


Operating System and Design (19CS2106S)**Lab- 11****Pre-Lab****1. Creating and Destroying Mutexes: pthread_mutex_init (mutex,attr)
pthread_mutex_destroy (mutex)**

```
#include <stdio.h>
#include <pthread.h>
int done = 0;
void* worker(void* arg) {
    printf("this should print first\n");
    done = 1;
    return NULL;
}

int main(int argc, char *argv[]) {
    pthread_t p;
    pthread_create(&p, NULL, worker, NULL);
    while (done == 0)
        ;
    printf("this should print last\n");
    return 0;
}
```

 osd-190031187@team-osd:~

```
[osd-190031187@team-osd ~]$ nano t1.c
[osd-190031187@team-osd ~]$ gcc t1.c -lpthread
[osd-190031187@team-osd ~]$ ./a.out
this should print first
this should print last
[osd-190031187@team-osd ~]$ █
```

2. Locking and Unlocking Mutexes: pthread_mutex_lock (mutex) pthread_mutex_trylock (mutex)


```
#include <stdio.h>
#include <pthread.h>

typedef struct __synchronizer_t {
    pthread_mutex_t lock;
    pthread_cond_t cond;
```

```

    int done;
} synchronizer_t;
synchronizer_t s;
void signal_init(synchronizer_t *s) {
    pthread_mutex_init(&s->lock, NULL);
    pthread_cond_init(&s->cond, NULL);
    s->done = 0;
}
void signal_done(synchronizer_t *s) {
    pthread_mutex_lock(&s->lock);
    s->done = 1;
    pthread_cond_signal(&s->cond);
    pthread_mutex_unlock(&s->lock);
}
void signal_wait(synchronizer_t *s) {
    pthread_mutex_lock(&s->lock);
    while (s->done == 0)
        pthread_cond_wait(&s->cond, &s->lock);
    pthread_mutex_unlock(&s->lock);
}
void* worker(void* arg) {
    printf("this should print first\n");
    signal_done(&s);
    return NULL;
}
int main(int argc, char *argv[]) {
    pthread_t p;
    signal_init(&s);
    pthread_create(&p, NULL, worker, NULL);
    signal_wait(&s);
    printf("this should print last\n");
    return 0;
}

```

 osd-190031187@team-osd:~

```

[osd-190031187@team-osd ~]$ nano lockthread.c
[osd-190031187@team-osd ~]$ gcc lockthread.c -lpthread
[osd-190031187@team-osd ~]$ ./a.out
this should print first
this should print last
[osd-190031187@team-osd ~]$ █

```

3. Synchronizing Threads with POSIX Semaphores: sem_init, sem_open sem_wait sem_post sem_getvalue sem_destroy

Semaphores:

Semaphores are used for process and thread synchronization. Semaphores are clubbed with message queues and shared memory under the Interprocess Communication (IPC) facilities in Unix-like systems such as Linux.

sem_init

```
#include <semaphore.h>
```

```
int sem_init (sem_t *sem, int pshared, unsigned int value);
```

sem_init is the equivalent of sem_open for unnamed semaphores. One defines a variable of type sem_t and passes its pointer as *sem* in the sem_init call.

sem_open

```
#include <fcntl.h>
```

```
#include <sys/stat.h>
```

```
#include <semaphore.h>
```

```
sem_t *sem_open (const char *name, int oflag);
```

```
sem_t *sem_open (const char *name, int oflag,  
                 mode_t mode, unsigned int value);
```

sem_open is the call to get started for a semaphore. sem_open opens an existing semaphore or creates a new semaphore and opens it for further operations.

sem_post

```
#include <semaphore.h>
```

```
int sem_post (sem_t *sem);
```

sem_post increments the semaphore. It provides the V operation for the semaphore. It returns 0 on success and -1 on error.

sem_wait

```
#include <semaphore.h>
```

```
int sem_wait (sem_t *sem);
```

sem_wait decrements the semaphore pointed by *sem*. If the semaphore value is non-zero, the decrement happens right away. If the semaphore value is zero, the call blocks till the time semaphore becomes greater than zero and the decrement is done. sem_wait returns zero on success and -1 on error.

sem_getvalue

```
#include <semaphore.h>
```

```
int sem_getvalue (sem_t *sem, int *sval);
```

sem_getvalue gets the value of semaphore pointed by *sem*. The value is returned in the integer pointed by *sval*. It returns 0 on success and -1 on error, with *errno* indicating the actual error.

sem_destory

```
#include <semaphore.h>
```

```
int sem_destroy (sem_t *sem);
```

sem_destroy destroys the unnamed semaphore pointed by sem.

