

Intro :- Unit :- 1 megapixels = 10^6 pixels
 FPS = frames per second

09/08/2023

Computer Graphics:- Computer graphics are the graphics created using computer and the representation of image data by a computer specifically with help from specialized graphic hardware and software.

★ Uses of Computer graphics :-

- ↳ CAD (Computer Aided Design)
- ↳ Presentation graphics ↳ Computer art
- ↳ Entertainment industry ↳ Visualization
- ↳ Education & training ↳ GUI creation
- ↳ Image processing ↳ I/O devices

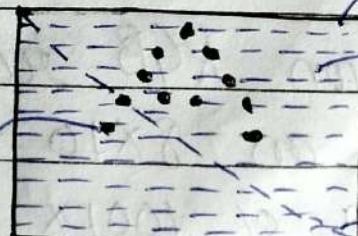
⇒ Cathode Ray Tube (CRT)

⇒ Aspect ratio = $\frac{\text{No. of horizontal lines (Pixel)}}{\text{No. of vertical lines (Pixel)}}$

• Persistence

⇒ Raster Scan :-

Line grows at some point when they needed

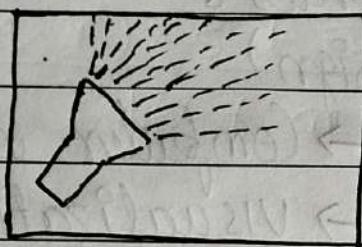


line by line
 → Scanning
 Horizontal retrace
 Vertical retrace

→ It also helps in refresh buffer (one to one mapping)

⇒ Interlaced Tracing System :- It traces alternatively like firstly it traces all odd lines then even lines and then combine it.

⇒ Random Scan System :-



Information can store in display buffer in the form of commands

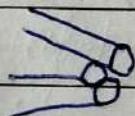
Color CRT monitor :-

→ Beam penetration → shadow masking

(Used with random scan monitors) (Used with raster scan system)

⇒ Two methods :- (in shadow masking)

↳ Delta-Delta method ↳ In-line method



(R) (G) (B)

(Ans) Suppose an RGB raster system is to be design on 8x10 inch screen with a resolution of 100px per inch in each direction. If we want to store 6 bits

per pixel in the frame buffer. How much storage in bytes do we need in the frame buffer.

Soln

$$8 \boxed{10} \Rightarrow 8 \times 10 \text{ entries}$$

$\therefore 8 \text{ bits} = 1 \text{ byte}$

$$\Rightarrow \text{No. of pixels} = 8 \times 10 \times 100 \times 100$$

$$\Rightarrow \text{Total no. of bits} = 8 \times 10 \times 100 \times 100 \times 6$$

$$\Rightarrow \text{for one frame} = 600000 \quad \text{ans/}$$

(Ques2) How long would it take to load a 640×480 frame buffer with 12 bits per px. If 10^5 bits can be transferred per s.

Soln $\Rightarrow \text{Total no. of bits} = 640 \times 480 \times 12$

$$\Rightarrow 1 \text{ sec} = 10^5 \text{ bits transferred.}$$

then,

$$\Rightarrow \text{Time to load one frame buffer} = \frac{640 \times 480 \times 10^5}{10^5}$$

$$\Rightarrow 36.864 \text{ seconds.} \quad \text{ans/}$$

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(Ques3) What is the fraction of the total refresh time per frame spent in refresh of e-beam for a non-interlaced raster system with a resolution of 1280×1024 .

A refresh rate of 60Hz a horizontal refresh time of 5ms micro seconds and a vertical

vertical time of 500 micro seconds

$$\text{So} \Rightarrow \text{Total refresh time} = \text{Horizontal} + \text{vertical}$$
$$= 500\mu\text{s} + 5\mu\text{s}$$
$$= 505\mu\text{s}$$

$$\Rightarrow \text{Refresh rate} = 60\text{Hz} = \frac{1}{60} \text{ sec to scan.}$$
$$= 16.7 \text{ Sec}$$

$$\Rightarrow \text{Horizontal Refresh time} = (1024-1) \times 5\mu\text{s}$$

$$\Rightarrow \text{Vertical Refresh time} = (1024-1) \times 5\mu\text{s} + 500\mu\text{s}$$

$$\Rightarrow (1024-1) \times 5 + 500\mu\text{s}$$

$$16.7 \text{ ms}$$

Program to Create a Pixel

#include <graphics.h>

void main()

{ int gd = DETECT, gm;

initgraph(&gd, &gm, "C:\I\+C\BG");

putpixel(10, 10, RED);

}

closegraph();

when $m > 1$

$y_{act}++$

$$x = \frac{y - c}{m}$$

when $m < 1$

$x_{act}++$

$$y = mx + c$$

$m > 1$

$m < 1$

$$m = \frac{y_2 - y_1}{x_2 - x_1}$$

```
#include <graphics.h>
#define ROUND(x) (int)(x+0.5)
void main()
{ int gd = DETECT, gm;
initgraph(&gd, &gm, "c://+c//bg");
putpixel(ROUND(x), ROUND(y), RED);
closegraph()
}
```

```
#include <graphics.h>
void main()
{ float x, y, m, c, i, x1, x2, y1, y2;
scanf("%.f %.f %.f %.f", &x1, &x2, &y1, &y2);
m = (y2 - y1) / (x2 - x1);
c = y1 - m * x1;
x = x1; y = y1;
if (m <= 1)
{ for (i = x1; i <= x2; i++)
{ putpixel(ROUND(x), ROUND(y), RED);
x++;
y = m * x + c;
}
}
else
{ for (i = y1; i <= y2; i++)
{ putpixel(ROUND(x), ROUND(y), RED);
y++;
x = (y - c) / m;
}
}
```

$\Rightarrow (x_1, y_1)$ to (x_2, y_2)

$$x = x_1 + (x_2 - x_1)u$$

$$y = y_1 + (y_2 - y_1)u$$

where $0 \leq u \leq 1$

$$u = u + du$$

$$du = \frac{1}{L} \quad \text{where } L = |dx| + |dy|$$

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Digital Differential analyser (DDA)

$$\therefore y = mx + c$$

\Rightarrow if $m < 1$

$$\Rightarrow \frac{dy}{dx} = m \Rightarrow dy = m dx$$

$$\Rightarrow y_{n+1} - y_n = m(x_{n+1} - x_n)$$

$$\text{for } m < 1 \quad x_{n+1} = x_n + 1$$

$$y_{n+1} - y_n = m(x_{n+1} - x_n)$$

$$y_{n+1} = y_n + m$$

\Rightarrow if $m > 1$

$$\Rightarrow y_{n+1} - y_n = (x_{n+1} - x_n)$$

$$\text{for } m > 1 \quad y_{n+1} = y_n + 1$$

$$x_{n+1} = x_n + 1/m$$

Void lineDDA (int xa, int xb, int ya, int yb)
{ int dx = xb - xa, dy = yb - ya, steps,
float xInc, yInc, x = xa, y = ya;
if (abs(dx) > abs(dy)) steps = abs(dx);

```

else steps = abs(dy),
xInc = dx / (float) steps;
yInc = dy / (float) steps;
putpixel(ROUND(x), ROUND(y), RED);
for (k=0; k<steps, k++)
    if x++ = xInc;
        y++ = yInc;
        putpixel(ROUND(x), ROUND(y), RED);
    }
}

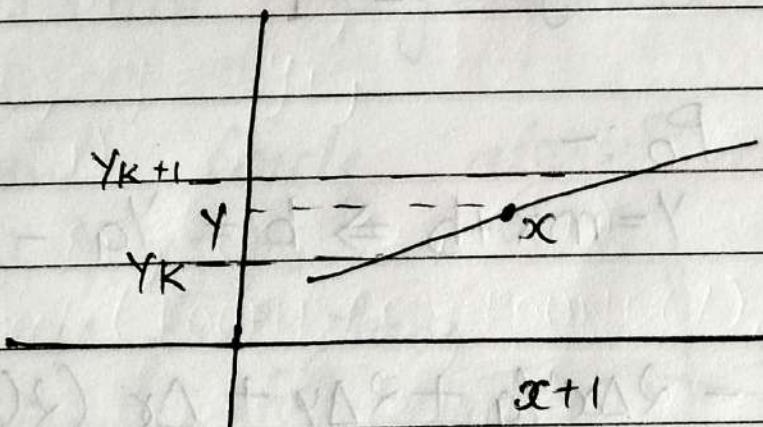
```

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#Bresenham's line Drawing Algo

$$x_{k+1} = x_k + 1, \quad y_{k+1} = y_k + 1/y_k$$

★ This algo is also known as integer line draw algo.



