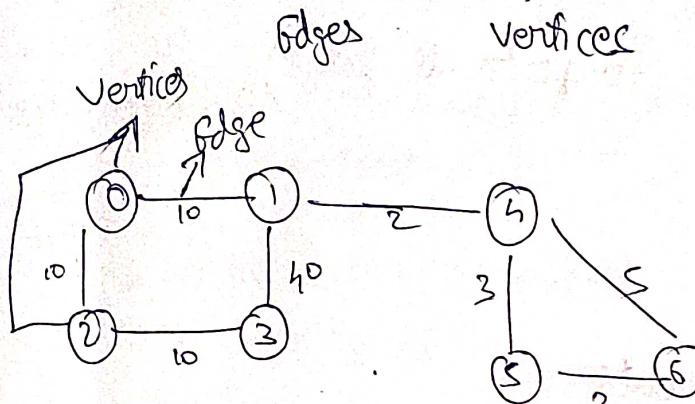


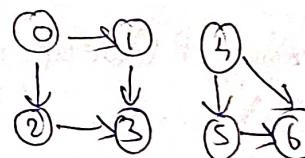
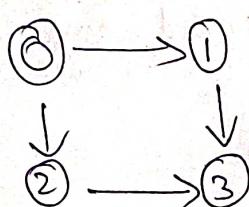
APR 24

## Graphs

All trees are directed and acyclic graphs and connected



Undirected graph & weighted



Directed graph & Unweighted

$10^3 \Rightarrow 10^6$  vertices space  
Max. Space you can use is  $10^5$

Types in graph

- \* Directed Graph
- \* Undirected Graph
- \* Weighted graph
- \* Unweighted graph

Variation in question

\* path

\* group

\* cyclic

\* MST Prufer's algo  
Kruskal's algo

\* matrix [1, 1, 1, 1, 1, 1] (Top, bottom, left, right)

Construction in graph

\* Adjacency Matrix

\* Adjacency List

\* Hashmap

Construction using Adjacency List

$N_1 - V_2 @ wt$

$V_2 - V_1 @ wt$

src nbr

Has Path

\* DFS Approach, visited

\* No need to change visited of src to false, (No need to backtrack)

because from src  $\rightarrow$  DFS will allow you to travel completely. (dest. connector not connected)

so no need to make false and try another path to check. Check video for clarity.

$V \rightarrow$  Vertices

$E \rightarrow$  Edges

TC  $O(VE)$

$E \rightarrow V^2$   
Intuition of V  
TC  $O(V^3)$

## Printpath

- \* Make a DFS travel
- \* Have to backtrack (to go to all paths).

## Multisolver

- \* Travel DFS
- \* Find find requirements
- \* For  $k^{th}$  largest, used floor logic 'k' times to find  $k^{th}$ 
  - ↳ After learning P. Queue, or implement using P.Q for  $k^{th}$ )

## Get Connected components

- \* Have a visited arr.
- \* Make a DFS at every vertex from visited arr.
  - ↳ Travel and collect components only if vertex is unvisited.
  - ↳ Else ignore and move forward.

## Is Graph connected

App 1: Get all connected components. If size of ~~collected~~ all collected connected comps = 1, then connected, else not connected

App 2: Make a DFS from a single vertex.  
Maintain a visited array (Don't backtrack here).  
Loop on visited, if any vertex is not visited, then not connected, else connected,

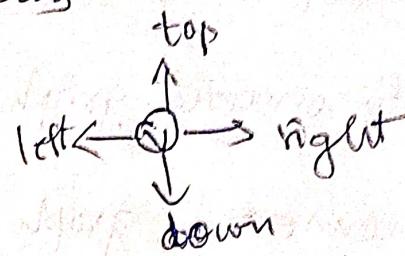
→ You can get ~~no~~ number of connected components by BFS as well,  
just use a counter.)

## Number of Islands

Inques. Application of Connected components

- \* Make dfs from every point moving to its neighbours (top, left, down, right).

In matrix, every element represents a matrix having neighbours at top, left, down, right.



(top, left, down, right),

In interviews, sometimes even diagonal can be said as neighbours. So be prepared to tackle it.

## Perfect friends

- \* Get all connected components first

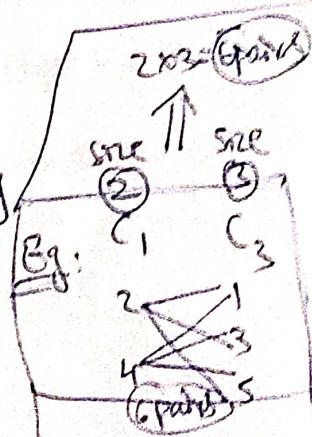
$$\text{ConnComps} = [C_1, C_2, C_3, C_4]$$

- \* Then find pairs from it by pairing calculate it with each.

