

Vv417 Lecture 13

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- Recall that \mathcal{S} is a spanning set for a vector space \mathcal{V} if and only if every vector in \mathcal{V} is a linear combination of vectors in \mathcal{S} .
- However, spanning sets can contain redundant vectors. For example,

$$\text{row}(\mathbf{A}) = \text{span}\{\mathbf{r}_1, \mathbf{r}_2, \dots, \mathbf{r}_m\}$$

where \mathbf{r}_i are row vectors of an $m \times n$ matrix \mathbf{A} .

Q: Why we might have redundant vectors in $\text{span}\{\mathbf{r}_1, \mathbf{r}_2, \dots, \mathbf{r}_m\}$?

- Often we want a **minimal spanning set**, “minimal” in the sense it contains as few vectors as possible, that is, the set would no longer be a spanning set of the original vector space if any element of the set is removed.
- The notion of minimal spanning set is closely related to the following

Definition

A **linearly independent spanning set** for a vector space \mathcal{V} is called a **basis** for \mathcal{V} .

- Just as in the case of spanning sets, a space can possess many distinct bases.

- Vectors $\mathbf{e}_1 = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$, $\mathbf{e}_2 = \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix}$, \dots , $\mathbf{e}_n = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{bmatrix}$ form the standard basis for \mathbb{R}^n .

Exercise

Do the vectors $\mathbf{v}_1 = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$, $\mathbf{v}_2 = \begin{bmatrix} 2 \\ 9 \\ 0 \end{bmatrix}$, and $\mathbf{v}_3 = \begin{bmatrix} 3 \\ 3 \\ 4 \end{bmatrix}$ form a basis for \mathbb{R}^3 ?

Solution

- We need to check linear independence, and whether it spans \mathbb{R}^3 .
- Since $\begin{bmatrix} 1 & 2 & 3 \\ 2 & 9 & 3 \\ 1 & 0 & 4 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \Rightarrow \begin{aligned} \alpha_1 \mathbf{v}_1 + \alpha_2 \mathbf{v}_2 + \alpha_3 \mathbf{v}_3 &= \mathbf{0}; \\ \beta_1 \mathbf{v}_1 + \beta_2 \mathbf{v}_2 + \beta_3 \mathbf{v}_3 &= \mathbf{b}, \forall \mathbf{b} \in \mathbb{R}^3 \end{aligned}$
- So they are linearly independent in \mathbb{R}^3 and span \mathbb{R}^3 , and form a basis for \mathbb{R}^3 .

- The standard basis for \mathcal{P}_n

$$\mathbf{p}_0 = 1, \quad \mathbf{p}_1 = x, \quad \mathbf{p}_2 = x^2, \quad \dots, \mathbf{p}_n = x^n$$

Exercise

Show that the following vectors

$$\mathbf{M}_1 = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \quad \mathbf{M}_2 = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \quad \mathbf{M}_3 = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \quad \mathbf{M}_4 = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$$

form a basis for the vector space $\mathcal{M}_{2 \times 2}$ of 2×2 real matrices.

Solution

- We need to show the given matrices are linearly independent, that is,

$$\begin{aligned} \alpha_1 \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + \alpha_2 \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + \alpha_3 \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} + \alpha_4 \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} &= \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \\ \begin{bmatrix} \alpha_1 & \alpha_2 \\ \alpha_3 & \alpha_4 \end{bmatrix} &= \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \end{aligned}$$

Solution

- It is clear that the only solution is

$$\alpha_1 = \alpha_2 = \alpha_3 = \alpha_4 = 0$$

- So the given matrices are linearly independent.
- We also need to show the given matrices span $\mathcal{M}_{2 \times 2}$, that is, we need to show there exist $\beta_1, \beta_2, \beta_3$ and $\beta_4 \in \mathbb{R}$ for all a, b, c and $d \in \mathbb{R}$ such that

$$\begin{aligned} \beta_1 \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + \beta_2 \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + \beta_3 \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} + \beta_4 \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} &= \begin{bmatrix} a & b \\ c & d \end{bmatrix} \\ \begin{bmatrix} \beta_1 & \beta_2 \\ \beta_3 & \beta_4 \end{bmatrix} &= \begin{bmatrix} a & b \\ c & d \end{bmatrix} \end{aligned}$$

- It is clear that we can always let

$$\beta_1 = a, \quad \beta_2 = b, \quad \beta_3 = c, \quad \text{and} \quad \beta_4 = d$$

- Therefore the given matrices span $\mathcal{M}_{2 \times 2}$, and they form a basis for $\mathcal{M}_{2 \times 2}$.