⇒ If $P_k < 0$

⇒ $(x_k + 1, y_k)$

⇒ else

⇒ $(x_k + 1, y_k + 1)$ $\left\{ \because y = mx + b \right\}$

⇒ $d_1 = y - y_k \Rightarrow m(x_k + 1) + b - y_k$

⇒ $d_2 = (y_k + 1) - y \Rightarrow y_k + 1 - m(x_k + 1) - b$

$$\Rightarrow P_k = \Delta x (d_1 - d_2) = (2m(x_k + 1) - 2y_k + 2b - 1) \times \Delta x$$

$$\Rightarrow P_k = 2\Delta y x_k - 2\Delta x y_k + C$$

$$\left\{ \because \text{where } C = 2\Delta y + \Delta x (Nb - 1) \right\}$$

$$\Rightarrow P_{k+1} = 2\Delta y x_{k+1} - 2\Delta x y_{k+1} + C$$

$$\Rightarrow P_{k+1} - P_k = 2\Delta y (x_{k+1} - x_k) - 2\Delta x (y_{k+1} - y_k)$$

$$\left\{ \because x_{k+1} = x_k + 1 \right\}$$

$$\Rightarrow P_{k+1} = P_k + 2\Delta y - 2\Delta x (y_{k+1} - y_k)$$

\Rightarrow if $P_k < 0$ then $y_{k+1} = y_k$ and Points (x_{k+1}, y_k)

$$\Rightarrow [P_{k+1} = P_k + 2\Delta y]$$

\Rightarrow else then $y_{k+1} = y_k + 1$ and Points (x_{k+1}, y_{k+1})

$$\Rightarrow [P_{k+1} = P_k + 2\Delta y - 2\Delta x]$$

\Rightarrow Calculating P_0 :-

$$\Rightarrow (x_a, y_a) \quad Y = mx + b \Rightarrow b = y_a - \frac{\Delta y}{\Delta x} x_a$$

$$\Rightarrow P_0 = 2\Delta y x_a - 2\Delta x y_a + 2\Delta y + \Delta x (2(y_a - \frac{\Delta y}{\Delta x} x_a))$$

$$\Rightarrow [P_0 = 2\Delta y - \Delta x]$$

Program for drawing a circle

$$\Rightarrow x^2 + y^2 = r^2$$

$$\Rightarrow (x - x_c)^2 + (y - y_c)^2 = r^2$$

$$\Rightarrow x = \sqrt{r^2 - y^2}$$

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PAGE

draw circle cent x, int y,
int. xc, int yc) (-x, y)

{ putpixel (x+xc, y+yc, RED)
putpixel (y+xc, x+yc, RED) (-x, -y)

}

for (Y=0 ; Y<=X ; Y++)
{ x = sqrt(x*x - y*y)

→ another eqn by which we can create circle

$$x = r \sin \theta, y = r \cos \theta.$$

Mid point Circle algorithm

$$m(x_{k+1}, y_{k+1})$$

now if we put these coordinates into below

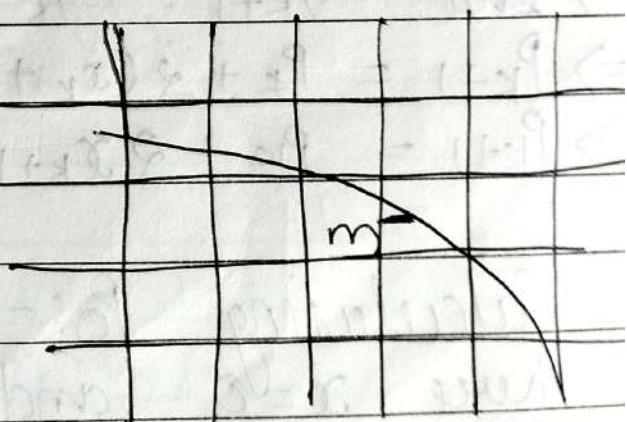
eqn if $m < 0$ then

m will go inside

and we will take

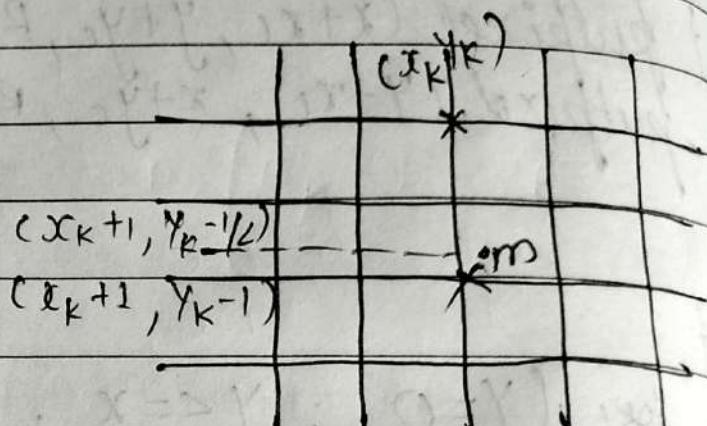
the value previous value of y and if it is outside the we will subtract 1 from y :

$$\text{eqn: } f(x, y) = x^2 + y^2 - r^2$$



- $\hookrightarrow < 0$ inside (x_{k+1}, y_k)
 $\hookrightarrow > 0$ outside (x_{k+1}, y_{k-1})

$$\Rightarrow f(x, y) = x^2 + y^2 = \sigma^2$$



$$\Rightarrow P_k = f(x_{k+1}, y_{k-1/2}) = (x_{k+1})^2 + (y_{k-1/2})^2 - \sigma^2 \quad (1)$$

$$\Rightarrow P_{k+1} = f(x_{k+1} + 1, y_{k+1} - 1/2) = (x_{k+1} + 1)^2 + (y_{k+1} - 1/2)^2 - \sigma^2 \quad (2)$$

$$\Rightarrow \therefore x_{k+1} = x_k + 1$$

$$\Rightarrow P_{k+1} = P_k + 2(x_k + 1) + (y_{k+1}^2 - y_k^2) - (y_{k+1} - y_k) +$$

$$\Rightarrow \text{if } P_k < 0 \text{ then } y_{k+1} = y_k, \text{ points } (x_{k+1}, y_k)$$

$$\Rightarrow P_{k+1} = P_k + 2(x_k + 1) + 1$$

$$\Rightarrow \text{else } y_{k+1} = y_k - 1, \text{ points } (x_{k+1}, y_{k-1})$$

$$\Rightarrow P_{k+1} = P_k + 2(x_k + 1) - 2(y_k - 1) + 1$$

$$\Rightarrow P_{k+1} = P_k + 2x_{k+1} - 2y_{k+1} + 1$$

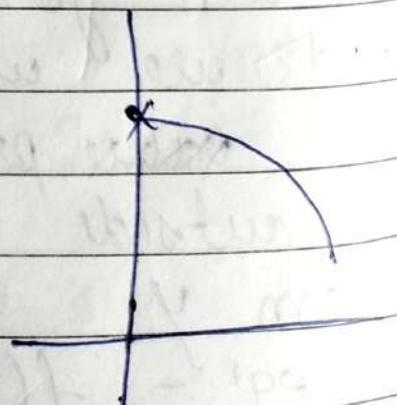
Calculating P_0 :-

here $x=0$, and $y=\sigma$

$$\Rightarrow P_0 = f(0, \sigma - 1/2)$$

$$\Rightarrow P_0 = 1 + (\sigma - 1/2)^2 - \sigma^2$$

$$\Rightarrow P_0 = \frac{5}{4} - \sigma \approx 1 - \sigma$$



$$P_0 \approx 1 - \gamma$$

\Rightarrow Algorithm for drawing Circle :-

1. Read x_c, y_c, γ
2. calculate, $P_0 = 1 - \gamma$
3. drawCircle $(0, \gamma, x_c, y_c)$
4. make a while loop where the condition will be $x! = y$. or use for loop where $x = 0$; $x <= y$ and $x++$

