How To Use the Notebooks

The notebooks use various packages (which you need to install) and also some local modules (FinEcmt_OLS etc) which are located in the src subfolder.

The next fell cells illustrate how to work with these notebooks.

Load Packages and Extra Functions

The next two cells puts the src subfolder in the LOAD_PATH (if it isn't already) and then loads some modules and packages.

- 1. The FinEcmt_OLS module is defined in the src subfolder. It uses many of the .jl files in that subfolder and exports the key functions. The cells below show two *different* ways of loading this module.
- 2. The Statistics package is part of the Julia distribution, so you don't have to install it (this may change in the future).
- 3. The Distributions.jl package needs to be installed. Do import Pkg; Pkg.add("Distributions").

```
#approach 1 to load the FinEcmt_OLS module, precompiles so is quicker

MyModulePath = joinpath(pwd(),"src")  #add /src to module path
!in(MyModulePath,LOAD_PATH) && push!(LOAD_PATH,MyModulePath);

using FinEcmt_OLS: OlsGM, printmat, @doc2  #to load a few functions from module
#using FinEcmt_OLS  #to load all functions in module
```

```
#approach 2 to load the FinEcmt_OLS module, works also on Colab
#=
include(joinpath(pwd(),"src","FinEcmt_OLS.jl"))
using .FinEcmt_OLS: OlsGM, printmat, @doc2  #to load a few functions from module
```

```
using Statistics, Distributions
```

See the Documentation

The next cell shows the documentation of the OLSGM function.

```
@doc2 OlsGM #`doc OlsGM` does not work in VS Code
#println(@doc OlsGM) #plain text printing instead
```

```
OlsGM(Y,X)
```

LS of Y on X; for one dependent variable, Gauss-Markov assumptions

Input

- Y:: Vector: T-vector, the dependent variable
- X:: Matrix: Txk matrix of regressors (including deterministic ones)

Output

- b:: Vector: k-vector, regression coefficients
- u:: Vector: T-vector, residuals Y yhat
- Yhat:: Vector: T-vector, fitted values X*b
- V:: Matrix: kxk matrix, covariance matrix of b
- R²:: Number: scalar, R² value

See the Source Code

To see the source code, either open the correct file in the src subfolder, or use the CodeTracking.jl package to print the source code here in the notebook. The latter approach requires "calling" on the function with some valid inputs (in this case we use [1],[1]). In many notebooks, such printing is coded but commented out.

```
function OlsGM(Y,X)

T = size(Y,1)

b = X \setminus Y

Yhat = X*b

u = Y - Yhat

\sigma^2 = var(u)

V = inv(X'X)*\sigma^2

R^2 = 1 - \sigma^2/var(Y)

return b, u, Yhat, V, R^2
```

println(@code_string OlsGM([1],[1])) #println gets the line breaks right

Use the Function

using CodeTracking

(here with some artificial inputs)

```
Y = [1,2,3]
X = [1 2;1 1;1 3]
b, = OlsGM(Y,X);
printmat(b)

1.000
0.500
```

Required External Packages

for the different local modules. These packages need to be installed:

- 1. FinEcmt_OLS: Distributions, StatsBase, FiniteDiff
- 2. FinEcmt_Lasso: OSQP
- 3. FinEcmt_TimeSeries: none
- 4. FinEcmt_MLEGMM: Optim, NLsolve, FiniteDiff

5. FinEcmt_KernelRegression: none

We also use a number of standard libraries (eg. Printf), but they are typically shipped with the Julia binary.

For the notebooks, some more external packages are needed, for instance, CodeTracking for printing the functions. See the different notebooks for more information.

In case a package is missing, Julia will give an error message (and often tell you what you need to do).

Review of Statistics

This notebook shows some basic statistics needed for this course in financial econometrics. Details are in the first chapter of the lecture notes (pdf).

It uses the Statistics package (built in) for descriptive statistics (averages, autocorrelations, etc) and the Distributions.jl package for statistical distributions (pdf, cdf, etc). For more stat functions, see the StatsBase.jl package (not used here).

Formatted printing is done with the printmat() function from the FinEcmt_OLS module (which is part of this repository). The source file is found in the src subfolder.

Load Packages and Extra Functions

```
MyModulePath = joinpath(pwd(),"src") #add /src to module path
!in(MyModulePath,LOAD_PATH) && push!(LOAD_PATH,MyModulePath)
using FinEcmt_OLS
```

```
#=
include(joinpath(pwd(),"src","FinEcmt_OLS.jl")) #alternative way
using .FinEcmt_OLS
=#
```

```
using Statistics, DelimitedFiles, Distributions
```

Distributions

Probability Density Function (pdf)

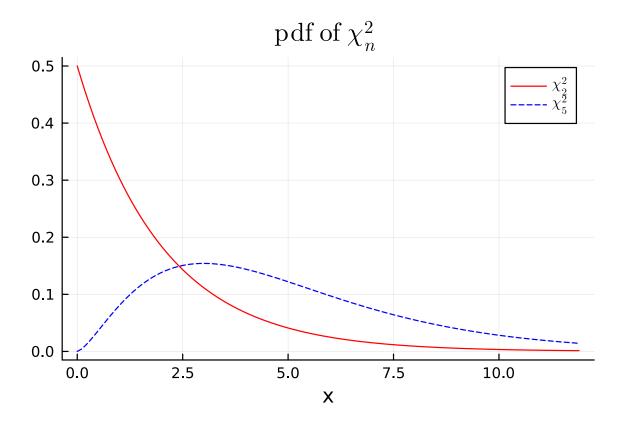
The cells below calculate and plot pdfs of some distributions often used in econometrics. The Distributions.jl package has many more distributions.

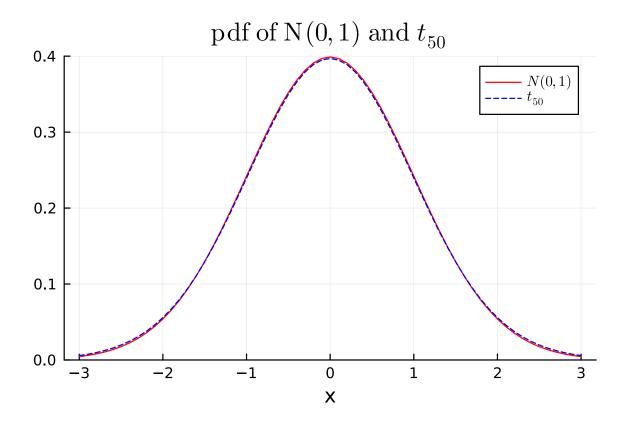
A Remark on the Code

- Notice that the Distributions.jl package wants Normal(μ , σ), where σ is the standard deviation. However, the notation in the lecture notes is $N(\mu, \sigma^2)$. For instance, N(0, 2) from the lectures is coded as Normal(0, sqrt(2)).
- pdf.(Normal(0,1),x) calculates the pdf of a standard normal variable at each value in the array x. Notice the dot(.).

```
x = -3:0.1:3
xb = x[x.<=1.645]
                                  #pick out x values <= 1.645</pre>
pdfx = pdf.(Normal(0,1),x)
                                  #calculate the pdf of a N(0,1) variable
pdfxb = pdf.(Normal(0,1),xb)
p1 = plot(x,pdfx,
                                          #plot pdf
           linecolor = :red,
           linewidth = 2,
           legend = nothing,
           ylims = (0,0.4),
           title = "pdf of N(0,1)",
           xlabel = "x",
           annotation = (1.1,0.3,text("the area covers 95%\n of the probability mass",:left,8)) )
plot!(xb,pdfxb,linecolor=:red,linewidth=2,legend=nothing,fill=(0,:red))
                                                                            #plot area under pdf
display(p1)
```

0.4 0.3 the area covers 95% of the probability mass 0.2 0.1 0.0 -3 -2 -1 0 1 2 3





Cumulative Distribution Function (cdf)

The cdf calculates the probability for the random variable (here denoted y) to be below or at a value x, for instance, $cdf(x) = Pr(y \le x)$.

Also, we can calculate the probability that y exceeds x, $\Pr(x < y)$ as $1 - \operatorname{cdf}(x)$ and $\Pr(x_1 < y \le x_2)$ as $\operatorname{cdf}(x_2) - \operatorname{cdf}(x_1)$.

A Remark on the Code

1 - cdf(x) can be coded as 1-cdf(dist,x) where dist is, for instance, Chisq(2). Alternatively, we could also use ccdf(dist,x). (The extra c stands for the complement.) We use the latter approach below.

```
\label{eq:printblue} $$ \begin{array}{lll} & & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & &
```

```
printlnPs("2<y<=3 when y is N(1,2) ",cdf(Normal(1,sqrt(2)),3)-cdf(Normal(1,sqrt(2)),2)) printlnPs("\ny>4.61 when y is Chisq(2) ",ccdf(Chisq(2),4.61)) printlnPs("y>9.24 when y is Chisq(5) ",ccdf(Chisq(5),9.24))
```

Probability of:

```
y <= -1.645 when y is N(0,1) 0.050

y <= 0 when y is N(0,1) 0.500

2 < y <= 3 when y is N(0,2) 0.062

2 < y <= 3 when y is N(1,2) 0.161

y > 4.61 when y is Chisq(2) 0.100

y > 9.24 when y is Chisq(5) 0.100
```

Quantiles (percentiles)

...are just about inverting the cdf. For instance, the 5th percentile is the value q such that cdf(q) = 0.05.

```
N_q = quantile.(Normal(0,1),[0.025,0.05])
Chisq_q = quantile(Chisq(5),0.9)

printblue("\npercentiles:")
printlnPs("2.5th and 5th percentiles of a N(0,1) ",N_q)
printlnPs("90th percentile of a Chisquare(5) ",Chisq_q)
```

```
percentiles:
2.5th and 5th percentiles of a N(0,1) -1.960 -1.645
90th percentile of a Chisquare(5) 9.236
```

Confidence Bands and t-tests

Suppose we have a point estimate equal to the value b and it has a standard deviation of σ . The next few cells create an approximate 90% confidence band around the point estimate (assuming it is normally distributed) and test various null hypotheses.

To get a somewhat more exact confidence band, replace 1.645 by quantile (Normal(0,1),0.05).

```
b = 0.5 \\ \sigma = 0.15 \\ confB = [(b-1.645*\sigma) (b+1.645*\sigma)] \\ \#std of the estimate. Do \sigma[Tab] to get \sigma \\ \#confidence band of the estimate \\ \#rintlnPs("90% confidence band around the point estimate:",confB) \\ \#rintln("If the null hypothesis is outside this band, then it is rejected")
```

90% confidence band around the point estimate: 0.253 0.747 If the null hypothesis is outside this band, then it is rejected

```
tstat1 = (b - 0.4)/\sigma  #testing H<sub>0</sub>: coefficient is 0.4

tstat2 = (b - 0.746)/\sigma  #testing H<sub>0</sub>: coefficient is 0.746

tstat3 = (b - 1)/\sigma  #testing H<sub>0</sub>: coefficient is 1.0

printblue("t-stats for different tests: are they beyond [-1.64,1.64]?\n")

rowNames = ["H<sub>0</sub>: 0.4","H<sub>0</sub>: 0.746","H<sub>0</sub>: 1"]  #Do H\_0[TAB] to get H<sub>0</sub>

printmat([tstat1,tstat2,tstat3];colNames=["t-stat"],rowNames)  #or rowNames=rowNames
```

t-stats for different tests: are they beyond [-1.64,1.64]?

compare with the confidence band

Sample period: 197901.0 to 201104.0

Load Data from a csv File

Means and Standard Deviations

If $\operatorname{std}(x)$ equals σ and x is iid, then $\operatorname{std}(\bar{x})$ equals σ/\sqrt{T} . This can be used to test hypotheses, for instance, that the mean is zero.

```
Rme HML average 0.602 0.330 std 4.604 3.127
```

```
printblue("std of sample average (assuming iid data):\n")

StdAvg = σ/sqrt(T)
tstat = xbar./StdAvg  #testing if the means are zero

printmat([xbar;StdAvg;tstat],colNames=["Rme","HML"],rowNames=["average","std(average)","t-stat"])
```

std of sample average (assuming iid data):

	Rme	HML
average	0.602	0.330
std(average)	0.234	0.159
t-stat	2.575	2.079

Skewness, Kurtosis and Jarque-Bera

We here construct the skewness, kurtosis and JB statistics ourselves. Otherwise, you could use the functions in the StatsBase.jl package.

The easiest approach is apply the tests to standardised data, $x = (y - \mu)/\sigma$.

Under the null hypothesis (x is N(0,1)), the skewness estimate is distributed as N(0,6/T) and the kurtosis as N(3,24/T). Since the two estimates two are independent, the Jarque-Bera test is just an application of the principle that $v^2 + w^2 \sim \chi_2^2$ if v and w are both distributed as N(0,1) and independent. To implement it, calculate

```
(\text{skewness}/\sqrt{6/T})^2 + ((\text{kurtosis} - 3)/\sqrt{24/T})^2
```

(see below)

```
x = (Rme .- mean(Rme))./std(Rme) #standardise to get zero mean and unit variance
skewness = mean(x.^3)
kurtosis = mean(x.^4)

σ_skew = sqrt(6/T)
σ_kurtosis = sqrt(24/T)

JB = (skewness/σ_skew)^2 + ((kurtosis-3)/σ_kurtosis)^2 #Chisq(2)

printblue("Skewness, kurtosis and Jarque-Bera:\n")
xx = [skewness,kurtosis,JB]
printmat(xx,colNames=["stat"],rowNames=["Skewness","Kurtosis","Jarque-Bera"])
```

Skewness, kurtosis and Jarque-Bera:

```
stat
Skewness -0.806
Kurtosis 5.347
Jarque-Bera 131.128
```

Covariances and Correlations

Let ρ be the estimated correlation coefficient. Under the null hypothesis of no correlation, $\sqrt{T} \frac{\rho}{\sqrt{1-\rho^2}}$ is distributed as N(0,1), that is, it's a t-stat.

```
println("\ncov([Rme RHML]) matrix: ")
printmat(cov([Rme RHML]))
println("\ncor([Rme RHML]) matrix: ")
printmat(cor([Rme RHML]))

\rho = cor(Rme,RHML)
tstat = sqrt(T)*\rho/sqrt(1-\rho^2)
printlnPs("correlation and its t-stat:",\rho,tstat)
```

```
cov([Rme RHML]) matrix:
```

```
21.197 -4.875

-4.875 9.775

cor([Rme RHML]) matrix:

1.000 -0.339

-0.339 1.000

correlation and its t-stat: -0.339 -7.090
```

For Data with Missing Values (indicated by NaN or missing)

We can use either the excise() or the FindNN() functions from the FinEcmt_OLS module. Alternatively, consider the NaNStatistics.jl package.

```
x = [1 11;NaN 12;3 33]

µ<sub>1</sub> = mean(excise(x),dims=1)  #excise(x) cuts rows with any NaN/missing

vv = FindNN(x)  #finds rows without any NaN/missing

µ<sub>2</sub> = mean(x[vv,:],dims=1)

printblue("averages estimated in different ways (to handle NaN/missing):")
printmat([µ<sub>1</sub>;µ<sub>2</sub>];rowNames=["excise","FindNN"],colNames=["x<sub>1</sub>","x<sub>2</sub>"])
```

Basic OLS

This notebook estimates a linear regression and reports traditional standard errors (assuming iid residuals).

For a package, consider GLM.jl or LinearRegression.jl (not used here).

Load Packages and Extra Functions

The key functions are from the FinEcmt_OLS module found in the src subfolder.

The DelimitedFiles package is used for importing the csv data file and the LinearAlgebra package for some matrix operations (eg. diag(), which extracts the diagonal of a matrix.)

```
MyModulePath = joinpath(pwd(),"src") #add /src to module path
!in(MyModulePath,LOAD_PATH) && push!(LOAD_PATH,MyModulePath)
using FinEcmt_OLS
```

```
#=
include(joinpath(pwd(),"src","FinEcmt_OLS.jl"))
using .FinEcmt_OLS
=#
```

```
using Statistics, DelimitedFiles, LinearAlgebra
```

Loading Data

```
x = nothing
printlnPs("Sample size:", size(Rme))
```

Sample size: (388,)

OLS Estimates and Their Distribution

Consider the linear regression

$$y_t = \beta' x_t + u_t,$$

When x_t and u_t are independent and u_t is iid (Gauss-Markov assumptions), then the distribution of the estimates is (typically)

$$\hat{\beta} \sim N(\beta_0, S_{xx}^{-1}\sigma^2),$$

where σ^2 is the variance of the residual and $S_{xx} = \sum_{t=1}^{T} x_t x_t'$.

In matrix form, these expressions are Y = Xb + u, and $S_{xx} = X'X$, where X is defined below.

Matrix Form

To calculate the estimates it is often convenient to work with matrices. Define $X_{T \times k}$ by letting x'_t and be the t^{th} row

$$X_{T \times k} = \begin{bmatrix} x_1' \\ \vdots \\ x_T' \end{bmatrix}$$

In contrast Y is a just a vector with T elements (or possibly a $T \times 1$ matrix).

This is implemented in the OlsGM() function from the FinEcmt_OLS module. The source file is in the src subfolder. The next cells print the documentation and source code of the function. In particular, notice the b = X Y and $V = inv(X'X)*\sigma^2$.

@doc2 OlsGM

OlsGM(Y,X)

LS of Y on X; for one dependent variable, Gauss-Markov assumptions

Input

- Y:: Vector: T-vector, the dependent variable
- X::Matrix: Txk matrix of regressors (including deterministic ones)

Output

```
b::Vector: k-vector, regression coefficients
u::Vector: T-vector, residuals Y - yhat
Yhat::Vector: T-vector, fitted values X*b
V::Matrix: kxk matrix, covariance matrix of b
R<sup>2</sup>::Number: scalar, R<sup>2</sup> value
```

```
using CodeTracking
println(@code_string OlsGM([1],[1]))  #print the source code
```

OLS Regression

end

```
Y = Rme  #to get standard OLS notation
T = size(Y,1)
X = [ones(T) RSMB RHML]
(b,-,-,V,R²) = OlsGM(Y,X)
```

```
Stdb = sqrt.(diag(V))  #standard errors

printblue("OLS Results:\n")
xNames = ["c","SMB","HML"]
printmat(b,Stdb,colNames=["b","std"],rowNames=xNames)

printlnPs("R<sup>2</sup>: ",R<sup>2</sup>)
```

OLS Results:

RegressionTable(b,V,["c","SMB","HML"]) #a function for printing regression results

	coef	stderr	t-stat	p-value
С	0.007	0.002	3.175	0.001
SMB	0.217	0.073	2.957	0.003
HML	-0.429	0.074	-5.836	0.000

Missing Values (extra)

The next cells use a simple function (excise()) to remove observations (t) where y_t and/or some of the x_t variables are NaN/missing. We illustrate the usage by a very simple example.

An alternative approach is to fill $both\ y_t$ and x_t with zeros (if any of them contains NaN/missing) by using the OLSyxReplaceNaN function and then do the regression. This is illustrated in the subsequent cell.

```
(y0,x0) = (copy(Y),copy(X))  #so we can can change some values
x0[2,2] = NaN  #set a value to NaN

(y1,x1) = excise(y0,x0)
println("obs 1-3 before")
printmat(y0[1:3],x0[1:3,:];colNames=vcat("y",xNames))
```

```
println("after")
printmat(y1[1:3],x1[1:3,:];colNames=vcat("y",xNames))
printblue("OLS using only observations without any NaN/missing:")
b = x1 y1
printmat(b)
obs 1-3 before
                           SMB
                                      HML
         У
     0.042
               1.000
                         0.037
                                    0.023
    -0.034
               1.000
                           NaN
                                    0.012
     0.058
               1.000
                         0.032
                                   -0.007
after
                           SMB
                                      HML
                   С
     0.042
               1.000
                         0.037
                                    0.023
     0.058
               1.000
                         0.032
                                   -0.007
     0.001
               1.000
                         0.022
                                    0.011
OLS using only observations without any NaN/missing:
     0.007
     0.218
    -0.428
(vv, y2, x2) = OLSyxReplaceNaN(y0, x0)
println("after")
printmat(y2[1:3],x2[1:3,:];colNames=vcat("y",xNames))
printblue("OLS from setting observations with any NaN/missing to 0:")
b = x2 \setminus y2
printmat(b)
after
                           SMB
                                      HML
                   С
         У
     0.042
               1.000
                         0.037
                                    0.023
     0.000
               0.000
                         0.000
                                    0.000
     0.058
               1.000
                         0.032
                                   -0.007
OLS from setting observations with any NaN/missing to 0:
```

0.007

Different Ways to Calculate OLS Estimates (extra)

Recall that OLS can be calculated as

$$\hat{\beta} = S_{xx}^{-1} S_{xy}$$
, where $S_{xx} = \sum_{t=1}^{T} x_t x_t'$ and $S_{xy} = \sum_{t=1}^{T} x_t y_t$.

The next cell calculates the OLS estimates in three different ways: (1) a loop to create S_{xx} and S_{xy} followed by $S_{xx}^{-1}S_{xy}$; (2) $(X'X)^{-1}X'Y$; (3) and X\Y. They should give the same result in well-behaved data sets, but (3) is probably the most stable version.

```
printblue("Three different ways to calculate OLS estimates:")
     = size(X, 2)
Sxx = zeros(k,k)
Sxy = zeros(k,1)
for t = 1:T
                               #local/global is needed in script
    #local x_t, y_t
    #global Sxx, Sxy
    x_t = X[t,:]
                               #a vector
    y_t = Y[t]
    Sxx = Sxx + x_t*x_t
                           #kxk, same as Sxx += x_t*x_t'
    Sxy = Sxy + x_t*y_t
                            #kx1, same as Sxy += x_t*y_t
end
                             #OLS coeffs, version 1
b1 = inv(Sxx)*Sxy
b2 = inv(X'X)*X'Y
                             #OLS coeffs, version 2
b3 = X \setminus Y
                             #OLS coeffs, version 3
printmat(b1,b2,b3,colNames=["b1","b2","b3"],rowNames=xNames)
```

Three different ways to calculate OLS estimates:

```
b1 b2 b3 c 0.007 0.007 0.007 SMB 0.217 0.217 0.217 HML -0.429 -0.429 -0.429
```

OLS Diagnostics

This notebook studies key properties of the model (measures of fit, normality, multicollinearity).

You may also consider the HypothesisTests.jl package (not used here).

Load Packages and Extra Functions

The key functions for the diagnostic tests are from the (local) FinEcmt_OLS module.

```
MyModulePath = joinpath(pwd(),"src")
!in(MyModulePath,LOAD_PATH) && push!(LOAD_PATH,MyModulePath)
using FinEcmt_OLS
```

```
#=
include(joinpath(pwd(),"src","FinEcmt_OLS.jl"))
using .FinEcmt_OLS
=#
```

```
using DelimitedFiles, Statistics, LinearAlgebra
```

Loading Data

```
T = size(Y,1)
X = [ones(T) RSMB RHML]
k = size(X,2)

(388,)
3

(b,u,_,V,R²) = OlsGM(Y,X) #do OLS
Stdb = sqrt.(diag(V))
```

```
Stdb = sqrt.(diag(V))
printblue("OLS with traditional standard errors:\n")
xNames = ["c","SMB","HML"]
printmat([b Stdb],colNames=["coef","std"],rowNames=xNames)
```

OLS with traditional standard errors:

```
coef std
c 0.007 0.002
SMB 0.217 0.073
HML -0.429 0.074
```

Measures of Fit

Adjusted R², AIC, BIC (the two latter is discussed in more detail in another chapter)

```
@doc2 RegressionFit
#using CodeTracking
#println(@code_string RegressionFit([1],0.0,3))  #print the source code
```

RegressionFit(u,R²,k)

Calculate adjusted R², AIC and BIC from regression residuals.

Input

```
• R<sup>2</sup>::Float: the R<sup>2</sup> value
• k::Int: number of regressors

(R<sup>2</sup>adj,AIC,BIC) = RegressionFit(u,R<sup>2</sup>,k)

printblue("Measures of fit")
printmat([R<sup>2</sup>,R<sup>2</sup>adj,AIC,BIC];rowNames=["R<sup>2</sup>","R<sup>2</sup>adj","AIC","BIC"])

Measures of fit
R<sup>2</sup>     0.134
R<sup>2</sup>adj     0.130
AIC     -6.285
BIC     -6.255
```

Test of Normality

of the residuals, applying the Jarque-Bera test.

• u:: Vector: T-vector of residuals

```
@doc2 JarqueBeraTest
#println(@code_string JarqueBeraTest([1])) #print the source code
```

JarqueBeraTest(x)

Calculate the JB test for each column in a matrix. Reports (skewness, kurtosis, JB).

```
(skewness,kurtosis,JB,pvals) = JarqueBeraTest(u)
printblue("Test of normality")
xut = vcat(skewness,kurtosis,JB)
printmat(xut,collect(pvals);rowNames=["skewness","kurtosis","Jarque-Bera"],colNames=["stat","p-valu
```

```
Test of normality
```

```
stat p-value
skewness -0.746 0.000
kurtosis 5.583 0.000
Jarque-Bera 143.834 0.000
```

Multicollinearity

by studying the correlation matrix and the variance inflation factor (VIF). A high VIF (5 to 10) might indicate issues with multicollinearity.

```
@doc2 VIF
#println(@code_string VIF([1]))  #print the source code

VIF(X)
```

Calculate the variance inflation factor

Input

• x::Matrix: Txk matrix with regressors

Output

```
maxVIF::Float: highest VIF valueallVIF::Vector: a k VIF values
```

```
printblue("Correlation matrix (checking multicollinearity)")
printmat(cor(X);colNames=xNames,rowNames=xNames)
```

```
Correlation matrix (checking multicollinearity)
            С
                     SMB
                               HML
        1.000
                     NaN
                               NaN
С
                  1.000
                            -0.320
SMB
          NaN
          NaN
HML
                 -0.320
                             1.000
```

```
(maxVIF,allVIF) = VIF(X)
printblue("VIF (checking multicollinearity)")
printmat(allVIF;rowNames=xNames)
```

```
VIF (checking multicollinearity)
c 1.000
SMB 1.114
HML 1.114
```

A Convenience Function for Printing All These Tests (extra)

```
@doc2 DiagnosticsTable
#println(@code_string DiagnosticsTable([1],[1],0.0))  #print the source code
```

```
DiagnosticsTable(X,u,R<sup>2</sup>,nlags,xNames="")
```

Compute and print a number of regression diagnostic tests.

Input

- X:: Matrix: Txk matrix of regressors
- u:: Vector: T-vector of residuals
- R²::Float: the R² value
- xNames:: Vector: of strings, regressor names

DiagnosticsTable(X,u,R²,xNames)

```
Test of all slopes = 0 stat 60.165 p-val 0.000 

Measures of fit R<sup>2</sup> 0.134 R<sup>2</sup>adj 0.130 AIC -6.285 BIC -6.255
```

Test of normality

	stat	p-value
skewness	-0.746	0.000
kurtosis	5.583	0.000
Jarque-Bera	143.834	0.000

Correlation matrix (checking multicollinearity)

	С	SMB	HML
С	1.000	NaN	NaN
SMB	NaN	1.000	-0.320
HML	NaN	-0.320	1.000

```
VIF (checking multicollinearity)
c 1.000
SMB 1.114
HML 1.114
```

OLS, The Frisch-Waugh Theorem

This notebook illustrates the Frish-Waugh theorem.

