# GROUP 5

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#### INTRODUCTION

In this laboratory, we implemented a genetic algorithm to optimize the **Styblinski–Tang function**, a well-known test function in continuous optimization. It is characterized by a **non-convex landscape** and **multiple local minima**, making it a suitable benchmark for evaluating the performance of global optimization techniques.

The goal was to find the global minimum of the Styblinski–Tang function in two dimensions:

$$f(x,y) = \frac{1}{2} \left( \frac{x^4}{2} - 16x^2 + 5x + \frac{y^4}{2} - 16y^2 + 5y \right)$$

The known global minimum of the function is at  $(x,y)\approx(-2.903,-2.903)(x, y)$ , where the function value is approximately  $f(x,y)\approx-78.332$ 

We applied a genetic algorithm using **Rank Selection** to choose parents, **Gaussian mutation**, and **random interpolation-based crossover**. Importantly, mutation and crossover were applied only to a portion of the population, while the rest was preserved. The population was initialized with values  $x,y \in [-5,5]x$ ,  $y \in [-5,5]x$ ,  $y \in [-5,5]x$ .

#### **IMPLEMENTATION**

The genetic algorithm was implemented in Python, using a modular structure in genetic\_algorithm.py. The algorithm follows the classic structure: initialize  $\rightarrow$  evaluate  $\rightarrow$  select  $\rightarrow$  crossover  $\rightarrow$  mutate  $\rightarrow$  replace.

Below is a breakdown of the key components with relevant code snippets and explanations.

**1. Population Initialization:** The population is initialized randomly within the specified range (in this case, [-5,5][-5,5] for both x and y):

```
population = [
    (random.uniform(*x_range), random.uniform(*y_range))
    for x in range(self.population_size)
]
```

This generates a list of individuals (2D vectors) with uniformly distributed random values.

2. Evaluate the Population: Each individual's fitness is determined by the function value (lower is better).

```
def evaluate_population(self, population):
    fitness = []
    for x in population:
        fitness.append(styblinski_tang_2d(*x))
    return fitness
```

**3. Selection:** We use fitness-proportional selection, where better individuals (lower values) get higher selection weights.

```
def selection(self, population, fitness_values):
    # sort indices of the population by fitness (lowest fitness is best)
   sorted indices = np.argsort(fitness values)
   max_weight = len(population)
    #creating array of length max weights
   weights = [0] * max_weight
   for rank, idx in enumerate(sorted_indices):
       weights[idx] = max weight - rank
   # normalize
   weights = np.array(weights)
    probabilities = weights / np.sum(weights)
    # how many are selected for reproduction
   num_selected = int(self.population_size * self.crossover_rate)
    # randomly select
   selected_indices = np.random.choice(max_weight, size=num_selected, replace=True, p=probabilities)
   return [population[i] for i in selected_indices]
```

**4.** Crossover: Pair parents to create children by blending their coordinates using a random mixing factor  $\alpha$ .

```
def crossover(self, parents):
    np.random.shuffle(parents)
    children = []
    num_parents = len(parents)
    # if there are odd parents, duplicate the random parent
    if num_parents % 2:
       random_index = np.random.randint(num_parents)
        random_parent = parents[random_index]
       parents = np.concatenate([parents, [random_parent]])
        num parents += 1
    for i in range(0, num_parents, 2):
        p1 = np.array(parents[i])
        p2 = np.array(parents[i + 1])
        alpha = np.random.rand()
        # child = parent1 * random(x) + parent2 * (1-random(x))
        child = alpha * p1 + (1 - alpha) * p2
        children.append(child)
    return np.array(children)
```

5. Mutation: With a certain chance, we randomly tweak each coordinate with Gaussian noise.

**6. Evolution loop:** Each generation, we: Evaluate current population, Select parents, Generate and mutate children, Replace part of the population with children

```
for generation in range(self.num_generations):
    fitness_values = self.evaluate_population(population)

best_idx = np.argmin(fitness_values)
    best_solutions.append(population[best_idx])

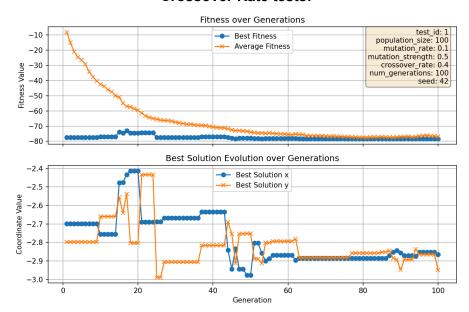
best_fitness_values.append(fitness_values[best_idx])
    average_fitness_values.append(np.average(fitness_values))

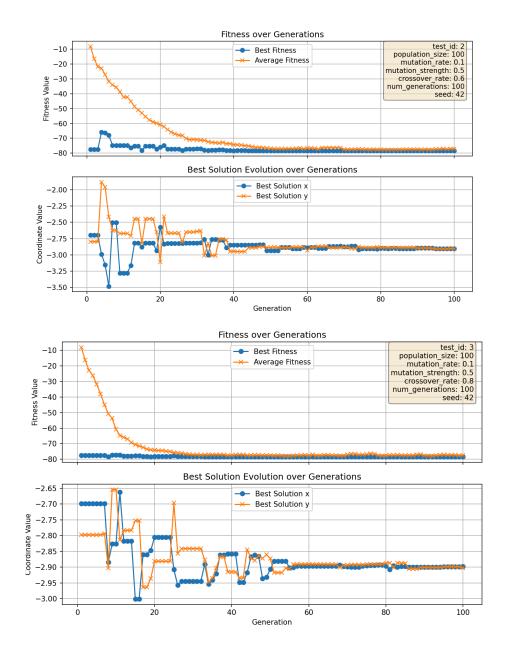
parents_for_reproduction = self.selection(population, fitness_values)
    children = self.crossover(parents_for_reproduction)
    children = self.mutate(children)

# MODIFY THIS
# make is so that each children is replacing a random individual in a population indices = np.random.choice(range(len(population)), size=len(children), replace=False)
    for i, child in zip(indices, children):
        population[i] = child
```

