# 1 Object Relational Programming

## 1. For this problem you can not use arrays.

Consider the relational schema Tree (parent int, child int) representing the schema for storing a rooted tree. A pair of nodes (m, n) is in Tree if m is the parent of n in Tree. Notice that a node m can be the parent of multiple children but a node n can have at most one parent node.

It should be clear that for each pair of different nodes m and n in Tree, there is a unique shortest path of nodes  $(n_1, \ldots, n_k)$  in Tree from m to n provided we interpret the edges in Tree as undirected. A good way to think about this path from a node m to a node n is to first consider the lowest common ancestor node of m of m in Tree. Then the unique path from m to m is the path that is comprised of the path up the tree from m to this common ancestor and then, from this common ancestor, the path down the tree to the node m. (Note that in this path m and m and

Define the distance from m to n to be k-1 if  $(n_1,\ldots,n_k)$  is the unique shortest path from m to n in Tree.

Write a PostgreSQL function distance(m,n) that computes the distance in Tree for any possible pair of different nodes m and n in Tree.

For example, if m is the parent of n in Tree then  $\operatorname{distance}(m,n)=1$  because the shortest path from m to n is (m,n) which has length 1. If m is the grandparent of n in Tree then  $\operatorname{distance}(m,n)=2$  since (m,p,n) is the path from m to n where p is the parent of m and p is a child of n. And if m and n have a common grandparent k then  $\operatorname{distance}(m,n)=\operatorname{distance}(m,k)+\operatorname{distance}(k,n)=4$ , etc.

## 2. For this problem you can use arrays.

Consider the relation schema  $Graph(source\ int,\ target\ int)$  representing the schema for storing a directed graph G of edges.

Now let G be a directed graph that is **acyclic**, a graph without cycles.<sup>2</sup>

A topological sort of an acyclic graph is a list of **all** of its nodes  $(n_1, n_2, \ldots, n_k)$  such that for each edge (m, n) in G, node m occurs before node n in this list.

Write a PostgreSQL program topologicalSort() that returns a topological sort of G.

<sup>&</sup>lt;sup>1</sup>We assume that a tree is a connected graph with a finite number of nodes.

<sup>&</sup>lt;sup>2</sup>A cycle is a path  $(v_0, \ldots, v_k)$  where  $v_0 = v_k$ .

## 3. For this problem, you can not use arrays.

Consider the following relational schemas. (You can assume that the domain of each of the attributes in these relations is int.)

A tuple (p, s, q) is in partSubPart if part s occurs q times as a **direct** subpart of part p. For example, think of a car c that has 4 wheels w and 1 radio r. Then (c, w, 4) and (c, r, 1) would be in partSubpart. Furthermore, then think of a wheel w that has 5 bolts b. Then (w, b, 5) would be in partSubpart.

A tuple (p, w) is in basicPart if basic part p has weight w. A basic part is defined as a part that does not have subparts. In other words, the pid of a basic part does not occur in the pid column of partSubpart.

(In the above example, a bolt and a radio would be basic parts, but car and wheel would not be basic parts.)

We define the aggregated weight of a part inductively as follows:

- (a) If p is a basic part then its aggregated weight is its weight as given in the basicPart relation
- (b) If p is not a basic part, then its aggregated weight is the sum of the aggregated weights of its subparts, each multiplied by the quantity with which these subparts occur in the partSubpart relation.

**Example tables**: The following example is based on a desk lamp with pid 1. Suppose a desk lamp consists of 4 bulbs (with pid 2) and a frame (with pid 3), and a frame consists of a post (with pid 4) and 2 switches (with pid 5). Furthermore, we will assume that the weight of a bulb is 5, that of a post is 50, and that of a switch is 3.

Then the partSubpart and basicPart relation would be as follows:

partSubPart

I		
pid	sid	quantity
1	2	4
1	3	1
3	4	1
3	5	2

basicPart

basici ai t		
pid	weight	
2	5	
4	50	
5	3	

Then the aggregated weight of a lamp is  $4 \times 5 + 1 \times (1 \times 50 + 2 \times 3) = 76$ .

Write a PostgreSQL function aggregatedWeight(p integer) that returns the aggregated weight of a part p.

#### 4. For this problem you need to use arrays.

Consider the relation schema document( $\underline{doc}$  int, words text[]) representing a relation of pairs (d, W) where d is a unique id denoting a document and W denotes the set of words that occur in d.

Let W denote the set of all words that occur in the documents and let t be a positive integer denoting a *threshold*.

Let  $X \subseteq \mathbf{W}$ . We say that X is t-frequent if

$$\operatorname{count}(\{d|(d,W) \in \operatorname{document} \operatorname{and} X \subseteq W\}) \geq t$$

In other words, X is t-frequent if there are at least t documents that contain all the words in X.

Write a PostgreSQL program frequentSets(t int) that returns the set of all t-frequent set.

In a good solution for this problem, you should use the following rule: if X is not t-frequent then any set Y such that  $X \subseteq Y$  is not t-frequent either. In the literature, this is called the Apriori rule of the frequent itemset mining problem. This rule can be used as a pruning rule. In other words, if you have determined that a set X in not t-frequent then you no longer have to consider any of X's supersets.

To learn more about this problem you can visit the site https://en.wikipedia.org/wiki/Apriori\_algorithm.

#### 5. For this problem you can use arrays.

For this problem, first read about the k-means clustering problem in

http://stanford.edu/~cpiech/cs221/handouts/kmeans.html

Look at the k-means clustering algorithm described in this document. Your task is to implement this algorithm in PostgreSQL for a dataset that consists of a set of points in a 2-dimensional space.

Assume that the dataset is stored in a ternary relation with schema

where p is an integer uniquely identifying a point (x, y).