In particular, it shows the following. First, we regress

$$y = x_1' \beta_1 + x_2' \beta_2 + u$$

Second, we run three regressions

- 1. $y = x_1' \gamma_1 + e_y$
- 2. $x_2 = x_1' \delta + e_2$
- 3. $e_y = e_2'\theta + v$, where (e_y, e_2) are from the regressions in 1. and 2.

Then, the estimates of β_2 and θ will be the same (as will their standard errors). This is used in, for instance, fixed effects panel regressions (where x_1 are dummies indicating different cross-sectional units).

Load Packages and Extra Functions

The OlsGM() function was used in ch. 2. It is from the (local) FinEcmt_OLS module.

```
MyModulePath = joinpath(pwd(),"src")
!in(MyModulePath,LOAD_PATH) && push!(LOAD_PATH,MyModulePath)
using FinEcmt_OLS
```

```
#=
include(joinpath(pwd(),"src","FinEcmt_OLS.jl")) #alternative way
using .FinEcmt_OLS
=#
```

```
using DelimitedFiles, LinearAlgebra
```

Loading Data

```
x = readdlm("Data/FFmFactorsPs.csv",',',skipstart=1)
(Rme,SMB,HML,Rf) = (x[:,2],x[:,3],x[:,4],x[:,5])

x = readdlm("Data/FF25Ps.csv",',') #no header line
R = x[:,2:end] #returns for 25 FF portfolios
Re = R .- Rf #excess returns for the 25 FF portfolios
T = size(Re,1) #number of observations
```

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```
y = Re[:,6] #to the notation used in comment, use asset 6

x_1 = [ones(T) Rme] #1st set of regressors (2)

x_2 = [SMB HML]; #2nd set of regressors
```

Regress y on Both x and x

```
(b,-,-,V,) = OlsGM(y,[x<sub>1</sub> x<sub>2</sub>])
std_b = sqrt.(diag(V))

printblue("OLS Results from y regressed on x:\n")
rowNames=["x<sub>1</sub> (c)","x<sub>1</sub> (Rme)","x<sub>2</sub> (SMB)","x<sub>2</sub> (HML)"]
printmat([b std_b];colNames=["b","std"],rowNames)
```

OLS Results from y regressed on x:

The Three Steps in Frisch-Waugh

1. Regress y on x_1 and save the residuals as e_y. (Sorry, cannot create a symbol like e_y .)

- 2. Regress x_2 on x_1 and save the residuals as e_2 .
- 3. Regress e_y on e₂.

```
(_,e_y,) = OlsGM(y,x<sub>1</sub>);  #step 1

(_,e<sub>2</sub>,) = OlsGM(x<sub>2</sub>,x<sub>1</sub>);  #step 2

(b,_,_,V,) = OlsGM(e_y,e<sub>2</sub>)  #step 3
std_b = isa(V,Number) ? sqrt(V) : sqrt.(diag(V)) #diag() fails if V is a number (not a matrix)

printblue("OLS Results from e_y regressed on e<sub>2</sub>:\n")
printmat([b std_b],colNames=["b","std"],rowNames=["e<sub>2</sub> (SMB)","e<sub>2</sub> (HML)"])
printred("Should be same coeff and std as in multiple regression (above)")
```

OLS Results from e_y regressed on e2:

Should be same coeff and std as in multiple regression (above)

A Partial Frisch-Waugh Approach (extra)

Regress y (not e_y) on e2. This gives the same point estimate, but wrong standard error.

```
(b,-,-,V,) = OlsGM(y,e2)  #step 3, adjusted
std_b = isa(V,Number) ? sqrt(V) : sqrt.(diag(V)) #diag() fails if V is a number (not a matrix)
printblue("OLS Results from y regressed on e2:\n")
printmat([b std_b],colNames=["b","std"],rowNames=["e2 (SMB)","e2 (HML)"])
printred("Should be same coeff (but different std) as in multiple regression (above)")
```

OLS Results from y regressed on e2:

Should be same coeff (but different std) as in multiple regression (above)

Betas

This notebook estimates (single and multi-) index models.

Load Packages and Extra Functions

```
MyModulePath = joinpath(pwd(),"src") #add /src to module path
!in(MyModulePath,LOAD_PATH) && push!(LOAD_PATH,MyModulePath)
using FinEcmt_OLS
```

```
#=
include(joinpath(pwd(),"src","FinEcmt_OLS.jl"))
using .FinEcmt_OLS
=#
```

```
using DelimitedFiles, LinearAlgebra
```

Loading Data

We load data from two data files: for the returns on Fama-French equity factors and then also for the 25 Fama-French portfolios. To keep the output simple (easy to display...), we use only 5 of those portfolios.

```
R = x[:,2:end]  #returns for 25 FF portfolios
Re = R .- Rf  #excess returns for the 25 FF portfolios
Re = Re[:,[1,7,13,19,25]]  #use just 5 assets to make the printing easier

(T,n) = size(Re)  #no. obs and no. test assets
```

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Estimating a Single-Index Model

for n returns, by looping. (As an alternative, OlsSure() can do all regressions in one call.)

```
x = [ones(T) Rme]
                                      #regressors
K = size(x, 2)
                                      #no. regressors
(\beta, tstat) = (fill(NaN, K, n), fill(NaN, K, n)) #to fill with results
for i in 1:n
    (b, -, -, V,) = OlsGM(Re[:, i], x)
    β[:,i]
              = b
                = sqrt.(diag(V))
    stdErr
    tstat[:,i] = b./stdErr
end
colNames = [string("asset ",i) for i=1:n]
rowNames = ["\alpha", "\beta \text{ on Rme"}]
printblue("coeffs for $n assets, from OLS of Re on constant and Rme:")
printmat(β;colNames,rowNames)
printblue("t-stats for $n assets, from OLS of Re on constant and Rme:")
printmat(tstat;colNames,rowNames)
```

```
coeffs for 5 assets, from OLS of Re on constant and Rme:
          asset 1
                    asset 2
                              asset 3
                                        asset 4
                                                 asset 5
           -0.504
                      0.153
                                0.305
                                          0.279
                                                   0.336
B on Rme
            1.341
                      1.169
                                0.994
                                          0.943
                                                    0.849
t-stats for 5 assets, from OLS of Re on constant and Rme:
          asset 1 asset 2 asset 3 asset 4 asset 5
           -1.656
                      1.031
                                2.471
                                          2.163
                                                   2.073
β on Rme
           20.427
                     36.534
                               37.298
                                         33.848
                                                  24.279
```

Estimating a Multi-Index Model

A multi-index model is based on

$$R_{it} = a_i + b_i' I_t + \varepsilon_{it},$$

where b_i is a K-vector of slope coefficients.

```
x = [ones(T)] Rme RSMB RHML
                                             #regressors
K = size(x, 2)
                                      #no. regressors
(\beta, tstat) = (fill(NaN, K, n), fill(NaN, K, n)) #to fill with results
for i in 1:n
    (b, -, -, V,) = OlsGM(Re[:, i], x)
    β[:,i]
              = b
    stdErr
               = sqrt.(diag(V))
    tstat[:,i] = b./stdErr
end
colNames = [string("asset ",i) for i=1:n]
rowNames = ["\alpha","\beta on Rme", "\beta on RSMB", "\beta on RHML"]
printblue("coeffs for $n assets, from OLS of Re on constant and Rme:")
printmat(β;colNames,rowNames)
printblue("t-stats for $n assets, from OLS of Re on constant and Rme:")
printmat(tstat;colNames,rowNames)
```

```
coeffs for 5 assets, from OLS of Re on constant and Rme:
           asset 1
                     asset 2
                              asset 3
                                        asset 4
                                                  asset 5
            -0.513
                      -0.006
                                0.030
                                         -0.020
                                                   -0.015
α
β on Rme
             1.070
                                1.035
                                         1.056
                                                   1.041
                      1.080
β on RSMB
                       0.768
                                          0.153
                                                   -0.088
             1.264
                                0.437
β on RHML
            -0.278
                       0.160
                                0.487
                                          0.603
                                                    0.770
t-stats for 5 assets, from OLS of Re on constant and Rme:
           asset 1
                     asset 2
                              asset 3
                                        asset 4
                                                  asset 5
            -2.306
                     -0.066
α
                                0.328
                                         -0.206
                                                   -0.133
            21.091
                   50.113
                               50.250
                                         48.060
                                                   41.247
β on Rme
β on RSMB
           17.068
                      24.418
                               14.534
                                         4.757
                                                   -2.380
β on RHML
            -3.629
                     4.928
                               15.665
                                         18.186
                                                   20.227
```

OLS, Testing

This notebook estimates a linear regression and tests various hypotheses using standard errors assuming iid residuals (Gauss-Markov assumptions).

You may also consider the HypothesisTests.jl package (not used here).

Load Packages and Extra Functions

```
MyModulePath = joinpath(pwd(),"src")
!in(MyModulePath,LOAD_PATH) && push!(LOAD_PATH,MyModulePath)
using FinEcmt_OLS

#=
include(joinpath(pwd(),"src","FinEcmt_OLS.jl"))
using .FinEcmt_OLS
=#
```

```
using DelimitedFiles, Statistics, LinearAlgebra, Distributions
```

Loading Data

OLS under the Gauss-Markov Assumptions

(assuming iid residuals)

```
Y = Rme
T = size(Y,1)
X = [ones(T) RSMB RHML]

(b,u,-,V,R²) = OlsGM(Y,X)
std_iid = sqrt.(diag(V))

printblue("OLS Results (assuming iid residuals):\n")
xNames = ["c","SMB","HML"]
printmat(b,std_iid;colNames=["b","std_iid"],rowNames=xNames)
```

OLS Results (assuming iid residuals):

```
b std_iid
c 0.007 0.002
SMB 0.217 0.073
HML -0.429 0.074
```

Testing a Joint Hypothesis

Since the estimator $\hat{\beta}_{k+1}$ satisfies

$$\hat{\beta} - \beta_0 \sim N(0, V_{k \times k}),$$

we can easily apply various tests. Consider a joint linear hypothesis of the form

$$H_0: R\beta = q,$$

where R is a $J \times k$ matrix and q is a J-vector. To test this, use

$$(R\beta-q)'(RVR')^{-1}(R\beta-q)\overset{d}{\to}\chi_J^2.$$

How we estimate V depends on whether there is heteroskedasticity and/or autocorrelation (discussed below).

```
 R = \begin{bmatrix} 0 & 1 & 0; & & \#testing if b_2 = 0 \text{ and } b_3 = 0 \\ & 0 & 0 & 1 \end{bmatrix}   q = \begin{bmatrix} 0; 0 \end{bmatrix}   test\_stat = (R*b-q)'inv(R*V*R')*(R*b-q) & \#R*V*R' is 2x2
```

```
printblue("Testing Rb = a:")
printmat([test_stat,quantile(Chisq(2),0.9)];rowNames=["test statistic","10% critical value"])

Testing Rb = a:
test statistic 60.010
10% critical value 4.605
```

Regression Diagnostics: Testing All Slope Coefficients

The OlsR2Test() function tests all slope coefficients (or equivalently, the \mathbb{R}^2) of a regression. Notice that the regression must contain an intercept for \mathbb{R}^2 to be useful.

```
@doc2 OlsR2Test
OlsR2Test(R2,T,df)
```

Test of all slope coefficients. Notice that the regression must contain an intercept for \mathbb{R}^2 to be useful.

Input

```
R<sup>2</sup>::Number: R<sup>2</sup> value
T::Int: number of observations
df::Number: number of (non-constant) regressors
```

• RegrStat:: Number: test statistic

Output

```
• pval::Number: p-value

using CodeTracking
println(@code_string OlsR2Test(1.0,1,25))  #print the source code

function OlsR2Test(R<sup>2</sup>,T,df)
    RegrStat = T*R<sup>2</sup>/(1-R<sup>2</sup>)  #R\^2[TAB]
    pval = ccdf(Chisq(df),RegrStat)  #same as 1-cdf()
    return RegrStat, pval
end
```

```
Test of all slopes = 0:

stat 60.165

p-val 0.000
```

The Delta Method

Load Packages and Extra Functions

The notebook first implements the delta method step-by-step. At the end it also presents a the function DeltaMethod() from the (local) FinEcmt_OLS module that wraps those calculations.

```
MyModulePath = joinpath(pwd(),"src")
!in(MyModulePath,LOAD_PATH) && push!(LOAD_PATH,MyModulePath)
using FinEcmt_OLS
#=
include(joinpath(pwd(),"src","FinEcmt_OLS.jl"))
```

```
using DelimitedFiles, Statistics
```

Load Data

using .FinEcmt_OLS

```
x = readdlm("Data/FFmFactorsPs.csv",',',skipstart=1)
x = x[:,2]  #x is an excess return in % (on the US equity market)
T = size(x,1)
```

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Point Estimates of the Mean and Variance

```
\begin{array}{ll} \mu &= mean(x) & \text{\#estimates of the mean and variance} \\ \sigma^2 &= var(x, corrected=false) \\ \\ printblue("mean and variance:") \\ momNames &= ["\mu", "\sigma^2"] \\ printmat([\mu, \sigma^2]; rowNames=momNames) \end{array}
```

```
mean and variance:  \mu \qquad 0.602 \\ \sigma^2 \qquad 21.142
```

The variance-covariance matrix (called V) of the point estimates depends on the distribution of the data. With a normal distribution, the form is particularly simple. We use that approximation in the next cell. Another approach is to estimate V from the moment conditions (see GMM).

```
 V = [\sigma^2 \ 0; \\ variance-covariance matrix of the estimates of [\mu, \sigma^2] \\ 0 \ 2*abs2(\sigma^2)]/T   printmat(V; rowNames=momNames, colNames=momNames)
```

```
\begin{array}{cccc} & \mu & \sigma^2 \\ \mu & 0.054 & 0.000 \\ \sigma^2 & 0.000 & 2.304 \end{array}
```

The Sharpe Ratio and Its Derivatives

The Sharpe ratio and its derivatives (with respect to the parameters of the Sharpe ratio) are

$$SR(\beta) = \mu/\sigma$$
, where $\beta = (\mu, \sigma^2)$

Let $f(\beta)$ denote the Sharpe ratio where β is a vector of parameters consisting of the mean and the variance (μ, σ^2) . The derivatives are then

$$\frac{\partial f(\beta)}{\partial \beta'} = \begin{bmatrix} \frac{1}{\sigma} & \frac{-\mu}{2\sigma^3} \end{bmatrix}$$

We will refer to the matrix of derivatives as *P*.

```
SRFn(\mu,\sigma^2)

Calculate the Sharpe ratio from the mean \mu and variance \sigma^2

"""

function SRFn(\mu,\sigma^2)

\sigma = sqrt(\sigma^2)

SR = \mu/\sigma

P = hcat(1/\sigma, -\mu/(2*\sigma^3)) #Jacobian of SR, 1x2

return SR, P

end
```

SRFn

```
(SR,P) = SRFn(μ,σ²)
printlnPs("Sharpe ratio: ",SR)
printblue("\nDerivatives of Sharpe ratio function wrt:")
printmat(P,colNames=momNames)
```

Applying the Delta Method

Recall that if

$$\hat{\beta} \sim N(\beta_0, V),$$

then the distribution of the function $f(\hat{\beta})$ is asymptotically

$$f(\hat{\beta}) \sim N(f(\beta_0), PVP')$$

where P are the derivatives of $f(\beta)$.

```
Std_SR = sqrt(only(P*V*P')) #only() to convert from 1x1 matrix to scalar
tstat = SR/Std_SR

printblue("Results from the delta method:")
printmat([SR Std_SR tstat],colNames=["SR","Std(SR)","t-stat"])
```

```
Results from the delta method:

SR Std(SR) t-stat

0.131 0.051 2.567
```

A Function for the Delta Method (extra)

is included below. It uses numerical derivatives from the FiniteDiff.jl package.

To use this, first write a function that takes (β, x) as inputs (see SRFn2 (β, x) below), where β is a vector of the parameters and x any data needed (for the Sharpe ratio, no data is needed).

```
@doc2 DeltaMethod
```

```
DeltaMethod(fn::Function,β,V,x=NaN)
```

Apply the delta method on the function $fn(\beta,x)$

Input

- fn:: Function: of the type $fn(\beta,x)$
- β:: Vector: with parameters
- V:: Matrix: Cov(β)
- x:: VecOrMat: data (if any is needed)

Requires

• using FiniteDiff: finite_difference_jacobian as jacobian

```
using CodeTracking
println(@code_string DeltaMethod(cos,[1],[1]))
```

```
function DeltaMethod(fn::Function,\beta,V,x=NaN)
    P = jacobian(b->fn(b,x),\beta)
                                    #numerical Jacobian
    Cov_fn = P*V*P'
    return Cov_fn
end
0.00
    SRFn2(\beta,x)
Function for Sharpe ratio in terms of the vector \beta. No derivatives
function SRFn2(\beta, x=NaN)
  (\mu,\sigma^2) = \beta
  \sigma = sqrt(\sigma^2)
  SR = \mu/\sigma
  return SR
end;
Var_SR = DeltaMethod(SRFn2, [\mu, \sigma^2], V)
printblue("Std of SR from DeltaMethod():")
printmat(sqrt(only(Var_SR)))
Std of SR from DeltaMethod():
     0.051
```

OLS, Testing with Non-iid Residuals

This notebook tests for autocorrelation and heteroskedasticity and then tests hypotheses using standard errors from White's and Newey-West's methods.

You may also consider the HypothesisTests.jl package (not used here).

Load Packages and Extra Functions

```
MyModulePath = joinpath(pwd(),"src")
!in(MyModulePath,LOAD_PATH) && push!(LOAD_PATH,MyModulePath)
using FinEcmt_OLS

#=
include(joinpath(pwd(),"src","FinEcmt_OLS.jl"))
using .FinEcmt_OLS
=#
```

```
using DelimitedFiles, Statistics, LinearAlgebra, Distributions
```

Loading Data

OLS under the Gauss-Markov Assumptions

(assuming iid residuals)

```
Y = Rme
T = size(Y,1)
X = [ones(T) RSMB RHML]

(b,u,_,V,R²) = OlsGM(Y,X)
std_iid = sqrt.(diag(V))

printblue("OLS Results (assuming iid residuals):\n")
xNames = ["c","SMB","HML"]
printmat(b,std_iid;colNames=["b","std_iid"],rowNames=xNames)
```

OLS Results (assuming iid residuals):

```
b std_iid
c 0.007 0.002
SMB 0.217 0.073
HML -0.429 0.074
```

Distribution of OLS Estimates without the Gauss-Markov Assumptions

The distribution of the OLS estimates is (typically)

$$(\hat{\beta} - \beta_0) \stackrel{d}{\rightarrow} N(0, V)$$
 where $V = S_{xx}^{-1} S S_{xx}^{-1}$.

and where $S_{xx} = \sum_{t=1}^{T} x_t x_t'$ and S is the covariance matrix of $\sum_{t=1}^{T} u_t x_t$.

When the Gauss-Markov assumptions hold, then S can be simplified to $S_{xx}\sigma^2$, where σ^2 is the variance of u_t , so $V = S_{xx}^{-1}\sigma^2$.

In contrast, with heteroskedasticity and/or autocorrelation, S must be estimated differently.

Heteroskedasticity

Regression Diagnostics: Heteroskedasticity

The OlsWhitesTest() function does White's test for heteroskedasticity. Again, the regression must have an intercept for this test to be useful.

```
@doc2 OlsWhitesTest
OlsWhitesTest(u,x)
```

Test of heteroskedasticity. Notice that the regression must contain an intercept for the test to be useful.

Input

```
u::Vector: T-vector, residualsx::Matrix: Txk, regressors
```

Output

White's Covariance Matrix

If $u_t x_t$ is not autocorrelated, then S simplifies to $\sum_{t=1}^T x_t x_t' \sigma_t^2$. White's method replaces σ_t^2 by \hat{u}_t^2 . This estimate is robust to heteroskedasticity (in particular, time variation in σ_t^2 that is related to x_t).

A Remark on the Code

```
S_{xx} can be calculated as Sxx = X'X and S as S = (X.*u)'*(X.*u).
```

Clearly, these calculations can also be done in a loop like

```
for t = 1:T
    Sxx = Sxx + X[t,:]*X[t,:]'
    S = S + X[t,:]*X[t,:]'*u[t]^2
end
```

```
Sxx = X'X

S = (X.*u)'*(X.*u)  #S according to White's method
V = inv(Sxx)'S*inv(Sxx)  #Cov(b), White
std_W = sqrt.(diag(V))

printblue("Coefficients and standard errors (from different methods):\n")
xx = [b std_iid std_W]
printmat(xx;colNames=["b","std_iid","std_White"],rowNames=xNames,width=12)
```

Coefficients and standard errors (from different methods):

	b	std_iid	std_White
С	0.007	0.002	0.002
SMB	0.217	0.073	0.113
HML	-0.429	0.074	0.097

Autocorrelation

Regression Diagnostics: Autocorrelation of the Residuals

The OlsAutoCorr() function estimates autocorrelations, calculates the DW and Box-Pierce statistics for the input (often, the residual).

```
@doc2 OlsAutoCorr
```

```
OlsAutoCorr(u,L=1)
```

Test the autocorrelation of OLS residuals

Input

- u:: Vector: T-vector, residuals
- L:: Int: scalar, number of lags in autocorrelation and Box-Pierce test

Output

```
    AutoCorr::Matrix: Lx3, autocorrelation, t-stat and p-value
    BoxPierce::Matrix: 1x2, Box-Pierce statistic and p-value
    DW::Number: DW statistic
```

Requires

• StatsBase, Distributions

```
#println(@code_string OlsAutoCorr([1],5))  #print the source code
```

```
L = 3  #number of autocorrs to test

(ρStats,BoxPierce,DW) = OlsAutoCorr(u,L)

printmagenta("Testing autocorrelation of residuals\n")

printblue("Autocorrelations (lag 1 to $L):\n")
printmat(ρStats,colNames=["autocorr","t-stat","p-val"],rowNames=1:L,cell00="lag")

printblue("\nBoxPierce ($L lags): ")
printblue("\nBoxPierce',rowNames=["stat","p-val"])

printblue("DW statistic:")
printlnPs(DW)
```

Testing autocorrelation of residuals

Autocorrelations (lag 1 to 3):

```
lag autocorr t-stat p-val
1 0.074 1.467 0.142
2 -0.037 -0.733 0.464
3 0.019 0.377 0.706
```

```
BoxPierce (3 lags):
stat 2.831
p-val 0.418
DW statistic:
1.849
```

Autocorrelation of of X.*u

What matters most for the uncertainty about a slope coefficient is not the autocorrelation of the residual itself, but of the residual times the regressor. This is tested below.

```
k = size(X,2)
for i in 1:k  #iterate over different regressors
  #local pStats
  pStats, = OlsAutoCorr(X[:,i].*u,L)
  printblue("Autocorrelations of $(xNames[i])*u (lag 1 to $L):")
  printmat(ρStats,colNames=["autocorr","t-stat","p-val"],rowNames=1:L,cell00="lag")
end
```

```
Autocorrelations of c*u (lag 1 to 3):
lag autocorr
                 t-stat
                             p-val
        0.074
                             0.142
1
                  1.467
2
       -0.037
                 -0.733
                             0.464
3
        0.019
                  0.377
                             0.706
Autocorrelations of SMB*u
                            (lag 1 to 3):
lag autocorr
                 t-stat
                             p-val
                             0.000
1
        0.219
                  4.312
2
       -0.014
                 -0.268
                             0.789
3
        0.044
                  0.857
                             0.391
Autocorrelations of HML*u
                            (lag 1 to 3):
lag autocorr
                             p-val
                 t-stat
                  5.472
                             0.000
1
        0.278
2
        0.131
                  2.582
                             0.010
3
        0.225
                  4.438
                             0.000
```

Newey-West's Covariance Matrix

Let $g_t = u_t x_t$ be a *k*-vector of data.

To calculate the Newey-West covariance matrix, we first need

$$\Lambda_{s} = \sum_{t=s+1}^{T} (g_{t} - \bar{g})(g_{t-s} - \bar{g})',$$

which is proportional to the sth autocovariance matrices.

Then we form a linear combination (with tent-shaped weights) of those autocovariance matrices (from lag - m to m) as in

$$S = \operatorname{Cov}(\sum_t g_t) = \Lambda_0 + \sum_{s=1}^m (1 - \tfrac{s}{m+1}) (\Lambda_s + \Lambda_s').$$

With m = 0 this is the same as White's method.

If we divide S by T, then we get an estimate of $\text{Cov}(\sqrt{T}\bar{g})$, and if we instead divide by T^2 then we get an estimate of $\text{Cov}(\bar{g})$.

The CovNW() function implements this.

@doc2 CovNW

CovNW(g0,m=0,DivideByT=0)

Calculates covariance matrix of sample sum (DivideByT=0), $\sqrt{T^*(\text{sample average})}$ (DivideByT=1) or sample average (DivideByT=2).

Input

- g0::Matrix: Txq matrix of data
- m:: Int: number of lags to use
- DivideByT:: Int: divide the result by T^DivideByT

Output

• S:: Matrix: qxq covariance matrix

Remark

- DivideByT=0: Var(g +g +...), variance of sample sum
- DivideByT=1: $Var(g + g + ...)/T = Var(\sqrt{T} gbar)$, where gbar is the sample average. This is the same as Var(g) if data is iid
- DivideByT=2: $Var(g + g + ...)/T^2 = Var(gbar)$

```
using CodeTracking
println(@code_string CovNW([1],2))
                                      #print the source code
function CovNW(g0,m=0,DivideByT=0)
    T = size(g0,1)
                                        #g0 is Txq
    m = min(m, T-1)
                                        #number of lags
    g = g0 \cdot - mean(g0, dims=1)
                                        #normalizing to zero means
    S = g'g
                                        \#(qxT)*(Txq)
    for s = 1:m
        \Lambda_s = g[s+1:T,:]'g[1:T-s,:] #same as Sum[g_t*g_{t-s}',t=s+1,T]
        S = S + (1 - s/(m+1))*(\Lambda_s + \Lambda_s')
    end
    (DivideByT > 0) && (S = S/T^DivideByT)
    return S
end
```

```
S = CovNW(X.*u,2)  #S acccording to Newey-West, 2 lags
V = inv(Sxx)'S*inv(Sxx)  #Cov(b), Newey-West
std_NW = sqrt.(diag(V))

S = CovNW(X.*u,0)  #S acccording to Newey-West, 0 lags
V = inv(Sxx)'S*inv(Sxx)
std_NW0 = sqrt.(diag(V))

printblue("Coefficients and standard errors (from different methods):\n")
xx = [b std_iid std_W std_NW std_NW0]
printmat(xx,colNames=["b","std_iid","std_White","std_NW","std_NW 0 lags"],rowNames=xNames,width=16)

printred("Remark: NW with 0 lags should be the same as White's method")
```

Coefficients and standard errors (from different methods):

	b	std_iid	std_White	std_NW	std_NW 0 lags
С	0.007	0.002	0.002	0.002	0.002
SMB	0.217	0.073	0.113	0.129	0.113
HML	-0.429	0.074	0.097	0.118	0.097

Remark: NW with 0 lags should be the same as White's method

A Convenience Function for Printing the Tests (extra)

```
DiagnosticsNoniidTable(X,u,3,xNames)
White's test (H<sub>0</sub>: heteroskedasticity is not correlated with regressors)
stat
         77.278
p-val
          0.000
Testing autocorrelation of residuals (lag 1 to 3)
lag autocorr
                 t-stat
                            p-val
1
        0.074
                 1.467
                            0.142
2
       -0.037
                 -0.733
                            0.464
3
        0.019
                 0.377
                            0.706
BoxPierce (3 lags)
stat
          2.831
          0.418
p-val
DW statistic
     1.849
Autocorrelations of c*u (lag 1 to 3)
lag autocorr
               t-stat
                            p-val
        0.074
                 1.467
                            0.142
       -0.037
                 -0.733
                            0.464
        0.019
                  0.377
                            0.706
Autocorrelations of SMB*u (lag 1 to 3)
lag autocorr
               t-stat
                            p-val
                 4.312
                            0.000
1
        0.219
```

-0.014

-0.268

0.789

3	0.044	0.85/	0.391
Auto	correlations	of HML*u	(lag 1 to 3)
lag	autocorr	t-stat	p-val
1	0.278	5.472	0.000
2	0.131	2.582	0.010
3	0.225	4.438	0.000

OLS on a System of Regressions

This notebook illustrates how to estimate a system of regressions with OLS - and to test (coefficients) across the regressions.

Load Packages and Extra Functions

The key function OlsSure() is from the (local) FinEcmt_OLS module.

