that decision rules must follow to obtain correct behaviour of the controller. A rule is a tuple given by:

$$((mx0, mx1, ..., mxn), (a0, a1, ..., an))$$

where mx0 is a membership function of the first input variable, mx1 is a membership function of the second input variable and so on; and a0 is the linear parameter, a1 is the parameter associated with the first input variable, a2 is the parameter associated with the second input variable and so on.

Notice that mx's are *functions* not fuzzy sets! They will be applied to the values of the input variables given in the function call, so, if they are anything different from a membership function, an exception will be raised. Please, consult the examples to see how they must be used.

### eval(self, r, xs)

Evaluates one decision rule in this controller

Takes a rule from the controller and evaluates it given the values of the input variables. The format of the rule is as given, and the response to the rule is calculated by:

$$y = a0 + a1*x1 + a2*x2 + ... + an*xn$$

### **Parameters**

r: The rule in the standard format, or an integer number. If r is an integer, then the r th rule in the knowledge base will be evaluated.

xs: A tuple, a list or an array containing the values of the input variables. The dimension must be coherent with the given rule.

### Return Value

This method evaluates each membership function in the rule for each given value, and and 's the results to obtain the condition. If the condition is zero, a tuple (0.0, 0.0) is returned. Otherwise, the result as given above is calculate, and a tuple containing ''(condition, result) (the membership value associated to the condition and the result of the calculation) is returned.

# $\_$ call $\_$ (self, \*xs)

Apply the controller to the set of input variables

Given the values of the input variables, evaluates every decision rule, and calculates the weighted average of the results. Returns the response of the controller. **Parameters** 

xs: A tuple, a list or an array with the values of the input variables.

# Return Value

The response of the controller.

### Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

### 5.4.2 Properties

Name	Description
rules	
Inherited from object	
class	

# 5.5 Class Sugeno

object —
peach.fuzzy.control.Parametric —
peach.fuzzy.control.Sugeno

Sugeno is an alias to Parametric

### 5.5.1 Methods

 $Inherited\ from\ peach.fuzzy.control.Parametric(Section\ 5.4)$ 

# Inherited from object

### 5.5.2 Properties

Name	Description
Inherited from peach.fuzzy.co	ontrol.Parametric (Section 5.4)
rules	
Inherited from object	
class	

# 6 Module peach.fuzzy.defuzzy

This package implements defuzzification methods for use with fuzzy controllers.

Defuzzification methods take a set of numerical values, their corresponding fuzzy membership values and calculate a defuzzified value for them. They're implemented as functions, not as classes. So, to implement your own, use the directions below.

These methods are implemented as functions with the signature (mf, y), where mf is the fuzzy set, and y is an array of values. That is, mf is a fuzzy set containing the membership values of each one in the y array, in the respective order. Both arrays should have the same dimensions, or else the methods won't work.

See the example:

```
>>> import numpy
>>> from peach import *
>>> y = numpy.linspace(0., 5., 100)
>>> m_y = Triangle(1., 2., 3.)
>>> Centroid(m_y(y), y)
2.0001030715316435
```

The methods defined here are the most commonly used.

#### 6.1 Functions

### Centroid (mf, y)

Center of gravity method.

The center of gravity is calculate using the standard formula found in any calculus book. The integrals are calculated using the trapezoid method.

#### **Parameters**

mf: Fuzzy set containing the membership values of the elements in the vector given in sequence

y: Array of domain values of the defuzzified variable.

## Return Value

The center of gravity of the fuzzy set.

# $\mathbf{Bisector}(mf, y)$

### Bisection method

The bisection method finds a coordinate y in domain that divides the fuzzy set in two subsets with the same area. Integrals are calculated using the trapezoid method. This method only works if the values in y are equally spaced, otherwise, the method will fail. **Parameters** 

- mf: Fuzzy set containing the membership values of the elements in the vector given in sequence
- y: Array of domain values of the defuzzified variable.

### Return Value

Defuzzified value by the bisection method.

# SmallestOfMaxima(mf, y)

Smallest of maxima method.

This method finds all the points in the domain which have maximum membership value in the fuzzy set, and returns the smallest of them.

### **Parameters**

- mf: Fuzzy set containing the membership values of the elements in the vector given in sequence
- y: Array of domain values of the defuzzified variable.

### Return Value

Defuzzified value by the smallest of maxima method.

# LargestOfMaxima(mf, y)

Largest of maxima method.

This method finds all the points in the domain which have maximum membership value in the fuzzy set, and returns the largest of them.

### **Parameters**

- mf: Fuzzy set containing the membership values of the elements in the vector given in sequence
- y: Array of domain values of the defuzzified variable.

## Return Value

Defuzzified value by the largest of maxima method.

# MeanOfMaxima(mf, y)

Mean of maxima method.

This method finds the smallest and largest of maxima, and returns their average. **Parameters** 

- mf: Fuzzy set containing the membership values of the elements in the vector given in sequence
- y: Array of domain values of the defuzzified variable.

# Return Value

Defuzzified value by the of maxima method.

### 6.2 Variables

	Name	Description
	doc	Value:
Ī	package	Value: 'peach.fuzzy'

# 7 Module peach.fuzzy.mf

# Membership functions

Membership functions are actually subclasses of a main class called Membership, see below. Instantiate a class to generate a function, optional arguments can be specified to configure the function as needed. For example, to create a triangle function starting at 0, with peak in 3, and ending in 4, use:

```
mu = Triangle(0, 3, 4)
```

Please notice that the return value is a *function*. To use it, apply it as a normal function. For example, the function above, applied to the value 1.5 should return 0.5:

```
>>> print mu(1.5)
0.5
```

### 7.1 Functions

### Saw(interval, n)

Splits an interval into n triangle functions.

Given an interval in any domain, this function will create n triangle functions of the same size equally spaced in the interval. It is very useful to create membership functions for controllers. The command below will create 3 triangle functions equally spaced in the interval (0, 4):

```
mf1, mf2, mf3 = Saw((0, 4), 3)
```

This is the same as the following commands:

```
mf1 = Triangle(0, 1, 2)
mf2 = Triangle(1, 2, 3)
mf3 = Triangle(2, 3, 4)
```

### **Parameters**

n: The number of functions in which the interval must be split.

### Return Value

A list of triangle membership functions, in order.

# FlatSaw(interval, n)

Splits an interval into a decreasing ramp, n-2 triangle functions and an increasing ramp.

Given an interval in any domain, this function will create a decreasing ramp in the start of the interval, n-2 triangle functions of the same size equally spaced in the interval, and a increasing ramp in the end of the interval. It is very useful to create membership functions for controllers. The command below will create a decreasing ramp, a triangle function and an increasing ramp equally spaced in the interval (0, 2):

```
mf1, mf2, mf3 = FlatSaw((0, 2), 3)
```

This is the same as the following commands:

```
mf1 = DecreasingRamp(0, 1)
```

mf2 = Triangle(0, 1, 2)

mf3 = Increasingramp(1, 2)

### **Parameters**

interval: A tuple containing the start and the end of the interval,

in the format (start, end);

n: The number of functions in which the interval must be

split.

### Return Value

A list of corresponding functions, in order.

### 7.2 Variables

Name	Description
doc	Value:
package	Value: 'peach.fuzzy'

### 7.3 Class Membership

object —

# peach.fuzzy.mf.Membership

Known Subclasses: peach.fuzzy.mf.Bell, peach.fuzzy.mf.DecreasingRamp, peach.fuzzy.mf.DecreasingSign peach.fuzzy.mf.Gaussian, peach.fuzzy.mf.IncreasingRamp, peach.fuzzy.mf.IncreasingSigmoid,

peach.fuzzy.mf. Raised Cosine, peach.fuzzy.mf. Smf, peach.fuzzy.mf. Trapezoid, peach.fuzzy.mf. Triangle, peach.fuzzy.mf. Zmf

Base class of all membership functions.

This class is used as base of the implemented membership functions, and can also be used to transform a regular function in a membership function that can be used with the fuzzy logic package.

To create a membership function from a regular function f, use:

```
mf = Membership(f)
```

A function this converted can be used with vectors and matrices and always return a FuzzySet object. Notice that the value range is not verified so that it fits in the range [0, 1]. It is responsibility of the programmer to warrant that.

To subclass Membership, just use it as a base class. It is suggested that the <code>\_\_init\_\_</code> method of the derived class allows configuration, and the <code>\_\_call\_\_</code> method is used to apply the function over its arguments.

#### 7.3.1 Methods

 $\_$ init $\_$ (self, f)

Builds a membership function from a regular function **Parameters** 

f: Function to be transformed into a membership function. It must be given, and it must be a FunctionType object, otherwise, a ValueError is raised.

Overrides: object.\_\_init\_\_

 $\_$ call $\_$ (self, x)

Maps the function on a vector **Parameters** 

x: A value, vector or matrix over which the function is evaluated.

#### Return Value

A FuzzySet object containing the evaluation of the function over each of the components of the input.

# Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

### 7.3.2 Properties

Name	Description
Inherited from object	
class	

## 7.4 Class IncreasingRamp

Increasing ramp.

Given two points, x0 and x1, with x0 < x1, creates a function which returns:

0, if 
$$x \le x0$$
;  
 $(x - x0) / (x1 - x0)$ , if  $x0 < x \le x1$ ;  
1, if  $x > x1$ .

#### 7.4.1 Methods

$$\_$$
call $\_$ (self,  $x$ )

Maps the function on a vector **Parameters** 

x: A value, vector or matrix over which the function is evaluated.

### Return Value

A FuzzySet object containing the evaluation of the function over each of the components of the input.

Overrides: peach.fuzzy.mf.Membership.\_\_call\_\_ extit(inherited documentation)

# Inherited from object

## 7.4.2 Properties

Name	Description
Inherited from object	
class	

# 7.5 Class DecreasingRamp

Decreasing ramp.

Given two points, x0 and x1, with x0 < x1, creates a function which returns:

1, if 
$$x \le x0$$
;  
 $(x1 - x) / (x1 - x0)$ , if  $x0 < x \le x1$ ;  
0, if  $x > x1$ .

### 7.5.1 Methods

Initializes the function. Parameters
x0: Start of the ramp;
x1: End of the ramp.

Overrides: object.\_\_init\_\_

$$\_$$
call $\_$ (self,  $x$ )

Maps the function on a vector **Parameters** 

x: A value, vector or matrix over which the function is evaluated.

## Return Value

A FuzzySet object containing the evaluation of the function over each of the components of the input.

Overrides: peach.fuzzy.mf.Membership.\_\_call\_\_ extit(inherited documentation)

## Inherited from object

#### 7.5.2 Properties

Name	Description
Inherited from object	
_class	

# 7.6 Class Triangle

Triangle function.

Given three points, x0, x1 and x2, with x0 < x1 < x2, creates a function which returns:

0, if 
$$x \le x0$$
 or  $x > x2$ ;  
 $(x - x0) / (x1 - x0)$ , if  $x0 < x <= x1$ ;  
 $(x2 - x) / (x2 - x1)$ , if  $x1 < x <= x2$ .

## 7.6.1 Methods

 $\_$ **init** $\_$ (self, x0, x1, x2)

Initializes the function. Parameters

x0: Start of the triangle;

x1: Peak of the triangle;

x2: End of triangle.

Overrides: object.\_\_init\_\_

 $\_$ call $\_$ (self, x)

Maps the function on a vector **Parameters** 

x: A value, vector or matrix over which the function is evaluated.

### Return Value

A FuzzySet object containing the evaluation of the function over each of the components of the input.

Overrides: peach.fuzzy.mf.Membership.\_call\_ extit(inherited documentation)

# Inherited from object

#### 7.6.2 Properties

Name	Description
Inherited from object	
class	

## 7.7 Class Trapezoid

object —
peach.fuzzy.mf.Membership —
peach.fuzzy.mf.Trapezoid

Trapezoid function.

Given four points, x0, x1, x2 and x3, with x0 < x1 < x2 < x3, creates a function which returns:

0, if 
$$x \le x0$$
 or  $x > x3$ ;  
 $(x - x0)/(x1 - x0)$ , if  $x0 \le x < x1$ ;  
1, if  $x1 \le x < x2$ ;  
 $(x3 - x)/(x3 - x2)$ , if  $x2 \le x < x3$ .

#### 7.7.1 Methods

 $_{\text{init}}_{\text{--}}(self, x0, x1, x2, x3)$ 

Initializes the function. Parameters

x0: Start of the trapezoid;

x1: First peak of the trapezoid;

x2: Last peak of the trapezoid;

x3: End of trapezoid.

Overrides: object.\_\_init\_\_

 $\_$ call $\_$ (self, x)

Maps the function on a vector **Parameters** 

x: A value, vector or matrix over which the function is evaluated.

## Return Value

A FuzzySet object containing the evaluation of the function over each of the components of the input.

Overrides: peach.fuzzy.mf.Membership.\_call\_ extit(inherited documentation)

### Inherited from object

### 7.7.2 Properties

Name	Description
Inherited from object	
class	

### 7.8 Class Gaussian



Gaussian function.

Given the center and the width, creates a function which returns a gaussian fit to these parameters, that is:

$$\exp(-(x - x0)**2)/a$$

#### 7.8.1 Methods

 $\_init_{--}(self, x\theta = 0.0, a = 1.0)$ 

Initializes the function. Parameters

x0: Center of the gaussian. Default value 0.0;

a: Width of the gaussian. Default value 1.0.

Overrides: object.\_init\_\_

 $\_$ call $\_$ (self, x)

Maps the function on a vector **Parameters** 

x: A value, vector or matrix over which the function is evaluated.

### Return Value

A FuzzySet object containing the evaluation of the function over each of the components of the input.

Overrides: peach.fuzzy.mf.Membership.\_\_call\_\_ extit(inherited documentation)

# Inherited from object

#### 7.8.2 Properties

Name	Description
Inherited from object	

continued on next page

Name	Description
class	

## 7.9 Class IncreasingSigmoid

Increasing Sigmoid function.

Given the center and the slope, creates an increasing sigmoidal function. It goes to 0 as x approaches to -infinity, and goes to 1 as x approaches infinity, that is:

$$1 / (1 + \exp(-a*(x - x0)))$$

#### 7.9.1 Methods

$$\_init_{-}(self, x\theta=0.0, a=1.0)$$

Initializes the function. Parameters

x0: Center of the sigmoid. Default value 0.0. The function evaluates to 0.5 if x = x0;

a: Slope of the sigmoid. Default value 1.0.

Overrides: object.\_\_init\_\_

$$\_$$
call $\_$ (self,  $x$ )

Maps the function on a vector **Parameters** 

x: A value, vector or matrix over which the function is evaluated.

## Return Value

A FuzzySet object containing the evaluation of the function over each of the components of the input.

Overrides: peach.fuzzy.mf.Membership.\_call\_ extit(inherited documentation)

### Inherited from object

#### 7.9.2 Properties

Name	Description
Inherited from object	
class	

## 7.10 Class DecreasingSigmoid

Decreasing Sigmoid function.

Given the center and the slope, creates an decreasing sigmoidal function. It goes to 1 as x approaches to -infinity, and goes to 0 as x approaches infinity, that is:

$$1 / (1 + \exp(a*(x - x0)))$$

### 7.10.1 Methods

 $_{init_{--}}(self, x\theta=0.0, a=1.0)$ 

Initializes the function. Parameters

x0: Center of the sigmoid. Default value 0.0. The function evaluates to 0.5 if x = x0;

a: Slope of the sigmoid. Default value 1.0.

Overrides: object.\_\_init\_\_

$$\_$$
call $\_$ (self,  $x$ )

Maps the function on a vector **Parameters** 

x: A value, vector or matrix over which the function is evaluated.

### Return Value

A FuzzySet object containing the evaluation of the function over each of the components of the input.

Overrides: peach.fuzzy.mf.Membership.\_call\_ extit(inherited documentation)

## Inherited from object

#### 7.10.2 Properties

Name	Description
Inherited from object	
class	

### 7.11 Class RaisedCosine

Raised Cosine function.

Given the center and the frequency, creates a function that is a period of a raised cosine, that is:

0, if 
$$x \le xm - pi/w$$
 or  $x > xm + pi/w$ ;  
0.5 + 0.5 \*  $cos(w*(x - xm))$ , if  $xm - pi/w \le x < xm + pi/w$ ;

#### **7.11.1** Methods

\_\_init\_\_(self, xm=0.0, w=1.0)

Initializes the function. Parameters

xm: Center of the cosine. Default value 0.0. The function evaluates to 1 if x = xm;

w: Frequency of the cosine. Default value 1.0.

Overrides: object.\_\_init\_\_

 $\_$ call $\_$ (self, x)

Maps the function on a vector **Parameters** 

x: A value, vector or matrix over which the function is evaluated.

## Return Value

A FuzzySet object containing the evaluation of the function over each of the components of the input.

Overrides: peach.fuzzy.mf.Membership.\_\_call\_\_ extit(inherited documentation)

## Inherited from object

#### 7.11.2 Properties

Name	Description
Inherited from object	
_class_	

### 7.12 Class Bell

Generalized Bell function.

A generalized bell is a symmetric function with its peak in its center and fast decreasing to 0 outside a given interval, that is:

$$1 / (1 + ((x - x0)/a)**(2*b))$$

#### **7.12.1** Methods

 $_{init}_{-}(self, x\theta=0.0, a=1.0, b=1.0)$ 

Initializes the function. Parameters

- x0: Center of the bell. Default value 0.0. The function evaluates to 1 if x = xm;
- a: Size of the interval. Default value 1.0. A generalized bell evaluates to 0.5 if x = -a or x = a;
- b: Measure of *flatness* of the bell. The bigger the value of b, the flatter is the resulting function. Default value 1.0.

Overrides: object.\_\_init\_\_

 $\_$ call $\_$ (self, x)

Maps the function on a vector **Parameters** 

x: A value, vector or matrix over which the function is evaluated.

### Return Value

A FuzzySet object containing the evaluation of the function over each of the components of the input.

Overrides: peach.fuzzy.mf.Membership.\_\_call\_\_ extit(inherited documentation)

# Inherited from object

\_\_delattr\_\_(), \_\_format\_\_(), \_\_getattribute\_\_(), \_\_hash\_\_(), \_\_new\_\_(), \_\_reduce\_\_(), \_\_reduce\_ex\_\_(), \_\_repr\_\_(), \_\_setattr\_\_(), \_\_sizeof\_\_(), \_\_str\_\_(), \_\_subclasshook\_\_()

## 7.12.2 Properties

Name	Description
Inherited from object	
class	

### 7.13 Class Smf

Increasing smooth curve with 0 and 1 minimum and maximum values outside a given range.

#### **7.13.1** Methods

 $\_$ **init** $\_$ (self, x0, x1)

Initializes the function. Parameters

x0: Start of the curve. For every value below this, the function returns 0;

x1: End of the curve. For every value above this, the function returns 1;

Overrides: object.\_\_init\_\_

 $\_$ call $\_$ (self, x)

Maps the function on a vector **Parameters** 

x: A value, vector or matrix over which the function is evaluated.

## Return Value

A FuzzySet object containing the evaluation of the function over each of the components of the input.

Overrides: peach.fuzzy.mf.Membership.\_call\_ extit(inherited documentation)

### Inherited from object

### 7.13.2 Properties

Name	Description
Inherited from object	
class	

### 7.14 Class Zmf

Decreasing smooth curve with 0 and 1 minimum and maximum values outside a given range.

#### **7.14.1** Methods

 $\_$ **init** $\_$ (self, x0, x1)

Initializes the function. Parameters

x0: Start of the curve. For every value below this, the function returns 1;

**x1:** End of the curve. For every value above this, the function returns 0;

Overrides: object.\_\_init\_\_

 $\_$ call $\_$ (self, x)

Maps the function on a vector **Parameters** 

x: A value, vector or matrix over which the function is evaluated.

## Return Value

A FuzzySet object containing the evaluation of the function over each of the components of the input.

Overrides: peach.fuzzy.mf.Membership.\_call\_ extit(inherited documentation)

### Inherited from object

### 7.14.2 Properties

Name	Description
Inherited from object	
class	

# 8 Module peach.fuzzy.norms

This package implements operations of fuzzy logic.

Basic operations are and (&), or (|) and not (~). Those are implemented as functions of, respectively, two, two and one values. The and is the t-norm of the fuzzy logic, and it is a function that takes two values and returns the result of the and operation. The or is a function that takes two values and returns the result of the or operation. the not is a function that takes one value and returns the result of the not operation. To implement your own operations there is no need to subclass -- just create the functions and use them where appropriate.

Also, implication and aglutination functions are defined here. Implication is the result of the generalized modus ponens used in fuzzy inference systems. Aglutination is the generalization from two different conclusions used in fuzzy inference systems. Both are implemented as functions that take two values and return the result of the operation. As above, to implement your own operations, there is no need to subclass -- just create the functions and use them where appropriate.

The functions here are provided as convenience.

#### 8.1 Functions

## ZadehAnd(x, y)

And operation as defined by Lofti Zadeh.

And operation is the minimum of the two values. **Return Value** The result of the and operation.

## ZadehOr(x, y)

Or operation as defined by Lofti Zadeh.

Or operation is the maximum of the two values. Return Value
The result of the or operation.

## ZadehNot(x)

Not operation as defined by Lofti Zadeh.

Not operation is the complement to 1 of the given value, that is, 1 - x.

### Return Value

The result of the not operation.

## ZadehImplication(x, y)

Implication operation as defined by Zadeh. Return Value
The result of the implication.

## $\mathbf{DrasticProduct}(x, y)$

Drastic product that can be used as and operation Return Value

The result of the and operation

## DrasticSum(x, y)

Drastic sum that can be used as or operation Return Value

The result of the or operation

## EinsteinProduct(x, y)

Einstein product that can be used as and operation. **Return Value**The result of the and operation.

## EinsteinSum(x, y)

Einstein sum that can be used as or operation. Return Value

The result of the or operation.

## MamdaniImplication(x, y)

Implication operation as defined by Mamdani.

Implication is the minimum of the two values. Return Value
The result of the implication.

## MamdaniAglutination(x, y)

Aglutination as defined by Mamdani.

Aglutination is the maximum of the two values. **Return Value** The result of the aglutination.

## $\mathbf{ProbabilisticAnd}(x, y)$

And operation as a probabilistic operation.

And operation is the product of the two values. **Return Value** The result of the and operation.

## ProbabilisticOr(x, y)

Or operation as a probabilistic operation.

Or operation is given as the probability of the intersection of two events, that is, x + y - xy. Return Value

The result of the or operation.

### ProbabilisticNot(x)

Not operation as a probabilistic operation.

Not operation is the complement to 1 of the given value, that is, 1 - x.

#### Return Value

The result of the not operation.

# ProbabilisticImplication(x, y)

Implication as a probabilistic operation.

