

```

#include <kipr/wombat.h>
int
main()
int int int int
RF
RR
LF
LR
B :
=
=
// RF is right front wheel
// RR is right rear wheel
// LF is left front wheel
// LR is left rear wheel
printf ("MecanumWheels\n") ;
motor (LF,100) ;motor (RF, 100); motor (LR, 100) ;motor (RR, 100) ; msleep (3000): // Drive
Forward
ao ();
msleep (500): // Pause
motor (LF, 100) ;motor (RF, -100); motor (LR, 100) ;motor (RR, -100) : msleep (500): // Right
Turn
ao ():

```