## 1 Baseline model

This model does not use strategic interactions, and takes place within a perfect information framework.

## 2 Players

This model has two agents: the Firm and the Government.

### 2.1 Firm

The firm is a monopoly, that maximises its profit with respect to its production technology  $g_{F,t}$  and its quantity of good produced q. The firm also receives a subsidy from the Government the less its good is polluting. We define its profit functions as:

$$\pi_{F,t} = q_t \cdot (p - c + s_t \cdot (g_t - g_{F,t}) - \beta (g_t - g_{F,t})^k) \tag{1}$$

Where:

- $\bullet$   $q_t$  is the quantity of good produced and sold at time t
- $p_t$  is the price at which one unit of good is sold
- c is the cost of production of unit of good
- $s_t \in (0,1)$  the share at which the one unit of good is subsidized or taxed (depending on the level of pollution produced per unit) at time t
- $g_t \in \mathbb{R}_+$  is the accepted level of pollution produced by unit of good fixed by the government at time t
- $g_{F,t} \in \mathbb{R}_+$  is the level of pollution created by the production of one unit by the firm at time t
- $\beta \in \mathbb{R}_+$  is the coefficient of Research and Development (RD) cost
- $\bullet$  k > 1 is the difficulty of upgrading the production technology so that it pollutes less

### 2.2 Government

The goal of the government is to maximise the social welfare function. The social welfare function here is defined as a utility function taking into account economic activities and the risk of environmental disaster. We define it as:

$$u_{G,t} = \mathrm{EA}_t^{\alpha} \cdot \mathrm{EQ}_t^{1-\alpha} \tag{2}$$

Where:

- $EA_t$  is the Economic Activity of society at time t
- $EQ_t$  is the Environmental Quality of the world at time t
- $\alpha \in (0,1)$  is the relative importance of Economic Activity compared to the Environmental Quality of the World.

This function has two main properties:

1. It has positive but decreasing returns for both Economic Activity and Environmental Quality:

$$\begin{split} \frac{\partial u_{G,t}}{\partial \mathbf{E} \mathbf{A}_t} &= \alpha \cdot \mathbf{E} \mathbf{A}_t^{\alpha-1} \cdot \mathbf{E} \mathbf{Q}_t^{1-\alpha} > 0 \\ \frac{\partial u_{G,t}}{\partial \mathbf{E} \mathbf{Q}_t} &= (1-\alpha) \cdot \mathbf{E} \mathbf{A}_t^{\alpha} \cdot \mathbf{E} \mathbf{Q}_t^{-\alpha} > 0 \\ \\ \frac{\partial^2 u_{G,t}}{\partial^2 \mathbf{E} \mathbf{A}_t} &= \alpha \cdot (\alpha-1) \cdot \mathbf{E} \mathbf{A}_t^{\alpha-2} \cdot \mathbf{E} \mathbf{Q}_t^{1-\alpha} < 0 \\ \\ \frac{\partial^2 u_{G,t}}{\partial^2 \mathbf{E} \mathbf{Q}_t} &= (1-\alpha) \cdot (-\alpha) \cdot \mathbf{E} \mathbf{A}_t^{\alpha-1} \cdot \mathbf{E} \mathbf{Q}_t^{-\alpha-1} < 0 \end{split}$$

2. Both Economic Activity and Environmental Quality are complementary goods, as the cross-derivative is positive:

$$\frac{\partial^2 u_{G,t}}{\partial \mathbf{E} \mathbf{A}_t \partial \mathbf{E} \mathbf{Q}_t} = \alpha \cdot (1-\alpha) \cdot \mathbf{E} \mathbf{A}_t^{\alpha-1} \cdot \mathbf{E} \mathbf{Q}_t^{-\alpha} > 0$$

# 3 Environment Quality

The environment quality  $EQ_t$  depends on the pollution in nature. We define:

$$EQ_t = (R(X_t) \cdot D(X_t) + d(X_t))^{-1}$$
(3)

$$\begin{cases} X_t \sim AR(1) \\ \iff \\ X_t = \rho \cdot X_{t-1} + P_{F,t} + \varepsilon_t \end{cases}$$
 (4)

Where:

- $R(X_t) \in [0,1]$  the risk of a natural disaster happening at time t
- $D(X_t) \in \mathbb{R}_+$  the potential dammage caused by a natural disaster happening at time t
- $d(X_t) \in \mathbb{R}_+$  the normal dammage caused by pollution at time t

- $X_t \in \mathbb{R}_+$  the total quantity of pollution in nature at time t
- $\rho \in [0, 1]$  the persistence level of pollution in nature
- $P_{F,t} = q_t \cdot g_{F,t}$  the quantity of pollution produced by the firm at time t
- $\varepsilon_t$  a white noise

## 4 Model solution

### 4.1 Firm's problem

In this simplified model, we first solve the Firm's problem for one period :

$$\max_{g_{F,t},q_t} \pi_{F,t} = q_t \cdot (p - c + s(g_t - g_{F,t})) - \beta (g_t - g_{F,t})^k$$

We solve the First Order Conditions. If we derive with respect to the pollution level per unit produced :

$$\frac{\partial \pi_{F,t}}{\partial g_{F,t}} = 0$$

$$\iff \\
-s_t \cdot q_t + \beta \cdot k \cdot (g_t - g_{F,t})^{k-1} = 0$$

$$\iff \\
\beta \cdot k(g_t - g_{F,t})^{k-1} = s_t \cdot q_t$$

$$\iff \\
\left(\frac{s_t \cdot q_t}{\beta \cdot k}\right)^{\frac{1}{k-1}} = g_t - g_{F,t}$$

$$\iff \\
g_{F,t} = g_t - \left(\frac{s_t \cdot q_t}{\beta \cdot k}\right)^{\frac{1}{k-1}}$$
(5)

