

# Vv255 Lecture 22

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1. **Definite integrals:** Given a *continuous* real-valued function  $y = f(x)$ ,

$$\int_a^b f(x) dx$$

represents the net area between the graph of  $f$ ,  $y = 0$ ,  $x = a$  and  $x = b$ .

- The definite integral can also be used to compute the arc length of a curve.
- Suppose a *smooth* curve  $\mathcal{C}$  is defined by

$$\mathbf{r}(t) \quad \text{for } \alpha \leq t \leq \beta.$$

then the arc length  $L$  of the curve  $\mathcal{C}$  is given by

$$L = \int_{\alpha}^{\beta} \left| \frac{d\mathbf{r}}{dt} \right| dt$$

- The **arc length function** is defined to be  $s(t) = \int_{\alpha}^t |\mathbf{r}'| d\tau$ , and by FTC

$$\frac{ds}{dt} = \left| \frac{d\mathbf{r}}{dt} \right|$$

2. Double integrals: Given a *continuous* real-valued function  $z = f(x, y)$ ,

$$\iint_{\mathcal{D}} f(x, y) dA$$

represents the net volume of the solid between the region  $\mathcal{D}$  and the graph of

$$z = f(x, y)$$

3. Triple integrals: Given a *continuous* real-valued function  $w = f(x, y, z)$ ,

$$\iiint_{\mathcal{E}} f(x, y, z) dV$$

represents the net hyper-volume of the 4-dimensional solid.

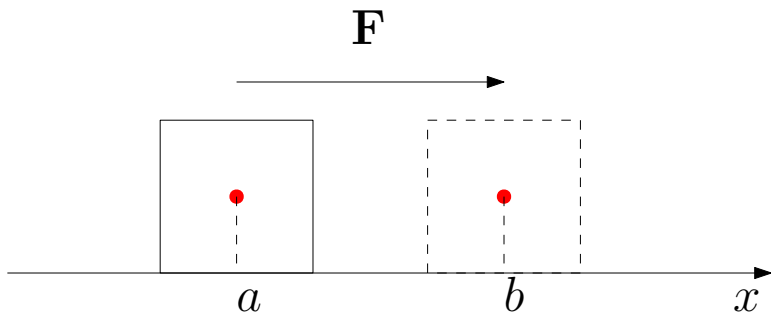
- A **line integral** is similar to a **definite integral** except instead of integrating on

$$[a, b]$$

which is really along a **straight line**, we integrate along a **curve** / **path**  $\mathcal{C}$ .

- To motivate the definition, let us recall,

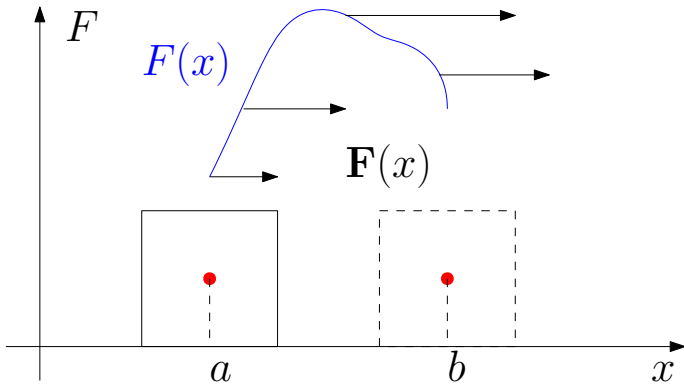
0. If a **constant force**  $F$  is applied to and moves an object **along  $x$ -axis**



