

Finiteness for Mapping Class Group Representations from Twisted Dijkgraaf-Witten Theory

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ABSTRACT

We show that any twisted Dijkgraaf-Witten representation of a mapping class group of an orientable, compact surface with boundary has finite image. This generalizes work of Etingof, Rowell and Witherspoon showing that the braid group images are finite [7]. In particular, our result answers their question regarding finiteness of images of arbitrary mapping class group representations in the affirmative.

Our approach is to translate the problem into manipulation of colored graphs embedded in the given surface. To do this translation, we use the fact that any twisted Dijkgraaf-Witten representation associated to a finite group G and 3-cocycle ω is isomorphic to a Turaev-Viro-Barrett-Westbury (TVBW) representation associated to the spherical fusion category Vec_G^ω of twisted G -graded vector spaces. The representation space for this TVBW representation is canonically isomorphic to a vector space of Vec_G^ω -colored graphs embedded in the surface [14]. By analyzing the action of the Birman generators [4] on a finite spanning set of colored graphs, we find that the mapping class group acts by permutations on a slightly larger finite spanning set. This implies that the representation has finite image.

Keywords: TQFT; mapping class group; twisted Dijkgraaf-Witten; Property F conjecture

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1. Introduction

Given a spherical fusion category \mathcal{A} over a field k and an oriented compact surface Σ , possibly with boundary, the Turaev-Viro-Barrett-Westbury (TVBW) construction gives a projective representation of the mapping class group $\text{MCG}(\Sigma)$ [23,3]. A natural problem is to determine the images of such representations. In particular, we would like to know when such a representation has finite image.

The original Property F conjecture states that all braid group representations coming from a braided monoidal category \mathcal{C} have finite image if and only if \mathcal{C} is weakly integral [17,7]. Instead of only considering braid group representations, one can consider mapping class groups of arbitrary orientable surfaces. In this case, the input categories to construct the representations must be more specialized than just braided monoidal. One can either apply the Reshitikhin-Turaev construction to a modular tensor category, or apply the TVBW construction to a spherical

fusion category. The former construction is more general than the latter since the Reshitikhin-Turaev construction for the Drinfeld center $Z(\mathcal{A})$ of a spherical fusion category \mathcal{A} yields the same representation as the TVBW construction for \mathcal{A} . Hence, the most general form of this modified conjecture is the following:

Conjecture 1.1 (Property F for mapping class groups). **All Reshitikhin-Turaev mapping class group representations associated to a modular tensor category \mathcal{C} have finite images if and only if \mathcal{C} is weakly integral.**

However, for the case considered in this paper, the simpler TVBW construction suffices. Our input category is $\mathcal{A} = \text{Vec}_G^\omega$, the spherical fusion category of G -graded vector spaces with associativity modified by a cocycle $\omega \in Z^3(G, k^\times)$. In this case, the TVBW construction corresponds to the twisted Dijkgraaf-Witten theory of [5]. The category Vec_G^ω is integral, so the one expects its associated mapping class group representations to have finite image. The main contribution of this paper is to verify this for arbitrary G and ω .

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2. Related Work

The closest related work is a result of Etingof, Rowell, and Witherspoon who showed purely algebraically that the braid group representations associated to the modular category $\text{Mod}(D^\omega(G))$ have finite images [7]. The braid group B_n is the mapping class group of a disk with n marked points relative to its boundary, so they asked whether their result generalizes to arbitrary mapping class group representations associated to $\text{Mod}(D^\omega(G))$. This paper answers their question affirmatively, using more topological techniques rather than strictly algebraic ones.

Prior to the current work, certain specific cases had already been solved. In the case of the torus, Ng and Schauenburg's Congruence Subgroup Theorem implies the much stronger result that any Reshitikhin-Turaev representation of the mapping class group of the torus has finite image [18]. Another related result is due to Fjelstad and Fuchs [8]. They showed that, given a surface with at most one boundary component, the mapping class group representations corresponding to the untwisted (i.e. $\omega = 1$) Dijkgraaf-Witten theory have finite image. Their paper uses an algebraic method of Lyubashenko [16] that gives a projective mapping class group representation to any factorizable ribbon Hopf algebra, in their case, the double $D(G)$. In our case, we instead consider the mapping class group action on a vector space of Vec_G^ω -colored embedded graphs defined by Kirillov [14], yielding a simpler, geometric proof of the more general twisted case.

Bantay also calculated the images of certain representations of mapping class groups on the Hilbert space of an orbifold model associated to $D^\omega(G)$ [2]. These rep-

representations appear to coincide with the twisted Dijkgraaf-Witten representations. However, due to lack of proof, the precise connection is unclear.

Much more is known for modular categories other than $\text{Mod}(D^\omega(G))$, especially for braid group representations. More precisely, the braid group Property F conjecture has been verified for all unitary modular tensor categories arising from the classical quantum group construction and various cases related to Hecke- and BMW-algebras [9,10,12,13,15,20,21].

Less is known about the more general mapping class group conjecture. Wright has shown that, for any closed surface, the mapping class group representations associated to $U_q(\mathfrak{sl}(2))$ at level 4 have finite image [25]. Funar proved that, for closed surfaces of genus $g \geq 2$, the mapping class group representations associated $SU(2)$ and $SO(3)$ are infinite for all sufficiently large levels [11].

