Distributed Systems

ECE428

Lecture 10

Adopted from Spring 2021

Today's agenda

- Mutual Exclusion
 - Chapter 15.2
- Leader Election
 - Chapter 15.3

Problem statement for mutual exclusion

- Critical Section Problem:
 - Piece of code (at all processes) for which we need to ensure there is <u>at most one process</u> executing it at any point of time.
- Each process can call three functions
 - enter() to enter the critical section (CS)
 - AccessResource() to run the critical section code
 - exit() to exit the critical section

Mutual exclusion in distributed systems

 Processes communicating by passing messages.

Cannot share variables like semaphores!

 How do we support mutual exclusion in a distributed system?

Mutual exclusion in distributed systems

- Our focus today: Classical algorithms for mutual exclusion in distributed systems.
 - Central server algorithm
 - Ring-based algorithm
 - Ricart-Agrawala Algorithm
 - Maekawa Algorithm

System Model

 Each pair of processes is connected by reliable channels (such as TCP).

 Messages sent on a channel are eventually delivered to a recipient, and in FIFO order.

- Processes do not fail.
 - Fault-tolerant variants exist in literature.

Analysis of Central Algorithm

- Safety at most one process in CS
 - Exactly one token
- Liveness every request for CS granted eventually
 - With N processes in system, queue has at most N processes
 - If each process exits CS eventually and no failures, liveness guaranteed
- Ordering:
 - FIFO ordering guaranteed in order of requests received at leader
 - Not in the order in which requests were sent or the order in which processes enter CS!

Analyzing Performance

Three metrics:

- Bandwidth: the total number of messages sent in each enter and exit operation.
- Client delay: delay incurred by a process at each enter and exit operation (when no other process is in CS, or waiting)
 - We will focus on the client delay for the enter operation.
- Synchronization delay: the time interval between one process exiting the critical section and the next process entering it (when there is *only one* process waiting).
 Measure of the *throughput* of the system.

Analysis of Central Algorithm

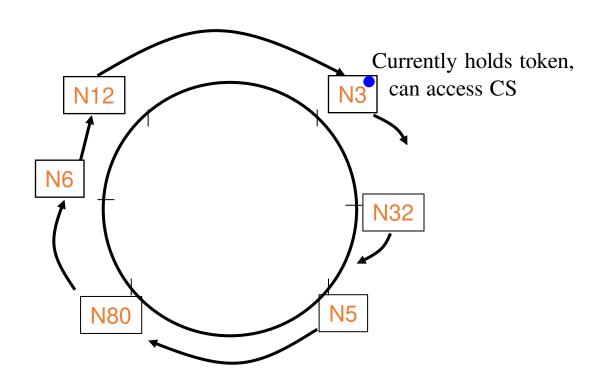
- Bandwidth: the total number of messages sent in each enter and exit operation.
 - 2 messages for enter
 - 1 message for exit
- Client delay: delay incurred by a process at each enter and exit operation (when no other process is in, or waiting)
 - 2 message latencies (1 round-trip, request + grant) on enter.
- Synchronization delay: the time interval between one process exiting the critical section and the next process entering it (when there is *only one* process waiting)
 - 2 message latencies (release + grant)

Limitations of Central Algorithm

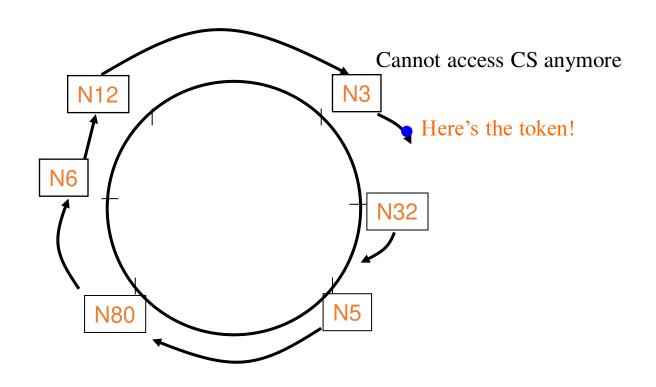
• The leader is the performance bottleneck and single point of failure.

