

FINITENESS FOR MAPPING CLASS GROUP REPRESENTATIONS FROM TWISTED DIJKGRAAF-WITTEN THEORY

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ABSTRACT. We show that any twisted Dijkgraaf-Witten representation of a mapping class group of an orientable, compact surface with boundary has finite image. This generalizes work of Etingof, Rowell and Witherspoon showing that the braid group images are finite [7]. In particular, we answer a question posed by them in the affirmative.

Any twisted Dijkgraaf-Witten representation associated to a finite group G and 3-cocycle ω is isomorphic to a Turaev-Viro-Barrett-Westbury (TVBW) representation associated to the spherical fusion category Vec_G^ω of twisted G -graded vector spaces. Moreover, the representation space for this TVBW representation is canonically isomorphic to a vector space of Vec_G^ω -colored graphs embedded in the surface [9]. We show that the mapping class group permutes a finite spanning set for this vector space, hence the image of the representation is finite.

1. INTRODUCTION

Given a spherical fusion category \mathcal{A} over a field k and an oriented compact surface Σ , possibly with boundary, the Turaev-Viro-Barrett-Westbury (TVBW) construction gives a projective representation of the mapping class group $\text{MCG}(\Sigma)$ [15, 3]. A natural problem is to determine the images of such representations. In particular, we would like to know when such a representation has finite image.

It is conjectured any TVBW mapping class group representation associated to a spherical fusion category \mathcal{A} has finite image if and only if \mathcal{A} is weakly integral. This conjecture is a modification of the Property F conjecture [11, 7], which states that braid group representations coming from a braided monoidal category \mathcal{C} should have finite image if and only if \mathcal{C} is weakly integral. Instead of only considering braid group representations, one can consider mapping class groups of arbitrary orientable surfaces. In this case, the input categories to construct the representations must be more specialized than just braided monoidal. One can either apply the Reshitikhin-Turaev construction to a modular tensor category, or apply the TVBW construction to a spherical fusion category. The former is more general than the latter since the Reshitikhin-Turaev construction for the Drinfeld center $Z(\mathcal{A})$ of a spherical fusion category \mathcal{A} yields the same representation as the TVBW construction for \mathcal{A} . However, for the case considered in this paper, the simpler TVBW construction suffices.

In this paper, our input category is $\mathcal{A} = \text{Vec}_G^\omega$, the spherical fusion category of G -graded vector spaces with associativity modified by a cocycle $\omega \in Z^3(G, k^\times)$. In this case, the TVBW construction corresponds to the twisted Dijkgraaf-Witten theory of [5]. The category Vec_G^ω is integral, so one expects its associated mapping class group representations to have finite image. The main contribution of this paper is to verify this for arbitrary G and ω .

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2. RELATED WORK

The closest related work is a result of Etingof, Rowell, and Witherspoon who showed purely algebraically that the braid group representations associated to the modular category $\text{Mod}(D^\omega(G))$ have finite images [7]. The braid group B_n is the mapping class group of a disk with n marked points relative to its boundary, so they asked whether their result generalizes to arbitrary mapping class group representations associated to $\text{Mod}(D^\omega(G))$. This paper answers their question affirmatively, using a more geometric method of proof.

Prior to the current work, certain specific cases had already been solved. In the case of the torus, Ng and Schauenburg's Congruence Subgroup Theorem implies the much stronger result that any Reshitikhin-Turaev representation of the mapping class group of the torus has finite image [12]. Another related result is due to Fjelstad and Fuchs [8]. They showed that, given a surface with at most one boundary component, the mapping class group representations corresponding to the untwisted (i.e. $\omega = 1$) Dijkgraaf-Witten theory have finite image. Their paper uses an algebraic method of Lyubashenko [10] that gives a projective mapping class group representation to any factorizable ribbon

1 Hopf algebra, in their case, the double $D(G)$. In our case, we instead consider the mapping class group action on
2 a vector space of Vec_G^ω -colored embedded graphs defined by Kirillov [9], yielding a simpler, geometric proof of the
3 more general twisted case.

4 Bantay also calculated the images of certain representations of mapping class groups on the Hilbert space of an
5 orbifold model associated to $D^\omega(G)$ [2]. These representations appear to coincide with the twisted Dijkgraaf-Witten
6 representations. However, due to lack of proof, the precise connection is unclear.

3. BACKGROUND

3.1. **The spherical fusion category Vec_G^ω .** The following definitions are well-known and can be found in, e.g., [6]. Let
 k be an algebraically closed field of characteristic 0, G a finite group, and $\omega \in Z^3(G, k^\times)$ a 3-cocycle. The spherical
fusion category of G -graded k -vector spaces with associativity defined by ω is denoted Vec_G^ω . The objects of this
category are vector spaces with a decomposition $V = \bigoplus_{g \in G} V_g$. Morphisms are linear maps preserving the grading.
The tensor product is defined by

$$(V \otimes W)_g = \bigoplus_{x, y \in G, xy=g} V_x \otimes W_y.$$

8 For each $g \in G$, pick a 1-dimensional vector space $\delta_g \in \text{Obj}(\text{Vec}_G^\omega)$ concentrated in degree g . The set $\{\delta_g : g \in G\}$
9 is a complete set of pairwise non-isomorphic representatives for the isomorphism classes of simple objects of Vec_G^ω .
10 We will sometimes abuse notation by referring to an object δ_g by the group element g . We have $1 \cong \delta_1$, and $\delta_g^* := \delta_{g^{-1}}$
11 with the coevaluation and evaluation maps defined below.

