

Paul Gustafson  
 Texas A&M University - Math 666  
 Instructor: Igor Zelenko

## HW 2

1 Let  $E_{ij}$  denote the standard basis of  $M_4(\mathbb{R})$ , and  $F_{ij} = E_{ij} - E_{ji}$ . Let  $\alpha \in \mathbb{R} \setminus \{0\}$  and  $A = F_{21} + \alpha F_{43}$ . Let  $B = F_{32}$ . We consider the following system on  $M := SO(4, \mathbb{R})$ :

$$\dot{E} = E(A + uB), \quad E \in M, u \in \{-1, 1\}.$$

a Show that the system is controllable iff  $\alpha \neq \pm 1$ .

*Proof.* Since  $SO(4)$  is a compact Lie group, the system is controllable iff it is bracket generating.

Fix any  $E \in M$ . To begin calculating the brackets, we have

$$\begin{aligned} [F_{ij}, F_{kl}] &= [E_{ij} - E_{ji}, E_{kl} - E_{lk}] \\ &= \delta_{jk}E_{il} - \delta_{jl}E_{ik} - \delta_{ik}E_{jl} + \delta_{il}E_{jk} - (\delta_{li}E_{kj} - \delta_{lj}E_{ki} - \delta_{ki}E_{lj} + \delta_{kj}E_{li}) \\ &= \delta_{jk}F_{il} - \delta_{jl}F_{ik} - \delta_{ik}F_{jl} + \delta_{il}F_{jk} \end{aligned}$$

Hence

$$\begin{aligned} [A, B] &= [F_{21} + \alpha F_{43}, F_{32}] \\ &= F_{13} + \alpha F_{42} \end{aligned}$$

$$\begin{aligned} [A, [A, B]] &= [F_{21} + \alpha F_{43}, F_{13} + \alpha F_{42}] \\ &= F_{23} + \alpha F_{14} - \alpha F_{41} - \alpha^2 F_{32} \\ &= 2\alpha F_{14} + (1 + \alpha^2)F_{23} \end{aligned}$$

$$\begin{aligned} [B, [A, B]] &= [F_{32}, F_{13} + \alpha F_{42}] \\ &= F_{21} - \alpha F_{34} \\ &= A \end{aligned}$$

Let  $C = (2\alpha)^{-1}([A, [A, B]] + (1 + \alpha^2)B) = F_{14}$ . Then  $\text{Lie}_E^3 = \text{span}(A, B, [A, B], C)$ .

Then we have

$$\begin{aligned}[A, C] &= [F_{21} + \alpha F_{43}, F_{14}] \\ &= \alpha(F_{24} + F_{31}) \\ &= -\alpha F_{13} - F_{42}\end{aligned}$$

$$\begin{aligned}[B, C] &= [F_{32}, \alpha F_{14}] \\ &= 0\end{aligned}$$

$$\begin{aligned}[C, [A, B]] &= [F_{14}, F_{13} + \alpha F_{42}] \\ &= -F_{43} + \alpha F_{12}\end{aligned}$$

*Case  $\alpha^2 = 1$ .* We have  $\alpha[A, C] = -F_{13} - \alpha F_{42} = -[A, B]$ , and  $\alpha[C, [A, B]] = F_{12} - \alpha F_{43} = -A$ . Thus  $[Lie_E^3, Lie_E^3] = Lie_E^3$ , and it is easy to see that  $\dim(Lie_E^3) = 4$ . Since this holds for all points of  $M$ ,  $Lie^3$  defines an involutive distribution of  $M$ . By the Frobenius theorem there exists an immersed submanifold  $N$  containing  $E$  such that  $T_q(N) = Lie_q^3(M)$  for all  $q \in N$ . In particular, the orbit of  $E$  and the admissible set lie in  $N$ . Since  $\dim(N) = 4 < 6 = \dim(M)$ , the inclusion map  $N \rightarrow M$  is everywhere singular. Hence, Sard's theorem implies that  $N$  has measure 0 as a subset of  $M$ , so  $N \neq M$ .

*Case  $\alpha^2 \neq 1$ .* Let  $D = (-\alpha^2 + 1)^{-1}([A, C] + [A, B]) = F_{13}$ . Since  $[B, D] = [F_{32}, F_{13}] = F_{21}$ , we have

$$(F_{12}, F_{13}, F_{14}, F_{23}, F_{24}, F_{34}) = (-[B, D], D, C, -B, [A, C] + \alpha D, [C, [A, B]] + \alpha[B, D]).$$

Hence  $\mathcal{F} := \{A + uB : u \in \{-1, 1\}\}$  is bracket-generating. Since  $SO(4)$  is connected, this implies the system is controllable.  $\square$

**b** Will the answer of the previous item change if  $u \in \{2, 3\}$  instead of  $\{-1, 1\}$ ?

*Proof.* No,  $\text{span}(A + 2B, A + 3B) = \text{span}(A, B) = \text{span}(A + B, A - B)$ , so  $Lie^1$ , hence every  $Lie^n$ , will be the same as in (a).  $\square$

**c** Assume that  $\alpha = \pm 1$ . Prove that for any point  $E \in M$  the attainable set from  $E$  coincides with the orbit, and find the dimension of every orbit.