Theorem

Let \mathcal{V} be a vector space, and let $\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_1, \dots, \mathbf{b}_n\} \subset \mathcal{V}$. Then \mathcal{B} is a basis for \mathcal{V} **if and only if** \mathcal{B} is a minimal spanning set for \mathcal{V} .

Proof

- First let \mathcal{B} be a basis for \mathcal{V} , then \mathcal{B} spans \mathcal{V} and \mathcal{B} is linearly independent.
- Let \mathcal{S} be the set obtained from \mathcal{B} with $\mathbf{b}_i \in \mathcal{B}$ removed. If \mathcal{S} spans \mathcal{V} , then

$$\mathbf{b}_i = \alpha_1 \mathbf{b}_1 + \alpha_2 \mathbf{b}_2 + \cdots \alpha_j \mathbf{b}_j + \cdots + \alpha_n \mathbf{b}_n, \quad \text{where } \mathbf{b}_j \in \mathcal{S}$$

- It contradicts the fact $\mathcal{B} = \mathcal{S} \cup \{\mathbf{b}_i\}$ is linearly independent. So \mathcal{B} is minimal.
- If \mathcal{B} is a minimal spanning set, and assume \mathcal{B} is not a basis, that is,

$$\mathbf{b}_i = \alpha_1 \mathbf{b}_1 + \alpha_2 \mathbf{b}_2 + \cdots \alpha_j \mathbf{b}_j + \cdots + \alpha_n \mathbf{b}_n \implies \text{span}(\mathcal{B}) = \text{span}(\mathcal{S})$$

where \mathcal{S} is the set obtained from \mathcal{B} with $\mathbf{b}_i \in \mathcal{B}$ removed.

- But this means that \mathcal{B} is not minimal, contrary to our assumption. So, \mathcal{B} must be linearly independent, and therefore it is a basis for \mathcal{V} .

Theorem

Bases of a given vector space \mathcal{V} have the same number of vectors in them.

Proof

- Let $\mathcal{U} = \{\mathbf{u}_1, \dots, \mathbf{u}_n\}$ and $\mathcal{W} = \{\mathbf{w}_1, \dots, \mathbf{w}_m\}$ be bases of \mathcal{V} , where

$$m = n + 1$$

that is, basis \mathcal{W} has one more vector than basis \mathcal{U} .

- Since $\mathcal{W} \subset \mathcal{V}$, every vector in \mathcal{W} is linear combination of vectors in \mathcal{U} .
- Consider n out of those $n + 1$ vectors in \mathcal{W} , which can be written as

$$\mathbf{w}_i = \sum_{j=1}^n a_{ij} \mathbf{u}_j \quad \text{for } i = 1, 2, \dots, n$$

- To avoid contradicting the set of \mathbf{w}_j 's being linearly independent, the $\mathbf{A}_{n \times n}$ matrix of a_{ij} must have n linearly independent rows.

Proof

- Since the row space is not altered by elementary row operations, thus

$$\text{row}(\mathbf{A}) = \text{row}(\mathbf{I}) \iff \mathbf{A} \sim \mathbf{I}$$

from which, we see the system of vector equations

$$\mathbf{w}_i = \sum_{j=1}^n a_{ij} \mathbf{u}_j \quad \text{for } i = 1, 2, \dots, n$$

can be manipulated by adding and scaling rows into the following system

$$\sum_{i=1}^n a_{ij}^* \mathbf{w}_i = \mathbf{u}_j \quad \text{for } j = 1, 2, \dots, n$$

- This leads to the contradiction that the remaining vector \mathbf{w}_{n+1} , which must be a linear combination of \mathbf{u}_i 's, must be a linear combination of $\mathbf{w}_1, \dots, \mathbf{w}_n$.
- Therefore, to avoid contradicting \mathcal{W} being linearly independent, $m = n$. \square

- A vector space \mathcal{V} can have many different bases, but the preceding 2 results:
 - all bases of \mathcal{V} contain the same number of vectors.
 - all minimal spanning sets of \mathcal{V} contain the same number of vectors.
- If \mathcal{B}_1 and \mathcal{B}_2 are each a basis for \mathcal{V} , then each is a minimal spanning set, thus they must contain the same number of vectors. It can be shown that it is also the number of vectors in a maximal linearly independent set.