#### Results

#### **Crossover Rate tests:**





# **Effect of Crossover Rate**

We tested three scenarios:

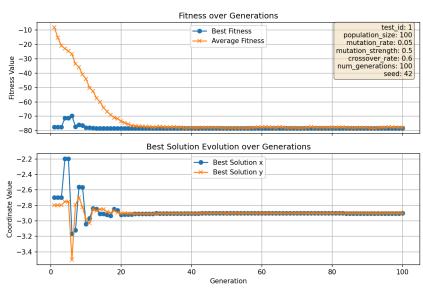
- Low crossover rate (0.4)
- Medium crossover rate (0.6)
- High crossover rate (0.8)

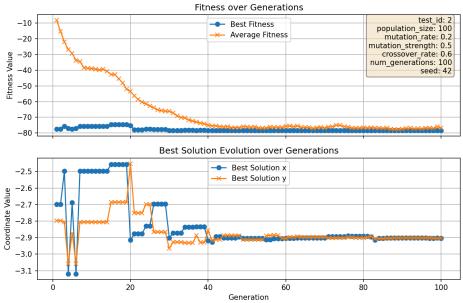
# Summary:

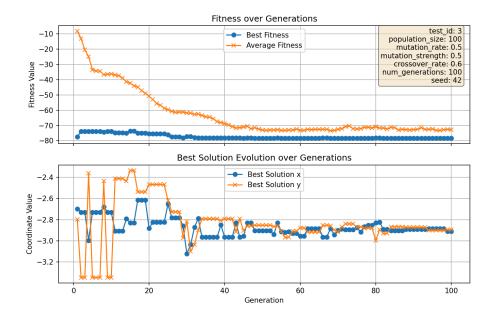
Increasing the crossover rate generally improved the convergence speed, as more individuals participated in generating new offspring.

- At low crossover rates, the algorithm preserved too much of the current population, slowing down progress.
- At medium rates, there was a healthy balance between preservation and exploration.
- At high rates, the algorithm explored the search space aggressively, often reaching near-optimal solutions faster, but also increasing the risk of converging too early

#### **Mutation Rate tests:**







# **Effect of Mutation Rate**

#### We tested:

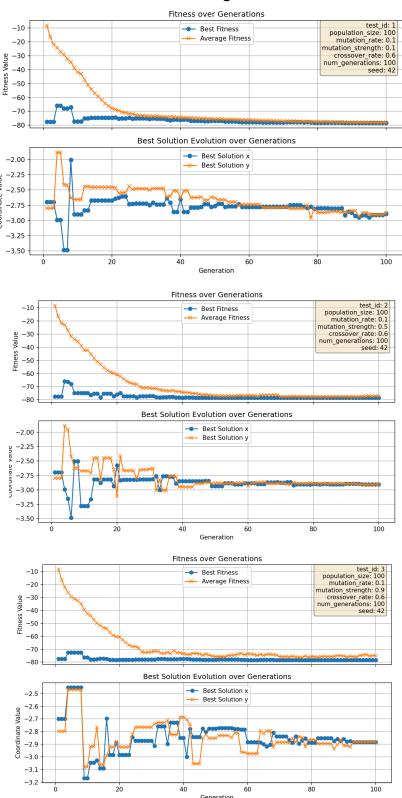
- Low mutation rate (0.05)
- Medium mutation rate (0.2)
- High mutation rate (0.5)

# Summary:

Mutation rate directly influenced the diversity of the population.

- Low mutation rates led to fast convergence, but may be stuck in local minimum
- Medium rates offered a good balance, allowing the algorithm to escape local optima
- High mutation leads to overshooting, and not being able to find the exact minimum

# **Mutation Strength tests:**



#### We tested:

- Low mutation strength (0.1)
- Medium mutation strength (0.5)
- High mutation strength (0.9)

### Summary:

Mutation strength controls how big the changes are when a gene is mutated.

- With low strength, changes are slow and it is ineffective to escape local minimum
- Medium strength helped the algorithm balance local search and broader exploration.
- High strength led to larger jumps which can escape local minima but also overshoot

#### Conclusion

Our experiments confirmed that genetic algorithms can effectively handle the challenges of optimizing non-convex functions with many local minima. However, the algorithm's performance is **highly sensitive to parameter tuning**, particularly the balance between **exploration** (via mutation) and **exploitation** (via selection and crossover).

#### Observations

- Medium crossover rate gives the best results. It balances keeping good solutions and trying new ones.
- Low crossover rate makes the algorithm slow. High crossover rate can lose good solutions too fast.
- Medium mutation rate helps escape local optima while still improving the solution.
- Low mutation rate can get stuck in bad areas. High mutation rate makes the results too random.
- Medium mutation strength makes helpful changes without jumping too far.
- Low mutation strength changes too little. High mutation strength changes too much and can make the search unstable.