## TD1

Exercise 1 (Linear algebra reminders). Let  $(E, \langle \cdot, \cdot \rangle_E)$  and  $(F, \langle \cdot, \cdot \rangle_F)$  be finite-dimensional Hilbert spaces, and let  $A \in \mathcal{L}(E, F)$ .

1. Let G be a subspace of E. Show that  $E = G \oplus G^{\perp}$ .

Hint: one may introduce a basis of G and use the projection operator on G.

- 2. Show that
  - $\operatorname{Ker} A^* = (\operatorname{Ran} A)^{\perp}$
  - Ran  $A^* = (\operatorname{Ker} A)^{\perp}$
  - $\operatorname{Ker} A^* A = \operatorname{Ker} A$
- 3. Show that if A has full column rank (hence dim  $E \leq \dim F$ ), then  $A^*A$  is invertible.

Solution.

1. Let  $x \in G \cap G^{\perp}$ . Then  $0 = \langle x, x \rangle_E = ||x||_E^2$ , hence x = 0. Therefore,  $\underline{G \cap G^{\perp}} = \{0\}$ . Let  $x \in E$ . Let  $(e_1, \ldots, e_k)$  be an orthonormal basis of G, and consider the projection on G:

$$\forall x \in E, \quad P_G(x) = \sum_{i=1}^k \langle x, e_i \rangle e_i$$

Then  $x = P_G(x) + (x - P_G(x))$ , and one checks easily that  $(x - P_G(x))$  is in  $G^{\perp}$ . Hence  $x \in G + G^{\perp}$ . This shows  $\underline{E} = G + G^{\perp}$ .

2. We only prove the second equality. The inclusion  $\operatorname{Ran} A^* \subset (\operatorname{Ker} A)^{\perp}$  is straightforward. Let  $\dim E = n$ ,  $\dim F = m$ . Then, since

 $\dim \operatorname{Ran} A^* = m - \dim \operatorname{Ker} A^* = m - \dim (\operatorname{Ran} A)^{\perp} = \dim \operatorname{Ran} A = n - \dim \operatorname{Ker} A = \dim (\operatorname{Ker} A)^{\perp}$  which proves the equality.

3. A full column rank means that  $\operatorname{Ker} A = \{0\}$ , and hence  $\operatorname{Ker} A^*A = \{0\}$ . Hence  $\operatorname{dim} \operatorname{Ran} A^*A = n$  and  $\operatorname{Ran} A^*A = F$ .

Exercise 2 (Regression). Given  $\tau = \{t_1, \ldots, t_m\} \subset \mathbb{R}$ , we define

$$\mathcal{A}_n^{\tau}: \mathbb{R}_{n-1}[X] \to \mathbb{R}^m$$

$$p \mapsto [p(t_1), \dots, p(t_m)]^{\top},$$

and we consider the inverse problem

$$\mathcal{A}_n^{\tau}(p) = y \tag{1}$$

given some  $y \in \mathbb{R}^m$ .

- 1. Show that  $\mathcal{A}_n^{\tau}$  is linear and give its matrix representation  $A_n^{\tau}$  with respect to the canonical bases of  $\mathbb{R}_{n-1}[X]$  and  $\mathbb{R}^m$ .
- 2. \* Suppose n=m. Show that  $\det(A_m^{\tau})=\prod_{i< j}(t_j-t_i)$ . When does (1) admit a unique solution in that case?
- 3. Suppose n < m. Why is the problem ill-posed in that case? We consider the least-square formulation

$$\min_{p \in \mathbb{R}^n} L(p) := \|A_n^{\tau} p - y\|_2^2. \tag{2}$$

Show that L is convex, and deduce the normal equations.

4. In this question, we assume that n=2 and m>n. Show that the solution of (2) is a line that passes through the arithmetic mean of the points  $((t_1,y_1),\ldots,(t_m,y_m))$ .

*Hint*: With  $p = (\alpha, \beta) \in \mathbb{R}^2$ , consider the partial derivative of  $L(\alpha, \beta)$  with respect to  $\alpha$ .

