

Meeting Record

Ziquan Yang

September 2, 2015

Contents

1 Meeting on Sept. 2nd

1. Prof: What do \mathbb{P}^n 's look like, for small n 's?
Me: (I drew the standard planar representation of $\mathbb{R}IP^2$ that identifies the boundary of a square using antipodal maps.) \mathbb{P}^1 is topologically the same as \mathbb{S}^1 .
2. Prof: Is \mathbb{P}^2 orientable?
Me: No. Ah, here is a quick proof. If \mathbb{P}^2 is orientable, then all open submanifolds of it are, but the Mobius strip is an open submanifold of \mathbb{P}^2 .
3. Prof: How about \mathbb{P}^3 ? Is it orientable? Me: My impression is that it is not. (Then I spent a while trying to come up with a quick proof)
4. Me: So I am going to cheat and use the fact that a manifold M is orientable if and only if $w_1(M) = 0$.
5. Prof: All line bundle over paracompact spaces are isomorphic to their duals.
Me: Emm, I can check that myself later.
Prof: The space of inner products on \mathbb{R} has a canonical orientation. Well, what is the dimension of the space of inner products of \mathbb{R}^n ?
Me: They correspond to $n \times n$ matrices, so I guess it is n^2 ?
Prof: But they have to be symmetric.
Me: Right. So the answer is $n(n+1)/2$.
Prof: Then what is the dimension (of the inner product space) when $n = 1$? Me: 1.

6. Prof: We can give a natural orientation on the inner product space by choosing the positive ones, i.e. those that send (v, v) to a positive number, to be a basis. You can then use partition of unity to construct a nowhere vanishing section.
7. Prof: What are other common manifolds of dimension 3 do you know?
 Me: Not really.
 Prof: How about the space $O(n) = \{M \in \mathbb{R}^{n \times n} : M^T M = 1\}$? How many equations are used to describe the condition?
 Me: 9, but (trying to count how many equations are repeated)...
 Prof: $M^T M$ is symmetric, so...
 Me: Ah, so there are actually only 6 equations. (thinking for some seconds) The other equations are algebraically independent, since they each introduce a new variable. Therefore we cannot further reduce the number of equations.
8. Prof: Yes, but it may happen that the intersection is nasty somewhere. How do you want to show that it is smooth?
 Me: Write down the equations using coordinates and then compute the Jacobian. Show that the Jacobian has appropriate rank.
 Prof: Right, what is the theorem that you are using?
 Me: If $f : \mathbb{R}^m \rightarrow \mathbb{R}^n$ is a smooth map and $p \in \mathbb{R}^n$ is a regular value, then $f^{-1}(p)$ is a smooth submanifold of \mathbb{R}^m .
 Prof: Right, what is the name of the theorem?
 Me: Regular value theorem? Or something like that?
 Prof: It's the implicit function theorem.
9. Me: My intuition is that $O(3)$ is homogeneous, so it suffices to check one point, for which we can simply use I .
10. Prof: That seems to be a lot of computations. Could you show that the derivative is surjective directly? So how would you compute the derivative?
 Me: The derivative of $M \rightarrow M^T T$ is
- $$\lim_{\|M\| \rightarrow 0} \frac{(I + M)^T(I + M) - I}{\|M\|}$$
- Prof: For a function $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$, you should be thinking of this formula:
- $$f'(x)(v) = \lim_{t \rightarrow 0} \frac{f(x + tv) - f(x)}{t}$$
- Me: But that computes the image of one v at a time. I guess if you let v run over a basis, you can reconstruct the derivative $f'(x)$.

11. Me: So using this formula, the answer is

$$\lim_{t \rightarrow 0} \frac{(I + tM)^T(I + tM) - I}{t} = \lim_{t \rightarrow \infty} \frac{I + tM + tM^T + t^2 M^T M - I}{t} = M + M^T$$

References

- [1] J. Milnor, J. Stasheff, *Characteristic classes*, Annals of mathematics studies, Princeton university press, Number 76, 1978