

ДЗ 7. Тензорный анализ.

н1. $S_{ij} = S_{ji}$

$$S'_{ij} = d_{ik} d_{jl} S_{kl} = d_{ik} d_{jl} S_{lk} = S'_{ji}$$

н2. т.г. $\Pi'_{ij} = d_{ik} d_{jl} \Pi_{kl} \equiv d \Pi d^T = \Pi'$

$$\Pi'_{ij} = d_{ik} d_{jl} \Pi_{kl} = d_{ik} \Pi_{kl} d_{lj}^T = (d \Pi d^T)_{ij}$$

н3. $d = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}, \quad \varepsilon_{ij} = -\varepsilon_{ji}, \quad \varepsilon_{11} = \varepsilon_{22} = 1$

$$\varepsilon_{ij} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, \quad \varepsilon'_{ij} = d \varepsilon_{ij} d^T, \quad d^T = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$

$$\varepsilon'_{ij} = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} =$$

$$= \begin{pmatrix} -\sin \theta & \cos \theta \\ -\cos \theta & -\sin \theta \end{pmatrix} \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} = \begin{pmatrix} -\sin \theta \cos \theta + \cos \theta \sin \theta & \sin^2 \theta - \cos^2 \theta \\ \cos^2 \theta - \sin^2 \theta & \sin \theta \cos \theta - \cos \theta \sin \theta \end{pmatrix}$$

$$= \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$

н4. Тензоры II ранга размерности A_{ij} и B_{ij}

1) $C_{ijkl} = A_{ij} B_{kl} = \sum_{am} d_{ia} d_{jm} A_{am} \cdot \sum_{pn} d_{kp} d_{ln} B_{pn} =$
 $= \sum_{a,m,p,n} d_{ia} d_{jm} d_{kp} d_{ln} A_{am} B_{pn} - \text{тензор IV ранга}$

2) $D_{il} = \sum_j C_{ijjl} = \sum_j A_{ij} B_{jl} = \sum_j \sum_{a,m} d_{ia} d_{jm} d_{jp} d_{lp} A_{am} B_{pj}$

$$= \sum_{k=1}^n \sum_{l=1}^n d_{ik} d_{lj} \delta_{kp} A_{kl} B_{pe} = d_{ik} d_{lj} A_{kl} B_{pe} = d_{ik} d_{lj} D_{kl} = D_{il}$$

$$3) D = \sum_i D_{ii} = \sum_i d_{ik} d_{ie} D_{ke} = \delta_{ke} D_{ke} = D$$

$$\sim 5. \psi(r) = \psi(x_1, x_2, x_3), \quad D_{ij} = \frac{\partial \psi}{\partial x_i \partial x_j}$$

$$X'_i = X'_i(x_1, x_2, x_3) - \text{новая система координат}$$

$$\frac{\partial \psi}{\partial x'_i} = \sum_{k=1}^3 \frac{\partial \psi}{\partial x_k} \frac{\partial x_k}{\partial x'_i} \quad x_k - \text{старые координаты}, \quad \frac{\partial x_k}{\partial x'_i} - \text{элемента преобр-я коорд}$$

$$\frac{\partial^2 \psi}{\partial x'_i \partial x'_j} = \frac{\partial}{\partial x'_j} \left(\frac{\partial \psi}{\partial x'_i} \right) = \frac{\partial}{\partial x'_j} \left(\sum_{k=1}^3 \frac{\partial \psi}{\partial x_k} \frac{\partial x_k}{\partial x'_i} \right) = \frac{\partial x_k}{\partial x'_i} \frac{\partial}{\partial x'_j} \frac{\partial \psi}{\partial x_k} +$$

$$+ \frac{\partial \psi}{\partial x_k} \frac{\partial}{\partial x'_j} \frac{\partial x_k}{\partial x'_i} = \frac{\partial x_k}{\partial x'_i} \frac{\partial x_l}{\partial x'_j} \frac{\partial^2 \psi}{\partial x_k \partial x_l} + \dots$$

$$D'_{ij} = \frac{\partial x_k}{\partial x'_i} \frac{\partial x_l}{\partial x'_j} D_{kl}$$

нб.

$$A_{ij} = \begin{pmatrix} 0 & w_3 & -w_2 \\ -w_3 & 0 & w_1 \\ w_2 & -w_1 & 0 \end{pmatrix}; \quad A_{ij} = -A_{ji}, \quad \text{т.е. } \vec{w} = (w_1, w_2, w_3) - \text{вектор}$$

$$P'_{ij} = d_{ik} d_{jl} P_{kl} = -d_{ik} d_{jl} P_{lk} = -d_{jl} d_{ik} P_{kl} = -P'_{ji}$$

$$W'_3 = P'_{12} = d_{1k} d_{2l} P_{kl} = w_1 (d_{12} d_{23} - d_{13} d_{22}) +$$

$$+ w_2 (d_{13} d_{21} - d_{11} d_{23}) + w_3 (d_{11} d_{22} - d_{12} d_{21}) =$$

$$= w_1 d_{31} + w_2 d_{32} + w_3 d_{33}$$

$$W'_i = d_{ik} w_k$$

н 7.

