Pavan R Vasishta

Curriculum Vitae

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May 27th, 1991

Professional Experience

March 2020 –	**Postdoctoral Researcher**, *ENSTA ParisTech*, Paris, France. Behaviour prediction of shared space users around autonomous vehicles for risk estimation; Anomaly detection in warehousing robot operations (With Magazino GmbH); Terrain adaptation and transfer learning for multi-legged robots (with GoodAI)
Feb 2016 – Sept 2019	**Doctoral Researcher**, *Inria Grenoble*, Grenoble, France. Trajectory prediction of pedestrians and risk estimation for Autonomous Vehicles in Urban Environments
February 2015–August 2015	**Student Intern**, *Institute de Recherche Technologique (IRT Jules Verne)*, Nantes, France. Implementation of a control strategy using multiple sensors for the UR10 Robot for safer operation around human workers in an industrial setting.
June 2012–July 2013	**Associate Software Engineer**, *Robert Bosch Engineering and Business Solutions Pvt. Ltd.*, Bangalore,India. Worked on Automotive Embedded Programming based on AUTOSAR standard and working experience with CAN and Flexray and AUTOSAR Diagnostic Modules
June 2011–August 2011	**Student Intern**, *iRobot India (Pvt.) Ltd.*, Mysore,India. Module design, fabrication, Programming a USB hub and microcontrollers for creating a gaming controller interface for the 210Negotiator robot.

Skills

Programming	Python, C++, PyCUDA, C, Matlab, Git/SVN, Latex
Packages	Scikit, Pandas, OpenCV, ROS, Gazebo, PyTorch
Strengths	Deep Reinforment Learning, Transfer Learning, Image Analysis, Probabilistic Prediction, Anomaly Detection, Machine Learning, Self Organising Networks, Pedestrian Behaviour, Deep Learning
Languages	English (Native), Kannada (Maternal), Hindi (Fluent), French (Intermediate)
Reviewer	RA-L'2020, ITS'2020, ITSC'18, IV'18, PPNIV- IROS'17
Experience with:	AUTOSAR development, AUTOSAR tools, scripting diagnostic tests. Embedded systems such as Intel 8051, AVR, PIC16, PIC32, Raspberry Pi, Infineon TriCore 27xx series, Freescale MPC 5675K, Renesas NEC V850.

Education

Feb 2016 – Sept 2019	**PhD in Mathematics and Informatics**, *Inria - Universite Grenoble Alpes*, Grenoble, France.
Sept 2013 – Sept 2015	**Master of Science in Control Engineering, Robotics and Applied Informatics - Advanced Robotics**, *Ecole Centrale de Nantes*, Nantes,France, *(2 Years)*.
Jul 2012 – Dec 2012	**Proficience Course in Intelligent Agents**, *part-time*, *Indian Institute of Science*, Bangalore,India, *(6 Months)*.
Sept 2008 – Jun 2012	**Bachelor of Engineering in Electrical and Electronics Engineering**, *The National Institute of Engineering*, Mysore,India, *(4 Years)*.

▬▬ Awards and Academic Affiliations

Award	**Best Student Paper** at The 15th International Conference on Control, Automation, Robotics and Vision (ICARCV), 2018
Award	**Funding** from the Dept. of Science and Technology, Govt. of India through the Innovation and Entrepreneurship Development Cell for the project "Semi-Automated Wheelchair"
Affiliation	Member, IEEE Intelligent Transportation Society
Affiliation	Vice Chairman of the National Institute of Engineering IEEE Student Branch
Affiliation	Campus Ambassador for IBM University Relations, India
Affiliation	Member of ONYX, the institutional branch of the National Entrepreneurship Network, India
Affiliation	Core Committee member of the National Institute of Engineering Literary Club

▬▬ PhD Thesis

Feb 2016 - Sept 2019	**Building and Leveraging Prior Knowledge for Predicting Pedestrian Behaviour Around Autonomous Vehicles in Urban Environments**.
	PhD carried out under Dr.Anne Spalanzani and Dr.Dominique Vaufreydaz at Inria Grenoble in the CHROMA team. The thesis deals with understanding and predicting pedestrian behaviour in urban areas for safer navigation of autonomous vehicles. The thesis focuses on using sociological ideas like *Natural Vision* as a basis for using probabilistic methods to predict pedestrian behaviour in urban areas. The thesis has been financed by an ANR (*French National Research Agency*) grant for a collaborative project involving the research labs Inria Grenoble, Inria Paris, LS2N and the industrial partner AKKA. *Keywords: Markov Models, Potential Fields, Situational Awareness, Pedestrian Behaviour Prediction*

▬▬ Selected Publications

Oct 2017	**Natural Vision Based Method for Predicting Pedestrian Behaviour in Urban Environments**, *IEEE 20th International Conference on Intelligent Transportation Systems(ITSC)*, Yokohama.
Sept 2017	**Urban Pedestrian Behaviour Modelling using Natural Vision and Potential Fields**, *9th Workshop on Planning, Perception and Navigation for Intelligent Vehicles at the IEEE International Conference on Intelligent Robots and Systems*, Vancouver.
Nov 2018	**Building Prior Knowledge: A Markov Based Pedestrian Prediction Model Using Urban Environment Data**, *The 15th International Conference on Control, Automation, Robotics and Vision (ICARCV)*, Singapore.