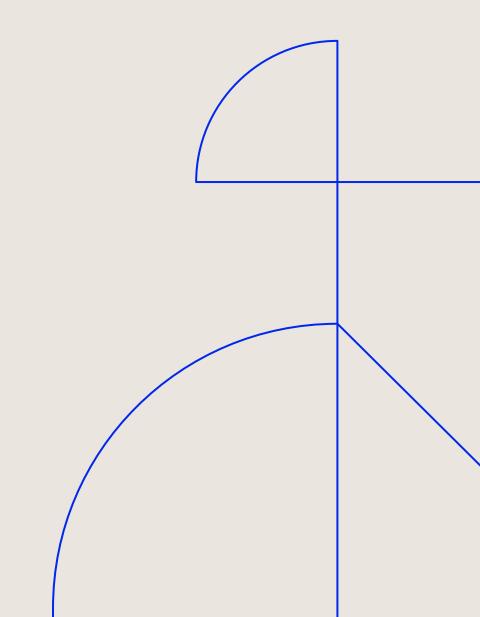




Motivation



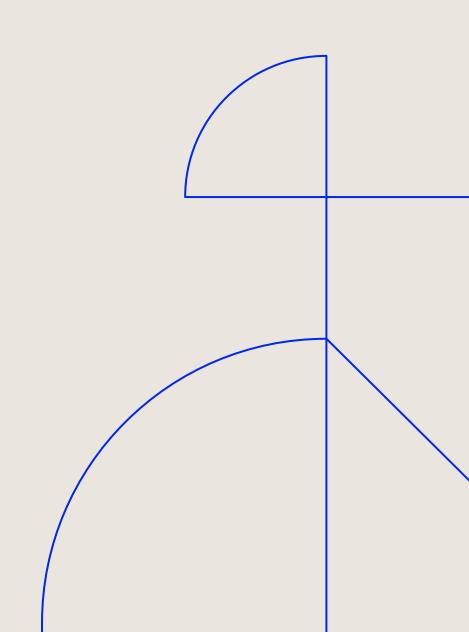


Motivation

- Non-polar director field $\vec{n}(\vec{x}) \in \mathbb{RP}^2 \cong S^2/\mathbb{Z}_2$
- Hopfions $\vec{n}: S^3 \to \mathbb{RP}^2$ and skyrmions $\vec{n}: S^2 \to \mathbb{RP}^2$
- Flexoelectric effect: electric polarization response $\vec{P}_f(\vec{n}) \longrightarrow \text{induced electric field } \vec{E}(\vec{n})$
- Associated electrostatic self-energy $\propto \vec{E}(\vec{n}) \cdot \vec{P}_f(\vec{n})$ \longrightarrow back-reaction on \vec{n}
- How to include this electrostatic self-interaction and back-reaction?
- Analogous to demagnetization in chiral magnets (depolarization)



Chiral liquid crystals





Isotropic elastic liquid crystal

Frank-Oseen free energy is

$$E_{\rm FO} = \frac{1}{2} K \int_{\mathbb{R}^3} \mathrm{d}^3 x |\nabla \vec{n}|^2$$

- ullet Energy minimizers are solutions of Laplace equation $\Delta ec{n} = ec{0}$
- Metastable inhomogeneous solutions found by Belavin and Polyakov^[1] in ferromagnets
- More insight can be gained by considering elastic modes
- Decompose director gradient tensor into these normal modes $^{[2]}(\vec{B},T,S,\mathbf{\Delta})$

$$\partial_i n_j = -n_i B_j + \frac{1}{2} T \epsilon_{ijk} n_k + \frac{1}{2} S(\delta_{ij} - n_i n_j) + \Delta_{ij}$$



Bend

$$\partial_i n_j = \boxed{-n_i B_j} + \frac{1}{2} T \epsilon_{ijk} n_k + \frac{1}{2} S(\delta_{ij} - n_i n_j) + \Delta_{ij}$$

- Standard bend vector $\dot{\vec{B}} = -(\vec{n}\cdot\vec{\nabla})\vec{n} = \vec{n}\times(\vec{\nabla}\times\vec{n})$
- Invariant under $\vec{n} \mapsto -\vec{n}$



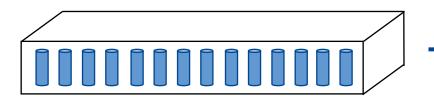
• Elastic bend energy $|\vec{B}|^2 = [\vec{n} \times (\vec{\nabla} \times \vec{n})]^2$

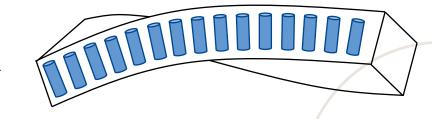


Twist

$$\partial_i n_j = -n_i B_j + \boxed{\frac{1}{2} T \epsilon_{ijk} n_k} + \frac{1}{2} S(\delta_{ij} - n_i n_j) + \Delta_{ij}$$

- Pseudoscalar twist $T = \vec{n} \cdot (\vec{\nabla} \times \vec{n})$
- Invariant under $\vec{n} \mapsto -\vec{n}$





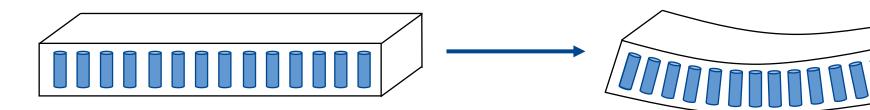
• Elastic twist energy $T^2 = [\vec{n} \cdot (\vec{\nabla} \times \vec{n})]^2$



Splay

$$\partial_i n_j = -n_i B_j + \frac{1}{2} T \epsilon_{ijk} n_k + \frac{1}{2} S(\delta_{ij} - n_i n_j) + \Delta_{ij}$$

- Standard scalar splay $S = \vec{\nabla} \cdot \vec{n}$
- Invariant under $\vec{n} \mapsto -\vec{n}$



• Elastic splay energy $|S\vec{n}|^2 = (\vec{\nabla} \cdot \vec{n})^2$



Nematic liquid crystal (NLC)