$$1) \sum_j A_{ij} \delta_{jk} = A_{i1} \delta_{1k} + A_{i2} \delta_{2k} + \dots + A_{in} \delta_{nk} = A_{ik}$$

$$\sum_i A_{ij} \delta_{ik} = \sum_i A_{ij} \delta_{ki} = A_{jk}$$

$$\sum_{ij} A_{ij} \delta_{ij} = A$$

$$2) \sum_k \delta_{ik} \delta_{kj} = \delta_{ij} \quad \sum_{ik} \delta_{ik} \delta_{ki} = \sum_{ik} \delta_{ik} \delta_{ik} = \delta = 1$$

$$\sum_{ik} \delta_{ik} \delta_{ik} = \delta = 1$$

н 8. $\nabla_i A_{ij} \dots \quad \epsilon_{ij} \epsilon_{lm} = \delta_{il} \delta_{jm} - \delta_{im} \delta_{jl}$

$$T_{ijk} \epsilon_{ijk} \epsilon_{lmn} = \det \begin{pmatrix} \delta_{il} & \delta_{im} & \delta_{in} \\ \delta_{jl} & \delta_{jm} & \delta_{jn} \\ \delta_{kl} & \delta_{km} & \delta_{kn} \end{pmatrix} \Rightarrow$$

$$\epsilon_{ij} \epsilon_{lm} = \det \begin{pmatrix} \delta_{il} & \delta_{im} \\ \delta_{jl} & \delta_{jm} \end{pmatrix} = \delta_{il} \delta_{jm} - \delta_{im} \delta_{jl}$$

антисимметричность в правой части сохр-на
т.к. при перестановке строк или столбцов
местами, знак определителя меняется
проверим для $i=l=1, j=m=2$:

$$\epsilon_{12} \epsilon_{12} = \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} = 1$$

9.

$$1) \det \begin{pmatrix} \delta_{il} & \delta_{im} & \delta_{in} \\ \delta_{jl} & \delta_{jm} & \delta_{jn} \\ \delta_{kl} & \delta_{km} & \delta_{kn} \end{pmatrix} = \delta_{il} (\delta_{jm} \delta_{kn} - \delta_{jn} \delta_{km}) +$$

$$+ \delta_{im} (\delta_{jn} \delta_{kl} - \delta_{jl} \delta_{kn}) + \delta_{in} (\delta_{jl} \delta_{km} - \delta_{jm} \delta_{kl})$$

$$2) \sum_k \epsilon_{ijk} \epsilon_{lmk} = \sum_k \epsilon_{ijk} \epsilon_{kml} = \epsilon_{ij} \epsilon_{lm} = \delta_{il} \delta_{jm} - \delta_{im} \delta_{jl}$$

$$3) \sum_{j,k} \epsilon_{ijk} \epsilon_{ejk} = \sum_{j,k} \epsilon_{ijk} \epsilon_{kej} = \sum_j \epsilon_{ij} \epsilon_{ej} = \delta_{il} \delta_{jj} - \delta_{ij} \delta_{jl} =$$

$$= 3\delta_{il} - \delta_{il} = 2\delta_{il}$$

10. $A_{ij} = -A_{ji}$, $S_{ij} = S_{ji}$, $\sum_{ij} A_{ij} S_{ij} \equiv 0$

$$A_{ij} S_{ij} = -A_{ji} S_{ij} = -C$$

$$A_{ij} S_{ij} = A_{ij} S_{ji} = C$$

$$C = -C \Rightarrow C = 0$$

11.

$$1) b_i = \sum_j \Gamma_{ij} a_j = \sum_j \sum_k \alpha_{ik} \alpha_{jl} \Gamma_{kl} \alpha_{jl} a_e =$$

$$b'_i = \sum_j \Gamma'_{ij} a'_j = \sum_j \sum_{kl} \alpha_{ik} \alpha_{jl} \Gamma_{kl} \alpha_{jl} a_e =$$

$$= \alpha_{ik} \sum_l \alpha_{jl} \Gamma_{kl} a_e = \alpha_{ik} b_k$$

$$2) c_j = \sum_i \Gamma_{ij} a_i$$

$$c'_j = \sum_i \Gamma'_{ij} a'_i = \sum_i \alpha_{ik} \alpha_{jl} \Gamma_{kl} \alpha_{im} a_m =$$

$$= \alpha_{jl} \sum_k \alpha_{ik} \Gamma_{kl} a_k = \alpha_{jl} c_l$$