For the structural morphisms, we follow [13]. We will treat the canonical isomorphisms $\delta_g \otimes \delta_h \cong \delta_{gh}$ as identities.
The associator $\alpha_{g,h,k} : (\delta_g \otimes \delta_h) \otimes \delta_k \rightarrow \delta_g \otimes (\delta_h \otimes \delta_k)$ is defined by

$$\alpha_{g,h,k} = \omega(g, h, k) \text{id}_{ghk}.$$

The evaluator $\text{ev}_g : \delta_g^* \otimes \delta_g \rightarrow 1$ is

$$\text{ev}_g = \omega(g^{-1}, g, g^{-1}) \text{id}_1.$$

The coevaluator $\text{coev}_g : 1 \rightarrow \delta_g \otimes \delta_g^*$ is

$$\text{coev}_g = \text{id}_1.$$

The pivotal structure $j_g : \delta_g \rightarrow \delta_g^{**}$ is

$$j_g = \omega(g^{-1}, g, g^{-1}) \text{id}_g.$$

12 If ω and ω' are cohomologous cocycles, then Vec_G^ω is monoidally equivalent to $\text{Vec}_G^{\omega'}$ [6]. This equivalence respects
13 the pivotal structure, so extends to an equivalence of spherical categories. It is a basic result in group cohomology that
14 any cocycle $\omega \in Z^3(G, k^\times)$ is cohomologous to a cocycle taking values in $\mu_{|G|}$, the roots of unity of order $|G|$. Thus,
15 by replacing Vec_G^ω with an equivalent spherical category, we assume without loss of generality that $\text{Im}(\omega) \subset \mu_{|G|}$.

3.2. **Colored graphs.** The following definitions and theorem are due to Kirillov [9], and recorded here for conve-
17 nience. For any spherical fusion category \mathcal{A} and surface Σ , Kirillov gives the following presentation of the Levin-Wen
18 model as a vector space of colored graphs modulo local relations. He also proves that this space is canonically isomor-
19 phic to the TVBW vector space associated to Σ . It is straightforward to check that this isomorphism, which amounts
20 to replacing a triangulation with its dual graph, commutes with the mapping class group action.

21 We use the convention that a tensor product of multiple objects with parentheses omitted correspond to the left-
22 associative parenthesization.

23 We define the functor $\mathcal{A}^{\boxtimes n} \rightarrow \text{Vec}$ by

$$(1) \quad \langle V_1, \dots, V_n \rangle = \text{Hom}_{\mathcal{A}}(1, V_1 \otimes \dots \otimes V_n)$$

24 for any collection V_1, \dots, V_n of objects of \mathcal{A} . Note that pivotal structure gives functorial isomorphisms

$$(2) \quad z : \langle V_1, \dots, V_n \rangle \cong \langle V_n, V_1, \dots, V_{n-1} \rangle$$

where, up to associators,

$$z(\phi) = (j^{**}_{V_n} \otimes \text{id}_{V_1 \otimes \dots \otimes V_{n-1}} \otimes \text{ev}_{V_n}) \circ (\text{id}^{**}_{V_n} \otimes \phi \otimes \text{id}_{V_n}) \circ \text{coev}^{**}_{V_n}$$

25 and $z^n = \text{id}$ (see [1, Section 5.3]). Thus, up to a canonical isomorphism, the space $\langle V_1, \dots, V_n \rangle$ only depends on the
26 cyclic order of V_1, \dots, V_n .

We have a natural composition map

$$(3) \quad \begin{aligned} \langle V_1, \dots, V_n, X \rangle \otimes \langle {}^*X, W_1, \dots, W_m \rangle &\rightarrow \langle V_1, \dots, V_n, W_1, \dots, W_m \rangle \\ \varphi \otimes \psi &\mapsto \varphi \circ_X \psi = \text{ev}_X \circ (\varphi \otimes \psi), \end{aligned}$$

up to associators. Note that, due to the order of X and *X in the tensor product, we use the right evaluation map $\text{ev}_X: X \otimes {}^*X \rightarrow 1$ for the left dual *X , instead of the right evaluation map $\text{ev}_X: X^* \otimes X \rightarrow 1$ for X . Since ${}^*X \cong X^*$, the defining equation for ev_X in $\text{Vec}_G^{\mathcal{O}}$ is the same as for ev_{X^*} , i.e. $\text{ev}_g = \omega(g, g^{-1}, g) \text{id}_1$.

We will consider finite graphs embedded in an oriented surface Σ (which may have boundary); for such a graph Γ , let $E(\Gamma)$ be the set of edges. Note that edges are not oriented. Let E^{or} be the set of oriented edges, i.e. pairs $\mathbf{e} = (e, \text{orientation of } e)$; for such an oriented edge \mathbf{e} , we denote by $\bar{\mathbf{e}}$ the edge with opposite orientation.

If Σ has a boundary, the graph is allowed to have uncolored one-valent vertices on $\partial\Sigma$ but no other common points with $\partial\Sigma$; all other vertices will be called interior. We will call the edges of Γ terminating at these one-valent vertices *legs*.

Definition 3.1. Let Σ be an oriented surface (possibly with boundary) and $\Gamma \subset \Sigma$ — an embedded graph as defined above. A coloring of Γ is the following data:

- Choice of an object $V(\mathbf{e}) \in \text{Obj } \mathcal{A}$ for every oriented edge $\mathbf{e} \in E^{or}(\Gamma)$ so that $V(\bar{\mathbf{e}}) = V(\mathbf{e})^*$.
- Choice of a vector $\varphi(v) \in \langle V(\mathbf{e}_1), \dots, V(\mathbf{e}_n) \rangle$ (see (1)) for every interior vertex v , where $\mathbf{e}_1, \dots, \mathbf{e}_n$ are edges incident to v , taken in counterclockwise order and with outward orientation.

An isomorphism f of two coloring $\{V(\mathbf{e}), \varphi(v)\}$, $\{V'(\mathbf{e}), \varphi'(v)\}$ is a collection of isomorphisms $f_{\mathbf{e}}: V(\mathbf{e}) \cong V'(\mathbf{e})$ which agree with isomorphisms $V(\bar{\mathbf{e}}) = V(\mathbf{e})^*$ and which identify φ', φ : $\varphi'(v) = f \circ \varphi(v)$.