Isotropic Frank-Oseen free energy for a NLC is

$$E_{\text{FO}} = \frac{1}{2} K \int_{\mathbb{R}^3} d^3 x \left\{ S^2 + T^2 + |\vec{B}|^2 \right\}$$

- Modes cost elastic free energy
- Energy cost of splay, twist and bend deformations are equivalent
- Energy of anisotropic NLC:

$$E_{\text{FO}} = \int_{\Omega} d^3x \left\{ \frac{K_1}{2} (\vec{\nabla} \cdot \vec{n})^2 + \frac{K_2}{2} \left[\vec{n} \cdot (\vec{\nabla} \times \vec{n}) \right]^2 + \frac{K_3}{2} \left[\vec{n} \times (\vec{\nabla} \times \vec{n}) \right]^2 \right\}$$

• Can introduce enantiomorphy into the system — chiral liquid crystals



Chiral liquid crystal (CLC)

- Molecular chirality characterized by (pseudoscalar) cholesteric twist $q_0 = rac{2\pi}{p}$
- Enantiomorphy introduced via twist $T\mapsto T+q_0^{\,\mathrm{[3]}}$
- Frank-Oseen free energy picks up 1st order term

$$F_{\text{FO}} = \int_{\Omega} d^3x \left\{ \frac{K_1}{2} (\vec{\nabla} \cdot \vec{n})^2 + \frac{K_2}{2} \left[\vec{n} \cdot (\vec{\nabla} \times \vec{n}) \right]^2 + \frac{K_3}{2} \left[\vec{n} \times \vec{\nabla} \times \vec{n} \right]^2 + K_2 q_0 \left[\vec{n} \cdot (\vec{\nabla} \times \vec{n}) \right] + V(\vec{n}) \right\}$$

- Equivalent to DMI term in chiral magnets arising from Dresselhaus SOC
 - Mechanism responsible for stabilization of bulk skyrmions
 - Favours Bloch modulations



Experimental realization

- ullet CLCs placed between parallel plates with separation d
- System restricted to confined geometry^[4]

$$\Omega = \left\{ (x, y, z) \in \mathbb{R}^3 : |z| \le \frac{d}{2} \right\}$$

- Apply potential difference $U \longrightarrow ext{ext} = \left(0,0,rac{U}{d}
 ight)$
- CLCs are dielectric materials

$$\mathcal{E}_{\rm elec} = -\frac{\epsilon_0 \Delta \epsilon}{2} (\vec{E}_{\rm ext} \cdot \vec{n})^2$$

- Can impose **strong homeotropic anchoring** $ec{n}(x,y,z=\pm d/2)=ec{n}_{\uparrow}$
- Mimicked in 2D systems by including Rapini-Papoular homeotropic surface anchoring potential^[5]

$$\mathcal{E}_{\mathrm{anch}} = -\frac{1}{2}W_0n_z^2$$
 Effective surface anchoring strength



Electrostatic self-interaction



Flexoelectric polarization

- Flexoelectricity: coupling between electrical polarization and non-uniform strain
- Orientational distortions \longrightarrow macroscopic electric polarization \vec{P}_f
- Fix splay, induce polarization:

$$F = \frac{1}{2}K_1 \left| \vec{n}(\vec{\nabla} \cdot \vec{n}) - c_1 \vec{P} \right|^2 + \frac{1}{2}\mu |\vec{P}|^2 \qquad \longrightarrow \qquad \frac{\delta F}{\delta \vec{P}} = \vec{0} \Rightarrow \vec{P} = \left(\frac{c_1 K_1}{c_1^2 K_1 + \mu} \right) (\vec{\nabla} \cdot \vec{n}) \vec{n}$$

Fix bend, induce polarization:

$$F = \frac{1}{2}K_3 \left| \left[\vec{n} \times (\vec{\nabla} \times \vec{n}) \right] - c_3 \vec{P} \right|^2 + \frac{1}{2}\mu |\vec{P}|^2 \longrightarrow \frac{\delta F}{\delta \vec{P}} = \vec{0} \Rightarrow \vec{P} = \left(\frac{c_3 K_3}{c_3^2 K_3 + \mu} \right) \left[\vec{n} \times (\vec{\nabla} \times \vec{n}) \right]$$

• Polarization caused by mechanical curvature (**flexion**) of director (flexoelectric)^[6,7]:

$$\vec{P}_f = e_1 \left[(\vec{\nabla} \cdot \vec{n}) \vec{n} \right] + e_3 \left[\vec{n} \times (\vec{\nabla} \times \vec{n}) \right]$$



Electrostatic potential

- Flexoelectric polarization induces continuous electric **dipole** moment distribution P_f
- Associated electric scalar potential

$$\varphi(\vec{x}) = \frac{1}{4\pi\epsilon_0} \int_{\Omega} d^3 \vec{y} \left\{ \frac{\vec{P}_f(\vec{y}) \cdot (\vec{x} - \vec{y})}{|\vec{x} - \vec{y}|^3} \right\} = -\frac{1}{\epsilon_0} \int_{\Omega} d^3 \vec{y} \left\{ \vec{P}_f(\vec{y}) \cdot \vec{\nabla}_{\vec{x}} G(\vec{x}, \vec{y}) \right\}$$

Green's function for Laplacian on \mathbb{R}^3

$$G(\vec{x}, \vec{y}) = \frac{1}{4\pi |\vec{x} - \vec{y}|}, \quad \Delta_{\vec{x}} G(\vec{x}, \vec{y}) = \delta(\vec{x} - \vec{y})$$

Electrostatic potential satisfies the Poisson equation^[8]
$$\Delta \varphi = -\nabla^2 \varphi = -\frac{1}{\epsilon_0} \vec{\nabla} \cdot \vec{P}_f$$

• Gauss' law
$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$

$$\rho = -\vec{\nabla} \cdot \vec{P}_f$$
 electric charge density



Flexoelectric self-energy

 $\Delta \varphi = -\frac{1}{\epsilon_0} \vec{\nabla} \cdot \vec{P}_f$

Energy of a continuous dipole density distribution^[9]

$$F_{\text{flexo}} = -\frac{1}{2} \int_{\Omega} d^3 x \, \vec{E}(\vec{x}) \cdot \vec{P}_f(\vec{x}) = \frac{1}{2} \int_{\Omega} d^3 x \, \vec{P}_f \cdot \vec{\nabla} \varphi$$