Mutual exclusion in distributed systems

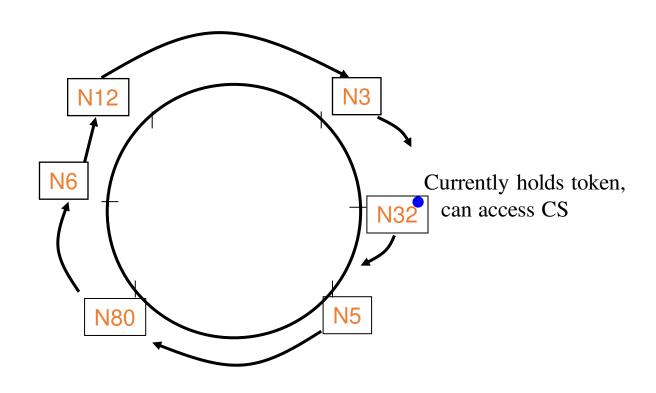
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Token:



Token:



Token:

- N Processes organized in a virtual ring
- Processes send message to their successor in ring
- Exactly 1 token
- enter()
 - Wait until you get token
- exit() // already have token
 - Pass on token to ring successor
- If receive token, and not currently in enter(), just pass on token to ring successor

Analysis of Ring-based algorithm

- Safety
 - Exactly one token
- Liveness
 - Token eventually loops around ring and reaches requesting process (we assume no failures)
- Ordering
 - Token not always obtained in order of enter events.

Analysis of ring-based algorithm

- Bandwidth
 - Per enter, 1 message at requesting process but up to *N* messages throughout system.
 - 1 message sent per exit.
 - Constantly consumes bandwidth even when no process requires entry to the critical section (except when a process is executing critical section).

Analysis of ring-based algorithm

- Client delay:
 - Best case: just received token
 - Worst case: just sent token to neighbor
 - 0 to N message transmissions after entering enter()
- Synchronization delay between one process' exit() from the CS and the next process' enter():
 - Best case: process in enter() is successor of process in exit()
 - Worst case: process in enter() is predecessor of process in exit()
 - Between 1 and (N-1) message transmissions.

Can we improve upon O(n) client and synchronization delays?

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Ricart-Agrawala's Algorithm

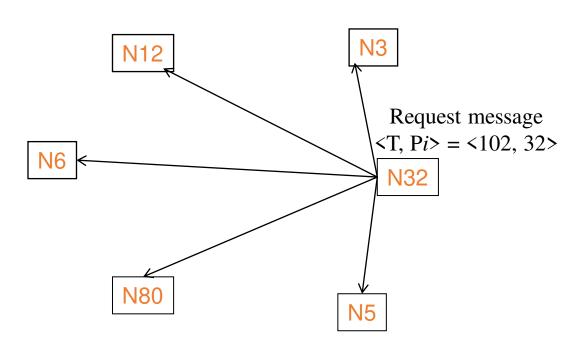
- Classical algorithm from 1981
- Invented by Glenn Ricart (NIH) and Ashok Agrawala (U. Maryland)
- No token.
- Uses the notion of causality and multicast.
- Has lower waiting time to enter CS than Ring-Based approach.