```
MyModulePath = joinpath(pwd(),"src")
!in(MyModulePath,LOAD_PATH) && push!(LOAD_PATH,MyModulePath)
using FinEcmt_OLS
```

```
#=
include(joinpath(pwd(),"src","FinEcmt_OLS.jl"))
using .FinEcmt_OLS
=#
```

```
using DelimitedFiles, LinearAlgebra, Distributions
```

Loading Data

```
x = readdlm("Data/FFmFactorsPs.csv",',',skipstart=1)
(Rme,Rf) = (x[:,2],x[:,5])  #market excess return, interest rate

x = readdlm("Data/FF25Ps.csv",',') #no header line
R = x[:,2:end]  #returns for 25 FF portfolios
Re = R - Rf  #excess returns for the 25 FF portfolios
Re = Re[:,[1,7,13,19,25]]  #use just 5 assets to make the printing easier

(T,n) = size(Re)  #number of observations and test assets
```

(388, 5)

A Function for Joint Estimation of Several Regressions (OLS)

Consider the linear regressions

$$y_{it} = x_t' \beta_i + u_{it},$$

where i = 1, 2, ..., n indicates n different dependent variables. The K regressors are the *same* across the n regressions. (This is often called SURE, Seemingly Unrelated Regression Equations.)

For the case of two regressions (n = 2), the variance-covariance matrix has the following structure. Stack the β coefficients into a vector (from equation 1 first, then from equation 2.) Then, the variance-covariance matrix is

$$\operatorname{Var}\left(\begin{bmatrix} \hat{\beta}_1 \\ \hat{\beta}_2 \end{bmatrix}\right) = \begin{bmatrix} S_{xx}^{-1} & \mathbf{0} \\ \mathbf{0} & S_{xx}^{-1} \end{bmatrix} \Omega \begin{bmatrix} S_{xx}^{-1} & \mathbf{0} \\ \mathbf{0} & S_{xx}^{-1} \end{bmatrix}$$

where

$$\Omega = \operatorname{Var}\left(\sum_{t=1}^{T} \begin{bmatrix} x_t u_{1t} \\ x_t u_{2t} \end{bmatrix}\right)$$

Notice that $x_t u_{1t}$ is a vector with K elements (as many as there are regressors) and $x_t u_{2t}$ is similar. The Ω matrix is thus $2K \times 2K$.

The case of n regressions (rather than 2) involves creating similar matrices. This is implemented in the OlsSure() function.

@doc2 OlsSure

OlsSure(Y,X,NWQ=false,m=0)

LS of Y on X; where Y is Txn, and X is the same for all regressions

Input

- Y:: Matrix: Txn, the n dependent variables
- X:: Matrix: Txk matrix of regressors (including deterministic ones)
- NWQ:Bool: if true, then Newey-West's covariance matrix is used, otherwise Gauss-Markov
- m:: Int: scalar, bandwidth in Newey-West

Output

```
• b::Matrix: kxn, regression coefficients (one column for each Y[:,i])
   • u:: Matrix: Txn, residuals Y - Yhat
   • Yhat:: Matrix: Txn, fitted values X*b
   • V:: Matrix: covariance matrix of \theta=vec(b)
   • R<sup>2</sup>:: Matrix: 1xn matrix, R<sup>2</sup> values
using CodeTracking
println(@code_string OlsSure([1],[1])) #print the source code
function OlsSure(Y,X,NWQ=false,m=0)
    (T,n) = (size(Y,1), size(Y,2))
    k = size(X,2)
          = X \setminus Y
    Yhat = X*b
       = Y - Yhat
    Sxx = X'X
    if NWQ
                = hcat([X.*u[:,i] for i=1:n]...)
                                                        #hcat(X.*u[:,1],X.*u[:,2], etc)
                = CovNW(g,m)
                                          #Newey-West covariance matrix
         SxxM_1 = kron(I(n), inv(Sxx))
                = SxxM_1 * S * SxxM_1
    else
         V = kron(cov(u),inv(Sxx)) #traditional covariance matrix, Gauss-Markov
    end
         = 1 .- var(u,dims=1)./var(Y,dims=1)
    return b, u, Yhat, V, R<sup>2</sup>
end
```

Using the Function

```
(b,u,yhat,V,R²) = OlsSure(Re,[ones(T) Rme],true)
Stdb = sqrt.(reshape(diag(V),2,n))  #V = Cov(vec(b)), in vec(b) 1:2 are for asset 1, 3:4 for
tstat = b./Stdb

printblue("CAPM regressions: α is the intecept, γ the coeff on Rme\n")
assetNames = [string("asset ",i) for i=1:n]
xNames = ["c","Rme"]

println("coeffs")
printmat(b;colNames=assetNames,rowNames=["α","γ"])

println("t-stats")
printmat(tstat;colNames=assetNames,rowNames=["α","γ"])
```

CAPM regressions: α is the intecept, γ the coeff on Rme

```
coeffs
                     asset 3
   asset 1
            asset 2
                             asset 4
                                       asset 5
                       0.305
                                0.279
    -0.504
              0.153
                                         0.336
     1.341
              1.169
                       0.994
                                0.943
                                         0.849
t-stats
   asset 1 asset 2 asset 3 asset 4 asset 5
    -1.720
                     2.436
                              2.094
                                         2.070
             1.045
α
    22.322
             30.609
                      28.416
                               23.209
                                        17.242
```

Testing Across Regressions

To test across regressions, we first stack the point estimates into a vector by $\theta = \text{vec}(b)$.

The test below applies the usual χ^2 test, where

$$H_0: R\theta = q$$
,

where R is a $J \times k$ matrix and q is a J-vector. To test this, use

$$(R\theta - q)'(RVR')^{-1}(R\theta - q) \stackrel{d}{\rightarrow} \chi_I^2$$
.

The *R* matrix clearly depends on which hypotheses that we want to test.

The next cell creates a matrix of coefficient names that will help us see how the results are organised.

```
bNames = fill("",2,n)  #matrix of coef names, subscript for the asset number
for i = 1:n
    bNames[:,i] = [string("α",'₀'+i),string("γ",'₀'+i)]  #'₀'+1 to get ₁
end
printmat(bNames)
```

```
θ = vec(b)
printblue("stacking the coeffs into a vector:")
```

 α_5

γ5

α4

```
stacking the coeffs into a vector:
      -0.504
α1
       1.341
γı
       0.153
α2
       1.169
Υ2
       0.305
αз
       0.994
γз
       0.279
α4
γ4
       0.943
       0.336
α5
       0.849
γ5
```

printmat(θ;rowNames=vec(bNames))

α₂

γ2

α3

γз

α1

γı

Testing if all intercepts are 0

CAPM implies that all intercepts should be zero. The next cell sets up a joint test.

```
R = zeros(n,2*n)  #are all intercepts == 0?
for i in 1:n
    R[i,(i-1)*2+1] = 1
end

printblue("The R matrix:")
hypNames = string.("hypothesis ",1:size(R,1))
printmat(R;colNames=bNames,rowNames=hypNames,width=4,prec=0)

J = size(R,1)
```

```
printlnPs("The number of hypotheses that we test: $J \n")
q = zeros(J)
printblue("R*vec(b) - q:")
printmat(R*θ-q;rowNames=hypNames)
The R matrix:
hypothesis 2 0 0 1 0 0 0 0 0
                                          0
hypothesis 3 0 0 0 0 1 0 0 0 0
hypothesis 4 0 0 0 0 0 0 1 0 0 0
hypothesis 5 0 0 0 0 0 0 0 1
                                          0
The number of hypotheses that we test: 5
R*vec(b) - q:
hypothesis 1
            -0.504
hypothesis 2
            0.153
hypothesis 3
              0.305
hypothesis 4
              0.279
hypothesis 5
              0.336
println("Joint test of all hypotheses")
\Gamma = R*V*R'
test_stat = (R*\theta - q)'inv(\Gamma)*(R*\theta - q)
critval = quantile(Chisq(J),0.9) #10% critical value
printmat([test_stat,critval];rowNames=["test statistic","10% crit value"])
Joint test of all hypotheses
```

test statistic

10% crit value

10.707

9.236

Model Selection

This notebook illustrates some topics in model selection.

Load Packages and Extra Functions

```
MyModulePath = joinpath(pwd(),"src")
!in(MyModulePath,LOAD_PATH) && push!(LOAD_PATH,MyModulePath)
using FinEcmt_OLS

#=
include(joinpath(pwd(),"src","FinEcmt_OLS.jl"))
using .FinEcmt_OLS
```

```
using DelimitedFiles, Statistics, Plots

default(size = (480,320),fmt = :png)
```

Loading Data

=#

```
x = readdlm("Data/FFmFactorsPs.csv",',',skipstart=1)
(Rme,SMB,HML,Rf) = (x[:,2],x[:,3],x[:,4],x[:,5])

x = readdlm("Data/FF25Ps.csv",',') #no header line
R = x[:,2:end] #returns for 25 FF portfolios
Re = R .- Rf #excess returns for the 25 FF portfolios
T = size(Re,1) #number of observations
```

```
y = Re[:,6] #to the notation used in comment, use asset 6

x_1 = [Rme SMB] #1st set of regressors (2), no intercept

x_2 = HML; #2nd set of regressors, which we focus on in the binscatter
```

Measures of Fit

Adjusted R2, AIC, BIC

The RegressionFit() function has been used in a previous notebook, so we just apply it without any further explanations.

```
X = [x_1 \ x_2 \ ones(T)]

k = size(X,2)

(b,u,-,V,R^2) = OlsGM(y,X); #do OLS
```

```
(R<sup>2</sup>adj,AIC,BIC) = RegressionFit(u,R<sup>2</sup>,k) #measures of fit
printblue("Measures of fit")
printmat([R<sup>2</sup>,R<sup>2</sup>adj,AIC,BIC];rowNames=["R<sup>2</sup>","R<sup>2</sup>adj","AIC","BIC"])
```

```
Measures of fit

R<sup>2</sup> 0.909

R<sup>2</sup>adj 0.908

AIC 1.702

BIC 1.743
```

Bin Scatter

A binscatter is a method studying whether a linear model is a reasonable approximation.

We want to assess whether y_t and a single variable x_{2t} are linearly related, controlling for the vector x_{1t} .

Consider the regression

$$y_t = x'_{1t}\gamma + d'_t\beta + u_t$$

where x_{1t} is a vector (possibly empty) of control variables and d_t is an $N \times 1$ dummy vector indicating whether the single variable x_{2t} belongs to each the bins. (Clearly, only one element in d_t is one and the

rest are zero). A common choice is to use the (minimum, 10th percentile, 20th percentile,..., maximum) as bin boundaries.

If the β estimates form a linear pattern when plotted against the *bin midpoints*, then a linear regression is a reasonable choice.

```
@doc2 BinScatter
```

```
BinScatter(y,x_1,x_2,L=[],U=[],N=20,critval=1.645)
```

Do a regression $y = x_1'\gamma + d'\beta + u$, where d is an N-vector indicating membership in a certain x_2 bin. Plotting β against those bins is a binscatter plot.

Input:

- y::Vector: dependent variable
- x₁:: VecOrMat: control variables
- x₂:: Vector: main regressor of interest
- L:: Vector: lower bin boundaries, if [] then quantiles (see N)
- U:: Vector: upper bin boundaries, if [] then quantiles (see N)
- N:: Vector: number of quantiles, giving N+1 bins. Used if L=U=[]
- critval:: Vector: for calculation of confidence band

Output

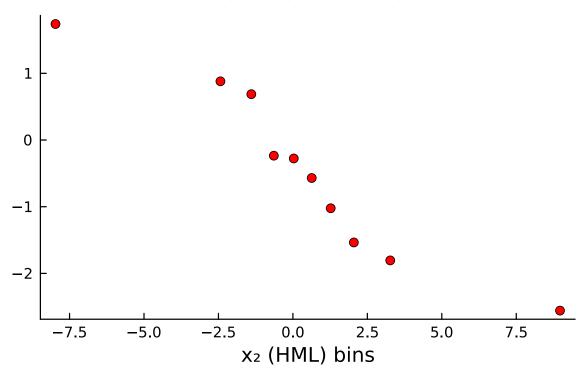
- β :: Vector: N-vector of coeffs on the bin (x) dummies
- stdβ:: Vector: N-vector of std of β
- fn0::NamedTuple: with (LU.confBand)

Using the Function

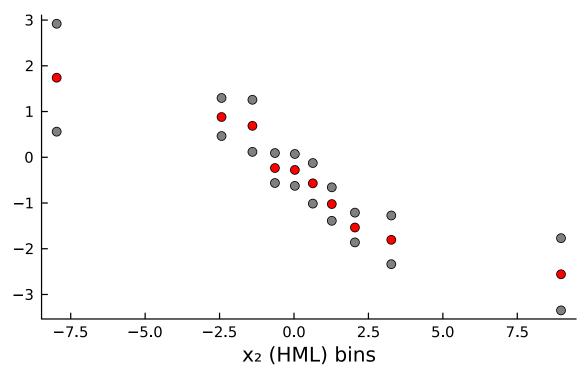
The next few cells calls on the function and plots the results

```
(\beta, std\beta, fn0) = BinScatter(y, x_1, x_2, [], [], 10) #use min, 10th, 20th, ... perctiles as bins 
(LU, cfB) = (fn0.LU, fn0.confBand)
LUmid = mean(LU, dims=2); #mid point of the bins
```

Point estimates



Point estimates and 90% conf band for each b



OLS vs. Lasso

This notebook presents a simple implementation of Lasso and elastic net regressions. It uses the OSQP.jl package for the numerical optimisation.

The purpose of using the Lasso and EN regressions is here to help with the model selection. These methods are useful for indicating which variables that are most important. With this variable selection done, we might choose to apply OLS on the chosen set of regressors.

Load Packages and Extra Functions

The key function for the LASSO/ridge/Elastic Net regressions is from the (local) FinEcmt_Lasso module.

```
MyModulePath = joinpath(pwd(),"src")
!in(MyModulePath,LOAD_PATH) && push!(LOAD_PATH,MyModulePath)
using FinEcmt_OLS, FinEcmt_Lasso
```

```
#=
include(joinpath(pwd(),"src","FinEcmt_OLS.jl"))
include(joinpath(pwd(),"src","FinEcmt_Lasso.jl"))
using .FinEcmt_OLS, .FinEcmt_Lasso
=#
```

```
using Dates, DelimitedFiles, LinearAlgebra
```

```
using Plots, LaTeXStrings
default(size = (480,320),fmt = :png)
```

Loading Data

An Elastic Net Regression

minimizes a combination of the Lasso and Ridge regression loss functions

$$(Y-Xb)'(Y-Xb)/T+\gamma\sum|b_i-\beta_{i0}|+\lambda\sum(b_i-\beta_{i0})^2,$$

where β_{i0} is the target for coefficient *i* (defaults to 0). Set $\lambda = 0, \gamma > 0$ to get a *Lasso* regression or instead $\lambda > 0, \gamma = 0$ to get a *ridge* regression.

Notice that we divide the sum of squared residuals by T. This helps the interpretation of the γ and λ values.

The problem is reformulated (see the code below) as a linear-quadratic problems with restrictions (see below). The code uses the OSQP.jl solver.

The function LassoEN() (included above) implements this.

```
#@doc LassoEN

@doc2 LassoEN
```

```
LassoEN(Y,X,\gammaM=0,\lambda=0,\beta<sub>0</sub>=0)
```

Do Lasso (set $\gamma > 0, \lambda = 0$), ridge (set $\gamma = 0, \lambda > 0$) or elastic net regression (set $\gamma > 0, \lambda > 0$). The function loops over the values in a vector γM , but requires λ to be a number (scalar).

Input

- Y:: Vector:: T-vector, zero mean dependent variable
- X:: Matrix: TxK matrix, zero mean regressors
- $\gamma M:: Vector: n\gamma$ -vector with different values of γ (could also be a number)
- λ :: Number: value of λ (a number)
- β_0 :: Vector: K-vector of target levels for the coeffs (could also be a common number)

Remark (details on the coding)

```
Choice variables z = [b;t] with lengths K and K respectively The objective  0.5*z'P*z + q'z  effectively involves  0.5*z'P*z = b'(X'X/T+\lambda I)b \text{ and }   q'z = (-2X'Y/T-2\lambda\beta_0)'b + \gamma 1't  The restrictions b <= Az <= b \text{ imply }   -\infty <= \beta-t <= \beta_0   \beta_0 <= \beta-t <= \infty
```

Requires

using OSQP, SparseArrays, LinearAlgebra

```
#using CodeTracking
#println(@code_string LassoEN([1],[1],0.1)) #print the source code
```

Lasso Regression

The next cell makes a Lasso regression for a single value of γ . The dependent variable is the (return of the) first mutual fund in RFunds (see data loading) and the regressors are (returns on) a number of benchmark portfolios (again, see data loading).

The data is standardised to have zero mean and unit variance before the estimation, by using the StandardiseYX() function (included above).

```
(Y,X) = StandardiseYX(RFunds[:,1],Rb)

Y = 0.05
(b,b_ls) = LassoEN(Y,X,Y)

printblue("OLS and Lasso coeffs (with Y=$Y):\n")
printmat(b_ls,b;colNames=["OLS","Lasso"],rowNames=IndNames,width=15)
```

OLS and Lasso coeffs (with $\gamma=0.05$):

OLS	Lasso
0.513	0.502
0.117	0.128
0.097	0.079
0.239	0.244
0.080	0.077
0.061	0.000
0.002	0.000
-0.045	-0.000
	0.513 0.117 0.097 0.239 0.080 0.061 0.002

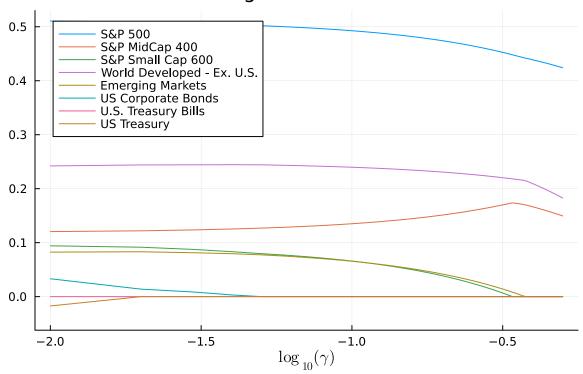
Redo the Lasso Regression with different (gamma) Values

The function LassoEN() can loop over γ values (and exploit the fact that this only requires a partial updating of the problem).

You can also change the target level β_0 to be something else than zero.

```
\begin{array}{l} n\gamma = 51 \\ \gamma M = range(0,0.5,length=n\gamma) \\ \beta_0 = 0.0 & \# change to eg. 0.1 to set another target, or specify a vector \\ \\ bLasso, = LassoEN(Y,X,\gamma M,0,\beta_0); \\ \# printmat([\gamma M bLasso']) \end{array}
```

Lasso regression coefficients



A Ridge Regression

minimizes

$$(Y-Xb)'(Y-Xb)/T + \lambda \sum (b_i - \beta_{i0})^2$$
,

where β_{i0} is the target for coefficient i (defaults to 0). We compare the results from using linear algrebra and optimization based ones from the LassoEN() function. A function for this is included above.

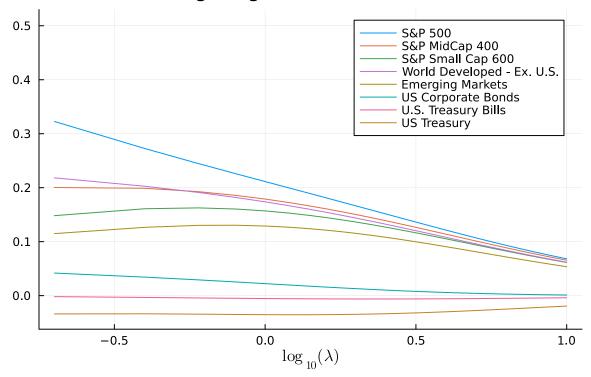
OLS and ridge regression:

	OLS	analytical ridge	numerical ridge
S&P 500	0.513	0.375	0.375
S&P MidCap 400	0.117	0.192	0.192
S&P Small Cap 600	0.097	0.129	0.129
World Developed - Ex. U.S.	0.239	0.229	0.229
Emerging Markets	0.080	0.102	0.102
US Corporate Bonds	0.061	0.048	0.048
U.S. Treasury Bills	0.002	-0.001	-0.001
US Treasury	-0.045	-0.036	-0.036

```
nλ = 51
λM = range(0,10,length=nλ)

bridge = fill(NaN,size(X,2),nλ)
for i = 1:nλ  #loop over λ values
    bridge[:,i] = RidgeRegression(Y,X,λM[i])
end
```

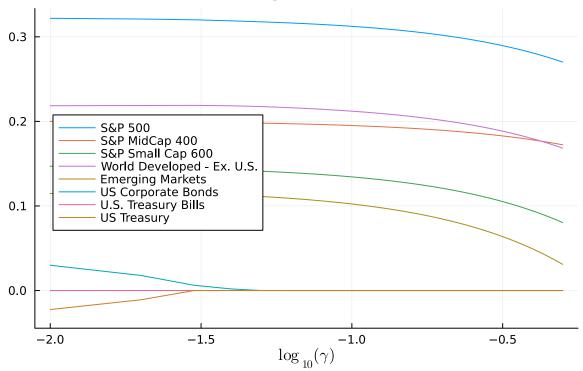
Ridge regression coefficients



An Elastic Net Regression

```
\lambda = 0.2
bEN, = LassoEN(Y,X,YM,\lambda);
```





OLS on the Most Important Variables

The Lasso approach suggests that some regressors are much more important than others. We now apply OLS to this set

```
vv = [1,4]
(Y,X) = (RFunds[:,1],Rb[:,vv])

(b,_,_,V,) = OlsGM(Y,X)
RegressionTable(b,V,IndNames[vv])
```

```
    coef
    stderr
    t-stat
    p-value

    S&P 500
    0.576
    0.008
    68.749
    0.000

    World Developed - Ex. U.S.
    0.284
    0.008
    34.090
    0.000
```

Simulations to Illustrate the Properties of OLS

This notebook uses Monte Carlo simulations to illustrate the properties of OLS. This is *not* asymptotics, but it does hint at what happens in longer and longer samples.

Load Packages and Extra Functions

The key functions are from the (local) FinEcmt_OLS module. We also use one function from the FinEcmt_TimeSeries module.

```
MyModulePath = joinpath(pwd(),"src")
!in(MyModulePath,LOAD_PATH) && push!(LOAD_PATH,MyModulePath)
using FinEcmt_OLS
using FinEcmt_TimeSeries: ARMAFilter
```

```
using Statistics, Random, Distributions, LaTeXStrings, Plots
Random.seed!(123) #random number generator starts on this point
NSim = 3000 #number of iterations in each simulation
```

3000

A Function for a Monte Carlo Simulation

SimulateOLS(CreateYXFn,T,NSim) makes NSim simulations of samples T long, where data is created in a function CreateYXFn(T) (see below for examples).

