

General problem:

$$\begin{aligned} \min & f(x) \\ \text{s.t.} & g_i(x) \leq 0 \quad i \in I = \{1, \dots, m\} \\ & x \in X \subseteq \mathbb{R}^n \\ & h_\ell(x) = 0 \quad \ell \in L = \{1, \dots, p\} \end{aligned} \quad := (P)$$

Suff. conditions for CQ:

- all g_i are linear
- all g_i are convex and $\exists x^*: g_i(x^*) < 0 \quad \forall i$ (Karlin) \rightarrow CQ $\forall x \in S$
- $\nabla g_i(\bar{x})$ are linearly $\perp \quad \forall i \in I(\bar{x})$ (Slater) \rightarrow CQ in $\bar{x} \in S$

First order (necessary) optimality conditions (KKT):

$f \in C^1, g_i \in C^1, \text{ CQ holds at } \bar{x}.$

If \bar{x} is a local minimum of (P) $\Rightarrow \exists u_i \geq 0 \quad \forall i \in I(\bar{x}); v_\ell \in \mathbb{R}:$

$$(\bullet) \quad \nabla f(\bar{x}) + \sum_{i \in I} u_i \nabla g_i(\bar{x}) = 0$$

$$\bullet \quad \nabla f(\bar{x}) + \sum_{i \in I} u_i \nabla g_i(\bar{x}) + \sum_{\ell \in L} v_\ell \nabla h_\ell(\bar{x}) = 0$$

$$\bullet \quad u_i g_i(\bar{x}) = 0 \quad \forall i \in I$$

$$\bullet \quad h_\ell(\bar{x}) = 0$$

$$\bullet \quad g_i(\bar{x}) \leq 0 \quad \forall i \in I$$

• If the problem is convex \Rightarrow the condition is necessary and sufficient

• If f and g_i are convex and $\exists x^*: g_i(x^*) < 0 \quad \forall i$ \Rightarrow the condition is necessary and sufficient

Lagrangian function associated:

$$L(x, u) = f(x) + \sum_{i \in I} u_i g_i(x)$$

$$\forall x \in X, u \geq 0$$

Dual function: $w(u) = \min_{x \in X} L(x, u)$

Dual problem: $\max_{u \geq 0} w(u)$

Properties:

- $\forall x \in X$ (x feasible solution) and $u \geq 0$: $w(u) \leq f(x)$ (weak duality)
- If $\exists \bar{u}, \bar{x}$ s.t. $w(\bar{u}) = f(\bar{x})$ we have strong duality: \bar{u} is optimal for the dual and \bar{x} is optimal for the original problem (P). Moreover (\bar{x}, \bar{u}) is a saddle point of $L(x, u)$.
- Generally we can have a duality gap: $\max_{u \geq 0} w(u) < \min_{x \in S} f(x)$

but if the problem is convex (or it holds the strong duality) the problem has a finite optimal solution and we have no duality gap.

How can we solve the dual:

If $X \subseteq \mathbb{Z}^n$ then $w(u)$ is piecewise concave and we can find the global optimal solutions with the subgradient method (since $w(u)$ may not be everywhere continuously differentiable we use the gradient if the point is cont. diff., the subgradient if it's not).

$\rightarrow w(u)$ is always concave, if $X \subseteq \mathbb{Z}^n$ then it's piecewise concave