More useful to express the flexoelectric energy as

$$F_{\text{flexo}} = -\frac{1}{2} \int_{\Omega} d^3 \vec{x} \, \left(\vec{\nabla} \cdot \vec{P}_f \right) \varphi + \frac{1}{2} \int_{\partial \Omega} d\vec{s} \, \left(\varphi \vec{P}_f \right) = \frac{\epsilon_0}{2} \int_{\mathbb{R}^3} d^3 \vec{x} \, \varphi \Delta \varphi$$

- In all cases we consider, surface term vanishes –
- ullet Coincides with the electrostatic self-energy of the charge distribution $ho = -(
 abla \cdot ec{P}_f)$

$$F_{\text{flexo}} = \frac{\epsilon_0}{2} \int_{\mathbb{R}^3} d^3 \vec{x} \, \varphi \Delta \varphi = \frac{\epsilon_0}{2} \int_{\mathbb{R}^3} d^3 \vec{x} \, |\vec{\nabla} \varphi|^2 = \frac{\epsilon_0}{2} \int_{\mathbb{R}^3} d^3 \vec{x} \, |\vec{E}|^2$$



Rescaling F_{flexo}

- Length and energy scales: $L_0=\frac{1}{q_0}\frac{K_1}{K_2}, E_0=\frac{1}{q_0}\frac{K_1^2}{K_2}$
- Scalar potential $\varphi = \lambda \hat{\varphi}$
- Flexoelectric energy and Poisson equation under rescaling

$$\hat{F}_{\text{flexo}} = \frac{1}{2} \frac{L_0 \lambda^2 \epsilon_0}{E_0} \int_{\Omega} d^3 \hat{x} \, \hat{\varphi} \Delta_{\hat{x}} \hat{\varphi} \qquad \qquad \Delta_{\hat{x}} \hat{\varphi} = - \frac{e_1}{\epsilon_0 \lambda} \vec{\nabla}_{\hat{x}} \cdot \vec{P}$$

- Dimensionless vacuum permittivity $\epsilon = \frac{L_0 \lambda^2 \epsilon_0}{E_0} = \left(\frac{e_1}{\epsilon_0 \lambda}\right)^{-1} \longrightarrow \lambda = \frac{K_1}{e_1}$
- Necessary rescaling is

$$\hat{F}_{\text{flexo}} = \frac{\epsilon}{2} \int_{\Omega} d^3 \hat{x} \, \hat{\varphi} \Delta_{\hat{x}} \hat{\varphi}, \quad \Delta_{\hat{x}} \hat{\varphi} = -\frac{1}{\epsilon} \vec{\nabla}_{\hat{x}} \cdot \vec{P}, \quad \epsilon = \frac{K_1 \epsilon_0}{e_1^2}$$

Adimensional polarization

$$\vec{P} = (\vec{\nabla}_{\hat{x}} \cdot \vec{n})\vec{n} + \frac{e_3}{e_1}(\vec{n} \times [\vec{\nabla}_{\hat{x}} \times \vec{n}])$$



Scale invariance of $F_{ m flexo}$

- Derrick scaling $\vec{x} \mapsto \vec{x}' = \mu \vec{x}$
- Director rescales as $\vec{n}_{\mu} = \vec{n}(\mu \vec{x})$

$$\longrightarrow \text{ Polarization } \vec{P}_{\mu} = \mu \left(\vec{\nabla}' \cdot \vec{n}(\mu \vec{x}) \right) \vec{n}(\mu \vec{x}) + \mu \frac{e_3}{e_1} \left(\vec{n}(\mu \vec{x}) \times \vec{\nabla}' \times \vec{n}(\mu \vec{x}) \right) = \mu \vec{P}(\mu \vec{x})$$

- Poisson equation: $\Delta'\varphi_{\mu}=-\frac{1}{\mu\epsilon}\nabla'\cdot\vec{P}_{\mu}=-\frac{1}{\epsilon}\nabla'\cdot\vec{P}(\mu\vec{x})=\Delta'\varphi(\mu\vec{x})$
- Scalar potential must scale as $\varphi_{\mu}(\vec{x}) = \varphi(\mu \vec{x})$
- In two dimensions, the flexoelectric Frank-Oseen energy rescales as

$$F_{\text{FFO}}(\mu) = F_2 + \frac{1}{\mu} F_1 + \frac{1}{\mu^2} F_0 + F_{\text{flexo}}$$

Conformally invariant in 2D



First variation of F_{flexo}

First variation is

$$\frac{\mathrm{d}}{\mathrm{d}t}\Big|_{t=0} F_{\mathrm{flexo}}(\vec{n}_t) = \frac{\epsilon}{2} \int_{\mathbb{R}^2} \mathrm{d}^2 x \left(\dot{\varphi} \Delta \varphi \right) + \varphi \Delta \dot{\varphi} \right)$$

Potential does not have compact support

$$\int_{\mathbb{R}^2} d^2 x \, \dot{\varphi} \Delta \varphi = \int_{\mathbb{R}^2} d^2 x \, \varphi \Delta \dot{\varphi} - \oint_{\partial B_{\infty}(0)} d\vec{s} \cdot \left(\varphi \vec{\nabla} \dot{\varphi} - \dot{\varphi} \vec{\nabla} \varphi \right)$$

• Does have 1/r localization

$$\lim_{R \to \infty} \frac{\epsilon}{2} \int_{\partial B_R(0)} (\dot{\varphi} \star d\varphi - \varphi \star d\dot{\varphi}) = \lim_{R \to \infty} \frac{\epsilon R}{2} \int_0^{2\pi} (\dot{\varphi} \varphi_r - \varphi \dot{\varphi}_r) d\theta = 0$$

First variation reduces to

$$\frac{\mathrm{d}}{\mathrm{d}t}\bigg|_{t=0} F_{\mathrm{flexo}}(\vec{n}_t) = \epsilon \int_{\Omega} \mathrm{d}^3 x \, \varphi \Delta \dot{\varphi}$$