Implication is the product of the two values. Return Value

The result of the and implication.

## ProbabilisticAglutination(x, y)

Implication as a probabilistic operation.

Implication is given as the probability of the intersection of two events, that is, x + y - xy. Return Value

The result of the and algutination.

## DienesRescherImplication(x, y)

Natural implication as in truth table, defined by Dienes-Rescher  $\,$  Return  $\,$  Value

The result of the implication.

# LukasiewiczImplication(x, y)

Implication of the Lukasiewicz three-valued logic. Return Value The result of the implication.

## GodelImplication(x, y)

Implication as defined by Godel. Return Value
The result of the implication.

#### 8.2 Variables

Name	Description
doc	Value:

 $continued\ on\ next\ page$ 

Name	Description
ZADEH_NORMS	Tuple containing, in order, Zadeh and, or and
	not operations
	Value: ZadehAnd, ZadehOr, ZadehNot
DRASTIC_NORMS	Tuple containing, in order, Drastic product
	(and), Drastic sum (or) and Zadeh not
	operations
	Value: DrasticProduct, DrasticSum,
	ZadehNot
EINSTEIN_NORMS	Tuple containing, in order, Einstein product
	(and), Einstein sum (or) and Zadeh not
	operations
	Value: EinsteinProduct, EinsteinSum,
	ZadehNot
MAMDANI_INFERENCE	Tuple containing, in order, Mamdani
	implication and algutination
	Value: MamdaniImplication,
	MamdaniAglutination
PROB_NORMS	Tuple containing, in order, probabilistic and, or
	and not operations
	Value: ProbabilisticAnd,
	ProbabilisticOr, ProbabilisticNot
PROB_INFERENCE	Tuple containing, in order, probabilistic
	implication and algutination
	Value: ProbabilisticImplication,
	ProbabilisticAglutination
package	Value: 'peach.fuzzy'

# 9 Package peach.ga

This package implements genetic algorithms. Consult:

base Implementation of the basic genetic algorithm;

**chromosome** Basic definitions to work with chromosomes. Defined as arrays of bits;

crossover Defines crossover operators and base classes;

fitness Defines fitness functions and base classes;

mutation Defines mutation operators and base classes;

selection Defines selection operators and base classes;

#### 9.1 Modules

- base: Basic Genetic Algorithm (GA) (Section 10, p. 49)
- **chromosome**: Basic definitions and classes for manipulating chromosomes (Section 11, p. 57)
- **crossover**: Basic definitions for crossover operations and base classes. (Section 12, p. 61)
- fitness: Basic definitions and base classes for definition of fitness functions for use with genetic algorithms.

  (Section 13, p. 67)
- mutation: Basic definitions and classes for operating mutation on chromosomes. (Section 14, p. 71)
- selection: Basic classes and definitions for selection operator. (Section 15, p. 74)

# 10 Module peach.ga.base

Basic Genetic Algorithm (GA)

This sub-package implements a traditional genetic algorithm as described in books and papers. It consists of selecting, breeding and mutating a population of chromosomes (arrays of bits) and reinserting the fittest individual from the previous generation if the GA is elitist. Please, consult a good reference on the subject, for the subject is way too complicated to be explained here.

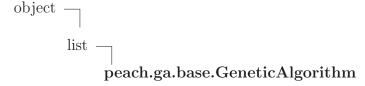
Within the algorithm implemented here, it is possible to specify and configure the selection, crossover and mutation methods using the classes in the respective sub-modules and custom methods can be implemented (check selection, crossover and mutation modules).

A GA object is actually a list of chromosomes. Please, refer to the documentation of the class below for more information.

#### 10.1 Variables

Name	Description
doc	Value:
package	Value: 'peach.ga'
add	Value: <ufunc 'add'=""></ufunc>

### 10.2 Class GeneticAlgorithm



Known Subclasses: peach.ga.base.GA

A standard Genetic Algorithm

This class implements the methods to generate, initialize and evolve a population of chromosomes according to a given fitness function. A standard GA implements, in this order:

- A selection method, to choose, from this generation, which individuals will be present in the next generation;
- A crossover method, to exchange information between selected individuals to add diversity to the population;

- A mutation method, to change information in a selected individual, also to add diversity to the population;
- The reinsertion of the fittest individual, if the population is elitist (which is almost always the case).

A population is actually a list of chromosomes, and individuals can be read and set as in a normal list. Use the [ ] operators to access individual chromosomes but please be aware that modifying the information on the list before the end of convergence can cause unpredictable results. The population and the algorithm have also other properties, check below to see more information on them.

#### 10.2.1 Methods

```
__init__(self, f, x0, ranges=[], fmt='f', fitness=<class
'peach.ga.fitness.Fitness'>, selection=<class
'peach.ga.selection.RouletteWheel'>, crossover=<class
'peach.ga.crossover.TwoPoint'>, mutation=<class
'peach.ga.mutation.BitToBit'>, elitist=True)
```

Initializes the population and the algorithm.

On the initialization of the population, a lot of parameters can be set. Those will deeply affect the results. The parameters are: **Parameters** 

A multivariable function to be evaluated. The nature of the parameters in the objective function will depend of the way you want the genetic algorithm to process. It can be a standard function that receives a one-dimensional array of values and computes the value of the function. In this case, the values will be passed as a tuple, instead of an array. This is so that integer, floats and other types of values can be passed and processed. In this case, the values will depend of the format string (see below)

If you don't supply a format, your objective function will receive a Chromosome instance, and it is the responsability of the function to decode the array of bits in any way. Notice that, while it is more flexible, it is certainly more difficult to deal with. Your function should process the bits and compute the return value which, in any case, should be a scalar.

Please, note that genetic algorithms maximize functions, so project your objective function accordingly. If you want to minimize a function, return its negated value.

A population of first estimates. This is a list, array or tuple of one-dimension arrays, each one corresponding to an estimate of the position of the minimum. The population size of the algorithm will be the same as the number of estimates in this list. Each component of the vectors in this list are one of the variables in the function to be optimized.

Since messing with the bits can change substantially the values obtained can diverge a lot from the maximum point. To avoid this, you can specify a range for each of the variables. range defaults to [], this means that no range checkin will be done. If given, then every variable will be checked. There are two ways to specify the ranges.

f:

x0:

ranges:

## $\mathbf{sanity}(self)$

Sanitizes the chromosomes in the population.

Since not every individual generated by the crossover and mutation operations might be a valid result, this method verifies if they are inside the allowed ranges (or if it is a number at all). Each invalid individual is discarded and a new one is generated.

This method has no parameters and returns no values.

## $\mathbf{restart}(\mathit{self}, x\theta)$

Resets the optimizer, allowing the use of a new set of estimates. This can be used to avoid stagnation. **Parameters** 

x0: A new set of estimates. It doesn't need to have the same size of the original population, but it must be a list of estimates in the same format as in the object instantiation. Please, see the documentation on the instantiation of the class.

## step(self)

Computes a new generation of the population, a step of the adaptation.

This method goes through all the steps of the GA, as described above. If the selection, crossover and mutation operators are defined, they are applied over the population. If the population is elitist, then the fittest individual of the past generation is reinserted.

This method has no parameters and returns no values. The GA itself can be consulted (using [ ]) to find the fittest individual which is the result of the process.

## $_{-}$ call $_{-}$ (self)

Transparently executes the search until the minimum is found. The stop criteria are the maximum error or the maximum number of iterations, whichever is reached first. Note that this is a \_\_call\_\_ method, so the object is called as a function. This method returns a tuple (x, e), with the best estimate of the minimum and the error. Return Value

This method returns a tuple (x, e), where x is the best estimate of the minimum, and e is the estimated error.

## Inherited from list

```
__add__(), __contains__(), __delitem__(), __delslice__(), __eq__(), __ge__(), __getattribute__(), __getitem__(), __getslice__(), __gt__(), __iadd__(), __imul__(), __iter__(), __le__(), __le__(), __len__(), __len__(), __reversed__(), __reversed__(), __reversed__(), __reversed__(), __setitem__(), __setslice__(), __sizeof__(), append(), count(), extend(), index(), insert(), pop(), remove(), reverse(), sort()
```

## Inherited from object

#### 10.2.2 Properties

Name	Description
chromosome_size	
fx	
best	
fbest	
fitness	
Inherited from object	
_class	

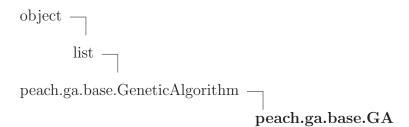
#### 10.2.3 Class Variables

Name	Description
Inherited from list	
_hash	

#### 10.2.4 Instance Variables

Name	Description
elitist	If True, then the population is elitist.
ranges	Holds the ranges for every variable. Although it
	is a writable property, care should be taken in
	changing parameters before ending the conver-
	gence.

### 10.3 Class GA



GA is an alias to GeneticAlgorithm

#### 10.3.1 Methods

# $Inherited\ from\ peach.ga.base.GeneticAlgorithm(Section\ 10.2)$

# Inherited from list

```
__add__(), __contains__(), __delitem__(), __delslice__(), __eq__(), __ge__(), __getattribute__(), __getitem__(), __getslice__(), __iadd__(), __imul__(), __iter__(), __le__(), __len__(), __len__(), __len__(), __reversed__(), __reversed__(), __reversed__(), __reversed__(), __setitem__(), __setslice__(), __sizeof__(), append(), count(), extend(), index(), insert(), pop(), remove(), reverse(), sort()
```

# Inherited from object

```
\_delattr\_(), \_format\_(), \_reduce\_(), \_reduce\_ex\_(), \_setattr\_(), \_str\_(), \_subclasshook\_()
```

## 10.3.2 Properties

Name	Description
Inherited from peach.ga.base.GeneticAlgorithm (Section 10.2)	
best, chromosome_size, fbest, fitness, fx	
Inherited from object	

continued on next page

Name	Description
_class	

## 10.3.3 Class Variables

Name	Description
Inherited from list	
_hash	

## 10.3.4 Instance Variables

Name	Description
Inherited from peach.ga.base.GeneticAlgorithm (Section 10.2)	
elitist, ranges	

# 11 Module peach.ga.chromosome

Basic definitions and classes for manipulating chromosomes

This sub-package is a vital part of the genetic algorithms framework within the module. This uses the bitarray module to implement a chromosome as an array of bits. It is, thus, necessary that this module is installed in your Python system. Please, check within the Python website how to install the bitarray module.

The class defined in this module is derived from bitarray and can also be derived if needed. In general, users or programmers won't need to instance this class directly -- it is manipulated by the genetic algorithm itself. Check the class definition for more information.

#### 11.1 Variables

Name	Description
doc	Value:
package	Value: 'peach.ga'

### 11.2 Class Chromosome

```
object —
bitarray._bitarray —
bitarray.bitarray —
peach.ga.chromosome.Chromosome
```

Implements a chromosome as a bit array.

Data is structured according to the struct module that exists in the Python standard library. Internally, data used in optimization with a genetic algorithm are represented as arrays of bits, so the bitarray module must be installed. Please consult the Python package index for more information on how to install bitarray. In general, the user don't need to worry about how the data is manipulated internally, but a specification of the format as in the struct module is needed.

If the internal format of the data is specified as an struct format, the genetic algorithm will take care of encoding and decoding data from and to the optimizer. However, it is possible to specify, instead of a format, the length of the chromosome. In that case, the fitness function must deal with the encoding and decoding of the information. It is strongly suggested that you use struct format strings, as they are much easier. This second option is provided as a convenience.

The Chromosome class is derived from the bitarray class. So, every property and method of this class should be accessible.

#### 11.2.1 Methods

\_new\_\_(cls, fmt=',', endian='little')

Allocates new memory space for the chromosome

This function overrides the bitarray.\_\_new\_\_ function to deal with the length of the chromosome. It should never be directly used, as it is automatically called by the Python interpreter in the moment of object creation. Return Value

A new Chromosome object. (type=a new object with type S, a subtype of T)

Overrides: object.\_new\_\_

 $_{--} ext{init}_{--} ( ext{\it self}, ext{\it fmt} = ext{\tt '} \, ext{\tt '})$ 

Initializes the chromosome.

This method is automatically called by the Python interpreter and initializes the data in the chromosome. No data should be provided to be encoded in the chromosome, as it is usually better start with random estimates. This method, in particular, does not clear the memory used in the time of creation of the bitarray from which a Chromosome derives -- so the random noise in the memory is used as initial value. Parameters

fmt: This parameter can be passed in two different ways. If fmt is a string, then it is assumed to be a struct-format string. Its size is calculated and a bitarray of the corresponding size is created. Please, consult the struct documentation, since what is explained there is exactly what is used here. For example, if you are going to use the optimizer to deal with three-dimensional vectors of continuous variables, the format would be something like:

fmt = 'fff'

If fmt, however, is an integer, then a bitarray of the given length is created. Note that, in this case, no format is given to the chromosome, and it is responsability of the programmer and the fitness function to provide for it.

Default value is an empty string.

Overrides: object.\_\_init\_\_

#### decode(self)

This method decodes the information given in the chromosome.

Data in the chromosome is encoded as a struct-formated string in a bitarray object. This method decodes the information and returns the encoded values. If a format string is not given, then it is assumed that this chromosome is just an array of bits, which is returned. Return Value

A tuple containing the decoded values, in the order specified by the format string.

Overrides: bitarray.bitarray.decode

### encode(self, values)

This method encodes the information into the chromosome.

Data in the chromosome is encoded as a struct-formated string in a bitarray object. This method encodes the given information in the bitarray. If a format string is not given, this method raises a TypeError exception. Parameters

values: A tuple containing the values to be encoded in an order consistent with the given struct-format.

Overrides: bitarray.bitarray.encode

## Inherited from bitarray.bitarray

```
_contains_(), search()
```

## Inherited from bitarray.\_bitarray

```
_add__(), _and__(), _copy__(), _deepcopy__(), _delitem__(), _eq__(), _ge__(), _getattribute__(), _getitem__(), _gt__(), _iadd__(), _iand__(), _imul__(), _invert__(), _ior__(), _iter__(), _iver__(), _le__(), _le__(), _le__(), _le__(), _le__(), _le__(), _ne__(), _or__(), _reduce__(), _repr__(), _rmul__(), _setitem__(), _xor__(), all(), any(), append(), buffer_info(), bytereverse(), copy(), count(), endian(), extend(), fill(), fromfile(), fromstring(), index(), insert(), invert(), length(), pack(), pop(), remove(), reverse(), setall(), sort(), tool(), tofile(), tolist(), tostring(), unpack()
```

## Inherited from object

```
__delattr__(), __format__(), __hash__(), __reduce_ex__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

### 11.2.2 Properties

Name	Description
size	
Inherited from object	
class	

#### 11.2.3 Instance Variables

Name	Description
format	Property that contains the chromosome struct
	format.

# 12 Module peach.ga.crossover

Basic definitions for crossover operations and base classes.

Crossover is a very basic and important operation in genetic algorithms. It is by means of crossover among the chromosomes that population gains diversity, thus exploring more completelly the solution space and giving better answers. This sub-module provides definitions of the most common crossover operations, and provides a class that can be subclassed to construct different types of crossover for experimentation.

#### 12.1 Variables

Name	Description
doc	Value:
package	Value: 'peach.ga'

#### 12.2 Class Crossover

object — peach.ga.crossover.Crossover

 $\textbf{Known Subclasses:} \ \ peach.ga.crossover. One Point, peach.ga.crossover. Two Point, peach.ga.crossover. Uniform Subclasses: peach.ga.crossover. Two Point, peach.ga.crossover. Uniform Subclasses: peach.ga.crossover. Two Point, peach.ga.crossover. Uniform Subclasses: peach.ga.crossover. Two Point, peach.ga$ 

Base class for crossover operators.

This class should be subclassed if you want to create your own crossover operator. The base class doesn't do much, it is only a prototype. As is done with all the base classes within this library, use the \_\_init\_\_ method to configure your crossover behaviour -- if needed -- and the \_\_call\_\_ method to operate over a population.

A class derived from this one should implement at least 2 methods, defined below:

\_\_init\_\_(self, \*cnf, \*\*kw) Initializes the object. There are no mandatory arguments, but any parameters can be used here to configure the operator. For example, a class can define a crossover rate -- this should be defined here:

A default value should always be offered, if possible.

\_\_call\_\_(self, population) The \_\_call\_\_ implementation should receive a population and operate over it. Please, consult the ga module to see more information on populations. It should return the processed population. No recomendation on the internals of the method is made. That being said, in general the

crossover operators pairs chromosomes and swap bits among them (but there is nothing to say that you can't do it differently).

Please, note that the GA implementations relies on this behaviour: it will pass a population to your \_\_call\_\_ method and expects to received the result back.

#### 12.2.1 Methods

# Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __init__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __sizeof__(), __str__(), __subclasshook__()
```

### 12.2.2 Properties

Name	Description
Inherited from object	
_class	

### 12.3 Class OnePoint

```
object —
peach.ga.crossover.Crossover —
peach.ga.crossover.OnePoint
```

A one-point crossover operator.

A one-point crossover randomly selects a single point in two chromosomes and swaps the bits among them from that point until the end of the bit stream. The crossover rate is the probability that two paired chromosomes will exchange bits.

#### 12.3.1 Methods

```
__init__(self, rate=0.75)

Initialize the crossover operator. Parameters
    rate: Probability that two paired chromosomes will exchange bits.

Overrides: object.__init__
```

 $\_$ call $\_$ (self, population)

Proceeds the crossover over a population.

In one-point crossover, chromosomes from a population are randomly paired. If a uniform random number is below the rate given in the instantiation of the operator, then a random point is selected and bits from that point until the end of the chromosomes are exchanged. **Parameters** 

population: A list of Chromosomes containing the present population of the algorithm. It is processed and the results of the exchange are returned to the caller.

#### Return Value

The processed population, a list of Chromosomes.

## Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

### 12.3.2 Properties

Name	Description
Inherited from object	
class	

### 12.3.3 Instance Variables

Name	Description
rate	Property that contains the crossover rate.

#### 12.4 Class TwoPoint

```
object —
peach.ga.crossover.Crossover —
peach.ga.crossover.TwoPoint
```

A two-point crossover operator.

A two-point crossover randomly selects two points in two chromosomes and swaps the bits

among them between these points. The crossover rate is the probability that two paired chromosomes will exchange bits.

#### 12.4.1 Methods

\_\_init\_\_(self, rate=0.75)

Initialize the crossover operator. Parameters

rate: Probability that two paired chromosomes will exchange bits.

Overrides: object.\_\_init\_\_

 $\_$ call $\_$ (self, population)

Proceeds the crossover over a population.

In two-point crossover, chromosomes from a population are randomly paired. If a uniform random number is below the rate given in the instantiation of the operator, then random points are selected and bits between those points are exchanged. **Parameters** 

population: A list of Chromosomes containing the present population of the algorithm. It is processed and the results of the exchange are returned to the caller.

### Return Value

The processed population, a list of Chromosomes.

### Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

## 12.4.2 Properties

Name	Description
Inherited from object	
class	

#### 12.4.3 Instance Variables

continued on next page

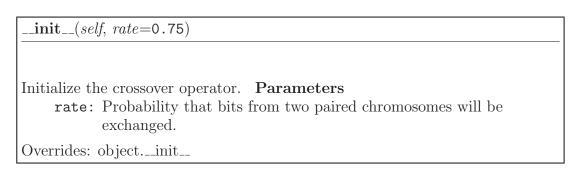
Name	Description
Name	Description
rate	Property that contains the crossover rate.

## 12.5 Class Uniform

A uniform crossover operator.

A uniform crossover scans two chromosomes in a bit-to-bit fashion. According to a given crossover rate, the corresponding bits are exchanged. The crossover rate is the probability that two bits will be exchanged.

#### 12.5.1 Methods



 $\_$ call $\_$ (self, population)

Proceeds the crossover over a population.

In uniform crossover, chromosomes from a population are randomly paired, and scaned in a bit-to-bit fashion. If a uniform random number is below the rate given in the instantiation of the operator, then the bits under scan will be exchanged in the chromosomes. **Parameters** 

population: A list of Chromosomes containing the present population of the algorithm. It is processed and the results of the exchange are returned to the caller.

### Return Value

The processed population, a list of Chromosomes.

# Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

### 12.5.2 Properties

Name	Description
Inherited from object	
_class	

### 12.5.3 Instance Variables

Name	Description
rate	Property that contains the crossover rate.

# 13 Module peach.ga.fitness

Basic definitions and base classes for definition of fitness functions for use with genetic algorithms.

Fitness is a function that rates higher the chromosomes that perform better according to the objective function. For example, if the minimum of a function needs to be found, then the fitness function should rate better the chromosomes that correspond to lower values of the objective function. This module gives support to use common Python functions as fitness functions in genetic algorithms.

The classes defined in this sub-module take a function and use some algorithm to rank a population. There are some different ranking functions, some are provided in this module. There is also a class that can be subclassed to generate other fitness methods. See the documentation of the corresponding class for more information.

### 13.1 Variables

Name	Description
doc	Value:
package	Value: 'peach.ga'

#### 13.2 Class Fitness

object — peach.ga.fitness.Fitness

Known Subclasses: peach.ga.fitness.Ranking

Base class for fitness function classifiers.

This class is used as the base of all fitness functions. However, even if it is intended to be used as a base class, it also provides some functionality, described below.

A subclass of this class should implement at least 2 methods:

\_\_init\_\_(self, \*args, \*\*kwargs) Initialization method. The initialization procedure doesn't need to take any parameters, but if any configuration must be done, it should be passed as an argument to the \_\_init\_\_ function. The genetic algorithm, however, does not expect parameters in the instantiation, so you should provide sensible defaults.

\_\_call\_\_(self, fx) This method is called to calculate population fitness. There is no

recomendation about the internals of the method, but its signature is expected as defined above. This method receives the values of the objective function applied over a population -- please, consult the ga module for more information on populations -- and should return a vector or list with the fitness value for each chromosome in the same order that they appear in the population.

This class implements the standard normalization fitness, as described in every book and article about GAs. The rank given to a chromosome is proportional to its objective function value.

#### 13.2.1 Methods

 $\_$ init $\_$ (self)

Initializes the operator. Overrides: object.\_init\_\_

 $\_$ call $\_$ (self, fx)

Calculates the fitness for all individuals in the population. Parameters

fx: The values of the objective function for every individual on the population to be processed. Please, consult the ga module for more information on populations. This method calculates the fitness according to the traditional normalization technique.

#### Return Value

A vector containing the fitness value for every individual in the population, in the same order that they appear there.

## Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

#### 13.2.2 Properties

Name	Description
Inherited from object	
class	

# 13.3 Class Ranking

```
object —

peach.ga.fitness.Fitness —

peach.ga.fitness.Ranking
```

Ranking fitness for a population

Ranking gives fitness values equally spaced between 0 and 1. The fittest individual receives fitness equals to 1, the second best equals to 1 - 1/N, the third best 1 - 2/N, and so on, where N is the size of the population. It is important to note that the worst fit individual receives a fitness value of 1/N, not 0. That allows that no individuals are excluded from the selection operator.

#### 13.3.1 Methods

```
__init__(self)

Initializes the operator. Overrides: object.__init__
```

 $\_$ call $\_$ (self, fx)

Calculates the fitness for all individuals in the population. Parameters fx: The values of the objective function for every individual on the population to be processed. Please, consult the ga module for more information on populations. This method calculates the fitness according to the equally spaced ranking technique.

#### Return Value

A vector containing the fitness value for every individual in the population, in the same order that they appear there.

Overrides: peach.ga.fitness.Fitness.\_\_call\_\_

## Inherited from object

#### 13.3.2 Properties

Name	Description
Inherited from object	
_class_	

# 14 Module peach.ga.mutation

Basic definitions and classes for operating mutation on chromosomes.

The mutation operator changes selected bits in the array corresponding to the chromosome. This operation is not as common as the others, but some genetic algorithms still implement it.

#### 14.1 Variables

Name	Description
doc	Value:
package	Value: 'peach.ga'

### 14.2 Class Mutation

object — peach.ga.mutation.Mutation

Known Subclasses: peach.ga.mutation.BitToBit

Base class for mutation operators.

This class should be subclassed if you want to create your own mutation operator. The base class doesn't do much, it is only a prototype. As is done with all the base classes within this library, use the \_\_init\_\_ method to configure your mutation behaviour -- if needed -- and the \_\_call\_\_ method to operate over a population.

A class derived from this one should implement at least 2 methods, defined below:

\_\_init\_\_(self, \*cnf, \*\*kw) Initializes the object. There is no mandatory arguments, but any parameters can be used here to configure the operator. For example, a class can define a mutation rate -- this should be defined here:

A default value should always be offered, if possible.

\_\_call\_\_(self, population) The \_\_call\_\_ implementation should receive a population and operate over it. Please, consult the ga module to see more information on populations. It should return the processed population. No recomendation on the internals of the method is made.

Please, note that the GA implementations relies on this behaviour: it will pass a population

to your \_\_call\_\_ method and expects to received the result back.

#### 14.2.1 Methods

# Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __init__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

### 14.2.2 Properties

Name	Description
Inherited from object	
class	

### 14.3 Class BitToBit

A simple bit-to-bit mutation operator.

This operator scans every individual in the population, in a bit-to-bit fashion. If a uniformly random number is less than the mutation rate (see below), then the bit is inverted. The mutation should be made very small, since large populations will represent a big number of bits; it should never be more than 0.5.

#### 14.3.1 Methods

init(self, rate=0.05)
Initialize the mutation operator. Parameters  rate: Probability that a single bit in an individual will be inverted.
Overrides: objectinit

 $\_$ call $\_$ (self, population)

Applies the operator over a population.

The behaviour of this operator is as described above: it scans every bit in every individual, and if a random number is less than the mutation rate, the bit is inverted. **Parameters** 

population: A list of Chromosomes containing the present population of the algorithm. It is processed and the results of the exchange are returned to the caller.

## Return Value

The processed population, a list of Chromosomes.

# Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

#### 14.3.2 Properties

Name	Description
Inherited from object	
_class	

#### 14.3.3 Instance Variables

Name	Description
rate	Property that contains the mutation rate.

# 15 Module peach.ga.selection

Basic classes and definitions for selection operator.

The first step in a genetic algorithm is the selection of the fittest individuals. The selection method typically uses the fitness of the population to compute which individuals are closer to the best solution. However, instead of deterministically deciding which individuals continue to the next generation, they are randomly choosen, the chances of an individual being choosen given by its fitness value. This sub-module implements selection methods.

#### 15.1 Variables

Name	Description
doc	Value:
package	Value: 'peach.ga'

### 15.2 Class Selection

object — peach.ga.selection.Selection

 $\textbf{Known Subclasses:} \ \ peach.ga.selection. Baker, \ peach.ga.selection. Binary Tournament, \$ 

Base class for selection operators.

This class should be subclassed if you want to create your own selection operator. The base class doesn't do much, it is only a prototype. As is done with all the base classes within this library, use the <code>\_\_init\_\_</code> method to configure your selection behaviour -- if needed -- and the <code>\_\_call\_\_</code> method to operate over a population.

A class derived from this one should implement at least 2 methods, defined below:

- \_\_init\_\_(self, \*cnf, \*\*kw) Initializes the object. There is no mandatory arguments, but any parameters can be used here to configure the operator. A default value should always be offered, if possible.
- \_\_call\_\_(self, population) The \_\_call\_\_ implementation should receive a population and operate over it. Please, consult the ga module to see more information on populations. It should return the processed population. No recomendation on the internals of the method is made.

Please, note that the GA implementations relies on this behaviour: it will pass a population to your \_\_call\_\_ method and expects to received the result back.

#### 15.2.1 Methods

# Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __init__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __sizeof__(), __str__(), __subclasshook__()
```

### 15.2.2 Properties

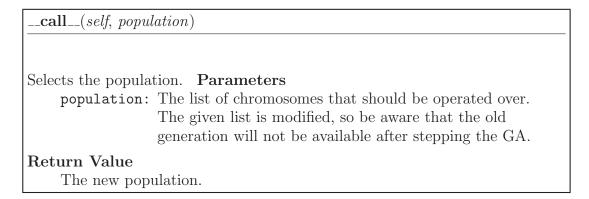
Name	Description
Inherited from object	
class	

### 15.3 Class RouletteWheel

The Roulette Wheel selection method.

This method randomly chooses a new population with the same size of the original population. An individual is choosen with a probability proportional to its fitness value, independent of what fitness method was used. This is usually abstracted as a roulette wheel in texts about the subject. Please, note that the selection is done *in loco*, that is, although the new population is returned, it is not a new list — it is the same list as before, but with values changed.

### 15.3.1 Methods



# Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __init__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __sizeof__(), __str__(), __subclasshook__()
```

#### 15.3.2 Properties

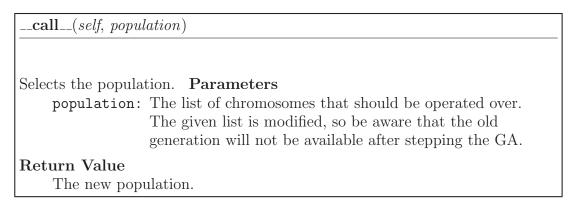
Name	Description
Inherited from object	
class	

# 15.4 Class BinaryTournament

The Binary Tournament selection method.

This method randomly chooses a new population with the same size of the original population. Two individuals are choosen at random and they "battle", the fittest surviving for the next generation. Please, note that the selection is done *in loco*, that is, although the new population is returned, it is not a new list -- it is the same list as before, but with values changed.

#### 15.4.1 Methods



# Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __init__(), __new__(), __reduce__(),
```

```
_reduce_ex_(), _repr_(), _setattr_(), _sizeof_(), _str_(), _subclasshook_()
```

### 15.4.2 Properties

Name	Description
Inherited from object	
class	

#### 15.5 Class Baker

The Baker selection method.

This method is very similar to the Roulette Wheel, but instead or randomly choosing every new member on the next generation, only the first probability is randomized. The others are determined as equally spaced numbers from 0 to 1, from this number. Please, note that the selection is done *in loco*, that is, although the new population is returned, it is not a new list — it is the same list as before, but with values changed.

#### 15.5.1 Methods

```
Selects the population. Parameters

population: The list of chromosomes that should be operated over.

The given list is modified, so be aware that the old generation will not be available after stepping the GA.

Return Value

The new population.
```

## Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __init__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __sizeof__(), __str__(), __subclasshook__()
```

# 15.5.2 Properties

Name	Description
Inherited from object	
_class	

# 16 Package peach.nn

This package implements support for neural networks. Consult:

base Basic definitions of the objects used with neural networks;

**af** A list of activation functions for use with neurons and a base class to implement different activation functions;

**lrule** Learning rules;

**nnet** Implementation of different classes of neural networks;

mem Associative memories and Hopfield model;

kmeans K-Means implementation for use with Radial Basis Networks;

#### 16.1 Modules

- af: Base activation functions and base class (Section 17, p. 80)
- base: Basic definitions for layers of neurons. (Section 18, p. 100)
- **kmeans**: K-Means clustering algorithm (Section 19, p. 104)
- **Irules**: Learning rules for neural networks and base classes for custom learning. (Section 20, p. 108)
- mem: Associative memories and Hopfield network model. (Section 21, p. 123)
- nnet: Basic topologies of neural networks. (Section 22, p. 128)

Class Activation Module peach.nn.af

# 17 Module peach.nn.af

Base activation functions and base class

Activation functions define if a neuron is activated or not. There are a lot of different definitions for activation functions in the literature, and this sub-package implements some of them. An activation function is defined by its response and its derivative. Being conveniently defined as classes, it is possible to define a custom derivative method.

In this package, also, there is a base class that should be subclassed if you want to define your own activation function. This class, however, can be instantiated with a standard Python function as an initialization parameter, and it is adjusted to work with the internals of the package.

If the base class is instantiated, then the function should take a real number as input, and return a real number. The response of the function determines if the neuron is activated or not.

#### 17.1 Variables

Name	Description
doc	Value:
package	Value: 'peach.nn'

### 17.2 Class Activation

object peach.nn.af.Activation

Known Subclasses: peach.nn.af.ArcTan, peach.nn.af.Linear, peach.nn.af.Sigmoid, peach.nn.af.Ramp, peach.nn.af.Signum, peach.nn.af.Threshold, peach.nn.af.TanH

Base class for activation functions.

This class can be used as base for activation functions. A subclass should have at least three methods, described below:

- \_\_init\_\_ This method should be used to configure the function. In general, some parameters to change the behaviour of a simple function is passed. In a subclass, the \_\_init\_\_ method should call the mother class initialization procedure.
- \_\_call\_\_ The \_\_call\_\_ interface is the function call. It should receive a *vector* of real numbers and return a *vector* of real numbers. Using the capabilities of

Class Activation Module peach.nn.af

the numpy module will help a lot. In case you don't know how to use, maybe instantiating this class instead will work better (see below).

**derivative** This method implements the derivative of the activation function. It is used in the learning methods. If one is not provided (but remember to call the superclass \_\_init\_\_ so that it is created).

#### 17.2.1 Methods

 $_{init}(self, f=None, df=None)$ 

Initializes the activation function.

Instantiating this class creates and adjusts a standard Python function to work with layers of neurons. **Parameters** 

- f: The activation function. It can be created as a lambda function or any other method, but it should take a real value, corresponding to the activation potential of a neuron, and return a real value, corresponding to its activation. Defaults to None, if none is given, the identity function is used.
- df: The derivative of the above function. It can be defined as above, or not given. If not given, an estimate is calculated based on the given function. Defaults to None.

Overrides: object.\_init\_\_

 $\_$ call $\_$ (self, x)

Call interface to the object.

This method applies the activation function over a vector of activation potentials, and returns the results. **Parameters** 

x: A real number or a vector of real numbers representing the activation potential of a neuron or a layer of neurons.

#### Return Value

The activation function applied over the input vector.

# **derivative**(self, x, dx = 5e-05)

An estimate of the derivative of the activation function.

This method estimates the derivative using difference equations. This is a simple estimate, but efficient nonetheless. **Parameters** 

- x: A real number or vector of real numbers representing the point over which the derivative is to be calculated.
- dx: The value of the interval of the estimate. The smaller this number is, the better. However, if made too small, the precision is not enough to avoid errors. This defaults to 5e-5, which is the values that gives the best results.

#### Return Value

The value of the derivative over the given point.

### Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

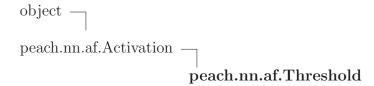
#### 17.2.2 Properties

Name	Description
Inherited from object	
_class_	

#### 17.2.3 Instance Variables

Name	Description
d	An alias to the derivative of the function.

### 17.3 Class Threshold



Threshold activation function.

#### 17.3.1 Methods

 $\_$ **init** $\_$ (self, threshold=0.0, amplitude=1.0)

Initializes the object. Parameters

threshold: The threshold value. If the value of the input is lower

than this, the function is 0, otherwise, it is the given

amplitude.

amplitude: The maximum value of the function.

Overrides: object.\_\_init\_\_

 $_{-}$ call $_{-}$ (self, x)

Call interface to the object.

This method applies the activation function over a vector of activation potentials, and returns the results. **Parameters** 

**x**: A real number or a vector of real numbers representing the activation potential of a neuron or a layer of neurons.

# Return Value

The activation function applied over the input vector.

Overrides: peach.nn.af.Activation.\_\_call\_\_

### derivative(self, x)

The function derivative. Technically, this function doesn't have a derivative, but making it equals to 1, this can be used in learning algorithms.

## **Parameters**

x: A real number or a vector of real numbers representing the activation potential of a neuron or a layer of neurons.

### Return Value

The derivative of the activation function applied over the input vector.

Overrides: peach.nn.af.Activation.derivative

### Inherited from object

\_\_delattr\_\_(), \_\_format\_\_(), \_\_getattribute\_\_(), \_\_hash\_\_(), \_\_new\_\_(), \_\_reduce\_\_(), \_\_reduce\_ex\_\_(),

### 17.3.2 Properties

Name	Description
Inherited from object	
_class	

#### 17.3.3 Instance Variables

Name	Description
Inherited from peach.nn.af.Activation (Section 17.2)	
d	

# 17.4 Class Threshold

object —
peach.nn.af.Activation —
peach.nn.af.Threshold

Threshold activation function.

### 17.4.1 Methods

\_\_init\_\_(self, threshold=0.0, amplitude=1.0)

Initializes the object. Parameters
 threshold: The threshold value. If the value of the input is lower than this, the function is 0, otherwise, it is the given amplitude.

amplitude: The maximum value of the function.

Overrides: object.\_\_init\_\_

 $_{-}$ call $_{-}$ (self, x)

Call interface to the object.

This method applies the activation function over a vector of activation potentials, and returns the results. **Parameters** 

x: A real number or a vector of real numbers representing the activation potential of a neuron or a layer of neurons.

### Return Value

The activation function applied over the input vector.

Overrides: peach.nn.af.Activation.\_\_call\_\_

## derivative(self, x)

The function derivative. Technically, this function doesn't have a derivative, but making it equals to 1, this can be used in learning algorithms.

### **Parameters**

**x**: A real number or a vector of real numbers representing the activation potential of a neuron or a layer of neurons.

#### Return Value

The derivative of the activation function applied over the input vector.

Overrides: peach.nn.af.Activation.derivative

### Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

### 17.4.2 Properties

Name	Description
Inherited from object	
class	

#### 17.4.3 Instance Variables

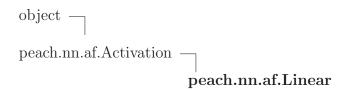
Name	Description
Inherited from peach.nn.af.A	ctivation (Section 17.2)

continued on next page

Class Linear Module peach.nn.af

Name	Description
d	

### 17.5 Class Linear



Identity activation function

#### 17.5.1 Methods

 $\_\mathbf{init}_{--}(self)$ 

Initializes the function Parameters

- f: The activation function. It can be created as a lambda function or any other method, but it should take a real value, corresponding to the activation potential of a neuron, and return a real value, corresponding to its activation. Defaults to None, if none is given, the identity function is used.
- df: The derivative of the above function. It can be defined as above, or not given. If not given, an estimate is calculated based on the given function. Defaults to None.

Overrides: object.\_\_init\_\_

Class Linear Module peach.nn.af

 $_{-}$ call $_{-}$ (self, x)

Call interface to the object.

This method applies the activation function over a vector of activation potentials, and returns the results. **Parameters** 

x: A real number or a vector of real numbers representing the activation potential of a neuron or a layer of neurons.

### Return Value

The activation function applied over the input vector.

Overrides: peach.nn.af.Activation.\_\_call\_\_

## derivative(self, x)

The function derivative. Parameters

x: A real number or a vector of real numbers representing the activation potential of a neuron or a layer of neurons.

### Return Value

The derivative of the activation function applied over the input vector.

Overrides: peach.nn.af.Activation.derivative

### Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

## 17.5.2 Properties

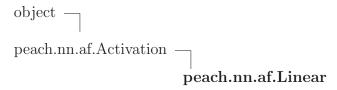
Name	Description
Inherited from object	
class	

#### 17.5.3 Instance Variables

Name	Description
Inherited from peach.nn.af.Activation (Section 17.2)	
d	

Class Linear Module peach.nn.af

## 17.6 Class Linear



Identity activation function

#### 17.6.1 Methods

 $\_$ **init** $\_\_(self)$ 

Initializes the function Parameters

- f: The activation function. It can be created as a lambda function or any other method, but it should take a real value, corresponding to the activation potential of a neuron, and return a real value, corresponding to its activation. Defaults to None, if none is given, the identity function is used.
- df: The derivative of the above function. It can be defined as above, or not given. If not given, an estimate is calculated based on the given function. Defaults to None.

Overrides: object.\_\_init\_\_

 $_{-}$ call $_{-}$ (self, x)

Call interface to the object.

This method applies the activation function over a vector of activation potentials, and returns the results. **Parameters** 

x: A real number or a vector of real numbers representing the activation potential of a neuron or a layer of neurons.

### Return Value

The activation function applied over the input vector.

Overrides: peach.nn.af.Activation.\_\_call\_\_

Class Ramp Module peach.nn.af

# derivative(self, x)

The function derivative. Parameters

x: A real number or a vector of real numbers representing the activation potential of a neuron or a layer of neurons.

### Return Value

The derivative of the activation function applied over the input vector.

Overrides: peach.nn.af.Activation.derivative

# Inherited from object

## 17.6.2 Properties

Name	Description
Inherited from object	
class	

### 17.6.3 Instance Variables

Name	Description
Inherited from peach.nn.af.Activation (Section 17.2)	
d	

## 17.7 Class Ramp

object —	
peach.nn.af.Activation	neach nn af Ramr

Ramp activation function

Class Ramp Module peach.nn.af

#### 17.7.1 Methods

 $\_init\_(self, p\theta = (-0.5, 0.0), p1 = (0.5, 1.0))$ 

Initializes the object.

Two points are needed to set this function. They are used to determine where the ramp begins and where it ends. **Parameters** 

- p0: The starting point, given as a tuple (x0, y0). For values of the input below x0, the function returns y0. Defaults to (-0.5, 0.0).
- p1: The ending point, given as a tuple (x1, y1). For values of the input above x1, the function returns y1. Defaults to (0.5, 1.0).

Overrides: object.\_\_init\_\_

 $\_$ call $\_$ (self, x)

Call interface to the object.

This method applies the activation function over a vector of activation potentials, and returns the results. **Parameters** 

**x**: A real number or a vector of real numbers representing the activation potential of a neuron or a layer of neurons.

## Return Value

The activation function applied over the input vector.

Overrides: peach.nn.af.Activation.\_\_call\_\_

derivative(self, x)

The function derivative. Parameters

x: A real number or a vector of real numbers representing the activation potential of a neuron or a layer of neurons.

### Return Value

The derivative of the activation function applied over the input vector.

Overrides: peach.nn.af.Activation.derivative

Class Sigmoid Module peach.nn.af

# Inherited from object

#### 17.7.2 Properties

Name	Description
Inherited from object	
class	

#### 17.7.3 Instance Variables

Name	Description
Inherited from peach.nn.af.Activation (Section 17.2)	
d	

# 17.8 Class Sigmoid

object —
peach.nn.af.Activation —
peach.nn.af.Sigmoid

Sigmoid activation function

### 17.8.1 Methods

 $\_init\_(self, a=1.0, x\theta=0.0)$ 

Initializes the object. Parameters

a: The slope of the function in the center x0. Defaults to 1.0.

x0: The center of the sigmoid. Defaults to 0.0.

Overrides: object.\_\_init\_\_

Class Sigmoid Module peach.nn.af

# $_{-}$ call $_{-}$ (self, x)

Call interface to the object.

This method applies the activation function over a vector of activation potentials, and returns the results. **Parameters** 

x: A real number or a vector of real numbers representing the activation potential of a neuron or a layer of neurons.

### Return Value

The activation function applied over the input vector.

Overrides: peach.nn.af.Activation.\_\_call\_\_

## derivative(self, x)

The function derivative. Parameters

x: A real number or a vector of real numbers representing the activation potential of a neuron or a layer of neurons.

### Return Value

The derivative of the activation function applied over the input vector.

Overrides: peach.nn.af.Activation.derivative

### Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

## 17.8.2 Properties

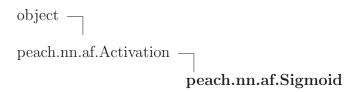
Name	Description
Inherited from object	
class	

#### 17.8.3 Instance Variables

Name	Description
Inherited from peach.nn.af.Activation (Section 17.2)	
d	

Class Sigmoid Module peach.nn.af

# 17.9 Class Sigmoid



Sigmoid activation function

#### 17.9.1 Methods

 $-init_{-}(self, a=1.0, x\theta=0.0)$ 

Initializes the object. Parameters

a: The slope of the function in the center x0. Defaults to 1.0.

x0: The center of the sigmoid. Defaults to 0.0.

Overrides: object.\_\_init\_\_

 $\_$ call $\_$ (self, x)

Call interface to the object.

This method applies the activation function over a vector of activation potentials, and returns the results. **Parameters** 

x: A real number or a vector of real numbers representing the activation potential of a neuron or a layer of neurons.

# Return Value

The activation function applied over the input vector.

Overrides: peach.nn.af.Activation.\_\_call\_\_

Class Signum Module peach.nn.af

# derivative(self, x)

The function derivative. Parameters

x: A real number or a vector of real numbers representing the activation potential of a neuron or a layer of neurons.

### Return Value

The derivative of the activation function applied over the input vector.

Overrides: peach.nn.af.Activation.derivative

# Inherited from object

## 17.9.2 Properties

Name	Description
Inherited from object	
_class	

### 17.9.3 Instance Variables

Name	Description
Inherited from peach.nn.af.Activation (Section 17.2)	
d	

# 17.10 Class Signum

object —	
peach.nn.af.Activation	neach nn af Signum

Signum activation function

Class Signum Module peach.nn.af

#### 17.10.1 Methods

 $\_$ **init** $\_$ (self)

Initializes the object. Parameters

f: The activation function. It can be created as a lambda function or any other method, but it should take a real value, corresponding to the activation potential of a neuron, and return a real value, corresponding to its activation. Defaults to None, if none is given, the identity function is used.

df: The derivative of the above function. It can be defined as above, or not given. If not given, an estimate is calculated based on the given function. Defaults to None.

