

Notes on Characteristic Classes

Ziquan Yang

August 13, 2015

Contents

1	Introduction	1
2	Algebraic Topology	1
2.1	Grassmann Manifolds	1
2.1.1	Universal bundle	1
2.1.2	Cell Structure	3
3	Differential Geometry	4
4	Algebraic Geometry	4

1 Introduction

2 Algebraic Topology

2.1 Grassmann Manifolds

2.1.1 Universal bundle

We first explain the ideas in this section. Many proofs are pretty technical topological arguments and are delayed.

Given a curve $M^1 \subseteq \mathbb{R}^{k+1}$, we may define a map

$$t : M^1 \rightarrow S^k$$

that sends every point in M to a unit tangent vector. Of course, to do it consistently we need an orientation of M^1 . However, when an orientation is not available or we may disregard it, it is always possible to define a map by passing to projective space, i.e. $t : M^1 \rightarrow \mathbb{P}^k$ that sends a point to its tangent space.

Similarly, given a hypersurface $M^k \subseteq \mathbb{R}^{k+1}$, we may define a map

$$n : M^k \rightarrow \mathbb{P}^k$$

that sends a point to the orthogonal complement of its tangent space.

More generally we would like a map for $M^n \subseteq \mathbb{R}^{n+k}$, so we need to space to parametrize the n -dimensional subspaces of \mathbb{R}^{n+k} . Therefore we introduce Grassmann manifolds. The underlying set $G_n(\mathbb{R}^{n+k})$ is the n -dimensional subspaces of \mathbb{R}^{n+k} and we topologize it as follows: Let

$$V_n(\mathbb{R}^{n+k}) \subseteq \mathbb{R}^{n+k} \times \cdots \times \mathbb{R}^{n+k}$$

be the subset parametrizing the n -tuples of vectors (v_1, \dots, v_n) that are linearly independent (such tuple is called a n -frame). Clearly V_n is a Zariski open subset. Each n -tuple in V_n determines a n -dimensional subspace in \mathbb{R}^{n+k} . Therefore there is a canonical function

$$q : V_n(\mathbb{R}^{n+k}) \rightarrow G_n(\mathbb{R}^{n+k})$$

This map gives $G_n(\mathbb{R}^{n+k})$ a quotient topology. Alternatively, we could have used the set of orthonormal n -frames V_n^0 . V_n^0 is clearly compact, and hence $G_n(\mathbb{R}^{n+k})$ is compact. We will verify later that $G_n(\mathbb{R}^{n+k})$, which now is a priori only a topological space, is indeed a topological manifold.

In particular \mathbb{P}^n can now be viewed as a special case of Grassmann manifolds, and we may define a canonical vector bundle on $G_n(\mathbb{R}^{n+k})$ in a completely analogous fashion:

$$\gamma^n(\mathbb{R}^{n+k}) = \{(n\text{-plane in } \mathbb{R}^{n+k}, \text{vectors in the plane})\}$$

With Grassmann manifolds we can define generalized Gauss maps $\bar{g} : M \rightarrow G_n(\mathbb{R}^{n+k})$ by sending a point to its tangent space. However, Grassmann manifolds can absorb much more bundles. In some sense it behaves like a terminal object in a category.

Lemma 2.1. *For any n -plane bundle ξ over a compact base space B there exists a bundle map $\xi \rightarrow \gamma^n(\mathbb{R}^{n+k})$ provided that k is sufficiently large.*

In order to generalize to common manifolds that do not happen to be compact, we do two things: replace “compact” by “paracompact” and introduce infinite Grassmann manifolds. A topological space is paracompact if it is Hausdorff and for every open cover, there is a locally finite refinement. Every metric space is paracompact, a direct limit of compact spaces is compact, and nearly all familiar topological spaces are paracompact. We realize the infinite Grassmann manifolds as a direct limit of the sequence

$$G_n(\mathbb{R}^n) \subset G_n(\mathbb{R}^{n+1}) \subset G_n(\mathbb{R}^{n+2}) \subset \cdots$$

To make sense of “ \subset ”: Define $\mathbb{R}^\infty = \bigoplus_{i=1}^\infty \mathbb{R}_i$ and view each \mathbb{R}^n as a subset $\bigoplus_{i=1}^n \mathbb{R}_i$. We denote the above infinite Grassmann manifold as $G_n(\mathbb{R}^\infty)$. As a special case, we have infinite projective space $\mathbb{P}^\infty = G_1(\mathbb{R}^\infty)$ is the direct limit of $\mathbb{P}^1 \subset \mathbb{P}^2 \subset \dots$.

A canonical bundle γ^n over G_n can be constructed just as in the finite case, i.e. as a subset of $G_n \times \mathbb{R}^\infty$ that consists of pairs of planes and vectors in the planes. It is topologized as a subset of the Cartesian product. We will verify that it does satisfy the local triviality condition and is a n -plane bundle over G_n . Now Lemma 2.1 can be extended to the theorem:

Theorem 2.2. *Any \mathbb{R}^n -bundle ξ over a paracompact base admits a bundle map $\xi \rightarrow \gamma^n$. Moreover, any two such bundle maps are homotopic.*

In particular, the homotopic bundle maps induce homotopic maps on base spaces. Therefore any \mathbb{R}^n -bundle ξ over a paracompact space B determines a unique homotopy class of maps $\overline{f}_\xi : B \rightarrow G_n$.

2.1.2 Cell Structure

In this section we use D^p to denote the closed unit disk in \mathbb{R}^p . Let us recall the definition of a CW-complex:

Definition 2.3. A CW-complex is a Hausdorff space K , together with a partition of K into disjoint subsets $\{e_\alpha\}$, such that

1. Each e_α is topologically an open cell of dimension $n(e)$. For each e_α , there is a characteristic map $\varphi_\alpha : D^{n(\alpha)} \rightarrow K$ that carries $\text{int } D^{n(\alpha)}$ homeomorphically onto e_α .
2. Each point $x \in \text{cl}(e_\alpha) - e_\alpha$ must lie in a cell e_β of lower dimension.
3. Each point of K is contained in a finite subcomplex.
4. K is topologized as a direct limit of its finite subcomplexes.

The last two conditions always hold if the complex is finite (i.e. has finitely many cells), so we only use them to deal with infinite complexes. Note that the closure of a cell need not be a cell. For example, S^n can be considered a cell complex with a n -cell and a 0-cell, but the closure of the n -cell is the entire sphere. Every CW-complex is paracompact. We first study the cell structure for $G_n(\mathbb{R}^m)$. Any n -plane $X \subseteq \mathbb{R}^m$ is filtrated by

$$0 \subseteq X \cap \mathbb{R}^1 \subseteq X \cap \mathbb{R}^2 \subseteq \dots \subseteq X \cap \mathbb{R}^m$$

The dimension of spaces in the above filtration increases from 0 and stabilizes at n . There are precisely n jumps. We use a Schubert symbol $\sigma = (\sigma_1, \dots, \sigma_n)$ to record a jump type, i.e.

$$\dim X \cap \mathbb{R}^{\sigma_i} = i, \dim X \cap \mathbb{R}^{\sigma_{i-1}} = i - 1$$

For each Schubert symbol σ , we use $e(\sigma)$ to denote the set of all n -planes with the same jump type.

Let us use the standard basis for \mathbb{R}^n and \mathbb{R}^∞ . For each n -plane $X \subseteq \mathbb{R}^m$ we can write down a $n \times m$ matrix whose row space is X , i.e. a generator matrix for X . Then we reduce the matrix to echelon form, then the columns with pivotal entries are in the support of σ .

3 Differential Geometry

4 Algebraic Geometry