In-Lab

1. Illustrate how mutex is used for thread synchronization, print the counter variable upon each increment which is in the critical section. (Two threads update a global shared variable with and without synchronization).

```
#include <pthread.h>

static volatile int glob = 0; /* "volatile" prevents compiler optimizations
                               of arithmetic operations on 'glob' */
static void *      /* Loop 'arg' times incrementing 'glob' */
threadFunc(void *arg)
{
    int loops = *((int *) arg);
    int loc, j;

    for (j = 0; j < loops; j++) {
        loc = glob;
        loc++;
        glob = loc;
    }
    return NULL;
}

int
main(int argc, char *argv[])
{
    pthread_t t1, t2;
    int loops, s;
    loops = strtol(argv[1], NULL, 10);
    s = pthread_create(&t1, NULL, threadFunc, &loops);
    if (s != 0){
        perror("pthread_create fail");
        exit(1);}
    s = pthread_create(&t2, NULL, threadFunc, &loops);
    if (s != 0){
        perror("pthread_create fail");
        exit(2);}

    s = pthread_join(t1, NULL);
    if (s != 0){
        perror("pthread_join fail");
        exit(1);}
    s = pthread_join(t2, NULL);
    if (s != 0){
        perror("pthread_join fail");
        exit(1);}

    printf("glob = %d\n", glob);
}
```

```
    exit(0);  
}
```

 osd-190031187@team-osd:~

```
[osd-190031187@team-osd ~]$ nano thread_mutex.c  
[osd-190031187@team-osd ~]$ gcc thread_mutex.c -lpthread  
[osd-190031187@team-osd ~]$ ./a.out 500  
glob = 1000  
[osd-190031187@team-osd ~]$ ./a.out 5000  
glob = 10000  
[osd-190031187@team-osd ~]$ ./a.out 5000000  
glob = 10000000  
[osd-190031187@team-osd ~]$ █
```

2. Write a UNIX system program to implement concurrent Linked List

```
#include <stdio.h>  
#include <stdlib.h>  
#include <pthread.h>  
typedef struct __node_t {  
    int      key;  
    struct __node_t  *next;  
} node_t;  
// basic list structure (one used per list)  
typedef struct __list_t {  
    node_t *head;  
    pthread_mutex_t lock;  
} list_t;  
  
void List_Init(list_t *L) {  
    L->head = NULL;  
    pthread_mutex_init(&L->lock, NULL);  
}  
  
void List_Insert(list_t *L, int key) {  
    // synchronization not needed  
    node_t *new = malloc(sizeof(node_t));  
    if (new == NULL) {  
        perror("malloc");  
        return;  
    }  
    new->key = key;  
  
    // just lock critical section  
    pthread_mutex_lock(&L->lock);  
    new->next = L->head;  
    L->head = new;
```

```

        pthread_mutex_unlock(&L->lock);
    }
    int List_Lookup(list_t *L, int key) {
        int rv = -1;
        pthread_mutex_lock(&L->lock);
        node_t *curr = L->head;
        while (curr) {
            if (curr->key == key) {
                rv = 0;
                break;
            }
            curr = curr->next;
        }
        pthread_mutex_unlock(&L->lock);
        return rv; // now both success and failure
    }
    void List_Print(list_t *L) {
        node_t *tmp = L->head;
        while (tmp) {
            printf("%d ", tmp->key);
            tmp = tmp->next;
        }
        printf("\n");
    }
    int main(int argc, char *argv[])
    {
        list_t mylist;
        List_Init(&mylist);
        List_Insert(&mylist, 10);
        List_Insert(&mylist, 30);
        List_Insert(&mylist, 5);
        List_Print(&mylist);
        printf("In List: 10? %d 20? %d\n",
            List_Lookup(&mylist, 10), List_Lookup(&mylist, 20));
        return 0;
    }

```

 osd-190031187@team-osd:~

```


[osd-190031187@team-osd ~]$ nano concurrent_list.c
[osd-190031187@team-osd ~]$ gcc concurrent_list.c -lpthread
[osd-190031187@team-osd ~]$ ./a.out
5 30 10
In List: 10? 0 20? -1
[osd-190031187@team-osd ~]$ ./a.out;./a.out
5 30 10
In List: 10? 0 20? -1
5 30 10
In List: 10? 0 20? -1
[osd-190031187@team-osd ~]$ █

```

Post-Lab

1. Write a Unix System program to make A Parent Waiting for Its Child using semaphores.

```
#include <stdio.h>
#include <unistd.h>
#include <pthread.h>
#include <semaphore.h>
sem_t done;
void *
child(void *arg) {
    sleep(5);
    printf("child\n");
    sem_post(&done);
    return NULL;
}
int
main(int argc, char *argv[]) {
    pthread_t p;
    printf("parent: begin\n");
    sem_init(&done, 0, 0);
    pthread_create(&p, NULL, child, NULL);
    sem_wait(&done);
    printf("parent: end\n");
    return 0;
}
```

 osd-190031187@team-osd:~

```
[osd-190031187@team-osd ~]$ nano semaphore.c
[osd-190031187@team-osd ~]$ gcc semaphore.c -lpthread
[osd-190031187@team-osd ~]$ ./a.out
parent: begin
child
parent: end
[osd-190031187@team-osd ~]$
```