# Predictions on how well barbell lifts are performed based on accelerometers data

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## **Synposis**

We investigate data from here. There is a training data set and a testing set. We train our models to predict the variable "classe" (present in training and absent in testing data set). As models, we use SVM, Decision trees and random forest. We also consider an ensemble of all three models.

## **Data Preparation**

First we load training and testing data from working directory and consider the structure of the training data

The training set consists of 19622 observations with 160 variables (s. Appendix, table in sub-section "Structure Table for Training Data"). We do not need all of them. Since they do not discribe a particular movement, we drop variables "X", "user-name", "raw\_timestamp\_part\_1", "raw\_timestamp\_part\_2", "cvtd\_timestamp", "new\_window" and "num\_window". We treat all other variables except of "classe" as numeric. We do the same for testing set (test has no variable "classe" but variable "problem\_id).

It is noticeable that a lot of variables in training and testing sets do not include any values (all values of a variable are NAs). We also drop those variables which are NA in testing data set (applied to both data sets). We stay with 52 predictors and 1 response variable. All predictors do not include any NAs values.

# Data spliting

Since we have a lot of observations in training data set, we can split it into actual training part (70%) and cross-testing part (30%) (seed was set to 2019)

# **Data Scaling**

Since one of the models we use is SVM, we should scale our data. We perform standard normalization using mean and standard deviation. To determine these parameters, actual training set is used. These parameters are also applied to cross-testing and testing data. For decision trees and random forest, we omit scaling.

#### Models

#### SVM

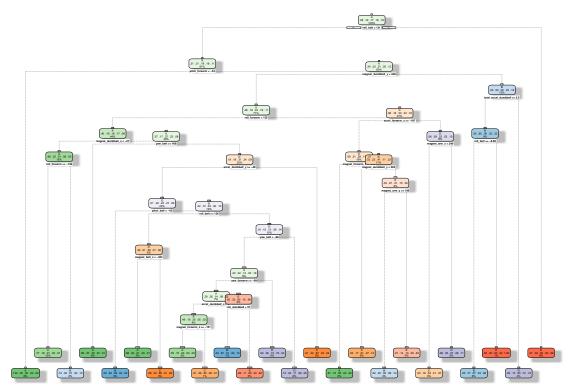
Now, we train SVM model. Note that we have already performed scaling of data befor.

## Accuracy ## 0.9564679 ## Accuracy ## 0.9456245

The accuracy of SVM model on actual training set is 95.65% and on cross-testing set 94.56%!

## **Decision Trees**

Now, we consider decision trees (default settings)



Rattle 2019-Jul-30 18:27:13 vtmw-07

```
## Accuracy
## 0.7571522
## Accuracy
## 0.7524214
```

The accuracy of decision trees model on actual training set is 75.72% and on cross-testing set 75.24%!

#### **Random Forest**

Now, we consider random forest (default settings)

```
## Accuracy
## 1
## Accuracy
## 0.995582
```

The accuracy of random forest model on actual training set is 100% and on cross-testing set 99.56%!

#### Ensemble model

Now, we consider an ensemble consisting of our previous SVM, decision tree and random forest models. We combine them using random forest since it seems to perform very weel

## Accuracy

```
## 1
## Accuracy
## 0.9954121
```

The accuracy of random forest model on actual training set is 100% and on cross-testing set 99.54%!

## Final testing

We see that SVM, random forest and our ensamble are performing amazingly well. Since random forest provides best accuracy on cross-testing set. We apply it to our final testing set which is not labeld with "classe".

```
## 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 ## B A B A A E D B A A B C B A E E A B B B ## Levels: A B C D E
```

#### Conclusion

On considered data set, random forest performs better than SVM, decision trees and even ensemble. SVM performs also very well.