Overrides: object.\_\_init\_\_

 $_{-}$ call $_{-}$ (self, x)

Call interface to the object.

This method applies the activation function over a vector of activation potentials, and returns the results. **Parameters** 

**x**: A real number or a vector of real numbers representing the activation potential of a neuron or a layer of neurons.

#### Return Value

The activation function applied over the input vector.

Overrides: peach.nn.af.Activation.\_\_call\_\_

### derivative(self, x)

The function derivative. Technically, this function doesn't have a derivative, but making it equals to 1, this can be used in learning algorithms.

#### **Parameters**

**x**: A real number or a vector of real numbers representing the activation potential of a neuron or a layer of neurons.

#### Return Value

The derivative of the activation function applied over the input vector.

Overrides: peach.nn.af.Activation.derivative

Class ArcTan Module peach.nn.af

# Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

#### 17.10.2 Properties

Name	Description
Inherited from object	
class	

#### 17.10.3 Instance Variables

Name	Description
Inherited from peach.nn.af.Activation (Section 17.2)	
d	

### 17.11 Class ArcTan

Inverse tangent activation function

#### 17.11.1 Methods

\_\_init\_\_(self, a=1.0, x0=0.0)

Initializes the object Parameters

a: The slope of the function in the center x0. Defaults to 1.0.

x0: The center of the sigmoid. Defaults to 0.0.

Overrides: object.\_\_init\_\_

Class ArcTan Module peach.nn.af

# $\_$ call $\_$ (self, x)

Call interface to the object.

This method applies the activation function over a vector of activation potentials, and returns the results. **Parameters** 

x: A real number or a vector of real numbers representing the activation potential of a neuron or a layer of neurons.

### Return Value

The activation function applied over the input vector.

Overrides: peach.nn.af.Activation.\_\_call\_\_

## derivative(self, x)

The function derivative. Parameters

**x**: A real number or a vector of real numbers representing the activation potential of a neuron or a layer of neurons.

### Return Value

The derivative of the activation function applied over the input vector.

Overrides: peach.nn.af.Activation.derivative

### Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

#### 17.11.2 Properties

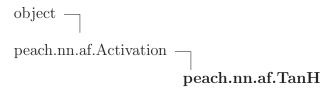
Name	Description
Inherited from object	
class	

#### 17.11.3 Instance Variables

Name	Description
Inherited from peach.nn.af.Activation (Section 17.2)	
d	

Class TanH Module peach.nn.af

# 17.12 Class TanH



Hyperbolic tangent activation function

### 17.12.1 Methods

 $-init_{-}(self, a=1.0, x\theta=0.0)$ 

Initializes the object Parameters

a: The slope of the function in the center x0. Defaults to 1.0.

x0: The center of the sigmoid. Defaults to 0.0.

Overrides: object.\_\_init\_\_

 $\_$ call $\_$ (self, x)

Call interface to the object.

This method applies the activation function over a vector of activation potentials, and returns the results. **Parameters** 

x: A real number or a vector of real numbers representing the activation potential of a neuron or a layer of neurons.

# Return Value

The activation function applied over the input vector.

Overrides: peach.nn.af.Activation.\_\_call\_\_

Class TanH Module peach.nn.af

# derivative(self, x)

The function derivative. Parameters

x: A real number or a vector of real numbers representing the activation potential of a neuron or a layer of neurons.

### Return Value

The derivative of the activation function applied over the input vector.

Overrides: peach.nn.af.Activation.derivative

# Inherited from object

### 17.12.2 Properties

Name	Description
Inherited from object	
class	

## 17.12.3 Instance Variables

Name	Description
Inherited from peach.nn.af.Activation (Section 17.2)	
d	

# 18 Module peach.nn.base

Basic definitions for layers of neurons.

This subpackage implements the basic classes used with neural networks. A neural network is basically implemented as a layer of neurons. To speed things up, a layer is implemented as a array, where each line represents the weight vector of a neuron. Further definitions and algorithms are based on this definition.

#### 18.1 Variables

Name	Description
_doc_	Value:
package	Value: 'peach.nn'

### 18.2 Class Layer

object — peach.nn.base.Layer

Known Subclasses: peach.nn.nnet.SOM, peach.nn.mem.Hopfield

Base class for neural networks.

This class implements a layer of neurons. It is represented by a array of real values. Each line of the array represents the weight vector of a single neuron. If the neurons on the layer are biased, then the first element of the weight vector is the bias weight, and the bias input is always valued 1. Also, to each layer is associated an activation function, that determines if the neuron is fired or not. Please, consult the module **af** to see more about activation functions.

In general, this class should be subclassed if you want to use neural nets. But, as neural nets are very different one from the other, check carefully the documentation to see if the attributes, properties and methods are suited to your task.

#### **18.2.1** Methods

# $\_$ call $\_$ (self, x)

The feedforward method to the layer.

The \_\_call\_\_ interface should be called if the answer of the neuron to a given input vector **x** is desired. This method has collateral effects, so beware. After the calling of this method, the **v** and **y** properties are set with the activation potential and the answer of the neurons, respectively. **Parameters** 

x: The input vector to the layer.

### Return Value

The vector containing the answer of every neuron in the layer, in the respective order.

# $\_$ getitem $\_$ (self, n)

The [ ] get interface.

The input to this method is forwarded to the weights property. That means that it will return the respective line/element of the weight array.

#### **Parameters**

n: A slice object containing the elements referenced. Since it is forwarded to an array, it behaves exactly as one.

## Return Value

The element or elements in the referenced indices.

Class Layer Module peach.nn.base

\_init\_\_(self, shape, phi=<class 'peach.nn.af.Linear'>, bias=False)

Initializes the layer.

A layer is represented by a array where each line is the weight vector of a single neuron. The first element of the vector is the bias weight, in case the neuron is biased. Associated with the layer is an activation function defined in an appropriate way. **Parameters** 

shape: Stablishes the size of the layer. It must be a two-tuple of the
format (m, n), where m is the number of neurons in the
layer, and n is the number of inputs of each neuron. The
neurons in the layer all have the same number of inputs.

phi: The activation function. It can be an Activation object (please, consult the af module) or a standard Python function. In this case, it must receive a single real value and return a single real value which determines if the neuron is activated or not. Defaults to Linear.

bias: If True, then the neurons on the layer are biased. That means that an additional weight is added to each neuron to represent the bias. If False, no modification is made.

Overrides: object.\_init\_\_

 $_{-}$ setitem $_{-}(self, n, w)$ 

The [ ] set interface.

The inputs to this method are forwarded to the weights property. That means that it will set the respective line/element of the weight array. **Parameters** 

- n: A slice object containing the elements referenced. Since it is forwarded to an array, it behaves exactly as one.
- w: A value or array of values to be set in the given indices.

## Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

#### 18.2.2 Properties

continued on next page

Name	Description
Name	Description
bias	
inputs	
phi	
shape	
size	
V	
weights	
У	
Inherited from object	
class	

# 19 Module peach.nn.kmeans

# K-Means clustering algorithm

This sub-package implements the K-Means clustering algorithm. This algorithm, given a set of points, finds a set of vectors that best represents a partition for these points. These vectors represent the center of a cloud of points that are nearest to them.

This algorithm is one that can be used with radial basis function (RBF) networks to find the centers of the RBFs. Usually, training a RBFN in two passes -- first positioning them, and then computing their variance.

#### 19.1 Functions

# ClassByDistance(xs, c)

Given a set of points and a list of centers, classify the points according to their euclidian distance to the centers. **Parameters** 

- xs: Set of points to be classified. They must be given as a list or array of one-dimensional vectors, one per line.
- c: Set of centers. Must also be given as a lista or array of one-dimensional vectors, one per line.

### Return Value

A list of index of the classification. The indices are the position of the cluster in the given parameters c.

### ClusterByMean(x)

This function computes the center of a cluster by averaging the vectors in the input set by simply averaging each component. **Parameters** 

x: Set of points to be clustered. They must be given in the form of a list or array of one-dimensional points.

## Return Value

A one-dimensional array representing the center of the cluster.

## 19.2 Variables

Name	Description
doc	Value:

continued on next page

Name	Description
_package_	Value: 'peach.nn'

### 19.3 Class KMeans

object — peach.nn.kmeans.KMeans

K-Means clustering algorithm

This class implements the known and very used K-Means clustering algorithm. In this algorithm, the centers of the clusters are selected randomly. The points on the training set are classified in accord to their closeness to the cluster centers. This changes the positions of the centers, which changes the classification of the points. This iteration is repeated until no changes occur.

Traditional K-Means implementations classify the points in the training set according to the euclidian distance to the centers, and centers are computed as the average of the points associated to it. This is the default behaviour of this implementation, but it is configurable. Please, read below for more detail.

#### 19.3.1 Methods

 $\_$ init $\_$ (self,  $training\_set$ , nclusters, classifier = <function ClassByDistance at 0x973d10c>, clusterer = <function ClusterByMean at 0x973d294>)

Initializes the algorithm. Parameters

training\_set: A list or array of vectors containing the data to be

classified. Each of the vectors in this list *must* have the same dimension, or the algorithm won't behave correctly. Notice that each vector can be given as a tuple -- internally, everything is converted to arrays.

nclusters: The number of clusters to be found. This must be,

of course, bigger than 1. These represent the number of centers found once the algorithm

terminates.

classifier: A function that classifies each of the points in the

training set. This function receives the training set and a list of centers, and classify each of the points according to the given metric. Please, look at the documentation on these functions for more

information. Its default value is "ClassByDistance',

which uses euclidian distance as metric.

clusterer: A function that computes the center of the cluster,

given a set of points. This function receives a list of points and returns the vector representing the

cluster. For more information, look at the documentation for these functions. Its default value

is ClusterByMean, in which the cluster is represented by the mean value of the vectors.

Overrides: object.\_\_init\_\_

## step(self)

This method runs one step of the algorithm. It might be useful to track the changes in the parameters. Return Value

The computed centers for this iteration.

 $\_$ call $\_$ (self, imax=20)

The \_\_call\_\_ interface is used to run the algorithm until convergence is found. Parameters

imax: Specifies the maximum number of iterations admitted in the execution of the algorithm. It defaults to 20.

## Return Value

An array containing, at each line, the vectors representing the centers of the clustered regions.

# Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

### 19.3.2 Properties

Name	Description
С	
Inherited from object	
class	

# 20 Module peach.nn.lrules

Learning rules for neural networks and base classes for custom learning.

This sub-package implements learning methods commonly used with neural networks. There are a lot of different topologies and different learning methods for each one. It is very difficult to find a consistent framework for defining learning methods, in consequence. This method defines some base classes that are coupled with the neural networks that they are supposed to work with. Also, based on these classes, some of the traditional methods are implemented.

If you want to implement a different learning method, you must subclass the correct base class. Consult the classes below. Also, pay attention to how the implementation is expected to behave. Since learning algorithms are usually somewhat complex, care should be taken to make everything work accordingly.

#### 20.1 Variables

Name	Description
doc	Value:
package	Value: 'peach.nn'

# 20.2 Class FFLearning

object — peach.nn.lrules.FFLearning

Known Subclasses: peach.nn.lrules.BackPropagation, peach.nn.lrules.LMS

Base class for FeedForwarding Multilayer neural networks.

As a base class, this class doesn't do anything. You should subclass this class if you want to implement a learning method for multilayer networks.

A learning method for a neural net of this kind must deal with a FeedForward instance. A FeedForward object is a list of Layers (consulting the documentation of these classes is important!). Each layer is a bidimensional array, where each line represents the synaptic weights of a single neuron. So, a multilayer network is actually a three-dimensional array, if you will. Usually, though, learning methods for this kind of net propagate some measure of the error from the output back to the input (the BackPropagation method, for instance).

A class implementing a learning method should have at least two methods:

\_\_init\_\_ The \_\_init\_\_ method should initialize the object. It is in general used to

configure some property of the learning algorithm, such as the learning rate.

\_\_call\_\_ The \_\_call\_\_ interface is how the method should interact with the neural network. It should have the following signature:

where nn is the FeedForward instance to be modified in loco, x is the input vector and d is the desired response of the net for that particular input vector. It should return nothing.

#### 20.2.1 Methods

 $\_$ call $\_$ (self, nn, x, d)

The \_\_call\_\_ interface.

Read the documentation for this class for more information. A call to the class should have the following parameters: **Parameters** 

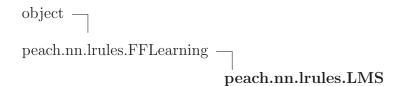
- nn: A FeedForward neural network instance that is going to be modified by the learning algorithm. The modification is made *in loco*, that is, the synaptic weights of nn should be modified in place, and not returned from this function.
- x: The input vector from the training set.
- d: The desired response for the given input vector.

### Inherited from object

#### 20.2.2 Properties

Name	Description
Inherited from object	
_class	

### 20.3 Class LMS



The Least-Mean-Square (LMS) learning method.

The LMS method is a very simple method of learning, thoroughly described in virtually every book about the subject. Please, consult a good book on neural networks for more information. This implementation tries to use the numpy routines as much as possible for better efficiency.

#### 20.3.1 Methods

```
\_init\_(self, lrate=0.05)
```

Initializes the object. Parameters

lrate: Learning rate to be used in the algorithm. Defaults to 0.05.

Overrides: object.\_\_init\_\_

```
\_call\_(self, nn, x, d)
```

The \_\_call\_\_ interface.

The learning implementation. Read the documentation for the base class for more information. A call to the class should have the following parameters:

#### **Parameters**

nn: A FeedForward neural network instance that is going to be modified by the learning algorithm. The modification is made *in loco*, that is, the synaptic weights of nn should be modified in place, and not returned from this function.

x: The input vector from the training set.

d: The desired response for the given input vector.

Overrides: peach.nn.lrules.FFLearning.\_call\_

# Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(),
```

# 20.3.2 Properties

Name	Description
Inherited from object	
class	

#### 20.3.3 Instance Variables

Name	Description
lrate	Learning rate used in the algorithm.

### 20.4 Class LMS

object —
peach.nn.lrules.FFLearning —
peach.nn.lrules.LMS

The Least-Mean-Square (LMS) learning method.

The LMS method is a very simple method of learning, thoroughly described in virtually every book about the subject. Please, consult a good book on neural networks for more information. This implementation tries to use the numpy routines as much as possible for better efficiency.

### 20.4.1 Methods

\_\_init\_\_(self, lrate=0.05)

Initializes the object. Parameters

lrate: Learning rate to be used in the algorithm. Defaults to 0.05.

Overrides: object.\_\_init\_\_

 $\_$ call $\_$ (self, nn, x, d)

The \_\_call\_\_ interface.

The learning implementation. Read the documentation for the base class for more information. A call to the class should have the following parameters:

## **Parameters**

- nn: A FeedForward neural network instance that is going to be modified by the learning algorithm. The modification is made *in loco*, that is, the synaptic weights of nn should be modified in place, and not returned from this function.
- **x**: The input vector from the training set.
- d: The desired response for the given input vector.

Overrides: peach.nn.lrules.FFLearning.\_call\_

# Inherited from object

# 20.4.2 Properties

Name	Description
Inherited from object	
class	

### 20.4.3 Instance Variables

Name	Description
lrate	Learning rate used in the algorithm.

### 20.5 Class LMS

object —
peach.nn.lrules.FFLearning —
peach.nn.lrules.LMS

The Least-Mean-Square (LMS) learning method.

The LMS method is a very simple method of learning, thoroughly described in virtually every book about the subject. Please, consult a good book on neural networks for more information. This implementation tries to use the numpy routines as much as possible for better efficiency.

#### 20.5.1 Methods

\_init\_\_(self, lrate=0.05)

Initializes the object. Parameters

lrate: Learning rate to be used in the algorithm. Defaults to 0.05.

Overrides: object.\_\_init\_\_

 $\_$ call $\_$ (self, nn, x, d)

The \_\_call\_\_ interface.

The learning implementation. Read the documentation for the base class for more information. A call to the class should have the following parameters:

### **Parameters**

- nn: A FeedForward neural network instance that is going to be modified by the learning algorithm. The modification is made *in loco*, that is, the synaptic weights of nn should be modified in place, and not returned from this function.
- x: The input vector from the training set.
- d: The desired response for the given input vector.

Overrides: peach.nn.lrules.FFLearning.\_call\_

## Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

#### 20.5.2 Properties

Name	Description
Inherited from object	
class	

#### 20.5.3 Instance Variables

Name	Description
lrate	Learning rate used in the algorithm.

# 20.6 Class BackPropagation



The BackPropagation learning method.

The backpropagation method is a very simple method of learning, thoroughly described in virtually every book about the subject. Please, consult a good book on neural networks for more information. This implementation tries to use the numpy routines as much as possible for better efficiency.

#### 20.6.1 Methods

\_\_init\_\_(self, lrate=0.05)

Initializes the object. Parameters
 lrate: Learning rate to be used in the algorithm. Defaults to 0.05.

Overrides: object.\_\_init\_\_

 $\_$ call $\_$ (self, nn, x, d)

The \_\_call\_\_ interface.

The learning implementation. Read the documentation for the base class for more information. A call to the class should have the following parameters:

## **Parameters**

- nn: A FeedForward neural network instance that is going to be modified by the learning algorithm. The modification is made *in loco*, that is, the synaptic weights of nn should be modified in place, and not returned from this function.
- **x**: The input vector from the training set.
- d: The desired response for the given input vector.

Overrides: peach.nn.lrules.FFLearning.\_call\_

# Inherited from object

#### 20.6.2 Properties

Name	Description
Inherited from object	
_class	

### 20.6.3 Instance Variables

Name	Description
lrate	Learning rate used in the algorithm.

# 20.7 Class SOMLearning

object peach.nn.lrules.SOMLearning

Known Subclasses: peach.nn.lrules.Competitive, peach.nn.lrules.Cooperative, peach.nn.lrules.WinnerTa Base class for Self-Organizing Maps. As a base class, this class doesn't do anything. You should subclass this class if you want to implement a learning method for self-organizing maps.

A learning method for a neural net of this kind must deal with a SOM instance. A SOM object is a Layer (consulting the documentation of these classes is important!).

A class implementing a learning method should have at least two methods:

- \_\_init\_\_ The \_\_init\_\_ method should initialize the object. It is in general used to configure some property of the learning algorithm, such as the learning rate.
- \_\_call\_\_ The \_\_call\_\_ interface is how the method should interact with the neural network. It should have the following signature:

where nn is the SOM instance to be modified in loco, and x is the input vector. It should return nothing.

#### 20.7.1 Methods

 $\_$ call $\_$ (self, nn, x, d)

The \_\_call\_\_ interface.

Read the documentation for this class for more information. A call to the class should have the following parameters: **Parameters** 

nn: A SOM neural network instance that is going to be modified by the learning algorithm. The modification is made in loco, that is, the synaptic weights of nn should be modified in place, and not returned from this function.

x: The input vector from the training set.

## Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __init__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __sizeof__(), __str__(), __subclasshook__()
```

#### 20.7.2 Properties

Name	Description
Inherited from object	
class	

## 20.8 Class WinnerTakesAll



Purely competitive learning method without learning rate adjust.

A winner-takes-all strategy detects the winner on the self-organizing map and adjusts it in the direction of the input vector, scaled by the learning rate. Its tendency is to cluster around the gravity center of the points in the training set.

#### 20.8.1 Methods

\_\_init\_\_(self, lrate=0.05)

Initializes the object. Parameters
 lrate: Learning rate to be used in the algorithm. Defaults to 0.05.

Overrides: object.\_\_init\_\_

```
\_call\_(self, nn, x)
```

The \_\_call\_\_ interface.

The learning implementation. Read the documentation for the base class for more information. A call to the class should have the following parameters:

#### **Parameters**

nn: A SOM neural network instance that is going to be modified by the learning algorithm. The modification is made in loco, that is, the synaptic weights of nn should be modified in place, and not returned from this function.

x: The input vector from the training set.

Overrides: peach.nn.lrules.SOMLearning.\_call\_

# Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

### 20.8.2 Properties

Name	Description
Inherited from object	
_class_	

#### 20.8.3 Instance Variables

Name	Description
lrate	Learning rate used with the algorithm.

### 20.9 Class WinnerTakesAll

Purely competitive learning method without learning rate adjust.

A winner-takes-all strategy detects the winner on the self-organizing map and adjusts it in the direction of the input vector, scaled by the learning rate. Its tendency is to cluster around the gravity center of the points in the training set.

## 20.9.1 Methods

\_\_init\_\_(self, lrate=0.05)

Initializes the object. Parameters
 lrate: Learning rate to be used in the algorithm. Defaults to 0.05.

Overrides: object.\_\_init\_\_

 $\_$ call $\_$ (self, nn, x)

The \_\_call\_\_ interface.

The learning implementation. Read the documentation for the base class for more information. A call to the class should have the following parameters:

## **Parameters**

nn: A SOM neural network instance that is going to be modified by the learning algorithm. The modification is made *in loco*, that is, the synaptic weights of nn should be modified in place, and not returned from this function.

x: The input vector from the training set.

Overrides: peach.nn.lrules.SOMLearning.\_\_call\_\_

# Inherited from object

### 20.9.2 Properties

Name	Description
Inherited from object	
class	

### 20.9.3 Instance Variables

Name	Description
lrate	Learning rate used with the algorithm.

# 20.10 Class Competitive

object —
peach.nn.lrules.SOMLearning —
peach.nn.lrules.Competitive

Competitive learning with time adjust of the learning rate.

A competitive strategy detects the winner on the self-organizing map and adjusts it in the

direction of the input vector, scaled by the learning rate. Its tendency is to cluster around the gravity center of the points in the training set. As time passes, the learning rate grows smaller, this allows for better adjustment of the synaptic weights.

#### **20.10.1** Methods

\_init\_\_(self, lrate=0.05, tl=1000.0)

Initializes the object. Parameters

lrate: Learning rate to be used in the algorithm. Defaults to 0.05.

t1: Time constant that measures how many iterations will be needed to reduce the learning rate to a small value. Defaults to 1000.

Overrides: object.\_\_init\_\_

 $\_$ call $\_$ (self, nn, x)

The \_\_call\_\_ interface.

The learning implementation. Read the documentation for the base class for more information. A call to the class should have the following parameters:

#### **Parameters**

nn: A SOM neural network instance that is going to be modified by the learning algorithm. The modification is made in loco, that is, the synaptic weights of nn should be modified in place, and not returned from this function.

x: The input vector from the training set.

Overrides: peach.nn.lrules.SOMLearning.\_call\_

# Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

### 20.10.2 Properties

Name	Description
Inherited from object	
class	

# 20.11 Class Cooperative

```
object —
peach.nn.lrules.SOMLearning —
peach.nn.lrules.Cooperative
```

Cooperative learning with time adjust of the learning rate and neighborhood function to propagate cooperation

A cooperative strategy detects the winner on the self-organizing map and adjusts it in the direction of the input vector, scaled by the learning rate. Its tendency is to cluster around the gravity center of the points in the training set. As time passes, the learning rate grows smaller, this allows for better adjustment of the synaptic weights.