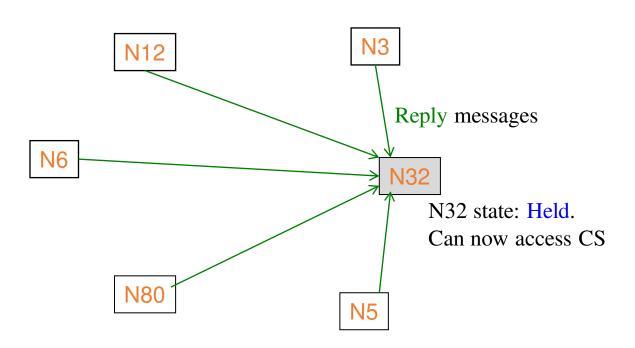
Key Idea: Ricart-Agrawala Algorithm

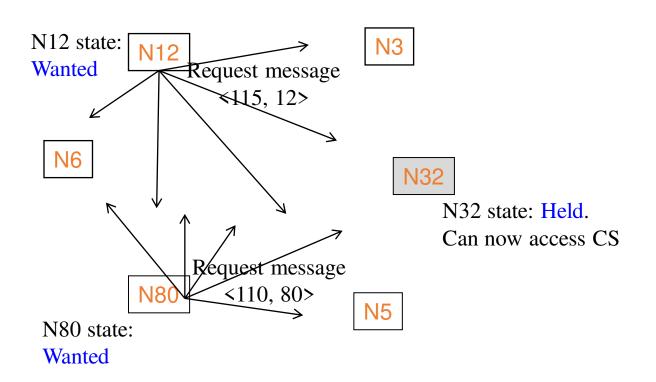
- enter() at process Pi
 - multicast a request to all processes
 - Request: <T, Pi>, where T = current Lamport timestamp at Pi
 - Wait until all other processes have responded positively to request
- Requests are granted in order of causality.
- <T, Pi> is used lexicographically: Pi in request <T, Pi> is used to break ties (since Lamport timestamps are not unique for concurrent events).

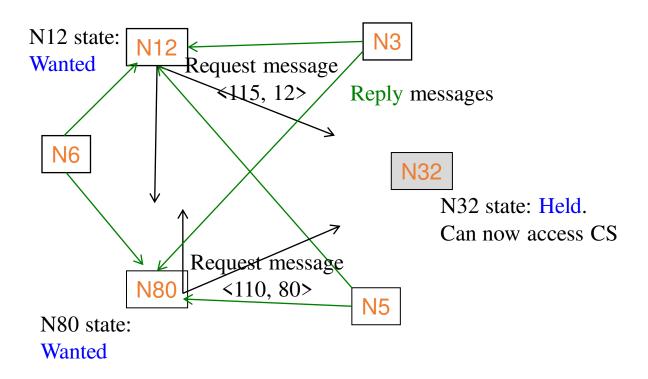
Messages in RA Algorithm

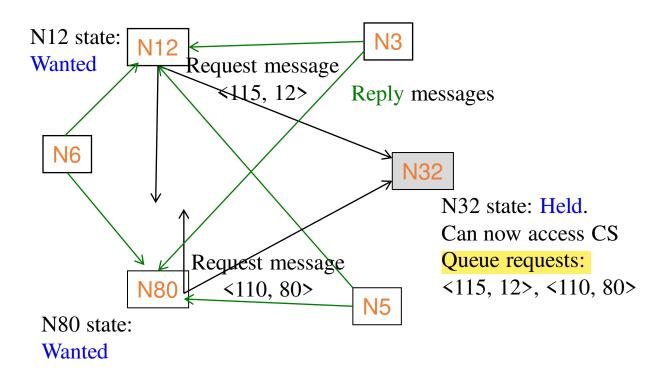
- enter() at process Pi
 - set state to Wanted
 - multicast "Request" <Ti, Pi> to all other processes, where Ti = current Lamport timestamp at Pi
 - wait until <u>all</u> other processes send back "Reply"
 - change state to <u>Held</u> and enter the CS
- On receipt of a Request <Tj, j> at Pi (i ≠ j):
 - if (state = Held) or (state = Wanted & (Ti, i) < (Tj, j))
 // lexicographic ordering in (Tj, j), Ti is Lamport timestamp of Pi's request add request to local queue (of waiting requests)
 else send "Reply" to Pj
- exit() at process Pi
 - change state to <u>Released</u> and "Reply" to <u>all</u> queued requests.