## References

## **Appendix**

#### Structure Table for Training Data

```
19622 obs. of 160 variables:
## 'data.frame':
##
   $ X
                              : int
                                    1 2 3 4 5 6 7 8 9 10 ...
##
   $ user_name
                                     "carlitos" "carlitos" "carlitos" ...
                              : chr
   $ raw timestamp part 1
                                    1323084231 1323084231 1323084231 1323084232 1323084232 1323084232
                              : int
   $ raw_timestamp_part_2
                                    788290 808298 820366 120339 196328 304277 368296 440390 484323 484
                              : int
                                     "05/12/2011 11:23" "05/12/2011 11:23" "05/12/2011 11:23" "05/12/20
##
   $ cvtd_timestamp
                              : chr
##
  $ new_window
                              : chr
                                     "no" "no" "no" "no" ...
##
  $ num_window
                                    11 11 11 12 12 12 12 12 12 12 ...
                              : int.
                                     1.41 1.41 1.42 1.48 1.48 1.45 1.42 1.42 1.43 1.45 ...
##
   $ roll_belt
                              : num
##
   $ pitch belt
                                    8.07 8.07 8.07 8.05 8.07 8.06 8.09 8.13 8.16 8.17 ...
                              : num
                                    -94.4 - 94.4 - 94.4 - 94.4 - 94.4 - 94.4 - 94.4 - 94.4 - 94.4 - 94.4 \dots
##
  $ yaw_belt
                              : num
   $ total_accel_belt
                              : int
                                    3 3 3 3 3 3 3 3 3 ...
                                     ... ... ...
##
   $ kurtosis_roll_belt
                              : chr
##
                              : chr
                                     ... ...
   $ kurtosis_picth_belt
                                     ... ... ... ...
##
   $ kurtosis_yaw_belt
                              : chr
##
   $ skewness_roll_belt
                              : chr
                                     11 11 11 11
   $ skewness_roll_belt.1
                              : chr
##
  $ skewness_yaw_belt
                              : chr
  $ max_roll_belt
                                    NA NA NA NA NA NA NA NA NA ...
                              : num
                                    NA NA NA NA NA NA NA NA NA ...
##
   $ max_picth_belt
                              : int
                                     "" "" "" ...
##
   $ max_yaw_belt
                              : chr
                                    NA NA NA NA NA NA NA NA NA ...
##
   $ min_roll_belt
                              : num
  $ min_pitch_belt
                                    NA NA NA NA NA NA NA NA NA ...
                              : int
                                     ... ... ... ...
##
   $ min_yaw_belt
                              : chr
                              : num NA ...
## $ amplitude_roll_belt
## $ amplitude_pitch_belt
                                     NA NA NA NA NA NA NA NA NA ...
                              : int
                                     ...
## $ amplitude_yaw_belt
                              : chr
```

```
## $ var total accel belt
                                 NA NA NA NA NA NA NA NA NA ...
                           : num
## $ avg_roll_belt
                           : num
                                 NA NA NA NA NA NA NA NA NA ...
## $ stddev roll belt
                                 NA NA NA NA NA NA NA NA NA ...
                           : num
                                NA NA NA NA NA NA NA NA NA ...
## $ var_roll_belt
                           : num
## $ avg_pitch_belt
                           : num
                                 NA NA NA NA NA NA NA NA NA ...
## $ stddev_pitch_belt
                           : num NA NA NA NA NA NA NA NA NA ...
## $ var_pitch_belt
                                NA NA NA NA NA NA NA NA NA ...
                           : num
                                 NA NA NA NA NA NA NA NA NA ...
##
   $ avg_yaw_belt
                           : num
##
   $ stddev_yaw_belt
                           : num
                                 NA NA NA NA NA NA NA NA NA ...
## $ var_yaw_belt
                           : num
                                 NA NA NA NA NA NA NA NA NA ...
## $ gyros_belt_x
                           : num
                                 ## $ gyros_belt_y
                                 0 0 0 0 0.02 0 0 0 0 0 ...
                           : num
## $ gyros_belt_z
                           : num
                                 -0.02 -0.02 -0.02 -0.03 -0.02 -0.02 -0.02 -0.02 -0.02 0 ...
                                 -21 -22 -20 -22 -21 -21 -22 -22 -20 -21 ...
## $ accel_belt_x
                           : int
## $ accel_belt_y
                                 4 4 5 3 2 4 3 4 2 4 ...
                           : int
## $ accel_belt_z
                           : int
                                 22 22 23 21 24 21 21 21 24 22 ...
## $ magnet_belt_x
                                 -3 -7 -2 -6 -6 0 -4 -2 1 -3 ...
                           : int
## $ magnet_belt_y
                           : int
                                 599 608 600 604 600 603 599 603 602 609 ...