We will denote the set of all colored graphs on a surface Σ by $\text{Graph}(\Sigma)$.

Note that if Σ has a boundary, then every colored graph Γ defines a collection of points $B = \{b_1, \dots, b_n\} \subset \partial\Sigma$ (the endpoints of the legs of Γ) and a collection of objects $V_b \in \text{Obj } \mathcal{A}$ for every $b \in B$: the colors of the legs of Γ taken with outgoing orientation. We will denote the pair $(B, \{V_b\})$ by $\mathbf{V} = \Gamma \cap \partial\Sigma$ and call it *boundary value*. We will denote

$$\text{Graph}(\Sigma, \mathbf{V}) = \text{set of all colored graphs in } \Sigma \text{ with boundary value } \mathbf{V}.$$

We can also consider formal linear combinations of colored graphs. Namely, for fixed boundary value \mathbf{V} as above, we will denote

$$(4) \quad \text{VGraph}(\Sigma, \mathbf{V}) = \{\text{formal linear combinations of graphs } \Gamma \in \text{Graph}(\Sigma, \mathbf{V})\}$$

In particular, if $\partial\Sigma = \emptyset$, then the only possible boundary condition is trivial ($B = \emptyset$); in this case, we will just write $\text{VGraph}(\Sigma)$.

The following theorem is a variation of result of Reshitikhin and Turaev.

Theorem 3.2. There is a unique way to assign to every colored planar graph Γ in a disk $D \subset \mathbb{R}^2$ a vector

$$(5) \quad \langle \Gamma \rangle_D \in \langle V(\mathbf{e}_1), \dots, V(\mathbf{e}_n) \rangle$$

where $\mathbf{e}_1, \dots, \mathbf{e}_n$ are the edges of Γ meeting the boundary of D (legs), taken in counterclockwise order and with outgoing orientation, so that that following conditions are satisfied:

- (1) $\langle \Gamma \rangle$ only depends on the isotopy class of Γ .
- (2) If Γ is a single vertex colored by $\varphi \in \langle V(\mathbf{e}_1), \dots, V(\mathbf{e}_n) \rangle$, then $\langle \Gamma \rangle = \varphi$.
- (3) Local relations shown in Figure 1 hold.

Local relations should be understood as follows: for any pair Γ, Γ' of colored graphs which are identical outside a subdisk $D' \subset D$, and in this disk are homeomorphic to the graphs shown in Figure 1, we must have $\langle \Gamma \rangle = \langle \Gamma' \rangle$.

Moreover, so defined $\langle \Gamma \rangle$ satisfies the following properties:

- (1) $\langle \Gamma \rangle$ is linear in color of each vertex v (for fixed colors of edges and other vertices).
- (2) $\langle \Gamma \rangle$ is additive in colors of edges as shown in Figure 2.
- (3) If Γ, Γ' are two isomorphic colorings of the same graph, then $\langle \Gamma \rangle = \langle \Gamma' \rangle$.
- (4) Composition property: if $D' \subset D$ is a subdisk such that $\partial D'$ does not contain vertices of Γ and meets edges of Γ transversally, then $\langle \Gamma \rangle_D$ will not change if we replace subgraph $\Gamma \cap D'$ by a single vertex colored by $\langle \Gamma \cap D' \rangle_{D'}$.

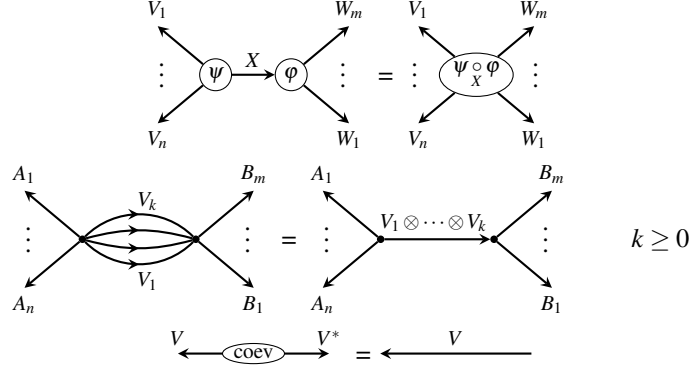


FIGURE 1. Local relations for colored graphs.

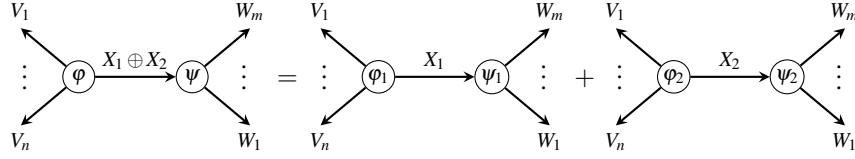


FIGURE 2. Linearity of $\langle \Gamma \rangle$. Here ϕ_1, ϕ_2 are compositions of ϕ with projector $X_1 \oplus X_2 \rightarrow X_1$ (respectively, $X_1 \oplus X_2 \rightarrow X_2$), and similarly for ψ_1, ψ_2 .

1 The vector $\langle \Gamma \rangle$ is called the evaluation of Γ .

2 To define local relations between graphs, Kirillov defines the space of null graphs as follows. Let $\Gamma = c_1 \Gamma_1 + \dots +$
3 $c_n \Gamma_n$ be a formal linear combination of colored graphs in Σ . If there exists an embedded disk $D \subset M$ such that

- 4 (1) Γ is transversal to ∂D (i.e., no vertices of Γ_i are on the boundary of D and edges of each Γ_i meet ∂D transversally),
5 (2) all Γ_i coincide outside of D ,
6 (3) and $\langle \Gamma \rangle_D = \sum c_i \langle \Gamma_i \cap D \rangle_D = 0$;
7 then Γ is called a null graph.