Eg:

- \* No. of pair two conn comp can make,

$$\text{pairs} = C_1.\text{size} \times C_2.\text{size}$$



- \* Like this map every component with each other.

## Hamiltonian Path and Cycle: (Use path so far logic)

Hamiltonian path: when you can visit all vertex ~~on~~ of graph only once. ~~you cannot back track~~

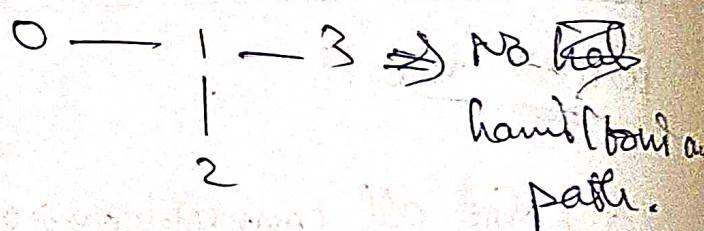
Hamiltonian cycle: when first vertex and the last vertex has a direct edge.

Hamiltonian path & cycle can be applied only on

connected graphs. There is no point of finding

→ HPC on disconnected graphs.

Not all connected graph have ~~has~~ hamiltonian path. e.g.  $\Rightarrow$



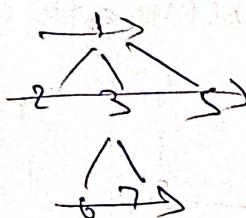
Generic tree is a special type of graph.

- \* Connected
- \* Directed (parent to child)
- \* No cycle

## Trees

- \* Pre, post, In (recursion)

- \* Level order



a) normal level order:

1 2 3 5 6 7

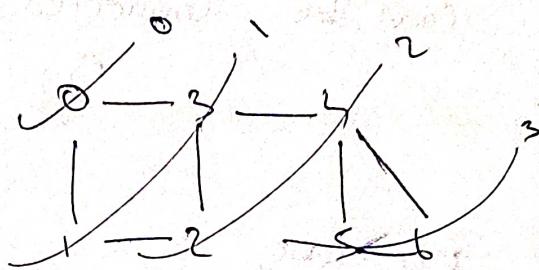
b) level order otherwise

1  
2 3 5  
6 7

## Graphs

- \* Depth first traversal (DFS) (recursion)

- \* Breadth first traversal (BFS)

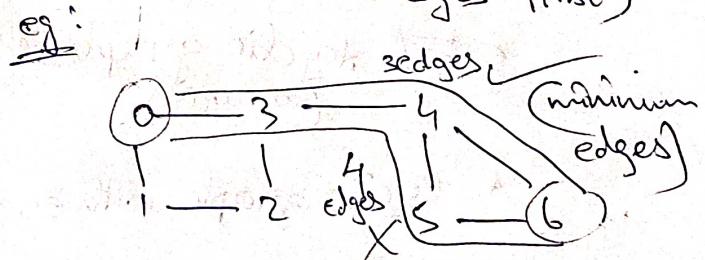


a) normal level order: 0 1 3 2 4 5 6

b) level order otherwise:

0 (0 edges far from src)  
1 3 (1 edges far)  
2 5 (2 edges far)  
4 6 (3 edges far)

(∴ This BFS takes vertex of minimum edges first)



BFS of graph! Use queue

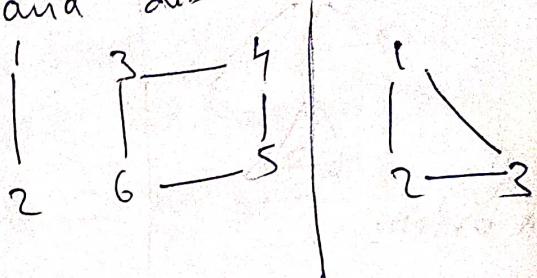
- \* Remove
- \* Mark
- \* Work
- \* add nbrs (unvisited)

If visiting already visited node after removal, then just ignore.

## Is Graph cyclic

If there is any cycle (even one), then it is cyclic. If any component of graph has cycle, then it is cyclic. Here graph can be connected and disconnected components.

Eg:



\* Use BFS

\* Using DFS,  $\Rightarrow$  for every visited vertex 'v'  
 (Refer GFG) if there is an adjacent 'u' such that u is already visited and u is not parent of v, then there is a cycle in graph

Ref

## Is Graph Bipartite

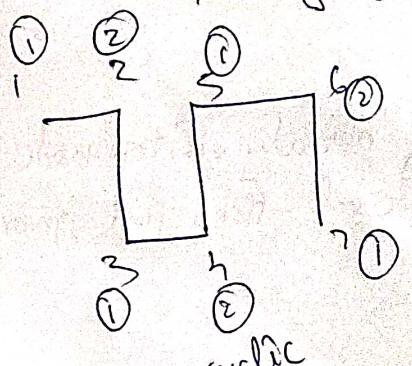
More graph can be connected or disconnected as well

\* All vertices edge must be across the sets.

