```
import cv2
import numpy as np
import pyautogui

low_green = np.array([25, 52, 72])
high_green = np.array([102, 255, 255])

cap = cv2.VideoCapture(0)
prev_y = 0

while True:
    ret, frame = cap.read()
    hsv = cv2.cvtColor(frame, cv2.COLOR_BGR2HSV)
    mask = cv2.inRange(hsv, low_green, high_green)
    contours, _ = cv2.findContours(mask, cv2.RETR_EXTERNAL, cv2.CHAIN_APPROX_SIMPLE)

    for i in contours:
        area = cv2.contourArea(i)
        if area > 1000:
            x, y, w, h = cv2.boundingRect(i)
            cv2.rectangle(frame, (x, y), (x+w, y+h), (0, 255, 0), 2)
            if y < prev_y:
                pyautogui.press('space')  # You can change 'space' to 'down' or 'up'
            prev_y = y

    cv2.imshow('frame', frame)
    if cv2.waitKey(1) == ord('q'):
        break

cap.release()
cv2.destroyAllWindows()
```