# **Synchronization: Advanced**

15-213: Introduction to Computer Systems 25<sup>th</sup> Lecture, Nov. 24, 2015

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# **Review: Semaphores**

- **Semaphore:** non-negative global integer synchronization variable. Manipulated by *P* and *V* operations.
- P(s)
  - If s is nonzero, then decrement s by 1 and return immediately.
  - If s is zero, then suspend thread until s becomes nonzero and the thread is restarted by a V operation.
  - After restarting, the P operation decrements s and returns control to the caller.
- V(s):
  - Increment s by 1.
  - If there are any threads blocked in a P operation waiting for s to become non-zero, then restart exactly one of those threads, which then completes its P operation by decrementing s.
- Semaphore invariant: (s >= 0)

# Review: Using semaphores to protect shared resources via mutual exclusion

#### Basic idea:

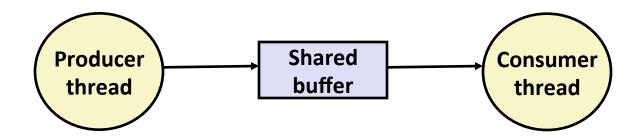
- Associate a unique semaphore mutex, initially 1, with each shared variable (or related set of shared variables)
- Surround each access to the shared variable(s) with P(mutex) and V(mutex) operations

```
mutex = 1
P(mutex)
cnt++
V(mutex)
```

# Using Semaphores to Coordinate Access to Shared Resources

- Basic idea: Thread uses a semaphore operation to notify another thread that some condition has become true
  - Use counting semaphores to keep track of resource state and to notify other threads
  - Use mutex to protect access to resource
- Two classic examples:
  - The Producer-Consumer Problem
  - The Readers-Writers Problem

### **Producer-Consumer Problem**



#### Common synchronization pattern:

- Producer waits for empty slot, inserts item in buffer, and notifies consumer
- Consumer waits for *item*, removes it from buffer, and notifies producer

#### Examples

- Multimedia processing:
  - Producer creates MPEG video frames, consumer renders them
- Event-driven graphical user interfaces
  - Producer detects mouse clicks, mouse movements, and keyboard hits and inserts corresponding events in buffer
  - Consumer retrieves events from buffer and paints the display

## Producer-Consumer on an *n*-element Buffer

- Requires a mutex and two counting semaphores:
  - mutex: enforces mutually exclusive access to the buffer
  - slots: counts the available slots in the buffer
  - items: counts the available items in the buffer
- Implemented using a shared buffer package called sbuf.

# sbuf Package - Declarations

```
#include "csapp.h"
typedef struct {
   int *buf; /* Buffer array */
                   /* Maximum number of slots */
   int n:
   int front;  /* buf[(front+1)%n] is first item */
   int rear;  /* buf[rear%n] is last item */
   sem_t mutex; /* Protects accesses to buf */
   sem_t slots; /* Counts available slots */
   sem t items; /* Counts available items */
} sbuf t;
void sbuf_init(sbuf_t *sp, int n);
void sbuf deinit(sbuf t *sp);
void sbuf insert(sbuf t *sp, int item);
int sbuf remove(sbuf t *sp);
```

# sbuf Package - Implementation

Initializing and deinitializing a shared buffer:

```
/* Create an empty, bounded, shared FIFO buffer with n slots */
void sbuf_init(sbuf_t *sp, int n)
{
    sp->buf = Calloc(n, sizeof(int));
                                 /* Buffer holds max of n items */
    sp->n = n;
    sp->front = sp->rear = 0;  /* Empty buffer iff front == rear */
    Sem_init(&sp->mutex, 0, 1);  /* Binary semaphore for locking */
Sem_init(&sp->slots, 0, n);  /* Initially, buf has n empty slots */
    Sem_init(&sp->items, 0, 0); /* Initially, buf has 0 items */
/* Clean up buffer sp */
void sbuf deinit(sbuf t *sp)
    Free(sp->buf);
```

# sbuf Package - Implementation

Inserting an item into a shared buffer:

# sbuf Package - Implementation

#### Removing an item from a shared buffer:

### **Readers-Writers Problem**

Generalization of the mutual exclusion problem

#### Problem statement:

- Reader threads only read the object
- Writer threads modify the object
- Writers must have exclusive access to the object
- Unlimited number of readers can access the object