Definition 3.3. The vector space $H := H(\Sigma, \mathbf{V})$ associated to a oriented surface Σ with boundary condition \mathbf{V} by the spherical fusion category \mathcal{A} is the quotient space

$$H(\Sigma, \mathbf{V}) = \text{VGraph}(\Sigma, \mathbf{V}) / N(\Sigma, \mathbf{V})$$

9 where $N(\Sigma, \mathbf{V})$ is the subspace spanned by null graphs (for all possible embedded disks $D \subset \Sigma$).

10 4. RESULTS

11 To show that the image of any Vec_G^ω mapping class group representation is finite, we will analyze the action of
12 the mapping class group on a finite collection of colored graphs that span the representation space H . To define this
13 spanning set, we will need the following definitions of simple morphisms and simple colored graphs.

14 **Definition 4.1.** Let $g_1, \dots, g_n \in G$. A morphism $\phi \in \langle g_1, \dots, g_n \rangle$ will be called simple if it is the composition of the
15 isomorphism $1 \cong \delta_1$ and tensor product isomorphisms of the form $\delta_{gh} \cong \delta_g \otimes \delta_h$.

16 By MacLane's coherence theorem, there is a unique simple morphism in $\langle g_1, \dots, g_n \rangle$ whenever $\prod_{i=1}^n g_i = 1$. This
17 simple morphism is a canonical basis element for the 1-dimensional space $\langle g_1, \dots, g_n \rangle$. We will describe a map
18 between such spaces as multiplication by a scalar, where the scalar is the matrix coefficient of the map with respect to
19 these canonical bases.

20 **Definition 4.2.** Let Γ be a graph embedded in a surface Σ . A Vec_G^ω coloring (V, ϕ) of Γ will be called simple if the
21 following conditions both hold:

- (1) For every oriented edge $\mathbf{e} \in E^{or}(\Gamma)$, there exists a group element $g(\mathbf{e}) \in G$ such that the coloring $V(e_i) = \delta_{g(\mathbf{e})}$.
- (2) If v is an interior vertex of Γ , then there exists an enumeration $\mathbf{e}_1, \dots, \mathbf{e}_n$ of the edges incident to v , taken in counterclockwise order and with outward orientation, such that $\prod_{i=1}^n g(\mathbf{e}_i) = 1$ and $\phi(v) \in \langle g(\mathbf{e}_1), \dots, g(\mathbf{e}_n) \rangle$ is a simple morphism.

Lemma 4.3. Let $\phi \in \langle g_1, \dots, g_n \rangle$ and $\psi \in \langle g_n, g_1, \dots, g_{n-1} \rangle$ be simple morphisms. Then $z(\phi) = \alpha\psi$, where $\alpha \in \mu_{|G|}$.

Proof. The definition of the z -morphism in Equation 2 only involves tensors and compositions of structural morphisms – i.e. associators, unitors, the pivotal j -morphism, evaluation, and coevaluation morphisms. Since all the tensor factors in the codomain of ϕ are simple objects, the definition of $\text{Vec}_G^{\mathcal{O}}$ states that each of the structural morphisms simply consist of multiplication by elements of the form $\omega(g, h, k)$ for some $g, h, k \in G$. Thus, $z(\phi) = \alpha\psi$ for some α which is a product of elements in $\text{Im}(\omega)$. Since $\text{Im}(\omega) \subset \mu_{|G|}$, it follows that $\alpha \in \mu_{|G|}$. \square

Proposition 4.4. Let Γ be a simple colored graph embedded in a surface Σ . Let Δ be the colored graph given by applying one of the three local moves in Figure 1 to Γ . Then

- (1) each edge of Δ is labeled by δ_g for some $g \in G$, and
- (2) there exists $\alpha \in \mu_{|G|}$ such that

$$\Delta - \alpha\Delta' \in N(\Sigma, \mathbf{V}),$$

where Δ' is a simple colored graph given by replacing each vertex label in Δ with a simple morphism.

Proof. The proof of (1) follows directly from the definition of each local move. For (2), we'll consider each local move separately. In each case, we need to show that Δ is equivalent to $\alpha\Delta'$ in H .

For the first (edge contraction) local move in Figure 1, using the same notation as in the figure, the vertex label $\psi \circ \phi_X$ in Δ is given by the following composition. Since Γ is simple, there exist integers l, k and simple morphisms ϕ', ψ' such that $\psi = z^l(\psi')$ and $\phi = z^k(\phi')$. Then we repeatedly apply associators and the cyclic z -morphism of Equation 2 to ϕ and ψ until the tensor factors of the codomain are rearranged in the order of the left hand side of Equation 3 and that X and X^* are isolated (not contained in any parentheses). After applying the ev_X morphism, we reassociate until the new label $\phi \circ_X \psi$ has the left-associated parenthesization. Since every edge is labeled by a simple object, each associator morphism consists of multiplication by $\omega(g, h, k)$ for some $g, h, k \in G$. Similarly, by Lemma 4.3, every z -morphism consists of multiplication by some $\beta \in \mu_{|G|}$. Thus, the overall composition consists of multiplication by an element $\alpha \in \mu_{|G|}$.

For the second local move (tensoring parallel edges), there are two cases: $k = 0$ and $k > 0$. In the $k = 0$ case, we apply inverse unitors to each vertex label introduce an edge labeled by the unit object, followed by reassociation. In the $k > 0$ case, we need to reassociate to group together labels of the parallel edges then reassociate at the end. For the same reasons as for the first move (every edge is labeled by a simple object), it follows that the result of this local move is also of the desired form.

For the third local move (adding a coev-labeled vertex), the colored graph given by direct application of the local move to a simple graph is already simple, so we can pick $\alpha = 1$. \square

4.1. No Boundary Case. We first prove our theorem in the easier case where the surface Σ is closed.

Theorem 4.5. The image of any twisted Dijkgraaf-Witten representation of a mapping class group of an orientable, closed surface Σ is finite.

