

# Vv417 Lecture 8

Jing Liu

UM-SJTU Joint Institute

September 26, 2019

- So far, we have considered only **direct methods** for solving

$$\mathbf{Ax} = \mathbf{b} \quad \text{where } \mathbf{A} \text{ is } n \times n.$$

- In absence of rounding errors direct methods reach the exact solution using a finite number of arithmetic operations. However, they usually fail to take computational advantage of the sparsity.
- In an **iterative method**, we start with an approximation

$$\mathbf{x}^{(0)}$$

to the exact solution and then compute a sequence of

$$\left\{ \mathbf{x}^{(k)} \right\}$$

such that  $\mathbf{x}^{(k)}$  becomes closer and closer to the exact as  $k$  grows.

- The main advantage of iterative methods are reduced storage requirements.

- Let  $\mathbf{A}$  has nonzero diagonal elements, then the diagonal matrix

$$\mathbf{D}$$

formed from the diagonal elements of  $\mathbf{A}$  is invertible.

$$\mathbf{A}\mathbf{x} = \mathbf{b}$$

$$\mathbf{A}\mathbf{x} - \mathbf{D}\mathbf{x} + \mathbf{D}\mathbf{x} = \mathbf{b}$$

$$\mathbf{D}\mathbf{x} = (\mathbf{D} - \mathbf{A})\mathbf{x} + \mathbf{b}$$

$$\mathbf{x} = \mathbf{D}^{-1}(\mathbf{b} + (\mathbf{D} - \mathbf{A})\mathbf{x})$$

from which we have the so-called [Jacobi iteration](#)

$$\mathbf{x}^{(k+1)} = \mathbf{D}^{-1}(\mathbf{b} + (\mathbf{D} - \mathbf{A})\mathbf{x}^{(k)})$$

Q: What does Jacobi iteration actually set to zero in parallel?

- Jacobi iteration is reasonable for a small system

$$\mathbf{Ax} = \mathbf{b}$$

but the convergence tends to be too slow for large systems.

Q: Intuitively, what is a clear modification to speed up the convergence?

- Instead of updating elements of  $\mathbf{x}^{(k)}$  in parallel,

$$x_i^{(k+1)} = \frac{1}{a_{ii}} \left( b_i - \sum_{j=1}^{i-1} a_{ij} x_j^{(k)} - \sum_{j=i+1}^n a_{ij} x_j^{(k)} \right) \quad \text{for } i = 1, 2, \dots, n$$

we could update successively

$$x_i^{(k+1)} = \frac{1}{a_{ii}} \left( b_i - \sum_{j=1}^{i-1} a_{ij} x_j^{(k+1)} - \sum_{j=i+1}^n a_{ij} x_j^{(k)} \right) \quad \text{for } i = 1, 2, \dots, n$$

- Let  $\mathbf{D}$ ,  $\mathbf{L}$  and  $\mathbf{U}$  be triangular matrices such that

$$d_{ij} = \begin{cases} a_{ij} & i = j \\ 0 & i \neq j \end{cases}, \quad \ell_{ij} = \begin{cases} a_{ij} & i < j \\ 0 & i \geq j \end{cases} \quad \text{and} \quad u_{ij} = \begin{cases} a_{ij} & i > j \\ 0 & i \leq j \end{cases}$$

from which it is clear that

$$\mathbf{A} = \mathbf{D} + \mathbf{L} + \mathbf{U}$$

- The modification in this notation, which is known as [Gauss-Seidel iteration](#),

$$x_i^{(k+1)} = \frac{1}{a_{ii}} \left( b_i - \sum_{j=1}^{i-1} a_{ij} x_j^{(k+1)} - \sum_{j=i+1}^n a_{ij} x_j^{(k)} \right)$$

$$\implies \mathbf{D}\mathbf{x}^{(k+1)} = \mathbf{b} - \mathbf{L}\mathbf{x}^{(k+1)} - \mathbf{U}\mathbf{x}^{(k)}$$

$$\implies \mathbf{x}^{(k+1)} = (\mathbf{D} + \mathbf{L})^{-1} (\mathbf{b} - \mathbf{U}\mathbf{x}^{(k)})$$

Q: Do you think the sequences produced by the Jacobi or Gauss-Seidel methods

$$\left\{ \mathbf{x}^{(k)} \right\}$$

always converge to the exact solutions?

### Definition

A square matrix  $\mathbf{A}$  is said to be **strictly diagonally dominant** if

$$|a_{ii}| > \sum_{j=1}^{i-1} |a_{ij}| + \sum_{j=i+1}^n |a_{ij}| \quad \text{for all } i = 1, 2, \dots, n$$

Q: Is the following matrix strictly diagonally dominant?

$$\begin{bmatrix} 7 & -2 & 3 \\ 4 & 1 & -6 \\ 5 & 12 & -4 \end{bmatrix}$$

- The following theorem gives a sufficient condition for convergence.

### Theorem

If  $\mathbf{A}$  is strictly diagonally dominant, then

$$\mathbf{Ax} = \mathbf{b}$$

has a unique solution, and for any choice of the initial guess  $\mathbf{x}^{(0)}$ , the sequence

$$\left\{ \mathbf{x}^{(k)} \right\}$$

produced by the Jacobi or Gauss-Seidel iteration converge to the exact solution.

Q: How to prove the first half of the theorem?

- We will prove it when we have the tools for defining convergence rigorously.

Q: Can you see why iterative methods save storage requirements?