#### Occurs frequently in real systems, e.g.,

- Online airline reservation system
- Multithreaded caching Web proxy

### **Variants of Readers-Writers**

- First readers-writers problem (favors readers)
  - No reader should be kept waiting unless a writer has already been granted permission to use the object
  - A reader that arrives after a waiting writer gets priority over the writer
- Second readers-writers problem (favors writers)
  - Once a writer is ready to write, it performs its write as soon as possible
  - A reader that arrives after a writer must wait, even if the writer is also waiting
- Starvation (where a thread waits indefinitely) is possible in both cases

### Solution to First Readers-Writers Problem

#### **Readers:**

```
int readcnt; /* Initially = 0 */
sem t mutex, w; /* Initially = 1 */
void reader(void)
    while (1) {
        P(&mutex);
        readcnt++;
        if (readcnt == 1) /* First in */
            P(&w);
        V(&mutex);
        /* Critical section */
        /* Reading happens */
        P(&mutex);
        readcnt--:
        if (readcnt == 0) /* Last out */
            V(&w);
        V(&mutex);
```

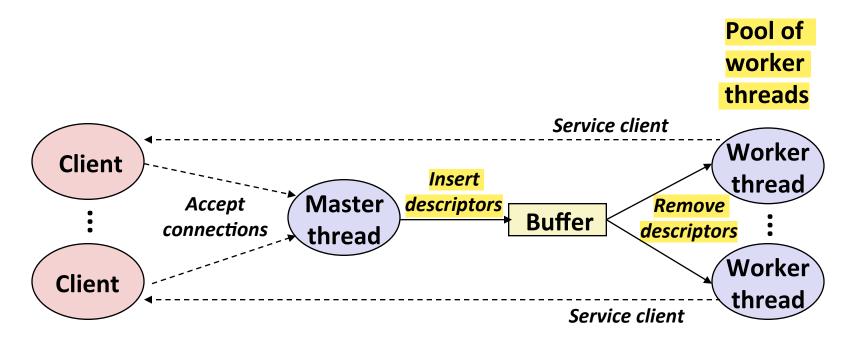
#### **Writers:**

```
void writer(void)
{
    while (1) {
        P(&w);

        /* Critical section */
        /* Writing happens */

        V(&w);
    }
}
```

# Putting It All Together: Prethreaded Concurrent Server



```
sbuf t sbuf; /* Shared buffer of connected descriptors */
int main(int argc, char **argv)
{
    int i, listenfd, connfd;
    socklen t clientlen;
    struct sockaddr_storage clientaddr;
    pthread t tid;
    listenfd = Open listenfd(argv[1]);
    sbuf_init(&sbuf, SBUFSIZE);
    for (i = 0; i < NTHREADS; i++) /* Create worker threads */</pre>
       Pthread create(&tid, NULL, thread, NULL);
    while (1) {
       clientlen = sizeof(struct sockaddr storage);
       connfd = Accept(listenfd, (SA *) &clientaddr, &clientlen);
       sbuf insert(&sbuf, connfd); /* Insert connfd in buffer */
    }
                                                      echoservert pre.c
```

#### Worker thread routine:

```
void *thread(void *vargp)
{
    Pthread_detach(pthread_self());
    while (1) {
        int connfd = sbuf_remove(&sbuf); /* Remove connfd from buf */
        echo_cnt(connfd); /* Service client */
        Close(connfd);
    }
}
```

### echo\_cnt initialization routine:

```
static int byte_cnt;  /* Byte counter */
static sem_t mutex;  /* and the mutex that protects it */

static void init_echo_cnt(void)
{
    Sem_init(&mutex, 0, 1);
    byte_cnt = 0;
}

echo_cnt.c
```

#### Worker thread service routine:

```
void echo cnt(int connfd)
{
    int n;
    char buf[MAXLINE];
    rio t rio;
    static pthread once t once = PTHREAD ONCE INIT;
    Pthread_once(&once, init_echo_cnt);
    Rio readinitb(&rio, connfd);
    while((n = Rio readlineb(&rio, buf, MAXLINE)) != 0) {
       P(&mutex):
       byte cnt += n;
       printf("thread %d received %d (%d total) bytes on fd %d\n",
               (int) pthread_self(), n, byte_cnt, connfd);
       V(&mutex);
       Rio_writen(connfd, buf, n);
                                                             echo cnt.o
```