Proof. Let Γ be a $\text{Vec}_G^{\mathcal{O}}$ -colored graph embedding, and let $g \geq 1$ be the genus of Σ (if $g = 0$, the mapping class group is trivial). Thinking of Σ as a quotient of its fundamental $4g$ -gon, by isotopy we may assume that the vertices of Γ lie in the interior of the polygon, none of the edges of Γ intersect the corners of the polygon, and that the edges of Γ only meet the sides of the polygon transversally. Evaluating on the interior of the polygon shows that Γ is equivalent to a graph with a single vertex whose edges are simple closed curves, each of which intersect the boundary of the polygon precisely once. By using the local relations, we can replace all the edges intersecting a side with a single edge labeled by the tensor product of their labels. If there are no edges intersecting a side, we can insert a single edge labeled by the group identity into Γ that intersects only that side. Thus, Γ is equivalent to a colored graph with one vertex v and edges e_1, \dots, e_{2g} corresponding to the standard generators of $\pi_1(M, v)$ as shown in Figure 3.

By Theorem 4.1 and the definition of the quotient map identifying the sides of the fundamental polygon, the vertex v is colored by an element $\phi(v) \in \text{Hom}(1, \bigotimes_{i=1}^g V(e_{2i-1}) \otimes V(e_{2i}) \otimes V(e_{2i-1})^* \otimes V(e_{2i})^*)$, where $V(e_i) \in \text{Obj}(\text{Vec}_G^{\mathcal{O}})$ is the coloring of the edge e_i .

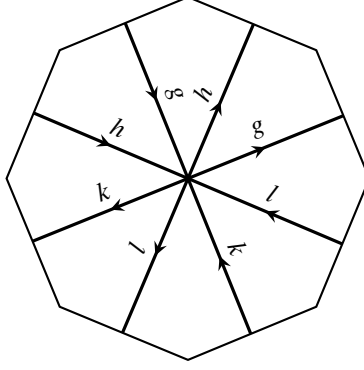


FIGURE 3. Element of the spanning set S for a genus 2 surface

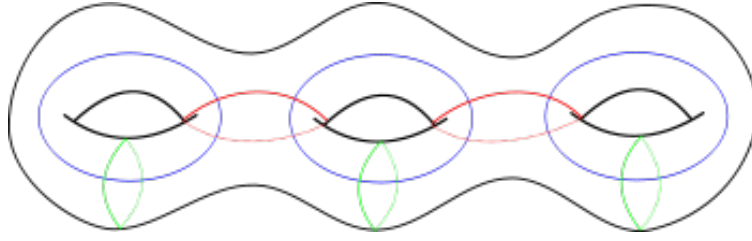


FIGURE 4. Lickorish generating set (Image source: https://en.wikipedia.org/wiki/Dehn_twist)

We claim that the representation space H is spanned by the set of such colored graphs Γ such that each $V(e_i)$ is simple. This follows from the additivity of the evaluation map of Theorem in the direct sum. Strictly speaking, we can only take advantage of the additivity on a disk, not on an edge e_i , which is a v -based loop. However, we can easily add a coev-labeled vertex to any edge e_i , apply the additivity on one of the two resulting edges (which lies in an embedded disk), and then contract on the other edge to get the decomposition we want.

Since isomorphic colorings give the same evaluation, it follows that H is spanned by colored graphs Γ such that each $V(e_i) = \delta_{g_i}$ for some $g_i \in G$. For such Γ , the space of possible v -colors $\text{Hom}(1, \bigotimes_{i=1}^g V(e_{2i-1}) \otimes V(e_{2i}) \otimes V(e_{2i-1})^* \otimes V(e_{2i})^*)$ is one-dimensional if $\prod_{i=1}^g [g_{2i-1}, g_{2i}] = 1$, and zero-dimensional otherwise.

By using the linearity in each vertex label, we can further restrict to simple colored graphs Γ . Thus, the representation space H has a spanning set S consisting of all simple colored graphs Γ with one vertex v and edges e_1, \dots, e_{2g} corresponding to the standard generators of $\pi_1(M, v)$. Since there are only $|G|$ simple objects in Vec_G^0 and at most $2g$ choices of simple morphisms labeling the vertex for any choice of edge labels, the spanning set S is finite.

The mapping class group of Σ is generated by the Lickorish generating set consisting of Dehn twists around $3g - 1$ simple closed curves. These can be divided into two types of twists: the ones around a single hole (the blue and green curves in Figure 4), and the ones connecting two holes (the red curves). The action of a Dehn twist around a simple closed curve corresponds to cutting the manifold along the curve, holding one piece in place and twisting the other piece by 2π radians in a clockwise direction, then gluing the two pieces back together.

To understand the action of each type of Dehn twist on the representation space H , we will consider the action on the spanning set S . First, we claim that we can apply local moves to any element of S to get a colored graph of the form shown in the first figure of Table 1, where the unshown part of the fundamental polygon looks the same as in the definition of S . Indeed, to pass from an arbitrary element of S , to a colored graph of the form shown in the first figure of 1, we first add coevaluation-labeled vertices to each edge intersecting the three shown sides of the fundamental polygon. Then connect the new vertices using 1-labeled edges (this corresponds to applying the second local move in Figure 1 with $k = 0$), contract the connections to get one new vertex, and tensor together the edges connecting the old vertex to the new vertex.