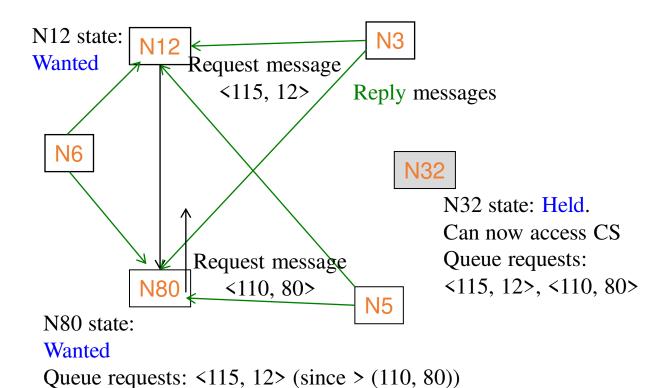


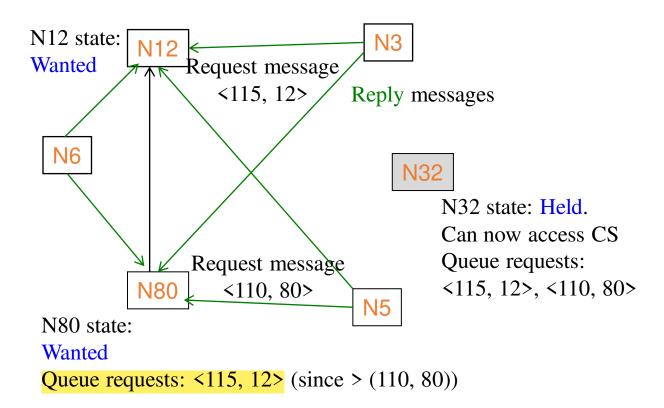


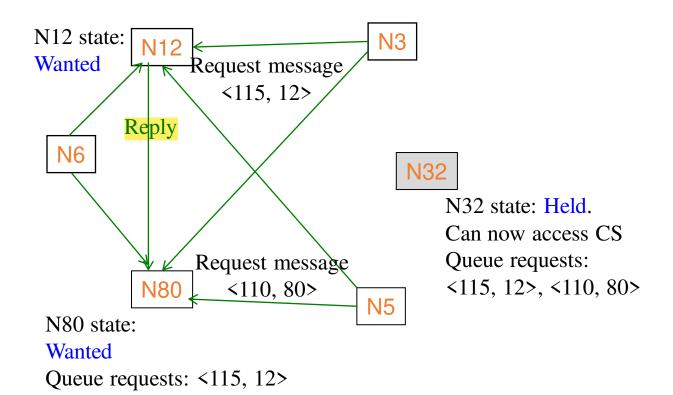


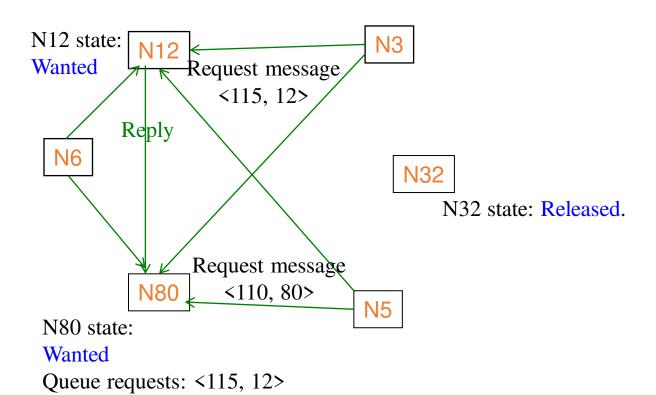


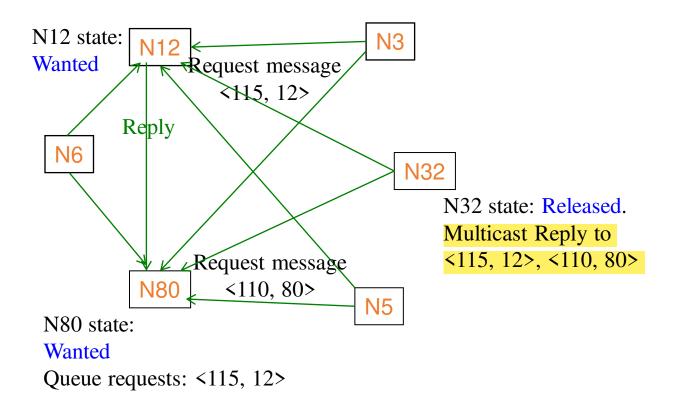


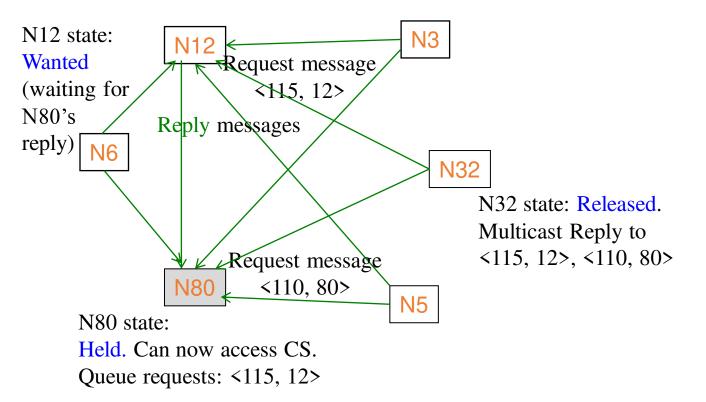












Analysis: Ricart-Agrawala Algorithm

Safety

- Two processes Pi and Pj cannot both have access to CS
 - If they did, then both would have sent Reply to each other.
 - Thus, (Ti, i) < (Tj, j) and (Tj, j) < (Ti, i), which are together not possible.
 - What if (Ti, i) < (Tj, j) and Pi replied to Pj's request before it created its own request?
 - But then, causality and Lamport timestamps at Pi implies that Ti > Tj, which is a contradiction.
 - So this situation cannot arise.

Analysis: Ricart-Agrawala Algorithm

Safety

 Two processes Pi and Pj cannot both have access to CS.

Liveness

 Worst-case: wait for all other (N-1) processes to send Reply.

Ordering

 Requests with lower Lamport timestamps are granted earlier.

Analysis: Ricart-Agrawala Algorithm

