Chemistry 3P51 – Fall 2013 Quantum Chemistry

Lecture No. 15 Oct 11th, 2013

1

Objectives

- · To introduce the classical angular momentum vector.
- To state the physical significance of the angular momentum vector.
- To introduce the quantum-mechanical angular momentum vector operator.
- To present the commutation relations involving the angular momentum operator components.
- To remind the student the spherical polar coordiantes.
- To show the angular momentum operator components and square in spherical coordinates.

Angular momentum

In classical mechanics, the angular momentum of a particle is a vector quantity defined by

$$L = r \times p$$
 vector product

 $\mathbf{r} = (x, y, z)$ is the particle's position vector;

 $\mathbf{p} = (p_y, p_y, p_z)$ is the particle's linear momentum vector

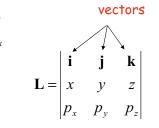
The Cartesian components of $\mathbf{L} = (L_x, L_y, L_z)$ are given by

$$L_x = yp_z - zp_y$$

$$L_y = zp_x - xp_z$$

$$L_z = xp_y - yp_x$$

Remark: One can formally write the vector \mathbf{L} as a 3×3 determinant:



Cartesian unit

3

4

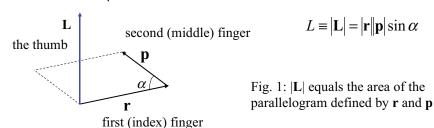
Magnitude and direction of the angular momentum

The magnitude of the L-vector is

$$L \equiv |\mathbf{L}| = \sqrt{L^2} = \sqrt{\mathbf{L} \cdot \mathbf{L}} = \sqrt{L_x^2 + L_y^2 + L_z^2}$$

 ${f L}$ is always perpendicular to the plane defined by the vectors ${f r}$ and ${f p}$. The direction of ${f L}$ is determined by the right-hand rule (see Fig. 1).

Geometric interpretation:



The angular momentum of a particle is proportional to the particle's velocity and its distance $r=|\mathbf{r}|$ from the origin.

Physical significance of the angular momentum

For an isolated particle (or a system of particles), the total angular momentum is a conserved quantity (just like the total energy) that can be used to characterize the state of the system.

The angular momentum of a particle of mass m is related to the **kinetic energy** by a simple formula, provided that the particle moves in such a manner that its distance r from the origin remain fixed:

$$T = \frac{L^2}{2mr^2} \qquad \text{provided } r = \text{const}$$

The above formula applies when the particle is in **orbital motion**, specifically, when it moves:

- (a) in a circle of radius r centered at the origin, or
- (b) on the surface of a sphere of radius r

5

Quantum-mechanical operators of angular momentum

Angular momentum is a three-component (vector) quantity represented by linear Hermitian operators.

In Cartesian coordinates, these operators are:

$$\hat{L}_{x} = y\hat{p}_{z} - z\hat{p}_{y} = -i\hbar\left(y\frac{\partial}{\partial z} - z\frac{\partial}{\partial y}\right)$$

$$\hat{L}_{y} = z\hat{p}_{x} - x\hat{p}_{z} = -i\hbar\left(z\frac{\partial}{\partial x} - x\frac{\partial}{\partial z}\right)$$

$$\hat{L}_{z} = x\hat{p}_{y} - y\hat{p}_{x} = -i\hbar\left(x\frac{\partial}{\partial y} - y\frac{\partial}{\partial x}\right)$$

$$\hat{L}^2 = \hat{L}_x^2 + \hat{L}_y^2 + \hat{L}_z^2$$

No two components of the angular momentum vector operator can be determined simultaneously

Using the definitions of the operators for the x-, y-, z-components of the angular momentum one can show that no two of them commute:

$$[\hat{L}_x, \hat{L}_y] = i\hbar \hat{L}_z \qquad [\hat{L}_y, \hat{L}_z] = i\hbar \hat{L}_x \qquad [\hat{L}_z, \hat{L}_x] = i\hbar \hat{L}_y$$

Each of the three components, however, commutes individually with the square of the total angular momentum:

$$[\hat{L}_x, \hat{L}^2] = 0,$$
 $[\hat{L}_y, \hat{L}^2] = 0,$ $[\hat{L}_z, \hat{L}^2] = 0$

This means that one can observe simultaneously definite values of the total angular momentum and **only one** of its x-, y-, z-components.

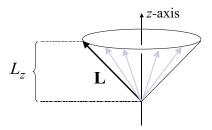
By convention, the "definite" component is always chosen to be L_z .

7

Physical interpretation of the commutation relations for the angular momentum

A particle can have simultaneously definite values of L and L_z , but then the other two components (L_x and L_y) will not have definite values.

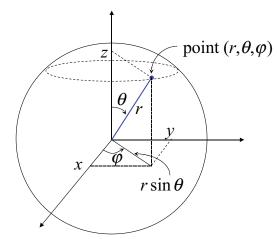
In other words, only the component L_z of the total angular momentum can be known precisely alongside with L^2 .



Note that by specifying $L = |\mathbf{L}|$ and L_z we are not specifying the vector \mathbf{L} , only its magnitude and the projection on the z-axis.

Spherical polar coordinates

Cartesian coordinates are not ideal for describing orbital motion. Spherical coordinates are better suited for this purpose.



$$x = r \sin \theta \cos \varphi$$
$$y = r \sin \theta \sin \varphi$$
$$z = r \cos \theta$$

$$r^2 = x^2 + y^2 + z^2 \qquad (1)$$

$$\cos\theta = \frac{z}{r} \tag{2}$$

$$\tan \varphi = \frac{y}{x} \tag{3}$$

$$0 \le r < \infty$$
, $0 \le \theta \le \pi$, $0 \le \varphi \le 2\pi$

Angular momentum in spherical coordinates

When expressed in spherical coordinates, the components of the angular momentum operator and its square take the following form

$$\begin{split} \hat{L}_x &= -i \, \hbar \left(-\sin \varphi \, \frac{\partial}{\partial \theta} - \frac{\cos \theta}{\sin \theta} \cos \varphi \, \frac{\partial}{\partial \varphi} \right) \\ \hat{L}_y &= -i \, \hbar \left(\cos \varphi \, \frac{\partial}{\partial \theta} - \frac{\cos \theta}{\sin \theta} \sin \varphi \, \frac{\partial}{\partial \varphi} \right) \\ \hat{L}_z &= -i \, \hbar \, \frac{\partial}{\partial \varphi} \end{split}$$

$$\hat{L}^2 = -\hbar^2 \left(\frac{\partial^2}{\partial \theta^2} + \frac{\cos \theta}{\sin \theta} \frac{\partial}{\partial \theta} + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \varphi^2} \right)$$