# **Crucial concept: Thread Safety**

- Functions called from a thread must be thread-safe
- Def: A function is thread-safe iff it will always produce correct results when called repeatedly from multiple concurrent threads
- Classes of thread-unsafe functions:
  - Class 1: Functions that do not protect shared variables
  - Class 2: Functions that keep state across multiple invocations
  - Class 3: Functions that return a pointer to a static variable
  - Class 4: Functions that call thread-unsafe functions ©

# **Thread-Unsafe Functions (Class 1)**

- Failing to protect shared variables
  - Fix: Use *P* and *V* semaphore operations
  - Example: goodcnt.c
  - Issue: Synchronization operations will slow down code

# **Thread-Unsafe Functions (Class 2)**

- Relying on persistent state across multiple function invocations
  - Example: Random number generator that relies on static state

```
static unsigned int next = 1;
/* rand: return pseudo-random integer on 0..32767 */
int rand(void)
    next = next*1103515245 + 12345;
    return (unsigned int)(next/65536) % 32768;
/* srand: set seed for rand() */
void srand(unsigned int seed)
   next = seed;
```

### **Thread-Safe Random Number Generator**

- Pass state as part of argument
  - and, thereby, eliminate global state

```
/* rand_r - return pseudo-random integer on 0..32767 */
int rand_r(int *nextp)
{
    *nextp = *nextp * 1103515245 + 12345;
    return (unsigned int)(*nextp/65536) % 32768;
}
```

Consequence: programmer using rand\_r must maintain seed

# **Thread-Unsafe Functions (Class 3)**

- Returning a pointer to a static variable
- Fix 1. Rewrite function so caller passes address of variable to store result
  - Requires changes in caller and callee
- Fix 2. Lock-and-copy
  - Requires simple changes in caller (and none in callee)
  - However, caller must free memory.

# **Thread-Unsafe Functions (Class 4)**

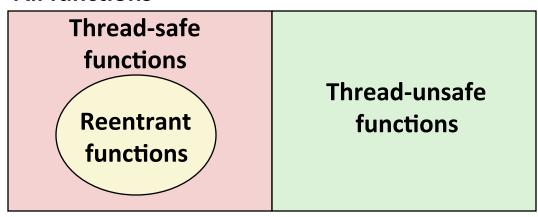
#### Calling thread-unsafe functions

- Calling one thread-unsafe function makes the entire function that calls it thread-unsafe
- Fix: Modify the function so it calls only thread-safe functions ©

### **Reentrant Functions**

- Def: A function is reentrant iff it accesses no shared variables when called by multiple threads.
  - Important subset of thread-safe functions
    - Require no synchronization operations
    - Only way to make a Class 2 function thread-safe is to make it reetnrant (e.g., rand r)

#### All functions



# **Thread-Safe Library Functions**

- All functions in the Standard C Library (at the back of your K&R text) are thread-safe
  - Examples: malloc, free, printf, scanf
- Most Unix system calls are thread-safe, with a few exceptions:

Thread-unsafe function	Class	Reentrant version
asctime	3	asctime_r
ctime	3	ctime_r
gethostbyaddr	3	gethostbyaddr_r
gethostbyname	3	gethostbyname_r
inet_ntoa	3	(none)
localtime	3	localtime_r
rand	2	rand_r

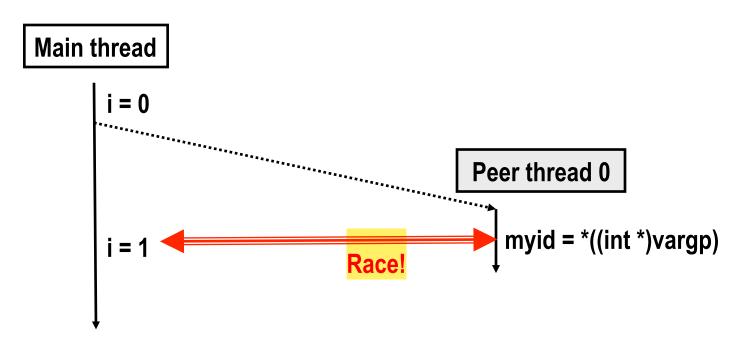
## One worry: Races

 A <u>race</u> occurs when <u>correctness of the program</u> depends on one thread reaching point x before another thread reaches point y

```
/* A threaded program with a race */
int main()
                                     N threads are sharing i
    pthread t tid[N];
    int i; ←
    for (i = 0; i < N; i++)
        Pthread_create(&tid[i], NULL, thread, &i);
    for (i = 0; i < N; i++)
        Pthread join(tid[i], NULL);
    exit(0);
/* Thread routine */
void *thread(void *vargp)
    int myid = *((int *)vargp);
    printf("Hello from thread %d\n", myid);
    return NULL:
                                               race.c
```