then the amount of work done between  $x = a$  and  $x = b$  is defined to be

$$W = F \cdot (b - a).$$

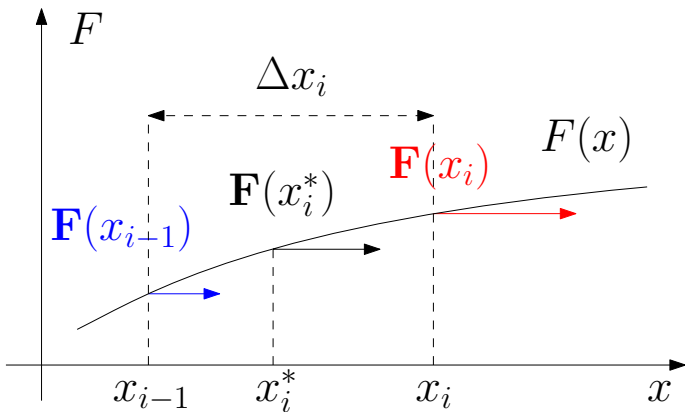
1. If the magnitude of the force is not constant, but is instead **dependent on  $x$**



then the work done is defined to be

$$W = \int_a^b F(x) dx$$

- This definition is based on using the “basic” formula inside each subinterval



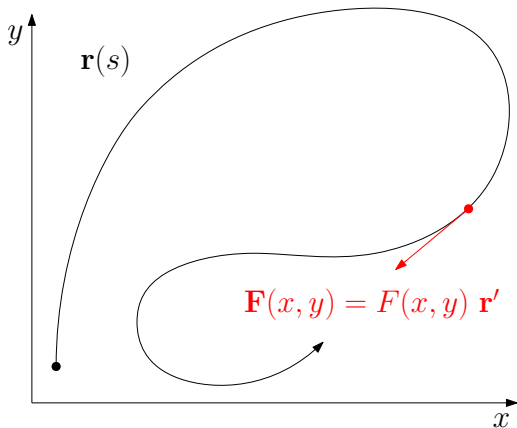
and take the limit of the sum of all those work done inside each subinterval

$$W = \lim_{n \rightarrow \infty} \sum_{i=1}^n F(x_i^*) \Delta x_i = \int_a^b F(x) dx$$

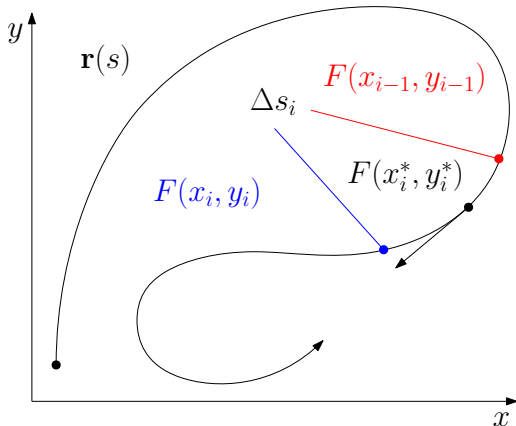
2. If a variable force is applied to and moves an object along a smooth curve  $\mathcal{C}$

$$\mathbf{r} = x(s)\mathbf{e}_x + y(s)\mathbf{e}_y \quad \text{where } s \text{ is an arc length parameter.}$$

- Suppose the force  $\mathbf{F}(x, y)$  is always in the direction of motion,



- If we partition the curve  $\mathcal{C}$  into sub-curves,



- We can approximate the work within each sub-curve with the work done by

$$F(x_i^*, y_i^*) \Delta s_i$$



- It is reasonable to expect the following definition for the work done,

$$W = \lim_{n \rightarrow \infty} \sum_{i=1}^n F(x_i^*, y_i^*) \Delta s_i$$

- If  $F$  is continuous, then we expect the limit to converge, and denoted by

$$W = \lim_{n \rightarrow \infty} \sum_{i=1}^n F(x_i^*, y_i^*) \Delta s_i = \int_C F(x, y) ds$$

- The notation indicates the fact that it is integrated along the smooth

$$\mathcal{C}: \mathbf{r}(s) = x(s)\mathbf{e}_x + y(s)\mathbf{e}_y$$

- Although we have introduced line integrals in the context of computing work, this approach can be used to integrate any function along a smooth curve  $\mathcal{C}$ .