```
SimulateOLS(CreateYXFn,T,NSim)

Simple function for Monte Carlo simulations of OLS. Data is created by the 'CreateYXFn(T)' function.
```

```
function SimulateOLS(CreateYXFn::Function,T,NSim)
  (y,x) = CreateYXFn(T)
  k = size(x,2)
  b = fill(NaN,NSim,k)  #to put the results in
  for i in 1:NSim
    (y,x) = CreateYXFn(T)
    b[i,:] = x\y  #OLS estimates
  end
  return b
end
```

SimulateOLS

Estimating an AR(1) on Samples of Different Lengths (T)

```
Create YXFn_ARMA11(T,\rho,\theta)

Create Yy,x' for an ARMA(1,1). Set \theta=0 to simulate an AR(1)

"""

function CreateYXFn_ARMA11(T,\rho,\theta)

Tb = T + 100

y = ARMAFilter(randn(Tb),[\rho],[\theta])

x = [ones(T) y[100:end-1]]

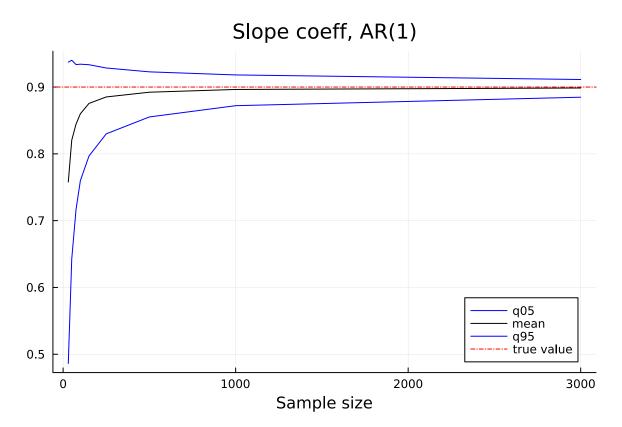
y = y[101:end]

return y,x

end
```

CreateYXFn_ARMA11

```
\begin{array}{lll} \rho = 0.9 \\ TM = \left[30,50,75,100,150,250,500,1000,3000\right] & \text{\#calculate for different sample sizes} \\ bM = fill(NaN,NSim,length(TM)) \\ for (i,T) in enumerate(TM) \\ local bHat, <math>\rhoHat \\ bHat = SimulateOLS(z \rightarrow CreateYXFn_ARMA11(z,\rho,0),T,NSim) \#\theta=0 to get AR(1)
```



Estimating a Regression with Non-Normal Residuals

```
CreateYXFn_Chisq(T,b)

Create 'y,x' when the residual has a chisq(2) distribution

function CreateYXFn_Chisq(T,b)  #to generate iid (y,x)

k = length(b)

x = [ones(T) 10*randn(T,k-1)]

u = rand(Chisq(2),T) .- 2

y = x*b + u

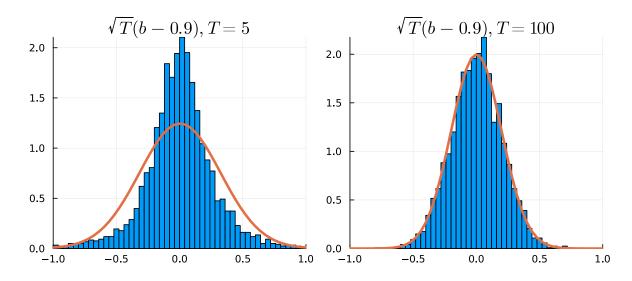
return y,x
end
```

CreateYXFn_Chisq

```
b = [0,0.9]
TM = [5,100]
bM = fill(NaN, NSim, length(TM))
for (i,T) in enumerate(TM)
  local bHat, pHat
  bHat = SimulateOLS(z \rightarrow CreateYXFn\_Chisq(z,b),T,NSim)
  bM[:,i] = bHat[:,2]
end
xGrid = range(-1,1,length=51)
pdfX1 = pdf.(Normal(mean(bM[:,1].-0.9), sqrt(5)*std(bM[:,1])), xGrid)
pdfX2 = pdf.(Normal(mean(bM[:,2].-0.9), sqrt(100)*std(bM[:,2])), xGrid)
p1 = histogram(sqrt(5)*(bM[:,1].-0.9),bins=range(-1,1,length=51),
                 normalized = true,
                 legend = false,
                 xlim = (-1,1),
                 title = L" \setminus T\{T\}(b-0.9), T=5",
                 guidefontsize = 8 )
plot!(xGrid,pdfX1,linewidth=3)
p2 = histogram( sqrt(100)*(bM[:,2].-0.9), bins=range(-1,1, length=51),
```

```
normalized = true,
    legend = false,
    xlim = (-1,1),
    title = L"\sqrt{T}(b-0.9), T=100",
        guidefontsize = 8 )
plot!(xGrid,pdfX2,linewidth=3)

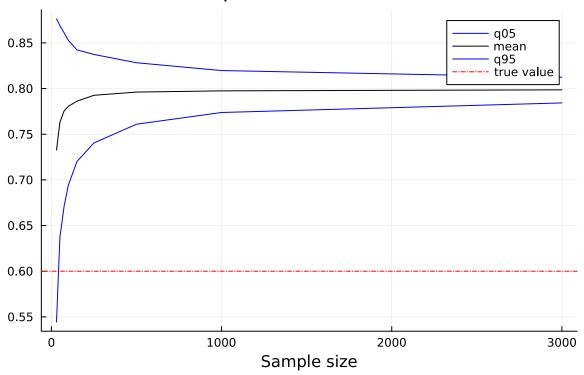
pAll = plot(p1,p2,layout=(1,2),size=(700,300))  #set up subplots
display(pAll)
```



Estimating an ARMA(1,1) on Samples of Different Lengths (T)

```
 (\rho,\theta) = (0.6,0.9) \\ TM = [30,50,75,100,150,250,500,1000,3000] \qquad \text{\#calculate for different sample sizes} \\ bM = fill(NaN,NSim,length(TM)) \\ for (i,T) in enumerate(TM) \\ local bHat, \rhoHat \\ bHat = SimulateOLS(z \rightarrow CreateYXFn\_ARMA11(z,\rho,\theta),T,NSim) \\ bM[:,i] = bHat[:,2] \qquad \text{\#save the slope coef} \\ end \\ q05 = [quantile(z,0.05) for z in eachcol(bM)] \\ q95 = [quantile(z,0.95) for z in eachcol(bM)] \\ meanb = mean(bM,dims=1)' \\ \end{cases}
```

Slope coeff, ARMA(1,1)



Omitted Variables

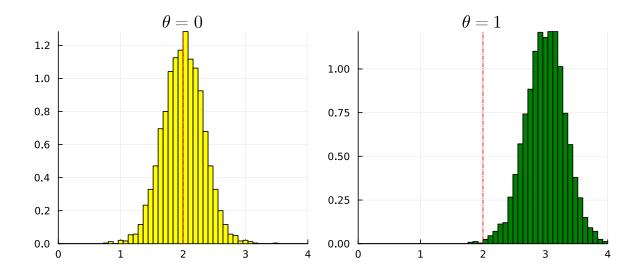
```
CreateYXFn_omitted(T,b)

Create 'y,x' when there is an omitted variable
```

```
function CreateYXFn_omitted(T,b,0)
x = [ones(T) randn(T)*sqrt(0.5)]
h = 0*x[:,2] + randn(T)
v = randn(T)*sqrt(4)
y = x*b + h + v
return y,x
end
```

CreateYXFn_omitted

```
(T,b) = (100,[1,2])
bM0 = SimulateOLS(z \rightarrow CreateYXFn_omitted(T,b,0),T,NSim)[:,2]
bM1 = SimulateOLS(z \rightarrow CreateYXFn\_omitted(T,b,1),T,NSim)[:,2]
p1 = histogram( bM0,bins=range(0,4,length=51),
                normalized = true,
                legend = false,
                color=:yellow,
                 xlim = (0,4),
                title = L"\theta=0",
                 guidefontsize = 8 )
     vline!([2],linecolor=:red,line=:dashdot)
p2 = histogram( bM1,bins=range(0,4,length=51),
                normalized = true,
                legend = false,
                color=:green,
                 xlim = (0,4),
                title = L"\theta=1",
                 guidefontsize = 8 )
     vline!([2],linecolor=:red,line=:dashdot)
pAll = plot(p1,p2,layout=(1,2),size=(700,300))
display(pAll)
```



Measurement Errors in Regressors

```
CreateYXFn_measurement(T,b)

Create 'y,x' when there is an omitted variable

function CreateYXFn_measurement(T,b,\sigma_e)

w = [ones(T) randn(T)*sqrt(0.5)]

v = randn(T)*sqrt(4)

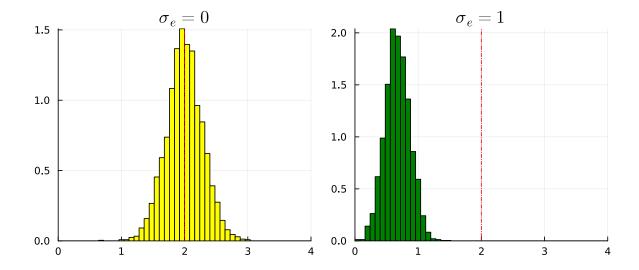
y = w*b + v

x = w .+ [zeros(T) randn(T)*\sigma_e]

return y,x
end
```

CreateYXFn_measurement

```
color=:yellow,
    xlim = (0,4),
    title = L"\sigma_e=0",
    guidefontsize = 8 )
    vline!([2],linecolor=:red,line=:dashdot)
p2 = histogram( bM1,bins=range(0,4,length=51),
    normalized = true,
    legend = false,
    color=:green,
    xlim = (0,4),
    title = L"\sigma_e=1",
    guidefontsize = 8 )
    vline!([2],linecolor=:red,line=:dashdot)
pAll = plot(p1,p2,layout=(1,2),size=(700,300))
display(pAll)
```



Monte Carlo Simulations

This notebook shows examples of Monte Carlo simulations for: (a) the distribution from a GARCH process; (b) the effect of heteroskedasticity on OLS standard errors.

Load Packages and Extra Functions

The key functions for simulations are coded in this notebook. However, the function for OLS is from the (local) FinEcmt_OLS module.

```
MyModulePath = joinpath(pwd(),"src")
!in(MyModulePath,LOAD_PATH) && push!(LOAD_PATH,MyModulePath)
using FinEcmt_OLS
```

```
#=
include(joinpath(pwd(),"src","FinEcmt_OLS.jl"))
using .FinEcmt_OLS
=#
```

```
using Random, Distributions
```

```
using Plots, LaTeXStrings
default(size = (480,320),fmt = :png)
```

Simulating the Distribution of a GARCH(1,1) Variable

The GarchSim(T, ω , α , β) function (see below) generates T observations of a variable u_t whose conditional distribution (based on information in t-1) is $N(0,\sigma_t^2)$, where σ_t^2 follows a GARCH(1,1) process:

$$\sigma_t^2 = \omega + \alpha u_{t-1}^2 + \beta \sigma_{t-1}^2.$$

The subsequent cells call on the GarchSim() function and plots a histogram of the simulated values. This is repeated for two different values of α : a high value and a low value.

```
GarchSim(T,\omega,\alpha,\beta)

Simulate a time series of T residuals from a GARCH(1,1) process.

### Remark

- The vector of \sigma^2 values is not exported from the function. If needed, this could easily be change [IIIII]

function GarchSim(T,\omega,\alpha,\beta)

(\sigma^2,\omega) = [zeros(T) for i=1:2]

\sigma^2[1] = \omega/(1-\alpha-\beta)

#average \sigma^2 as starting value for t = 2:T

\sigma^2[t] = \omega + \alpha*\omega[t-1]^2 + \beta*\sigma^2[t-1]

\omega[t] = sqrt(\sigma^2[t])*randn()

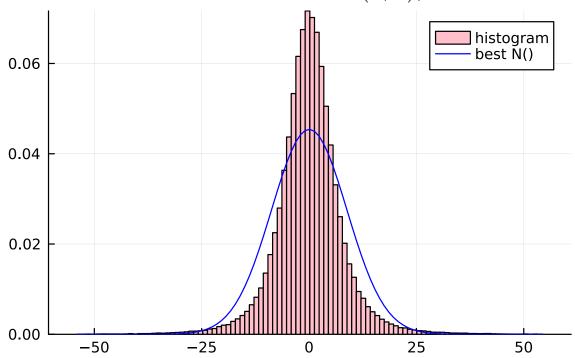
end

return \omega
```

GarchSim

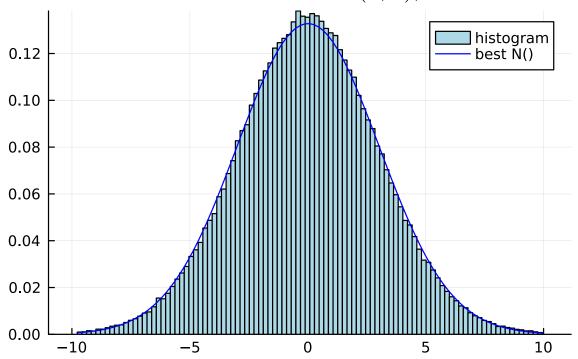
```
(T,\omega,\alpha,\beta) = (200\_000,1,0.19,0.8)
                                                    #fairly high \alpha value
Random.seed! (123456)
                                                    #to replicate the same random numbers
u = GarchSim(T, \omega, \alpha, \beta)
(qL,qH) = quantile(u,[0.001,0.999])
                                                    #quantiles 0.001 and 0.999
                                                    #a grid of values between the quantiles
uGrid = range(qL,qH,length=101)
pdfNu = pdf.(Normal(mean(u),std(u)),uGrid)
                                                    #best fitting N() as a comparison
p1 = histogram( u,
                 bins = uGrid,
                 fillcolor = :pink,
                 normalized = true,
                 label = "histogram",
                 title = L"\mathrm{Distribution \ of \ GARCH(1,1), \ } \alpha =0.19" )
plot!(uGrid,pdfNu,color=:blue,label="best N()")
display(p1)
```

Distribution of GARCH(1, 1), $\alpha = 0.19$



the histogram is clearly non-N()





the histogram looks almost N()

Simulating (White's) Heteroskedasticity in OLS

The $SimOL(NSim,T,\alpha)$ function (see below) first simulates T observations where the residuals in an OLS regression are heteroskedastic, since they are generated as

$$\epsilon_t = u_t(1+\alpha|f_t|),$$

where u_t is N(0, 1) and f_t is a regressor.

The function then estimates the traditional OLS standard errors and also White's standard errors.

The subsequent cell compares the different standard errors in two cases: $\alpha = 0$ and $\alpha = 1$.

```
SimOLS(NSim, T, \alpha)
Simulate data for a regression model with heteroskedastic errors and then estimate both point estim
and standard errors according to traditional OLS (Gauss-Markov) and White.
### Input
- 'NSim::Int':
                  number of simulations (eg. 3000)
- 'T::Int':
                  sample length (eg. 200)
- `α::Number`:
                  degree of heteroskedasticity
function SimOLS(NSim,T,\alpha)
    (bLS,StdLS,StdWhite) = [fill(NaN,NSim) for i = 1:3]
    for i = 1:NSim
        f = randn(T)
                                                  #some random regressors
        \epsilon = \text{randn}(T) \cdot * (1 \cdot + \alpha * abs.(f))
                                                 #heteroskedastic residuals
        y = 1 \cdot + 0.9 * f + \epsilon
        x = [f ones(T)]
        (b,u,) = OlsGM(y,x)
                                             #OLS, point estimates
        bLS[i] = b[1]
        Sxx
                    = x'x
                    = (x.*u)'*(x.*u)
        V_W
                   = inv(Sxx)'S*inv(Sxx)
                                                #Cov(b), White
        StdWhite[i] = sqrt(V_W[1,1])
        V_{iid} = inv(Sxx)*var(u)
                                                  #OLS, traditional
        StdLS[i] = sqrt(V_iid[1,1])
    end
    return bLS, StdLS, StdWhite
end
```

SimOLS

```
NSim = 25000 #number of simulated samples
T = 200 #sample size
\alpha = 0 #no heteroskedasticity
```

```
Random.seed!(123456)  (bLS,StdLS,StdWhite) = SimOLS(NSim,T,\alpha)   printblue("Std of slope when $\alpha = \$(\alpha): \n")   printmat(std(bLS),mean(StdLS),mean(StdWhite);colNames=["Simulated","OLS","White"])   printred("the standard errors are similar")
```

Std of slope when $\alpha=0$:

Simulated OLS White 0.071 0.071 0.070

the standard errors are similar

```
 \alpha = 1 \\ \text{#lots of heteroskedasticity} \\ \text{Random.seed!(123456)} \\ \text{(bLS,StdLS,StdWhite)} = \text{SimOLS(NSim,T,}\alpha) \\ \\ \text{printblue("Std of slope when } \alpha = \$(\alpha) : \n") \\ \\ \text{printmat(std(bLS),mean(StdLS),mean(StdWhite);colNames} = ["Simulated","OLS","White"]) \\ \\ \text{printred("the standard errors are clearly different")}
```

Std of slope when $\alpha=1$:

Simulated OLS White 0.189 0.134 0.185

the standard errors are clearly different

Bootstrapping a Linear Regression

This notebook implements both a traditional bootstrap and a block bootstrap in order to get more robust standard errors of OLS coefficients.

Load Packages and Extra Functions

The key functions (for doing OLS and block bootstrap) are from the (local) FinEcmt_OLS module.

```
MyModulePath = joinpath(pwd(),"src")
!in(MyModulePath,LOAD_PATH) && push!(LOAD_PATH,MyModulePath)
using FinEcmt_OLS
```

```
#=
include(joinpath(pwd(),"src","FinEcmt_OLS.jl"))
using .FinEcmt_OLS
=#
```

```
using DelimitedFiles, Statistics, LinearAlgebra, Random
```

Loading Data

The regressions used below are of the type

$$y_t = x_t'b + u_t$$

where y_t is monthly data on 1-year excess returns on a 5-year bond (so there is an 11-month overlap between two data points) and x_t includes a constant and the lagged 1-year forward rates for investments starting (0,1,2,3,4) years ahead.

```
T = 580, n = 1, K = 6
```

Point Estimates

```
(bLS,u,yhat,Covb,) = OlsGM(y,x) #OLS estimate and traditional std errors
StdbLS = sqrt.(diag(Covb))

printblue("OLS estimates:\n")
rowNames = [string("x",'o'+i) for i=1:K] #'o'+1 to get 1
printmat(bLS,StdbLS;colNames=["coeff","std (trad.)"],rowNames=rowNames,width=15)
```

OLS estimates:

```
coeff
                       std (trad.)
Х1
            -3.306
                             0.824
            -4.209
                             0.712
Х2
            10.627
                             4.513
Хз
           -14.397
                             12.896
Χ4
             7.096
                             15.876
X 5
             1.284
                             6.904
X 6
```

Standard Bootstrap (I)

In each loop, a new series of residuals, \tilde{u}_t , is created by drawing (with replacement) values from the fitted residuals (from the estimates in earlier cells). Then, simulated values of the dependent variable are created as

$$\tilde{y}_t = x_t' \beta + \tilde{u}_t$$

and we redo the estimation on (\tilde{y}_t, x_t) . Notice that x_t is the same as in the data.

This is repeated NSim times.

```
NSim
         = 2000
                                 #no. of simulations
Random.seed! (123)
bBoot = fill(NaN, NSim, K)
for i = 1:NSim
                                                     #loop over simulations
                                                     #local/global is needed in script
  #local t_i, utilde, ytilde
                                                     #T random numbers from 1:T (with replacement)
      = rand(1:T,T)
  #println(t_i)
                                                     #uncomment to see which rows that are picked of
  utilde = u[t_i]
  ytilde = x*bLS + utilde[1:T]
 bBoot[i,:] = OlsGM(ytilde,x)[1]
end
printblue("Coefficients:")
xx = [bLS mean(bBoot,dims=1)']
printmat(xx;colNames=["OLS","avg. bootstr"],rowNames=rowNames,width=20)
printblue("Std:")
xx = [StdbLS std(bBoot,dims=1)']
printmat(xx;colNames=["trad.","bootstrap 1"],rowNames=rowNames,width=20)
printred("The results from these bootstrap are similar to standard OLS, but...see below")
```

Coefficients:

	0LS	avg. bootstr
X ₁	-3.306	-3.315
X 2	-4.209	-4.225
X 3	10.627	10.693
X 4	-14.397	-14.619
X 5	7.096	7.403
X 6	1.284	1.150

S	t	d	:

	trau.	bootstrap 1
X 1	0.824	0.828
X 2	0.712	0.722
X 3	4.513	4.576

+rad

hootstran 1

X 4	12.896	13.011
X 5	15.876	15.924
X 6	6.904	6.891

The results from these bootstrap are similar to standard OLS, but...see below

Block Bootstrap (II)

To handle autocorrelated residuals, we now consider a block bootstrap.

In each loop, we initially define a random starting point (observation number) of each block (by using the rand() function). For instance, if we randomly draw that the blocks should start with observations 27 and 35 and have decided that each block should contain 10 data points, then the artificial sample will pick out observations 27 - 36 and 35 - 44. Clearly, some observations can be in several blocks. This is done by the DrawBlocks(T,BlockSize) function, included above.

Once we have T data points, we define a new series of residuals, \tilde{u}_t .

Then, new values of the dependent variable are created as

```
\tilde{y}_t = x_t' \beta + \tilde{u}_t
```

and we redo the estimation on (\tilde{y}_t, x_t) .

```
@doc2 DrawBlocks
```

DrawBlocks(T,BlockSize)

Draw a T-vector of indices v that can be used to create bootstrap residuals. The indices are such that they form blocks of length BlockSize.

```
#using CodeTracking
#println(@code_string DrawBlocks(1,1)) #print the source code
```

```
Random.seed!(1234567)
BlockSize = 10  #size of blocks

printblue("illustrating how to draw 30 observations, in blocks of $BlockSize:\n")
t_i = DrawBlocks(30,BlockSize)

printmat(reshape(t_i,BlockSize,:);colNames=["block 1","block 2","block 3"])
```

illustrating how to draw 30 observations, in blocks of 10:

block 1	. block 2	block 3
7	11	19
8	12	20
9	13	21
10	14	22
11	15	23
12	16	24
13	17	25
14	18	26
15	19	27
16	20	28

```
BlockSize = 10
                                #size of blocks
NSim = 2000
                                #no. of simulations
Random.seed!(123)
bBoot2 = fill(NaN,NSim,K*n)
for i = 1:NSim
                                                   #loop over simulations
    #local t_i, utilde, ytilde
                                                   #local/global is needed in script
   t_i = DrawBlocks(T,BlockSize)
             = u[t_i]
   utilde
   ytilde = x*bLS + utilde[1:T]
   bBoot2[i,:] = OlsGM(ytilde,x)[1]
end
printblue("Std:")
xx = [StdbLS std(bBoot,dims=1)' std(bBoot2,dims=1)']
printmat(xx;colNames=["trad.","bootstrap 1","block bootstr"],rowNames=rowNames,width=20)
printred("The block bootstrap accounts for autocorrelation, so the stds tend to be higher (since the
```

Std:

	trad.	bootstrap 1	block bootstr
X ₁	0.824	0.828	2.102
X 2	0.712	0.722	1.407
X 3	4.513	4.576	8.327
X 4	12.896	13.011	23.881
X 5	15.876	15.924	29.839
X 6	6.904	6.891	13.219

The block bootstrap accounts for autocorrelation, so the stds tend to be higher (since there is indeed at

Portfolio Sorts

This notebook implements univariate and bivariate portfolio sorts.

Load Packages and Extra Functions

The key functions used in this notebook are from the (local) FinEcmt_OLS module.

```
MyModulePath = joinpath(pwd(),"src")
!in(MyModulePath,LOAD_PATH) && push!(LOAD_PATH,MyModulePath)
using FinEcmt_OLS
using FinEcmt_TimeSeries: EMA
```

```
#=
include(joinpath(pwd(),"src","FinEcmt_OLS.jl"))
include(joinpath(pwd(),"src","FinEcmt_TimeSeries.jl"))
using .FinEcmt_OLS
using .FinEcmt_TimeSeries: EMA
=#
```

```
using Dates, DelimitedFiles, Statistics
```

Load Data

The data set contains daily data for "dates", the equity market return, riskfree rate and the treturns of the 25 Fama-French portfolios. All returns are in percent.

```
x = readdlm("Data/MomentumSR.csv",',')
dN = Date.(x[:,1],"yyyy-mm-dd") #Julia dates
y = convert.(Float64,x[:,2:end])
```

```
(Rm,Rf,R) = (y[:,1],y[:,2],y[:,3:end])
println("size of dN, Rm, Rf, R")
println(size(dN),"\n",size(Rm),"\n",size(Rf),"\n",size(R))

(T,n) = size(R);  #number of periods and assets

size of dN, Rm, Rf, R
(9837,)
(9837,)
(9837,)
(9837,)
(9837,)
(9837,25)
```

A Univariate Sort

on recent returns.

The next cells create a sorting variable X and does a portfolio sort to create a Lo portfolio and a Hi portfolio (corresponding to the 5 lowest and highest values of X). The sort is done for each trading day of the sample, so the portfolios are dynamic (has time-varying portfolio weights).

A Remark on the Code

- The EMA(R,22) function (included above) calculates a moving average of R[t-21:t,i] for each column i. We then lag thus result using lag().
- With x = [9,7,8], the rankPs(x) function (included above) gives the output [3,1,2]. This says, for instance, that 7 is the lowest number (rank 1).

Return Statistics

...comparing with a passive portfolio.

Excess returns for the Lo, Hi and passive (p) portfolios are calculated.

We then use the ReturnStats (Re, Annfactor) function (included above) to calculate the mean (excess) return, its standard deviation and the Sharpe ratio. Annualisation is done by assuming 252 trading days per year.

In calculating the return stats, we drop the first q observations (and thus extract observation q+1:end, since we use q observations to form the first dynamic portfolio.

```
ReLo = RLo - Rf  #create excess returns
ReHi = RHi - Rf
Rep = Rp - Rf  #excess return of passive portfolio

Stats = ReturnStats([ReLo ReHi Rep][q+1:end,:],252)  #return stats for obs q+1 to T

printblue("Stats for the portfolio returns, annualized:\n")
printmat(Stats;colNames=["Lo" "Hi" "passive"],rowNames=["µ";"o";"SR"])
```

Stats for the portfolio returns, annualized:

```
\begin{array}{cccccccc} \mu & 3.745 & 14.022 & 9.626 \\ \sigma & 19.056 & 17.340 & 16.928 \\ \text{SR} & 0.197 & 0.809 & 0.569 \end{array}
```

A Univariate Sort (again)

on recent returns - but using another approach, which turns out to be easy to apply to the double sort as well.

A Remark on the Code

- The sortLoHi(x,v,m) function (included above) below create n-vectors vL and vH with trues/falses indicating membership of the Lo and Hi groups.
- As an example, (vL,vH) = sortLoHi([3,1,2],[false,true,true],1) gives vL=[false,true,false] and vH=[false,false,true]. This means that the 'Lo' portfolio consists of asset 2 and the 'Hi' portfolio of asset 3. Asset 1 is not assigned to any.
- The EWportf(v) function (also from FinEcmt_OLS) takes such a Bool vector (eg. vL) and calculates (equal) portfolio weights among those assets that are true in v. It handles the case of an empty portfolio (all elements in v are false) by setting all portfolio weights to NaN.

```
@doc2 sortLoHi
```

```
sortLoHi(x,v,m)
```

Create vectors vL and vH with trues/falses indicating membership of the Lo and Hi groups. It sorts according to x[v], setting the m lowest (in vL) and m highest values (in vH) to true. All other elements (also those in x[.!v]) are set to false.

Input

- x:: Vector: n-vector, sorting variable
- v :: Vector: n-vector of true/false. Sorting is done within <math>x[v]
- m:: Int: number of assets in Lo/Hi portfolio

Output

- vL:: Vector: n-vector of true/false, indicating membership of Lo portfolio
- vH:: Vector: n-vector of true/false, indicating membership of Hi portfolio

```
#using CodeTracking
#println(@code_string sortLoHi([1],trues(1),1))  #print the source code
```

```
X = lag(EMA(R,q))
                                       #sort on lag of MA(q) of R
                                           #m asset in each of Lo and Hi
m = 5
(RH,RL) = (fill(NaN,T),fill(NaN,T))
for t = 2:T
                               #loop over periods, save portfolio returns
    #local vL,vH,wL,wH
                               #local/global is needed in script
    (vL,vH) = sortLoHi(X[t,:],trues(n),m)
    (wL,wH) = (EWportf(vL),EWportf(vH)) #portfolio weights, EW
    RL[t] = wL'R[t,:]
    RH[t] = wH'R[t,:]
end
ReL = RL - Rf
ReH = RH - Rf
                   #cut out t=1, excess returns
Statm = ReturnStats([ReL ReH Rep][q+1:end,:],252)
printblue("Stats for the portfolio returns, annualized:\n")
printmat(Stats,colNames=["Lo" "Hi" "passive"],rowNames=["μ";"σ";"SR"])
printred("Compare with the previous results to verify that they are the same")
```

Stats for the portfolio returns, annualized:

Compare with the previous results to verify that they are the same

An Independent Double Sort

on recent volatility (X) and and returns (Z).

This creates four portfolios: (Low X, Low Z), (Low X, High Z), (High X, Low Z) and (High X, High Z). Each of them is an intersection from independent sorts on X and Z.

The size of each of these portfolios can vary over time: sometimes the portfolio is empty. The portfolio weights created by the EWportf() function are then NaN.

A Remark on the Code

• vXL .& vZL tests if vXL[i] and vZL[i] are both true (and then repeats for each i).

```
X = lag(EMA(abs.(R),q)) #(lag of) MA of |R|, first sort variable Z = lag(EMA(R,q)); #(lag of) MA of R, second sort variable
```

```
(mX, mZ) = (10, 10)
(RLL,RLH,RHL,RHH) = [fill(NaN,T) for i=1:4]
for t = 2:T
                               #loop over periods, save portfolio returns
   #local vXL,vXH,vZL,vZH,vLL,vLH,vHL,vHH,wLL,wLH,wHL,wHH
                                                                 #local/global is needed in script
    (vXL, vXH) = sortLoHi(X[t,:], trues(n), mX)
                                                 #in Lo/Hi according to X
    (vZL,vZH) = sortLoHi(Z[t,:],trues(n),mZ)
                                                 #in Lo/Hi according to Z
           = vXL . & vZL
                                                          #in Lo X,Low Z
   vLL
           = vXL . & vZH
                                                          #in Lo X, Hi Z
   vLH
           = vXH .& vZL
                                                          #in Hi X, Lo Z
   vHL
                                                          #in Hi X, Hi Z
           = vXH . & vZH
   vHH
    (wLL,wLH,wHL,wHH) = (EWportf(vLL),EWportf(vLH),EWportf(vHL),EWportf(vHH)) #portfolio weights,
    (RLL[t],RLH[t],RHL[t],RHH[t]) = (WLL'R[t,:],WLH'R[t,:],WHL'R[t,:],WHH'R[t,:])
end
```

Handling NaNs and Reporting Results

There are NaNs in the return series, since the portfolios are sometimes empty. We need to decide on how to handle those data points.

The assumption below is that an empty portfolio (when all weights are NaNs) means that the full investment is done in the riskfree asset and thus the excess return is zero. We thus replace the excess return of a NaN return with zero.

We typically want to study RLH - RLL and RHH - RHL since they show the "effect" of the second sort variable (Z) while controlling for the first (X).