## Solution.

1. One checks easily that  $\mathcal{A}_n^{\tau}(\lambda p + \mu q) = \lambda \mathcal{A}_n^{\tau}(p) + \mu \mathcal{A}_n^{\tau}(q)$  for all  $\lambda, \mu \in \mathbb{R}, p, q \in \mathbb{R}_{n-1}[X]$ . The representing matrix is

$$A_n^{\tau} = \begin{pmatrix} 1 & t_1 & \dots & t_1^{n-1} \\ 1 & t_2 & \dots & t_2^{n-1} \\ \vdots & \vdots & & \vdots \\ 1 & t_m & \dots & t_m^{n-1} \end{pmatrix}$$

2. We reason inductively. The formula is easily verifiable for m=2. Let us assume that it holds for a given m. We consider the determinant

$$D_m(X) = \begin{vmatrix} 1 & X & \dots & X^m \\ 1 & t_1 & \dots & t_1^m \\ \vdots & \vdots & & \vdots \\ 1 & t_m & \dots & t_m^m \end{vmatrix}$$

This is a polynomial of degree m, and one has  $D(t_i) = 0$  for all i = 1, ..., m, hence necessarily

$$D_m(X) = a_m \prod_{i=1}^m (X - t_i).$$

The leading coefficient  $a_m$  is obtained by developing the determinant with respect to  $X^m$ , which gives  $a_m = \det(A_m^{\tau})$ . By the induction hypothesis, we deduce

$$D_m(X) = \prod_{1 \le i < j \le m} (t_j - t_i) \prod_{i=1}^m (X - t_i)$$

and therefore

$$\det(A_{m+1}^{\tau}) = D_m(t_{m+1}) = \prod_{1 \le i < j \le m+1} (t_j - t_i),$$

which concludes the induction. The linear system admits a unique solution if and only if  $A_m^{\tau}$  is injective, hence invertible in the case m=n, which happens when  $t_i \neq t_j$  for all  $i \neq j$  (since then the determinant is nonzero).

3. If n < m, then rank  $A_m^{\tau} < m$  and  $A_m^{\tau}$  cannot be surjective, so the linear system might have no solution.

The convexity of L is a simple verification. We can differentiate L with respect to p to obtain

$$\nabla L(p) = 2(A_n^{\tau})^{\top} (A_n^{\tau} p - y).$$

The first order optimality conition  $\nabla L(p) = 0$  leads to the normal equations.

4. In this situation the problem boils down to finding a line  $y(t) = p_0 + p_1 t$  (a polynomial of degree 1) going through the point  $(t_1, y_1), \ldots, (t_m, y_m)$ . The least-squares problem associated with the linear system

$$\begin{bmatrix} 1 & t_1 \\ \vdots & \vdots \\ 1 & t_m \end{bmatrix} \begin{bmatrix} p_1 \\ p_2 \end{bmatrix} = \begin{bmatrix} y_1 \\ \vdots \\ y_m \end{bmatrix}$$

leads to the normal equations

$$\begin{bmatrix} m & \sum t_i \\ \sum t_i & \sum t_i^2 \end{bmatrix} \begin{bmatrix} p_1 \\ p_2 \end{bmatrix} = \begin{bmatrix} \sum y_i \\ \sum y_i t_i \end{bmatrix}$$

which solves in

$$p_2 = \frac{\sum y_i t_i - m\overline{y}\overline{t}}{\sum_i t_i^2 - m\overline{t}^2}, \quad p_1 = \overline{y} - \beta\overline{t},$$

where  $\overline{y} = m^{-1} \sum y_i$  and  $\overline{t} = m^{-1} \sum t_i$ . In particular, we do have  $\overline{y} = p_1 + p_2 \overline{t}$ .

- Exercise 3. Let  $A = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$  and  $y = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}$  with  $y_1 \leqslant y_2 \leqslant y_3$ . We consider the linear system Ax = y for  $x \in \mathbb{R}$ .
  - 1. Is this system well-posed? why?
  - 2. Let  $p \in [1, +\infty]$ . We replace the system by the following problem

$$\min_{x \in \mathbb{R}} \|Ax - y\|_p^p \tag{3}$$

Compute the solution of (3) for  $p = 1, 2, \infty$ .

Solution.