3. Background

3.1. The spherical fusion category Vec_G^ω

The following definitions are well-known and can be found in [6]. Let k be an algebraically closed field of characteristic 0, G a finite group, and $\omega \in Z^3(G, k^\times)$ a 3-cocycle. The spherical fusion category of G -graded k -vector spaces with associativity defined by ω is denoted Vec_G^ω . The objects of this category are vector spaces with a decomposition $V = \bigoplus_{g \in G} V_g$. Morphisms are linear maps preserving the grading. The tensor product is defined by

$$(V \otimes W)_g = \bigoplus_{x,y \in G, xy=g} V_x \otimes W_y.$$

For each $g \in G$, pick a 1-dimensional vector space $\delta_g \in \text{Obj}(\text{Vec}_G^\omega)$ concentrated in degree g . The set $\{\delta_g : g \in G\}$ is a complete set of pairwise non-isomorphic representatives for the isomorphism classes of simple objects of Vec_G^ω . We will sometimes abuse notation by referring to an object δ_g by the group element g . We have $1 \cong \delta_1$, and $\delta_g^* := \delta_{g^{-1}}$ with the coevaluation and evaluation maps defined below.

For the structural morphisms, we follow [19]. We will treat the canonical isomorphisms $\delta_g \otimes \delta_h \cong \delta_{gh}$ as identities. The associator $\alpha_{g,h,k} : (\delta_g \otimes \delta_h) \otimes \delta_k \rightarrow \delta_g \otimes (\delta_h \otimes \delta_k)$ is defined by

$$\alpha_{g,h,k} = \omega(g, h, k) \text{id}_{ghk}.$$

The evaluator $\text{ev}_g : \delta_g^* \otimes \delta_g \rightarrow 1$ is

$$\text{ev}_g = \omega(g^{-1}, g, g^{-1}) \text{id}_1.$$

The coevaluator $\text{coev}_g : 1 \rightarrow \delta_g \otimes \delta_g^*$ is

$$\text{coev}_g = \text{id}_1.$$

The pivotal structure $j_g : \delta_g \rightarrow \delta_g^{**}$ is

$$j_g = \omega(g^{-1}, g, g^{-1}) \text{id}_g.$$

If ω and ω' are cohomologous cocycles, then Vec_G^ω is monoidally equivalent to $\text{Vec}_G^{\omega'}$ [6]. This equivalence respects the pivotal structure, so extends to an equivalence of spherical categories. It is a basic result in group cohomology that any cocycle $\omega \in Z^3(G, k^\times)$ is cohomologous to a cocycle taking values in $\mu_{|G|}$, the roots of unity of order $|G|$. Thus, by replacing Vec_G^ω with an equivalent spherical category, we assume without loss of generality that $\text{Im}(\omega) \subset \mu_{|G|}$.

3.2. Colored graphs

The following definitions and theorem are due to Kirillov Jr. [14], and recorded here for convenience. For any spherical fusion category \mathcal{A} and surface Σ , Kirillov gives the following presentation of the Levin-Wen model as a vector space of colored graphs modulo local relations. He also proves that this space is canonically isomorphic to the TVBW vector space associated to Σ . It is straightforward to check that this isomorphism, which amounts to replacing a triangulation with its dual graph, commutes with the mapping class group action.

We use the convention that a tensor product of multiple objects with parentheses omitted correspond to the left-associative parenthesization.

We define the functor $\mathcal{A}^{\boxtimes n} \rightarrow \text{Vec}$ by

$$\langle V_1, \dots, V_n \rangle = \text{Hom}_{\mathcal{A}}(1, V_1 \otimes \dots \otimes V_n) \quad (3.1)$$

for any collection V_1, \dots, V_n of objects of \mathcal{A} . Note that pivotal structure gives functorial isomorphisms

$$z: \langle V_1, \dots, V_n \rangle \cong \langle V_n, V_1, \dots, V_{n-1} \rangle \quad (3.2)$$

where, up to associators,

$$z(\phi) = (j_{*}V_n \otimes \text{id}_{V_1 \otimes \dots \otimes V_{n-1}} \otimes \text{ev}_{*}V_n) \circ (\text{id}_{**}V_n \otimes \phi \otimes \text{id}_{*}V_n) \circ \text{coev}_{**}V_n$$

and $z^n = \text{id}$ (see [1, Section 5.3]). Thus, up to a canonical isomorphism, the space $\langle V_1, \dots, V_n \rangle$ only depends on the cyclic order of V_1, \dots, V_n .

We have a natural composition map

$$\begin{aligned} \langle V_1, \dots, V_n, X^* \rangle \otimes \langle X, W_1, \dots, W_m \rangle &\rightarrow \langle V_1, \dots, V_n, W_1, \dots, W_m \rangle \\ \varphi \otimes \psi &\mapsto \varphi \circ_X \psi = \text{ev}_{*}X \circ (\varphi \otimes \psi), \end{aligned} \quad (3.3)$$

up to associators. Note that, due to the order of X and $*X$ in the tensor product, we use the right evaluation map $\text{ev}_{*}X: X \otimes *X \rightarrow 1$ for the left dual $*X$, instead of the right evaluation map $\text{ev}_X: X^* \otimes X \rightarrow 1$ for X .

We will consider finite graphs embedded in an oriented surface Σ (which may have boundary); for such a graph Γ , let $E(\Gamma)$ be the set of edges. Note that edges are not oriented. Let E^{or} be the set of oriented edges, i.e. pairs $\mathbf{e} = (e, \text{orientation of } e)$; for such an oriented edge \mathbf{e} , we denote by $\bar{\mathbf{e}}$ the edge with opposite orientation.

If Σ has a boundary, the graph is allowed to have uncolored one-valent vertices on $\partial\Sigma$ but no other common points with $\partial\Sigma$; all other vertices will be called interior. We will call the edges of Γ terminating at these one-valent vertices *legs*.