\Rightarrow Program for drawing circle

```
void midPoint (int xc, int yc, int r) {
```

```
    int P = 1 - r, x = 0, y = r;
```

```
    drawCircle (x, y, xc, yc);
```

```
    for (x = 0; xc >= y; x++) {
```

```
        if (P < 0) {
```

```
            P = P + 2(x+1) + 1;
```

```
            x++;
```

```
            drawCircle (x, y, xc, yc);
```

```
        } else {
```

```
            y = y - 1;
```

```
            x++;
```

```
            P = P + 2(x+1) - 2(y-1) + 1;
```

```
            drawCircle (x, y, xc, yc);
```

```
}
```

```
}
```

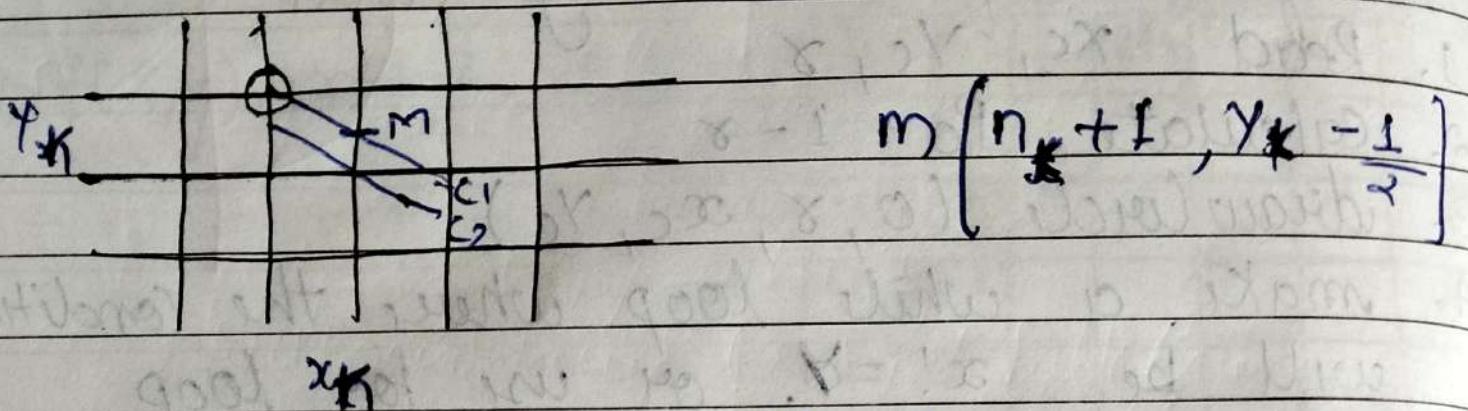
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Putpixel ($x+x_c, y+y_c, \text{RED}$)

.. $(-x+x_c, y+y_c, \text{..})$

$$\text{II } (-x + xc_c, -y + yc_c, '')$$

$$\text{II } (x + xc_c, -y + yc_c, '')$$



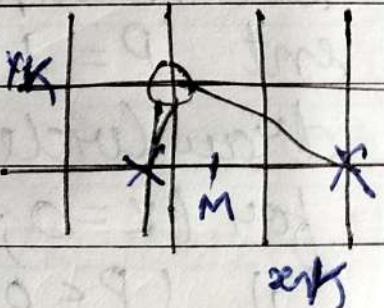
$$\Rightarrow f(x, y) = x^2 \delta y^2 + y^2 \delta x^2 - \delta x^2 \delta y^2$$

$$\begin{cases} f(m) < 0 & (x_k+1, y_k) \\ f(m) > 0 & (x_{k+1}, y_{k-1}) \end{cases} \begin{cases} \text{for } R_1 \\ \text{region} \end{cases}$$

for R_2 region

$$f(m) < 0 \quad (x_k+1, y_k-1)$$

$$f(m) > 0 \quad (x_k, y_{k-1})$$



$$m (x_{k+1}, y_{k-1})$$

Now parameter of decision

↳ decision parameters are

$$P_{1K} = f\left(x_k+1, y_k-\frac{1}{2}\right) \Rightarrow (x_k+1)^2 \delta y^2 + (y_k-\frac{1}{2})^2 \delta x^2 - \delta x^2 \delta y^2$$

$$P'_{1K+1} = f\left(x_{k+1}, y_{k+1}-\frac{1}{2}\right)$$

$$P'_{1K+1} - P_{1K}$$

$$\Rightarrow \text{if } P_{I_k} < 0 \text{ then}$$

$$P_{I_{k+1}} = P_{I_k} + 2\gamma y^2 x_{k+1} + \gamma y^2$$

$$= P_{I_k} + 2\gamma y^2 (x_{k+1}) + \gamma y^2$$

$\therefore [x_{k+1} = x_k + 1]$

$$P_{I_{k+1}} = P_{I_k} + 2\gamma y^2 x_{k+1} + \gamma y^2 - 2\gamma x^2 y_{k+1}$$

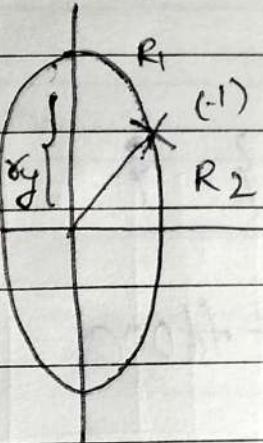
$$[y_{k+1} = y_k + 1]$$

Now,

$$\text{Since } x = 0, y = \gamma$$

then

$$f(0+1, \gamma - 1/2)$$

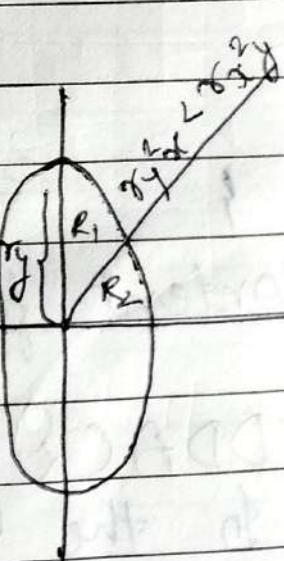


Now same for finding P_2 (decision parameter two)

\Rightarrow for finding slope i.e. m

$$\frac{dy}{dx} = \frac{d(x^2 \gamma y^2 + y^2 \gamma x^2 - \gamma x^2 \gamma y^2)}{dx}$$

$$= \frac{2 \gamma y^2 x}{2 \gamma x^2 y} = -1$$



Boundary fill Algo

```

void fullBoundary (int x, int y, int fullc, int
boundaryc)
{
    int currentc = getPixel (x, y);
    if (currentc != boundaryc && currentc != fullc)
        putpixel (x, y, fullc);
        fullBoundary (x-1, y, fullc, boundaryc);
        " (x+1, y, " , " );
        " (x, y+1, " , " );
        " (x, y-1, " , " );
}
}