Also, a neighborhood is defined on the winner. Neurons close to the winner are also updated in the direction of the input vector, although with a smaller scale determined by the neighborhood function. A neighborhood function is 1. at 0., and decreases monotonically as the distance increases.

There are issues with this class! -- some of the class capabilities are yet to be developed.

#### 20.11.1 Methods

\_init\_\_(self, lrate=0.05, tl=1000, tn=1000)

Initializes the object. Parameters

lrate: Learning rate to be used in the algorithm. Defaults to 0.05.

t1: Time constant that measures how many iterations will be needed to reduce the learning rate to a small value. Defaults to 1000.

tn: Time constant that measures how many iterations will be needed to shrink the neighborhood. Defaults to 1000.

Overrides: object.\_\_init\_\_

 $\_$ call $\_$ (self, nn, x)

The \_\_call\_\_ interface.

The learning implementation. Read the documentation for the base class for more information. A call to the class should have the following parameters:

## **Parameters**

nn: A SOM neural network instance that is going to be modified by the learning algorithm. The modification is made in loco, that is, the synaptic weights of nn should be modified in place, and not returned from this function.

x: The input vector from the training set.

Overrides: peach.nn.lrules.SOMLearning.\_call\_

# Inherited from object

#### 20.11.2 Properties

Name	Description
Inherited from object	
class	

# 21 Module peach.nn.mem

Associative memories and Hopfield network model.

This sub-package implements associative memories. In associative memories, information is recovered by supplying not an exact index (such as in their usual counterparts), but supplying an index simmilar enough that the information can be deduced from what is stored in its synaptic weights. There are a number of different memories of this kind.

The most common type is the Hopfield network. A Hopfield network is a recurrent self-associative memory. Although there are real-valued versions of the network, the binary type is more common. In it, patterns are recovered from an initial estimate through an iterative process.

### 21.1 Functions

 $\mathbf{randn}(d\theta, d1, dn, ...)$ 

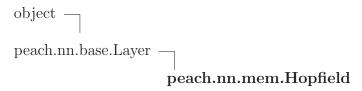
Returns zero-mean, unit-variance Gaussian random numbers in an array of shape (d0, d1, ..., dn).

Note: This is a convenience function. If you want an interface that takes a tuple as the first argument use numpy.random.standard\_normal(shape\_tuple).

#### 21.2 Variables

Name	Description
doc	Value:
package	Value: 'peach.nn'
arctan	Value: <ufunc 'arctan'=""></ufunc>
cosh	Value: <ufunc 'cosh'=""></ufunc>
exp	Value: <ufunc 'exp'=""></ufunc>
pi	Value: 3.14159265359
sign	Value: <ufunc 'sign'=""></ufunc>
tanh	Value: <ufunc 'tanh'=""></ufunc>

# 21.3 Class Hopfield



Hopfield neural network model

A Hopfield network is a recurrent network of one layer of neurons. There output of every neuron is conected to the inputs of every other neuron, but not to itself. This kind of network is autoassociative, or content-based memory. That means that, given a noisy version of a pattern stored in it, the network is capable of, through an iterative algorithm, recover the original pattern, removing the noise. There is a limit in the quantity of patterns that can be stored without causing error, and if a pattern is stored, its negated form is also stored.

This is the binary form of the Hopfield network, which is the most common form. It implements a Layer of neurons, without bias, and with the Signum as the activation function.

#### 21.3.1 Methods

Initializes the Hopfield network.

The Hopfield network is implemented as a layer of neurons. Parameters size: The number of neurons in the network. In a Hopfield network, the number of neurons is also the number of inputs in each neuron, and the dimensionality of the patterns to be stored and recovered.

phi: The activation function. Traditionally, the Hopfield network uses the signum function as activation. This is the default value.

Overrides: object.\_\_init\_\_

# learn(self, x)

Applies one example of the training set to the network.

Training a Hopfield network is not exactly an iterative procedure. The network usually stores a small number of patterns, and the learning procedure consists only in computing the synaptic weight matrix, which can be done in very few steps (in fact, just the number of patterns). This method is here for consistency with the rest of the library, but it works, anyway. **Parameters** 

x: The pattern to be stored. It must be a vector with the same size as the network, or else an exception will be raised. The pattern can be of any dimensionality, but it will internally be converted to a column vector.

## $train(self, train\_set)$

Presents a training set to the network

This method stores all the patterns of the training set in the weight matrix. It calls the learn method for every pattern in the set. Parameters

train\_set: A list containing all the patterns to be stored in the network. Each pattern is a vector of any dimensions, which are converted internally to a column vector.

## step(self, x)

Performs a step in the recovering procedure

The algorithm for recovering the patterns stored in a Hopfield network is an iterative algorithm which goes from a starting test pattern (a stored pattern with noise) and recovers the noiseless version -- if possible. This method takes the test pattern and performs one step of the convergence **Parameters** 

x: The noisy pattern.

## Return Value

The result of one step of the convergence. This might be the same as the input pattern, or the pattern with one component inverted. Class Hopfield Module peach.nn.mem

 $\_$ call $\_$ (self, x, imax=2000, eqmax=100)

Recovers a stored pattern

The \_\_call\_\_ interface should be called if a memory needs to be recovered from the network. Given a noisy pattern x, the algorithm will be executed until convergence or a maximum number of iterations occur. This method repeatedly calls the step method until a stop condition is reached. The stop condition is the maximum number of iterations, or a number of iterations where no changes are found in the retrieved pattern. **Parameters** 

x: The noisy pattern vector presented to the network.

imax: The maximum number of iterations the algorithm is to be repeated. When this number of iterations is reached, the algorithm will stop, whether the pattern was found or not. Defaults to 2000.

eqmax: The maximum number of iterations the algorithm will be repeated if no changes occur in the retrieval of the pattern. At each iteration of the algorithm, a component might change. It is considered that, if a number of iterations are performed and no changes are found in the pattern, then the algorithm converged, and it stops. Defaults to 100.

#### Return Value

The vector containing the recovered pattern from the stored memories.

Overrides: peach.nn.base.Layer.\_\_call\_\_

## Inherited from peach.nn.base.Layer(Section 18.2)

```
__getitem__(), __setitem__()
```

## Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

### 21.3.2 Properties

Name	Description
inputs	
weights	
Inherited from peach.nn.base.Layer (Section 18.2)	
bias, phi, shape, size, v, y	

 $continued\ on\ next\ page$ 

Name	Description
Inherited from object	
class	

# 22 Module peach.nn.nnet

Basic topologies of neural networks.

This sub-package implements various neural network topologies, see the complete list below. These topologies are implemented using the Layer class of the base sub-package. Please, consult the documentation of that module for more information on layers of neurons. The neural nets implemented here don't derive from the Layer class, instead, they have instance variables to take control of them. Thus, there is no base class for networks. While subclassing the classes of this module is usually safe, it is recomended that a new kind of net is developed from the ground up.

#### 22.1 Functions

 $\mathbf{randn}(d\theta, d1, dn, ...)$ 

Returns zero-mean, unit-variance Gaussian random numbers in an array of shape (d0, d1, ..., dn).

Note: This is a convenience function. If you want an interface that takes a tuple as the first argument use numpy.random.standard\_normal(shape\_tuple).

### 22.2 Variables

Name	Description
doc	Value:
package	Value: 'peach.nn'
arctan	Value: <ufunc 'arctan'=""></ufunc>
cosh	Value: <ufunc 'cosh'=""></ufunc>
exp	Value: <ufunc 'exp'=""></ufunc>
pi	Value: 3.14159265359
sign	Value: <ufunc 'sign'=""></ufunc>
tanh	Value: <ufunc 'tanh'=""></ufunc>

## 22.3 Class FeedForward



Classic completely connected neural network.

A feedforward neural network is implemented as a list of layers, each layer being a Layer object (please consult the documentation on the base module for more information on layers). The layers are completely connected, which means that every neuron in one layers is connected to every other neuron in the following layer.

There is a number of learning methods that are already implemented, but in general, any learning class derived from FFLearning can be used. No other kind of learning can be used. Please, consult the documentation on the lrules (learning rules) module.

#### 22.3.1 Methods

 $\_$ init $\_$ (self, layers, phi = <class 'peach.nn.af.Linear'>, lrule = <class 'peach.nn.lrules.BackPropagation'>, bias =False)

Initializes a feedforward neural network.

A feedforward network is implemented as a list of layers, completely connected. **Parameters** 

layers: A list of integers containing the shape of the network. The first element of the list is the number of inputs of the network (or, as somebody prefer, the number of input neurons); the number of outputs is the number of neurons in the last layer. Thus, at least two numbers should be given.

phi: The activation functions to be used with each layer of the network. Please consult the Layer documentation in the base module for more information. This parameter can be a single function or a list of functions. If only one function is given, then the same function is used in every layer. If a list of functions is given, then the layers use the functions in the sequence given. Note that heterogeneous networks can be created that way. Defaults to Linear.

lrule: The learning rule used. Only FFLearning objects (instances of the class or of the subclasses) are allowed. Defaults to BackPropagation. Check the lrules documentation for more information.

bias: If True, then the neurons are biased.

### Return Value

new empty list

Overrides: object.\_\_init\_\_

# $_{-}$ call $_{-}$ (self, x)

The feedforward method of the network.

The \_\_call\_\_ interface should be called if the answer of the neuron network to a given input vector **x** is desired. This method has collateral effects, so beware. After the calling of this method, the **y** property is set with the activation potential and the answer of the neurons, respectively. **Parameters** 

x: The input vector to the network.

## Return Value

The vector containing the answer of every neuron in the last layer, in the respective order.

## learn(self, x, d)

Applies one example of the training set to the network.

Using this method, one iteration of the learning procedure is made with the neurons of this network. This method presents one example (not necessarilly of a training set) and applies the learning rule over the network. The learning rule is defined in the initialization of the network, and some are implemented on the lrules method. New methods can be created, consult the lrules documentation but, for FeedForward instances, only FFLearning learning is allowed.

Also, notice that this method only applies the learning method! The network should be fed with the same input vector before trying to learn anything first. Consult the feed and train methods below for more ways to train a network.

#### **Parameters**

- x: Input vector of the example. It should be a column vector of the correct dimension, that is, the number of input neurons.
- d: The desired answer of the network for this particular input vector. Notice that the desired answer should have the same dimension of the last layer of the network. This means that a desired answer should be given for every output of the network.

#### Return Value

The error obtained by the network.

# $\mathbf{feed}(\mathit{self}, x, d)$

Feed the network and applies one example of the training set to the network.

Using this method, one iteration of the learning procedure is made with the neurons of this network. This method presents one example (not necessarilly of a training set) and applies the learning rule over the network. The learning rule is defined in the initialization of the network, and some are implemented on the lrules method. New methods can be created, consult the lrules documentation but, for FeedForward instances, only FFLearning learning is allowed.

Also, notice that *this method feeds the network* before applying the learning rule. Feeding the network has collateral effects, and some properties change when this happens. Namely, the y property is set. Please consult the \_\_call\_\_interface. Parameters

- x: Input vector of the example. It should be a column vector of the correct dimension, that is, the number of input neurons.
- d: The desired answer of the network for this particular input vector. Notice that the desired answer should have the same dimension of the last layer of the network. This means that a desired answer should be given for every output of the network.

# Return Value

The error obtained by the network.

train(self, train\_set, imax=2000, emax=1e-05, randomize=False)

Presents a training set to the network.

This method automatizes the training of the network. Given a training set, the examples are shown to the network (possibly in a randomized way). A maximum number of iterations or a maximum admitted error should be given as a stop condition. **Parameters** 

train\_set: The training set is a list of examples. It can have any size and can contain repeated examples. In fact, the definition of the training set is open. Each element of the training set, however, should be a two-tuple (x, d),

where x is the input vector, and d is the desired response of the network for this particular input. See

the learn and feed for more information.

imax: The maximum number of iterations. Examples from the

training set will be presented to the network while this

limit is not reached. Defaults to 2000.

emax: The maximum admitted error. Examples from the

training set will be presented to the network until the error obtained is lower than this limit. Defaults to 1e-5.

randomize: If this is True, then the examples are shown in a

randomized order. If False, then the examples are shown in the same order that they appear in the

train\_set list. Defaults to False.

# Inherited from list

```
__add__(), __contains__(), __delitem__(), __delslice__(), __eq__(), __ge__(), __getattribute__(), __getitem__(), __getslice__(), __gt__(), __iadd__(), __imul__(), __iter__(), __le__(), __le__(), __len__(), __len__(), __reversed__(), __reversed__(), __reversed__(), __reversed__(), __setitem__(), __setslice__(), __sizeof__(), append(), count(), extend(), index(), insert(), pop(), remove(), reverse(), sort()
```

### Inherited from object

\_\_delattr\_\_(), \_\_format\_\_(), \_\_reduce\_\_(), \_\_reduce\_ex\_\_(), \_\_setattr\_\_(), \_\_str\_\_(), \_\_subclasshook\_\_()

### 22.3.2 Properties

Name	Description
nlayers	
bias	

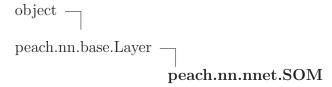
continued on next page

Name	Description
У	
phi	
Inherited from object	
class	

### 22.3.3 Class Variables

Name	Description
Inherited from list	
_hash	

## 22.4 Class SOM



A Self-Organizing Map (SOM).

A self-organizing map is a type of neural network that is trained via unsupervised learning. In particular, the self-organizing map finds the neuron closest to an input vector -- this neuron is the winning neuron, and it is the answer of the network. Thus, the SOM is usually used for classification and pattern recognition.

The SOM is a single-layer network, so this class subclasses the Layer class. But some of the properties of a Layer object are not available or make no sense in this context.

#### 22.4.1 Methods

 $\_init\_(self, shape, lrule = < class 'peach.nn.lrules.Competitive'>)$ 

Initializes a self-organizing map.

A self-organizing map is implemented as a layer of neurons. There is no connection among the neurons. The answer to a given input is the neuron closer to the given input. phi (the activation function) v (the activation potential) and bias are not used. Parameters

shape: Stablishes the size of the SOM. It must be a two-tuple of the format (m, n), where m is the number of neurons in the layer, and n is the number of inputs of each neuron. The neurons in the layer all have the same number of inputs.

lrule: The learning rule used. Only SOMLearning objects (instances of the class or of the subclasses) are allowed. Defaults to Competitive. Check the lrules documentation for more information.

Overrides: object.\_init\_\_

 $\_$ call $\_$ (self, x)

The response of the network to a given input.

The \_\_call\_\_ interface should be called if the answer of the neuron network to a given input vector **x** is desired. This method has collateral effects, so beware. After the calling of this method, the **y** property is set with the activation potential and the answer of the neurons, respectively. **Parameters** 

x: The input vector to the network.

## Return Value

The winning neuron.

Overrides: peach.nn.base.Layer.\_\_call\_\_

# learn(self, x)

Applies one example of the training set to the network.

Using this method, one iteration of the learning procedure is made with the neurons of this network. This method presents one example (not necessarilly of a training set) and applies the learning rule over the network. The learning rule is defined in the initialization of the network, and some are implemented on the lrules method. New methods can be created, consult the lrules documentation but, for SOM instances, only SOMLearning learning is allowed.

Also, notice that this method only applies the learning method! The network should be fed with the same input vector before trying to learn anything first. Consult the feed and train methods below for more ways to train a network. Parameters

x: Input vector of the example. It should be a column vector of the correct dimension, that is, the number of input neurons.

# Return Value

The error obtained by the network.

## $\mathbf{feed}(\mathit{self}, x)$

Feed the network and applies one example of the training set to the network.

Using this method, one iteration of the learning procedure is made with the neurons of this network. This method presents one example (not necessarilly of a training set) and applies the learning rule over the network. The learning rule is defined in the initialization of the network, and some are implemented on the lrules method. New methods can be created, consult the lrules documentation but, for SOM instances, only SOMLearning learning is allowed.

Also, notice that *this method feeds the network* before applying the learning rule. Feeding the network has collateral effects, and some properties change when this happens. Namely, the y property is set. Please consult the \_\_call\_\_ interface. Parameters

x: Input vector of the example. It should be a column vector of the correct dimension, that is, the number of input neurons.

## Return Value

The error obtained by the network.

train(self, train\_set, imax=2000, emax=1e-05, randomize=False)

Presents a training set to the network.

This method automatizes the training of the network. Given a training set, the examples are shown to the network (possibly in a randomized way). A maximum number of iterations or a maximum admitted error should be given as a stop condition. **Parameters** 

train\_set: The training set is a list of examples. It can have any

size and can contain repeated examples. In fact, the definition of the training set is open. Each element of the training set, however, should be a input vector of the correct dimensions, See the learn and feed for

more information.

imax: The maximum number of iterations. Examples from the

training set will be presented to the network while this

limit is not reached. Defaults to 2000.

emax: The maximum admitted error. Examples from the

training set will be presented to the network until the error obtained is lower than this limit. Defaults to 1e-5.

randomize: If this is True, then the examples are shown in a

randomized order. If False, then the examples are shown in the same order that they appear in the

train\_set list. Defaults to False.

### Inherited from peach.nn.base.Layer(Section 18.2)

```
__getitem__(), __setitem__()
```

# Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

#### 22.4.2 Properties

Name	Description
У	
Inherited from peach.nn.base	Layer (Section 18.2)
bias, inputs, phi, shape, size, v, weights	
Inherited from object	
_class	

#### 22.5 Class GRNN



GRNN is the implementation of General Regression Neural Network, a kind of probabilistic neural network used in regression tasks.

#### 22.5.1 Methods

### $\_init\_(self, sigma=0.1)$

Initializes the network.

Is not necessary to inform the training set size, GRNN will do it by itself in train method. Parameters

sigma: A real number. This value determines the spread of probability density function (i.e is the smoothness parameter). A great value for sigma will result in a large spread gaussian and the sample points will cover a wide range of inputs, while a small value will create a limited spread gaussian and the sample points will cover a small range of inputs

Overrides: object.\_\_init\_\_

**train**(self, sampleInputs, targets)

Presents a training set to the network.

This method uses the sample inputs to set the size of network. Parameters

sampleInputs: Should be a list of numbers or a list of numpy.array

to set the sample inputs. These inputs are used to calculate the distance between prediction points.

targets: The target values of sample inputs. Should be a list

of numbers.

 $\_$ call $\_$ (self, x)

The method to predict a value from input x. Parameters

x: The input vector to the network.

### Return Value

The predicted value.

# Inherited from object

#### 22.5.2 Properties

Name	Description
Inherited from object	
class	

### 22.6 Class PNN

object peach.nn.nnet.PNN

PNN is the implementation of Probabilistic Neural Network, a network used for classification tasks

#### 22.6.1 Methods

 $\_init\_(self, sigma=0.1)$ 

Initializes the network.

Is not necessary to inform the training set size, PNN will do it by itself in train method. Parameters

sigma: A real number. This value determines the spread of probability density function (i.e is the smoothness parameter). A great value for sigma will result in a large spread gaussian and the sample points will cover a wide range of inputs, while a small value will create a limited spread gaussian and the sample points will cover a small range of inputs

Overrides: object.\_\_init\_\_

**train**(self, trainSet)

Presents a training set to the network.

This method uses the sample inputs to set the size of network. Parameters train\_set: The training set is a list of examples. It can have any size. In fact, the definition of the training set is open.

Each element of the training set, however, should be a two-tuple (x, d), where x is the input vector, and d is the desired response of the network for this particular input, i.e the category of x pattern.

 $\_$ call $\_$ (self, x)

The method to classify the input x into one of trained category. **Parameters** x: The input vector to the network.

Return Value

The category that best represent the input vector.

# Inherited from object

\_\_delattr\_\_(), \_\_format\_\_(), \_\_getattribute\_\_(), \_\_hash\_\_(), \_\_new\_\_(), \_\_reduce\_\_(), \_\_reduce\_ex\_\_(), \_\_repr\_\_(), \_\_setattr\_\_(), \_\_sizeof\_\_(), \_\_str\_\_(), \_\_subclasshook\_\_()

# 22.6.2 Properties

Name	Description
Inherited from object	
_class	

# 23 Package peach.optm

This package implements deterministic optimization methods. Consult:

base Basic definitions and interface with the optimization methods;

linear Basic methods for one variable optimization;

multivar Gradient, Newton and othe multivariable optimization methods;

quasinewton Quasi-Newton methods;

Every optimizer works in pretty much the same way. Instantiate the respective class, using as parameter the cost function to be optimized, the first estimate (a scalar in case of a single variable optimization, and a one-dimensional array in case of multivariable optimization) and some other parameters. Use step() to perform one iteration of the method, use the \_\_call\_\_() method to perform the search until the stop conditions are met. See each method for details.

#### 23.1 Modules

- base: Basic definitions and base class for optimizers (Section 24, p. 143)
- linear: This package implements basic one variable only optimizers. (Section 25, p. 148)
- multivar: This package implements basic multivariable optimizers, including gradient and Newton searches.
   (Section 26, p. 160)
- quasinewton: This package implements basic quasi-Newton optimizers. Newton optimizer is very efficient, except that inverse matrices need to be calculated at each convergence step. These methods try to estimate the hessian inverse iteratively, thus increasing performance.
- (Section 27, p. 175)
- stochastic (Section 28, p. 185)

# 24 Module peach.optm.base

Basic definitions and base class for optimizers

This sub-package exports some auxiliary functions to work with cost functions, namely, a function to calculate gradient vectors and hessian matrices, which are extremely important in optimization.

Also, a base class, Optimizer, for all optimizers. Sub-class this class if you want to create your own optmizer, and follow the interface. This will allow easy configuration of your own scripts and comparison between methods.

### 24.1 Functions

```
\mathbf{gradient}(f, dx = 1e-05)
```

Creates a function that computes the gradient vector of a scalar field.

This function takes as a parameter a scalar function and creates a new function that is able to compute the derivative (in case of single variable functions) or the gradient vector (in case of multivariable functions. Please, note that this function takes as a parameter a function, and returns as a result another function. Calling the returned function on a point will give the gradient vector of the original function at that point:

In the above example, df is a generated function which will return the result of the expression 2\*x, the derivative of the original function. In the case f is a multivariable function, it is assumed that its argument is a line vector.

#### **Parameters**

- f: Any function, one- or multivariable. The function must be an scalar function, though there is no checking at the moment the function is created. If f is not an scalar function, an exception will be raised at the moment the returned function is used.
- dx: Optional argument that gives the precision of the calculation. It
  is recommended that dx = sqrt(D), where D is the machine
  precision. It defaults to 1e-5, which usually gives a good
  estimate.