Definition 3.1. Let Σ be an oriented surface (possibly with boundary) and $\Gamma \subset \Sigma$ — an embedded graph as defined above. A *coloring* of Γ is the following data:

- Choice of an object $V(\mathbf{e}) \in \text{Obj } \mathcal{A}$ for every oriented edge $\mathbf{e} \in E^{or}(\Gamma)$ so that $V(\bar{\mathbf{e}}) = V(\mathbf{e})^*$.
- Choice of a vector $\varphi(v) \in \langle V(\mathbf{e}_1), \dots, V(\mathbf{e}_n) \rangle$ (see (3.1)) for every interior vertex v , where $\mathbf{e}_1, \dots, \mathbf{e}_n$ are edges incident to v , taken in counterclockwise order and with outward orientation.

An *isomorphism* f of two coloring $\{V(\mathbf{e}), \varphi(v)\}, \{V'(\mathbf{e}), \varphi'(v)\}$ is a collection of isomorphisms $f_{\mathbf{e}}: V(\mathbf{e}) \cong V'(\mathbf{e})$ which agree with isomorphisms $V(\bar{\mathbf{e}}) = V(\mathbf{e})^*$ and which identify $\varphi', \varphi: \varphi'(v) = f \circ \varphi(v)$.

We will denote the set of all colored graphs on a surface Σ by $\text{Graph}(\Sigma)$.

Note that if Σ has a boundary, then every colored graph Γ defines a collection of points $B = \{b_1, \dots, b_n\} \subset \partial\Sigma$ (the endpoints of the legs of Γ) and a collection of objects $V_b \in \text{Obj } \mathcal{A}$ for every $b \in B$: the colors of the legs of Γ taken with outgoing orientation. We will denote the pair $(B, \{V_b\})$ by $\mathbf{V} = \Gamma \cap \partial\Sigma$ and call it *boundary value*. We will denote

$\text{Graph}(\Sigma, \mathbf{V}) = \text{set of all colored graphs in } \Sigma \text{ with boundary value } \mathbf{V}.$

We can also consider formal linear combinations of colored graphs. Namely, for fixed boundary value \mathbf{V} as above, we will denote

$$\text{VGraph}(\Sigma, \mathbf{V}) = \{\text{formal linear combinations of graphs } \Gamma \in \text{Graph}(\Sigma, \mathbf{V})\} \quad (3.4)$$

In particular, if $\partial\Sigma = \emptyset$, then the only possible boundary condition is trivial ($B = \emptyset$); in this case, we will just write $\text{VGraph}(\Sigma)$.

The following theorem is a variation of result of Reshitikhin and Turaev.

Theorem 3.1. *There is a unique way to assign to every colored planar graph Γ in a disk $D \subset \mathbb{R}^2$ a vector*

$$\langle \Gamma \rangle_D \in \langle V(\mathbf{e}_1), \dots, V(\mathbf{e}_n) \rangle \quad (3.5)$$

where $\mathbf{e}_1, \dots, \mathbf{e}_n$ are the edges of Γ meeting the boundary of D (legs), taken in counterclockwise order and with outgoing orientation, so that that following conditions are satisfied:

- (1) $\langle \Gamma \rangle$ only depends on the isotopy class of Γ .
- (2) If Γ is a single vertex colored by $\varphi \in \langle V(\mathbf{e}_1), \dots, V(\mathbf{e}_n) \rangle$, then $\langle \Gamma \rangle = \varphi$.

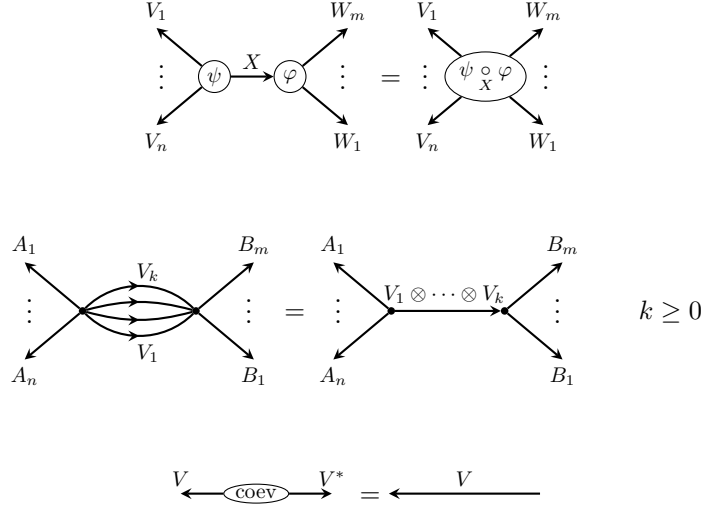


Fig. 1. Local relations for colored graphs.

(3) Local relations shown in Figure 1 hold.

Local relations should be understood as follows: for any pair Γ, Γ' of colored graphs which are identical outside a subdisk $D' \subset D$, and in this disk are homeomorphic to the graphs shown in Figure 1, we must have $\langle \Gamma \rangle = \langle \Gamma' \rangle$.

Moreover, so defined $\langle \Gamma \rangle$ satisfies the following properties:

- (1) $\langle \Gamma \rangle$ is linear in color of each vertex v (for fixed colors of edges and other vertices).
- (2) $\langle \Gamma \rangle$ is additive in colors of edges as shown in Figure 2.

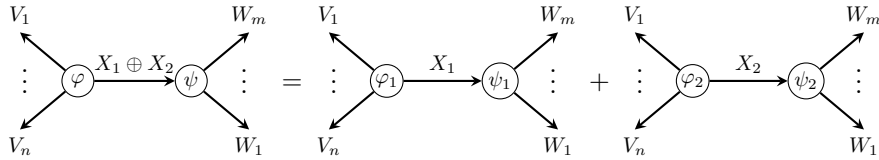


Fig. 2. Linearity of $\langle \Gamma \rangle$. Here φ_1, φ_2 are compositions of φ with projector $X_1 \oplus X_2 \rightarrow X_1$ (respectively, $X_1 \oplus X_2 \rightarrow X_2$), and similarly for ψ_1, ψ_2 .