```
ReAll = [RLL RLH RHL RHH] .- Rf #excess returns replace!(ReAll,NaN⇒0) #replace NaN by 0, assuming investment in riskfree Stats = ReturnStats(ReAll[q+1:end,:],252) printblue("Stats for the portfolio returns, annualized:\n") colNames = ["LL","LH","HL","HH"] printmat(Stats,colNames=colNames,rowNames=["μ";"σ";"SR"])
```

```
printblue("Study LH-LL and HH-HL to see the momentum effect (controlling for volatility):\n")
RLH_LL = ReAll[:,2] - ReAll[:,1]  #(L,H) minus (L,L)
RHH_HL = ReAll[:,4] - ReAll[:,3]  #(H,H) minus (H,L)

Stats = ReturnStats([RLH_LL RHH_HL][q+1:end,:],252)
printmat(Stats,colNames=["LH-LL","HH-HL"],rowNames=["µ";"o";"SR"])
```

Stats for the portfolio returns, annualized:

```
LL
                     LH
                                HL
                                          НН
       6.207
                 12.508
                            4.731
                                      12.483
μ
σ
      14.644
                 14.350
                           20.575
                                      19.069
SR
       0.424
                 0.872
                            0.230
                                       0.655
```

Study LH-LL and HH-HL to see the momentum effect (controlling for volatility):

```
\begin{array}{cccc} & \text{LH-LL} & \text{HH-HL} \\ \mu & 6.301 & 7.752 \\ \sigma & 7.878 & 11.195 \\ \text{SR} & 0.800 & 0.692 \end{array}
```

A Dependent Double Sort

on recent volatility (X) and and returns (Z).

This also creates four portfolios: (Low X, Low Z), (Low X, High Z), (High X, Low Z) and (High X, High Z). However, in this case, the Low X group is split up into: (Low X, Low Z) and (Low X, High Z), and similarly for the high X group.

The size of each of these portfolios is constant over time (unless there are missing values).

A Remark on the Code

- The vXL from (vXL, vXH) = sortLoHi(X[t,:],trues(n),mX) is an n-vector where element i is true when asset i belongs to 'low according to X[t,:]'.
- sortLoHi(Z[t,:],vXL,mZ) sorts Z[t,vXL] into low/high. The other elements in Z[t,:] will not belong to either.

```
(mX, mZ) = (10, 5)
(RLL,RLH,RHL,RHH) = [fill(NaN,T) for i=1:4]
for t = 2:T
                               #loop over periods, save portfolio returns
    #local vXL,vXH,vLL,vLH,vHL,vHH,wLL,wLH,wHL,wHH
                                                         #local/global is needed in script
                                                 #Lo/Hi according to X
    (vXL,vXH) = sortLoHi(X[t,:],trues(n),mX)
    (vLL,vLH) = sortLoHi(Z[t,:],vXL,mZ)
                                                   #within Lo X, Lo/Hi according to Z
    (vHL,vHH) = sortLoHi(Z[t,:],vXH,mZ)
                                                   #within Hi X, Lo/Hi according to Z
    (wLL,wLH,wHL,wHH) = (EWportf(vLL),EWportf(vLH),EWportf(vHL),EWportf(vHH)) #portfolio weights,
    (RLL[t],RLH[t],RHL[t],RHH[t]) = (WLL'R[t,:],WLH'R[t,:],WHL'R[t,:],WHH'R[t,:])
end
Reall = [RLL RLH RHL RHH] .- Rf
replace!(ReAll, NaN⇒0)
                               #replace NaN by 0, assuming investment in riskfree
Stats = ReturnStats(ReAll[q+1:end,:],252)
printblue("Stats for the portfolio returns, annualized:\n")
colNames = ["LL","LH","HL","HH"]
printmat(Stats,colNames=colNames,rowNames=["μ";"σ";"SR"])
printblue("Study LH-LL and HH-HL to see the momentum effect (controlling for volatility):\n")
RLH_{LL} = ReAll[:,2] - ReAll[:,1]
                                       \#(L,H) minus (L,L)
RHH_HL = ReAll[:,4] - ReAll[:,3]
                                        \#(H,H) minus (H,L)
Stats = ReturnStats([RLH_LL RHH_HL][q+1:end,:],252)
printmat(Stats,colNames=["LH-LL","HH-HL"],rowNames=["\mu";"\sign";"SR"])
Stats for the portfolio returns, annualized:
          LL
                    LH
                              HL
                                        ΗН
μ
       7.324
                12.648
                           5.212
                                    13.063
      15.010
                14.466
                          20.824
                                    19.783
σ
                 0.874
                           0.250
                                     0.660
SR
       0.488
Study LH-LL and HH-HL to see the momentum effect (controlling for volatility):
       LH-LL
                 HH-HL
       5.324
μ
                 7.852
       4.565
                 7.326
σ
SR
       1.166
                 1.072
```

Panel Regressions

This notebook uses functions to do panel regressions, handling autocorrelation, cross-sectional clustering and unbalanced panels.

Load Packages and Extra Functions

The key functions used in this notebook are from the (local) FinEcmt_OLS module.

```
MyModulePath = joinpath(pwd(),"src")
!in(MyModulePath,LOAD_PATH) && push!(LOAD_PATH,MyModulePath)
using FinEcmt_OLS

#=
include(joinpath(pwd(),"src","FinEcmt_OLS.jl"))
using .FinEcmt_OLS
=#
```

```
using DelimitedFiles, Statistics, LinearAlgebra
```

Loading Data and Reshuffling Data

```
(data,header) = readdlm("Data/nls_panelEd.txt",header=true)  #classical data set from Hill et al

d = PutDataInNT(data,header)  #NamedTuple with d.id, d.lwage, etc
println(keys(d))

id = convert.(Int,d.id)  #id of individuals: 1,2,...,N
per = convert.(Int,d.year)
T = length(unique(per))  #number of time periods
```

```
N = length(unique(id))  #number of individuals
println("\nT=$T and N=$N")
```

```
(:id, :year, :lwage, :hours, :age, :educ, :collgrad, :msp, :nev_mar, :not_smsa, :c_city, :south, :black
T=5 and N=716
```

Creating Variables for the Regressions

The next cell creates a NT-vector y and a $NT \times K$ matrix x.

We then print the first few observations of (some of) the data. Notice the structure: the first 5 observations are for individual (id) 1 (period 1-5), the next 5 for individual 2.

```
y = d.lwage
c = ones(length(y))  #constant

xNames = ["exper/100","exper^2/100","tenure/100","tenure^2/100","south","union"]
x = [c d.exper/100 d.exper2/100 d.tenure/100 d.tenure2/100 d.south d.union]
K = size(x,2)  #number of regressors

printblue("The first few lines of (some of) the data:\n")
printmat(id[1:11],y[1:11],x[1:11,1:2];colNames=["id","lnwage","c","exper/100"],rowNames=string.(1:11)
```

The first few lines of (some of) the data:

obs		id	lnwage	С	exper/100
1	1		1.808	1.000	0.077
2	1		1.863	1.000	0.086
3	1		1.789	1.000	0.102
4	1		1.847	1.000	0.122
5	1		1.856	1.000	0.136
6	2		1.281	1.000	0.076
7	2		1.516	1.000	0.084
8	2		1.930	1.000	0.104
9	2		1.919	1.000	0.120
10	2		2.201	1.000	0.132
11	3		1.815	1.000	0.114

Pooled OLS with OlsNW()

The next cell does pooled OLS estimation and reports White's standard errors. It is straightforward to used the IndividualDemean() or the FirstDiff() functions from the local FinEcmt_OLS module to also do fixed effects and first difference estimations.

However, the OLS code is cumbersome to extend to clustered standard errors and also for handling autocorrelation. Especially, if we need to handle both. For that reason, we later introduce the PanelOls() function which can handle these complications.

```
(b_LS,res,yhat,Covb,R2,) = OlsNW(y,x)  #pooled OLS
tstat_LS = b_LS./sqrt.(diag(Covb))

printblue("results from Ols():\n")
printmat(b_LS,tstat_LS,colNames=["coef","t-stat"],rowNames=["c";xNames])
```

results from Ols():

	coef	t-stat
С	1.285	28.513
exper/100	7.837	8.954
exper^2/100	-0.201	-5.264
tenure/100	1.206	2.346
tenure^2/100	-0.024	-0.828
south	-0.196	-13.247
union	0.110	6.928

Reshuffling the Data

to fit the convention in the PanelOls() function which we use below.

We use the PanelReshuffle(y,x,[],id,per) from the local FinEcmt_OLS module function to reshuffle the dependent variable into an $T \times N$ matrix Y and the regressors into a $T \times K \times N$ array X. This allows the PanelOls() function to handle autocorrelation and cross-sectional clustering.

```
#@doc2 PanelReshuffle
```

```
(Y,X) = PanelReshuffle(y,x,[],id,per) #[] is not important here
(T,N,K) = (size(Y,1),size(Y,2),size(X,2))
println("The Y matrix is now $(T)x$(N), while X is $(T)x$(K)x$(N)")
display(Y)
```

The Y matrix is now 5x716, while X is 5x7x716

```
5×716 Matrix{Float64}:

1.80829 1.28093 1.81482 2.31254 ... 1.53039 1.52823 1.46094 1.60944

1.86342 1.51585 1.91991 2.34858 1.59881 2.4065 1.49669 1.45944

1.78937 1.93017 1.95838 2.37349 1.60405 2.55886 1.55984 1.42712

1.84653 1.91903 2.00707 2.3689 1.26794 2.64418 1.6536 1.49437

1.85645 2.20097 2.08985 2.35053 1.55823 2.58664 1.61586 1.34142
```

Pooled Estimation with PanelOls()

using the PanelOls() function from the FinEcmt_OLS module. The output is a named tuple. Use keys(f0) to see the names of the entries. The function reports White's covariance matrix () which gives the same results as using a traditional OLS approach, but it can also report a covariance matrix that allows for clustering (see further below in the notebook).

```
@doc2 PanelOls

#using CodeTracking
#println(@code_string PanelOls([1],[1]))
```

PanelOls(y,x,m=0,clust=[];FixNaNQ=false,HacMethod=:NW)

Pooled OLS estimation.

Input

- y0::Matrix: TxN matrix with the dependent variable, y[t,i] is for period t, individual i
- x0::3D Array: TxKxN matrix with K regressors
- m:: Int: (optional), scalar, number of lags in covariance estimation
- clust:: Vector {Int}: (optional), N vector with cluster number for each individual, [ones(N)]
- FixNaNQ::Bool: (optional), true: replace all cases (y[t,i],x[t,:,i]) with some NaN/missing with (0,0), using PanelReplaceNaN()
- HacMethod:: Symbol: :NW for Newey-West (tent shaped weights), :HH for Hodrick-Hansen (flat weights)

Output

- fnOutput:: NamedTuple: named tuple with the following elements
 - theta (K*L)x1 vector, LS estimates of regression coefficients on kron(z,x)
 - CovDK (KL)x(KL) matrix, Driscoll-Kraay covariance matrix
 - CovC covariance matrix, cluster
 - CovNW covariance matrix, Newey-West (or White if m=0)
 - CovAR covariance matrix, Arellano (handles autocorrelation)
 - CovCAR covariance matrix, cluster, Arellano (handles autocorrelation)
 - CovLS covariance matrix, iid
 - R2 scalar, (pseudo-) R2
 - yhat TxN matrix with fitted values
 - Nb T-vector, number of obs in each period

Notice

• for TxNxK -> TxKxN, do x = permutedims(z,[1,3,2])

Pooled Estimation with the PanelOls() Function

results from pooled OLS using PanelOls(), White's standard errors:

```
coef
                         t-stat
                1.285
                         28.513
С
exper/100
                7.837
                         8.954
exper^2/100
               -0.201
                         -5.264
tenure/100
                1.206
                         2.346
tenure^2/100
               -0.024
                         -0.828
```

```
south -0.196 -13.247
union 0.110 6.928
```

compare with the result from 'OlsNW()': they should be the same

First Difference Estimation

by first creating first difference (ΔY , ΔX) and then using PanelOls.

results from first difference model using PanelOls(), White's standard errors:

```
coef
                           t-stat
                 0.010
                            0.633
С
exper/100
                 3.548
                            2.277
exper^2/100
                -0.045
                           -0.933
                 1.293
tenure/100
                            2.527
tenure^2/100
                -0.083
                           -2.329
south
                -0.024
                           -0.395
union
                 0.044
                            3.115
```

Fixed Effects Estimation

We drop the intercept and then apply the FixedIndivEffects() function from the FinEcmt_OLS module. It removes individual fixed effects. Then we apply the PanelOls() function.

```
(y*,x*) = FixedIndivEffects(Y,X[:,2:end,:]) #drop the intercept

f0 = PanelOls(y*,x*)

θ_FE = f0.theta
StdErr = sqrt.(diag(f0.CovNW))
tstat_FE = θ_FE./StdErr

printblue("results from fixed effects model using PanelOls(), White's standard errors:\n")
printmat(θ_FE,tstat_FE,colNames=["coef","t-stat"],rowNames=xNames)
```

results from fixed effects model using PanelOls(), White's standard errors:

	coef	t-stat
exper/100	4.108	6.616
exper^2/100	-0.041	-1.640
tenure/100	1.391	4.445
tenure^2/100	-0.090	-4.624
south	-0.016	-0.411
union	0.064	4.675

Clustered Standard Errors

We now redo the FE estimation but provide information on clustering for the standard errors. For simplicity, the clusters are defined as the value of the South dummy in t = 1. Clearly, this could be done for the pooled OLS and the first difference models as well.

FE estimation with clustered standard errors:

	coef	t-stat White	t-stat Clust
exper/100	4.108	6.616	5.586
exper^2/100	-0.041	-1.640	-2.027
tenure/100	1.391	4.445	3.829
tenure^2/100	-0.090	-4.624	-4.880
south	-0.016	-0.411	-0.467
union	0.064	4.675	3.631

Unbalanced Panels (extra)

The PanelOls(;FixNaNQ=true) handles an unbalanced panel (NaNs/missings in (y,x)) by zeroing out all of (y[t,i],x[t,:,i]) if there is a NaN/missing value for observation (t,i).

Importantly, FixedIndivEffects() always calculates means based on only those observations that have no NaNs/missings, that is, based on those observations that are effectlively used in PanelOls(). This carries over to FixedIndivTimeEffects() and the other functions

This is illustrated in the cell below by first setting some of the data to NaN and then apply the functions. (The results are similar, but clearly not identical, to those above.)

```
(Yc,Xc) = (copy(Y),copy(X[:,2:end,:]))  #create new arrays (we change them below by inserting som
(Yc[1],Xc[end]) = (NaN,NaN)  #introduce some missings/NaNs

(yc<sup>x</sup>,xc<sup>x</sup>,) = FixedIndivEffects(Yc,Xc)  #demeans, using only those obs that have no missings/NaNs
f0 = PanelOls(yc<sup>x</sup>,xc<sup>x</sup>;FixNaNQ=true)

θ  = f0.theta
StdErr = sqrt.(diag(f0.CovNW))
tstat = θ./StdErr

printblue("Results after zeroing out observations with some missing values/NaNs:\n")
printmat(θ,tstat,colNames=["coef","t-stat"],rowNames=xNames)
```

Results after zeroing out observations with some missing values/NaNs:

	coef	t-stat
exper/100	4.080	6.563
exper^2/100	-0.039	-1.579
tenure/100	1.402	4.478
tenure^2/100	-0.090	-4.667

south	-0.016	-0.413
union	0.064	4.673

Individual and Time Fixed Effects (extra)

Redo the FE panel regression, but first we reconstruct (y^x, x^x) to handle *both* individual and time fixed effects.

For an unbalanced panel this is done in steps. First, remove individual effects (as above). Second, regress everything from the first step on time dummies. These two steps are done by the FixedIndiv-TimeEffects() function. Third, do a regression of the results from the 2nd step.

Reversing step 1 and 2 can be done, and makes sense when T > N. Use FixedTimeIndivEffects() for this.

Panel regression with individual and time fixed effects:

	coef	t-stat
exper/100	6.713	4.654
exper^2/100	-0.045	-1.762
tenure/100	1.347	4.279
tenure^2/100	-0.090	-4.641
south	-0.014	-0.358
union	0.065	4.801

Instrumental Variables

This notebook uses a function for 2SLS and illustrates it by redoing an example from Ch 10.3.3 in "Principles of Econometrics", 3rd edition (Hill, Griffiths and Lim).

Load Packages and Extra Functions

The key functions used for OLS and IV/2SLS are from the (local) FinEcmt_OLS module.

```
MyModulePath = joinpath(pwd(),"src")
!in(MyModulePath,LOAD_PATH) && push!(LOAD_PATH,MyModulePath)
using FinEcmt_OLS
```

```
#=
include(joinpath(pwd(),"src","FinEcmt_OLS.jl"))
using .FinEcmt_OLS
=#
```

```
using DelimitedFiles, LinearAlgebra
```

Loading the Data

The next cells replicates an old example from Hill et al (2008). See the lecture notes for more details.

A remark on the code

The data set contains many different variables. To import them with their correct names, we create a named tuple of them by using the function PutDataInNT() from the FinEcmt_OLS module. (This is convenient, but not important for the focus of this notebook. An alternative is to use the DataFrames.jl package.)

```
The variables in X (use as, for instance, X.wage): (:taxableinc, :federaltax, :hsiblings, :hfathereduc, :hmothereduc, :siblings, :lfp, :hours, :kidsl6, :
```

OLS

estimation of the log wage on education, experience and experience^2. Only data points where wage > 0 are used.

OLS estimates:

	coef	std
С	-0.522	0.198
educ	0.107	0.014
exper	0.042	0.013
exper^2	-0.001	0.000

IV (2SLS)

using the function TwoSLS() function.

In this application, the mother's education is used as an instrument for the person's education.

@doc2 TwoSLS

```
TwoSLS(y,x,z,NWQ=false,m=0)
```

Input

- y:: VecOrMat: Tx1 or T-vector of the dependent variable
- x:: VecOrMat: Txk matrix (or vector) of regressors
- z:: VecOrMat: TxL matrix (or vector) of instruments
- NWQ:Bool: if true, then Newey-West's covariance matrix is used, otherwise Gauss-Markov
- m:: Int: scalar, bandwidth in Newey-West; 0 means White's method

Output

- b:: Vector: k-vector, regression coefficients
- fnOutput::NamedTuple: with
 - res Tx1 or Txn matrix, residuals y yhat
 - yhat Tx1 or Txn matrix, fitted values
 - Covb matrix, covariance matrix of vec(b) = [beq1;beq2;...]
 - R2 1xn, R2
 - R2_stage1 k-vector, R2 of each x[:,i] in first stage regression on z
 - δ _stage1 Lxk matrix, coeffs from 1st stage x = z' δ
 - Stdδ_stage1 Lxk matrix, std of δ

Requires

- Statistics, LinearAlgebra
- CovNW

```
#using CodeTracking
#println(@code_string TwoSLS([1],[1],[1]))  #print the source code
```

```
printmat(f02.δ_stage1;colNames=rowNames,rowNames=zNames)

printblue("first-stage estimates: std errors")
printmat(f02.Stdδ_stage1;colNames=rowNames,rowNames=zNames)

printblue("first-stage estimates: R²")
printmat(f02.R2_stage1';colNames=rowNames)
```

first-stage estimates: coeffs (each regression in its own column)

	С	educ	exper	exper^2
С	1.000	9.775	-0.000	0.000
exper	0.000	0.049	1.000	-0.000
exper^2	-0.000	-0.001	0.000	1.000
mothereduc	0.000	0.268	-0.000	-0.000

first-stage estimates: std errors

	С	educ	exper	exper^2
С	0.000	0.422	0.000	0.000
exper	0.000	0.042	0.000	0.000
exper^2	0.000	0.001	0.000	0.000
mothereduc	0.000	0.031	0.000	0.000

first-stage estimates: R²

c educ exper exper^2 NaN 0.153 1.000 1.000

```
Stdb_iv = sqrt.(diag(f02.Covb))
printblue("IV estimates")
printmat(b_iv,Stdb_iv;colNames,rowNames)

printred("The results should be very close to Hill et al, 10.3.3,
but with small differences due to how df adjustments are made to variances")
```

IV estimates

	coef	std
С	0.198	0.471
educ	0.049	0.037
exper	0.045	0.014
exper^2	-0.001	0.000

The results should be very close to Hill et al, 10.3.3,

but with small differences due to how df adjustments are made to variances

GMM

This notebook shows a simple example of how GMM can be used to estimate model parameters. It starts with an exactly identified case and then moves on to different ways of estimating an overidentified case (pre-defined weighting matrix, recombining the moment conditions, optimal weighting matrix).

Load Packages and Extra Functions

The general GMM functions are from the (local) FinEcmt_MLEGMM module. In contrast, the functions for the moment conditions ("the model") are coded in the notebook below.

```
MyModulePath = joinpath(pwd(),"src")
!in(MyModulePath,LOAD_PATH) && push!(LOAD_PATH,MyModulePath)
using FinEcmt_OLS
using FinEcmt_MLEGMM: GMMAgbar, GMMExactlyIdentified, GMMgbarWgbar, meanV
```

```
#=
include(joinpath(pwd(),"src","FinEcmt_OLS.jl"))
include(joinpath(pwd(),"src","FinEcmt_MLEGMM.jl"))
using .FinEcmt_OLS
using .FinEcmt_MLEGMM: GMMAgbar, GMMExactlyIdentified, GMMgbarWgbar, meanV
=#
```

```
using DelimitedFiles, Statistics, NLsolve, LinearAlgebra
```

Loading Data

```
x = readdlm("Data/FFmFactorsPs.csv",',',skipstart=1) #start on line 2, column 1
x = x[:,2] #excess market returns, in %
T = size(x,1)
```

Exactly Identified GMM

This section describes the exactly identified GMM, that is, when we have as many moment conditions as parameters. In this case GMM is the same as the classical method of moments.

Traditional Estimation of Mean and Variance

The next cell applies the traditional way of estimating the mean and the variance. The standard errors are text book formulas.

Traditional estimates:

```
\begin{array}{ccc} & coef & std \\ \mu & 0.602 & 0.233 \\ \sigma^2 & 21.142 & 1.518 \end{array}
```

GMM Point Estimates

To estimate the mean and variance of x_t , use the following moment condition

$$g_t(\beta) = \begin{bmatrix} x_t - \mu \\ (x_t - \mu)^2 - \sigma^2 \end{bmatrix},$$

where
$$\beta = [\mu, \sigma^2]$$
.

The parameter values (μ, σ^2) that make these moment conditions hold are the same as from the traditional method. It is easy to solve for these parameters when the moment conditions are linear in the

parameters (as they are here). However, to facilitate adapting the code to non-linear models, we solve for the parameters by a numerical method.

Gmm2MomFn

A Remark on the Code

...in the next cells.

- The meanV() function calculates the sample mean of each column in a matrix and returns a vector.
- The $p\rightarrow meanV(Gmm2MomFn(p,x))$ defines an anonymous function (in terms of the vector of parameters p) that returns a vector of the sample averages of the moment conditions.
- Sol = $nlsolve(p\rightarrow meanV(Gmm2MomFn(p,x)),par_a)$ solves for the vector p that makes the average moment conditions equal to [0,0]. (This could be done manually in this case, but perhaps not in another application.)
- To extract the solution, use Sol.zero.

```
Sol = nlsolve(p→meanV(Gmm2MomFn(p,x)),par_a) #numerically solve for the estimates
par_1 = Sol.zero
printblue("GMM estimates:")
```

```
printmat(par_1;rowNames=parNames)

g = Gmm2MomFn(par_1,x)  #Tx2, moment conditions
gbar = meanV(g)  #2-vector with average moment conditions

printblue("Checking if mean of moment conditions = 0")
printmat(gbar;rowNames=["g1","g2"])
```

```
GMM estimates:  \mu \qquad 0.602 \\ \sigma^2 \qquad 21.142  Checking if mean of moment conditions = 0  g_1 \qquad 0.000 \\ g_2 \qquad 0.000
```

GMM Distribution

The distribution of the basic GMM estimates is

$$\hat{\beta} \stackrel{a}{\to} N(\beta_0, V_T),$$

where

$$V_T = (D'\Sigma^{-1}D)^{-1}/T,$$

$$\Sigma = \operatorname{Var}(\sqrt{T}\bar{g}),$$

$$D = \operatorname{plim} \frac{\partial \bar{g}}{\partial B'}$$
.

(This holds for exactly identified models and models using the optimal weighting matrix.)

A Remark on the Code

- CovNW(g,1,1) estimates Σ by using the Newey-West method with one lag.
- We can notice that $D = -I_2$ for the moment conditions used above.

```
 D = -I(2) \qquad \qquad \# Jacobian, does not really matter here \\ \Sigma = CovNW(g,1,1) \qquad \# variance of sqrt(T)*gbar, NW with 1 lag \\ V_T = inv(D'inv(\Sigma)*D)/T \\ printblue("GMM estimates:\n") \\ printmat(par_1,sqrt.(diag(V_T));colNames,rowNames=parNames) \\ printstyled("Compare with the traditional estimates",color=:red,bold=true)
```

GMM estimates:

```
\begin{array}{ccc} & coef & std \\ \mu & 0.602 & 0.244 \\ \sigma^2 & 21.142 & 2.381 \end{array}
```

Compare with the traditional estimates

A Function for Exactly Identified GMM

The functions printed in the next cell combines the previous code into a function for getting both point estimates and standard errors. The Jacobian is calculated numerically. The result should be the same as before. (For the rest of the notebook, the code will come in functions like this.)

```
@doc2 GMMExactlyIdentified
```

```
GMMExactlyIdentified(GmmMomFn::Function,x,par0,m)
```

Estimates GMM coeffs and variance-covariance matrix from an exactly identified model. The Jacobian is calculated numerically.

Input

- GmmMomFn:: Function: for the moment conditions, called as GmmMomFn(p,x) where p are the coefficients and x is the data.
- x::VecOrMat: data
- par0::Vector: initial guess
- m:: Int: number of lags in NW covariance matrix

```
#using CodeTracking
#println(@code_string GMMExactlyIdentified(cos,[1],[1],1))
```

```
(par_1b,Std_1b,) = GMMExactlyIdentified(Gmm2MomFn,x,par_a,1)
printblue("Results from GMMExactlyIdentified():\n")
printmat(par_1,sqrt.(diag(V_T));colNames,rowNames=parNames)
printstyled("Compare with GMM results from above",color=:red,bold=true)
```

Results from GMMExactlyIdentified():

```
\begin{array}{ccc} & coef & std \\ \mu & 0.602 & 0.244 \\ \sigma^2 & 21.142 & 2.381 \end{array}
```

Compare with GMM results from above

Overidentified GMM

This section discusses an overidentified case: more moment conditions than parameters.

Warning: some of the variables (g, Σ, etc) are overwritten with new values.

The Moment Conditions

If x_t is $N(\mu, \sigma^2)$, then the following moment conditions should all be zero (in expectation)

$$g_t(\beta) = \begin{bmatrix} x_t - \mu \\ (x_t - \mu)^2 - \sigma^2 \\ (x_t - \mu)^3 \\ (x_t - \mu)^4 - 3\sigma^4 \end{bmatrix},$$

where $\beta = [\mu, \sigma^2]$.

The first moment condition defines the mean μ , the second defines the variance σ^2 , while the third and forth are the skewness and excess kurtosis respectively.