Need to compute



First variation of F_{flexo}

First variation is

$$\frac{\mathrm{d}}{\mathrm{d}t}\Big|_{t=0} F_{\mathrm{flexo}}(\vec{n}_t) = \epsilon \int_{\Omega} \mathrm{d}^3 x \, \varphi \Delta \dot{\varphi}$$

Poisson equation variation

$$\Delta \dot{\varphi} = -\frac{1}{\epsilon} \vec{\nabla} \cdot \left(\frac{\mathrm{d}}{\mathrm{d}t} \Big|_{t=0} \vec{P}(\vec{n}_t) \right)$$

Flexoelectric variation becomes

$$\frac{\mathrm{d}}{\mathrm{d}t}\Big|_{t=0} F_{\mathrm{flexo}}(\vec{n}_t) = -\int_{\mathbb{R}^2} \mathrm{d}^2 x \, \varphi \vec{\nabla} \cdot \left(\frac{\mathrm{d}}{\mathrm{d}t}\Big|_{t=0} \vec{P}(\vec{n}_t)\right) = \int_{\mathbb{R}^2} \mathrm{d}^2 x \, \vec{\nabla} \varphi \cdot \left(\frac{\mathrm{d}}{\mathrm{d}t}\Big|_{t=0} \vec{P}(\vec{n}_t)\right)$$

$$= \int_{\mathbb{R}^2} \mathrm{d}^2 x \, \left(\operatorname{grad}_{\vec{n}} F_{\mathrm{flexo}}\right) \cdot \vec{\varepsilon} \qquad \vec{\varepsilon} = \partial_t \vec{n}_t|_{t=0}$$

$$\operatorname{grad}_{\vec{n}} F_{\text{flexo}} = \frac{e_3}{e_1} \left[\left((\vec{\nabla} \times \vec{n}) \times \vec{\nabla} \varphi \right) + \left(\vec{\nabla} \times (\vec{\nabla} \varphi \times \vec{n}) \right) \right] - \vec{\nabla} (\vec{\nabla} \varphi \cdot \vec{n}) + (\vec{\nabla} \cdot \vec{n}) \vec{\nabla} \varphi$$



Numerical method



Relation to chiral magnets

- Stability of 2D skyrmions in chiral liquid crystals arises from same mechanism responsible for existence of skyrmions in chiral magnetic systems^[10]
- One constant approximation $K_i = K$
- Vector identity for unit vector $\vec{n}^{\text{[11]}}$:

$$(\nabla \vec{n})^2 = \left(\vec{\nabla} \cdot \vec{n}\right)^2 + \left(\vec{n} \cdot \vec{\nabla} \times \vec{n}\right)^2 + (\vec{n} \times \vec{\nabla} \times \vec{n})^2 + \vec{\nabla} \cdot \left[(\vec{n} \cdot \vec{\nabla})\vec{n} - (\vec{\nabla} \cdot \vec{n})\vec{n}\right]$$

• Frank-Oseen energy reduces to chiral magnet energy with Dresselhaus DMI

$$F_{\text{FO}} = \int_{\mathbb{R}^2} d^2x \left\{ \frac{1}{2} (\nabla \vec{n})^2 + \left[\vec{n} \cdot (\vec{\nabla} \times \vec{n}) \right] + \frac{1}{q_0^2} \frac{1}{K} V(\vec{n}) \right\}$$



Numerical problem

- Director field $\vec{n}(\vec{x}) \in \mathbb{RP}^2$
- Topological solitons are minimizers of the adimensional flexoelectric Frank-Oseen energy

$$F_{\text{FFO}}[\vec{n}] = \int_{\Omega} d^3x \left\{ \frac{1}{2} (\nabla \vec{n})^2 + \left[\vec{n} \cdot (\vec{\nabla} \times \vec{n}) \right] + \frac{1}{q_0^2} \frac{1}{K} V(\vec{n}) + \frac{1}{2} \vec{P} \cdot \vec{\nabla} \varphi \right\}$$

Electrostatic potential subject to constraint

$$\begin{cases} \Delta \varphi = -\frac{1}{\epsilon} \vec{\nabla} \cdot \vec{P} & \text{in } \Omega, \\ \Delta \varphi = 0 & \text{in } \mathbb{R}^3 / \Omega. \end{cases} \qquad \Omega = \left\{ (x, y, z) \in \mathbb{R}^3 : |z| \le \frac{d}{2} \right\}$$

Adimensional self-induced polarization is

$$\vec{P} = (\vec{\nabla} \cdot \vec{n})\vec{n} + \frac{e_3}{e_1} \left[\vec{n} \times (\vec{\nabla} \times \vec{n}) \right]$$



Electrostatic potential constraint

- Flexoelectric self-interaction introduces non-locality into minimization problem
- Reformulate problem as unconstrained optimization problem^[12]: minimize the functional

$$F(\varphi) = \frac{1}{2} \int_{\mathbb{R}^3} d^3 x \, |d\varphi|^2 + \frac{1}{\epsilon} \int_{\Omega} d^3 x \, \varphi \left(\vec{\nabla} \cdot \vec{P} \right)$$

- Director \vec{n} is fixed
 - → So is divergence of polarization

$$\vec{\nabla} \cdot \vec{P} = \frac{e_3}{e_1} \left[(\vec{\nabla} \times \vec{n})^2 - \vec{n} \cdot [\vec{\nabla} (\vec{\nabla} \cdot \vec{n})] + \vec{n} \cdot \nabla^2 \vec{n} \right] + (\vec{\nabla} \cdot \vec{n})^2 + \vec{n} \cdot [\vec{\nabla} (\vec{\nabla} \cdot \vec{n})]$$

- Approach: non-linear conjugate gradient method with line search strategy^[13]
- Conjugate stepsize determined using Polak-Ribiere-Polyak method



Arrested Newton flow

- Accelerated gradient descent with flow arresting criteria
- Starting from rest $\partial_t \vec{n}_t|_{t=0} = \vec{0}$
- ullet Solve for motion of a particle in the configuration space under the potential $F_{
 m FFO}$

$$\frac{\mathrm{d}^2}{\mathrm{d}t^2}\vec{n}_t = -\mathrm{grad}_{\vec{n}} \left(F_{\mathrm{FO}} + F_{\mathrm{flexo}} \right) \left[\vec{n}_t \right]$$