- (3) If Γ, Γ' are two isomorphic colorings of the same graph, then $\langle \Gamma \rangle = \langle \Gamma' \rangle$.
- (4) Composition property: if $D' \subset D$ is a subdisk such that $\partial D'$ does not contain vertices of Γ and meets edges of Γ transversally, then $\langle \Gamma \rangle_D$ will not change if

we replace subgraph $\Gamma \cap D'$ by a single vertex colored by $\langle \Gamma \cap D' \rangle_{D'}$.

The vector $\langle \Gamma \rangle$ is called the evaluation of Γ .

To define local relations between embedded graphs, Kirillov defines the space of null graphs as follows. Let $\Gamma = c_1\Gamma_1 + \dots + c_n\Gamma_n$ be a formal linear combination of colored graphs in Σ . If there exists an embedded disk $D \subset M$ such that

- (1) Γ is transversal to ∂D (i.e., no vertices of Γ_i are on the boundary of D and edges of each Γ_i meet ∂D transversally),
- (2) all Γ_i coincide outside of D ,
- (3) and $\langle \Gamma \rangle_D = \sum c_i \langle \Gamma_i \cap D \rangle_D = 0$;

then Γ is called a null graph.

Definition 3.2. The vector space $H := H(\Sigma, \mathbf{V})$ associated to a oriented surface Σ with boundary condition \mathbf{V} by the spherical fusion category \mathcal{A} is the quotient space

$$H(\Sigma, \mathbf{V}) = \text{VGraph}(\Sigma, \mathbf{V}) / N(\Sigma, \mathbf{V})$$

where $N(\Sigma, \mathbf{V})$ is the subspace spanned by null graphs (for all possible embedded disks $D \subset \Sigma$).

4. Results

To show that the image of any Vec_G^ω mapping class group representation is finite, we will analyze the action of the mapping class group on a finite collection of colored graphs that span the representation space H . To define this spanning set, we will need the following definitions of simple morphisms and simple colored graphs.

Definition 4.1. Let $g_1, \dots, g_n \in G$. A morphism $\phi \in \langle g_1, \dots, g_n \rangle$ will be called *simple* if it is the composition of the isomorphism $1 \cong \delta_1$ and tensor product isomorphisms of the form $\delta_{gh} \cong \delta_g \otimes \delta_h$.

By MacLane's coherence theorem, there is a unique simple morphism in $\langle g_1, \dots, g_n \rangle$ whenever $\prod_{i=1}^n g_i = 1$. This simple morphism is a canonical basis element for the 1-dimensional space $\langle g_1, \dots, g_n \rangle$. We will describe a map between such spaces as multiplication by a scalar, where the scalar is the matrix coefficient of the map with respect to these canonical bases.

Definition 4.2. Let Γ be a graph embedded in a surface Σ . A Vec_G^ω coloring (V, ϕ) of Γ will be called *simple* if the following conditions both hold:

- (1) For every oriented edge $\mathbf{e} \in E^{or}(\Gamma)$, there exists a group element $g(\mathbf{e}) \in G$ such that the coloring $V(e_i) = \delta_{g(\mathbf{e})}$.

- (2) If v is an interior vertex of Γ , then there exists an enumeration $\mathbf{e}_1, \dots, \mathbf{e}_n$ of the edges incident to v , taken in counterclockwise order and with outward orientation, such that $\prod_{i=1}^n g(\mathbf{e}_i) = 1$ and $\phi(v) \in \langle g(\mathbf{e}_1), \dots, g(\mathbf{e}_n) \rangle$ is a simple morphism.

Lemma 4.1. *Let $\phi \in \langle g_1, \dots, g_n \rangle$ and $\psi \in \langle g_n, g_1, \dots, g_{n-1} \rangle$ be simple morphisms. Then $z(\phi) = \alpha\psi$, where $\alpha \in \mu_{|G|}$.*

Proof. The definition of the z -morphism in Equation 3.2 only involves tensors and compositions of structural morphisms – i.e. associators, unitors, the pivotal j -morphism, evaluation, and coevaluation morphisms. Since all the tensor factors in the codomain of ϕ are simple objects, the definition of Vec_G^ω states that each of the structural morphisms simply consist of multiplication by elements of the form $\omega(g, h, k)$ for some $g, h, k \in G$. Thus, $z(\phi) = \alpha\psi$ for some α which is a product of elements in $\text{Im}(\omega)$. Since $\text{Im}(\omega) \subset \mu_{|G|}$, it follows that $\alpha \in \mu_{|G|}$. \square

Proposition 4.1. *Let Γ be a simple colored graph embedded in a surface Σ . Let Δ be the colored graph given by applying one of the three local moves in Figure 1 to Γ . Then*

- (1) *each edge of Δ is labeled by δ_g for some $g \in G$, and*
 (2) *there exists $\alpha \in \mu_{|G|}$ such that*

$$\Delta - \alpha\Delta' \in N(\Sigma, \mathbf{V}),$$

where Δ' is a simple colored graph given by replacing each vertex label in Δ with a simple morphism.

Proof. The proof of (1) follows directly from the definition of each local move. For (2), we'll consider each local move separately. In each case, we need to show that Δ is equivalent to $\alpha\Delta'$ in H .