The action of the first type of Dehn twist on an arbitrary element of S is shown in the first two figures of Table 1. After applying the Dehn twist, we have the simple colored graph shown in the second figure of Table 1. We then

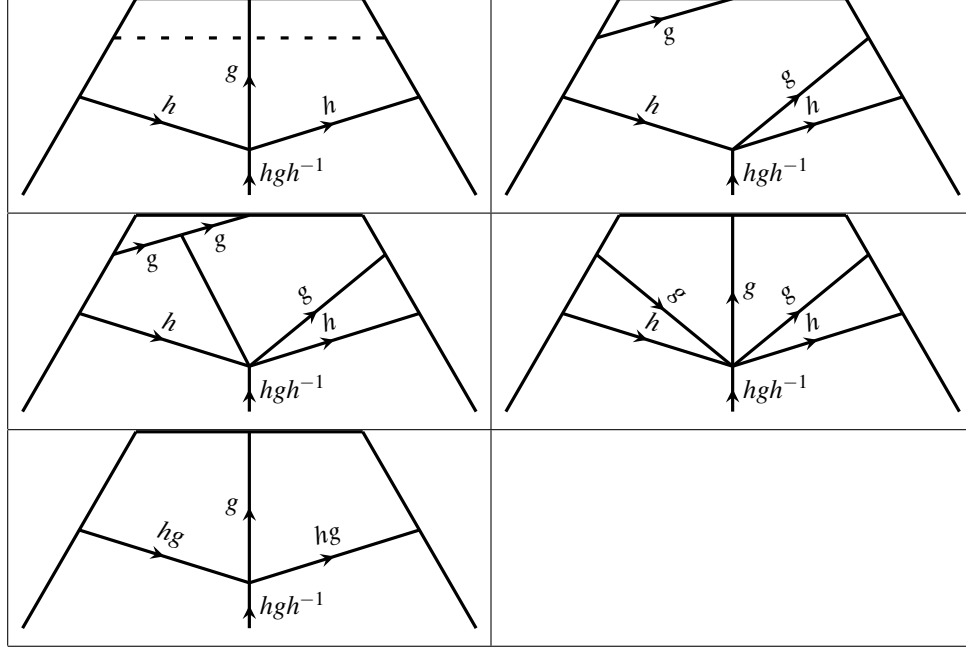


TABLE 1. First type of Dehn twist. Read from left to right, then top to bottom. The Dehn twist is performed along the dashed simple closed curve.

1 apply local moves in the remaining figures. By repeated application of Proposition 4.4, the resulting colored graph is
2 equivalent to $\beta\Delta$, for some $\beta \in \mu_{|G|}$ and $\Delta \in S$. Thus, the first type of Dehn twist maps S to $\mu_{|G|}S$.

3 An analogous proof works for the second type of Dehn twist shown in Table 2. Thus, the image of any such
4 mapping class group representation is a quotient of the group of permutations of the finite set $\mu_{|G|}S$, hence finite. \square

5 **Remark 4.6.** When $\omega = 1$ and Σ is closed, this representation is a permutation representation.

6 *Proof.* Under the assumption that the representation in [8] coincides with ours, this fact follows from Theorem 2.6 in
7 [8]. We can also see this directly by first noting that G acts on S by simultaneously conjugation of all edge labels by a
8 single element $g \in G$. If $s \in S$ and $g \in G$, then we can retrieve s from gs by separating two oppositely oriented, g -labeled
9 edges from each edge in the embedded graph gs . This results in a loop labeled by g , whose evaluation is 1. Thus gs
10 is equivalent to s . Moreover, the cardinality $|S/G| = |\text{Hom}(\pi_1(M), G)|/|G|$ is equal to the dimension of the untwisted
11 Dijkgraaf-Witten representation space H [5]. Hence, S/G is a basis for H . The mapping class group action on S
12 commutes with the G -action, so the mapping class group permutes S/G , i.e. H is a permutation representation. \square

13 **4.2. Boundary Case.** When Σ has boundary, we denote by $\text{MCG}(\Sigma)$ the group of isotopy classes of homeomorphisms
14 fixing the boundary of Σ setwise. Given any labelling of the boundary by objects in the Drinfeld center, $l : \pi_0(\partial M) \rightarrow$
15 $\text{Obj}(Z(\text{Vec}_\omega^G))$, we get a mapping class group representation. The representation space is $H(\Sigma, \mathbf{V})$ where the boundary
16 condition $\mathbf{V} = F \circ l$, where F is the forgetful functor $F : Z(\text{Vec}_\omega^G) \rightarrow \text{Vec}_\omega^G$. The same local relations are valid in this
17 representation space [9].

18 By a similar argument as in the proof of the Theorem 4.5, any such representation space has a finite spanning set S
19 consisting of all simple colored graphs with a single vertex, loops for each of the usual generators of the fundamental
20 group of Σ , and a leg from the vertex to each of the boundary components.

21 Let N denote the closed surface obtained by filling in all the boundary components of Σ with disks. The mapping
22 class group $\text{MCG}(\Sigma)$ is generated by the same Dehn twists as $\text{MCG}(N)$, as well as braids interchanging boundary
23 components and mapping classes corresponding to dragging a boundary component along a representative of a stan-
24 dard generator of $\pi_1(N)$ [4]. As in the proof of Theorem 4.5, applying any of these generators of $\text{MCG}(\Sigma)$ to a colored
25 graph in S yields an element in $\mu_{|G|}S$ (see Tables 3 and 4). Since the braid group is also generated by such braids, we
26 have the following theorem.