## $ magnet_belt_z
                                 -313 -311 -305 -310 -302 -312 -311 -313 -312 -308 ...
                           : int
## $ roll arm
                           : num
                                 ## $ pitch_arm
                           : num
                                22.5 22.5 22.5 22.1 22.1 22 21.9 21.8 21.7 21.6 ...
## $ yaw arm
                                 : num
## $ total_accel_arm
                                 34 34 34 34 34 34 34 34 34 ...
                           : int
## $ var accel arm
                                 NA NA NA NA NA NA NA NA NA ...
                           : num
## $ avg_roll_arm
                           : num NA NA NA NA NA NA NA NA NA ...
## $ stddev_roll_arm
                           : num NA NA NA NA NA NA NA NA NA ...
## $ var_roll_arm
                                NA NA NA NA NA NA NA NA NA ...
                           : num
                           : num
                                NA NA NA NA NA NA NA NA NA ...
## $ avg_pitch_arm
## $ stddev_pitch_arm
                                NA NA NA NA NA NA NA NA NA ...
                           : num
## $ var_pitch_arm
                                NA NA NA NA NA NA NA NA NA . . .
                           : num
## $ avg_yaw_arm
                           : num
                                 NA NA NA NA NA NA NA NA NA ...
## $ stddev_yaw_arm
                           : num
                                 NA NA NA NA NA NA NA NA NA ...
## $ var_yaw_arm
                                 NA NA NA NA NA NA NA NA NA ...
                           : num
## $ gyros_arm_x
                                 : num
## $ gyros_arm_y
                                 0 -0.02 -0.02 -0.03 -0.03 -0.03 -0.03 -0.02 -0.03 -0.03 ...
                           : num
## $ gyros_arm_z
                                 -0.02 -0.02 -0.02 0.02 0 0 0 0 -0.02 -0.02 ...
                          : num
## $ accel arm x
                          : int
                                 ## $ accel_arm_y
                          : int
                                 109 110 110 111 111 111 111 111 109 110 ...
## $ accel arm z
                           : int
                                 -123 -125 -126 -123 -123 -122 -125 -124 -122 -124 ...
## $ magnet_arm_x
                                 -368 -369 -368 -372 -374 -369 -373 -372 -369 -376 ...
                           : int
## $ magnet arm y
                                 337 337 344 344 337 342 336 338 341 334 ...
                           : int
## $ magnet_arm_z
                                 516 513 513 512 506 513 509 510 518 516 ...
                           : int
## $ kurtosis_roll_arm
                                 ... ... ... ...
                           : chr
## $ kurtosis_picth_arm
                                 ... ... ... ...
                           : chr
                                 ## $ kurtosis_yaw_arm
                           : chr
##
   $ skewness_roll_arm
                           : chr
                                 ... ... ... ...
##
   $ skewness_pitch_arm
                           : chr
                                 ... ... ... ...
## $ skewness_yaw_arm
                           : chr
## $ max_roll_arm
                           : num
                                NA NA NA NA NA NA NA NA NA ...
## $ max_picth_arm
                           : num
                                 NA NA NA NA NA NA NA NA NA ...
## $ max_yaw_arm
                                 NA NA NA NA NA NA NA NA NA ...
                           : int
## $ min_roll_arm
                           : num NA NA NA NA NA NA NA NA NA ...
## $ min_pitch_arm
                           : num NA NA NA NA NA NA NA NA NA ...
## $ min yaw arm
                           : int NA NA NA NA NA NA NA NA NA ...
```

```
## $ amplitude roll arm
                           : num NA NA NA NA NA NA NA NA NA ...
## $ amplitude_pitch_arm
                           : num NA NA NA NA NA NA NA NA NA ...
## $ amplitude yaw arm
                           : int NA NA NA NA NA NA NA NA NA ...
## $ roll_dumbbell
                           : num 13.1 13.1 12.9 13.4 13.4 ...
## $ pitch dumbbell
                           : num -70.5 -70.6 -70.3 -70.4 -70.4 ...
## $ yaw dumbbell
                           : num -84.9 -84.7 -85.1 -84.9 -84.9 ...
## $ kurtosis_roll_dumbbell : chr "" "" "" ...
                                 ...
## $ kurtosis_picth_dumbbell : chr
                                 ...
## $ kurtosis yaw dumbbell
                           : chr
## $ skewness_roll_dumbbell : chr
                                 ... ... ... ...
                                 ... ... ... ...
## $ skewness_pitch_dumbbell : chr
                                 ...
## $ skewness_yaw_dumbbell : chr
## $ max_roll_dumbbell
                           : num NA NA NA NA NA NA NA NA NA ...
## $ max_picth_dumbbell
                           : num NA NA NA NA NA NA NA NA NA ...
                                 ... ... ... ...
## $ max_yaw_dumbbell
                           : chr
## $ min_roll_dumbbell
                           : num NA NA NA NA NA NA NA NA NA ...
## $ min_pitch_dumbbell
                           : num NA NA NA NA NA NA NA NA NA ...
                                 ...
## $ min yaw dumbbell
                           : chr
## $ amplitude_roll_dumbbell : num NA ...
   [list output truncated]
```

