This is a companion notebook for the book Deep Learning with Python, Second Edition. For readability, it only contains runnable code blocks and section titles, and omits everything else in the book: text paragraphs, figures, and pseudocode.

If you want to be able to follow what's going on, I recommend reading the notebook side by side with your copy of the book.

This notebook was generated for TensorFlow 2.6.

Deep learning for timeseries

Different kinds of timeseries tasks

A temperature-forecasting example

```
!wget https://s3.amazonaws.com/keras-datasets/jena_climate_2009_2016.csv.zip
!unzip jena_climate_2009_2016.csv.zip
```

Inspecting the data of the Jena weather dataset

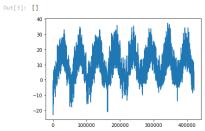
```
import os
fname = os.path.join("jena_climate_2009_2016.csv")
 lines = data.split("\n")
header = lines[0].split(",")
lines = lines[1:]
print(header)
print(len(lines))
[""Date Time"', '"p (mbar)"', '"T (degc)"', '"Tpot (K)"', '"Tdew (degc)"', '"rh (%)"', '"VPmax (mbar)"', '"VPact (mbar)"', '"VPdef (mbar)"', '"sh (g/k 420451 ""), '"H2OC (mmol/mol)"', '"rho (g/m*3)"', '"wv (m/s)"', '"wd (deg)"']
```

Parsing the data

```
In [2]:
                                     import numpy as np
temperature = np.zeros((len(lines),))
raw_data = np.zeros((len(lines), len(header) - 1))
for i, line in enumerate(lines):
    values = [flost(x) for x in line.split(",")[1:]]
    temperature[i] = values[i]
    raw_data[i, :] = values[:]
```

Plotting the temperature timeseries

```
from matplotlib import pyplot as plt
plt.plot(range(len(temperature)), temperature)
```



Plotting the first 10 days of the temperature timeseries

```
In [4]:
         plt.plot(range(1440), temperature[:1440])
```


Computing the number of samples we'll use for each data split

```
In [5]:
    num_train_samples = int(0.5 * len(raw_data))
    num_val_samples = int(0.25 * len(raw_data))
    num_test_samples = len(raw_data) - num_test_samples = len(raw_data) - num_train_samples - num_val_samples
    print("num_train_samples:", num_train_samples)
    print("num_val_samples:", num_val_samples)
    print("num_test_samples:", num_test_samples)

num_train_samples: 210225
    num_val_samples: 105112
    num_test_samples: 105114
```

Preparing the data

Normalizing the data

```
In [6]:
    mean = raw_data[:num_train_samples].mean(axis=0)
    raw_data -= mean
    std = raw_data[:num_train_samples].std(axis=0)
    raw_data /= std
```

```
import numpy as np
from tensorflow import keras
int_sequence inp_arange(10)
dummy_dataset = keras_utils_timeseries_dataset_from_array(
    data=int_sequence[:3],
    targets=int_sequence[3:],
    sequence_length=3,
    batch_size=2,
)

for inputs, targets in dummy_dataset:
    for i in range(inputs_shape[e]):
        print([int(x) for x in inputs[i]], int(targets[i]))

[0, 1, 2] 3
[1, 2, 3] 4
[2, 3, 4] 5
[3, 4, 5] 6
[4, 5, 6] 7
```

Instantiating datasets for training, validation, and testing

```
sampling_rate = 6
sequence_length = 120
delay = sampling_rate * (sequence_length + 24 - 1)
batch_size = 256

train_dataset = keras.utils.timeseries_dataset_from_array(
    raw_data[:-delay],
    targets-temperature[delay:],
    sampling_rate-sampling_rate,
    sequence_length-sequence_length,
    shuftle=True,
    batch_size-batch_size,
    start_index=0,
    end_index=num_train_samples)

val_dataset = keras.utils.timeseries_dataset_from_array(
    raw_data[:-delay],
    targets-temperature[delay:],
    sampling_rate-sampling_rate,
    sequence_lengths-sequence_length,
    shuftle=True,
    batch_size-batch_size,
    start_index=num_train_samples,
    end_index=num_train_samples = num_val_samples)

test_dataset = keras.utils.timeseries_dataset_from_array(
    raw_data[:-delay],
    targets-temperature[delay:],
    sampling_rate-sampling_rate,
    sequence_lengths-sequence_length,
    shuftle=True,
    batch_size-batch_size,
    start_index=num_train_samples + num_val_samples)
```

```
In [9]:
    for samples, targets in train_dataset:
        print("samples shape:", samples.shape)
        print("targets shape:", targets.shape)
        break

samples shape: (256, 120, 14)
targets.shape: (256,)
```

A common-sense, non-machine-learning baseline

Computing the common-sense baseline MAE

```
In [10]:

def evaluate_naive_method(dataset):
    total_abs_err = 0.
    samples_seen = 0
    for samples, targets in dataset:
        preds = samples[:, -1, 1] * std[1] + mean[1]
        total_abs_err += np.sum(np.abs(preds - targets))
        samples_seen += samples.shape[0]
        return total_abs_err / samples_seen

print(f"Validation MAE: {evaluate_naive_method(val_dataset):.2f}")

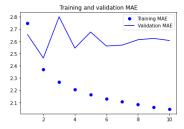
print(f"Test MAE: {evaluate_naive_method(test_dataset):.2f}")
```