## Definition

If  $\mathcal{C}$  is a smooth curve in  $\mathbb{R}^2$  or  $\mathbb{R}^3$ , then the

line integral of  $f$  with respect to  $s$  along  $\mathcal{C}$

is defined to be

$$\int_{\mathcal{C}} f(x, y) \, ds = \lim_{n \rightarrow \infty} \sum_{i=1}^n f(x_i^*, y_i^*) \Delta s_i$$

or

$$\int_{\mathcal{C}} f(x, y, z) \, ds = \lim_{n \rightarrow \infty} \sum_{i=1}^n f(x_i^*, y_i^*, z_i^*) \Delta s_i$$

provided the limit exists and doesn't depend on the choice of the tagged partition.

Q: How can we evaluate such integrals?

$$\int_{\mathcal{C}} f \, ds \quad \text{where } \mathcal{C} \text{ is defined by } \mathbf{r}(t)$$

- I. To evaluate a line integral along a smooth curve  $\mathbf{r}(s)$  is given in terms of  $s$

$$\int_{\mathcal{C}} f(x, y) \, ds \quad \text{where } \mathcal{C} \text{ is defined by } \mathbf{r}(s) = x(s)\mathbf{e}_x + y(s)\mathbf{e}_y$$

we only need to convert it into a ordinary single integral by substitution

$$\int_{\mathcal{C}} f(x, y) \, ds = \int f(x(s), y(s)) \, ds = \int F(s) \, ds$$

- II. If the smooth curve  $\mathbf{r}(t)$  is given in terms of other parameter  $t$

$$\int_{\mathcal{C}} f(x, y) \, ds \quad \text{where } \mathcal{C} \text{ is defined by } \mathbf{r}(t) = x(t)\mathbf{e}_x + y(t)\mathbf{e}_y$$

we have to use the  $u$ -substitution formula to change the variable  $s = s(t)$

$$\begin{aligned} \int_{\mathcal{C}} f(x, y) \, ds &= \int f(x(s), y(s)) \, ds \\ &= \int f(x(t), y(t)) s'(t) \, dt & s = s(t) &= \int_{\alpha}^t |\mathbf{r}'(\tau)| \, d\tau \\ &= \int f(x(t), y(t)) |\mathbf{r}'(t)| \, dt & s'(t) &= |\mathbf{r}'(t)| \end{aligned}$$

## Exercise

(a) Evaluate the following line integral

$$\int_C x^2 z \, ds$$

where  $C$  is the line segment between

$$(0, 6, -1) \text{ and } (4, 1, 5).$$

(b) Evaluate the following line integral

$$\int_C 2x + 9z \, ds$$

where  $C$  is defined by the parametric equations

$$x = t, \quad y = t^2, \quad z = t^3$$

for  $0 \leq t \leq 1$ .

- It is usually impractical to evaluate line integrals directly from the definition.
- However, the definition is important in the interpretation of line integrals.

Q: If  $\mathcal{C}$  is a smooth plane curve and  $f(x, y)$  is a non-negative continuous on  $\mathcal{C}$ , what does the following line integral represent geometrically?

$$\int_{\mathcal{C}} f(x, y) ds$$

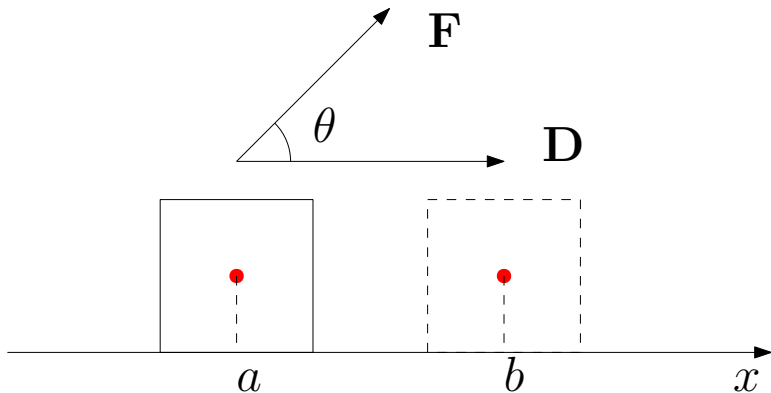
- If  $\mathcal{C}$  is a curve in  $\mathbb{R}^3$  that models a thin wire, and if  $f(x, y, z)$  gives the density function of the wire, then the mass  $m$  of the wire is given by