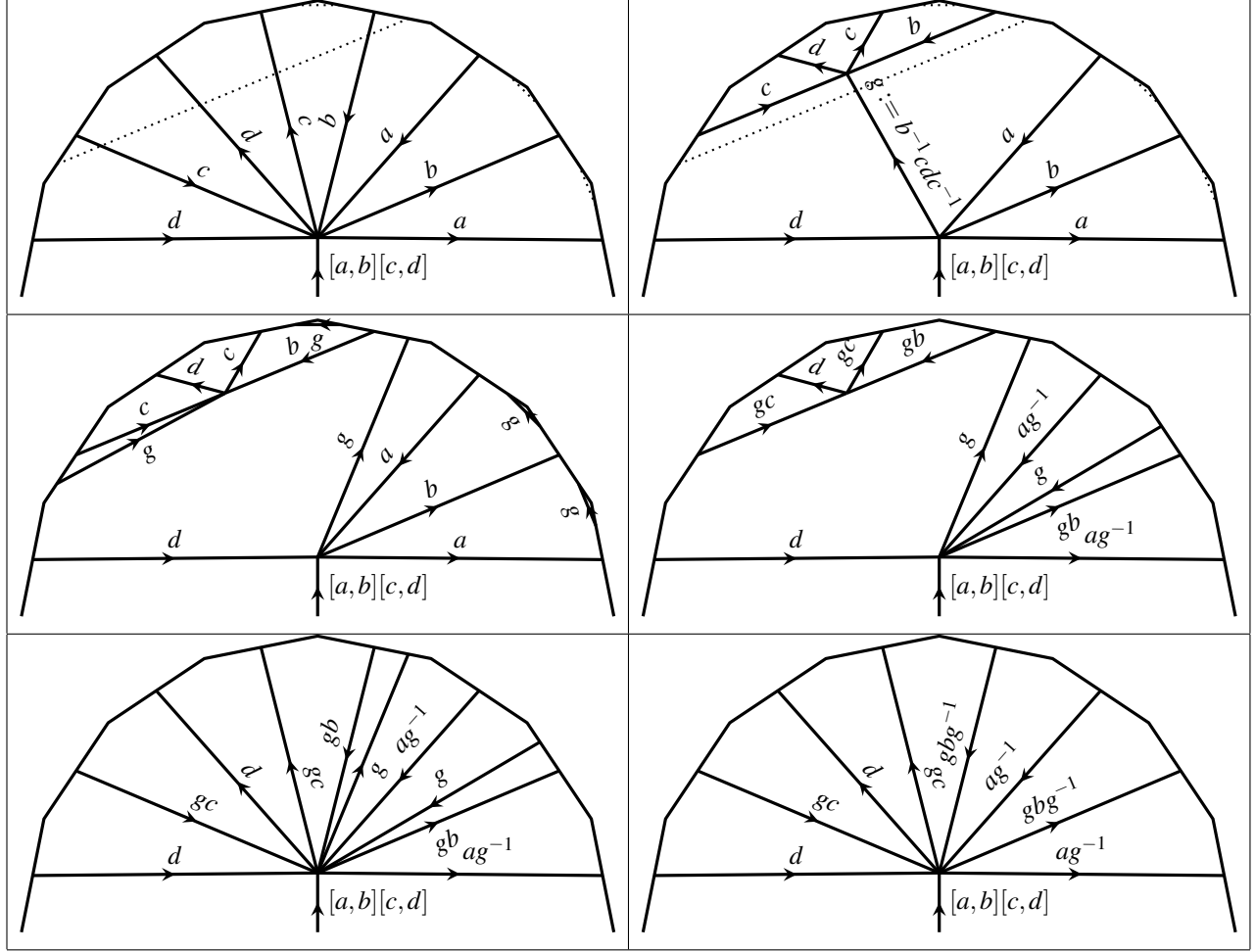


TABLE 2. Second type of Dehn twist. Read from left to right, then top to bottom. The Dehn twist is performed along the dashed simple closed curve.

Theorem 4.7. *The image of any twisted Dijkgraaf-Witten representation of a mapping class group of an orientable, compact surface with boundary is finite. In particular, the image of any such braid group representation is finite.*

5. FURTHER DIRECTIONS

We have proved that every twisted Dijkgraaf-Witten representation of a mapping class group of a compact, orientable surface has finite image. This is a generalization of the results of [7] and [8], as well as another step towards the (modified) Property F conjecture. A potential next step would be to consider more complicated spherical categories than Vec_ω^G . One candidate is the class of Tambara-Yamagami categories [14]. The main additional complication here is the appearance of multifusion channels, i.e. the tensor product of two simple objects can be a direct sum of multiple simple objects.

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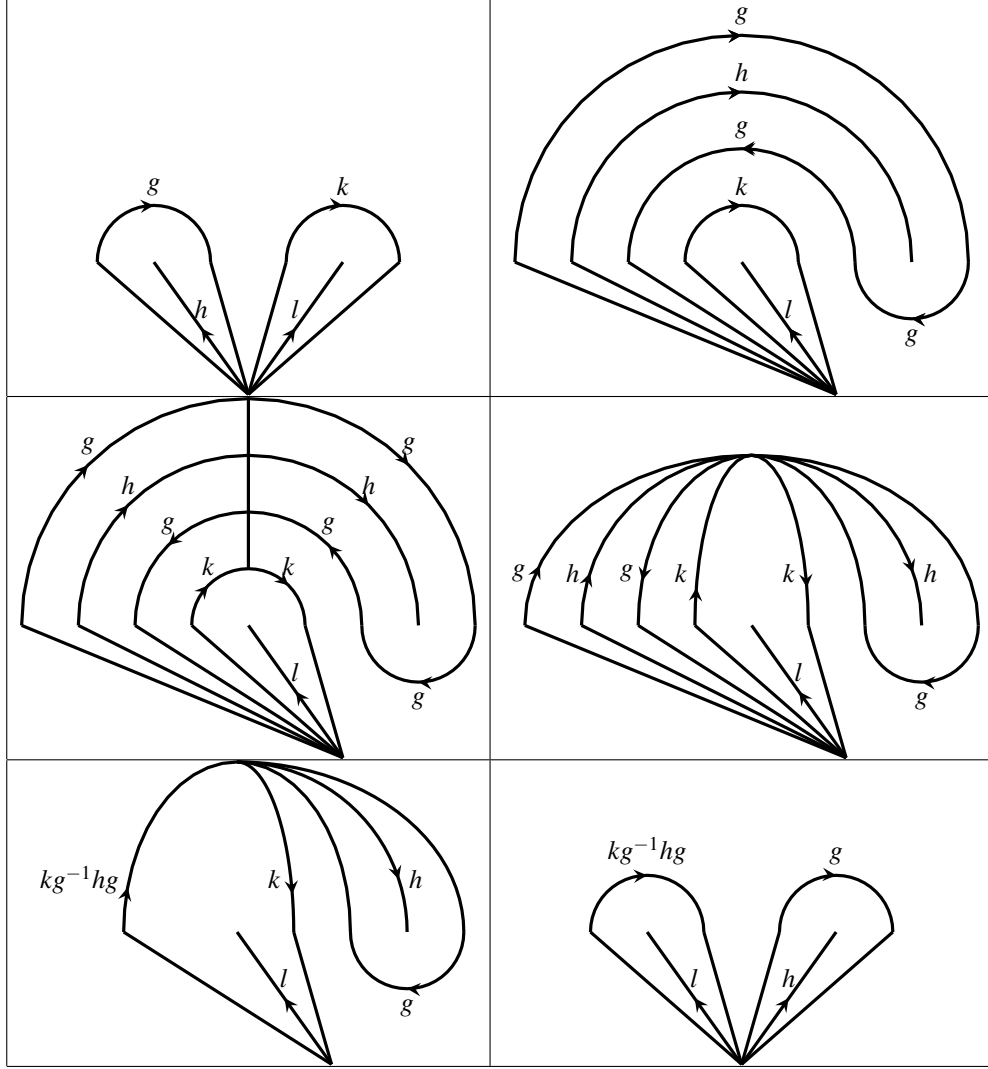