- Bandwidth:
 - 2*(N-1) messages per enter operation
 - N-1 unicasts for the multicast request + N-1 replies
 - Maybe fewer depending on the multicast mechanism.
 - N-1 unicasts for the multicast release per exit operation
 - Maybe fewer depending on the multicast mechanism.
- Client delay:
 - one round-trip time
- Synchronization delay:
 - one message transmission time
- Client and synchronization delays have gone down to O(1).
- Bandwidth usage is still high. Can we bring it down further?

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Maekawa's Algorithm: Key Idea

 Ricart-Agrawala requires replies from all processes in group.

Instead, get replies from only some processes in group.

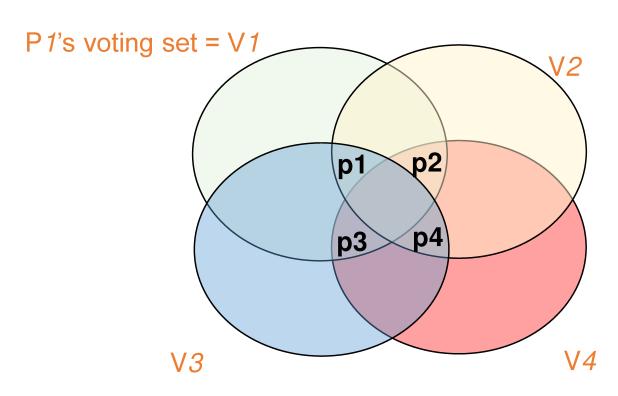
 But ensure that only one process is given access to CS (Critical Section) at a time.

Maekawa's Voting Sets

- Each process Pi is associated with a <u>voting set</u> Vi (subset of processes).
- Each process belongs to its own voting set.
- The intersection of any two voting sets must be non-empty.