$$m = \int_{\mathcal{C}} f(x, y, z) ds$$

- If  $\mathcal{C}$  is a smooth curve of arc length  $L$ , and  $f$  is identically 1, then

$$\int_{\mathcal{C}} ds = \lim_{n \rightarrow \infty} \sum_{i=1}^n \Delta s_i = \lim_{n \rightarrow \infty} L = L$$

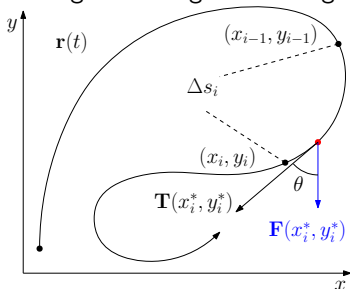
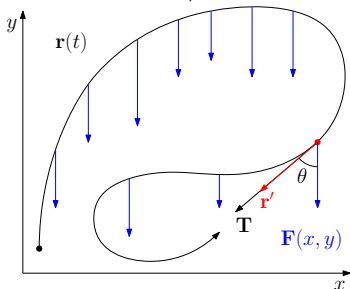
3. If a **constant force**  $\mathbf{F}$  is applied to an object NOT in the direction of motion,



but rather makes an angle  $\theta$  with a **constant displacement vector**  $\mathbf{D}$ ,

$$W = |\mathbf{F}| \cos \theta |\mathbf{D}| = \mathbf{F} \cdot \mathbf{D}$$

4. Suppose an object moving along a curve  $\mathcal{C}$  in a force field  $\mathbf{F}(x, y)$ , so subject to a **variable force**, both the direction and the magnitude might be changing



- Consider a partition of the curve  $\mathcal{C}$ , in each sub-curve, we treat  $\mathbf{F}$  as a constant force  $\mathbf{F}(x_i^*, y_i^*)$  and the displacement as  $\Delta \mathbf{s}_i \mathbf{T}(x_i^*, y_i^*)$

$$W_i \approx \mathbf{F}(x_i^*, y_i^*) \cdot (\Delta \mathbf{s}_i \mathbf{T}(x_i^*, y_i^*)) = \mathbf{F}(x_i^*, y_i^*) \cdot \mathbf{T}(x_i^*, y_i^*) \Delta s_i$$

- It is reasonable to expect the following definition, when the limit converges,

$$W = \lim_{n \rightarrow \infty} \sum_{i=1}^n \mathbf{F}(x_i^*, y_i^*) \cdot \mathbf{T}(x_i^*, y_i^*) \Delta s_i = \int_{\mathcal{C}} \mathbf{F} \cdot \mathbf{T} ds$$

## Definition

If  $\mathcal{C}$  is a smooth curve in  $\mathbb{R}^2$  or  $\mathbb{R}^3$ , then the

line integral of  $\mathbf{F}$  with respect to  $s$  along  $\mathcal{C}$

is defined to be

$$\int_{\mathcal{C}} \mathbf{F} \cdot \mathbf{T} ds$$

Q: Is this integral so different from the first type? How to evaluate this type?