```

flood fill fill Algo

```

void fillflood (int x, int y, int oldcolor, int fillcolor)
{
    if (getPixel (x, y) == oldcolor)
        putpixel (x, y, fillcolor);
        fillflood (x-1, y, oldcolor, fillcolor);
        " (x+1, y, " , " );
        " (x, y+1, " , " );
        " (x, y-1, " , " );
}
}

```

Content for Internal :-

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- ① DDA (Digital Differential Analyser) :-
In the question we are given with the

Points of line

e.g. $(1, 1)$ and $(3, 3)$

Step 1 :- calculate slope (m) = $\frac{\Delta y}{\Delta x} = \frac{y_2 - y_1}{x_2 - x_1}$

$$\Rightarrow m = \frac{3 - 1}{3 - 1} = \frac{2}{2} \Rightarrow 1$$

Step 2 :- find Δx and Δy

$$\Rightarrow \Delta x = \frac{\Delta y}{m} = \frac{y_2 - y_1}{x_2 - x_1} \quad \left(\because m = \frac{y_2 - y_1}{x_2 - x_1} \right)$$

$$\Rightarrow \Delta x = x_2 - x_1 \Rightarrow 2$$

$$\Rightarrow \Delta y = m \Delta x = \frac{y_2 - y_1}{x_2 - x_1} \Delta x = y_2 - y_1$$

$$\Rightarrow \Delta y = 2$$

Step 3 :- $|\Delta x| \geq |\Delta y|$, so assign $\Delta x = 1$

there are 2 cases

case 1 :- if $|\Delta x| \geq |\Delta y|$ then assign $\Delta x = 1$

$$\Rightarrow x_{i+1}^0 = x_i + \Delta x$$

$$\Rightarrow x_{i+1} = x_i + 1$$

$$\Rightarrow y_{i+1} = y_i + \Delta y = y_i + m \Delta x$$

$$\Rightarrow y_{i+1} = y_i + m$$

case 2 :- if $|\Delta x| < |\Delta y|$ then assign $\Delta y = 1$

$$\Rightarrow x_{i+1} = x_i + \Delta x = x_i + \frac{\Delta y}{m}$$

$$\Rightarrow x_{i+1} = x_i + 1/m$$

$$\Rightarrow y_{i+1} = y_i + \Delta y$$

$$\Rightarrow y_{i+1} = y_i + 1$$

In this question we are having case 1
that why we have assigned $\Delta x = 1$

$$\Rightarrow x_{i+1} = x_i + 1 \Rightarrow y_{i+1} = y_i + m$$

$$\Rightarrow x_{i+1} = 1 + 1 = 2, \quad \Rightarrow y_{i+1} = 1 + 1 = 2$$

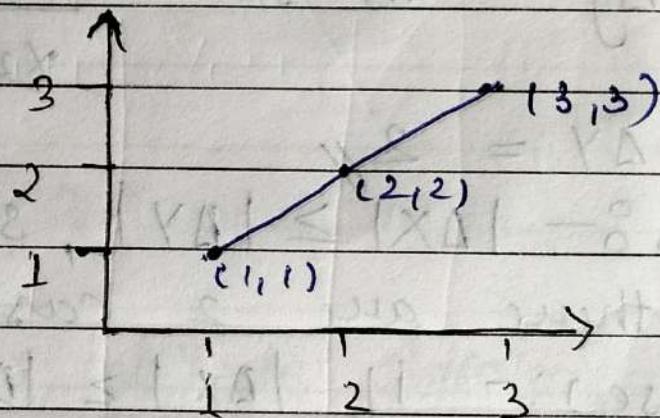
again calculating with the updated value
of x_i and y_i

$$\Rightarrow x_{i+1} = x_i + 1 = 2 + 1 \Rightarrow y_{i+1} = y_i + m = 2 + 1$$

$$\Rightarrow x_{i+1} = 3 \quad \Rightarrow y_{i+1} = 3$$

Now the points are $(1, 1)$, $(2, 2)$ and $(3, 3)$

x_i	y_i	x_{i+1}	y_{i+1}
1	1	2	2
2	2	3	3



② Bresenham's line drawing algorithm

In DDA in most of the cases the points are in floating point which cause problem that why we had Bresenham's algorithm
ex:- $(1, 1)$ and $(5, 3)$

Step 1 :- calculate slope (m) = $\frac{\Delta Y}{\Delta X} = \frac{y_2 - y_1}{x_2 - x_1}$

$$\Rightarrow m = \frac{3 - 1}{5 - 1} = \frac{2}{4} = \frac{1}{2} = 0.5 \Rightarrow m = \frac{0.5}{2}$$

Step 2 :- calculate Decision Parameter (P)

$$P = 2 \cdot Y - X$$

Now there are 2 cases:-	
case 1:- $0.5m < 1$	case 2:-
(a) $P < 0$	I) $m \geq 1$
$x_{i+1} = x_i + 1$	$x_{i+1} = x_i$
$y_{i+1} = y_i$	$y_{i+1} = y_i + 1$
$P_{k+1} = P_k + 2\Delta y$	$P_{k+1} = P_k + 2\Delta x$
(b) $P \geq 0$	II) $P \geq 0$
$x_{i+1} = x_i + 1$	$x_{i+1} = x_i + 1$
$y_{i+1} = y_i + 1$	$y_{i+1} = y_i + 1$
$P_{k+1} = P_k + 2\Delta y - 2\Delta x$	$P_{k+1} = P_k + 2\Delta x - \Delta y$

\Rightarrow our $m = 0.5 < 1$ so we'll follow case 1

so now let us check the value of P

$$\Rightarrow P = 2\Delta y - \Delta x = 2(y_2 - y_1) - (x_2 - x_1)$$

$$\Rightarrow P = 2(3 - 1) - (5 - 1) = 2(2) - 4 = 0$$

$$\Rightarrow [P = 0]$$

now we will follow the (b) part of case 1

as our $P = 0$

\Rightarrow now we will calculate $x_{i+1}, y_{i+1}, P_{k+1}$

$$\Rightarrow x_{i+1} = x_i + 1 = 1 + 1 \Rightarrow [x_{i+1} = 2]$$

$$\Rightarrow y_{i+1} = y_i + 1 = 1 + 1 \Rightarrow [y_{i+1} = 2]$$

$$\Rightarrow P_{k+1} = P_k + 2\Delta y - 2\Delta x = 0 + 2(2) - 2(4)$$

$$\Rightarrow P_{k+1} = 4 - 8 \Rightarrow [P_{k+1} = -4]$$

Now $P < 0$ so (a) part will be followed

$$\Rightarrow x_{i+1} = x_i + 1 = 2 + 1 \Rightarrow [x_{i+1} = 3]$$

$$\Rightarrow y_{i+1} = y_i \Rightarrow [y_{i+1} = 2]$$

$$\Rightarrow P_{k+1} = P_k + 2\Delta y \Rightarrow P_{k+1} = -4 + 2(2) = 0,$$

now $P=0$ so following part (b)