### **Race Illustration**

```
for (i = 0; i < N; i++)
Pthread_create(&tid[i], NULL, thread, &i);</pre>
```



- Race between increment of i in main thread and deref of vargp in peer thread:
  - If deref happens while i = 0, then OK
  - Otherwise, peer thread gets wrong id value

# Could this race really occur?

#### Main thread

#### Peer thread

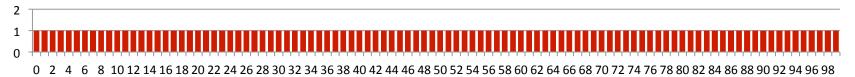
```
void *thread(void *vargp) {
    Pthread_detach(pthread_self());
    int i = *((int *)vargp);
    save_value(i);
    return NULL;
}
```

#### Race Test

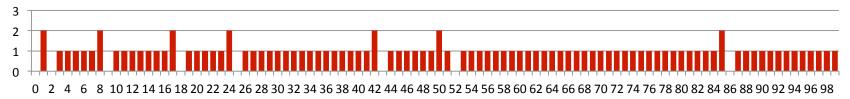
- If no race, then each thread would get different value of i
- Set of saved values would consist of one copy each of 0 through 99

# **Experimental Results**

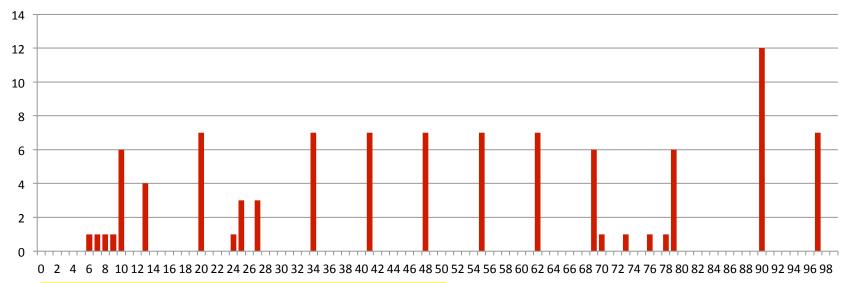
#### No Race



#### Single core laptop



#### **Multicore** server



### The race can really happen!

### Race Elimination

```
/* Threaded program without the race */
    int main()
                                         Avoid unintended sharing of
    {
        pthread t tid[N];
                                         state
        int i, *ptr;
        for (i = 0; i < N; i++) {
            ptr = Malloc(sizeof(int));
            *ptr = i;
            Pthread_create(&tid[i], NULL, thread, ptr);
        for (i = 0; i < N; i++)
            Pthread join(tid[i], NULL);
        exit(0);
    /* Thread routine */
    void *thread(void *vargp)
    {
        int myid = *((int *)vargp);
        Free(vargp);
        printf("Hello from thread %d\n", myid);
        return NULL:
                                                   norace.c
Bryant a
```

# **Another worry: Deadlock**

■ Def: A process is *deadlocked* iff it is waiting for a condition that will never be true

#### Typical Scenario

- Processes 1 and 2 needs two resources (A and B) to proceed
- Process 1 acquires A, waits for B
- Process 2 acquires B, waits for A
- Both will wait forever!