TABLE 3. A braid generator. Read from left to right, then top to bottom. Unlabeled interior edges are colored by the group identity element.

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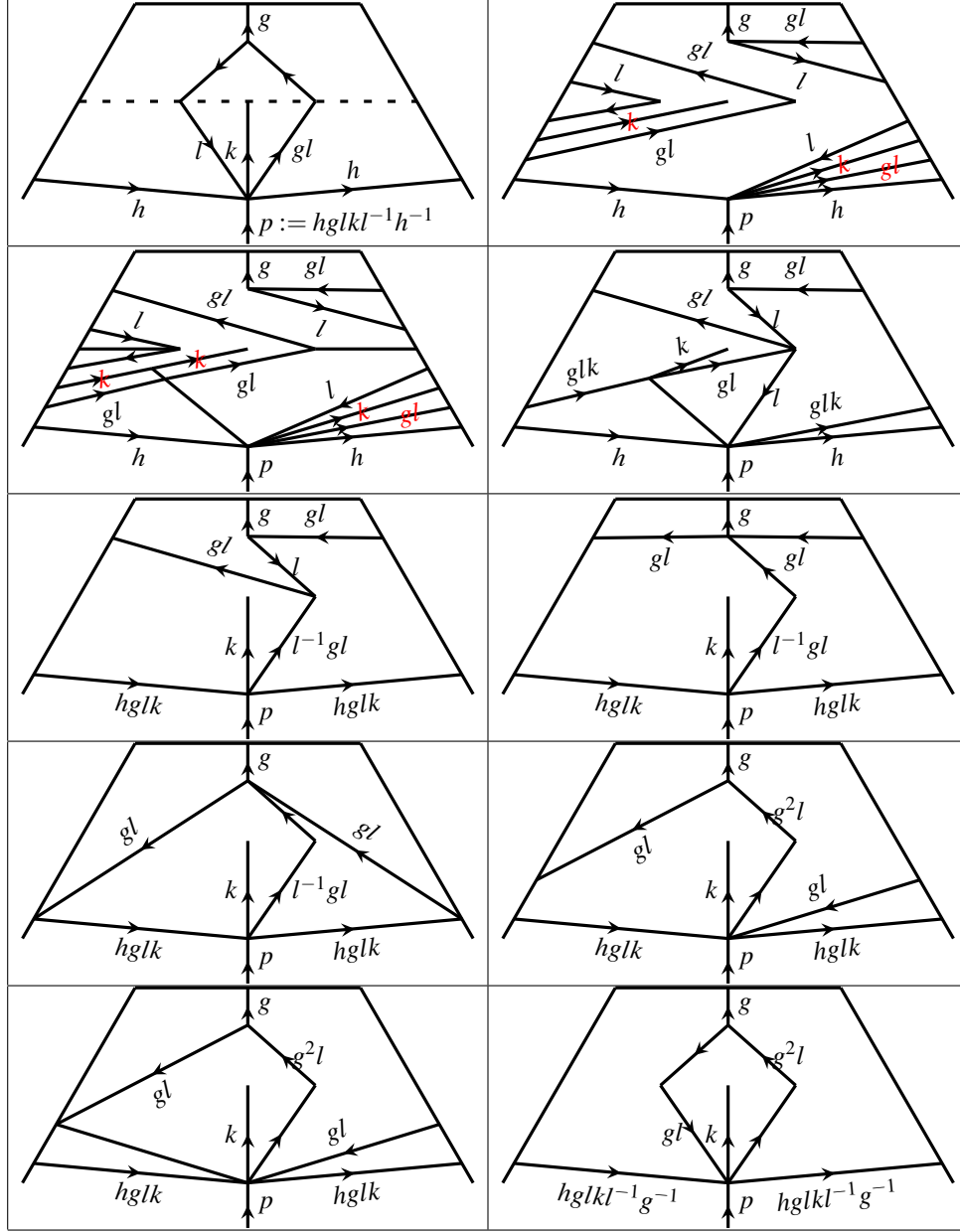


TABLE 4. Pulling a boundary component along a generator for the fundamental group of the corresponding closed surface. Read from left to right, then top to bottom. Unlabeled interior edges are colored by the group identity element.