#### Code

```
# Used libraries
library(ggplot2)
library(caret)
library(rpart)
library(e1071)
library(rattle)
library(randomForest)
library(mgcv)
# Load data
input_training <- read.csv("pml-training.csv", stringsAsFactors = FALSE)</pre>
input_testing <- read.csv("pml-testing.csv", stringsAsFactors = FALSE)</pre>
# Delete variables which will not be used
training <- cbind(as.data.frame(lapply(input_training[, 8:159], as.numeric)),</pre>
                   classe = input_training$classe)
testing <- cbind(as.data.frame(lapply(input_testing[, 8:159], as.numeric)),</pre>
                   problem_id = input_testing$problem_id)
# Consider only variables which are present (not NA) in testing data set
training <- training[, colSums(is.na(testing)) != nrow(testing)]</pre>
testing <- testing[, colSums(is.na(testing)) != nrow(testing)]
# Split training data into true training part and cross-testing part
set.seed(2019)
inTrain <- createDataPartition(training$classe, p = 0.7, list = FALSE)</pre>
Ttraining <- training[inTrain, ]</pre>
Ttesting <- training[-inTrain, ]</pre>
# Parameters for normalization
means <- as.data.frame(lapply(Ttraining[, 1:52], mean))</pre>
sds <- as.data.frame(lapply(Ttraining[, 1:52], sd))</pre>
Ttraining_norm <- cbind(as.data.frame(scale(Ttraining[,1:52], center = means,
                                              scale = sds)),
                         classe = Ttraining$classe)
Ttesting_norm <- cbind(as.data.frame(scale(Ttesting[,1:52], center = means,</pre>
```

```
scale = sds)),
                         classe = Ttesting$classe)
testing_norm <- cbind(as.data.frame(scale(testing[,1:52], center = means,</pre>
                                            scale = sds)),
                         problem_id = testing$problem_id)
SVM_model <- svm(classe ~ ., data = Ttraining_norm, scale = FALSE)</pre>
SVM_pred_Ttraining <- predict(SVM_model, Ttraining_norm)</pre>
acc_SVM_Ttraining <- confusionMatrix(SVM_pred_Ttraining, Ttraining_norm$classe)</pre>
SVM pred Ttesting <- predict(SVM model, Ttesting norm)</pre>
acc_SVM_Ttesting <- confusionMatrix(SVM_pred_Ttesting, Ttesting_norm$classe)
acc_SVM_Ttraining$overall[1]
acc_SVM_Ttesting$overall[1]
tree model <- rpart(classe ~ ., data = Ttraining, method = "class")
fancyRpartPlot(tree_model)
tree_pred_Ttraining <- predict(tree_model, Ttraining, type = "class")</pre>
acc_tree_Ttraining <- confusionMatrix(tree_pred_Ttraining,</pre>
                                        Ttraining$classe)
tree_pred_Ttesting <- predict(tree_model, Ttesting, type = "class")</pre>
acc_tree_Ttesting <- confusionMatrix(tree_pred_Ttesting, Ttesting$classe)</pre>
acc_tree_Ttraining$overall[1]
acc_tree_Ttesting$overall[1]
rf_model <- randomForest(classe ~ ., data = Ttraining)</pre>
rf_pred_Ttraining <- predict(rf_model, Ttraining)</pre>
acc_rf_Ttraining <- confusionMatrix(rf_pred_Ttraining,</pre>
                                        Ttraining$classe)
rf pred Ttesting <- predict(rf model, Ttesting)</pre>
acc_rf_Ttesting <- confusionMatrix(rf_pred_Ttesting, Ttesting$classe)</pre>
acc_rf_Ttraining$overall[1]
acc_rf_Ttesting$overall[1]
newdata_Ttraining = data.frame(classe = Ttraining$classe,
                                SVM = SVM_pred_Ttraining,
                                tree = tree_pred_Ttraining,
                                 rf = rf_pred_Ttraining)
ens_model <- randomForest(classe ~ ., data = newdata_Ttraining)</pre>
ens_pred_Ttraining <- predict(ens_model, newdata_Ttraining)</pre>
acc_ens_Ttraining <- confusionMatrix(ens_pred_Ttraining,</pre>
                                        newdata_Ttraining$classe)
newdata_Ttesting = data.frame(classe = Ttesting$classe,
                                SVM = SVM_pred_Ttesting,
                                tree = tree_pred_Ttesting,
                                rf = rf_pred_Ttesting)
ens_pred_Ttesting <- predict(ens_model, newdata_Ttesting)</pre>
acc_ens_Ttesting <- confusionMatrix(ens_pred_Ttesting, newdata_Ttesting$classe)
acc_ens_Ttraining$overall[1]
acc_ens_Ttesting$overall[1]
rf_pred_testing <- predict(rf_model, testing)</pre>
rf_pred_testing
# Structure of training set
str(input_training)
```