

Vv256 Lecture 1

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Defintion

A **differential equation** is an equation of

an **unknown function** and its derivatives.

- For some unknown function

$$y = y(t)$$

the following is an example of differential equations

$$\frac{dy}{dt} = y^2 \iff \dot{y} = y^2 \iff y' = y^2$$

Q: What does the above equation say regarding the unknown function

$$y = y(t)$$

- A differential equation provides a way to specify/define a function just like an algebraic equation specifies a number

$$x^3 = 1$$

Q: Can you think of a very simple function $y(t)$ that satisfies

$$\dot{y} = y^2$$

- The function that is **identically zero** clearly satisfies the above equation.

$$y(t) = 0$$

Q: Is there any other function that satisfies the differential equation?

- Since the differential equation is in the form of

$$\dot{y} = \Phi(t, y) = y^2$$

we can graphically investigate all functions that satisfy the equation.

$$\underbrace{\dot{y}}_{\substack{\text{The slope of some} \\ \text{unknown function}}} = \underbrace{\Phi(t, y)}_{\substack{\text{The value of the} \\ \text{slope at } (t, y)}}$$

- Specifically, we construct a vector field,

$$\mathbf{F} = 1\mathbf{e}_t + \Phi(t, y)\mathbf{e}_y$$

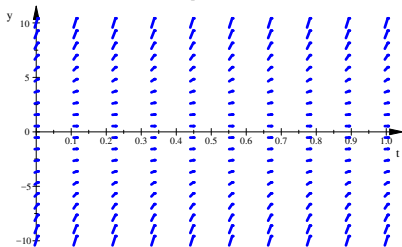
then the graph of the \mathbf{F} shows the family of functions satisfy the equation

$$\dot{y} = \Phi(t, y)$$

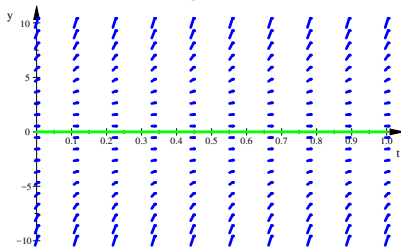
Definition

The vector field $\mathbf{F} = 1\mathbf{e}_t + \Phi(t, y)\mathbf{e}_y$ is known as a **slope field** or a **direction field**.

Slope Field



Slope Field



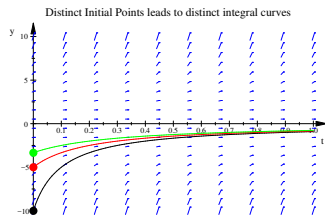
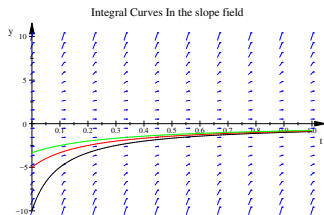
- Matlab can solve this simple equation symbolically, the output is given as

$$\left\{ 0, -\frac{1}{C+t} \right\}$$

where $y = 0$ is known as the **trivial solution**, and the second part

$$y = -\frac{1}{C+t} \quad \text{where } C \text{ is an arbitrary constant.}$$

represents a family of solutions, which seem to have different initial points.



- Note a solution to a differential equation is a **function** instead of a number.

- If we demand the solution to have value $y = -10$ at $t = 0$ while satisfying

$$\dot{y} = y^2$$

we can narrow it down to a single solution in this case.

Definition

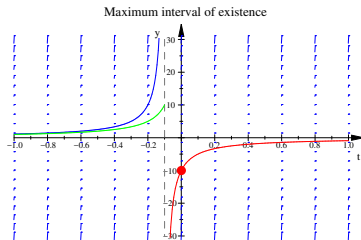
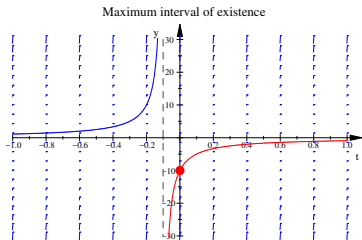
A differential equation with conditions for the value of the **unknown** function and possibly its derivatives at one particular point in the domain is known as an **initial value problem**.

- For example, the following is an initial value problem (IVP)

$$\dot{y} = y^2, \quad y(0) = -10$$

Q: What is the domain of the solution $y = -\frac{1}{0.1 + t}$ to the initial value problem

$$\dot{y} = y^2, \quad y(0) = -10$$



- The branch in blue certainly satisfies the differential equation, but it is not relevant to the initial condition. For the green branch is just as good

$$y(t) = \begin{cases} -\frac{1}{0.1+t} & \text{for } t > -0.1 \\ -\frac{1}{t} & \text{for } t \leq -0.1 \end{cases}$$

that is, a piecewise function is just as good as a function that can be written using a single formula. If we allow such functions, the solution is not unique.