- Reduce problem to coupled system of 1st order ODEs
- Solve coupled system simultaneously with 4th order Runge-Kutta method
- Flow arresting: if $F_{\text{FFO}}(t + \delta t) > F_{\text{FFO}}(t) \longrightarrow \text{set } \partial_t \vec{n}(t + \delta t) = \vec{0}$ and restart flow
- Convergence criteria: $||F_{FFO}(\vec{n})||_{\infty} < 10^{-6}$

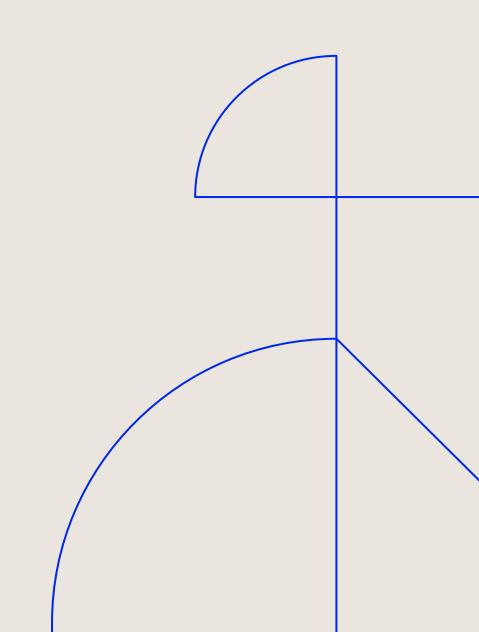


Algorithm summary

- 1. Perform step of ANF method for director field \vec{n} using RK4 method
- 2. Solve Poisson's equation for electric potential φ using NCGD with PRP method
- 3. Compute total energy of the configuration (\vec{n}_i, φ_i) and compare to the energy of the previous configuration $(\vec{n}_{i-1}, \varphi_{i-1})$. If energy has increased, arrest the flow
- 4. Check convergence criteria: $||F_{FFO}(\vec{n})||_{\infty} < 10^{-6}$. If the convergence criteria has been satisfied, then stop the algorithm
- 5. Repeat the process (return to step 1)



Liquid crystal skyrmions





Twist favoured Bloch skyrmions

- In chiral magnets, demagnetizing magnetic potential satisfies $\Delta \psi = -\mu_0 M_s \vec{\nabla} \cdot \vec{n}$
- Dresselhaus DMI favours Bloch skyrmions

$$\vec{n}_{\text{Bloch}}(r,\theta) = \sin f(r)\vec{e}_{\theta} + \cos f(r)\vec{e}_{z}$$

ullet Bloch skyrmions in chiral magnets are solenoidal $ec{
abla}\cdotec{n}_{
m Bloch}=0$

$$\rightarrow \Delta \psi = 0 \Rightarrow F_{\text{flexo}} = 0$$

- Unaffected by magnetostatic self-interaction
- CLCs: Bloch ansatz is solenoidal, associated polarization is not

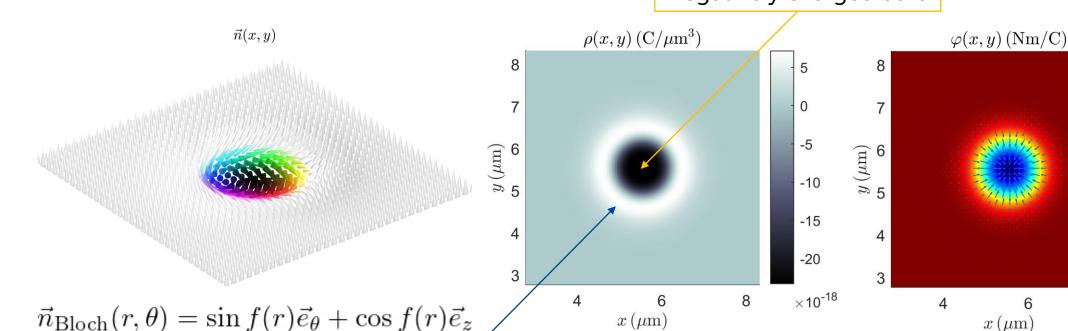
$$\vec{P}_{\text{Bloch}} = \frac{e_3}{e_1} \frac{1}{r} \sin^2 f(r) \vec{e}_r \qquad \longrightarrow \qquad \vec{\nabla} \cdot \vec{P}_{\text{Bloch}} = \frac{e_3}{e_1} \frac{1}{r} \frac{\mathrm{d}f}{\mathrm{d}r} \sin 2f(r) \neq 0$$

→ Bloch skyrmions in liquid crystals are **affected** by electrostatic self-interaction



Twist favoured Bloch skyrmions $(e_1=e_3)$





Outer ring of positive charge

$$\rho = -\vec{\nabla} \cdot \vec{P}_f = \epsilon_0 \Delta \varphi$$

$$\vec{P}_f = e_1 \left[(\vec{\nabla} \cdot \vec{n}) \vec{n} \right] + e_3 \left[\vec{n} \times (\vec{\nabla} \times \vec{n}) \right]$$

-0.1

-0.2

-0.3

-0.4



Splay and bend favoured liquid crystals

- Nematic liquid crystal $F_{\mathrm{FO}}=rac{1}{2}K\int_{\Omega}\mathrm{d}^3x\left\{|\vec{S}|^2+T^2+|\vec{B}|^2
 ight\}$ $\vec{S}=\vec{n}(\vec{\nabla}\cdot\vec{n})$ Splay vector
- Introduce enantiomorphy

 — Chiral (twist favoured) liquid crystal

$$F_{\text{FO}} = \frac{1}{2} K \int_{\Omega} d^3 x \left\{ |\vec{S}|^2 + (T + q_0)^2 + |\vec{B}|^2 \right\}$$

What about splay and bend favoured liquid crystals?

$$F = \frac{K}{2} \int_{\mathbb{R}^3} d^3x \left\{ (\vec{S} + \vec{S}_0)^2 + T^2 + (\vec{B} + \vec{B}_0)^2 \right\}$$