Definition

The dimension of a vector space \mathcal{V} is denoted by $\dim(\mathcal{V})$ and is defined to be the number of vectors in a basis for \mathcal{V} .

- Engineers often use the term degrees of freedom as a synonym for dimension
- Dimensions of some familiar vector spaces

$$\dim(\mathbb{R}^n) = n \qquad \dim(\mathcal{P}_n) = n + 1 \qquad \dim(\mathcal{M}_{m \times n}) = mn$$

Exercise

Find a basis for the solution space of $\mathbf{Ax} = \mathbf{0}$ if the general solution of it is

$$x_1 = -3r - 4s - 2t, \quad x_2 = r, \quad x_3 = -2s, \quad x_4 = s, \quad x_5 = t, \quad x_6 = 0$$

What is the dimension of the solution space?

Solution

- It is more clear in the vector form

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \end{bmatrix} = \begin{bmatrix} -3r - 4s - 2t \\ r \\ -2s \\ s \\ t \\ 0 \end{bmatrix} = r \begin{bmatrix} -3 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} + s \begin{bmatrix} -4 \\ 0 \\ -2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} -2 \\ 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}$$

zero only if $r=s=t=0$ \mathbf{v}_1 \mathbf{v}_2 \mathbf{v}_3

- Thus, $\mathcal{S} = \{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ is a basis for the null space and the dimension is 3.

Exercise

Show that the vector space

$$\mathcal{P}_{\infty}$$

the space of all polynomials with real coefficients is infinite-dimensional.

Solution

- Assume \mathcal{P}_{∞} is finite-dimensional with a basis \mathcal{S} of size n for some integer n .
- Since \mathcal{S} is finite, there are vectors in \mathcal{S} that have the highest degree, say m .
- It is clear that x^{m+1} is in \mathcal{P}_{∞} , however,

$$x^{m+1}$$

is not a linear combination of vectors in \mathcal{S} .

- So the finite basis does not span \mathcal{P}_{∞} , contradiction to the assumption.
- Hence the vector space is infinite-dimensional.

- The simplest of all vector spaces is the zero vector space $\mathcal{V} = \{\mathbf{0}\}$.
- Q: What do you think the dimension of the zero vector space should be?
- Q: What is the spanning set for the zero vector space?
- Q: What is then the dimension of the zero vector space?
- Q: Is the following set linearly independent?

$$\{\mathbf{0}, \mathbf{u}\}, \quad \text{where } \mathbf{u} \text{ is any vector in } \mathcal{V}.$$

- However, the empty set \emptyset is defined to be the basis for $\mathcal{V} = \{\mathbf{0}\}$.
- Recall engineers use the term **degrees of freedom** instead of dimension.
- In the zero space case, there are no degrees of freedom; you can go nowhere.
- It is important not to confuse the **dimension** of a vector space $\mathcal{V} \subset \mathbb{R}^n$ with the number of components contained in the individual vectors from \mathcal{V} . e.g.,

A plane through the origin in \mathbb{R}^3 .

Exercise

Suppose \mathcal{V} is an n -dimensional vector space and

$$\mathcal{S}_r = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_r\}, \quad \text{where } r < n,$$

is a linearly independent subset of \mathcal{V} . Show it is possible to find an extension set

$$\mathcal{S}_{\text{ext}} = \{\mathbf{v}_{r+1}, \dots, \mathbf{v}_n\} \subset \mathcal{V}$$

such that

$$\mathcal{S}_n = \mathcal{S}_r \cup \mathcal{S}_{\text{ext}} = \{\mathbf{v}_1, \dots, \mathbf{v}_r, \mathbf{v}_{r+1}, \dots, \mathbf{v}_n\}$$

is a basis for \mathcal{V} .