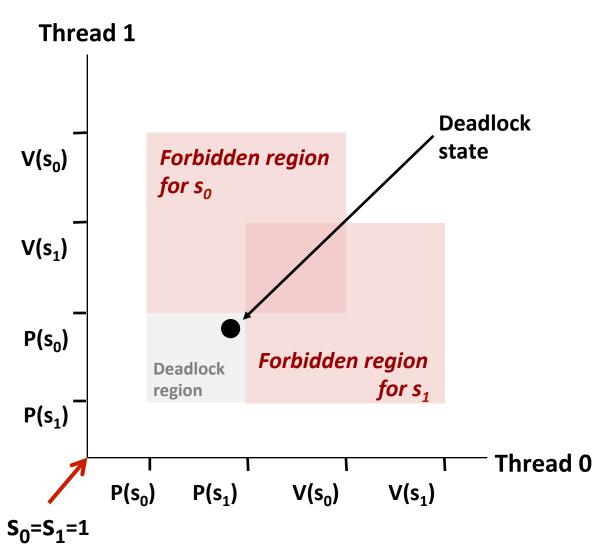
# **Deadlocking With Semaphores**

```
int main()
{
    pthread_t tid[2];
    Sem_init(&mutex[0], 0, 1); /* mutex[0] = 1 */
    Sem_init(&mutex[1], 0, 1); /* mutex[1] = 1 */
    Pthread_create(&tid[0], NULL, count, (void*) 0);
    Pthread_create(&tid[1], NULL, count, (void*) 1);
    Pthread_join(tid[0], NULL);
    Pthread_join(tid[1], NULL);
    printf("cnt=%d\n", cnt);
    exit(0);
}
```

```
void *count(void *vargp)
{
    int i;
    int id = (int) vargp;
    for (i = 0; i < NITERS; i++) {
        P(&mutex[id]); P(&mutex[1-id]);
        cnt++;
        V(&mutex[id]); V(&mutex[1-id]);
    }
    return NULL;
}</pre>
```

```
Tid[0]: Tid[1]: P(s<sub>0</sub>); P(s<sub>1</sub>); P(s<sub>0</sub>); Cnt++; V(s<sub>0</sub>); V(s<sub>1</sub>); V(s<sub>1</sub>);
```

# **Deadlock Visualized in Progress Graph**



Locking introduces the potential for deadlock: waiting for a condition that will never be true

Any trajectory that enters the deadlock region will eventually reach the deadlock state, waiting for either S<sub>0</sub> or S<sub>1</sub> to become nonzero

Other trajectories luck out and skirt the deadlock region

Unfortunate fact: deadlock is often nondeterministic (race)

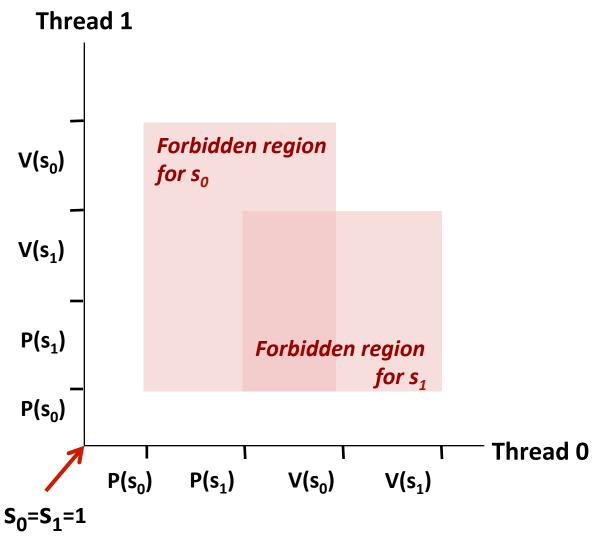
# Avoiding Deadlock Acquire shared resources in same order

```
int main()
   pthread t tid[2];
   Sem init(&mutex[0], 0, 1); /* mutex[0] = 1 */
   Sem init(&mutex[1], 0, 1); /* mutex[1] = 1 */
   Pthread create(&tid[0], NULL, count, (void*) 0);
   Pthread create(&tid[1], NULL, count, (void*) 1);
   Pthread join(tid[0], NULL);
   Pthread join(tid[1], NULL);
   printf("cnt=%d\n", cnt);
   exit(0);
```

```
void *count(void *varqp)
    int i;
    int id = (int) varqp;
    for (i = 0; i < NITERS; i++) {
        P(&mutex[0]); P(&mutex[1]);
       cnt++;
       V(&mutex[id]); V(&mutex[1-id]);
    return NULL;
```

```
Tid[0]:
           Tid[1]:
           P(s0);
P(s0);
P(s1);
           P(s1);
cnt++;
           cnt++;
V(s0);
           V(s1);
V(s1);
           V(s0);
```

# **Avoided Deadlock in Progress Graph**



No way for trajectory to get stuck

Processes acquire locks in same order

Order in which locks released immaterial