• For convenience, consider $ec{S}_0 = ec{B}_0 = q_0 ec{e}_3$

DMI from Rashba SOC

$$\longrightarrow F = \int_{\mathbb{R}^3} d^3x \left\{ \frac{K}{2} (\nabla \vec{n})^2 + Kq_0 \left[n_z (\vec{\nabla} \cdot \vec{n}) - \vec{n} \cdot \vec{\nabla} n_z \right] + V(\vec{n}) \right\}$$



Splay and bend favoured Néel skyrmions

Adimensional splay and bend favoured liquid crystals

$$F = \int_{\mathbb{R}^2} d^2x \left\{ \frac{1}{2} (\nabla \vec{n})^2 + \left[n_z (\vec{\nabla} \cdot \vec{n}) - \vec{n} \cdot \vec{\nabla} n_z \right] + \frac{1}{q_0^2} \frac{1}{K} V(\vec{n}) + \frac{\epsilon}{2} \varphi \Delta \varphi \right\}$$

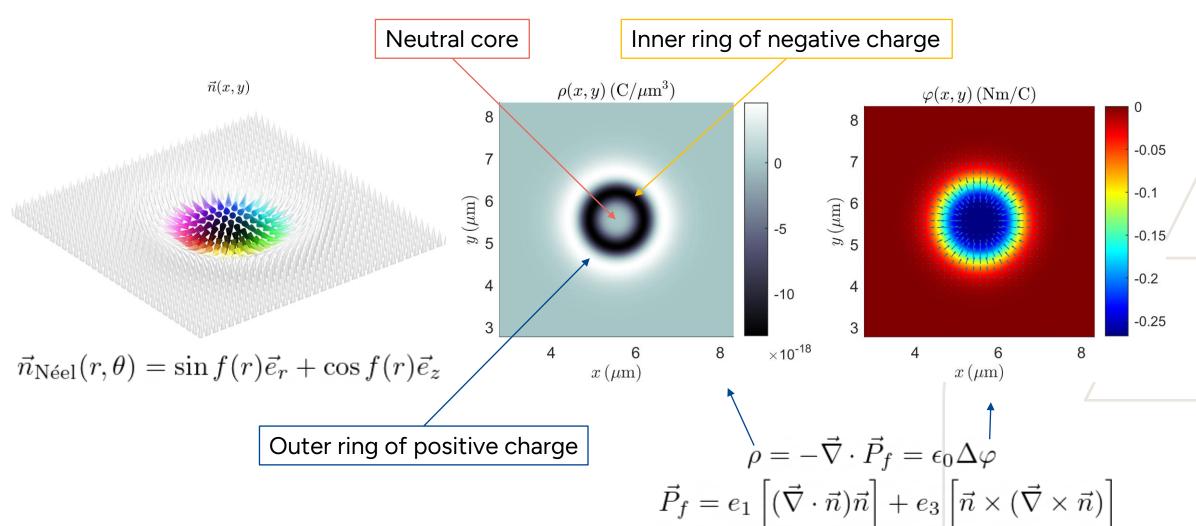
• Rashba DMI term prefers Néel hedgehog skyrmions

$$\vec{n}_{\text{N\'eel}}(r,\theta) = \sin f(r)\vec{e}_r + \cos f(r)\vec{e}_z$$

- Néel polarization picks up out-of-plane component
- Equal flexoelectric coefficients $e_1 = e_3 \Rightarrow \vec{\nabla} \cdot \vec{P}_{\mathrm{Bloch}} = \vec{\nabla} \cdot \vec{P}_{\mathrm{N\'eel}} = \frac{1}{r} \frac{\mathrm{d}f}{\mathrm{d}r} \sin 2f(r)$
- Flexoelectric Bloch and Néel skyrmions equivalent for $e_1=e_3$

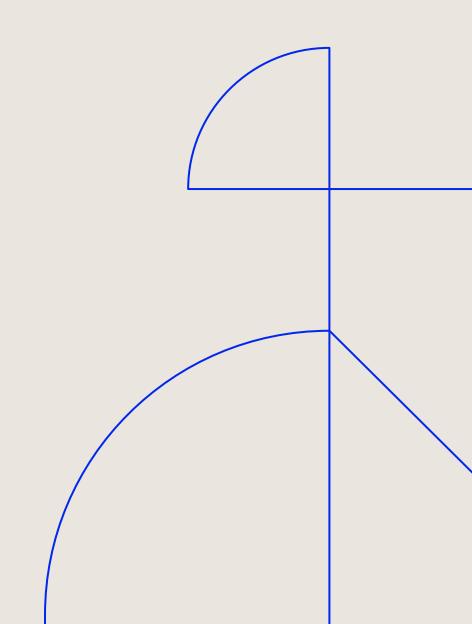


Splay and bend favoured Néel skyrmions $(e_1 < e_3)$





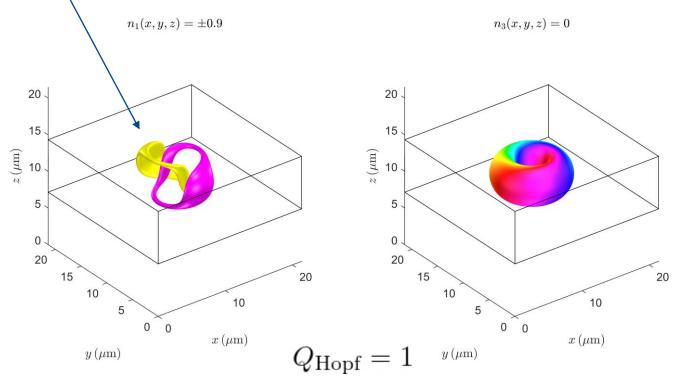
Liquid crystal hopfions





Hopfions

- Can be interpreted as a twisted skyrmion string, forming a closed loop in real space
- They comprise inter-linked closed-loop preimages of constant $ec{n}(x,y,z)$
- **Linking** of closed-loop preimages of anti-podal points in $S^2/\mathbb{Z}_2\cong\mathbb{RP}^2$ defines Hopf index



