

Necessary opt. conditions	→	CQ, KKT (inequality & equality)
Sufficient opt. conditions	→	saddle point of $L(\underline{x}, \underline{u})$
Lagrangian duality	→	(P) → (D) → solve (D)
Second order opt.	→	KKT sufficient / necessary (w/ $L(\underline{x}, \underline{u})$)
Quadratic Programming $q(\underline{x}) = \frac{1}{2} \underline{x}^T Q \underline{x} + \underline{c}^T \underline{x}$	→	{ only equality → Null space method eq. & ineq. → Active-set method
Penalty methods	→	{ Quadratic penalty method Augmented Lagrangian method Barrier method