For the first (edge contraction) local move in Figure 1, using the same notation as in the figure, the vertex label $\psi \circ_X \phi$ in Δ is given by the following composition. Since Γ is simple, there exist integers l, k and simple morphisms ϕ', ψ' such that $\psi = z^l(\psi')$ and $\phi = z^k(\phi')$. Then we repeatedly apply associators and the cyclic z -morphism of Equation 3.2 to ϕ and ψ until the tensor factors of the codomain are rearranged in the order of the left hand side of Equation 3.3 and that X and X^* are isolated (not contained in any parentheses). After applying the ev_X morphism, we reassociate until the new label $\varphi \circ_X \psi$ has the left-associated parenthesization. Since every edge is labeled by a simple object, each associator morphism consists of multiplication by $\omega(g, h, k)$ for some $g, h, k \in G$. Similarly, by Lemma 4.1, every z -morphism consists of multiplication by some $\beta \in \mu_{|G|}$. Thus, the overall composition consists of multiplication by an element $\alpha \in \mu_{|G|}$.

For the second local move (tensoring parallel edges), there are two cases: $k = 0$ and $k > 0$. In the $k = 0$ case, we apply inverse unitors to each vertex label introduce

an edge labeled by the unit object, followed by reassociation. In the $k > 0$ case, we need to reassociate to group together labels of the parallel edges then reassociate at the end. For the same reasons as for the first move (every edge is labeled by a simple object), it follows that the result of this local move is also of the desired form.

For the third local move (adding a coev-labeled vertex), the colored graph given by direct application of the local move to a simple graph is already simple, so we can pick $\alpha = 1$. \square

4.1. No Boundary Case

We first prove our theorem in the easier case where the surface Σ is closed.

Theorem 4.1. *The image of any twisted Dijkgraaf-Witten representation of a mapping class group of an orientable, closed surface Σ is finite.*

Proof. Let Γ be a Vec_G^ω -colored graph embedding, and let $g \geq 1$ be the genus of Σ (if $g = 0$, the mapping class group is trivial). Thinking of Σ as a quotient of its fundamental $4g$ -gon, by isotopy we may assume that the vertices of Γ lie in the interior of the polygon, none of the edges of Γ intersect the corners of the polygon, and that the edges of Γ only meet the sides of the polygon transversally. Evaluating on the interior of the polygon shows that Γ is equivalent to a graph with a single vertex whose edges are simple closed curves, each of which intersect the boundary of the polygon precisely once. By using the local relations, we can replace all the edges intersecting a side with a single edge labeled by the tensor product of their labels. If there are no edges intersecting a side, we can insert a single edge labeled by the group identity into Γ that intersects only that side. Thus, Γ is equivalent to a colored graph with one vertex v and edges e_1, \dots, e_{2g} corresponding to the standard generators of $\pi_1(M, v)$ as shown in Figure 3.

By Theorem 3.1 and the definition of the quotient map identifying the sides of the fundamental polygon, the vertex v is colored by an element $\phi(v) \in \text{Hom}(1, \bigotimes_{i=1}^g V(e_{2i-1}) \otimes V(e_{2i}) \otimes V(e_{2i-1})^* \otimes V(e_{2i}))^*$, where $V(e_i) \in \text{Obj}(\text{Vec}_G^\omega)$ is the coloring of the edge e_i .

We claim that the representation space H is spanned by the set of such colored graphs Γ such that each $V(e_i)$ is simple. This follows from the additivity of the evaluation map of Theorem 3.1 in the direct sum. Strictly speaking, we can only take advantage of the additivity on a disk, not on an edge e_i , which is a v -based loop. However, we can easily add a coev-labeled vertex to any edge e_i , apply the additivity on one of the two resulting edges (which lies in an embedded disk), and then contract on the other edge to get the decomposition we want.

Since isomorphic colorings give the same evaluation, it follows that H is spanned by colored graphs Γ such that each $V(e_i) = \delta_{g_i}$ for some $g_i \in G$. For such Γ , the space of possible v -colors $\text{Hom}(1, \bigotimes_{i=1}^g V(e_{2i-1}) \otimes V(e_{2i}) \otimes V(e_{2i-1})^* \otimes V(e_{2i}))^*$ is one-dimensional if $\prod_{i=1}^g [g_{2i-1}, g_{2i}] = 1$, and zero-dimensional otherwise.

By using the linearity in each vertex label, we can further restrict to simple colored graphs Γ . Thus, the representation space H has a spanning set S consisting of all simple colored graphs Γ with one vertex v and edges e_1, \dots, e_{2g} corresponding to the standard generators of $\pi_1(M, v)$. Since there are only $|G|$ simple objects in Vec_G^ω and at most $2g$ choices of simple morphisms labeling the vertex for any choice of edge labels, the spanning set S is finite.

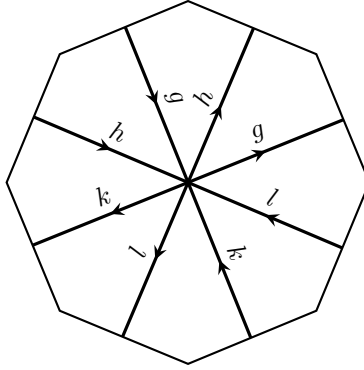


Fig. 3. Element of the spanning set S for a genus 2 surface

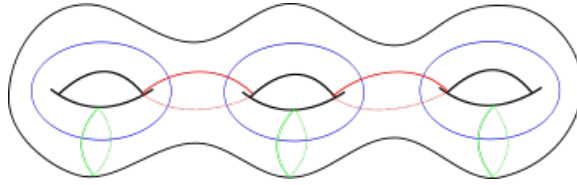


Fig. 4. Simple closed curves for the Dehn twists in the Lickorish generating set for the mapping class group of a genus 3 closed surface (Image source: https://en.wikipedia.org/wiki/Dehn_twist)

The mapping class group of Σ is generated by the Lickorish generating set consisting of Dehn twists around $3g - 1$ simple closed curves. These can be divided into two types of twists: the ones around a single hole (the blue and green curves in Figure 4), and the ones connecting two holes (the red curves). The action of a Dehn twist around a simple closed curve corresponds to cutting the manifold along the curve, holding one piece in place and twisting the other piece by 2π radians in a clockwise direction, then gluing the two pieces back together.