#### Return Value

A new function which, upon calling, gives the derivative or gradient vector of the original function on the analised point. The parameter of the returned function is a real number or a line vector where the gradient should be calculated.

### hessian(f, dx=1e-05)

Creates a function that computes the hessian matrix of a scalar field.

This function takes as a parameter a scalar function and creates a new function that is able to calculate the second derivative (in case of single variable functions) or the hessian matrix (in case of multivariable functions. Please, note that this function takes as a parameter a *function*, and returns as a result *another function*. Calling the returned function on a point will give the hessian matrix of the original function at that point:

In the above example, ddf is a generated function which will return the result of the expression 12\*x\*\*2, the second derivative of the original function. In the case f is a multivariable function, it is assumed that its argument is a line vector. Parameters

- f: Any function, one- or multivariable. The function must be an scalar function, though there is no checking at the moment the function is created. If f is not an scalar function, an exception will be raised at the moment the returned function is used.
- dx: Optional argument that gives the precision of the calculation. It
  is recommended that dx = sqrt(D), where D is the machine
  precision. It defaults to 1e-5, which usually gives a good
  estimate.

#### Return Value

A new function which, upon calling, gives the second derivative or hessian matrix of the original function on the analised point. The parameter of the returned function is a real number or a line vector where the hessian should be calculated.

#### 24.2 Variables

Name	Description
doc	Value:
package	Value: 'peach.optm'

## 24.3 Class Optimizer

```
object peach.optm.base.Optimizer
```

Known Subclasses: peach.optm.quasinewton.BFGS, peach.optm.quasinewton.DFP, peach.optm.quasine peach.optm.linear.Direct1D, peach.optm.linear.Fibonacci, peach.optm.linear.GoldenRule, peach.optm.linear.peach.optm.multivar.Direct, peach.optm.multivar.Gradient, peach.optm.multivar.MomentumGradient, peach.optm.multivar.Newton

Base class for all optimizers.

This class does nothing, and shouldn't be instantiated. Its only purpose is to serve as a template (or interface) to implemented optimizers. To create your own optimizer, subclass this.

This class defines 3 methods that should be present in any subclass. They are defined here:

\_\_init\_\_ Initializes the optimizer. There are three usual parameters in this method, which signature should be:

```
__init__(self, f, x0, ..., emax=1e-8, imax=1000)
```

#### where:

- f is the cost function to be minimized;
- x0 is the first estimate of the location of the minimum;
- ... represent additional configuration of the optimizer, and it is dependent of the technique implemented;
- emax is the maximum allowed error. The default value above is only a suggestion;
- imax is the maximum number of iterations of the method. The default value above is only a suggestions.
- step() This method should take an estimate and calculate the next, possibly better, estimate. Notice that the next estimate is strongly dependent of the method, the optimizer state and configuration, and two calls to this method with the same estimate might not give the same results. The method signature is:

### step(self)

and the implementation should keep track of all the needed parameters. The method should return a tuple (x, e) with the new estimate of the solution and the estimate of the error.

- restart() Implement this method to restart the optimizer. An optimizer might be restarted for a number of reasons: to escape a local minimum, to try different estimates and so on. This method should take at least one argument, x0, a new estimate for the optimizer. Optionally, new configuration might be given, but, if not, the old ones must be used.
- \_\_call\_\_ This method should take an estimate and iterate the optimizer until one of the stop criteria is met: either less than the maximum error or more than the maximum number of iterations. Error is usually calculated as an estimate using the previous estimate, but any technique might be used. Use a counter to keep track of the number of iterations. The method signature is:

```
__call__(self)
```

and the implementation should keep track of all the needed parameters. The method should return a tuple (x, e) with the final estimate of the solution and the estimate of the error.

#### 24.3.1 Methods

```
__init__(self, f=None, x0=None, emax=1e-08, imax=1000)

x.__init__(...) initializes x; see x.__class__.__doc__ for signature Overrides:
object.__init__ extit(inherited documentation)
```

```
step(self, x)
```

$$\_$$
call $\_$ (self,  $x$ )

# Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

### 24.3.2 Properties

Name	Description
Inherited from object	
class	

# 25 Module peach.optm.linear

This package implements basic one variable only optimizers.

### 25.1 Variables

Name	Description
doc	Value:
package	Value: 'peach.optm'

#### 25.2 Class Direct1D

### 1-D direct search.

This methods 'oscilates' around the function minimum, reducing the updating step until it achieves the maximum error or the maximum number of steps. This is a very inefficient method, and should be used only at times where no other methods are able to converge (eg., if a function has a lot of discontinuities, or similar conditions).

#### 25.2.1 Methods

\_init\_\_(self, f, x0, range=None, h=0.5, emax=1e-08, imax=1000)

Initializes the optimizer.

To create an optimizer of this type, instantiate the class with the parameters given below: **Parameters** 

f: A one variable only function to be optimized. The function should have only one parameter and return the function value.

x0: First estimate of the minimum. Since this is a linear method, this should be a float or int.

range: A range of values might be passed to the algorithm, but it is not necessary. If supplied, this parameter should be a tuples of two values, (x0, x1), where x0 is the start of the interval, and x1 its end. Obviously, x0 should be smaller than x1. When this parameter is present, the algorithm will not let the estimates fall outside the given interval.

h: The initial step of the search. Defaults to 0.5

emax: Maximum allowed error. The algorithm stops as soon as the error is below this level. The error is absolute.

imax: Maximum number of iterations, the algorithm stops as soon this number of iterations are executed, no matter what the error is at the moment.

Overrides: object.\_\_init\_\_

#### $\mathbf{restart}(self, x\theta, h = \mathsf{None})$

Resets the optimizer, returning to its original state, and allowing to use a new first estimate. **Parameters** 

x0: The new initial value of the estimate of the minimum. Since this is a linear method, this should be a float or int.

h: The initial step of the search. Defaults to 0.5

# step(self)

One step of the search.

In this method, the result of the step is highly dependent of the steps executed before, as the search step is updated at each call to this method. **Return Value** 

This method returns a tuple (x, e), where x is the updated estimate of the minimum, and e is the estimated error.

Overrides: peach.optm.base.Optimizer.step

### $\_$ call $\_$ (self)

Transparently executes the search until the minimum is found. The stop criteria are the maximum error or the maximum number of iterations, whichever is reached first. Note that this is a \_\_call\_\_ method, so the object is called as a function. This method returns a tuple (x, e), with the best estimate of the minimum and the error. Return Value

This method returns a tuple (x, e), where x is the best estimate of the minimum, and e is the estimated error.

Overrides: peach.optm.base.Optimizer.\_\_call\_\_

# Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

#### 25.2.2 Properties

Name	Description
X	
Inherited from object	
class	

#### 25.2.3 Instance Variables

Name	Description
range	Holds the range for the estimates. If this at-
	tribute is set, the algorithm will never let the
	estimates fall outside the given interval.

# 25.3 Class Interpolation

```
object —
peach.optm.base.Optimizer —
peach.optm.linear.Interpolation
```

Optimization by quadractic interpolation.

This methods takes three estimates and finds the parabolic function that fits them, and returns as a new estimate the vertex of the parabola. The procedure can be repeated until a good approximation is found.

#### 25.3.1 Methods

\_init\_\_(self, f, x0, emax=1e-08, imax=1000)

Initializes the optimizer.

To create an optimizer of this type, instantiate the class with the parameters given below: **Parameters** 

- f: A one variable only function to be optimized. The function should have only one parameter and return the function value.
- x0: First estimate of the minimum. The interpolation search needs three estimates to approximate the parabolic function. Thus, the first estimate must be a triple (x1, xm, xh), with the property that x1 < xm < xh. Be aware, however, that no checking is done -- if the estimate doesn't correspond to this condition, in some point an exception will be raised.</p>

Notice that, given the nature of the estimate of the interpolation method, it is not necessary to have a specific parameter to restrict the range of acceptable values — it is already embedded in the estimate. If you need to restrict your estimate between an interval, just use its limits as x1 and xh in the estimate.

emax: Maximum allowed error. The algorithm stops as soon as the error is below this level. The error is absolute.

imax: Maximum number of iterations, the algorithm stops as soon this number of iterations are executed, no matter what the error is at the moment.

Overrides: object.\_\_init\_\_

#### $\mathbf{restart}(self, x\theta)$

Resets the optimizer, returning to its original state, and allowing to use a new first estimate. **Parameters** 

x0: The new initial value of the estimate of the minimum. The interpolation search needs three estimates to approximate the parabolic function. Thus, the estimate must be a triple (x1, xm, xh), with the property that x1 < xm < xh. Be aware, however, that no checking is done -- if the estimate doesn't correspond to this condition, in some point an exception will be raised.</p>

## step(self)

One step of the search.

In this method, the result of the step is dependent only of the given estimated, so it can be used for different kind of investigations on the same cost function.

### Return Value

This method returns a tuple (x, e), where x is the updated triplet of estimates of the minimum, and e is the estimated error.

Overrides: peach.optm.base.Optimizer.step

### $\_$ call $\_$ (self)

Transparently executes the search until the minimum is found. The stop criteria are the maximum error or the maximum number of iterations, whichever is reached first. Note that this is a \_\_call\_\_ method, so the object is called as a function. This method returns a tuple (x, e), with the best estimate of the minimum and the error. Return Value

This method returns a tuple (x, e), where x is the best estimate of the minimum, and e is the estimated error.

Overrides: peach.optm.base.Optimizer.\_\_call\_\_

### Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

#### 25.3.2 Properties

Name	Description
X	
Inherited from object	
class	

# 25.4 Class GoldenRule

object —	
peach.optm.base.Optimizer	
	peach.optm.linear.GoldenRule

Optimizer by the Golden Section Rule

This optimizer uses the golden rule to section an interval in search of the minimum. Using a simple heuristic, the interval is refined until an interval small enough to satisfy the error requirements is found.

#### 25.4.1 Methods

 $_{-init_{--}}(self, f, x0, emax=1e-08, imax=1000)$ 

Initializes the optimizer.

To create an optimizer of this type, instantiate the class with the parameters given below: **Parameters** 

- f: A one variable only function to be optimized. The function should have only one parameter and return the function value.
- x0: First estimate of the minimum. The golden rule search needs two estimates to partition the interval. Thus, the first estimate must be a duple (x1, xh), with the property that x1 < xh. Be aware, however, that no checking is done -- if the estimate doesn't correspond to this condition, in some point an exception will be raised.</li>

Notice that, given the nature of the estimate of the golden rule method, it is not necessary to have a specific parameter to restrict the range of acceptable values -- it is already embedded in the estimate. If you need to restrict your estimate between an interval, just use its limits as xl and xh in the estimate.

emax: Maximum allowed error. The algorithm stops as soon as the error is below this level. The error is absolute.

imax: Maximum number of iterations, the algorithm stops as soon this number of iterations are executed, no matter what the error is at the moment.

Overrides: object.\_\_init\_\_

#### $\mathbf{restart}(self, x\theta)$

Resets the optimizer, returning to its original state, and allowing to use a new first estimate. **Parameters** 

x0: The new value of the estimate of the minimum. The golden rule search needs two estimates to partition the interval. Thus, the estimate must be a duple (x1, xh), with the property that x1 < xh.</p>

## step(self)

One step of the search.

In this method, the result of the step is dependent only of the given estimated, so it can be used for different kind of investigations on the same cost function.

### Return Value

This method returns a tuple (x, e), where x is the updated duple of estimates of the minimum, and e is the estimated error.

Overrides: peach.optm.base.Optimizer.step

## $\_$ call $\_$ (self)

Transparently executes the search until the minimum is found. The stop criteria are the maximum error or the maximum number of iterations, whichever is reached first. Note that this is a \_\_call\_\_ method, so the object is called as a function. This method returns a tuple (x, e), with the best estimate of the minimum and the error. Return Value

This method returns a tuple (x, e), where x is the best estimate of the minimum, and e is the estimated error.

Overrides: peach.optm.base.Optimizer.\_\_call\_\_

# Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

#### 25.4.2 Properties

Name	Description
X	
Inherited from object	
class	

# 25.5 Class Fibonacci



Optimization by the Golden Rule Section, estimated by Fibonacci numbers.

This optimizer uses the golden rule to section an interval in search of the minimum. Using a simple heuristic, the interval is refined until an interval small enough to satisfy the error requirements is found. The golden section is estimated at each step using Fibonacci numbers. This can be useful in situations where only integer numbers should be used.

#### 25.5.1 Methods

\_init\_\_(self, f, x0, emax=1e-08, imax=1000)

Initializes the optimizer.

To create an optimizer of this type, instantiate the class with the parameters given below: **Parameters** 

- f: A one variable only function to be optimized. The function should have only one parameter and return the function value.
- x0: First estimate of the minimum. The Fibonacci search needs two estimates to partition the interval. Thus, the first estimate must be a duple (x1, xh), with the property that x1 < xh. Be aware, however, that no checking is done -- if the estimate doesn't correspond to this condition, in some point an exception will be raised.</p>

Notice that, given the nature of the estimate of the Fibonacci method, it is not necessary to have a specific parameter to restrict the range of acceptable values — it is already embedded in the estimate. If you need to restrict your estimate between an interval, just use its limits as xl and xh in the estimate.

emax: Maximum allowed error. The algorithm stops as soon as the error is below this level. The error is absolute.

imax: Maximum number of iterations, the algorithm stops as soon this number of iterations are executed, no matter what the error is at the moment.

Overrides: object.\_\_init\_\_

#### $\mathbf{restart}(self, x\theta)$

Resets the optimizer, returning to its original state, and allowing to use a new first estimate. **Parameters** 

x0: The new value of the estimate of the minimum. The Fibonacci search needs two estimates to partition the interval. Thus, the estimate must be a duple (x1, xh), with the property that x1 < xh. Be aware, however, that no checking is done -- if the estimate doesn't correspond to this condition, in some point an exception will be raised.</li>

# step(self)

One step of the search.

In this method, the result of the step is highly dependent of the steps executed before, as the estimate of the golden ratio is updated at each call to this method. **Return Value** 

This method returns a tuple (x, e), where x is the updated duple of estimates of the minimum, and e is the estimated error.

Overrides: peach.optm.base.Optimizer.step

### $\_$ call $\_$ (self)

Transparently executes the search until the minimum is found. The stop criteria are the maximum error or the maximum number of iterations, whichever is reached first. Note that this is a \_\_call\_\_ method, so the object is called as a function. This method returns a tuple (x, e), with the best estimate of the minimum and the error. Return Value

This method returns a tuple (x, e), where x is the best estimate of the minimum, and e is the estimated error.

Overrides: peach.optm.base.Optimizer.\_\_call\_\_

### Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

#### 25.5.2 Properties

Name	Description
Inherited from object	
_class	

# 26 Module peach.optm.multivar

This package implements basic multivariable optimizers, including gradient and Newton searches.

# 26.1 Variables

Name	Description
doc	Value:
package	Value: 'peach.optm'

### 26.2 Class Direct

Multidimensional direct search

This optimization method is a generalization of the 1D method, using variable swap as search direction. This results in a very simplistic and inefficient method that should be used only when any other method fails.

#### 26.2.1 Methods

\_init\_\_(self, f, x0, ranges=None, h=0.5, emax=1e-08, imax=1000)

Initializes the optimizer.

To create an optimizer of this type, instantiate the class with the parameters given below: **Parameters** 

f: A multivariable function to be optimized. The function should have only one parameter, a multidimensional line-vector, and return the function value, a scalar.

x0: First estimate of the minimum. Estimates can be given in any format, but internally they are converted to a one-dimension vector, where each component corresponds to the estimate of that particular variable. The vector is computed by flattening the array.

ranges: A range of values might be passed to the algorithm, but it is not necessary. If supplied, this parameter should be a list of ranges for each variable of the objective function. It is specified as a list of tuples of two values, (x0, x1), where x0 is the start of the interval, and x1 its end. Obviously, x0 should be smaller than x1. It can also be given as a list with a simple tuple in the same format. In that case, the same range will be applied for every variable in the optimization.

h: The initial step of the search. Defaults to 0.5

emax: Maximum allowed error. The algorithm stops as soon as the error is below this level. The error is absolute.

imax: Maximum number of iterations, the algorithm stops as soon this number of iterations are executed, no matter what the error is at the moment.

Overrides: object.\_\_init\_\_

## $\mathbf{restart}(self, x0, h=0.5)$

Resets the optimizer, returning to its original state, and allowing to use a new first estimate. **Parameters** 

x0: New estimate of the minimum. Estimates can be given in any format, but internally they are converted to a one-dimension vector, where each component corresponds to the estimate of that particular variable. The vector is computed by flattening the array.

h: The initial step of the search. Defaults to 0.5

### step(self)

One step of the search.

In this method, the result of the step is highly dependent of the steps executed before, as the search step is updated at each call to this method. **Return Value** 

This method returns a tuple (x, e), where x is the updated estimate of the minimum, and e is the estimated error.

Overrides: peach.optm.base.Optimizer.step

#### $_{-}$ call $_{-}$ (self)

Transparently executes the search until the minimum is found. The stop criteria are the maximum error or the maximum number of iterations, whichever is reached first. Note that this is a \_\_call\_\_ method, so the object is called as a function. This method returns a tuple (x, e), with the best estimate of the minimum and the error. Return Value

This method returns a tuple (x, e), where x is the best estimate of the minimum, and e is the estimated error.

Overrides: peach.optm.base.Optimizer.\_\_call\_\_

# Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

#### 26.2.2 Properties

Name	Description
X	
Inherited from object	
class	

#### 26.2.3 Instance Variables

Name	Description
ranges	Holds the ranges for every variable. Although it
	is a writable property, care should be taken in
	changing parameters before ending the conver-
	gence.

# 26.3 Class Gradient

object —
peach.optm.base.Optimizer —
peach.optm.multivar.Gradient

### Gradient search

This method uses the fact that the gradient of a function points to the direction of largest increase in the function (in general called uphill direction). So, the contrary direction (down-hill) is used as search direction.

#### 26.3.1 Methods

 $\_init\_(self, f, x0, ranges = None, df = None, h = 0.1, emax = 1e - 05, imax = 1000)$ 

Initializes the optimizer.

To create an optimizer of this type, instantiate the class with the parameters given below: **Parameters** 

f: A multivariable function to be optimized. The function should have only one parameter, a multidimensional line-vector, and return the function value, a scalar.

x0: First estimate of the minimum. Estimates can be given in any format, but internally they are converted to a one-dimension vector, where each component corresponds to the estimate of that particular variable. The vector is computed by flattening the array.

ranges: A range of values might be passed to the algorithm, but it is not necessary. If supplied, this parameter should be a list of ranges for each variable of the objective function. It is specified as a list of tuples of two values, (x0, x1), where x0 is the start of the interval, and x1 its end. Obviously, x0 should be smaller than x1. It can also be given as a list with a simple tuple in the same format. In that case, the same range will be applied for every variable in the optimization.

df: A function to calculate the gradient vector of the cost function f. Defaults to None, if no gradient is supplied, then it is estimated from the cost function using Euler equations.

h: Convergence step. This method does not takes into consideration the possibility of varying the convergence step, to avoid Stiefel cages.

emax: Maximum allowed error. The algorithm stops as soon as the error is below this level. The error is absolute.

imax: Maximum number of iterations, the algorithm stops as soon this number of iterations are executed, no matter what the error is at the moment.

Overrides: object.\_\_init\_\_

## $\mathbf{restart}(\mathit{self}, x\theta, h = \mathtt{None})$

Resets the optimizer, returning to its original state, and allowing to use a new first estimate. **Parameters** 

- x0: New estimate of the minimum. Estimates can be given in any format, but internally they are converted to a one-dimension vector, where each component corresponds to the estimate of that particular variable. The vector is computed by flattening the array.
- h: Convergence step. This method does not takes into consideration the possibility of varying the convergence step, to avoid Stiefel cages.

### step(self)

One step of the search.

In this method, the result of the step is dependent only of the given estimated, so it can be used for different kind of investigations on the same cost function.

#### Return Value

This method returns a tuple (x, e), where x is the updated estimate of the minimum, and e is the estimated error.

Overrides: peach.optm.base.Optimizer.step

### $_{-}$ call $_{-}$ (self)

Transparently executes the search until the minimum is found. The stop criteria are the maximum error or the maximum number of iterations, whichever is reached first. Note that this is a \_\_call\_\_ method, so the object is called as a function. This method returns a tuple (x, e), with the best estimate of the minimum and the error. Return Value

This method returns a tuple (x, e), where x is the best estimate of the minimum, and e is the estimated error.

Overrides: peach.optm.base.Optimizer.\_call\_\_

# Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

### 26.3.2 Properties

Name	Description
X	
Inherited from object	
class	

#### 26.3.3 Instance Variables

Name	Description
ranges	Holds the ranges for every variable. Although it
	is a writable property, care should be taken in changing parameters before ending the convergence.

### 26.4 Class MomentumGradient



#### Gradient search with momentum

This method uses the fact that the gradient of a function points to the direction of largest increase in the function (in general called *uphill* direction). So, the contrary direction (*downhill*) is used as search direction. A momentum term is added to avoid local minima.

#### 26.4.1 Methods

 $\_$ init $\_$ (self, f, x0, ranges=None, df=None, h=0.1, a=0.1, emax=1e-05, imax=1000)

Initializes the optimizer.

To create an optimizer of this type, instantiate the class with the parameters given below: **Parameters** 

- f: A multivariable function to be optimized. The function should have only one parameter, a multidimensional line-vector, and return the function value, a scalar.
- x0: First estimate of the minimum. Estimates can be given in any format, but internally they are converted to a one-dimension vector, where each component corresponds to the estimate of that particular variable. The vector is computed by flattening the array.
- ranges: A range of values might be passed to the algorithm, but it is not necessary. If supplied, this parameter should be a list of ranges for each variable of the objective function. It is specified as a list of tuples of two values, (x0, x1), where x0 is the start of the interval, and x1 its end. Obviously, x0 should be smaller than x1. It can also be given as a list with a simple tuple in the same format. In that case, the same range will be applied for every variable in the optimization.
- df: A function to calculate the gradient vector of the cost function f. Defaults to None, if no gradient is supplied, then it is estimated from the cost function using Euler equations.
- h: Convergence step. This method does not takes into consideration the possibility of varying the convergence step, to avoid Stiefel cages. Defaults to 0.1.
- a: Momentum term. This term is a measure of the memory of the optmizer. The bigger it is, the more the past values influence in the outcome of the optimization. Defaults to 0.1
- emax: Maximum allowed error. The algorithm stops as soon as the error is below this level. The error is absolute.
- imax: Maximum number of iterations, the algorithm stops as soon this number of iterations are executed, no matter what the error is at the moment.