A way to construct voting sets

One way of doing this is to put N processes in a \sqrt{N} by \sqrt{N} matrix and for each Pi, its voting set Vi = row containing Pi + column containing Pi. Size of voting set = $2*\sqrt{N-1}$.



p1	p2
p3	p4

Maekawa: Key Differences From Ricart-Agrawala

- Each process requests permission from only its voting set members.
 - Not from all

- Each process (in a voting set) gives permission to at most one process at a time.
 - Not to all

Actions

- state = Released, voted = false
- enter() at process Pi:
 - state = Wanted
 - Multicast Request message to all processes in Vi
 - Wait for Reply (vote) messages from all processes in Vi (including vote from self)
 - state = Held
- exit() at process Pi:
 - state = Released
 - Multicast Release to all processes in Vi

Actions (contd.)

```
 When Pi receives a Request from Pj:
     if (state == Held OR voted = true)
         queue Request
     else
     send Reply to Pj and set voted = true
```

```
 When Pi receives a Release from Pj:
     if (queue empty)
     voted = false
     else
     dequeue head of queue, say Pk
     Send Reply only to Pk
     voted = true
```

Size of Voting Sets

- Each voting set is of size K.
- Each process belongs to M other voting sets.
- Maekawa showed that K=M=approx. \sqrt{N} works best.

Optional self-study: Why √N?

- Let each voting set be of size K and each process belongs to M other voting sets.
- Total number of voting set members (processes may be repeated) = K*N
- But since each process is in *M* voting sets
 - K*N = M*N => K = M (1)
- Consider a process Pi
 - Total number of voting sets = members present in Pi's voting set and all their voting sets = (M-1)*K + 1
 - All processes in group must be in above
 - To minimize the overhead at each process (*K*), need each of the above members to be unique, i.e.,
 - N = (M-1)*K + 1
 - N = (K-1)*K + 1 (due to (1))
 - K ~ √N

Size of Voting Sets

- Each voting set is of size K.
- Each process belongs to M other voting sets.
- Maekawa showed that K=M=approx. \sqrt{N} works best.
- Matrix technique gives a voting set size of $2*\sqrt{N-1} = O(\sqrt{N})$.

Performance: Maekawa Algorithm

Bandwidth

- $2K = 2\sqrt{N}$ messages per enter
- $K = \sqrt{N}$ messages per exit
- Better than Ricart and Agrawala's (2*(N-1) and N-1 messages)
- \sqrt{N} quite small. $N \sim 1$ million => $\sqrt{N} = 1$ K
- Client delay:
 - One round trip time
- Synchronization delay:
 - 2 message transmission times

Safety

- When a process Pi receives replies from all its voting set Vi members, no other process Pj could have received replies from all its voting set members Vj.
 - Vi and Vj intersect in at least one process say Pk.
 - But Pk sends only one Reply (vote) at a time, so it could not have voted for both Pi and Pj.

Liveness

- Does not guarantee liveness, since can have a deadlock.
- System of 6 processes {0,1,2,3,4,5}. 0,1,2 want to enter critical section:
 - $V_0 = \{0, 1, 2\}$:
 - 0, 2 send reply to 0, but 1 sends reply to 1;
 - $V_1 = \{1, 3, 5\}$:
 - 1, 3 send reply to 1, but 5 sends reply to 2;
 - $V_2 = \{2, 4, 5\}$:
 - 4, 5 send reply to 2, but 2 sends reply to 0;
- Now, 0 waits for 1's reply, 1 waits for 5's reply (5 waits for 2 to send a release), and 2 waits for 0 to send a release. Hence, deadlock!

Analysis: Maekawa Algorithm

Safety:

 When a process Pi receives replies from all its voting set Vi members, no other process Pj could have received replies from all its voting set members Vj.

Liveness

Not satisfied. Can have deadlock!

Ordering:

· Not satisfied.

Next Class

 How can we extend Maekawa's algorithm to break deadlock?