To understand the action of each type of Dehn twist on the representation space H , we will consider the action on the spanning set S . First, we claim that we can apply local moves to any element of S to get a colored graph of the form shown in

the first subfigure of Figure 5, where the unshown part of the fundamental polygon looks the same as in the definition of S . Indeed, to pass from an arbitrary element of S , to a colored graph of the form shown in the first subfigure of 5, we first add coevaluation-labeled vertices to each edge intersecting the three shown sides of the fundamental polygon. Then connect the new vertices using 1-labeled edges (this corresponds to applying the second local move in Figure 1 with $k = 0$), contract the connections to get one new vertex, and tensor together the edges connecting the old vertex to the new vertex.

The action of the first type of Dehn twist on an arbitrary element of S is shown in the first two subfigures of Figure 5. After applying the Dehn twist, we have the simple colored graph shown in the second subfigure of Figure 5. We then apply local moves in the remaining subfigures. By repeated application of Proposition 4.1, the resulting colored graph is equivalent to $\beta\Delta$, for some $\beta \in \mu_{|G|}$ and $\Delta \in S$. Thus, the first type of Dehn twist maps S to $\mu_{|G|}S$.

An analogous proof works for the second type of Dehn twist shown in Figure 6. Thus, the image of any such mapping class group representation is a quotient of the group of permutations of the finite set $\mu_{|G|}S$, hence finite. \square

Corollary 4.1. *When $\omega = 1$ and Σ is closed, this representation is a permutation representation.*

Proof. Under the assumption that the representation in [8] coincides with ours, this fact follows from Theorem 2.6 in [8]. We can also see this directly by first noting that G acts on S by simultaneously conjugation of all edge labels by a single element $g \in G$. If $s \in S$ and $g \in G$, then we can retrieve s from gs by separating two oppositely oriented, g -labeled edges from each edge in the embedded graph gs . This results in a loop labeled by g , whose evaluation is 1. Thus gs is equivalent to s . Moreover, the cardinality $|S/G| = |\text{Hom}(\pi_1(M), G)|/|G|$ is equal to the dimension of the untwisted Dijkgraaf-Witten representation space H [5]. Hence, S/G is a basis for H . The mapping class group action on S commutes with the G -action, so the mapping class group permutes S/G , i.e. H is a permutation representation. \square

4.2. Boundary Case

When Σ has boundary, we denote by $\text{MCG}(\Sigma)$ the group of isotopy classes of homeomorphisms fixing the boundary of Σ setwise. Given any labelling of the boundary by objects in the Drinfeld center, $l : \pi_0(\partial M) \rightarrow \text{Obj}(Z(\text{Vec}_\omega^G))$, we get a mapping class group representation. The representation space is $H(\Sigma, \mathbf{V})$ where the boundary condition $\mathbf{V} = F \circ l$, where F is the forgetful functor $F : Z(\text{Vec}_\omega^G) \rightarrow \text{Vec}_\omega^G$. The same local relations are valid in this representation space [14].

By a similar argument as in the proof of the Theorem 4.1, any such representation space has a finite spanning set S consisting of all simple colored graphs with

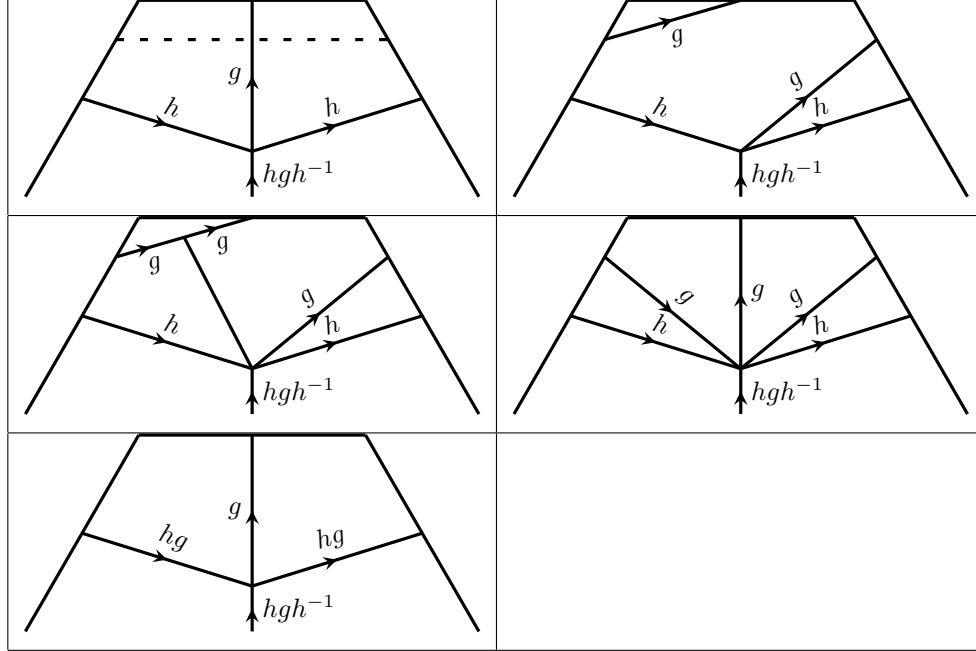


Fig. 5. First type of Dehn twist. Read from left to right, then top to bottom. The Dehn twist is performed along the dashed simple closed curve.

a single vertex, loops for each of the usual generators of the fundamental group of Σ , and a leg from the vertex to each of the boundary components.

