

Vv256 Lecture 9

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September 28, 2017

- In general, the n th-order linear differential equation is

$$\alpha_n y^{(n)} + \alpha_{n-1} y^{(n-1)} + \cdots + \alpha_1 y' + \alpha_0 y = f \quad (1)$$

where α_i and f are functions of x . In the standard form, we have

$$y^{(n)} + P_1 y^{(n-1)} + \cdots + P_{n-1} y' + P_n y = Q \quad (2)$$

where P_i and Q are functions of x .

- In general, for IVPs of an n th-order linear equation, we have the following

Existence and Uniqueness

If P_1, P_2, \dots, P_n , and Q are continuous on the open interval \mathcal{I} , then there exists **exactly one** solution y on the open interval \mathcal{I} for

$$y^{(n)} + P_1 y^{(n-1)} + \cdots + P_{n-1} y' + P_n y = Q$$

that also satisfies the initial conditions

$$y(x_0) = y_0, \quad y'(x_0) = y_1, \quad \dots, \quad y^{(n-1)}(x_0) = y_{n-1}$$

- In developing a general theory of linear equations, it is helpful to introduce

Linear differential operator

- In calculus, Leibniz and Euler's notation for differentiation is more dominant,

$$\frac{d}{dx}, \quad \mathcal{D}$$

for the notations emphasize differentiation being an operation, just like

$$\sqrt{\quad}$$

- In addition to $\frac{d}{dx}$ or \mathcal{D} , there are many differential operators, e.g. ∇ .
- Other differential operator can be “built” from the simple operator \mathcal{D} :

$$y'' = \frac{d}{dt} \left(\frac{dy}{dt} \right) = \frac{d^2 y}{dt^2} = \mathcal{D}(\mathcal{D}y) = \mathcal{D}^2 y, \quad \text{and} \quad \frac{d^n}{dt^n} = \mathcal{D}^n y$$

where y represents a sufficiently differentiable function.

- Not only powers of \mathcal{D} denote an operator,

$$\mathcal{D}^n$$

polynomial expressions of \mathcal{D} are used to denote differential operators, e.g.

$$\mathcal{D} + 3, \quad \mathcal{D}^2 + 3\mathcal{D} - 4, \quad \text{and} \quad 5x^3\mathcal{D}^3 - 6x^2\mathcal{D}^2 + 4x\mathcal{D} + 9$$

are valid notations for differential operators.

Definition

In general, we define an *n*th-order linear differential or polynomial operator to be

$$\mathcal{L} = \alpha_n \mathcal{D}^n + \alpha_{n-1} \mathcal{D}^{n-1} + \cdots + \alpha_1 \mathcal{D} + \alpha_0 \quad (3)$$

where $\alpha_0, \alpha_1, \dots, \alpha_n$ are functions of x .

- Any linear differential equation can be expressed in terms of \mathcal{D} , for example,

$$\begin{aligned} y'' + 5y' + 6y = 5x - 3 &\iff \mathcal{D}^2 y + 5\mathcal{D}y + 6y = 5x - 3 \\ &\iff (\mathcal{D}^2 + 5\mathcal{D} + 6)y = 5x - 3 \end{aligned}$$

- Once we have defined a specific differential operator \mathcal{L} , for example

$$\mathcal{L} = \mathcal{D}^2 + 5\mathcal{D} + 6$$

then the following defines a differential equation

$$\mathcal{L}(y) = 5x - 3$$

- Homogeneous linear equations with constant coefficients is simply written as

$$\mathcal{L}(y) = 0$$

where $\mathcal{L} = a_n \mathcal{D}^n + a_{n-1} \mathcal{D}^{n-1} + \cdots + a_1 \mathcal{D} + a_0$, and a_i are constants.

- As a consequence of two basic properties of differentiation,

$$1. \mathcal{D}[cf] = c\mathcal{D}[f] \qquad 2. \mathcal{D}[f+g] = \mathcal{D}[f] + \mathcal{D}[g]$$

the polynomial operator \mathcal{L} a linear operator.

Superposition Principle

Let ϕ_1, \dots, ϕ_k be solutions of the **homogeneous** n th-order linear equation, then

$$y = c_1\phi_1 + c_2\phi_2 + \dots + c_k\phi_k, \quad \text{where the } c_i\text{'s are arbitrary constants.}$$

is also a solution.

Proof

- Suppose \mathcal{L} is the differential operator defined by equation (3), and if

$$\mathcal{L}(\phi_1) = 0, \quad \dots, \quad \mathcal{L}(\phi_k) = 0, \quad \text{and} \quad y = c_1\phi_1 + c_2\phi_2 + \dots + c_k\phi_k$$

then

$$\begin{aligned}\mathcal{L}(y) &= \mathcal{L}(c_1\phi_1 + c_2\phi_2 + \dots + c_k\phi_k) \\ &= c_1\mathcal{L}(\phi_1) + c_2\mathcal{L}(\phi_2) + \dots + c_k\mathcal{L}(\phi_k) \\ &= c_1 \cdot 0 + c_2 \cdot 0 + \dots + c_k \cdot 0 = 0\end{aligned}$$

Theorem

Let y_p be any particular solution of the nonhomogeneous equation (1), and y_c be the complementary solution, then the general solution of equation (1) is

$$y = y_c + y_p$$

Proof

- Suppose \mathcal{L} is the corresponding differential operator for equation (1), and let

$$\mathcal{L}(y_p) = f$$

- If we let $y^* = y - y_p$, where y is the general solution of $\mathcal{L}(y) = f$, then

$$\mathcal{L}(y^*) = \mathcal{L}(y - y_p) = \mathcal{L}(y) - \mathcal{L}(y_p) = f - f = 0$$

so y^* is the general solution of $\mathcal{L}(y) = 0$, hence the complementary solution.