- However, if we consider a smaller interval, e.g. $t > 0$, the solution is unique.
- So the domain of a solution might be smaller than the usual set in which the expression is defined.

Q: Having an essential discontinuity is problematic, and we may have to reduce the domain, but how about a solution that is everywhere continuous?

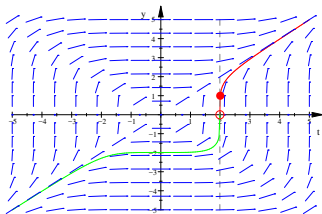
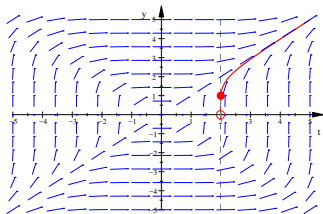
- For example, the initial value problem

$$\dot{y} = \frac{t^4}{y^4}, \quad y(2) = 1$$

is known to have the following solution, which is continuous everywhere,

$$y = \sqrt[5]{t^5 - 31}$$

Q: Why we have to exclude $t = \sqrt[5]{31}$.



- So we expect the following to be reasonable over an open interval.

Definition

A function

$$y = y(t)$$

defined on an interval $a < t < b$, is called a **solution** of the differential equation

$$\dot{y} = \Phi(t, y)$$

provided that y is a differentiable function of t on the interval

$$a < t < b$$

and the equation is defined and satisfied for every t in $a < t < b$.

- Note we say “a” solution rather than “the” solution. A differential equation, if it has a solution at all, usually has more than one solution.
- The solution to an initial value problem is a **particular solution** that satisfies the initial condition as well as satisfying the differential equation.

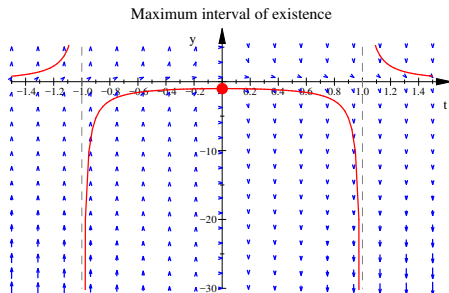
Exercise

(a) Verify that $y = \frac{1}{t^2 + c}$, where c is an arbitrary constant, is a solution to

$$\dot{y} + 2ty^2 = 0$$

(b) Find the particular solution that satisfies $y(0) = -1$.

(c) Find the maximum interval on which the solution you found above is valid.



- To study how to solve differential equations, it is essential to classify them since different classes of equations often need to be solve differently.

Defintion

An **ordinary differential equation** (ODE) contains only derivatives of one or more dependent variables with respect to a **single** independent variable.

Q: Are the following equations ODEs?

$$\dot{y} + 5y = e^t \quad \text{and} \quad \dot{x} + \dot{y} = 2x + y$$

- ODEs are different from **partial differential equations** (PDEs), which involve partial derivatives of two or more independent variables.

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0 \quad \text{and} \quad \operatorname{div}(\rho \mathbf{v}) + \frac{\partial \rho}{\partial t} = 0$$

Definition

The **order** of a differential equation is the order of the **highest-order** derivative that occurs in the equation

Q: What is the order of the following differential equations?

$$\ddot{y} + 2e^t \ddot{y} + y\dot{y} = t^4 \quad \text{and} \quad (\dot{y})^2 + t(\dot{y})^3 + 4y = 0$$

- We will first consider first-order equations

$$\alpha(t)\dot{y} + \beta(t)y = \gamma(t), \quad \dot{y}y = 2, \quad \dot{y} = y^2 \quad \text{and} \quad (\dot{y})^2 = 4y$$

which might be **linear** or **nonlinear**.

- A linear first-order equation involves only $\alpha(t)y$ and $\beta(t)\dot{y}$ “by themselves”.
- If any term involves a function of y or \dot{y} in the equation, then it is nonlinear.

Defintion

An n th-order ordinary differential equation

$$F(t, y, y', y'', \dots, y^{(n)}) = f(t)$$

is said to be **linear** if F is a linear function in terms of $y, y', \dots, y^{(n)}$.

- A function F is said to be linear in terms of $y, y', \dots, y^{(n)}$ if and only if

$$F(t, ay, ay', \dots, ay^{(n)}) = aF(t, y, y', \dots, y^{(n)})$$

$$F(t, y_1 + y_2, \dots, y_1^{(n)} + y_2^{(n)}) = F(t, y_1, y_1', \dots, y_1^{(n)}) + F(t, y_2, y_2', \dots, y_2^{(n)})$$

Q: Which of the followings is a linear differential equation?

1. $\ddot{y} + \frac{1}{\dot{y}} = 0$

2. $\ddot{y} + \sin y = 0$

3. $t^2 \ddot{y} + yt^2 \sin t = t \cos t$

4. $\ddot{\ddot{y}} = \exp(\ddot{y})$