$$\Rightarrow x_{i+1} = x_i + 1 = 3 + 1 \Rightarrow x_{i+1} = 4$$

$$\Rightarrow y_{i+1} = y_i + 1 = 2 + 1 \Rightarrow y_{i+1} = 3$$

$$\Rightarrow P_{k+1} = P_k + 2\Delta y - 2\Delta x \Rightarrow -4 + 4 - 8$$

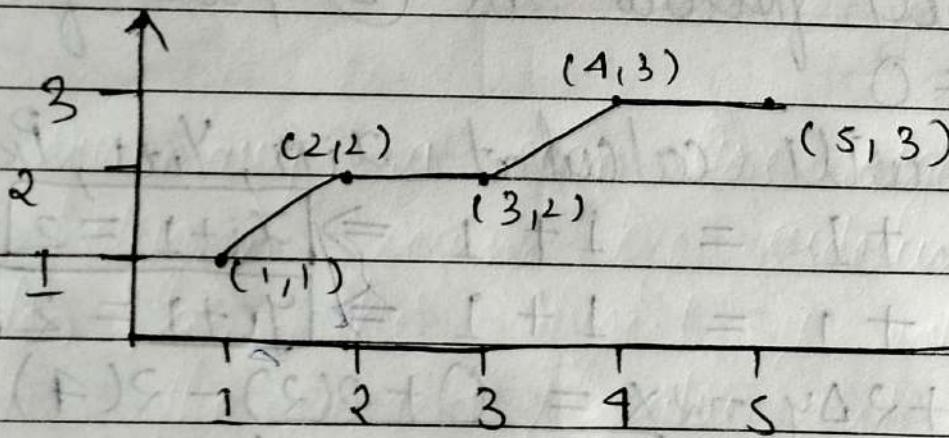
$P_k < 0$ so following part (a)

$$\Rightarrow x_{i+1} = x_i + 1 = 4 + 1 = 5 \Rightarrow x_{i+1} = 5$$

$$\Rightarrow y_{i+1} = y_i = 3 \Rightarrow y_{i+1} = 3$$

Our points are $(1, 1), (2, 2), (3, 2), (4, 3)$
and $(5, 3)$

P	x_i	y_i	x_{i+1}	y_{i+1}
0	1	1	2	2
-4	2	2	3	3
0	3	2	4	3
-4	4	3	5	3



③ Mid point circle drawing algorithm

$$\Rightarrow x^2 + y^2 = r^2 - ① \Rightarrow x^2 + y^2 - r^2 = 0 - ②$$

point of $M = (x_m, y_m)$

$$\Rightarrow (x_m)^2 + (y_m)^2 - r^2 - ③$$

if the result of eqn ③ is

- $\rightarrow 0$: Point lies on a circle
- $\rightarrow <0$: Point lies inside (x_{k+1}, y_k)
- $\rightarrow >0$: Point lies outside (x_{k+1}, y_k)

$$\Rightarrow \text{Mid point coordinate} = \left[\frac{(x_k + 1, x_{k+1})}{2}, \frac{(y_k + y_{k+1})}{2} \right]$$

$$= (x_k + 1, y_k - 1/2) \quad (\because d_k = \text{decision parameter})$$

$$\Rightarrow d_k = (x_k + 1)^2 + (y_k - 1/2)^2 - \gamma^2 \quad \text{--- (1)}$$

$$\Rightarrow d_{k+1} = (x_{k+1} + 1)^2 + (y_{k+1} - 1/2)^2 - \gamma^2$$

$$\Rightarrow d_{k+1} - d_k$$

after solving this we got

$$\Rightarrow d_{k+1} = d_k + 2x_k + 3 + (y_k + 1)^2 - y_{k+1} - y_k^2 + y_k$$

- if $d_k < 0$ then $y_{k+1} = y_k$

$$\Rightarrow d_{k+1} = d_k + 2x_k + 3$$

- if $d_k > 0$ then $y_{k+1} = y_k - 1$

$$\Rightarrow d_{k+1} = d_k + 2x_k - 2y_k + 5$$

$$\Rightarrow (0, \gamma) \text{ IDP} (d_0) \quad \{ \text{IDP} = \text{Initial decision Parameter}$$

Put $(0, \gamma)$ in eqn ④

$$\Rightarrow d_0 = (0+1)^2 + (\gamma - 1/2)^2 - \gamma^2$$

$$\Rightarrow d_0 = 5/4 - \gamma$$

25/09/2023

How to find a point inside a polygon
or outside a polygon

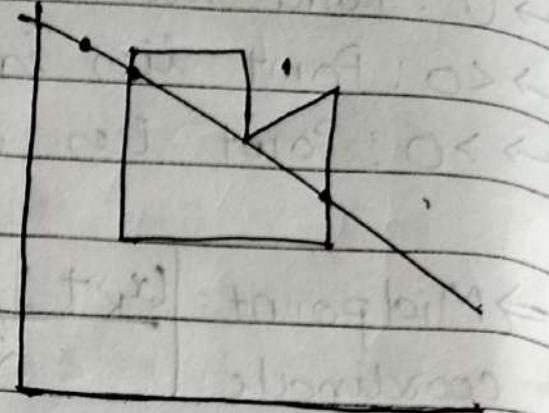
① Even Odd method

⇒ odd intersection = In

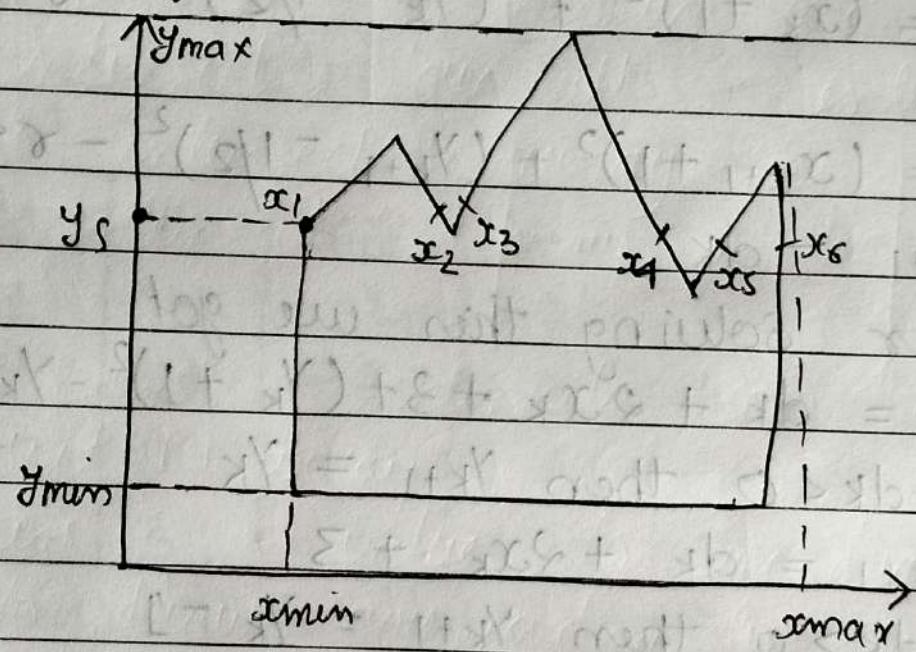
⇒ even intersection = Out

⇒ non zero = inside

⇒ zero = outside



Scan Line Algorithm:-



In summary, a scan line algorithm for filling a polygon begins by ordering the polygon sides on the largest y value. It begins with the largest y value and scans down the polygon. For each y, it determines which sides can be intersected and finds the x values of these intersection points. It then sorts, pairs and passes these x values to a line drawing routine.

⇒ Scan line conversion Algorithm for polygon filling :-

1. Read n , the number of vertices of polygon
2. Read x and y coordinates of all vertices in array $x[n]$ and $y[n]$
3. find y_{\min} and y_{\max}
4. Store the initial x values (x_1) y values y_1 and y_2 for two endpoints and x increment Δx from scan line for each edge in the array edges [n] [4]
while doing this check that $y_1 > y_2$ if not interchange y_1 and y_2 and corresponding x_1 and x_2 so that for each edge, y_1 represents its maximum y coordinate and y_2 represents its minimum y coordinate
5. Sort the pairs of arrays, edges [n] [4] in descending order of y_1 , descending order of y_2 and ascending order of x_2
6. Set $y = y_{\max}$
7. find the active edges and update active edge list
if ($y > y_2$ and $y \leq y_1$)
 edge is active
else
 edge is not active
8. compute the x intersects for all active edges for current y values initially x intersects

is x_i and x intersect for successive y values can be given as.

$$x_{i+1} = x_i + \Delta x$$

where $\Delta x = -\frac{1}{m}$ and $m = \frac{y_2 - y_1}{x_2 - x_1}$ i.e

slope of a line segment

9. If x -intersect is vertex i.e x -intersect $= x_i$, and $y = y_i$, then apply vertex list to check whether to consider one intersect or two intersect. Store all x -intersect in the x -intersect f¹f array.