Overrides: object.\_\_init\_\_

### restart(self, x0, h=None, a=None)

Resets the optimizer, returning to its original state, and allowing to use a new first estimate. **Parameters** 

- x0: New estimate of the minimum. Estimates can be given in any format, but internally they are converted to a one-dimension vector, where each component corresponds to the estimate of that particular variable. The vector is computed by flattening the array.
- h: Convergence step. This method does not takes into consideration the possibility of varying the convergence step, to avoid Stiefel cages. If not given in this method, the old value is used.
- a: Momentum term. This term is a measure of the memory of the optimizer. The bigger it is, the more the past values influence in the outcome of the optimization. If not given in this method, the old value is used.

# step(self)

One step of the search.

In this method, the result of the step is dependent only of the given estimated, so it can be used for different kind of investigations on the same cost function.

#### Return Value

This method returns a tuple (x, e), where x is the updated estimate of the minimum, and e is the estimated error.

Overrides: peach.optm.base.Optimizer.step

### $\_$ call $\_$ (self)

Transparently executes the search until the minimum is found. The stop criteria are the maximum error or the maximum number of iterations, whichever is reached first. Note that this is a \_\_call\_\_ method, so the object is called as a function. This method returns a tuple (x, e), with the best estimate of the minimum and the error. Return Value

This method returns a tuple (x, e), where x is the best estimate of the minimum, and e is the estimated error.

Overrides: peach.optm.base.Optimizer.\_\_call\_\_

# Inherited from object

#### 26.4.2 Properties

Name	Description
X	
Inherited from object	
class	

#### 26.4.3 Instance Variables

Name	Description
ranges	Holds the ranges for every variable. Although it
	is a writable property, care should be taken in
	changing parameters before ending the conver-
	gence.

#### 26.5 Class Newton

#### Newton search

This is a very effective method to find minimum points in functions. In a very basic fashion, this method corresponds to using Newton root finding method on f'(x). Converges *very* fast if the cost function is quadratic of similar to it.

#### 26.5.1 Methods

 $\_$ init $\_$ (self, f,  $x\theta$ , ranges=None, df=None, hf=None, h=0.1, emax=1e-05, imax=1000)

Initializes the optimizer.

To create an optimizer of this type, instantiate the class with the parameters given below: **Parameters** 

- f: A multivariable function to be optimized. The function should have only one parameter, a multidimensional line-vector, and return the function value, a scalar.
- x0: First estimate of the minimum. Estimates can be given in any format, but internally they are converted to a one-dimension vector, where each component corresponds to the estimate of that particular variable. The vector is computed by flattening the array.
- ranges: A range of values might be passed to the algorithm, but it is not necessary. If supplied, this parameter should be a list of ranges for each variable of the objective function. It is specified as a list of tuples of two values, (x0, x1), where x0 is the start of the interval, and x1 its end. Obviously, x0 should be smaller than x1. It can also be given as a list with a simple tuple in the same format. In that case, the same range will be applied for every variable in the optimization.
- df: A function to calculate the gradient vector of the cost function f. Defaults to None, if no gradient is supplied, then it is estimated from the cost function using Euler equations.
- hf: A function to calculate the hessian matrix of the cost function f. Defaults to None, if no hessian is supplied, then it is estimated from the cost function using Euler equations.
- h: Convergence step. This method does not takes into consideration the possibility of varying the convergence step, to avoid Stiefel cages.
- emax: Maximum allowed error. The algorithm stops as soon as the error is below this level. The error is absolute.
- imax: Maximum number of iterations, the algorithm stops as soon this number of iterations are executed, no matter what the error is at the moment.

Overrides: object.\_\_init\_\_

## restart(self, x0, h=None)

Resets the optimizer, returning to its original state, and allowing to use a new first estimate. **Parameters** 

- x0: New estimate of the minimum. Estimates can be given in any format, but internally they are converted to a one-dimension vector, where each component corresponds to the estimate of that particular variable. The vector is computed by flattening the array.
- h: Convergence step. This method does not takes into consideration the possibility of varying the convergence step, to avoid Stiefel cages.

## step(self)

One step of the search.

In this method, the result of the step is dependent only of the given estimated, so it can be used for different kind of investigations on the same cost function.

#### Return Value

This method returns a tuple (x, e), where x is the updated estimate of the minimum, and e is the estimated error.

Overrides: peach.optm.base.Optimizer.step

### $_{-}$ call $_{-}$ (self)

Transparently executes the search until the minimum is found. The stop criteria are the maximum error or the maximum number of iterations, whichever is reached first. Note that this is a \_\_call\_\_ method, so the object is called as a function. This method returns a tuple (x, e), with the best estimate of the minimum and the error. Return Value

This method returns a tuple (x, e), where x is the best estimate of the minimum, and e is the estimated error.

Overrides: peach.optm.base.Optimizer.\_call\_\_

## Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

# 26.5.2 Properties

Name	Description
X	
Inherited from object	
class	

## 26.5.3 Instance Variables

Name	Description
ranges	Holds the ranges for every variable. Although it
	is a writable property, care should be taken in changing parameters before ending the conver-
	changing parameters before ending the conver-
	gence.

# 27 Module peach.optm.quasinewton

This package implements basic quasi-Newton optimizers. Newton optimizer is very efficient, except that inverse matrices need to be calculated at each convergence step. These methods try to estimate the hessian inverse iteratively, thus increasing performance.

### 27.1 Variables

Name	Description
doc	Value:
package	Value: 'peach.optm'

### 27.2 Class DFP

```
object —
peach.optm.base.Optimizer —
peach.optm.quasinewton.DFP
```

DFP (Davidon-Fletcher-Powell) search

#### **27.2.1** Methods

\_\_init\_\_(self, f, x0, ranges=None, df=None, h=0.1, emax=1e-08, imax=1000)

Initializes the optimizer.

To create an optimizer of this type, instantiate the class with the parameters given below: **Parameters** 

f: A multivariable function to be optimized. The function should have only one parameter, a multidimensional line-vector, and return the function value, a scalar.

x0: First estimate of the minimum. Estimates can be given in any format, but internally they are converted to a one-dimension vector, where each component corresponds to the estimate of that particular variable. The vector is computed by flattening the array.

ranges: A range of values might be passed to the algorithm, but it is not necessary. If supplied, this parameter should be a list of ranges for each variable of the objective function. It is specified as a list of tuples of two values, (x0, x1), where x0 is the start of the interval, and x1 its end. Obviously, x0 should be smaller than x1. It can also be given as a list with a simple tuple in the same format. In that case, the same range will be applied for every variable in the optimization.

df: A function to calculate the gradient vector of the cost function f. Defaults to None, if no gradient is supplied, then it is estimated from the cost function using Euler equations.

h: Convergence step. This method does not takes into consideration the possibility of varying the convergence step, to avoid Stiefel cages.

emax: Maximum allowed error. The algorithm stops as soon as the error is below this level. The error is absolute.

imax: Maximum number of iterations, the algorithm stops as soon this number of iterations are executed, no matter what the error is at the moment.

Overrides: object.\_\_init\_\_

## restart(self, x0, h=None)

Resets the optimizer, returning to its original state, and allowing to use a new first estimate. **Parameters** 

- x0: New estimate of the minimum. Estimates can be given in any format, but internally they are converted to a one-dimension vector, where each component corresponds to the estimate of that particular variable. The vector is computed by flattening the array.
- h: Convergence step. This method does not takes into consideration the possibility of varying the convergence step, to avoid Stiefel cages.

## step(self)

One step of the search.

In this method, the result of the step is dependent of parameters calculated before (namely, the estimate of the inverse hessian), so it is not recomended that different investigations are used with the same optimizer in the same cost function. **Return Value** 

This method returns a tuple (x, e), where x is the updated estimate of the minimum, and e is the estimated error.

Overrides: peach.optm.base.Optimizer.step

### $_{-}$ call $_{-}$ (self)

Transparently executes the search until the minimum is found. The stop criteria are the maximum error or the maximum number of iterations, whichever is reached first. Note that this is a \_\_call\_\_ method, so the object is called as a function. This method returns a tuple (x, e), with the best estimate of the minimum and the error. Return Value

This method returns a tuple (x, e), where x is the best estimate of the minimum, and e is the estimated error.

Overrides: peach.optm.base.Optimizer.\_\_call\_\_

### Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

## 27.2.2 Properties

Name	Description
X	
Inherited from object	
class	

### 27.2.3 Instance Variables

Name	Description
ranges	Holds the ranges for every variable. Although it
	is a writable property, care should be taken in
	changing parameters before ending the conver-
	gence.

### 27.3 Class BFGS

object —  $\begin{array}{c} \text{object } -\\ \text{peach.optm.base.Optimizer } -\\ \text{peach.optm.quasinewton.BFGS} \end{array}$ 

BFGS  $(Broyden ext{-}Fletcher ext{-}Goldfarb ext{-}Shanno)$  search

### **27.3.1** Methods

\_\_init\_\_(self, f, x0, ranges=None, df=None, h=0.1, emax=1e-05, imax=1000)

Initializes the optimizer.

To create an optimizer of this type, instantiate the class with the parameters given below: **Parameters** 

f: A multivariable function to be optimized. The function should have only one parameter, a multidimensional line-vector, and return the function value, a scalar.

x0: First estimate of the minimum. Estimates can be given in any format, but internally they are converted to a one-dimension vector, where each component corresponds to the estimate of that particular variable. The vector is computed by flattening the array.

ranges: A range of values might be passed to the algorithm, but it is not necessary. If supplied, this parameter should be a list of ranges for each variable of the objective function. It is specified as a list of tuples of two values, (x0, x1), where x0 is the start of the interval, and x1 its end. Obviously, x0 should be smaller than x1. It can also be given as a list with a simple tuple in the same format. In that case, the same range will be applied for every variable in the optimization.

df: A function to calculate the gradient vector of the cost function f. Defaults to None, if no gradient is supplied, then it is estimated from the cost function using Euler equations.

h: Convergence step. This method does not takes into consideration the possibility of varying the convergence step, to avoid Stiefel cages.

emax: Maximum allowed error. The algorithm stops as soon as the error is below this level. The error is absolute.

imax: Maximum number of iterations, the algorithm stops as soon this number of iterations are executed, no matter what the error is at the moment.

Overrides: object.\_\_init\_\_

## $\mathbf{restart}(\mathit{self}, x\theta, h = \mathtt{None})$

Resets the optimizer, returning to its original state, and allowing to use a new first estimate. **Parameters** 

- x0: New estimate of the minimum. Estimates can be given in any format, but internally they are converted to a one-dimension vector, where each component corresponds to the estimate of that particular variable. The vector is computed by flattening the array.
- h: Convergence step. This method does not takes into consideration the possibility of varying the convergence step, to avoid Stiefel cages.

## step(self)

One step of the search.

In this method, the result of the step is dependent of parameters calculated before (namely, the estimate of the inverse hessian), so it is not recomended that different investigations are used with the same optimizer in the same cost function. **Return Value** 

This method returns a tuple (x, e), where x is the updated estimate of the minimum, and e is the estimated error.

Overrides: peach.optm.base.Optimizer.step

### $_{-}$ call $_{-}$ (self)

Transparently executes the search until the minimum is found. The stop criteria are the maximum error or the maximum number of iterations, whichever is reached first. Note that this is a \_\_call\_\_ method, so the object is called as a function. This method returns a tuple (x, e), with the best estimate of the minimum and the error. Return Value

This method returns a tuple (x, e), where x is the best estimate of the minimum, and e is the estimated error.

Overrides: peach.optm.base.Optimizer.\_\_call\_\_

### Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

## 27.3.2 Properties

Name	Description
Inherited from object	
_class_	

### 27.3.3 Instance Variables

Name	Description
ranges	Holds the ranges for every variable. Although it
	is a writable property, care should be taken in
	changing parameters before ending the conver-
	gence.

## 27.4 Class SR1

object —  $\begin{array}{c} \text{peach.optm.base.Optimizer} & - \\ & \text{peach.optm.quasinewton.SR1} \end{array}$ 

SR1 (Symmetric Rank 1 ) search method

#### 27.4.1 Methods

\_\_init\_\_(self, f, x0, ranges=None, df=None, h=0.1, emax=1e-05, imax=1000)

Initializes the optimizer.

To create an optimizer of this type, instantiate the class with the parameters given below: **Parameters** 

f: A multivariable function to be optimized. The function should have only one parameter, a multidimensional line-vector, and return the function value, a scalar.

x0: First estimate of the minimum. Estimates can be given in any format, but internally they are converted to a one-dimension vector, where each component corresponds to the estimate of that particular variable. The vector is computed by flattening the array.

ranges: A range of values might be passed to the algorithm, but it is not necessary. If supplied, this parameter should be a list of ranges for each variable of the objective function. It is specified as a list of tuples of two values, (x0, x1), where x0 is the start of the interval, and x1 its end. Obviously, x0 should be smaller than x1. It can also be given as a list with a simple tuple in the same format. In that case, the same range will be applied for every variable in the optimization.

df: A function to calculate the gradient vector of the cost function f. Defaults to None, if no gradient is supplied, then it is estimated from the cost function using Euler equations.

h: Convergence step. This method does not takes into consideration the possibility of varying the convergence step, to avoid Stiefel cages.

emax: Maximum allowed error. The algorithm stops as soon as the error is below this level. The error is absolute.

imax: Maximum number of iterations, the algorithm stops as soon this number of iterations are executed, no matter what the error is at the moment.

Overrides: object.\_\_init\_\_

## $\mathbf{restart}(\mathit{self}, x\theta, h = \mathtt{None})$

Resets the optimizer, returning to its original state, and allowing to use a new first estimate. **Parameters** 

- x0: New estimate of the minimum. Estimates can be given in any format, but internally they are converted to a one-dimension vector, where each component corresponds to the estimate of that particular variable. The vector is computed by flattening the array.
- h: Convergence step. This method does not takes into consideration the possibility of varying the convergence step, to avoid Stiefel cages.

## step(self)

One step of the search.

In this method, the result of the step is dependent of parameters calculated before (namely, the estimate of the inverse hessian), so it is not recomended that different investigations are used with the same optimizer in the same cost function. **Return Value** 

This method returns a tuple (x, e), where x is the updated estimate of the minimum, and e is the estimated error.

Overrides: peach.optm.base.Optimizer.step

### $_{-}$ call $_{-}$ (self)

Transparently executes the search until the minimum is found. The stop criteria are the maximum error or the maximum number of iterations, whichever is reached first. Note that this is a \_\_call\_\_ method, so the object is called as a function. This method returns a tuple (x, e), with the best estimate of the minimum and the error. Return Value

This method returns a tuple (x, e), where x is the best estimate of the minimum, and e is the estimated error.

Overrides: peach.optm.base.Optimizer.\_\_call\_\_

### Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

# 27.4.2 Properties

Name	Description
X	
Inherited from object	
class	

## 27.4.3 Instance Variables

Name	Description
ranges	Holds the ranges for every variable. Although it
	is a writable property, care should be taken in
	changing parameters before ending the conver-
	gence.

# 28 Module peach.optm.stochastic

#### 28.1 Variables

Name	Description
doc	Value:

## 28.2 Class CrossEntropy

peach.optm.Optimizer -

## peach.optm.stochastic.CrossEntropy

Multidimensional search based on cross-entropy technique.

In cross-entropy, a set of N possible solutions is randomly generated at each interaction. To converge the solutions, the best M solutions are selected and its statistics are calculated. A new set of solutions are randomly generated from these statistics.

#### 28.2.1 Methods

 $\_init\_(self, f, M=30, N=60, emax=1e-8, imax=1000)$ 

Initializes the optimizer.

To create an optimizer of this type, instantiate the class with the parameters given below: **Parameters** 

- f: A multivariable function to be optimized. The function should have only one parameter, a multidimensional line-vector, and return the function value, a scalar.
- M: Size of the solution set used to calculate the statistics to generate the next set of solutions
- N: Total size of the solution set.
- emax: Maximum allowed error. The algorithm stops as soon as the error is below this level. The error is absolute.
- imax: Maximum number of iterations, the algorithm stops as soon this number of iterations are executed, no matter what the error is at the moment.

# step(self)

One step of the search ( $NOT\ IMPLEMENTED\ YET$ )

In this method, the solution set is searched for the M best solutions. Mean and variance of these solutions is calculated, and these values are used to randomly generate, from a gaussian distribution, a set of N new solutions.

# 29 Package peach.pso

Basic Particle Swarm Optimization (PSO)

This sub-package implements traditional particle swarm optimizers as described in literature. It consists of a very simple algorithm emulating the behaviour of a flock of birds (though in a very simplified way). A population of particles is created, each particle with its corresponding velocity. They fly towards the particle local best and the swarm global best, thus exploring the whole domain.

For consistency purposes, the particles are represented internally as a list of vectors. The particles can be accessed externally by using the [ ] interface. See the rest of the documentation for more information.

### 29.1 Modules

- acc: Functions to update the velocity (ie, accelerate) of the particles in a swarm. (Section 30, p. 188)
- base: This package implements the simple continuous version of the particle swarm optimizer. In this implementation, it is possible to specify, besides the objective function and the first estimates, the ranges of search, which will influence the max velocity of the particles, and the population size. Other parameters are available too, please refer to the rest of this documentation for further details. (Section 31, p. 192)

# 30 Module peach.pso.acc

Functions to update the velocity (ie, accelerate) of the particles in a swarm.

Acceleration of a particle is an important concept in the theory of particle swarm optimizers. By choosing an adequate acceleration, particle velocity is changed so that they can search the domain of definition of the objective function such that there is a greater probability that a global minimum is found. Since particle swarm optimizers are derived from genetic algorithms, it can be said that this is what creates diversity in a swarm, such that the space is more thoroughly searched.

### 30.1 Variables

Name	Description
doc	Value:
_package_	Value: 'peach.pso'

#### 30.2 Class Accelerator

object — peach.pso.acc.Accelerator

Known Subclasses: peach.pso.acc.StandardPSO

Base class for accelerators.

This class should be derived to implement a function which computes the acceleration of a vector of particles in a swarm. Every accelerator function should implement at least two methods, defined below:

\_\_init\_\_(self, \*cnf, \*\*kw) Initializes the object. There are no mandatory arguments, but any parameters can be used here to configure the operator. For example, a class can define a variance for randomly chose the acceleration -- this should be defined here:

```
__init__(self, variance=1.0)
```

A default value should always be offered, if possible.

\_\_call\_\_(self, v): The \_\_call\_\_ interface should be programmed to actually compute the new velocity of a vector of particles. This method should receive a velocity in v and use whatever parameters from the instantiation to compute the new velocities. Notice that this function should operate over a vector of

velocities, not on a single velocity. This class, however, can be instantiated with a single function that is adapted to perform over a vector.

#### **30.2.1** Methods

 $\_$ **init** $\_$ (self, f)

Initializes an accelerator object.

This method initializes an accelerator. It receives as argument a simple function that is adapted to operate over a vector of velocities. **Parameters** 

f: The function to be used as acceleration. This function can be simple function that receives a n-dimensional vector representing the velocity of a single particle, where n is the dimensionality of the objective function. The object then wraps the function such that it can receive a list of velocities and applies the acceleration on every one of them.

Overrides: object.\_\_init\_\_

 $\_$ call $\_$ (self, v)

Computes new velocities for every particle.

This method should be overloaded in implementations of different accelerators. This method receives the velocities as a list or a vector of the velocities (a n-dimensional vector in each line) or each particle in a swarm and computes, for each one of them, a new velocity. **Parameters** 

v: A list or a vector of velocities, where each velocity is one line of the vector or one element of the list.

#### Return Value

A vector of the same size as the argument with the updated velocities. The returned vector is returned as a bidimensional array.

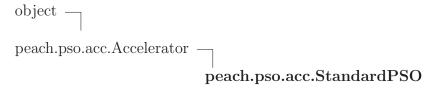
#### Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

#### 30.2.2 Properties

Name	Description
Inherited from object	
class	

### 30.3 Class StandardPSO



Standard PSO Accelerator

This class implements a method for changing the velocities of particles in a particle swarm. The standard way is to retain information on local bests and the global bests, and update the velocity based on that.

#### 30.3.1 Methods

 $cinit_{-}(self, ps, vmax=None, cp=2.05, cq=2.05)$ 

Initializes the accelerator. Parameters

- ps: A reference to the Particle Swarm that should be updated. This class, in instantiation, will assume that the position of the particles in the moment of creation are the local best. The objective function is computed for all particles, and the values saved for reference in the future. Also, at the same time, the global best is computed.
- cp: The velocity adjustment constant associated with the particle best values. Defaults to 2.05.
- cg: The velocity adjustment constant associated with the global best values. Defaults to 2.05. The defaults in the cp and cg parameters are such that the inertia weight in the constrition method satisfies cp + cg > 4. Please, look in the bibliography for more information.

Overrides: object.\_\_init\_\_

call	(self.	v)
	(000)	~ /

Computes the new velocities for every particle in the swarm. This method receives the velocities as a list or a vector of the velocities (a n-dimensional vector in each line) or each particle in a swarm and computes, for each one of them, a new velocity. **Parameters** 

v: A list or a vector of velocities, where each velocity is one line of the vector or one element of the list.

### Return Value

A vector of the same size as the argument with the updated velocities. The returned vector is returned as a bidimensional array.

Overrides: peach.pso.acc.Accelerator.\_\_call\_\_

## Inherited from object

### 30.3.2 Properties

Name	Description
Inherited from object	
class	

#### 30.3.3 Instance Variables

Name	Description		
ср	Velocity adjustment constant associated with the		
	particle best values.		
cg	Velocity adjustment constant associated with the		
	global best values.		

# 31 Module peach.pso.base

This package implements the simple continuous version of the particle swarm optimizer. In this implementation, it is possible to specify, besides the objective function and the first estimates, the ranges of search, which will influence the max velocity of the particles, and the population size. Other parameters are available too, please refer to the rest of this documentation for further details.

#### 31.1 Variables

Name	Description
doc	Value:
package	Value: 'peach.pso'
abs	Value: <ufunc 'absolute'=""></ufunc>
sign	Value: <ufunc 'sign'=""></ufunc>
sqrt	Value: <ufunc 'sqrt'=""></ufunc>

## 31.2 Class ParticleSwarmOptimizer



Known Subclasses: peach.pso.base.PSO

A standard Particle Swarm Optimizer

This class implements a particle swarm optimization (PSO) procedure. A swarm is a list of estimates, and should answer to every list method. A population of particles is created to travel through the search domain with a certain velocity. At each point, the objective function is evaluated for each particle, and the positions are adjusted correspondingly. The velocity is then modified (ie, the particles are accelerated) towards its 'personal' best (the best value found by that particle at the moment) and a global best (the best value found overall at the moment).