$$Q_{\text{Hopf}} \in \pi_3(\mathbb{RP}^2) = \pi_3(S^2) = \mathbb{Z}$$



Hopfions

- Explicit Hopf index^[14]: $Q_{\text{Hopf}} = \frac{1}{32\pi^2} \int_{\Omega} d^3x \, \epsilon^{ijk} A_i F_{jk}$
- Introduce vector potential \vec{A} such that $\vec{F_{ij}} = \epsilon^{abc} n_a \partial_i n_b \partial_j n_c = \frac{1}{2} (\partial_i A_j \partial_j A_i)$
- Hopfion ansatz with Hopf index $Q_{\text{Hopf}} = 1^{[15,16]}$:

$$\vec{n}_{\mathrm{Hopf}}(r,\theta,z) = \left(\frac{4r[2z\cos\theta - (r^2+z^2-1)\sin\theta]}{(1+r^2+z^2)^2}, \frac{4r[2z\sin\theta + (r^2+z^2-1)\cos\theta]}{(1+r^2+z^2)^2}, 1 - \frac{8r^2}{(1+r^2+z^2)^2}\right)$$
• Hopfion is not axially symmetric, but is equivariant
$$(n_1 + in_2) \mapsto (n_1 + in_2)e^{i\alpha}$$

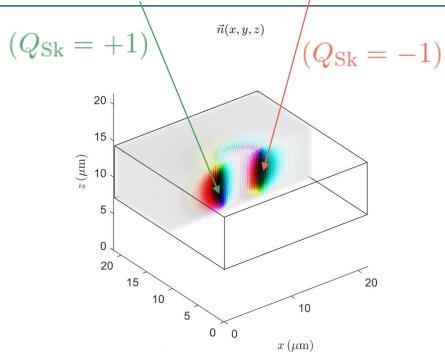
- Spatial rotations $heta\mapsto heta+lpha$ induces rotation in (n_1,n_2) -plane through same angle
- Energy is invariant under **combined** rotations \longrightarrow Energy is axially symmetric

^[15] P. Sutcliffe, Hopfions in chiral magnets, J. Phys. A: Math. Theor. 51 (2018) 375401



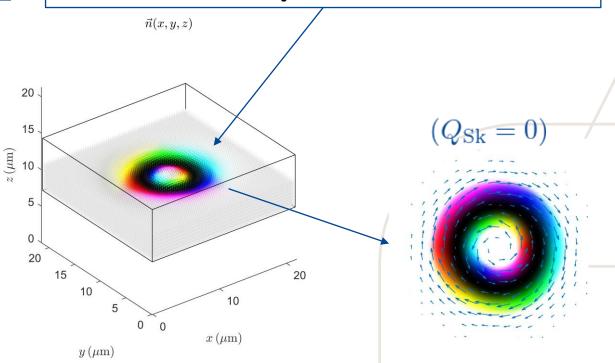
Hopfion structure $(e_1 = e_3 = 4 p \text{Cm}^{-1})$

Skyrmion twisting as it winds around the hopfion core, changing from an in-plane skyrmion to an out-of-plane antiskyrmion



 $y (\mu m)$

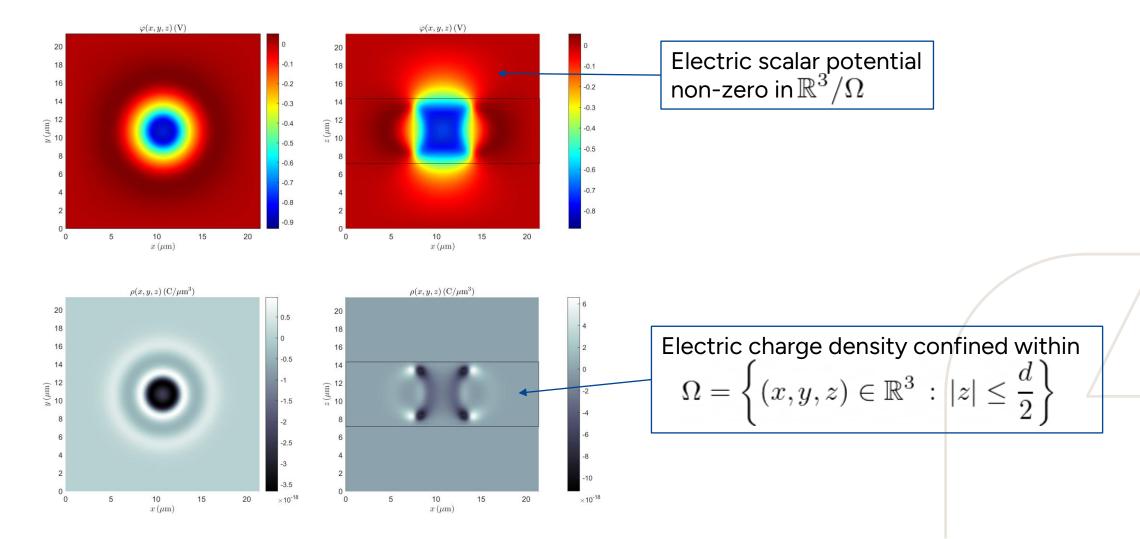
Structure of Bloch skyrmionium or a 2π -vortex^[17]



[17] A. Bogdanov and A. Hubert, The stability of vortex-like structures in uniaxial ferromagnets, J. Magn. Magn. Mater. 195 (1999) 182