10. Sort x -intersect f¹f array in the ascending order

11. Extract pairs of intersects from the sorted x -intersect [] array

12. Pass pairs of x value to line drawing routine to draw corresponding line segments

13. Set $y = y - 1$

14. Repeat steps 7 through 13 until $y \geq y_{min}$ is stop.

03/10/2023

2D Transformation

$$x' = r \cos(\phi + \theta) \Rightarrow r \cos \phi \cos \theta - r \sin \phi \sin \theta$$

$$y' = r \sin(\phi + \theta) \Rightarrow r \cos \phi \sin \theta + r \sin \phi \cos \theta$$

$$x = r \cos \phi$$

$$y = r \sin \phi$$

$$\begin{aligned}x' &= x \cos\theta - y \sin\theta \\y' &= x \sin\theta + y \cos\theta\end{aligned}\quad \left. \begin{aligned}x'y' &= [x \ y] \begin{bmatrix} \cos\theta & \sin\theta \\ \sin\theta & \cos\theta \end{bmatrix} \\P' &= P \times R\end{aligned}\right.$$

→ Scaling an Object :-

$$x' = x \times s_x$$

$$y' = y \times s_y$$

$$[x' \ y'] = [x \ y] \begin{bmatrix} s_x & 0 \\ 0 & s_y \end{bmatrix}$$

$$P' = P \times S$$

s_x and s_y are scaling factors.

Ques :- Scale the triangle with coordinates A (2, 5) ; B (7, 10) ; C (10, 2) by 2 unit in X direction and 2 unit in Y direction

$$\text{Soln} \quad P' = P \times S$$

$$\begin{aligned}A' &= \begin{bmatrix} x'_1 & x'_2 & x'_3 \\ y'_1 & y'_2 & y'_3 \end{bmatrix} = \begin{bmatrix} 2 & 7 & 10 \\ 5 & 10 & 2 \end{bmatrix} \times \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} = \begin{bmatrix} 4 & 14 & 20 \\ 10 & 20 & 4 \end{bmatrix} \\&\text{A} \quad \text{B} \quad \text{C}\end{aligned}$$

New coordinates are :-

$$A(4, 10) ; B(14, 20) ; C(20, 4)$$

\Rightarrow Homogeneous Coordinate

$$[x_w \ y_w \ w]$$

$$T = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ tx & ty & 1 \end{bmatrix}$$

$$x = \frac{x_w}{w}, \ y = \frac{y_w}{w}$$

$$[x, y, 1]$$

$$R = \begin{bmatrix} \cos\theta & \sin\theta & 0 \\ -\sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

P' = $P \times$ Transformable Matrix

$$S = \begin{bmatrix} sx & 0 & 0 \\ 0 & sy & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\Rightarrow P' = P \times T$$

$$\Rightarrow P' = P \times R$$

$$\Rightarrow P' = P \times S$$

$$P' = P \cdot M_1 + M_2$$

M_1 = Identity Matrix

M_2 = Translation Vector

$$P' = P \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} tx \\ ty \end{bmatrix} \text{ translation}$$

$$P' = P \begin{bmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \end{bmatrix} \text{ rotation}$$

$$P' = P \begin{bmatrix} sx & 0 \\ 0 & sy \end{bmatrix}$$

From previous Ques. But here we have
 to do ① $tx = 5$, $ty = 3$ and ② $Sx=2$, $sy=1/2$
 sol' first calculate $CM = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 5 & 3 & 1 \end{pmatrix} \times \begin{pmatrix} 2 & 0 & 0 \\ 0 & 1/2 & 0 \\ 0 & 0 & 1 \end{pmatrix}$

$$\Rightarrow P' = P \times CM$$

$$A' \begin{pmatrix} x_1' & y_1' \end{pmatrix} = \begin{pmatrix} 2 & 5 & 1 \\ 0 & 10 & 1 \\ 10 & 2 & 1 \end{pmatrix} \times \begin{pmatrix} CM \end{pmatrix}$$

04/10/2023

Q find the transformation matrix that transform the square ABCD to half its size with centre still remaining at the same position. The coordinates of square are A(1,1); B(3,1); C(3,3); D(1,3) and center at (2,2) also find the resultant coordinate of square.

sol' $CM = T_{(-2,-2)}^{-1} \times S_{(1/2, 1/2)} \times T_{(2,2)}$

$$\Rightarrow CM = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -2 & -2 & 1 \end{pmatrix} \times \begin{pmatrix} 1/2 & 0 & 0 \\ 0 & 1/2 & 0 \\ 0 & 0 & 1 \end{pmatrix} \times \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 2 & 0 & 1 \end{pmatrix}$$

$$\Rightarrow CM = \begin{pmatrix} 0.5 & 0 & 0 \\ 0 & 0.5 & 0 \\ 1 & 1 & 1 \end{pmatrix}$$

$$P' = P \times CM$$

$$\begin{bmatrix} A' \\ B' \\ C' \\ D' \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 3 & 1 & 1 \\ 3 & 3 & 1 \\ 1 & 3 & 1 \end{bmatrix} \times \begin{bmatrix} 0.5 & 0 & 0 \\ 0 & 0.5 & 0 \\ 1 & 1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1.5 & 1.5 & 1 \\ 2.5 & 1.5 & 1 \\ 2.5 & 2.5 & 1 \\ 1.5 & 2.5 & 1 \end{bmatrix}$$

A(1.5, 1.5)

B(2.5, 1.5)

C(2.5, 2.5)

D(1.5, 2.5)

ans

Now rotate that square by 45°

$$CM = T^{-1} \times R \times VT$$

$$(-2, -2) \quad (45^\circ) \quad (2, 2)$$

$$\Rightarrow CM = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -2 & -2 & 1 \end{bmatrix} \times \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} & 0 \\ -1/\sqrt{2} & 1/\sqrt{2} & 0 \\ 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 2 & 2 & 1 \end{bmatrix}$$

then calculate CM and P'

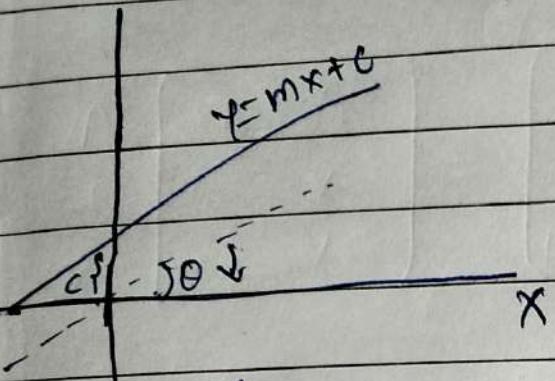
(Q) find a transformation of ΔA_1O
 $B_0, 1 \quad C_1, 1$

(Q) Rotating 45° about origin then translating

1 unit in x direction and 1 unit in y direction
 (B) translate in x and y direction and then rotate 45° about the origin