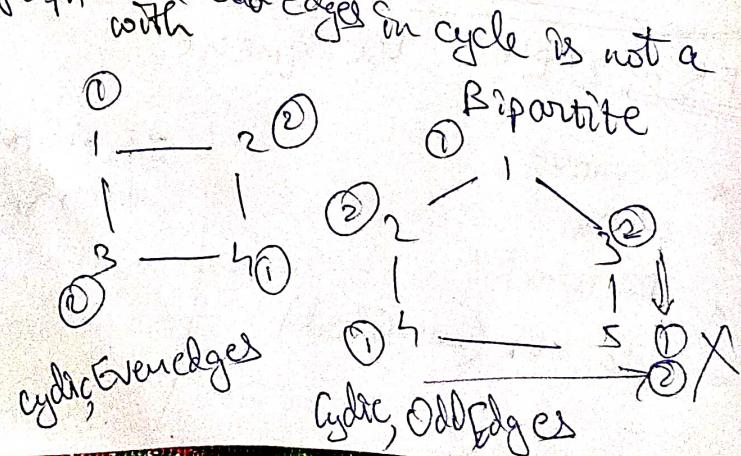
\* ~~A~~ Acyclic graph is a Bipartite graph.  
 (non-cyclic)

\* Cyclic graph with even edges <sup>in cycle</sup> is a Bipartite

\* Cyclic graph with odd edges in cycle is not a



Non-cyclic



cyclic, Even edges

cyclic, Odd edges

- \* All components has to be bipartite, for a graph to be bipartite

\* Apply BFS

### Spread of Infection

\* Apply BFS

- \* Doesn't matter if we have disconnected components  
Because anyways we won't be reaching that vertex from our source)

compareTo()

+ve  $\rightarrow$  this > other

-ve  $\rightarrow$  this < other

0  $\rightarrow$  this = other

(If +ve value, do some work)

### Dijkstra's Algo (Shortest Path in weights)

- \* Single source to all dest.

\* Work only for positive weights

- \* Use Priority Queue (BFS)

### Minimum Spanning Tree

Minimum wt  
Minimum wire to connect all  
(Prim's Algo) PCs

i) Acyclic, connected graph is a tree

ii) to travel all the vertices (Span)

iii) Use Priority Queue (all vertices should be included).

Here we try to break cycle, & we break cycle by removing the heavier edge wt.

(BFS)

(Dijkstra's)  $\rightarrow$  Competition in path  
Prim's (MST)  $\rightarrow$  Competition in edges

Prim's

Dijkstra's

\* Src doesn't matter  
you will have the  
same MST from  
any source

→ Edges  $\rightarrow$

\* wt.

\* Src matters to travel  
path

→ Path ~~wf~~

\* wf

Topological sort: DAG

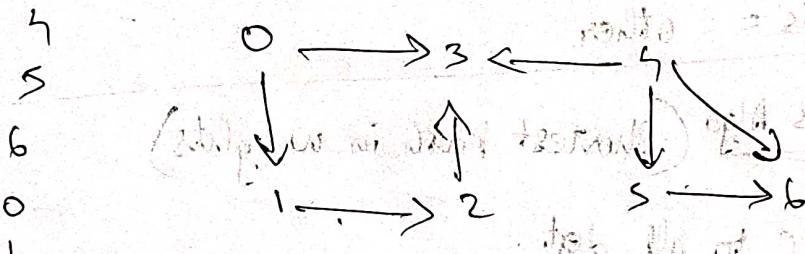
(This can be applied  
only on DAG)

(Directed Acyclic graph)

Valid T.S

(graph)

Acyclic



Topological sort: A permutation of all vertices

such that for all edges of type  $u \rightarrow v$ ,

$u$  should always come before  $v$ .

Order of work or compilation is opposite of topological sort i.e.; T.S.  $u \rightarrow v$  ( $u$  is dependent on  $v$ )

T.S | 0 1 2 3 4 5  
---+-----  
5 | 3  
4 | 2  
3 | 1  
2 | 0  
1 | 6  
0 | 5

In order of compilation; since  $u$  is dependent on  $v$ , so  $v$  must be complete ~~before~~ before  $u$ .

→ USE Stack & DFS travel

(A graph can have more than one topological order It's just that the T.S condition has to be satisfied)

- \* Topological sort  $\rightarrow$  Push in stack (post order)
- \* Order of compilation  $\rightarrow$  Print directly (post order)

### Iterative Depth First Search:

Replace BFS Queue with stack & follow  
BFS Algo pattern.

As a result you will travel in DFS  
(Reverse order)

DFS Order ~~of~~ doesn't matter in graph. The point  
travel <sup>Euler</sup>

as you have to travel unlike trees

④ this approach can be used in trees as well <sup>output</sup> ~~post~~ <sup>post</sup> in reverse  
~~Euler order~~