Write a PostgreSQL program kMeans(k integer) that returns a set of k points that denote the centroids for the points in Points. Note that k is an input parameter to the kMeans function.

You will need to reason about how to determine when the algorithm terminates. A possible termination condition is to set a number of iterations that denotes how many iterations are run to approximate the centroids. Another termination condition is to consider when the set of centroids no longer changes.

# 2 Physical Database Organization and Algorithms

6. Consider the following parameters:

block size = 4096 bytes block-address size = 9 bytes

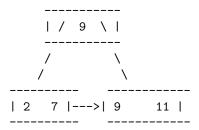
block access time = 10 ms (micro seconds)

record size = 200 bytes record key size = 12 bytes

Assume that there is a  $B^+$ -tree, adhering to these parameters, that indexes  $10^8$  million records on their primary key values.

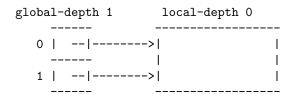
Show all the intermediate computations leading to your answers.

- (a) Specify (in ms) the minimum time to retrieve a record with key k in the B<sup>+</sup>-tree provided that there is a record with this key.
- (b) Specify (in ms) the maximum time to retrieve a record with key k in the B<sup>+</sup>-tree.
- 7. Consider the following B<sup>+</sup>-tree of order 2 that holds records with keys 2, 7, 9, and 11. (Observe that (a) an internal node of a B<sup>+</sup>-tree of order 2 can have either 1 or 2 keys values, and 2 or 3 sub-trees, and (b) a leaf node can have either 1 or 2 key values.)



- (a) Show the contents of your B<sup>+</sup>-tree after inserting records with keys 6, 10, 14, and 4, in that order.
- (b) Starting from your answer in question 7a, show the contents of your B<sup>+</sup>-tree after deleting records with keys 2, 14, 4, and 10, in that order.

8. Consider an extensible hashing data structure wherein (1) the initial global depth is set at 1 and (2) all directory pointers point to the same **empty** block which has local depth 0. So the hashing structure looks like this:



Assume that a block can hold at most two records.

- (a) Show the state of the hash data structure after each of the following insert sequences:<sup>3</sup>
  - i. records with keys 2 and 6.
  - ii. records with keys 1 and 7.
  - iii. records with keys 4 and 8.
  - iv. records with keys 0 and 9.
- (b) Starting from the answer you obtained for Question 8a, show the state of the hash data structure after each of the following delete sequences:
  - i. records with keys 1 and 2.
  - ii. records with keys 6 and 7.
  - iii. records with keys 0 and 9.
- 9. Let R(A,B) and S(B,C) be two relations and consider their natural join  $R\bowtie S.$

Assume that R has 1,500,000 records and that S has 5,000 records.

Furthermore, assume that 30 records of R can fit in a block and that 10 records of S can fit in a block.

Assume that you have a main-memory buffer with 101 blocks.

- (a) How many block IO's are necessary to perform  $R \bowtie S$  using the block nested-loops join algorithm? Show your analysis.
- (b) How many block IO's are necessary to perform  $R \bowtie S$  using the sort-merge join algorithm? Show your analysis.

<sup>&</sup>lt;sup>3</sup>You should interpret the key values as bit strings of length 4. So for example, key value 7 is represented as the bit string 0111 and key value 2 is represented as the bit string 0010.

- (c) Repeat question 9b under the following assumptions.
  - Assume that there are p different B-values and that these are uniformly distributed in R and S.
  - Observe that to solve this problem, depending on p, it may be necessary to perform a block nested-loop join per occurrence of a B-value.
- (d) How many block IO's are necessary to perform  $R \bowtie S$  using the hash-join algorithm? Show your analysis.

# 3 Concurrency Control

- 10. State which of the following schedules  $S_1$ ,  $S_2$ , and  $S_3$  over transactions  $T_1$ ,  $T_2$ , and  $T_3$  are conflict-serializable, and for each of the schedules that is serializable, given a serial schedule with which that schedule is conflict-equivalent.
  - (a)  $S_1 = R_1(x)R_2(y)R_1(z)R_2(x)R_1(y)$ .
  - (b)  $S_2 = R_1(x)W_2(y)R_1(z)R_3(z)W_2(x)R_1(y)$ .
  - (c)  $S_3 = R_1(z)W_2(x)R_2(z)R_2(y)W_1(x)W_3(z)W_1(y)R_3(x)$ .
- 11. Give 3 transactions  $T_1$ ,  $T_2$ ,  $T_3$  and a schedule S on these transactions whose precedence graph (i.e. serialization graph) consists of the edges  $(T_1, T_2)$ ,  $(T_2, T_1)$ ,  $(T_1, T_3)$ ,  $(T_3, T_2)$ .
- 12. Give 3 transactions  $T_1$ ,  $T_2$ , and  $T_3$  that each involve read and write operations and a schedule S that is conflict-equivalent with **all** serial schedules over  $T_1$ ,  $T_2$ , and  $T_3$ .
- 13. Consider the following transactions:

```
T1: read(A);
    read(B);
    if A = 0 then B := B+1;
    write(B).

T2: read(B);
    read(A);
    if B = 0 then A := A+1;
    write(A).
```

Let the consistency requirement be  $\mathtt{A}=0 \vee \mathtt{B}=0,$  and let  $\mathtt{A}=\mathtt{B}=0$  be the initial values.

(a) Show that each serial schedule involving transaction  $T_1$  and  $T_2$  preserves the consistency requirement of the database.

- (b) Construct a schedule on  $T_1$  and  $T_2$  that produces a non-serializable schedule.
- (c) Is there a non-serial schedule on  $T_1$  and  $T_2$  that produces a serializable schedule. If so, give an example.