Let N denote the closed surface obtained by filling in all the boundary components of Σ with disks. The mapping class group $\text{MCG}(\Sigma)$ is generated by the same Dehn twists as $\text{MCG}(N)$, as well as braids interchanging boundary components and mapping classes corresponding to dragging a boundary component along a representative of a standard generator of $\pi_1(N)$ [4]. As in the proof of Theorem 4.1, applying any of these generators of $\text{MCG}(\Sigma)$ to a colored graph in S yields an element in $\mu_{|G|}S$ (see Figures 7 and 8). Since the braid group is also generated by such braids, we have the following theorem.

Theorem 4.2. *The image of any twisted Dijkgraaf-Witten representation of a mapping class group of an orientable, compact surface with boundary is finite. In particular, the image of any such braid group representation is finite.*

5. Further Directions

We have proved that every twisted Dijkgraaf-Witten representation of a mapping class group of a compact, orientable surface has finite image. This is a generalization of the results of [7] and [8], as well as another step towards the (modified) Prop-

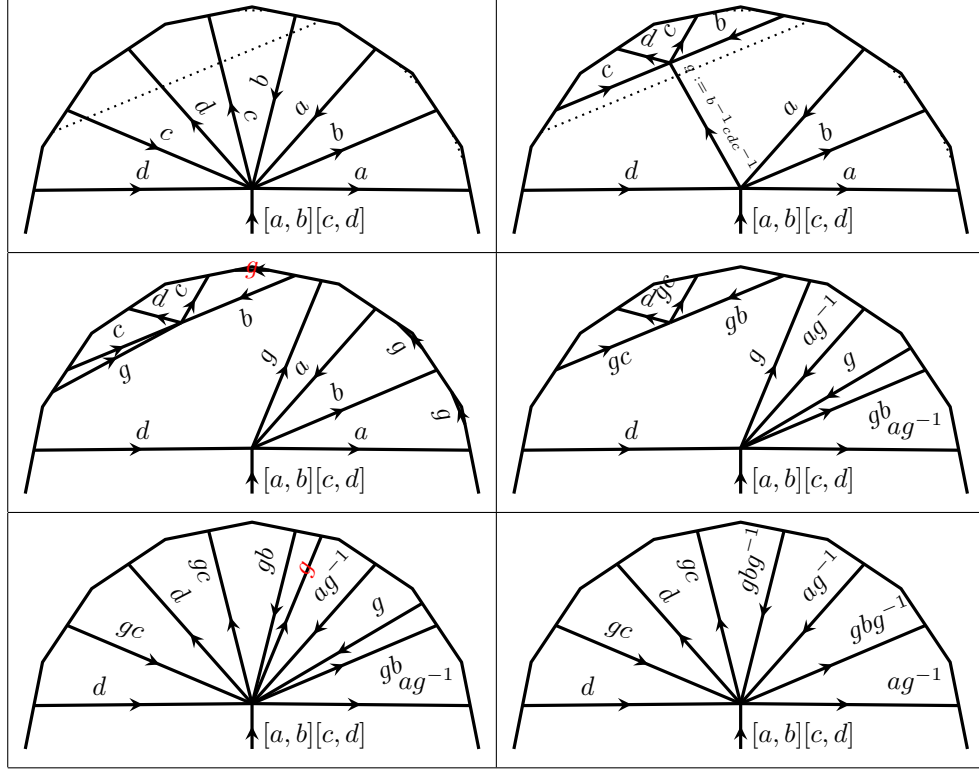


Fig. 6. Second type of Dehn twist. Read from left to right, then top to bottom. The Dehn twist is performed along the dashed simple closed curve.

erty F conjecture. A potential next step would be to consider more complicated spherical categories than Vec_ω^G . One candidate is the class of Tambara-Yamagami categories [22]. The main additional complication here is the appearance of multi-fusion channels, i.e. the tensor product of two simple objects can be a direct sum of multiple simple objects.

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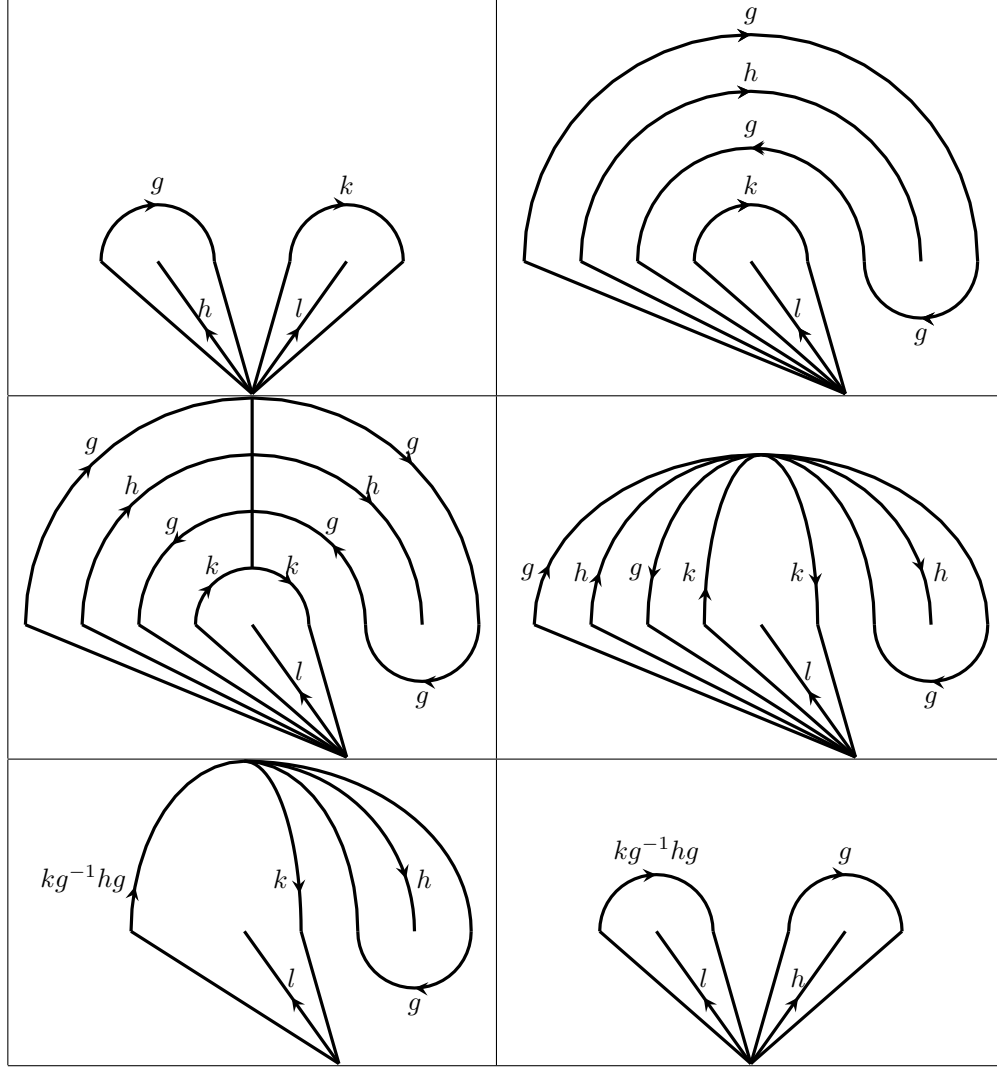