05/10/2023

Reflection

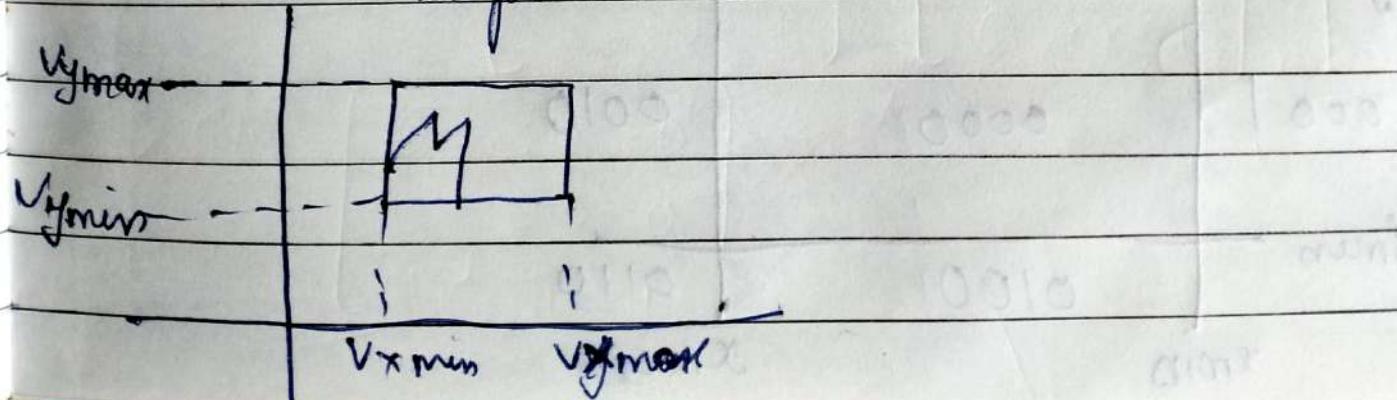
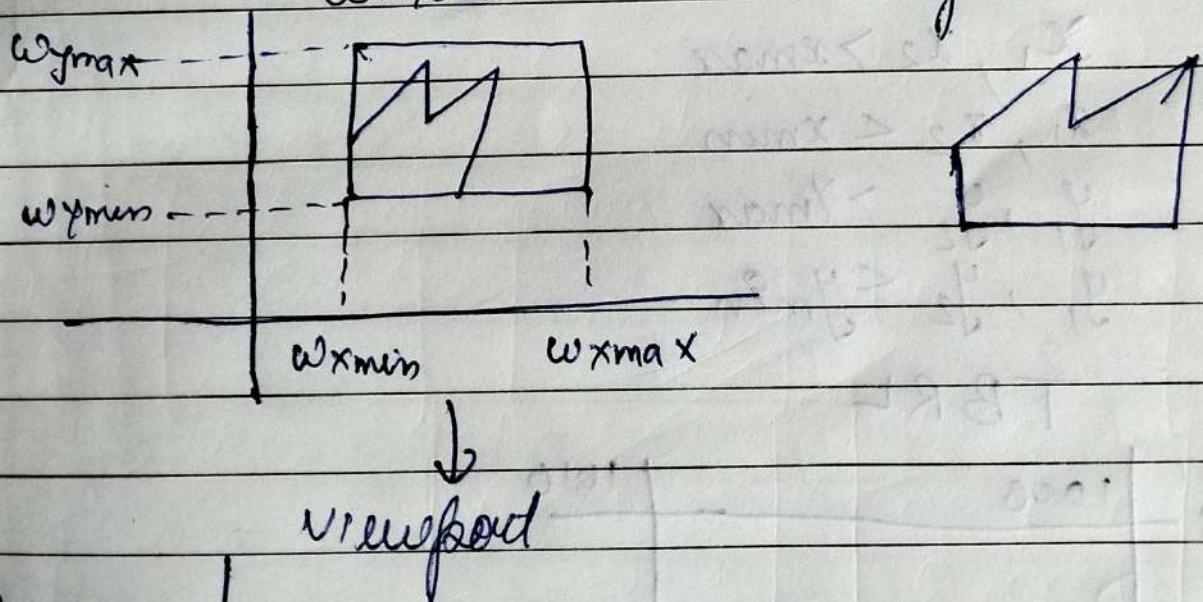


$$m = \tan \theta$$

$$\theta = \tan^{-1} m$$

$$cm = T(0, -c) \times R(-\theta) \times \text{Ref}_x \times R(\theta) \times T(0, c)$$

Windowing and Clipping window original image :-



$$C_M = T \begin{pmatrix} -w_{x_{\min}} - w_{y_{\min}} \end{pmatrix} \times S \begin{pmatrix} s_x, s_y \end{pmatrix} \times T \begin{pmatrix} v_{x_{\min}} - v_{y_{\min}} \end{pmatrix}$$

$$\Rightarrow s_x = \frac{v_{x_{\max}} - v_{x_{\min}}}{w_{x_{\max}} - w_{x_{\min}}}$$

$$\Rightarrow s_y = \frac{v_{y_{\max}} - v_{y_{\min}}}{w_{y_{\max}} - w_{y_{\min}}}$$