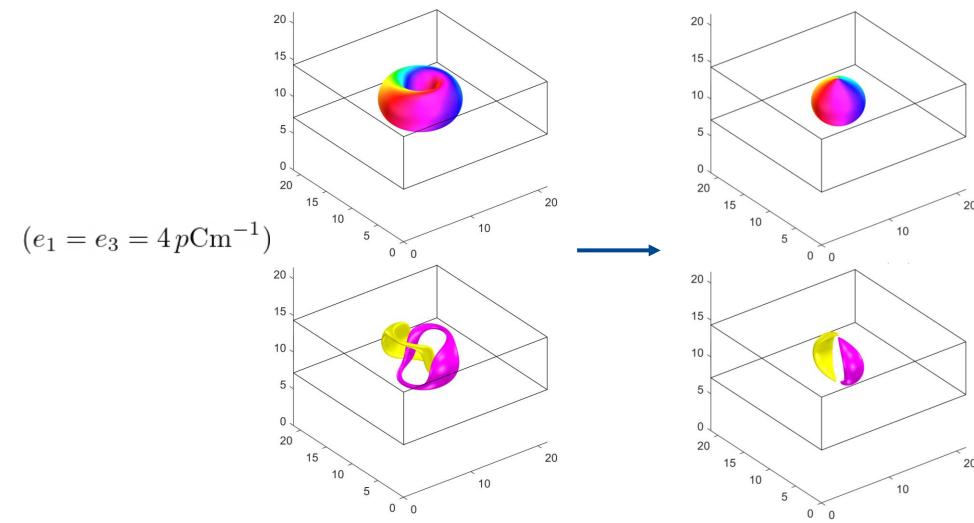


Flexoelectric CLC hopfion $(e_1 = e_3 = 4 p \text{Cm}^{-1})$





Hopfion to skyrmion transition

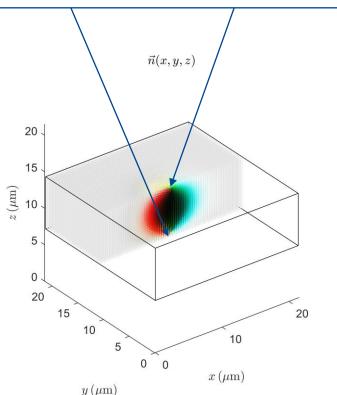


$$(e_1 = e_3 = 8 p \text{Cm}^{-1})$$

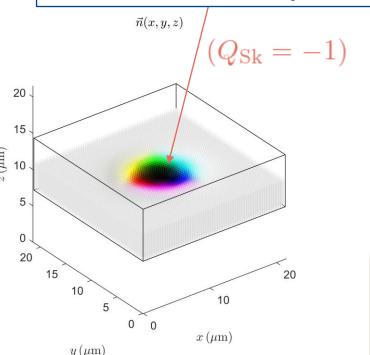


Hopfion — Skyrmion $(e_1 = e_3 = 8 p \text{Cm}^{-1})$

Skyrmion terminating at point defects due to boundary conditions^[18]



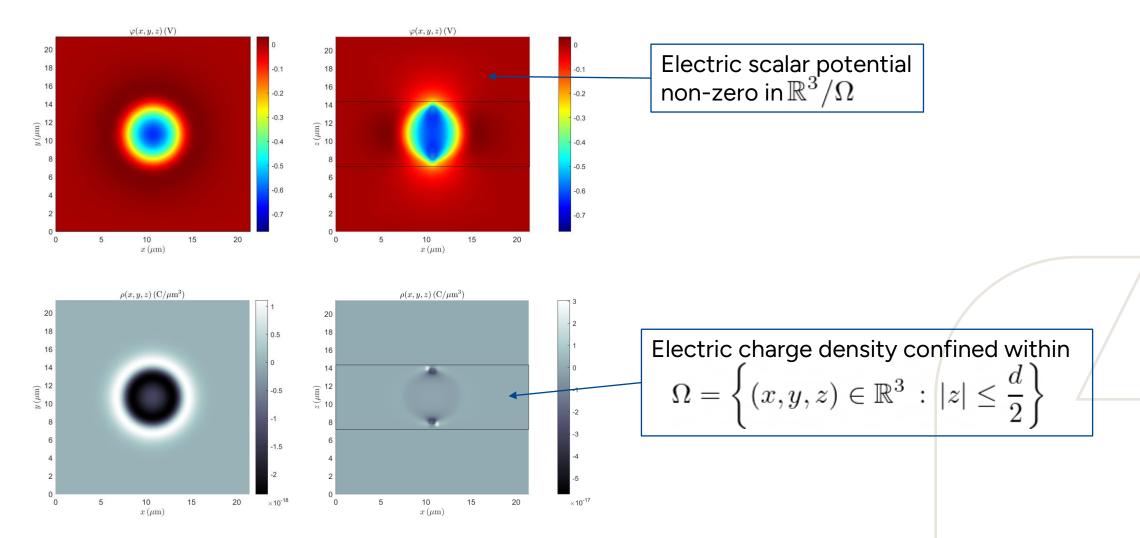
Structure of a Bloch skyrmion



[18] J. B. Tai and I. I. Smalyukh, Surface anchoring as a control parameter for stabilizing torons, skyrmions, twisted walls, fingers, and their hybrids in chiral nematics, Phys. Rev. E **101** (2020) 042702

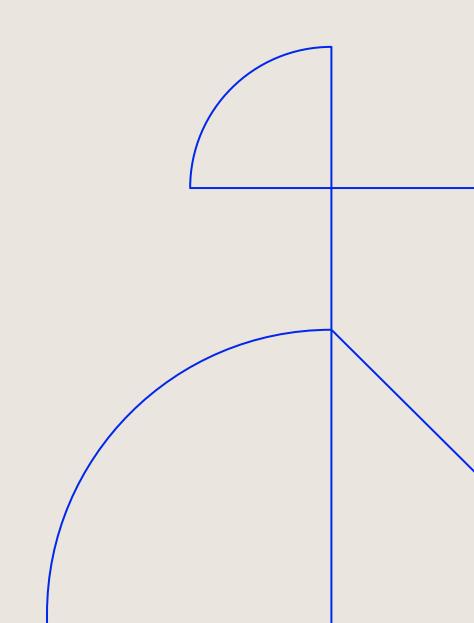


Flexoelectric CLC skyrmion $(e_1 = e_3 = 8 p \text{Cm}^{-1})$





Conclusion





Concluding remarks

- Topological defects induce non-uniform strain
- We have shown how to include the electrostatic self-energy and how to compute the backreaction
- Stray depolarizing field outside thin film included
- Method can be applied 3D skyrmion textures in chiral magnets
- Main differences with chiral magnets (CM):
 - Electric potential depends on divergence of polarization (divergence of magnetization in CM)
 - Electrostatic energy is second order (zeroth order in CM)
 - Bloch skyrmions affected by self-interaction (unaffected in CM)
- Flexoelectric self-interaction can cause hopfion to transition into skyrmion