#### 31.2.1Methods

\_init\_\_(self, f, x0, ranges=None, accelerator=<class 'peach.pso.acc.StandardPSO'>, emax=1e-05, imax=1000)

Initializes the optimizer. Parameters

A multivariable function to be evaluated. It must

receive only one parameter, a multidimensional line-vector with the same dimensions of the range list

(see below) and return a real value, a scalar.

x0: A population of first estimates. This is a list, array or

tuple of one-dimension arrays, each one

corresponding to an estimate of the position of the minimum. The population size of the algorithm will be the same as the number of estimates in this list. Each component of the vectors in this list are one of

the variables in the function to be optimized.

A range of values might be passed to the algorithm, ranges:

but it is not necessary. If this parameter is not supplied, then the ranges will be computed from the estimates, but be aware that this might not represent

the complete search space. If supplied, this

parameter should be a list of ranges for each variable of the objective function. It is specified as a list of tuples of two values, (x0, x1), where x0 is the start of the interval, and x1 its end. Obviously, x0 should be smaller than x1. It can also be given as a list with a simple tuple in the same format. In that case, the same range will be applied for every variable in the

optimization.

accelerator: An acceleration method, please consult the

documentation on acc module. Defaults to Standard PSO, that is, velocities change based on

local and global bests.

Maximum allowed error. The algorithm stops as soon emax:

as the error is below this level. The error is absolute.

Maximum number of iterations, the algorithm stops imax:

as soon this number of iterations are executed, no

matter what the error is at the moment.

Return Value

new empty list

Overrides: object.\_\_init\_\_

## $\mathbf{restart}(\mathit{self}, x\theta)$

Resets the optimizer, allowing the use of a new set of estimates. This can be used to avoid stagnation **Parameters** 

x0: A new set of estimates. It doesn't need to have the same size of the original swarm, but it must be a list of estimates in the same format as in the object instantiation. Please, see the documentation on the instantiation of the class. New velocities will be computed.

## step(self)

Computes the new positions of the particles, a step of the algorithm.

This method updates the velocity given the constants associated with the particle and global bests; and then updates the positions accordingly.

This method has no parameters and returns no values. The particles positions can be consulted with the [] interface (as a swarm of particles is a list of estimates), best property, to find the global best, and fbest property to find the minimum (see above).

## $\_$ call $\_$ (self)

Transparently executes the search until the minimum is found. The stop criteria are the maximum error or the maximum number of iterations, whichever is reached first. Note that this is a \_\_call\_\_ method, so the object is called as a function. This method returns a tuple (x, e), with the best estimate of the minimum and the error. Return Value

This method returns a tuple (x, e), where x is the best estimate of the minimum, and e is the estimated error.

## Inherited from list

```
__add__(), __contains__(), __delitem__(), __delslice__(), __eq__(), __ge__(), __getattribute__(), __getitem__(), __getslice__(), __gt__(), __iadd__(), __imul__(), __iter__(), __le__(), __le__(), __len__(), __len__(), __reversed__(), __reversed__(), __remul__(), __setitem__(), __setslice__(), __sizeof__(), append(), count(), extend(), index(), insert(), pop(), remove(), reverse(), sort()
```

## Inherited from object

\_\_delattr\_\_(), \_\_format\_\_(), \_\_reduce\_ex\_\_(), \_\_setattr\_\_(), \_\_str\_\_(), \_\_subclasshook\_\_()

## 31.2.2 Properties

Name	Description
fx	
best	
fbest	
Inherited from object	
class	

#### 31.2.3 Class Variables

Name	Description
Inherited from list	
_hash	

#### 31.2.4 Instance Variables

Name	Description		
ranges	Holds the ranges for every variable. Although it		
	is a writable property, care should be taken in changing parameters before ending the conver-		
	gence.		

## 31.3 Class PSO



PSO is an alias to ParticleSwarmOptimizer

## 31.3.1 Methods

 $Inherited\ from\ peach.pso.base.ParticleSwarmOptimizer(Section\ 31.2)$ 

# Inherited from list

```
__add__(), __contains__(), __delitem__(), __delslice__(), __eq__(), __ge__(), __getattribute__(), __getitem__(), __getslice__(), __gt__(), __iadd__(), __imul__(), __iter__(), __le__(), __len__(), __len__(), __len__(), __reversed__(), __reversed__(), __reversed__(), __reversed__(), __setitem__(), __setslice__(), __sizeof__(), append(), count(), extend(), index(), insert(), pop(), remove(), reverse(), sort()
```

## Inherited from object

### 31.3.2 Properties

Name	Description		
Inherited from peach.pso.base.ParticleSwarmOptimizer (Section 31.2)			
best, fbest, fx			
Inherited from object			
class			

#### 31.3.3 Class Variables

Name	Description
Inherited from list	
_hash	

#### 31.3.4 Instance Variables

Name	Description	
Inherited from peach.pso.base.ParticleSwarmOptimizer (Section 31.2)		
ranges		

# 32 Package peach.sa

This package implements optimization by simulated annealing. Consult:

base Implementation of the basic simulated annealing algorithms;

**neighbor** Some methods for determining the neighbor of the present estimate;

Simulated Annealing is a meta-heuristic designed for optimization of functions. It tries to mimic the way that atoms settle in crystal structures of metals. By slowly cooling the metal, atoms settle in a position of low energy -- thus, it is a natural optimization method.

Two kinds of optimizer are implemented here. The continuous version of the algorithm can be used for optimization of continuous objective functions; the discrete (or binary) one, can be used in combinatorial optimization problems.

### 32.1 Modules

- base: This package implements two versions of simulated annealing optimization. One works with numeric data, and the other with a codified bit string. This last method can be used in discrete optimization problems.

  (Section 33, p. 199)
- **neighbor**: This module implements a general class to compute neighbors for continuous and binary simulated annealing algorithms. The continuous neighbor functions return an array with a neighbor of a given estimate; the binary neighbor functions return a bitarray object.

(Section 34, p. 210)

# 33 Module peach.sa.base

This package implements two versions of simulated annealing optimization. One works with numeric data, and the other with a codified bit string. This last method can be used in discrete optimization problems.

#### 33.1 Functions

## $standard\_normal(size = None)$

Returns samples from a Standard Normal distribution (mean=0, stdev=1).

#### **Parameters**

## size (int, shape tuple, optional)

Returns the number of samples required to satisfy the size parameter. If not given or 'None' indicates to return one sample.

#### Returns

out (float, ndarray)

Samples the Standard Normal distribution with a shape satisfying the size parameter.

#### 33.2 Variables

Name	Description	
doc	Value:	
package	Value: 'peach.sa'	

### 33.3 Class ContinuousSA

object peach.sa.base.ContinuousSA

Simulated Annealing continuous optimization.

This is a simulated annealing optimizer implemented to work with vectors of continuous variables (obviously, implemented as floating point numbers). In general, simulated annealing methods searches for neighbors of one estimate, which makes a lot more sense in discrete problems. While in this class the method is implemented in a different way (to deal with continuous variables), the principle is pretty much the same -- the neighbor is found based on a gaussian neighborhood.

A simulated annealing algorithm adapted to deal with continuous variables has an enhancement that can be used: a gradient vector can be given and, in case the neighbor is not accepted, the estimate is updated in the downhill direction.

#### 33.3.1 Methods

\_\_init\_\_( $self, f, x\theta, ranges=$ None, neighbor=<class 'peach.sa.neighbor.GaussianNeighbor'>, optm=None,  $T\theta=$ 1000.0, rt=0.95, emax=1e-08, imax=1000)

Initializes the optimizer.

To create an optimizer of this type, instantiate the class with the parameters given below: **Parameters** 

f: A multivariable function to be optimized. The function

should have only one parameter, a multidimensional line-vector, and return the function value, a scalar.

x0: First estimate of the minimum. Estimates can be given

in any format, but internally they are converted to a one-dimension vector, where each component corresponds to the estimate of that particular variable.

The vector is computed by flattening the array.

ranges: A range of values might be passed to the algorithm, but

it is not necessary. If supplied, this parameter should be a list of ranges for each variable of the objective function. It is specified as a list of tuples of two values, (x0, x1), where x0 is the start of the interval, and x1 its end. Obviously, x0 should be smaller than x1. It can also be given as a list with a simple tuple in the same format. In that case, the same range will be applied for every

variable in the optimization.

neighbor: Neighbor function. This is a function used to compute the neighbor of the present estimate. You can use the

ones defined in the neighbor module, or you can implement your own. In any case, the neighbor parameter must be an instance of ContinuousNeighbor or of a subclass. Please, see the documentation on the neighbor module for more information. The default is GaussianNeighbor, which computes the new estimate based on a gaussian distribution around the present

estimate.

optm: A standard optimizer such as gradient or Newton. This

is used in case the estimate is not accepted by the algorithm -- in this case, a new estimate is computed in a standard way, providing a little improvement in any case. It defaults to None; in that case, no standard optimization will be used. Notice that, if you want to use a standard optimization you must create it before you

instantiate this class. By doing it this way, you can configure the optimizer in any way you want. Please, consult the documentation in Gradient, Newton and

others.

## **restart**(self, x0, T0 = 1000.0, rt = 0.95, h = 0.5)

Resets the optimizer, returning to its original state, and allowing to use a new first estimate. Restartings are essential to the working of simulated annealing algorithms, to allow them to leave local minima. **Parameters** 

- x0: New estimate of the minimum. Estimates can be given in any format, but internally they are converted to a one-dimension vector, where each component corresponds to the estimate of that particular variable. The vector is computed by flattening the array.
- T0: Initial temperature of the system. The temperature is, of course, an analogy. Defaults to 1000.
- rt: Temperature decreasing rate. The temperature must slowly decrease in simulated annealing algorithms. In this implementation, this is controlled by this parameter. At each step, the temperature is multiplied by this value, so it is necessary that 0 < rt < 1. Defaults to 0.95, smaller values make the temperature decay faster, while larger values make the temperature decay slower.
- h: The initial step of the search. Defaults to 0.5

### step(self)

One step of the search.

In this method, a neighbor of the given estimate is chosen at random, using a gaussian neighborhood. It is accepted as a new estimate if it performs better in the cost function *or* if the temperature is high enough. In case it is not accepted, a gradient step is executed. **Return Value** 

This method returns a tuple (x, e), where x is the updated estimate of the minimum, and e is the estimated error.

cal	$I_{}($	sel	f

Transparently executes the search until the minimum is found. The stop criteria are the maximum error or the maximum number of iterations, whichever is reached first. Note that this is a \_\_call\_\_ method, so the object is called as a function. This method returns a tuple (x, e), with the best estimate of the minimum and the error. Return Value

This method returns a tuple (x, e), where x is the best estimate of the minimum, and e is the estimated error.

## Inherited from object

#### 33.3.2 Properties

Name	Description
X	
fx	
Inherited from object	
_class_	

#### 33.3.3 Instance Variables

Name	Description
ranges	Holds the ranges for every variable. Although it
	is a writable property, care should be taken in
	changing parameters before ending the conver-
	gence.

### 33.4 Class BinarySA

Simulated Annealing binary optimization.

This is a simulated annealing optimizer implemented to work with vectors of bits, which can be floating point or integer numbers, characters or anything allowed by the struct

module of the Python standard library. The neighborhood of an estimate is calculated by an appropriate method given in the class instantiation. Given the nature of this implementation, no alternate convergence can be used in the case of rejection of an estimate.

Class BinarySA Module peach.sa.base

Class BinarySA Module peach.sa.base

#### **33.4.1** Methods

 $\_init\_(self, f, x0, ranges = [], fmt = None, neighbor = < class$ 'peach.sa.neighbor.InvertBitsNeighbor'>,  $T\theta = 1000.0$ , rt = 0.95, emax=1e-08, imax=1000)

Initializes the optimizer.

To create an optimizer of this type, instantiate the class with the parameters given below: Parameters

A multivariable function to be optimized. The function f: should have only one parameter, a multidimensional

line-vector, and return the function value, a scalar.

x0: First estimate of the minimum. Estimates can be given

> in any format, but internally they are converted to a one-dimension vector, where each component corresponds to the estimate of that particular variable.

The vector is computed by flattening the array.

ranges:

Ranges of values allowed for each component of the input vector. If given, ranges are checked and a new estimate is generated in case any of the components fall beyond the value. range can be a tuple containing the inferior and superior limits of the interval; in that case, the same range is used for every variable in the input vector. range can also be a list of tuples of the same format, inferior and superior limits; in that case, the first tuple is assumed as the range allowed for the first variable, the second tuple is assumed as the range allowed for the

second variable and so on.

A struct-module string with the format of the data used. Please, consult the struct documentation, since what is explained there is exactly what is used here. For example, if you are going to use the optimizer to deal with three-dimensional vectors of continuous variables,

the format would be something like:

Default value is an empty string. Notice that this is implemented as a bitarray, so this module must be

It is strongly recommended that integer numbers are used! Floating point numbers can be simulated with long integers. The reason for this is that random bit sequences can have no representation as floating point numbers, and that can make the algorithm not perform adequatelly.

The default value for this parameter is None, meaning that a default format is not supplied. If a format is not

fmt:

fmt = 'fff'

present.

restart(self, x0, ranges=None, T0=1000.0, rt=0.95, h=0.5)

Resets the optimizer, returning to its original state, and allowing to use a new first estimate. Restartings are essential to the working of simulated annealing algorithms, to allow them to leave local minima. **Parameters** 

x0: New estimate of the minimum. Estimates can be given in any format, but internally they are converted to a one-dimension vector, where each component corresponds to the estimate of that particular variable. The vector is computed by flattening the array.

ranges: Ranges of values allowed for each component of the input vector. If given, ranges are checked and a new estimate is generated in case any of the components fall beyond the value. range can be a tuple containing the inferior and superior limits of the interval; in that case, the same range is used for every variable in the input vector. range can also be a list of tuples of the same format, inferior and superior limits; in that case, the first tuple is assumed as the range allowed for the first variable, the second tuple is assumed as the range allowed for the second variable and so on.

T0: Initial temperature of the system. The temperature is, of course, an analogy. Defaults to 1000.

rt: Temperature decreasing rate. The temperature must slowly decrease in simulated annealing algorithms. In this implementation, this is controlled by this parameter. At each step, the temperature is multiplied by this value, so it is necessary that 0 < rt < 1. Defaults to 0.95, smaller values make the temperature decay faster, while larger values make the temperature decay slower.

## step(self)

One step of the search.

In this method, a neighbor of the given estimate is obtained from the present estimate by choosing nb bits and inverting them. It is accepted as a new estimate if it performs better in the cost function or if the temperature is high enough. In case it is not accepted, the previous estimate is mantained.

### Return Value

This method returns a tuple (x, e), where x is the updated estimate of the minimum, and e is the estimated error.

## $\_$ call $\_$ (self)

Transparently executes the search until the minimum is found. The stop criteria are the maximum error or the maximum number of iterations, whichever is reached first. Note that this is a \_\_call\_\_ method, so the object is called as a function. This method returns a tuple (x, e), with the best estimate of the minimum and the error. Return Value

This method returns a tuple (x, e), where x is the best estimate of the minimum, and e is the estimated error.

## Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

#### 33.4.2 Properties

Name	Description
X	Getter for the estimate. The estimate is
	decoded as the format supplied. If no format
	was supplied, then the estimate is returned as a
	bitarray.
best	Getter for the best value so far. Returns a tuple
	containing both the best estimate and its value.
Inherited from object	
_class	

# 34 Module peach.sa.neighbor

This module implements a general class to compute neighbors for continuous and binary simulated annealing algorithms. The continuous neighbor functions return an array with a neighbor of a given estimate; the binary neighbor functions return a bitarray object.

#### 34.1 Variables

Name	Description
doc	Value:
_package_	Value: 'peach.sa'

## 34.2 Class ContinuousNeighbor

object — peach.sa.neighbor.ContinuousNeighbor

Known Subclasses: peach.sa.neighbor.GaussianNeighbor, peach.sa.neighbor.UniformNeighbor

Base class for continuous neighbor functions

This class should be derived to implement a function which computes the neighbor of a given estimate. Every neighbor function should implement at least two methods, defined below:

\_\_init\_\_(self, \*cnf, \*\*kw) Initializes the object. There are no mandatory arguments, but any parameters can be used here to configure the operator. For example, a class can define a variance for randomly chose the neighbor -- this should be defined here:

```
__init__(self, variance=1.0)
```

A default value should always be offered, if possible.

\_\_call\_\_(self, x): The \_\_call\_\_ interface should be programmed to actually compute the value of the neighbor. This method should receive an estimate in x and use whatever parameters from the instantiation to compute the new estimate. It should return the new estimate.

Please, note that the SA implementations relies on this behaviour: it will pass an estimate to your \_\_call\_\_ method and expects to received the result back.

This class can be used also to transform a simple function in a neighbor function. In this case, the outside function must compute in an appropriate way the new estimate.

### 34.2.1 Methods

 $\_$ **init** $\_$ (self, f)

Creates a neighbor function from a function. Parameters

f: The function to be transformed. This function must receive an array of any size and shape as an estimate, and return an estimate of the same size and shape as a result. A function that operates only over a single number can be used -- in this case, the function operation will propagate over all components of the estimate.

Overrides: object.\_\_init\_\_

$$\_$$
call $\_$ (self,  $x$ )

Computes the neighbor of the given estimate. **Parameters** x: The estimate to which the neighbor must be computed.

## Inherited from object

#### 34.2.2 Properties

Name	Description
Inherited from object	
class	

## 34.3 Class GaussianNeighbor

object —
peach.sa.neighbor.ContinuousNeighbor —
peach.sa.neighbor.GaussianNeighbor

A new estimate based on a gaussian distribution

This class creates a function that computes the neighbor of an estimate by adding a gaussian

distributed randomly choosen vector with the same shape and size of the estimate.

### 34.3.1 Methods

 $\_init\_(self, variance=0.05)$ 

Initializes the neighbor operator Parameters

variance: This is the variance of the gaussian distribution used to randomize the estimate. This can be given as a single value or as an array. In the first case, the same value will be used for all the components of the estimate; in the second case, variance should be an array with the same number of components of the estimate, and each component in this array is the variance of the corresponding component in the estimate array.

Overrides: object.\_\_init\_\_

 $\_$ call $\_$ (self, x)

Computes the neighbor of the given estimate. Parameters

x: The estimate to which the neighbor must be computed.

Overrides: peach.sa.neighbor.ContinuousNeighbor.\_call\_

### Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

#### 34.3.2 Properties

Name	Description
Inherited from object	
_class	

#### 34.3.3 Instance Variables

Name	Description
variance	Variance of the gaussian distribution.

## 34.4 Class UniformNeighbor

A new estimate based on a uniform distribution

This class creates a function that computes the neighbor of an estimate by adding a uniform distributed randomly choosen vector with the same shape and size of the estimate.

#### 34.4.1 Methods

 $_{\text{init}}_{\text{--}}(self, xl = -1.0, xh = 1.0)$ 

Initializes the neighbor operator Parameters

x1: The lower limit of the distribution;

xh: The upper limit of the distribution. Both values can be given as a single value or as an array. In the first case, the same value will be used for all the components of the estimate; in the second case, they should be an array with the same number of components of the estimate, and each component in this array is the variance of the corresponding component in the estimate array.

Overrides: object.\_\_init\_\_

 $\_$ call $\_$ (self, x)

Computes the neighbor of the given estimate. Parameters

x: The estimate to which the neighbor must be computed.

Overrides: peach.sa.neighbor.ContinuousNeighbor.\_call\_

## Inherited from object

### 34.4.2 Properties

Name	Description
Inherited from object	
class	

#### 34.4.3 Instance Variables

Name	Description
xl	Lower limit of the uniform distribution.
xh	Upper limit of the uniform distribution.

## 34.5 Class BinaryNeighbor

object — peach.sa.neighbor.BinaryNeighbor

Known Subclasses: peach.sa.neighbor.InvertBitsNeighbor

Base class for binary neighbor functions

This class should be derived to implement a function which computes the neighbor of a given estimate. Every neighbor functions should implement at least two methods, defined below:

\_\_init\_\_(self, \*cnf, \*\*kw) Initializes the object. There are no mandatory arguments, but any parameters can be used here to configure the operator. For example, a class can define a bit change rate -- this should be defined here:

A default value should always be offered, if possible.

\_\_call\_\_(self, x): The \_\_call\_\_ interface should be programmed to actually compute the value of the neighbor. This method should receive an estimate in x and use whatever parameters from the instantiation to compute the new estimate. It should return the new estimate.

Please, note that the SA implementations relies on this behaviour: it will pass an estimate to your \_\_call\_\_ method and expects to received the result back. Notice, however, that the SA implementation does not expect that the result is sane, ie, that it is in conformity with the representation used in the algorithm. A sanity check is done inside the binary SA class. Please, consult the documentation on BinarySA for further details.

This class can be used also to transform a simple function in a neighbor function. In this case, the outside function must compute in an appropriate way the new estimate.

### 34.5.1 Methods

 $\_$ **init** $\_$ (self, f)

Creates a neighbor function from a function. Parameters

f: The function to be transformed. This function must receive a bitarray of any length as an estimate, and return a new bitarray of the same length as a result.

Overrides: object.\_\_init\_\_

$$\_$$
call $\_$ (self,  $x$ )

Computes the neighbor of the given estimate. Parameters

x: The estimate to which the neighbor must be computed.

## Inherited from object

#### 34.5.2 Properties

Name	Description
Inherited from object	
class	

## 34.6 Class InvertBitsNeighbor

object — peach.sa.neighbor.BinaryNeighbor —

## peach.sa. neighbor. InvertBits Neighbor

A simple neighborhood based on the change of a few bits.

This neighbor will be computed by randomly choosing a bit in the bitarray representing the estimate and change a number of bits in the bitarray and inverting their value.

### 34.6.1 Methods

 $\_init\_(self, nb=2)$ 

Initializes the operator. Parameters

nb: The number of bits to be randomly choosen to be inverted in the calculation of the neighbor. Be very careful while choosing this parameter. While very large optimizations can benefit from a big value here, it is not recommended that more than one bit per variable is inverted at each step -- otherwise, the neighbor might fall very far from the present estimate, which can make the algorithm not work accordingly. This defaults to 2, that is, at each step, only one bit will be inverted at most.

Overrides: object.\_\_init\_\_

 $_{-}$ call $_{-}$ (self, x)

Computes the neighbor of the given estimate. Parameters

x: The estimate to which the neighbor must be computed.

Overrides: peach.sa.neighbor.BinaryNeighbor.\_call\_

### Inherited from object

```
__delattr__(), __format__(), __getattribute__(), __hash__(), __new__(), __reduce__(), __reduce_ex__(), __repr__(), __setattr__(), __sizeof__(), __str__(), __subclasshook__()
```

#### 34.6.2 Properties

Name	Description
Inherited from object	
class	

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