→ Point Clipping :-

$$w_{x_{\min}} \leq x \leq w_{x_{\max}}$$

$$w_{y_{\min}} \leq y \leq w_{y_{\max}}$$

09/10/2023

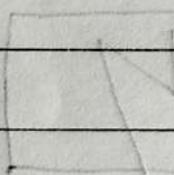
Cohen Sutherland line clipping Algo

$$x_1, x_2 > x_{\max}$$

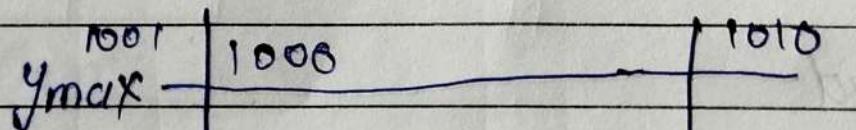
$$x_1, x_2 < x_{\min}$$

$$y_1, y_2 > y_{\max}$$

$$y_1, y_2 < y_{\min}$$



T B R L



000 | 0000 0010

y_{min} 0100 0110

Visible \rightarrow 0000

Not visible \Rightarrow Bitwise AND non zero

$$x_i = x_{\min} \text{ or } x_{\max}$$

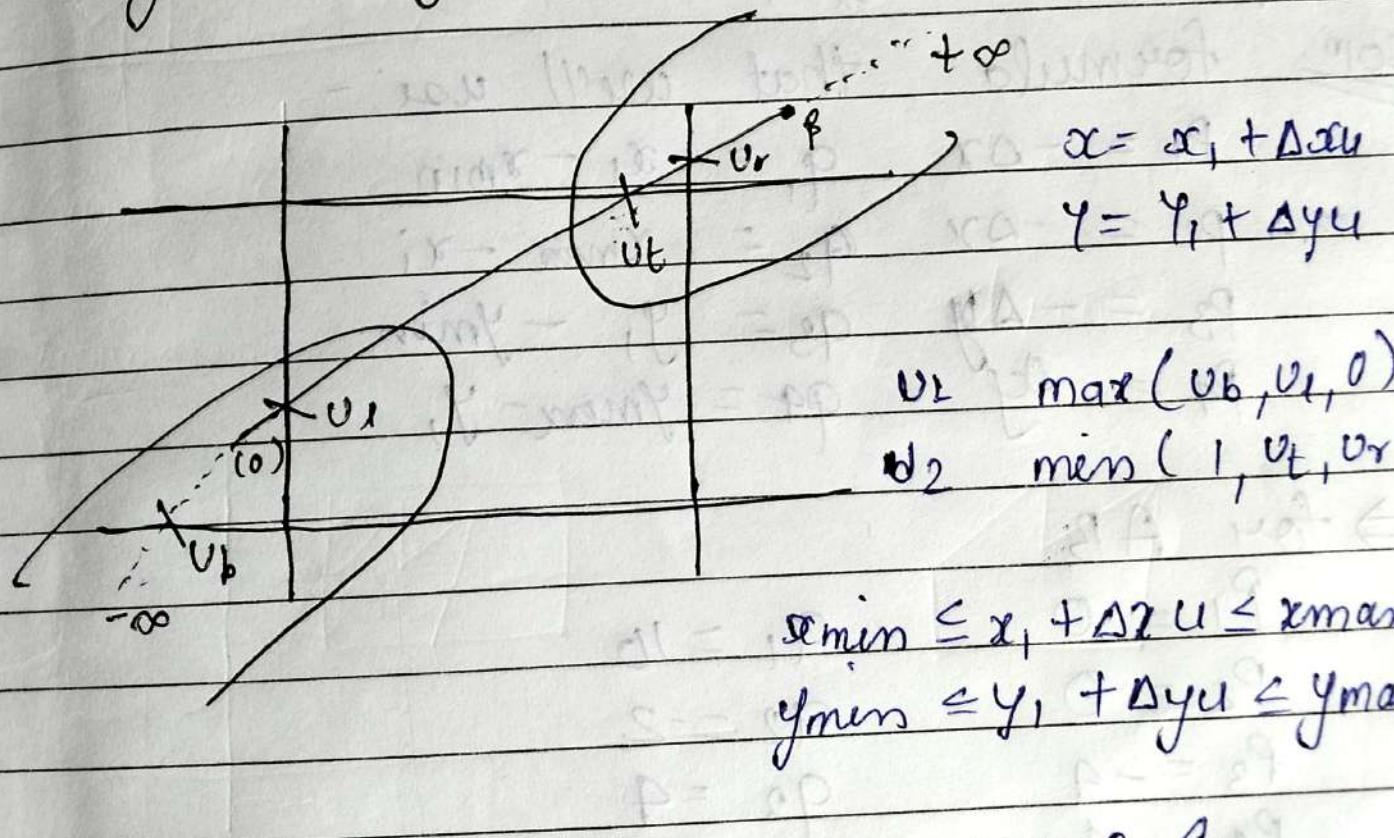
$$y_i = y_1 + m(x_i - x_1)$$

and

$$x_i = x_1 + (y_i - y_1)/m$$

$$y_i = y_{\min} \text{ or } y_{\max}$$

Liang Barsky line clipping equation



$$P_k \quad 0 \leq q_k \quad k = 1, 2, 3, 4$$

$$\Rightarrow P_1 = -\Delta x \quad q_1 = x_1 - x_{\min} \quad (\text{left})$$

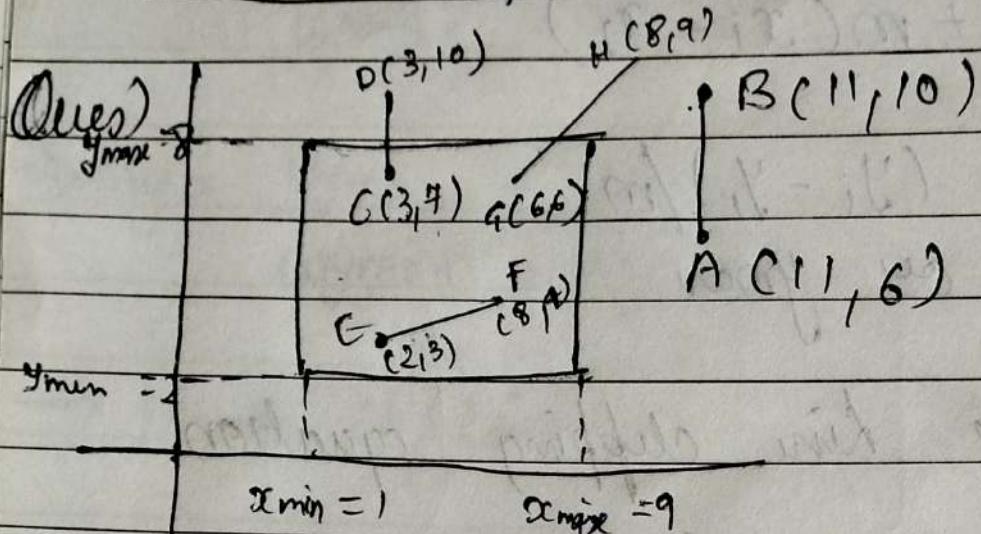
$$\Rightarrow P_2 = \Delta x \quad q_2 = x_{\max} - x_1 \quad (\text{Right})$$

$$\Rightarrow P_3 = -\Delta y \quad q_3 = y_1 - y_{\min} \quad (\text{Bottom})$$

$$\Rightarrow P_4 = \Delta y \quad q_4 = y_{\max} - y_1 \quad (\text{top})$$

$$\Rightarrow -\Delta x \quad 0 \leq x_1 - x_{\min}$$

$$\Rightarrow [x_{\min} \leq x_1 + \Delta x]$$



SOLⁿ formula that we'll use:-

$$P_1 = -\Delta x \quad q_1 = x_1 - x_{\min}$$

$$P_2 = -\Delta x \quad q_2 = x_{\max} - x_1$$

$$P_3 = -\Delta y \quad q_3 = y_1 - y_{\min}$$

$$P_4 = \Delta y \quad q_4 = y_{\max} - y_1$$

\Rightarrow for AB

$$P_1 = 0 \quad q_1 = 10$$

$$P_2 = 0 \quad q_2 = -2$$

$$P_3 = -4 \quad q_3 = 4$$

$$P_4 = 4 \quad q_4 = 2$$

\Rightarrow for CD

$$P_1 = 0 \quad q_1 = 3$$

$$P_2 = 0 \quad q_2 = 6$$

$$P_3 = -3 \quad q_3 = 5$$

$$P_4 = 3 \quad q_4 = 1$$

calculating γ for P_3 because $P_3 = -Ye$
 $\Rightarrow \gamma = \frac{s}{3} \Rightarrow u_1 = \max(0 \text{ and } -s/3) = 0$

$$\Rightarrow \gamma = \frac{1}{3} \Rightarrow v_2 = \min(1 \text{ and } 1/3) = 1/3$$

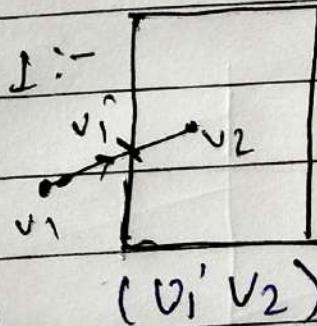
$$\Rightarrow x = x_1 + D_x u \quad y = y = y_1 + D_y u$$

$$\Rightarrow x = 3 + (3-3) \times 1/3, \quad y = 7 + 1/3 \times 3$$

$$\Rightarrow x = 3, \quad y = 8$$

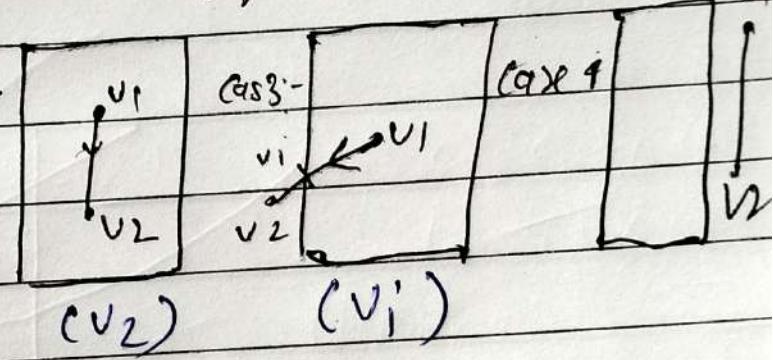
Sutherland Hodgeman Polygon Clipping

case 1:-



store (v_1, v_2)

case 2:-



(v_2)

(v_1')

This is how we can create vertex list