```
Gmm4MomFn(par,x)

Calculate 4 moment conditions for estimating [μ,σ²]

# Input
- 'par::Vector': [μ,σ²]
- 'x::Vector': T-vector with data

# Output
- 'g::Matrix': Tx4, moment conditions

"""

function Gmm4MomFn(par,x)
(μ,σ²) = (par[1],par[2])
g = hcat(x .- μ, (x .- μ).^2 .- σ², (x .- μ).^3, (x .- μ).^4 .- 3*σ²^2) #Tx4
return g
end
```

Gmm4MomFn

Overidentified GMM: Minimizing gbar'W*gbar

The following code applies a numerical method to solve a minimization problem with the weighting matrix

The results should be the same (or at least very close to) the previous results, since this W matrix puts all weight on the first two moments. Changing W, for instance, by setting W[3,3]=0.0001 will give other estimates.

We define the loss function as $\bar{g}'W\bar{g}$.

The expressions for variance-covatriance matrix are in the lecture notes.

A Function for gbar'W*gbar Estimation

```
@doc2 GMMgbarWgbar
```

```
GMMgbarWgbar(GmmMomFn::Function,W,x,par0,m;SkipCovQ=false)
```

Estimates GMM coeffs and variance-covariance matrix from A*gbar. The Jacobian is calculated numerically.

Input

- GmmMomFn:: Function: for the moment conditions, called as GmmMomFn(p,x) where p are the coefficients and x is the data.
- W::Matrix: length(gbar)xlength(gbar)
- x:: VecOrMat: data
- par0:: Vector: initial guess
- m:: Int: number of lags in NW covariance matrix
- SkipCovQ:: Bool: if true: the Jacobian and variance-covariance matrix are not calculated. This can be used to speed up calculations in iterative computations.

```
#println(@code_string GMMgbarWgbar(cos,[1],[1],[1],1))
```

```
W = diagm(0⇒[1.0,1.0,0.0,0.0]) #weighting matrix, try changing it
#W[3,3] = 0.0001
(par2,StdErr2,_,Σ2,_) = GMMgbarWgbar(Gmm4MomFn,W,x,par_a,1)
printblue("GMM estimates (gbar'W*gbar):\n")
printmat(par2,StdErr2;colNames,rowNames=parNames)
```

2.381

21.142

 σ^2

Overidentified GMM: Minimizing gbar'W*gbar, Iterating over W

The following code iterates over the weighting matrix by using $W = \Sigma^{-1}$, where $\Sigma = \text{Cov}(\sqrt{T}\bar{g})$ is from the previous iteration.

A Remark on the Code

- (maximum(abs,par par_old) > 1e-3) || (i < 2) loops while the |change| in the parameters > 1e-3 (and at least once).
- par_old = copy(par) makes an independent copy of the par. This is not needed here (since par is overwritten further below), but often a good routine.

```
println("\niterated GMM, using optimal weighting matrix, starting with \Sigma from previous estimation")
(par, par_old, \Sigma, i) = (copy(par2), fill(Inf, length(par2)), copy(\Sigma2), 1)
println("\n\niterating over W starting with the W choice above")
while (maximum(abs,par - par_old) > 1e-3) || (i < 2)
                                                        #require at least one iteration
    #global par, par_old, i, W, Σ
                                     #only needed in script
    global StdErr2, D
    println("-----iteration $i, old and new parameters----")
    par_old = copy(par)
                                      #update par_old
            = inv(\Sigma)
    (par, StdErr2, ..., \Sigma, D) = GMMgbarWgbar(Gmm4MomFn, W, x, par_old, 1)
            = i + 1
    printlnPs(par_old',"\n",par')
 end
printblue("\nGMM estimates (gbar'W*gbar, iteration over W):")
xx = [par StdErr2]
printmat(xx;colNames,rowNames=parNames,width=12)
```

iterated GMM, using optimal weighting matrix, starting with Σ from previous estimation

```
iterating over W starting with the W choice above
-----iteration 1, old and new parameters-----
    0.602
             21.142
    0.877
             16.916
-----iteration 2, old and new parameters-----
    0.877
             16.916
    0.879
             16.648
-----iteration 3, old and new parameters-----
    0.879
             16.648
    0.879
             16.645
```

```
0.879
              16.647
-----iteration 5, old and new parameters-----
     0.879
              16.647
     0.879
              16.647
GMM estimates (gbar'W*gbar, iteration over W):
          coef
                        std
         0.879
                      0.219
μ
\sigma^2
        16.647
                      1.341
printblue("W matrix used in the last iteration, (times 10000):\n")
momNames = ["g_1", "g_2", "g_3", "g_4"]
printmat(W*10000,colNames=momNames,rowNames=momNames)
W matrix used in the last iteration, (times 10000):
          g1
                    g 2
                               gз
                                         g4
   1525.564
                39.433
                          -16.963
                                     -0.674
g1
g 2
      39.433
                18.778
                          -0.297
                                     -0.050
     -16.963
                -0.297
                            0.306
                                      0.012
gз
      -0.674
                -0.050
                            0.012
                                      0.001
g4
V_T = inv(D'inv(\Sigma)*D)/T
                                               #with optimal weighting matrix
printblue("\nGMM estimates (gbar'W*gbar, iteration over W):")
xx = [par StdErr2 sqrt.(diag(V_T))]
printmat(xx;colNames=[colNames;"std ver. 2"],rowNames=parNames,width=12)
printred("Notice that the standard errors (calculated in two ways) are (almost) the same after the
```

-----iteration 4, old and new parameters-----

GMM estimates (gbar'W*gbar, iteration over W):

0.219

1.341

std std ver. 2

0.219

1.341

coef

0.879

16.647

 μ σ^2

16.645

0.879

Notice that the standard errors (calculated in two ways) are (almost) the same after the iterations

Overidentified GMM: A*g = 0

The following code from estimates the parameters by combining the 4 original moment conditions in \bar{g} into 2 effective moment conditions, $A\bar{g}$, where A is a 2 × 4 matrix

$$A = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}$$

This particular A matrix implies that we use the classical estimators of the mean and variance. Changing A, for instance, by setting A[1,3] = 0.001 will give different estimates.

The next cell prints a function for doing A*gbar GMM.

```
@doc2 GMMAgbar
```

```
GMMAgbar(GmmMomFn::Function,A,x,par0,m)
```

Estimates GMM coeffs and variance-covariance matrix from A*gbar. The Jacobian is calculated numerically.

Input

- GmmMomFn:: Function: for the moment conditions, called as GmmMomFn(p,x) where p are the coefficients and x is the data.
- A:: Matrix: length(p) x length(gbar)
- x::VecOrMat: data
- par0::Vector: initial guess
- m:: Int: number of lags in NW covariance matrix

```
#using CodeTracking
#println(@code_string GMMAgbar(cos,[1],[1],1))
```

```
A = [1 0 0 0;  #A in A*gbar=0 (here: all weight on first two moments)
      0 1 0 0]  #try setting A[1,3] = 0.001

(par_3b,Std_3b) = GMMAgbar(Gmm4MomFn,A,x,par_a,1)

printblue("GMM estimates (A*gbar) from GMMAgbar():\n")
printmat(par_3b,Std_3b;colNames,rowNames=parNames)
```

```
GMM estimates (A*gbar) from GMMAgbar():
```

 $\begin{array}{ccc} & coef & std \\ \mu & 0.602 & 0.244 \\ \sigma^2 & 21.142 & 2.381 \end{array}$

Time Series Analysis

This notebook estimates autocorrelations and different time series models (AR, MA and VAR).

Load Packages and Extra Functions

The key functions in this notebook are from the (local) FinEcmt_TimeSeries module, but we also use StatsBase.jl package for estimating autocorrelations.

```
MyModulePath = joinpath(pwd(),"src")
!in(MyModulePath,LOAD_PATH) && push!(LOAD_PATH,MyModulePath)
using FinEcmt_OLS, FinEcmt_TimeSeries
using FinEcmt_MLEGMM: MLE
```

```
#=
include(joinpath(pwd(),"src","FinEcmt_OLS.jl"))
include(joinpath(pwd(),"src","FinEcmt_TimeSeries.jl"))
using .FiniteDiff: finite_difference_hessian as hessian, finite_difference_jacobian as jacobian
using .FinEcmt_OLS, .FinEcmt_TimeSeries
using .FinEcmt_MLEGMM: MLE
=#
```

```
using DelimitedFiles, LinearAlgebra, Distributions, StatsBase
```

```
using Plots
default(size = (480,320),fmt = :png)
```

Load Data

```
xx = readdlm("Data/RvSP500.csv",',',skipstart=1)
y_data = xx[:,3]  #SP500 log realized monthly volatility
xx = nothing

T = size(y_data,1)
println("Sample size: $T")
```

Sample size: 574

Descriptive Statistics

Autocorrelations

The sth autocorrelation ρ_s is the correlation of y_t and y_{t-s} . It is a useful tool for describing the properties of data.

It can be shown that the t-stat of an autocorrelation is $\sqrt{T} \rho_s$.

We can (jointly) test the first L autocorrelations by the Box-Pierce test, which (under the null hypothesis of no autocorrelation) has a χ_L^2 distribution.

```
L = 5
lags = 1:L
ρ_data = autocor(y_data,lags)  #using the StatsBase package

printblue("Autocorrelations:\n")
printmat(ρ_data,sqrt(T)*ρ_data;colNames=["autocorrr","t-stat"],rowNames=lags,cell00="lag")

BP = T*sum(ρ_data.^2)  #the Box-Pierce test statistic

printblue("Box-Pierce test:\n")
printmat(BP,quantile(Chisq(L),0.9);rowNames=["test statistic","10% critical value"])
```

Autocorrelations:

```
lag autocorrr t-stat
1 0.709 16.982
2 0.602 14.419
3 0.529 12.684
4 0.459 11.000
```

5 0.455 10.903

Box-Pierce test:

test statistic 897.040 9.236

AR(p)

This section discusses the properties and estimation of autoregressive (AR) processes.

Rewriting an AR(p) as a VAR(1)

An easy way to do AR(p) calculation is to first transform the AR(p) to a VAR(1) (also called companion form) and then apply the rather straightforward formulas for VAR(1) models.

For instance, an AR(2)

$$y_t = a_1 y_{t-1} + a_2 y_{t-2} + \epsilon_t.$$

can be written as a 2-variable VAR(1)

$$x_t = A_1 x_{t-1} + u_t,$$

where

$$x_t = \begin{bmatrix} y_t \\ y_{t-1} \end{bmatrix}$$
 and $A_1 = \begin{bmatrix} a_1 & a_2 \\ 1 & 0 \end{bmatrix}$.

This is done in the CompanionFormAR(a) function.

```
(a_1,a_2) = (0.85,-0.5) #AR(2)

(A,\Omega) = CompanionFormAR([a_1,a_2]) #A and the Var(shocks)
```

([0.85 -0.5; 1.0 0.0], [1.0 0.0; 0.0 0.0])

Impulse Response Function of an AR Process

The next cell shows how a shock to an AR process propagates over time, the *impulse response function* (IRF). For *stationary models*, the effect of a shock eventually disappears.

The IRF can be calculated by an explicit loop for the specific model. We do that below in order to show the basic idea. As a comparison, we apply the approach of first transforming to a VAR(1) and then using the simple formulas for that model

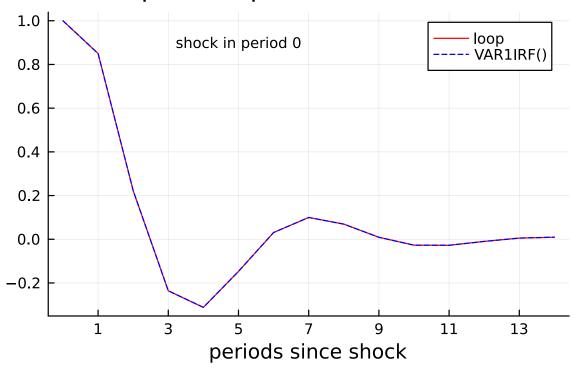
 $\partial x_{t+s}/\partial u_{j,t} = A^s e_j$, \$ where is a vector of zeros, except that element *j* is one. The function VAR1IRF() (from local module) does this.

(The ARMAFilter() function could also be used but this is not done here.)

The models used here is an AR(2)

```
y_t = a_1 y_{t-1} + a_2 y_{t-2} + \epsilon_t.
```

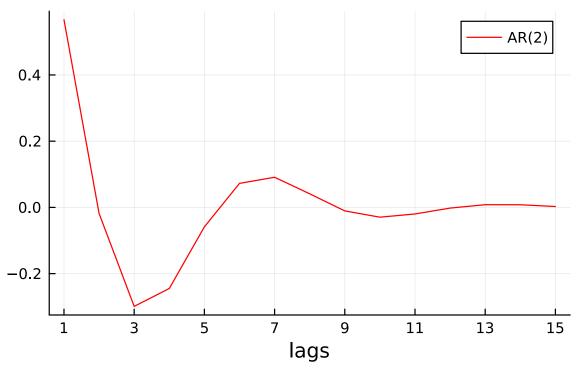
Impuse response function (IRF)



Autocorrelations Implied by an AR Process

by using VAR1AutoCov() (from local module)





Estimation of an AR Process

AR models can be estimated by OLS.

The ARpEst(y,p) function (from local module) provides a simple way of doing this.

```
#@doc2 ARpEst

#using CodeTracking
#println(@code_string ARpEst([1],2))  #print the source code
```

```
aAR1_data = ARpEst(y_data,1)
aAR2_data = ARpEst(y_data,2)
printlnPs("Estimated AR(1) coef: ",aAR1_data)
printlnPs("Estimated AR(2) coefs: ",aAR2_data)
```

Estimated AR(1) coef: 0.713

Estimated AR(2) coefs: 0.569 0.204

More Descriptive Statistics: Partial Autocorrelations

The partial autocorrelation coefficient is the regression coefficients on x_{t-p} in an AR(p) regression, that is, on the last regressor. It is a useful tool for describing the properties of your data.

```
pac_data = pacf(y_data,lags) #from the StatsBase package

printblue("autocorrelations and partial autocorrelations:\n")
printmat(ρ_data,pac_data;colNames=["autocorr","pac"],rowNames=lags,cell00="lag")

printred("ρ_data[1] and pac_data[1] are very similar: in a large sample they would be almost the sample they w
```

autocorrelations and partial autocorrelations:

lag	autocorr	pac
1	0.709	0.713
2	0.602	0.204
3	0.529	0.103
4	0.459	0.031
5	0.455	0.130

 $\rho_{data}[1]$ and pac_data[1] are very similar: in a large sample they would be almost the same

The Roots of an AR Model (extra)

The *roots* of an AR(p) is a formal way of determining whether it is stationary. (An informal way is to check whether the impulse response function goes to zero as the horizon is extended.)

An easy way to calculate the roots is to first transform the AR(p) to a VAR(1) and then calculate the eigenvalues. If their absolute values are lower than one, then the model is stationary.

```
\lambda = \text{eigen(A).values} #eigenvalues of the companion form 
println("absolute values of the eigenvalues: should be < 1 for stationarity") 
printmat(abs.(\lambda))
```

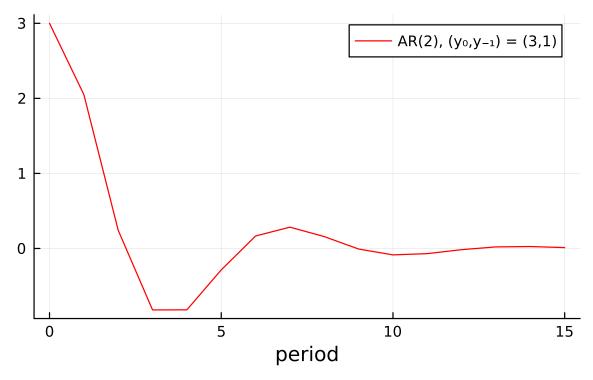
```
absolute values of the eigenvalues: should be < 1 for stationarity
    0.707
    0.707</pre>
```

Forecasting with an AR Process

Forecasts can be calculated in several ways. The perhaps easiest approach is to use the VAR(1) form and notice that $E_t x_{t+s} = A^s x_t$.

The VAR1Forecast() (from local module) implements this.

Forecasts based on t=0 info



VAR(p)

This section some of the calculations for vector autoregressive (VAR) processes. Formally, this is very similar to the computations for the AR(p) above, since we used the approach of converting the AR() model to a VAR(1). However, there is one key difference: we are now interested in the results for more than one (the first) variable.

To illustrate this, consider a VAR(2)

$$y_t = A_1 y_{t-1} + A_2 y_{t-2} + \epsilon_t$$

where y_t and y_{t-1} are vectors with two elements and

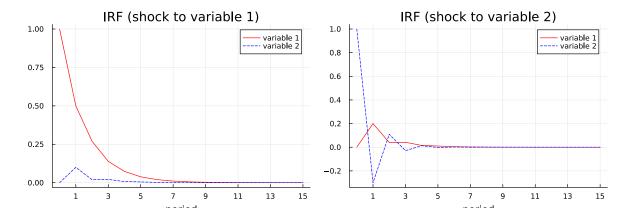
$$A_1 = \begin{bmatrix} 0.5 & 0.2 \\ 0.1 & -0.3 \end{bmatrix}$$

$$A_2 = \begin{bmatrix} 0.1 & 0.1 \\ 0.1 & 0.2 \end{bmatrix}$$

(You may want to change A_2 to a matrix of zeros to compare with the results in the lecture notes.)

```
A1 = [0.5 \ 0.2;
      0.1 - 0.3
A2 = [0.1 \ 0.1;
      0.1 0.2]
A2 = zeros(2,2)
Ap = cat(A1, A2, dims=3)
A, = CompanionFormVAR(Ap)
                                      #convert VAR(2) to larger VAR(1)
irf_var2 = VAR1IRF(A,t_max;m=2)
p1 = plot( 0:t_max,irf_var2[:,:,1],
           label = ["variable 1" "variable 2"],
           linecolor = [:red :blue],
           linestyle = [:solid :dash],
           xticks = 1:2:t_max,
           xlabel = "period",
           title = "IRF (shock to variable 1)" )
p2 = plot( 0:t_max,irf_var2[:,:,2],
           label = ["variable 1" "variable 2"],
           linecolor = [:red :blue],
           linestyle = [:solid :dash],
           xticks = 1:2:t_max,
           xlabel = "period",
```

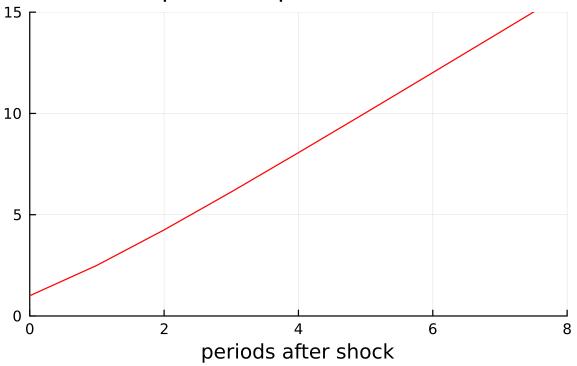
```
title = "IRF (shock to variable 2)" )
p = plot(p1,p2,layout=(1,2),size=(480*2,320))
display(p)
```



Non-Stationary Processes

The cells below shows the impulse response function and the roots of a non-stationary AR(3).

Impulse response function



```
\lambda = \text{eigen(A).values} #eigenvalues of the companion form 
println("absolute values of the eigenvalues: should be < 1 for stationarity") 
printmat(abs.(\lambda))
```

absolute values of the eigenvalues: should be < 1 for stationarity

- 0.500
- 1.000
- 1.000

Time Series Analysis

This notebook estimates autocorrelations and different time series models (AR, MA and VAR).

Load Packages and Extra Functions

The key functions in this notebook are from the (local) FinEcmt_TimeSeries module, but we also use StatsBase.jl package for estimating autocorrelations.

```
MyModulePath = joinpath(pwd(),"src")
!in(MyModulePath,LOAD_PATH) && push!(LOAD_PATH,MyModulePath)
using FinEcmt_OLS, FinEcmt_TimeSeries
using FinEcmt_MLEGMM: MLE
```

```
#=
include(joinpath(pwd(),"src","FinEcmt_OLS.jl"))
include(joinpath(pwd(),"src","FinEcmt_TimeSeries.jl"))
using .FiniteDiff: finite_difference_hessian as hessian, finite_difference_jacobian as jacobian
using .FinEcmt_OLS, .FinEcmt_TimeSeries
using .FinEcmt_MLEGMM: MLE
=#
```

```
using DelimitedFiles, LinearAlgebra, Distributions, StatsBase
```

```
using Plots
default(size = (480,320),fmt = :png)
```

Load Data

```
xx = readdlm("Data/RvSP500.csv",',',skipstart=1)
y_data = xx[:,3]  #SP500 log realized monthly volatility
xx = nothing

T = size(y_data,1)
println("Sample size: $T")
```

Sample size: 574

MA(q)

This section discusses the properties and estimation of moving average (MA) processes.

Note that the Impulse Response Function (IRF) and the autocorrelation of an MA(q) Process goes to zero at lag q + 1.

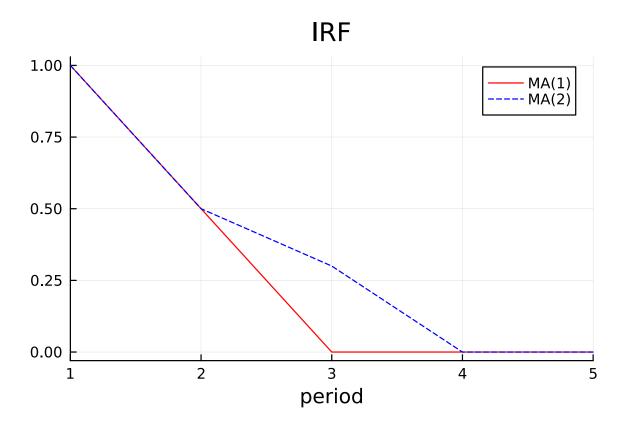
The ARMAFilter() creates an ARMA series from a series of white noise residuals. We apply that to the case when only an initial residual is non-zero, which gives the IRF.

```
#@doc2 ARMAFilter

#using CodeTracking
#println(@code_string ARMAFilter([1],[1]))  #print the source code
```

```
\begin{array}{lll} \theta = 0.5 & \# MA(1) \\ (\theta_1, \theta_2) = (0.5, 0.3) & \# MA(2) \\ \\ t_{max} = 15 & \\ \varepsilon & = zeros(t_{max}) \\ \varepsilon[1] = 1 & \# a single shock, otherwise zeros \\ \\ y1 & = ARMAFilter(\varepsilon, [], \theta) \\ y2 & = ARMAFilter(\varepsilon, [], [\theta_1, \theta_2]) \\ \\ p1 & = plot(1:t_{max}, [y1 \ y2], \\ & label = ["MA(1)" \ "MA(2)"], \\ & linecolor = [:red :blue], \\ & linestyle = [:solid :dash], \\ & xlims = (1,5), \\ \end{array}
```

```
xlabel = "period",
    title = "IRF" )
display(p1)
```



Estimation of an MA(q) (extra)

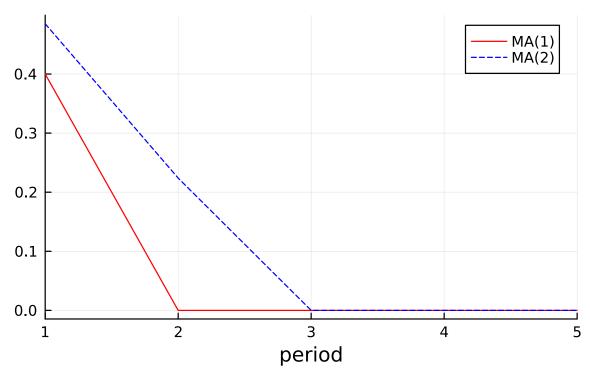
To estimate an MA model, we can apply MLE. For the numerical optimization we use the Optim.jl package.

The MAqLL(par,y_data) function (included above) calculates the likelihood function and returns it as its first output.

```
par0 = [0.5,0.3,0,0,1] \quad \#\theta_1,\theta_2,\theta_3,\theta_4,\sigma \qquad \text{#estimate an MA}(4) LLtFun\_MA(par,y,x) = MAqLL(par,y)[1] \qquad \#log likelihood fn par, = MLE(LLtFun\_MA,par0,y\_data,nothing) (\theta hat,\sigma hat) = (par[1:end-1],par[end])
```

Autocovariances

Autocorrelations of MA



Approximating an MA by an AR

by using the Yule-Walker equations

```
a2 = YuleWalker([1;\rho2[1:2]])
a3 = YuleWalker([1;\rho2[1:3]])

printblue("MA(2)")
printmat([\theta_1,\theta_2],\text{rowNames}=["\theta_1",\"\theta_2"])

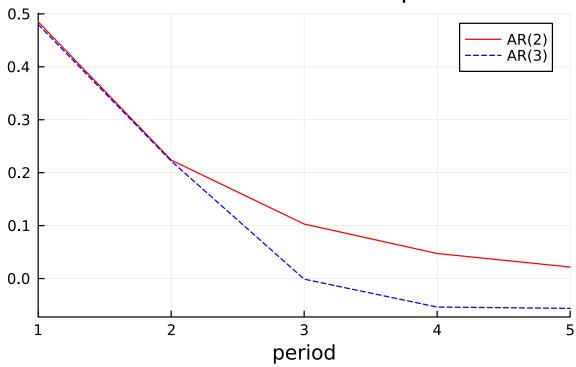
printblue("Approximating MA(2) by AR(2)")
printmat(a2;\text{rowNames}=["\text{a}_1",\"\text{a}_2"])

printblue("Approximating MA(2) by AR(3)")
printmat(a3;\text{rowNames}=["\text{a}_1",\"\text{a}_2",\"\text{a}_3"])
```

```
MA(2) \theta_1 0.500
```

```
θ2
       0.300
Approximating MA(2) by AR(2)
       0.492
      -0.015
a<sub>2</sub>
Approximating MA(2) by AR(3)
a<sub>1</sub>
       0.490
       0.051
a<sub>2</sub>
      -0.135
аз
A_ar2, = CompanionFormAR(a2)
                                              #AR(2) to companion form
(-,-,\rho_ar2) = VAR1AutoCov(A_ar2,t_max;m=1)
                                                   #implied autocorrelations
A_ar3, = CompanionFormAR(a3)
                                              #AR(2) to companion form
(\_,\_,\rho\_ar3) = VAR1AutoCov(A\_ar3,t\_max;m=1)
                                                 #implied autocorrelations
p1 = plot(1:t_max,[\rho_ar2 \rho_ar3],
           label = ["AR(2)" "AR(3)"],
           linecolor = [:red :blue],
            linestyle = [:solid :dash],
            xlims = (1,5),
            xlabel = "period",
            title = "Autocorrelations of AR. Compare with MA" )
display(p1)
```

Autocorrelations of AR. Compare with MA



Estimating and Testing Distributions

This notebook illustrates basic descriptive statistics (means, std, skewness, kurtosis), histograms, the Jarque-Bera test (of normality), Q-Q plots and tests of the empirical distribution function (Kolmogorov-Smirnov). It uses the Distributions.jl and StatsBase.jl packages.

You may also consider the HypothesisTests.jl package.

Load Packages and Extra Functions

The key functions used in this notebook (JarqueBeraTest() and KolSmirTest()) are from the (local) FinEcmt_OLS module.