*Proof.* Since  $SO(4)$  is a compact Lie group, the family of vector fields  $\mathcal{F}$  corresponding to the control system is Poisson stable (as shown in class). Hence, for every  $f \in \mathcal{F}$ ,  $-f$  is compatible with  $\mathcal{F}$ . Thus the attainable set is dense in the orbit of  $E$ .

By part (a), the orbit of  $E$  lies in an immersed submanifold  $N$  with  $T_q(N) = Lie^3(q)$  for all  $q \in N$ . By passing to the connected component of  $N$  containing  $E$ , WLOG  $N$  is connected. Then by the Rachevskii-Chow theorem,  $\mathcal{F}$  is controllable on  $N$ . Hence by Krener's theorem, the attainable set of  $E$  is equal to  $N$ , which coincides with the orbit of  $E$ . For every point  $q \in M$ , the orbit of  $q$  has dimension  $\dim(Lie^3(q)) = 4$ .  $\square$

**d** Assume that  $\alpha = 1$ . Define complex scalar multiplication on  $\mathbb{R}^4$  by  $ie_1 = -e_4$ ,  $ie_4 = e_1$ ,  $ie_2 = e_3$ , and  $ie_3 = -e_2$ . Show that a matrix  $D$  belongs to the tangent space at the identity  $I$  to the orbit iff the corresponding linear operator  $\hat{D}$  is also linear over  $\mathbb{C}$  and the 2x2 matrix  $D_1$  corresponding to this operator in the complex basis  $(e_1, e_2)$  satisfies  $\overline{D_1^T} = D_1$ .

*Proof.* Suppose  $v = \sum_{j=1}^4 v_j e_j \in \mathbb{R}^4$  and  $U \in M_4(\mathbb{R})$ , then  $U(iv) = U(v_1(-e_4) + v_2(e_3) + v_3(-e_2) + v_4(e_1)) = v_4 U e_1 - v_3 U e_2 + v_2 U e_3 - v_1 U e_4$ . We also have  $F_{jk} e_l = E_{jk} e_l - E_{kj} e_l = \delta_{kl} e_j - \delta_{jl} e_k$ .

Hence,

$$\begin{aligned} iF_{jk}(v) &= i \sum_l v_l (\delta_{kl} e_j - \delta_{jl} e_k) \\ &= v_k (ie_j) + v_j (-ie_k) \end{aligned}$$

and

$$\begin{aligned} F_{jk}(iv) &= v_4 F_{jk} e_1 - v_3 F_{jk} e_2 + v_2 F_{jk} e_3 - v_1 F_{jk} e_4 \\ &= v_4 (\delta_{k1} e_j - \delta_{j1} e_k) - v_3 (\delta_{k2} e_j - \delta_{j2} e_k) + v_2 (\delta_{k3} e_j - \delta_{j3} e_k) - v_1 (\delta_{k4} e_j - \delta_{j4} e_k) \\ &= (\delta_{k1} v_4 - \delta_{k2} v_3 + \delta_{k3} v_2 - \delta_{k4} v_1) e_j + (-\delta_{j1} v_4 + \delta_{j2} v_3 - \delta_{j3} v_2 + \delta_{j4} v_1) e_k \end{aligned}$$

Hence,

$$\begin{aligned} F_{12}(iv) &= -v_3 e_1 - v_4 e_2 = -v_3 (ie_4) - v_4 (-ie_3) = iF_{34}v \\ F_{13}(iv) &= v_2 e_1 - v_4 e_3 = v_2 (ie_4) - v_4 (ie_2) = iF_{42}v \\ F_{14}(iv) &= -v_1 e_1 - v_4 e_4 = -v_1 (ie_4) - v_4 (-ie_1) = iF_{14}v \\ F_{23}(iv) &= v_2 e_2 + v_3 e_3 = v_2 (-ie_3) + v_3 (ie_2) = iF_{23}v \\ F_{24}(iv) &= -v_1 e_2 + v_3 e_4 = -v_1 (-ie_3) + v_3 (-ie_1) = iF_{31}v \\ F_{34}(iv) &= -v_1 e_3 - v_2 e_4 = -v_1 (ie_2) - v_2 (-ie_1) = iF_{12}v \end{aligned}$$

Thus,  $\mathcal{B} := \{F_{14}, F_{23}, F_{34} + F_{12}, F_{13} + F_{42}\}$  is an  $\mathbb{R}$ -basis for the subspace of  $T_I(M)$  consisting of all  $\mathbb{C}$ -linear operators. From (a), we know that  $\mathcal{B}$  is also an  $\mathbb{R}$ -basis for  $Lie_I^3(M) = T_I(O_I(\mathcal{F}))$ . Hence,  $T_I(O_I(\mathcal{F}))$  coincides with the  $\mathbb{C}$ -linear subspace of  $T_I(M)$ . In the  $\mathbb{C}$ -basis  $\{e_1, e_2\}$  for  $\mathbb{R}^4$  with the given complex structure, we have

$$F_{14} = \begin{pmatrix} i & 0 \\ 0 & 0 \end{pmatrix} \quad F_{23} = \begin{pmatrix} 0 & 0 \\ 0 & i \end{pmatrix}$$

and

$$F_{34} + F_{12} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \quad F_{13} + F_{42} = \begin{pmatrix} 0 & -i \\ -i & 0 \end{pmatrix}$$

All of these matrices are self adjoint. Hence each element of  $\text{span}(\mathcal{B})$  is also self-adjoint.  $\square$