Let's try a basic machine-learning model

Training and evaluating a densely connected model

Plotting results

```
import matplotlib.pyplot as plt
loss = history.history["mae"]
val_loss = history.history["val_mae"]
epochs = range(1, len(loss) + 1)
plt.figure()
plt.plot(epochs, loss, "bo", label="Training MAE")
plt.plot(epochs, val_loss, "b", label="validation MAE")
plt.title("Training and validation MAE")
plt.tend()
plt.show()
```



Let's try a 1D convolutional model

```
inputs = keras.Input(shape=(sequence_length, raw_data.shape[-1]))

x = layers.Comv1D(8, 24, activation="relu")(inputs)

x = layers.Gomv1D(8, 22, activation="relu")(x)

x = layers.Gomv1D(8, 6, activation="relu")(x)

x = layers.Gomv1D(8, 6, activation="relu")(x)

callbacks = [activation="relu")(x)

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callbacks = [activation="relu")(x)

save_best_only="row")

pmodel = keras.Rodel(inputs, outputs)

callbacks = [activation="relu"](x)

save_best_only="row")

podel = keras.Rodel(inputs, outputs)

callbacks = [activation="resprop", loss="mac"], history = model.fit(train_dataset, epochs=10, validation_dataset, epochs=10, val
```

A first recurrent baseline

A simple LSTM-based model

```
inputs = keras.Imput(shape=(sequence_length, raw_data.shape[-1]))
    x = layers.isTM(15)(inputs)
    outputs = layers.lsTM(15)(inputs)
    inputs = layers.lsTM(15)(inputs)
    inpu
```

```
import numpy as np
timesteps = 100
input_features = 32
output_features = 34
inputs = np.random.random((timesteps, input_features))
state_t = np.zeros((output_features, input_features))
W = np.random.random((output_features, input_features))
U = np.random.random((output_features, output_features))
b = np.random.random((output_features, output_features))
successive_outputs = []
for input_t in inputs:
    output_t = np.tanh(np.dot(W, input_t) + np.dot(U, state_t) + b)
    successive_outputs.append(output_t)
    state_t = output_t
final_output_sequence = np.stack(successive_outputs, axis=0)
```

A recurrent layer in Keras

An RNN layer that can process sequences of any length

```
In [16]:
    num_features = 14
    inputs = keras.Input(shape=(None, num_features))
    outputs = layers.SimpleRNN(16)(inputs)
```

An RNN layer that returns only its last output step

```
In [17]:
    num_features = 14
    steps = 120
    inputs = keras.Input(shape=(steps, num_features))
    outputs = layers.SimpleRNN(16, return_sequences=False)(inputs)
    print(outputs.shape)

(None, 16)
```

An RNN layer that returns its full output sequence

```
In [18]

steps = 120
inputs = keras.Input(shape=(steps, num_features))
outputs = layers.SimpleRRM(16, return_sequences-True)(inputs)

(None, 120, 16)

Stacking RNN layers

In [19]:

stepsts = keras.Input(shape=(steps, num_features))
x = layers.SimpleRRM(16, return_sequences-True)(steps, num_features))
x = layers.SimpleRRM(16, return_sequences-True)(sy)
outputs = layers.SimpleRRM(16, return_sequences-True)(x)

Advanced use of recurrent neural netWorks
```

Using recurrent dropout to fight overfitting

Training and evaluating a dropout-regularized LSTM

```
callbacks = [
    keras.callbacks.ModelCheckpoint("jena_lste_dropout.keras",
    save_best_only-True)
]
model.compile(optimizer-"rmsprop", loss-"mse", metrics-["mae"])
history = model.fit(train_dataset,
epochs-50,
validation_datasval_dataset,
callbacks-callbacks)
MARKING:tensorflow:Layer lstm_1 will not use cuRNN kernels since it doesn't meet the criteris. It will use a generic GPU kernel as fallback when run ng on GPU.

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        -----] - 552s 673ms/step - loss: 9.7739 - mae: 2.4231 - val_loss: 9.7975 - val_mae: 2.4368
        Epoch 45/50
819/819 [===============] - 552s 674ms/step - loss: 8.9227 - mae: 2.3089 - val_loss: 10.3620 - val_mae: 2.5142
Epoch 46/50
```

```
In [21]:
    inputs = keras.Input(shape=(sequence_length, num_features))
    x = layers.LSTM(32, recurrent_dropout=0.2, unroll=True)(inputs)
```

WARNING:tensorflow:Layer lstm_2 will not use cuDNN kernels since it doesn't meet the criteria. It will use a generic GPU kernel as fallback when running on GPU.

Stacking recurrent layers

Training and evaluating a dropout-regularized, stacked GRU model

Using bidirectional RNNs

Training and evaluating a bidirectional LSTM

Going even further

Summary