```
MyModulePath = joinpath(pwd(),"src")
!in(MyModulePath,LOAD_PATH) && push!(LOAD_PATH,MyModulePath)
using FinEcmt_OLS
```

```
#=
include(joinpath(pwd(),"src","FinEcmt_OLS.jl"))
using .FinEcmt_OLS
=#
```

```
using DelimitedFiles, Statistics, Distributions, StatsBase
```

```
using Plots
default(size = (480,320),fmt = :png)
```

Load Data from a csv File

```
xx = readdlm("Data/FFdFactors.csv",',',skipstart=1)
x = xx[:,2]  #equity market excess returns
xx = nothing

T = size(x,1)
println("Sample size: $T")
```

Sample size: 15356

Histograms

The next few cells shows some basic descriptive statistics for the variable x (US equity market excess return).

```
µ = mean(x)

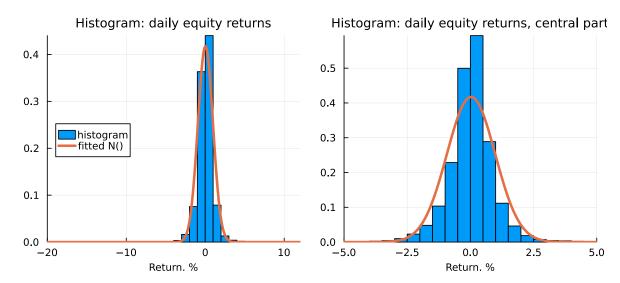
σ = std(x)
(xmin,xmax) = extrema(x)

printblue("Basic descriptive stats:\n")

xx = [µ,σ,xmin,xmax]
printmat(xx;rowNames=["μ","σ","min","max"])
```

Basic descriptive stats:

```
\begin{array}{lll} \mu & 0.026 \\ \sigma & 0.955 \\ \text{min} & -17.440 \\ \text{max} & 11.350 \\ \end{array}
```



Averaged Shifted Histogram

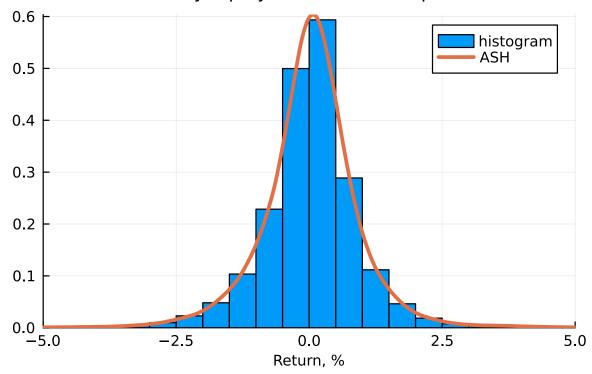
An averaged shifted histogram (ASH) first calculates histogram values over many bins and then averages across nearby bins. The output is a smoother histogram and something that comes very close to a kernel density estimate (see below).

```
(ashPdf1, BinMid_ash1,_) = HistAsh(x,-5:0.5:5,21) #21 shifts

p2 = histogram(x,bins = -5:0.5:5,
```

```
normalized = true,
label = "histogram",
xlim = (-5,5),
title = "Daily equity returns, central part",
titlefontsize = 10,
xlabel = "Return, %",
guidefontsize = 8 )
plot!(BinMid_ash1,ashPdf1,linewidth=3,label="ASH")
display(p2)
```

Daily equity returns, central part



Q-Q Plot

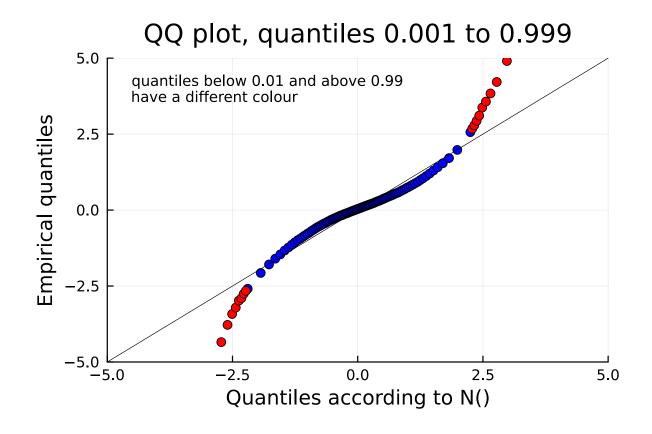
The Q-Q plot shows the empirical quantiles against the theoretical quantiles (possibly from an estimated distribution). If the theoretical distribution is a good fit to the data, then the results should cluster closely around a 45 degree line.

A Remark on the Code

The quantile() function for a distribution (from the Distributions.jl package) works slightly different from the quantile() function for data (from the StatsBase.jl package). In short,

- quantile. (Normal(μ , σ), pval1) calculates a vector of quantiles of a Normal(μ , σ) distribution.
- quantile(x,pval1) calculates a vector of empirical quantiles from the vector x (notice: no dot).

As an alternative, do dist = fit(Normal,x); quantile.(dist,pval1)



Skewness, Kurtosis and the Jarque-Bera Test

The JarqueBeraTest() function reports skewness, kurtosis and the B-J statistic.

@doc2 JarqueBeraTest

JarqueBeraTest(x)

Calculate the JB test for each column in a matrix. Reports (skewness, kurtosis, JB).

```
#using CodeTracking
#println(@code_string JarqueBeraTest([1]))
```

```
(skewness,kurtosis,JB,pvals) = JarqueBeraTest(x)

#critval_BJ = quantile(Chisq(2),0.9)  #critical values
#critval_skew = quantile(Normal(0,sqrt(6/T)),0.9)
```

More descriptive stats:

	Estimate	p-value
skewness	-0.519	0.000
excess kurtosis	16.166	0.000
Jarque-Bera	167896.608	0.000

The Empirical Distribution Function and the Kolmogorov-Smirnov Test

The empirical distribution function (edf) shows the frequence of data points below a given threshold. The Kolmogorov-Smirnov (K-S) test is designed to investigate whether the edf differs from a theoretical (possibly estimated) cdf. It is implemented in the function KolSmirTest().

An edf does essentially the following: rank all elements in x and divide the ranks by T to get relative ranks (0 to 1).

The K-S test finds the largest difference between the edf and the theoretical cdf, D. The 5% critical value of $\sqrt{T}D$ is 1.36.

```
@doc2 KolSmirTest
```

```
KolSmirTest(x1,TheoryCdf::Function)
```

Calculate the Kolmogorov-Smirnov test

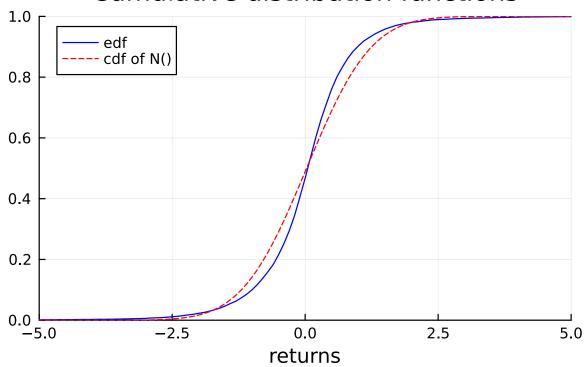
Output

- KSstat::Float64: KS test statistic
- xD:: Number: x value with the largest diff beteen empirical and theoretical cdf

```
#println(@code_string KolSmirTest([1],cos))
```

```
edfx = ecdf(x)
                                  #construct the empirical distribution function
                                  #from the StatsBase.jl package
edfEmp = edfx(xGrid)
                                         #evaluate the empirical distribution function at xGrid
       = cdf.(Normal(\mu,\sigma),xGrid);
                                         #cdf of Normal(\mu,\sigma), for comparison
p1 = plot( xGrid,[edfEmp cdfN],
           label = ["edf" "cdf of N()"],
           linecolor = [:blue :red],
           linestyle = [:solid :dash],
           title = "Cumulative distribution functions",
           xlabel = "returns",
           xlim = (-5,5),
           ylim = (0,1))
display(p1)
```

Cumulative distribution functions



```
(KSstat,xD) = KolSmirTest(x,z→cdf(Normal(μ,σ),z))
printblue("Kolmogorov-Smirnov test:\n")
printmat([KSstat,1.36,xD];rowNames=["sqrt(T)*D","5% critval","at which x"])
```

Kolmogorov-Smirnov test:

```
sqrt(T)*D 9.941
5% critval 1.360
at which x -0.400
```

Kernel Density Estimate

The KernelDensity() function estimates the probability density function (pdf) by using a gaussian kernel. The bandwidth parameter (h) can be supplied by the caller, otherwise it defaults to the rule of thumb value $h = 1.06 \text{std}(x_t)/T^{0.2}$. In practice, the choice of kernel is less important that the choice of bandwidth.

The estimate of the pdf at value x is $\hat{f}(x) = \frac{1}{h} \frac{1}{T} \sum_{t=1}^{T} K(\frac{x_t - x}{h})$,

where K() is one of the kernel functions listed below.

The function outputs both the estimate the estimate of pdf(x), denoted fx, and its standard deviation, denoted Stdfx. The values are estimated at a grid of x values, supplied by the user.

As an alternative to this code, consider the KernelDensity.jl package. Also, compare with the ASH used before.

```
using FinEcmt_KernelRegression
```

```
@doc2 KernelDensity
```

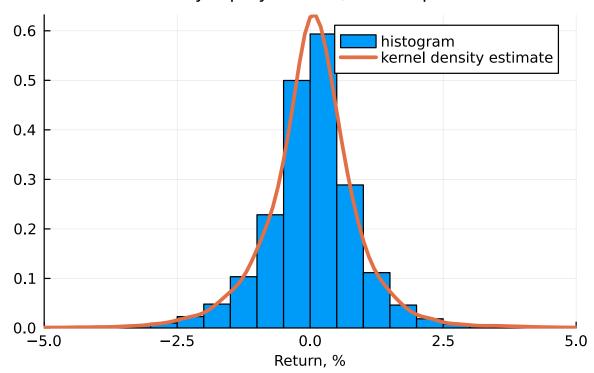
KernelDensity(x,xGrid,h=[],KernelFun=GaussianKernel)

Compute a kernel density estimate at each value of the grid xGrid, using the data in vector x. The bandwidth h can be specified (otherwise a default value is used). The kernel function defaults to a standard normal density function, but other choices are available.

```
#using CodeTracking
#println(@code_string KernelDensity([1],[1]))
```

```
label = "histogram",
    xlim = (-5,5),
    title = "Daily equity returns, central part",
    titlefontsize = 10,
    xlabel = "Return, %",
    guidefontsize = 8 )
plot!(xGrid,fx,linewidth=3,label="kernel density estimate")
display(p2)
```

Daily equity returns, central part



Maximum Likelihood Estimation

This notebook illustrates maximum likelihood estimation and how to calculate different standard errors (from the information matrix, the gradients and the "sandwich" approach).

The application is very simple: estimating the mean and variance of a random variable. Some of the subsequent chapters (notebooks) work with more complicated models, for instance, GARCH models.

Load Packages and Extra Functions

The notebook first implements MLE step-by-step. At the end it also presents the MLE() function from the (local) FinEcmt_MLEGMM module that wraps those calculations.

For the numerical optimization we use the Optim.jl package and for calculating derivatives the Finite-Diff.jl package. (ForwardDiff.jl is an alternative.)

```
MyModulePath = joinpath(pwd(),"src")
!in(MyModulePath,LOAD_PATH) && push!(LOAD_PATH,MyModulePath)
using FinEcmt_OLS
using FinEcmt_MLEGMM: MLE  #load only the MLE() function
```

```
#=
include(joinpath(pwd(),"src","FinEcmt_OLS.jl"))
include(joinpath(pwd(),"src","FinEcmt_MLEGMM.jl"))
using .FinEcmt_OLS
using .FinEcmt_MLEGMM: MLE  #load only the MLE() function
=#
```

```
using LinearAlgebra, DelimitedFiles, Statistics, Optim
#loading and renaming some functions from FiniteDiff (to get shorter names)
using FiniteDiff: finite_difference_hessian as hessian, finite_difference_jacobian as jacobian
```

Loading Data

```
xx = readdlm("Data/FFdSizePs.csv",',',skipstart=1)
x = xx[:,2]  #returns for the portfolio of the smallest firms
xx = nothing
```

Traditional Estimates

of the mean μ and the variance σ^2 .

The standard errors of the mean and standard deviation are from traditional textbook formulas.

```
T = \operatorname{length}(x) (\mu_{-}\operatorname{trad},\sigma^{2}_{-}\operatorname{trad}) = (\operatorname{mean}(x),\operatorname{var}(x,\operatorname{corrected=false})) \qquad \text{\#corrected=false gives 1/T formula, not 1/(1)} \operatorname{std\_trad} = \operatorname{sqrt.}([\sigma^{2}_{-}\operatorname{trad},2*\sigma^{2}_{-}\operatorname{trad}^{2}]/T) \qquad \text{\#standard errors, textbook formulas} \operatorname{printblue}(\text{"Traditional estimates and their std:} \n") xx = [[\mu_{-}\operatorname{trad},\sigma^{2}_{-}\operatorname{trad}] \operatorname{std\_trad}] \operatorname{printmat}(xx;\operatorname{colNames=}[\text{"estimate","std"}],\operatorname{rowNames=}[\text{"}\mu\text{","}\sigma^{2}\text{"}])
```

Traditional estimates and their std:

```
\begin{array}{ccc} & \text{estimate} & \text{std} \\ \mu & \text{0.042} & \text{0.010} \\ \sigma^2 & \text{0.840} & \text{0.013} \end{array}
```

Point Estimates from ML

The next few cells define a log likelihood function and estimate the coefficients by maximizing it.

The (log) Likelihood Function for Estimating the Parameters of a N(,)

A Remark on the Code

• (μ, σ^2) = par splits up the vector par into two numbers (for the mean and variance)

```
NormalLL(par,x)

Calculate log likelihood for a 'N(\mu,\sigma^2)' distribution.

'par = [\mu,\sigma^2]' is a vector with the parameters , 'x' is a vector with data

"""

function NormalLL(par,x)

(\mu,\sigma^2) = par

\sigma = sqrt(\sigma^2)

z = (x ·- \mu)./\sigma

LLt = logpdfNorm.(z) ·- log(\sigma) #shorter, from local module

#LLt = -(1/2)*log(2*pi) - (1/2)*log(\sigma^2) ·- (1/2)*abs2.(x.-\mu)/\sigma^2 #vector, all x[t]

return LLt

end;
```

Try the Likelihood Function

```
par0 = [0.0,1.0] #initial parameter guess of [\mu,\sigma^2]

LLt = NormalLL(par0,x) #just trying the log likelihood fn

printlnPs("log likelihood value at par0: ",sum(LLt))
```

log likelihood value at par0: -11155.385

Optimize the Likelihood Function

```
Sol = optimize(par→-sum(NormalLL(par,x)),par0) #minimize -sum(LLt)
parHat = Optim.minimizer(Sol) #the optimal solution

printlnPs("log-likelihood at point estimate (compare with the value above): ",-Optim.minimum(Sol))

printblue("\nParameter estimates:\n")

xx = [[µ_trad, \sigma^2_trad] parHat]
printmat(xx;colNames=["traditional","MLE"],rowNames=["µ","\sigma^2"],width=13)
```

log-likelihood at point estimate (compare with the value above): -11088.409

Parameter estimates:

```
\begin{array}{cccc} & \text{traditional} & \text{MLE} \\ \mu & \text{0.042} & \text{0.042} \\ \sigma^2 & \text{0.840} & \text{0.840} \end{array}
```

Standard Errors I: Information Matrix

If the likelihood function is correctly specified, then MLE is typically asymptotically normally distributed as

$$\sqrt{T}(\hat{\theta} - \theta) \rightarrow^d N(0, V)$$
, where $V = I(\theta)^{-1}$ with $I(\theta) = -E \frac{\partial^2 \ln L_t}{\partial \theta \partial \theta'}$

where $I(\theta)$ is the information matrix (*not* an identity matrix) and $\ln L_t$ is the contribution of period t to the log likelihood function.

A Remark on the Code

The code below calculates numerical derivatives. It does so by noticing that $E \frac{\partial^2 \ln L_t}{\partial \theta \partial \theta'} = \frac{\partial^2 E \ln L_t}{\partial \theta \partial \theta'}$, so we can differentiate the mean (across data points) log likelihood value. (Clearly, we could equally well calculate T different 2×2 matrices and then average.)

• hessian(par→mean(NormalLL(par,x)),parHat) calculates the 2nd derivatives of the average log-likelihood function.

```
Ia = -hessian(par→mean(NormalLL(par,x)),parHat) #(-1) * 2nd derivatives of mean(LLt)

Ia = (Ia+Ia')/2 #to guarantee symmetry, fixes possible rounding errors
vcv = inv(Ia)/T #variance-covariance matrix of estimates (not sqrt(T)*estimates)
std_hess = sqrt.(diag(vcv))

printblue("standard errors:\n")
xx = [std_trad std_hess]
printmat(xx;colNames=["traditional","MLE (InfoMat)"],rowNames=["μ","σ²"],width=18)
```

standard errors:

	traditional	MLE (InfoMat)
μ	0.010	0.010
σ^2	0.013	0.013

Standard Errors II: Gradients and Sandwich

An alternative way of calculating the information matrix is to use the outer product of the gradients:

$$J(\theta) = \mathrm{E}\left[\frac{\partial \ln L_t}{\partial \theta} \frac{\partial \ln L_t}{\partial \theta'}\right]$$

This would coincide with $I(\theta)$ as defined above, in a very large sample and if the model is correctly specified.

A Remark on the Code

The code below fills row t of a $T \times 2$ matrix (called δL) with $\frac{\partial \ln L_t}{\partial \theta}$. For each t, the outer product is a 2×2 matrix, and then we average across t. This is done by calculating $J = \delta L' \delta L/T$. A loop would also work well.

Std from the Gradients

```
δL = jacobian(par→NormalLL(par,x),parHat) #Tx2
J = δL'δL/T #2xT * Tx2

vcv = inv(J)/T
std_grad = sqrt.(diag(vcv)) #std from gradients

printblue("standard errors:\n")
xx = [std_trad std_hess std_grad]
printmat(xx;colNames=["traditional","MLE (InfoMat)","MLE (gradients)"],rowNames=["μ","σ²"],width=18
```

standard errors:

```
traditional MLE (InfoMat) MLE (gradients)  \mu \qquad 0.010 \qquad 0.010 \qquad 0.010 \\ \sigma^2 \qquad 0.013 \qquad 0.013 \qquad 0.005
```

Std from the Sandwich Estimator

We could also use the "sandwich" estimator

$$V = I(\theta)^{-1}J(\theta)I(\theta)^{-1}.$$

When the model (likelihood function) is misspecified, then the three variance-covariance matrices may differ, and the sandwich approach is often the most robust.

```
vcv = inv(Ia) * J * inv(Ia)/T
std_sandw = sqrt.(diag(vcv)) #std from sandwich

printblue("standard errors:\n")
xx = [std_trad std_hess std_grad std_sandw]
printmat(xx,colNames=["traditional","MLE (InfoMat)","MLE (gradients)","MLE (sandwich)"],rowNames=["traditional","muse (sandwich)"]
```

standard errors:

	traditional	MLE (InfoMat)	MLE (gradients)	MLE (sandwich)
μ	0.010	0.010	0.010	0.010
σ^2	0.013	0.013	0.005	0.036

Try this: replace the data series x with simulated data from a N() distribution. Then, do the different standard errors get closer to each other?

A Function for MLE (extra)

The next cell uses a function which combines the computations of several of the cells above.

It requires a function for the log-likehood function as written above, that is, taking (par,x) as inputs and generating a T-vector LLt as output.

```
@doc2 MLE
```

```
MLE(LLtFun,par0,y,x,lower,upper)
```

Calculate ML point estimates of K parameters and three different types of standard errors: from the Information matrix, from the gradients and the sandwich approach.

Input

- LLtFun::Function: name of log-likelihood function
- par0:: Vector: K-vector, starting guess of the parameters
- y:: VecOrMat: vector or matrix with the dependent variable
- x:: VecOrMat: vector or matrix with data, use nothing if not needed
- lower :: Vector: lower bounds on the parameters, nothing or fill(-Inf,K) if no bounds
- upper :: Vector: upper bounds on the parameters, nothing or fill(Inf,K) if no bounds

Requires

• using FiniteDiff: finite_difference_hessian as hessian, finite_difference_jacobian as jacobian

Notice

The LLtFun should take (par,y,x) as inputs and generate a T-vector LLt as output.

```
#using CodeTracking
#println(@code_string MLE(NormalLL,[1],[1],[1]))  #print the source code
```

```
LLtFun(par,y,x) = NormalLL(par,y)
  (parHat,std_hess,std_grad,std_sandw,LL_t) = MLE(LLtFun,par0,x,nothing)

printblue("point estimates and standard errors:\n")

xx = [parHat std_hess std_grad std_sandw]
printmat(xx;colNames=["estimate","std (InfoMat)","std (gradients)","std (sandwich)"],rowNames=["µ",
```

point estimates and standard errors:

Volatility Models: GARCH

This notebook estimates different GARCH models.

As an alternative, consider the ARCHModels.jl package.

Load Packages and Extra Functions

This notebook uses likelihood functions from the FinEcmt_TimeSeries module and then calls on the MLE() function from the FinEcmt_MLEGMM module. You may want to look at the MLE notebook before the current one.

```
MyModulePath = joinpath(pwd(),"src")
!in(MyModulePath,LOAD_PATH) && push!(LOAD_PATH,MyModulePath)
using FinEcmt_OLS, FinEcmt_TimeSeries
using FinEcmt_MLEGMM: MLE
```

```
#=
include(joinpath(pwd(),"src","FinEcmt_OLS.jl"))
include(joinpath(pwd(),"src","FinEcmt_TimeSeries.jl"))
include(joinpath(pwd(),"src","FinEcmt_MLEGMM.jl"))
using .FinEcmt_OLS, .FinEcmt_TimeSeries
using .FinEcmt_MLEGMM: MLE
=#
```

```
using Dates, DelimitedFiles, Statistics, LinearAlgebra
```

```
using Plots
default(size = (480,320),fmt = :png)
```

Loading Data

```
xx = readdlm("Data/FFdSizePs.csv",',',skipstart=1)
ymd = round.(Int,xx[:,1])  #YearMonthDay, like 20121231
R = xx[:,2]  #returns for the smallest size portfolio
xx = nothing

y = R[2:end]  #dependent variable, y(t)
x = [ones(size(y)) R[1:end-1]]  #regressors, [1, y(t-1)]

dN = Date.(string.(ymd),"yyyymmdd");  #to Julia dates
```

AR(1) + GARCH(1,1) Model

The next cells estimate an AR(1) where the residuals follow a different GARCH models. The results are used to calculate a time-varying (daily) value at risk and time-varying correlations.

The Likelihood Function

Consider a regression equation, where the residual follows a GARCH(1,1) process

$$y_t = x_t'b + u_t$$
 with $u_t = v_t\sigma_t$ and $\sigma_t^2 = \omega + \alpha u_{t-1}^2 + \beta \sigma_{t-1}^2$.

Notice that we require (ω, α, β) to all be positive and $\alpha + \beta < 1$.

If $v_t \sim N(0, 1)$, then the likelihood function is $\sum_{t=1}^{T} \ln L_t$ where

$$\ln L_t = \ln \phi(u_t/\sigma_t) - \ln \sigma_t.$$

The likelihood function of a GARCH(1,1) model is in garch11LL.

A Remark on the Code

- For simplicity, the σ_t^2 is calculated in a loop. As an alternative, consider the filt() function from the DSP.jl package.
- the code is in src/Garch.jl. The next cell prints the loglikelihood function.

```
@doc2 garch11LL
```

```
garch11LL(par,y,x)
```

Calculate (LL_t, σ^2 ,yhat,u) for regression y = x'b + u where u follows a GARCH(1,1) process with paramaters (ω,α,β).

Input

```
par::Vector: parameters, [b;ω;α;β]
y::VecOrMat: Tx1, dependent variable
x::VecOrMat: Txk, regressors
```

```
#using CodeTracking
#println(@code_string garch11LL([1],[1] [1]))  #print the source code
```

Try the GARCH(1,1) Likelihood Function

...just to see that it delivers something.

```
par0 = [mean(y),0,var(y)*0.05,0.05,0.90] #initial guess of b0,b1,\omega,\alpha,beta (LLt,) = garch11LL(par0,y,x) #trying the log lik printlnPs("Value of log-likelihood fn at starting guess of the parameters: ",sum(LLt))
```

Value of log-likelihood fn at starting guess of the parameters: -9231.913

Maximize the GARCH(1,1) Likelihood Function

by using the MLE() function from the FinEcmt_MLEGMM module. It wants at least four inputs: (LLfunction, startingGuess, y, x), but can also accept lower and upper bounds on the estimated parameters.

```
lower = [-Inf, -0.99, 0, 0, 0] #upper and lower bounds on the parameters: b0,b1,\omega,\alpha,beta upper = [Inf, 0.99, 10, 1, 1] #to get a function with just one output as MLE want (parHat,std_hess,std_grad,std_sandw,) = MLE(garch11LL_,par0,y,x,lower,upper) printblue("point estimates and standard errors:\n") coefNames = ["b_0","b_1","\omega","\alpha","\beta"]
```

```
xx = [parHat std_hess std_grad std_sandw]
printmat(xx;colNames=["estimate","std (InfoMat)","std (gradients)","std (sandwich)"],rowNames=coefN
```

point estimates and standard errors:

	estimate	std (InfoMat)	std (gradients)	std (sandwich)
b ₀	0.049	0.006	0.006	0.007
b ₁	0.256	0.012	0.012	0.013
ω	0.014	0.001	0.001	0.003
α	0.162	0.009	0.005	0.020
β	0.824	0.009	0.005	0.019

Value at Risk from GARCH(1,1)

calculated by assuming conditional (time-varying) normality,

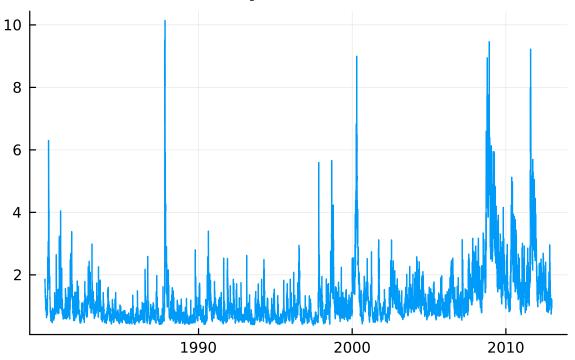
$$VaR = -(\mu_t - 1.645\sigma_t),$$

where μ_t are the predictions from the estimated mean equation $(x_t'b)$ and σ_t from the GARCH(1,1) model.

The fitted values of μ_t and σ_t are calculated by calling garch11LL(parHat,y,x), that is, using the point estimates and the data in the likelihood function. The outputs are (LL_t, σ^2 ,yhat,u,v), so we need the 2nd and 3rd.