- 1. The system is ill-posed, because A is not surjective, since  $\operatorname{Ran} A = \left\{ \begin{bmatrix} x \\ x \\ x \end{bmatrix} \; ; \; x \in \mathbb{R} \right\} \neq \mathbb{R}^3$ .
- 2. For p = 2, we retrieve the usual least-squares problem, whose solution is given by the normal equations

$$3x = \sum y_i$$
, i.e.  $x = \frac{1}{3}(y_1 + y_2 + y_3)$ .

For p=1, we want to minimize  $\sum |x-y_i|$  over  $x\in\mathbb{R}$ . For any  $x\in\mathbb{R}$ , we have that  $\sum |x-y_i|\geqslant |x-y_1|+|x-y_3|\geqslant |y_1-y_3|$ , with equality if  $x=y_2$  (since  $y_1\leqslant y_2\leqslant y_3$ ). Hence the minimum is attained for  $x=y_2$ .

For  $p = \infty$ , we want to minimize  $\max_i |x - y_i|$  for  $x \in \mathbb{R}$ . Because of the ordering  $y_1 \leqslant y_2 \leqslant y_3$ , we can see that the maximum over  $y_1, y_2, y_3$  is actually equal to the maximum over  $y_1$  and  $y_3$  only. The point that minimizes the largest distance to one of these two points is their mean: the solution is  $x = \frac{1}{2}(y_1 + y_3)$ .

Exercise 4 (An example in infinite dimension). Let  $E = L^2([0,1])$ , endowed with the  $L^2$ -norm, and let  $\mathcal{A}$  be the operator defined by

 $\mathcal{A}f(x) = \int_0^x f(t) dt$ 

- 1. Check that  $A \in \mathcal{L}(E, E)$ , and that it is continuous.
- 2. Show that A is injective.
- 3. Let  $F:=\big\{g\in C^1([0,1])\;;\;g(0)=0\big\}$ . Show that  $F\subset\operatorname{Ran} A$ . This allows to consider the restriction  $\mathcal{A}^{-1}|_F:F\to E$  of  $\mathcal{A}^{-1}:\operatorname{Ran} A\to E$ .
- 4. Show that  $\mathcal{A}^{-1}|_F$  is not continuous. Hint: consider the function  $f_n(x) = f(x) + \frac{1}{n}\sin(n^2x)$  for  $f \in C^1([0,1])$  with f(0) = 0.

Solution.

1. Linearity is easy to check. One has that  $\|\mathcal{A}f\|_2^2 \leq \|f\|_2^2$ , hence  $\mathcal{A}f \in L^2$ . For continuity, note that for any  $\varepsilon$ , if  $\|f - g\|_2 \leq \varepsilon$  then

$$\|\mathcal{A}f - \mathcal{A}g\|_2^2 = \int_0^1 \left| \int_0^x (f - g)(t) dt \right|^2 dx$$

$$\leq \int_0^1 \int_0^x |f - g|^2(t) dt dx$$

$$\leq \|f - g\|_2^2 \leq \varepsilon^2$$

2. Let  $f \in \text{Ker } A$ . Then, for any x,

$$\int_0^x f(t)\mathrm{d}t = 0,$$

hence, by derivating,

$$\forall x \in [0, 1], \quad f(x) = f(0)$$

and f is constant. But since  $\int_0^1 f(t)dt = 0$ , necessarily f = 0.

3. If  $g \in F$ , then it has a derivative g' and we have that

$$Ag'(x) = \int_0^x g'(t)dt = g(x) - g(0) = g(x)$$

hence  $g \in \operatorname{Ran} A$ .

4.  $\mathcal{A}^{-1}|_F$  is simply the standard derivation of a function. We have that

$$||f_n - f||_2^2 = \frac{1}{n^2} \int \sin^2(n^2 x) dx \leqslant \frac{1}{n^2}$$

but on the other hand

$$\|\mathcal{A}^{-1}f_n - \mathcal{A}^{-1}f\|_2^2 = \|f_n' - f'\|_2^2 = n \int_0^1 \cos^2(n^2x) \mathrm{d}x = \frac{n}{2} \int (1 + \cos(2n^2x)) \mathrm{d}x = \frac{n}{2} + \frac{\sin(2n^2)}{4n}.$$

Therefore,  $\lim_{n\to\infty} \|f_n - f\| = 0$ , but  $\lim_{n\to\infty} \|f'_n - f'\| = +\infty$ , which shows that  $\mathcal{A}^{-1}$  is not continuous.