Then, if we derive with respect to the quantity produced:

$$\frac{\partial \pi_{F,t}}{\partial q_t} = 0$$

$$\iff p - c + s_t \cdot (g_t - g_{F,t}) - \beta \cdot (g_t - g_{F,t})^k = 0$$

$$\iff p = c - s_t \cdot (g_t - g_{F,t}) + \beta \cdot (g_t - g_{F,t})^k$$
(6)

Now if we plug equation (5) into (6) we get:

$$p = c - s_t \cdot \left(g_t - g_t - \left(\frac{s}{\beta \cdot k}\right)^{\frac{1}{k-1}}\right) + \beta \cdot \left(g_t - g_t - \left(\frac{s}{\beta \cdot k}\right)^{\frac{1}{k-1}}\right)^k$$

$$\iff p = c + s_t \cdot \left(\frac{s_t}{\beta \cdot k}\right)^{\frac{1}{k-1}} - \beta \left(\left(\frac{s}{\beta \cdot k}\right)^{\frac{1}{k-1}}\right)^k$$

$$p = c + s_t \cdot \left(\frac{s_t}{\beta \cdot k}\right)^{\frac{1}{k-1}} - \beta \left(\frac{s}{\beta \cdot k}\right)^{\frac{k}{k-1}}$$

$$\Leftrightarrow p = c + s_t^{\frac{k-1}{k-1} + \frac{1}{k-1}} \cdot (\beta \cdot k)^{-\frac{1}{k-1}} - \beta \left(\frac{s}{k-1}\right)^{\frac{k}{k-1}} \cdot \left(\frac{s}{k}\right)^{\frac{k}{k-1}}$$

$$\Leftrightarrow p = c + s_t^{\frac{k}{k-1}} \cdot \left(\beta \cdot k\right)^{-\frac{1}{k-1}} - \beta^{-\frac{1}{k-1}} \cdot \left(\frac{s}{k}\right)^{\frac{k}{k-1}}$$

$$\Leftrightarrow p = c + s_t^{\frac{k}{k-1}} \cdot \left[\left(\beta \cdot k\right)^{-\frac{1}{k-1}} - \beta^{-\frac{1}{k-1}} \cdot \left(\frac{1}{k}\right)^{\frac{k}{k-1}}\right]$$

$$\Leftrightarrow p = c + s_t^{\frac{k}{k-1}} \cdot \beta^{-\frac{1}{k-1}} \cdot \left(k^{\frac{1}{k-1}} - \left(\frac{1}{k}\right)^{\frac{k}{k-1}}\right)$$

$$\Leftrightarrow p = c + \left(\frac{s_t^k}{\beta}\right)^{\frac{1}{k-1}} \cdot \left(k^{\frac{1}{k-1}} - k^{-\frac{k}{k-1}}\right)$$

$$\Leftrightarrow p = c + \left(\frac{s_t^k}{\beta}\right)^{\frac{1}{k-1}} \cdot k^{\frac{1}{k-1}} \cdot \left(1 - k^{-k}\right)$$

$$\Leftrightarrow p = c + \left(\frac{s_t^k}{\beta}\right)^{\frac{1}{k-1}} \cdot \left(1 - k^{-k}\right)$$

Therefore, the maximised profit of the firm will be:

$$\pi_{F,t} = q_t \cdot \left( p - c + s_t \cdot \left( g_t - g_{F,t} \right) - \beta \left( g_t - g_{F,t} \right)^k \right)$$

$$\pi_{F,t} = q_t \cdot \left(c + \left(\frac{s_t^k \cdot k}{\beta}\right)^{\frac{1}{k-1}} \cdot \left(1 - k^{-k}\right) - c + s_t \left[g_t - g_t - \left(\frac{s_t}{\beta \cdot k}\right)^{\frac{1}{k-1}}\right] \right)$$

$$-\beta \left[g_t - g_t - \left(\frac{s_t}{\beta \cdot k}\right)^{\frac{1}{k-1}}\right]^k )$$

$$\iff$$

$$\pi_{F,t} = q_t \cdot \left(\left(\frac{s_t^k \cdot k}{\beta}\right)^{\frac{1}{k-1}} \cdot \left(1 - k^{-k}\right) - s_t \left[\left(\frac{s_t}{\beta \cdot k}\right)^{\frac{1}{k-1}}\right] + \beta \left[\left(\frac{s_t}{\beta \cdot k}\right)^{\frac{1}{k-1}}\right]^k \right)$$

$$\iff$$

$$\pi_{F,t} = q_t \cdot \left(\left(\frac{s_t^k \cdot k}{\beta}\right)^{\frac{1}{k-1}} \cdot \left(1 - k^{-k}\right) - \left(\frac{s_t^k \cdot k}{\beta}\right)^{\frac{1}{k-1}} \cdot \left(1 - k^{-k}\right) \right)$$

$$\iff$$

$$\pi_{F,t} = q_t \cdot 0 \iff \pi_{F,t} = 0 \tag{8}$$

At the optimal, the profit of the firm will be null.

## 4.2 Government problem

In this simplified model, we say that the Economic Activity  $\mathrm{EA}_t$  is equivalent to the profit of the firm. Also, we have the following maximisation program :

$$\max_{s_t,g_t} u_{G,t} = \pi_{F,t}^{\alpha} \cdot \left( R(X_t) \cdot D(X_t) + d(X_t) \right)^{\alpha - 1}$$

subject to:

$$\begin{cases} s_t \left( g_t - g_{F,t} \right) q_t \leq \pi_{F,t} \\ X_t = X_{t-1} + q_t \cdot g_{F,t} + \varepsilon_t \\ X_0 = 0 \end{cases}$$