- Recall the unit tangent vector is given by  $\mathbf{T}(t) = \frac{\mathbf{r}'(t)}{|\mathbf{r}'(t)|}$ , and  $s' = |\mathbf{r}'(t)|$

$$\int_{\mathcal{C}} \mathbf{F} \cdot \mathbf{T} ds = \int_a^b \mathbf{F}(x(t), y(t)) \cdot \frac{\mathbf{r}'(t)}{|\mathbf{r}'(t)|} |\mathbf{r}'(t)| dt = \int_a^b \mathbf{F} \cdot \mathbf{r}' dt = \int_{\mathcal{C}} \mathbf{F} \cdot d\mathbf{r}$$

- The last form of the line integral is merely an abbreviation.



- For a given  $\mathbf{F}$  with component functions  $P$  and  $Q$ , and a curve  $\mathcal{C}$  defined by

$$\mathbf{r}(t) = x(t)\mathbf{e}_x + y(t)\mathbf{e}_y, \quad \text{where } a \leq t \leq b$$

- The line integral of  $\mathbf{F}$  can be evaluated using line integral of  $P$  and  $Q$ ,

$$\begin{aligned} \int_{\mathcal{C}} \mathbf{F} \cdot d\mathbf{r} &= \int_a^b \mathbf{F} \cdot \mathbf{r}'(t) dt \\ &= \int_a^b \left[ P(x(t), y(t))x'(t) + Q(x(t), y(t))y'(t) \right] dt \\ &= \int_a^b P(x(t), y(t))x'(t) dt + \int_a^b Q(x(t), y(t))y'(t) dt \\ &= \int_{\mathcal{C}} P(x, y) dx + \int_{\mathcal{C}} Q(x, y) dy \end{aligned}$$

Q: Why using the line integral notation in the last line?

- So the line integral of the **vector field**  $\mathbf{F}$  over  $\mathcal{C}$  can be obtained by summing the line integrals of its component functions w.r.t.  $x$  and  $y$  individually.

- However, it is important to note that unlike line integrals with respect to  $s$ ,

$$\int_{\mathcal{C}} f(x, y) \, ds = \int_a^b f(x(t), y(t)) |\mathbf{r}'(t)| \, dt$$

line integrals with respect to  $x$  or  $y$  depends on the **orientation** of  $\mathcal{C}$ .

- For example,

$$\int_{\mathcal{C}} P(x, y) \, dx = \int_a^b P(x(t), y(t)) \mathbf{x}'(t) \, dt$$

- If the curve is traced in reverse (that is, from the terminal point to the initial point), then the **sign** of the line integral is reversed as well. We denote by  $-\mathcal{C}$  the curve  $\mathcal{C}$  with its orientation reversed. We then have

$$\int_{\mathcal{C}} \mathbf{F} \cdot d\mathbf{r} = - \int_{-\mathcal{C}} \mathbf{F} \cdot d\mathbf{r}$$

since the components  $\int_{\mathcal{C}} P \, dx = - \int_{-\mathcal{C}} P \, dx$ , and  $\int_{\mathcal{C}} Q \, dy = - \int_{-\mathcal{C}} Q \, dy$ .

- All of this discussion can be generalized to space curves in a similar way.

## Exercise

(a) Evaluate the line integral

$$\int_C \mathbf{F} \cdot d\mathbf{r}$$

where  $\mathbf{F} = z\mathbf{e}_x + y\mathbf{e}_y - x\mathbf{e}_z$  and  $C$  is the curve defined by

$$\mathbf{r}(t) = t\mathbf{e}_x + (\sin t)\mathbf{e}_y + (\cos t)\mathbf{e}_z \quad \text{for } 0 \leq t \leq \pi.$$

(b) Evaluate the line integral

$$\int_C \mathbf{F} \cdot d\mathbf{r} \quad \text{where } \mathbf{F}(x, y) = (\sin x)\mathbf{e}_x + (\cos y)\mathbf{e}_y$$

and  $C$  is the top half of the circle

$$x^2 + y^2 = 1$$

from  $(1, 0)$  to  $(-1, 0)$ , then the line segment from  $(-1, 0)$  to  $(-2, 3)$ .