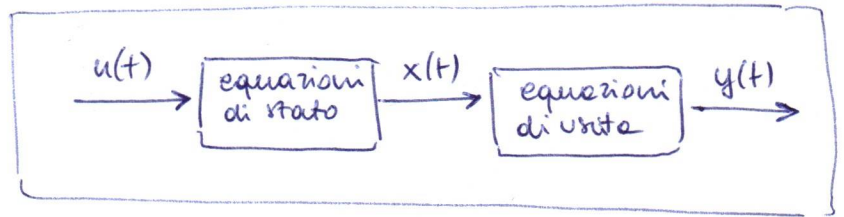
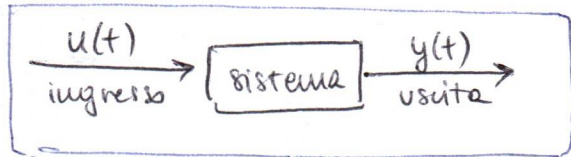
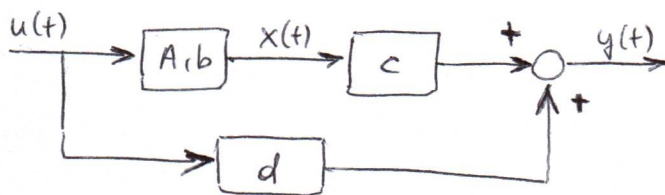


# AUTOMATICA (tempo discreto)



$$\begin{cases} \underline{x}(t+1) = A \underline{x}(t) + \underline{b} u(t) \\ y(t) = \underline{c}^T \underline{x}(t) + d u(t) \end{cases}$$

$A \in \mathbb{R}^{n \times n}$  : matrice di stato  
 $\underline{b} \in \mathbb{R}^n$  : vettore di ingresso  
 $\underline{c} \in \mathbb{R}^n$  : vettore di uscita



$$x(t+1) = Ax(t) + bu(t) \Rightarrow x(t) = A^t x(0) + \sum_{i=0}^{t-1} b u(t-i-1)$$

↑ modello interno  
 ↓ modello esterno

PREDIZIONE: conosco i valori fino al tempo  $(t+k-1)$  e voglio predire il comportamento al tempo  $(t+k)$

$$y = \frac{N(z)}{D(z)} u \Rightarrow G(z) := \frac{N(z)}{D(z)} := \text{funzione di trasferimento}$$

$$\Rightarrow y = G(z) u$$

$$v(t) : \text{generico segnale discreto} \Rightarrow v(t+k) = z^k v \quad k \in \mathbb{Z}$$

$$x(t+1) = Ax(t) + bu(t) \xrightarrow{u=0} x(t) = A^t x(0)$$

$$T := -\frac{1}{\log |A|} : \begin{cases} |A| < 1 & \text{asintoticamente stabile} \\ |A| = 1 & \text{semplicemente stabile} \\ |A| > 1 & \text{instabile} \end{cases} \quad (n=1)$$

$$\begin{aligned} &\bullet |\lambda_i| < 1 \quad \forall i && \text{asint. stabile} && (n=2) \\ &\bullet \exists \lambda_j : |\lambda_j| > 1 && \text{instabile} \\ &\bullet |\lambda_i| \leq 1 \quad \forall i, \exists \lambda_j : |\lambda_j| = 1 : && \begin{aligned} &\bullet b_i = 1 \quad \text{semp. stabile} \\ &\bullet b_i = 0 \quad \text{instabile} \end{aligned} && (T_i := -\frac{1}{\log |\lambda_i|}) \end{aligned}$$