```
 (\sigma^2,\mu) = \text{garch11LL}(\text{parHat},y,x)[2:3] \qquad \text{#get the fitted values of the } \sigma^2 - \text{ and } \mu\text{-vectors}   \text{VaR95} = -(\mu - 1.645*\text{sqrt}.(\sigma^2))   \text{xTicksLoc} = [\text{Date}(1990), \text{Date}(2000), \text{Date}(2010)]   \text{xTicksLab} = \text{Dates.format.}(\text{xTicksLoc},\text{"Y"})   \text{p1} = \text{plot}(\text{ dN}[2:\text{end}], \text{VaR95},   \text{xticks} = (\text{xTicksLoc},\text{xTicksLab}),   \text{legend} = \text{false},   \text{title} = \text{"1-day VaR (95\%)"} )   \text{display(p1)}
```

1-day VaR (95%)



Coverage ratio for VaR(95%): 0.058

eGARCH(1,1)

This section estimates an eGARCH model.

The structure of the likelihood function egarch11LL() is similar to garch11LL() used before.

```
# @doc2 egarch11LL

#using CodeTracking
#println(@code_string egarch11LL([1],[1],[1])) #print the source code
```

Estimate an eGARCH(1,1) model

b₁

ω

α

β

0.266

-0.231

0.272

0.969

-0.062

0.010

0.024

0.027

0.006

0.013

```
par0 = [mean(y), 0, var(y)*0.05, 0.05, 0.90, 0]
                                                 #initial parameter guess: b0, b1, \omega, \alpha, \beta, \gamma
lower = [-Inf,-0.99,-Inf,-Inf,0,-Inf]
                                                 #upper and lower bounds on the parameters
upper = [ Inf, 0.99, Inf, Inf,1, Inf]
egarch11LL_(par,y,x) = egarch11LL(par,y,x)[1]
                                                               #to get a function with just one output
(parHat,std_hess,std_grad,std_sandw,) = MLE(egarch11LL_,par0,y,x,lower,upper)
printblue("eGARCH(1,1), parameter estimates\n")
coefNames = ["b_0","b_1","\omega","\alpha","\beta","\gamma"]
printmat(parHat,std_sandw;colNames=["coef","std (sandw)"],rowNames=coefNames)
eGARCH(1,1), parameter estimates
        coefstd (sandw)
bΘ
                  0.004
       0.043
```

Volatility Models: DCC

This notebook estimates a multivariate GARCH model. We first apply an EWMA approach, then MLE.

As an alternative, consider the ARCHModels.jl package.

Load Packages and Extra Functions

This notebook uses likelihood functions from the (local) FinEcmt_TimeSeries module and then calls on the MLE() function from the (local) FinEcmt_MLEGMM module.

```
MyModulePath = joinpath(pwd(),"src")
!in(MyModulePath,LOAD_PATH) && push!(LOAD_PATH,MyModulePath)
using FinEcmt_OLS, FinEcmt_TimeSeries
using FinEcmt_MLEGMM: MLE
```

```
#=
include(joinpath(pwd(),"src","FinEcmt_OLS.jl"))
include(joinpath(pwd(),"src","FinEcmt_TimeSeries.jl"))
include(joinpath(pwd(),"src","FinEcmt_MLEGMM.jl"))
using .FinEcmt_OLS, .FinEcmt_TimeSeries
using .FinEcmt_MLEGMM: MLE
=#
```

```
using Dates, DelimitedFiles, Statistics, LinearAlgebra
```

```
using Plots
default(size = (480,320),fmt = :png)
```

Load Data

for two return series (called R9 and R10).

```
xx = readdlm("Data/FFdSizePs.csv",',','skipstart=1)
ymd = round.(Int,xx[:,1])  #YearMonthDay, like 20121231
R = xx[:,2:end]  #returns for 10 different size portfolios
xx = nothing

R9 = R[2:end,9]  #returns, 2nd largest firms
x9 = [ones(size(R9)) R[1:end-1,9]]  #regressors, [1, R9(t-1)]

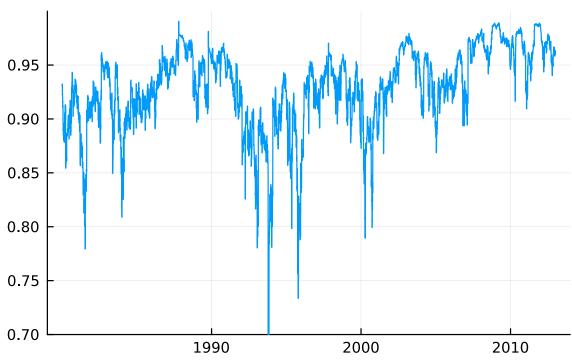
R10 = R[2:end,10]  #returns, largest firms
x10 = [ones(size(R10)) R[1:end-1,10]]  #regressors, [1, R10(t-1)]

dN = Date.(string.(ymd),"yyyymmdd");  #to Julia dates
```

EWMA-DCC

We first apply the DCC approach by using an EWMA approach.





DCC: Estimate Univariate eGARCH(1,1) Models

for each of the two return series. Also, calculate the standardized residuals as $v_t = u_t/\sigma_t$.

The estimation is done by the MLE() function from the FinEcmt_MLEGMM module. It wants at least four inputs: (LLfunction, startingGuess, y, x), but can also accept lower and upper bounds on the estimated parameters.

```
(v,\sigma^2) = (fill(NaN,T,n),fill(NaN,T,n)) #to fill with results, stand. residuals, variances
parHat = fill(NaN,K+4,n)
                                  #estimated parameters
for i in 1:n
                          #loop over estimations of y[:,i]
    local y_i,x_i
    (y_i, x_i) = (y[:,i], x[:,:,i])
    parHat_i, = MLE(egarch11LL_,par0,y_i,x_i,lower,upper)
                                                                #estimate
    (-,\sigma^2[:,i],-,-,v[:,i]) = egarch11LL(parHat_i,y_i,x_i)
                                                                #fitted values
    parHat[:,i] = parHat_i
end
printblue("eGARCH(1,1), parameter estimates:\n")
coefNames = ["b_0","b_1","\omega","\alpha","\beta","\gamma"]
printmat(parHat;colNames=["asset 1","asset 2"],rowNames=coefNames)
```

eGARCH(1,1), parameter estimates:

```
asset 1
                asset 2
       0.042
                  0.041
bο
       0.100
                  0.001
b<sub>1</sub>
      -0.116
                -0.100
ω
       0.147
                  0.130
α.
                  0.982
       0.980
      -0.088
                 -0.085
```

DCC: Estimation

This section estimates a DCC model by ML from the two series of standardized residuals (from the eGARCH estimation above).

The cells below use the MLE() function to estimate the DCC. However, the structure of the DCC model is a bit different from the main use case for MLE(). In particular, notice

- 1. To impose the necessary restrictions (α, β) being positive and summing to less than 1), we estimate (a,b) but they imply the following (α,β) via the DccParTrans() function: $\alpha = e^a/(1+e^a+e^b)$ and $\beta = e^b/(1+e^a+e^b)$.
- 2. We use the DcclL_() function for the loglikelihood. It's the same as the DcclL() function, except that it only outputs the loglikelihood contributions.
- 3. We call as MLE(DccLL_,par0,data,nothing), where par0 are starting guesses for (a,b) and data is a vector of arrays, where v = data[1], $\sigma^2 = data[2]$, Qbar = data[3]. The last argument is redundant (there are no "regressors" in this case).

```
#Initial guess of
par0 = [0.2, 1.5]
\#(\alpha,\beta) = DccParTrans(par0)
                                      #we estimate (a,b), but they imply (\alpha,\beta)
#println("Initial guess of parameters")
\#printmat([\alpha,\beta];colNames=["coef"],rowNames=["\alpha","\beta"])
Qbar = cov(v)
                                     #unconditional covariance matrix of v
data = [v, \sigma^2, Qbar]
                                     #vector of arrays, unpacked inside DccLL
                                                    #LL function, just one output
Dccll_(par,y,x) = Dccll(par,y,x)[1]
parHat, = MLE(DccLL_,par0,data,nothing)
                                                                    \#(a,b) \rightarrow (\alpha,beta)
(\alpha, \beta) = DccParTrans(parHat)
println("Estimated parameters")
printmat(parHat,[\alpha,\beta];colNames=["(a,b)","(\alpha,\beta)"],rowNames=["(a) \alpha","(b) \beta"])
```

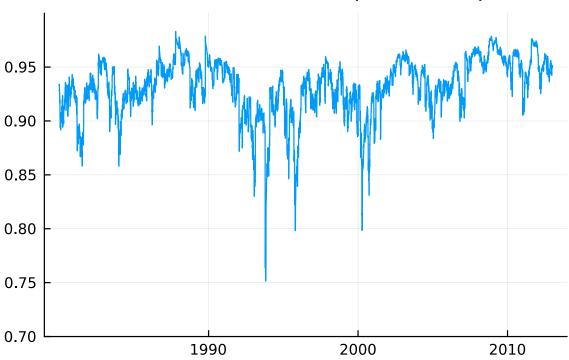
```
Estimated parameters
```

```
(a,b) (\alpha,\beta)
(a) \alpha 0.954 0.024
(b) \beta 4.669 0.967
```

DCC: Calculate the Fitted Variance-Covariance and Correlation Matrices

The next cell calculates the fitted variance-covariance matrices (nxnxT) by using the point estimates and data in the likelihood function, exported as the 2nd output. It then converts the results to the implied correlation, which we plot.

Fitted correlation (DCC/MLE)



Nonparametric Regressions

This notebook uses non-parametric methods to estimate regressions.

Load Packages and Extra Functions

The key functions used in this notebook are in the (local) FinEcmt_KernelRegression module.

```
MyModulePath = joinpath(pwd(),"src")
!in(MyModulePath,LOAD_PATH) && push!(LOAD_PATH,MyModulePath)
using FinEcmt_OLS, FinEcmt_KernelRegression
```

```
#=
include(joinpath(pwd(),"src","FinEcmt_OLS.jl"))
include(joinpath(pwd(),"src","FinEcmt_KernelRegression.jl"))
using .FinEcmt_OLS, .FinEcmt_KernelRegression
=#
```

```
using DelimitedFiles, Statistics
```

```
using Plots
default(size = (480,320),fmt = :png)
```

Loading Data

The data consists of daily returns on U.S. large caps.

```
xx = readdlm("Data/FFdSizePs.csv",',',skipstart=1)
R = xx[:,11]  #returns for the portfolio we want to study
xx = nothing

y = R[2:end]  #dependent variable
x = R[1:end-1]  #regressor, AR(1)
T = size(x,1)

println("Sample size: $T")
```

Sample size: 8324

Kernel Regression

is a regression of the sort $y_t = b(x_t) + \epsilon_t$ where regression function b() is estimated by using data in the neighbourhood of a grid point x

$$\hat{b}(x) = \frac{\sum_{t=1}^{T} w(x_t - x) y_t}{\sum_{t=1}^{T} w(x_t - x)},$$

where $w(x_t - x)$ is the weight of observation t, defined by a kernel function. This can be implemented as a regression of $\sqrt{w_t}y_t$ on $\sqrt{w_t}1$, which also gives a valid standard error of the estimates. (The function below uses White's method.)

The function KernelRegression() uses one of several available kernels, defaulting to the Gaussian kernel. The function requires the user to input a bandwidth parameter h, which controls how quick $w(x_t - x)$ tapers off as a x_t deviates from x.

As an alternative to this code, consider the NonparametricRegression.jl package.

In the application below, we are estimating a non-parametric AR(1) for returns.

```
@doc2 KernelRegression
```

```
KernelRegression(y,x,xGrid,h,vv = :all,DoCovb=true,KernelFun=GaussianKernel)
```

Do kernel regression y[vv] = b(x[vv]), evaluated at each point in the xGrid vector, using bandwidth h. Implemented as weighted least squares (WLS), which also provide heteroskedasticity robust standard errors.

Input

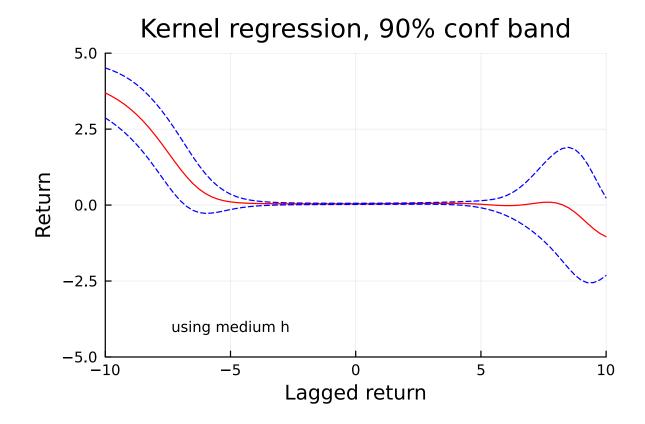
- y:: Vector: T-vector with data for the dependent variable
- x:: Vector: T-vector with data for the regressor
- xGrid:: Vector: Ngrid-vector with grid points where the estimates are done
- vv::Symbol or Vector: If vv = :all, then all data points are used, otherwise supply indices.
- DoCovb::Bool: If true, the standard error of the estimate is also calculated
- KernelFun::Function: Function used as kernel.

Remark

• The vv and DoCovb=false options are useful for speeding up the cross-validation below.

```
#println(@code_string KernelRegression([1],[1],[1],1))
```

AR(1), kernel regression | low h medium h | ---- high h | | |---- high h



Rule of Thumb Choice of h

for the non-parametric regression.

Run the regression

$$y = \alpha + \beta x + \gamma x^2 + \varepsilon$$

and use the following rule-of-thumb choice

$$h = T^{-1/5} |\gamma|^{-2/5} \sigma_{\varepsilon}^{2/5} (x_{\rm max} - x_{\rm min})^{1/5} \times 0.6.$$

In practice, replace $x_{\text{max}} - x_{\text{min}}$ by the difference between the 90th and 10th percentiles of x.

This is implemented in the hRuleOfThumb() function (included above).

Rule-of-thumb value of h: 0.667

Cross-Validation (extra)

to choose the bandwidth h for the kernel regression.

To do a cross-validation (leave-one-out)

- (1) Pick a bandwidth h, do the kernel regression but leave out observation t and then record the out-of-sample prediction error $y_t \hat{b}_{-t}(x_t, h)$. Notice that this is the error for observation t only.
- (2) Repeat for all t = 1 T to calculate the EPE

$$\mathrm{EPE}(h) = \sum_{t=1}^{T} [y_t - \hat{b}_{-t}(x_t, h)]^2 / T,$$

(3) Finally, redo for several different values of h, and pick the h value that minimizes EPE(h).

A Remark on the Code

Notice: Cross-validation calculations *take some time*. To save some computations the standard errors (which are not needed) are not calculated.

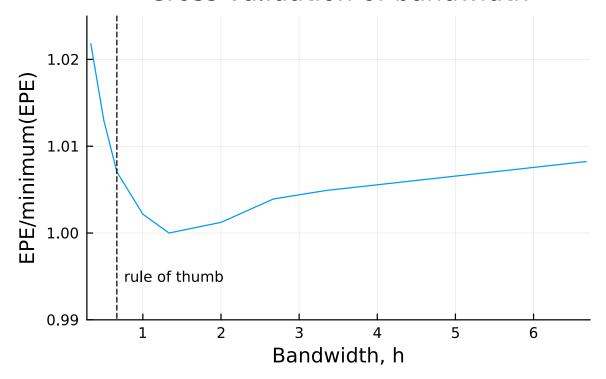
```
hM = h_crude*[0.5,0.75,1,1.5,2,3,4,5,10] #candiate h values
Nh = length(hM)
EPEM = fill(NaN,T,Nh)
for t in 1:T
   local v_No_t
    v_No_t = setdiff(1:T,t) #exclude t from estimation
    for (j,h) in enumerate(hM)
                                            #loop over hM[j] values
       local b_t
       b_t, = KernelRegression(y,x,x[t],h,v_No_t,false) #calculate fitted b(x[t])
        EPEM[t,j] = (y[t] - b_t[1])^2 #out-of-sample error for obs t
    end
end
EPE = mean(EPEM,dims=1)'
printblue("Cross-validation of bandwidth (h):\n")
printmat(hM,EPE,colNames=["h","EPE"])
```

Cross-validation of bandwidth (h):

```
h EPE 0.334 1.314
```

```
0.501
          1.302
0.667
          1.295
1.001
          1.288
1.335
          1.286
2.002
          1.287
2.670
          1.291
3.337
          1.292
6.674
          1.296
```

Cross validation of bandwidth



Local Linear Regression

estimates

```
y_t = a + b(x_t - x) + \epsilon_t
```

for a grid of x values. This can also be implemented as weighted least squares (which gives both point estimates and valid standard errors). This is implemented in the LocalLinearRegression() function.

```
@doc2 LocalLinearRegression
```

```
LocalLinearRegression(y,x,xGrid,h,vv = :all,DoCovb=true,KernelFun=GaussianKernel)
```

Do local linear regression y = a + b(x-xGrid[i]), where both a and b will differ across xGrid[i] values. The estimates of a and their standard errors are exported.

See KernRegrFn() for further comments

```
#println(@code_string LocalLinearRegression([1],[1],[1],1))
```

```
xGrid = -10:0.25:10
                                               \#x values to estimate b(x) at
      = 1.5
(aHat,StdaHat) = LocalLinearRegression(y,x,xGrid,h);
                                                                   #baseline choice of h
p1 = plot( xGrid,[aHat (aHat-1.645*StdaHat) aHat+1.645*StdaHat],
           linecolor = [:red :blue :blue],
           linestyle = [:solid :dash :dash],
           label = "",
           title = "Local linear regression, 90% conf band",
           xlabel = "Lagged return",
           ylabel = "Return",
           xlim = extrema(xGrid),
           ylim = (-5,5),
           annotation = (-5, -4, \text{text}("using medium h", 8)))
display(p1)
```

Local linear regression, 90% conf band 2.5 0.0 -2.5

Lagged return

5

10

using medium h

-5.0 L

Quantile Regressions

This notebook illustrates quantile regressions.

As an alternative, consider the QuantileRegressions.jl package.

Load Packages and Extra Functions

The key function used in this notebook QuantRegrIRLS() is from the (local) FinEcmt_OLS module.

```
MyModulePath = joinpath(pwd(),"src")
!in(MyModulePath,LOAD_PATH) && push!(LOAD_PATH,MyModulePath)
using FinEcmt_OLS
```

```
#=
include(joinpath(pwd(),"src","FinEcmt_OLS.jl"))
using .FinEcmt_OLS
=#
```

```
using DelimitedFiles, Statistics
```

```
using Plots
default(size = (480,320),fmt = :png)
```

Loading Data

```
xx = readdlm("Data/FFdFactors.csv",',',skipstart=1)
xx = xx[:,2] #equity market excess returns

y = xx[2:end] #dependent variable
x = xx[1:end-1] #regressor in an AR(1)
```

```
T = size(y,1)
println("Sample size: $T")
```

Sample size: 15355

A Function for Quantile Regressions

The QuantRegrIRLS() function from the FinEcmt_OLS estimates a quantile regression. It uses a simple iterative (re-)weighted least squares (IRLS) approach. It can be shown that a linear programming approach gives almost identical results for this data set. However, it seems that the iterative approach is quicker in really large data sets. The function returns several different calculations of the standard errors: see the code below and the lecture notes for details.

The subsequent cells calculate and show the results. The calculations take some time.

A Remark on the Code

• The arrays in the iteration are pre-allocated and then the new results overwrite the old ones, in an attempt to decrease the memory usage.

```
@doc2 QuantRegrIRLS
```

```
QuantRegrIRLS(y,x,q=0.5;prec=1e-8,epsu=1e-6,maxiter=1000)
```

Estimate a quantile regression for quantile q. The outputs are the point estimates and three different variance-covariance matrices of the estimates.

Input

- y:: Vector: T vector, dependent variable
- x:: VecOrMat: TXK, regressors (including any constant)
- q:: Number: quantile to estimate at, 0<q<1
- prec::Float64: convergence criterion, 1e-8
- epsu::Float64: lower bound on 1/weight, 1e-6
- maxiter :: Int: maximum number of iterations, 1000

Output

```
• theta:: Vector: K vector, estimated coefficients
```

- vcv:: Matrix: KxK, traditional covariance matrix
- vcv2::Matrix: KxK, Powell (1991) covariance matrix
- vcv3::Matrix: KxK, Powell (1991) covariance matrix, uniform

Remarks

- 1. while maximum(abs,b b_old) > prec ...end creates a loop that continues as long as the new and previous estimates differ more than prec. However, once the number of iterations exceed maxiter then the execution is stopped.
- 2. u = max.(u,epsu) limits how small u can become which makes the algorithm more stable (recall: the next command is x./u).

```
#using CodeTracking
#println(@code_string QuantRegrIRLS([1],[1],0.05))
```

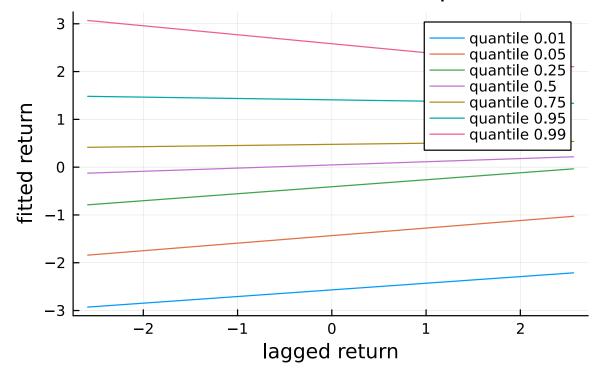
```
xGrid = quantile(x, 0.01:0.01:0.99)
                                                    #quantiles of the regressor, for plots
xGrid = [ones(size(xGrid)) xGrid]
qM = [0.01, 0.05, 0.25, 0.5, 0.75, 0.95, 0.99]
                                                    #quantiles
cx = [ones(T) x]
                                                    #[constant regressors]
     = fill(NaN,length(qM),2)
                                                    #to store regression coeffs
qPred = fill(NaN,length(qM),size(xGrid,1))
                                                    #to store predicted values
for (i,q) in enumerate(qM)
    #local b_q
               = QuantRegrIRLS(y,cx,q)[1]
    bM[i,:]
               = b_q
    qPred[i,:] = xGrid*b_q
end
printblue("quantile regression coefs:\n")
printmat(bM;colNames=["c","slope"],rowNames=string.(qM),cell00="quantile")
printred("\nThe function QuantRegrIRLS also outputs different variance-covariance matrices. Compare
```

quantile regression coefs:

```
quantile
                        slope
                  С
0.01
             -2.568
                        0.139
0.05
             -1.433
                        0.158
0.25
             -0.410
                        0.146
0.5
              0.047
                        0.067
0.75
              0.477
                        0.024
0.95
              1.409
                        -0.028
0.99
              2.582
                       -0.188
```

The function QuantRegrIRLS also outputs different variance-covariance matrices. Compare them.

Fitted values for various quantiles



Binary Choice and Censored Models

This notebook uses MLE to estimate Probit, truncated and censored models.

Load Packages and Extra Functions

The key functions used for OLS and IV/2SLS are from the (local) FinEcmt_OLS module.

```
MyModulePath = joinpath(pwd(),"src")
!in(MyModulePath,LOAD_PATH) && push!(LOAD_PATH,MyModulePath)
using FinEcmt_OLS, FinEcmt_ProbitTobit
using FinEcmt_MLEGMM: MLE
```

```
#=
include(joinpath(pwd(),"src","FinEcmt_OLS.jl"))
using .FinEcmt_OLS, .FinEcmt_ProbitTobit
using .FinEcmt_MLEGMM: MLE
=#
```

```
using DelimitedFiles, Statistics
```

Probit

and linear probaility models for binary data (typically, 0 or 1).

Loading Data

Estimate

OLS estimates

```
b_ols, = OlsGM(auto,x)
printmat("OLS estimates")
printmat(b_ols;rowNames=xNames)

LLtFun_p(par,y,x) = ProbitLL(par,y,x)[1]
(b_prob,_,_,std_sandw,LL1) = MLE(LLtFun_p,b_ols,auto,x)
t_prob = b_prob./std_sandw

(LL0,pHat) = BinLLConst(auto.>0.5)
R2 = 1 - sum(LL1)/LL0
predHat = ProbitLL(b_prob,auto,x)[2] .> 0.5

(R2_pred,cTab) = BinaryChoiceR2pred(auto.>0.5,predHat)

printlnPs("\nProbit parameter estimates, t-stat: ")
printmat([b_prob t_prob])
printlnPs("\nMcFadden's R2 ",R2,"\nR2_pred ",R2_pred)
```

```
c     0.485
dtime     0.007

Probit parameter estimates, t-stat:
     -0.064     -0.162
     0.030      3.109
```

```
McFadden's R2 0.576
R2_pred 0.800
```

Truncated Model

for the case where data (y, x) is unavailable when y < c, where c is some (known) threshold.

Loading the Data

The next cells replicates an old example from Hill et al (2008), Table 16.8. See the lecture notes for more details.

A remark on the code

The data set contains many different variables. To import them with their correct names, we create a named tuple of them by using the function PutDataInNT() from the FinEcmt_OLS module. (This is convenient, but not important for the focus of this notebook. An alternative is to use the DataFrames.jl package.)

```
The variables in X (use as, for instance, X.wage): (:taxableinc, :federaltax, :hsiblings, :hfathereduc, :hmothereduc, :siblings, :lfp, :hours, :kidsl6, :
```

```
vv = y .> 0
b_ols,res, = OlsGM(y[vv],x[vv,:])

par0 = par0 = [b_ols;std(res)]
LLtFun_t(par,y,x) = TruncRegrLL(par,y,x)[1]  #truncated
(b_trunc,_,_,std_sandw,_) = MLE(LLtFun_t,par0,y[vv],x[vv,:])
t_trunc = b_trunc./std_sandw
printlnPs("Truncated MLE: ")
printmat([b_ols b_trunc[1:end-1] t_trunc[1:end-1]];colNames=["OLS","MLE","t-stat (MLE)"])

Truncated MLE:
    OLS     MLEt-stat (MLE)
```

Censored Model

1829.746 1920.045

-16.462 -22.716

-17.108 -25.245 -305.309 -491.158

33.936 46.748

4.534

-1.062

6.050 -3.015

-2.225

Similar to the truncated case, except that the data (y, x) = (c, x) when y < c. This means that we have more information than in the truncated case.

Applied to the same model as for the truncated case. Again, see THill et al (2008), Table 16.8 and the lecture notes for more details.

```
LLtFun_c(par,y,x) = CensRegrLL(par,y,x)[1] #censored
(b_cens,_,_,std_sandw,_) = MLE(LLtFun_c,par0,y,x)
t_cens = b_cens./std_sandw
printlnPs("Censored MLE: ")
printmat([b_cens t_cens];colNames=["coef","std"])
```

Censored MLE:

std	coef
3.443	1349.900
3.595	73.290
13.066	80.536
-9.123	-60.768
-8.005	-918.911
26.187	1133.693