Fig. 7. A braid generator. Read from left to right, then top to bottom. Unlabeled interior edges are colored by the group identity element.

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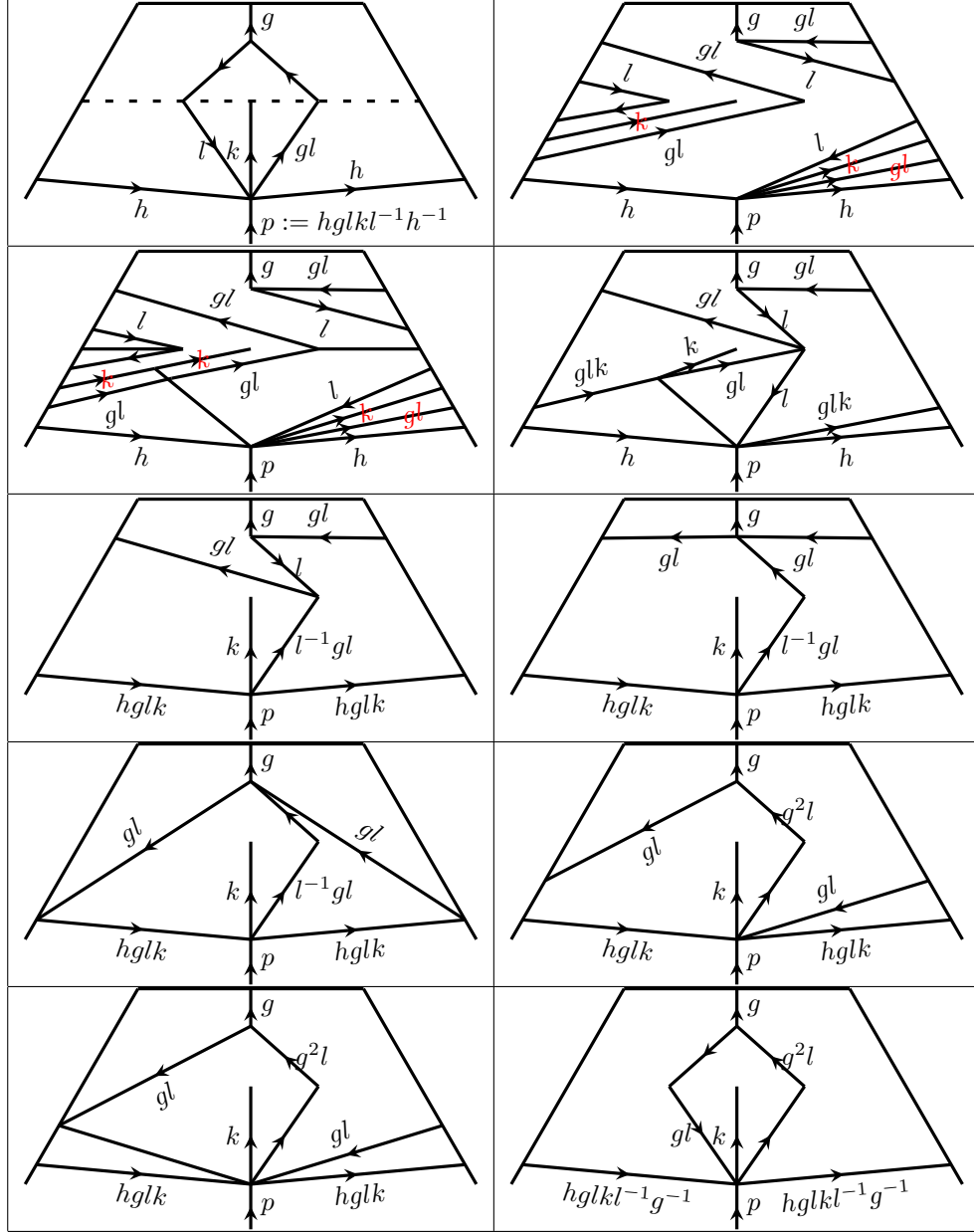


Fig. 8. Pulling a boundary component along a generator for the fundamental group of the corresponding closed surface. Read from left to right, then top to bottom. Unlabeled interior edges are colored by the group identity element.

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