Solution

- Since

$$r < n \implies \text{span}(\mathcal{S}_r) \neq \mathcal{V}$$

Solution

- Hence there is a vector

$$\mathbf{v}_{r+1} \in \mathcal{V}$$

such that

$$\mathbf{v}_{r+1} \notin \text{span}(\mathcal{S}_r)$$

- The extension set below is a linearly independent subset of \mathcal{V} .

$$\mathcal{S}_{r+1} = \mathcal{S}_r \cup \{\mathbf{v}_{r+1}\}$$

- This can be repeated to generate linear independent subsets

$$\mathcal{S}_{r+2}, \quad \mathcal{S}_{r+2}, \dots$$

- Eventually

$$\dim(\mathcal{S}_r \cup \mathcal{S}_{\text{ext}}) = n$$

Theorem

For vector spaces \mathcal{M} and \mathcal{N} such that $\mathcal{M} \subset \mathcal{N}$, then

$$\dim \mathcal{M} \leq \dim \mathcal{N}$$

If $\dim \mathcal{M} = \dim \mathcal{N}$, then

$$\mathcal{M} = \mathcal{N}$$

Proof

- Let $\mathcal{B}_{\mathcal{M}}$ and $\mathcal{B}_{\mathcal{N}}$ be minimal spanning sets of \mathcal{M} and \mathcal{N} , respectively.
- Suppose

$$\dim \mathcal{M} > \dim \mathcal{N}$$

that is, there are more vectors in $\mathcal{B}_{\mathcal{M}}$ than in $\mathcal{B}_{\mathcal{N}}$.

- Although $\mathcal{B}_{\mathcal{N}}$ is not necessarily a minimal spanning set of \mathcal{M} , it must be a spanning set of \mathcal{M} since $\mathcal{M} \subset \mathcal{N}$, which means a minimal spanning of \mathcal{M} formed from $\mathcal{B}_{\mathcal{N}}$ must have equal or less number of vectors than $\mathcal{B}_{\mathcal{N}}$.
- This contradicts the fact that all minimal spanning set of \mathcal{M} should have the same number of vectors because $\mathcal{B}_{\mathcal{M}}$ already has more vectors than $\mathcal{B}_{\mathcal{N}}$.

Proof

- Suppose $\dim \mathcal{M} = \dim \mathcal{N}$ but $\mathcal{M} \neq \mathcal{N}$, then there is an extension set

$$\mathcal{S}_{\text{ext}}$$

such that

$$\mathcal{B}_{\mathcal{M}} \cup \mathcal{S}_{\text{ext}}$$

is minimal spanning set of \mathcal{N} , which means this minimal spanning set of \mathcal{N} ,

$$\mathcal{B}_{\mathcal{M}} \cup \mathcal{S}_{\text{ext}}$$

has more vectors than the minimal spanning set $\mathcal{B}_{\mathcal{N}}$.

- This contradicts the fact that the number vectors in minimal spanning sets of the vector space is the same. Therefore, no \mathcal{S}_{ext} should be found, that is

$$\mathcal{M} = \mathcal{N} \quad \square$$

Q: How can we find the extension set for a given linearly independent set in \mathbb{R}^n ?

$$\mathcal{S} = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_r\}$$

- Let the following set be any basis for \mathbb{R}^n ,

$$\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2, \dots, \mathbf{b}_n\}$$

- Now if we place vectors in \mathcal{S} along with vectors in \mathcal{B} as columns in a matrix

$$\mathbf{A} = [\mathbf{v}_1 \quad \mathbf{v}_2 \quad \dots \quad \mathbf{v}_r \quad \mathbf{b}_1 \quad \mathbf{b}_2 \quad \dots \quad \mathbf{b}_n]$$

- Clearly

$$\text{col}(\mathbf{A}) = \mathbb{R}^n$$

- The set of pivot columns from \mathbf{A} is a basis for $\text{col}(\mathbf{A})$. Notice vectors

$$\mathcal{S} = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_r\}$$

are the first r pivot columns in \mathbf{A} for \mathcal{S} is linearly independent, the rest in \mathcal{B} .

Exercise

Find the extension set to the following

$$\mathcal{S} = \left\{ \begin{bmatrix} 1 \\ 0 \\ -1 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ -2 \end{bmatrix} \right\}$$

to form basis for \mathbb{R}^4 .

Solution

- Let

$$\mathbf{A} = \begin{bmatrix} 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ -1 & 1 & 0 & 0 & 1 & 0 \\ 2 & 2 & 0 & 0 & 0 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & -\frac{1}{2} \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & \frac{1}{2} \end{bmatrix}$$

- Hence the extension set of $\mathcal{S}_{\text{ext}} = \{\mathbf{e}_2, \mathbf{e}_3\}$ will make $\mathcal{S} \cup \mathcal{S}_{\text{ext}}$ a basis for \mathbb{R}^4 .