Q: Can you guess the form of the complementary solution y_c ?

- Suppose $y = e^{rx}$, where $r \in \mathbb{C}$, is a solution of the homogeneous equation

$$\mathcal{L}(y) = 0, \quad \text{where } \mathcal{L} \text{ is defined by equation (3).}$$

- Since $\mathcal{D}^k(e^{rx}) = r^k e^{rx}$, then

$$\begin{aligned}\mathcal{L}(e^{rx}) &= \alpha_n \mathcal{D}^n e^{rx} + \alpha_{n-1} \mathcal{D}^{n-1} e^{rx} + \cdots + \alpha_1 \mathcal{D} e^{rx} + \alpha_0 e^{rx} \\ &= \alpha_n r^n e^{rx} + \alpha_{n-1} r^{n-1} e^{rx} + \cdots + \alpha_1 r e^{rx} + \alpha_0 e^{rx} \\ &= (\alpha_n r^n + \alpha_{n-1} r^{n-1} + \cdots + \alpha_1 r + \alpha_0) e^{rx}\end{aligned}$$

- Hence $\mathcal{L}(e^{rx}) = 0$ if and only if r is a root of the **characteristic polynomial**

$$p(r) = \alpha_n r^n + \alpha_{n-1} r^{n-1} + \cdots + \alpha_1 r + \alpha_0$$

- You should be able to extend theorems for second-order equations, without too much effort, to higher-order equations if the characteristic polynomial leads to **distinct roots**.

Q: What is the form of the general solution for

$$y^{(4)} - y = 0$$

- Solve the corresponding characteristic equation

$$r^4 = 1 \implies r_{1,2} = \pm 1 \quad \text{and} \quad r_{3,4} = \pm i$$

- Thus we expect the general solution to be

$$y = c_1 e^{r_1 x} + c_2 e^{r_2 x} + d_1 e^{r_3 x} + d_2 e^{r_4 x} = c_1 e^x + c_2 e^{-x} + d_1 e^{ix} + d_2 e^{-ix}$$

- Eliminating complex numbers,

$$\begin{aligned} y &= c_1 e^x + c_2 e^{-x} + e^{0 \cdot x} (c_3 \cos 1 \cdot x + c_4 \sin 1 \cdot x) \\ &= c_1 e^x + c_2 e^{-x} + c_3 \cos x + c_4 \sin x \end{aligned}$$

Q: Can we always solve the initial-value problem involving the above equation?

- In operational calculus, we have the following theorem,

Theorem

Suppose a_i s and b_j s are **constant**, and

$$\mathcal{P} = \sum_{i=0}^k a_i \mathcal{D}^i \quad \text{and} \quad \mathcal{Q} = \sum_{j=0}^m b_j \mathcal{D}^j$$

are two linear differential operators, then

$$\mathcal{P}\mathcal{Q} = \mathcal{Q}\mathcal{P} = \sum_{i=0}^k \sum_{j=0}^m a_i b_j \mathcal{D}^{i+j}$$

- So we can, without altering the result, factor and change the orders e.g.

$$y'' + 5y' + 6y = (\mathcal{D}^2 + 5\mathcal{D} + 6)y = (\mathcal{D} + 2)(\mathcal{D} + 3)y = (\mathcal{D} + 3)(\mathcal{D} + 2)y$$

- Notice the above is **NOT** true for variable coefficients.

- The characteristic polynomial completely determines the operator, we write

$$p(\mathcal{D}) = a_n \mathcal{D}^n + a_{n-1} \mathcal{D}^{n-1} + \cdots + a_1 \mathcal{D} + a_0$$

where p is a polynomial. So p takes differential operator \mathcal{D} as a “variable”.

The Exponential Shift Law

If p is a polynomial and r is a constant $\in \mathbb{C}$, then

$$p(\mathcal{D})\left(e^{rx}h\right) = e^{rx}p(\mathcal{D} + r)(h)$$

where h is a general function of x .

Proof

By the product rule,

$$\mathcal{D}\left(e^{rx}h\right) = e^{rx}\mathcal{D}(h) + re^{rx}h = e^{rx}\mathcal{D}(h) + re^{rx}\mathcal{I}(h) = e^{rx}(\mathcal{D} + r)(h)$$

where \mathcal{I} is the identity operator.

Proof

Now subtracting $se^{rx}h$ from both sides, where $s \in \mathbb{C}$,

$$\mathcal{D}(e^{rx}h) - se^{rx}h = e^{rx}(\mathcal{D} + r)(h) - se^{rx}h$$

$$\mathcal{D}(e^{rx}h) - s\mathcal{I}(e^{rx}h) = e^{rx}[(\mathcal{D} + r)(h) - s\mathcal{I}(h)]$$

$$(\mathcal{D} - s\mathcal{I})(e^{rx}h) = e^{rx}(\mathcal{D} + r - s\mathcal{I})(h)$$

Dropping the identity operator,

$$(\mathcal{D} - s)(e^{rx}h) = e^{rx}(\mathcal{D} + r - s)(h) \quad (4)$$

Now with the equation (4) proved, we next need to show that

$$(\mathcal{D} - s)^k(e^{rx}h) = e^{rx}(\mathcal{D} + r - s)^k(h), \quad \text{where } k \text{ is an integer.}$$

This can be done by mathematical induction.

Proof

We have just proved that it is true for $k = 1$, let us assume it is true for $k = n$, where n is some integer. We need to show it is true for $k = n + 1$.

$$(\mathcal{D} - s)^{n+1} (e^{rx} h)$$

Using the last theorem, we can factor $(\mathcal{D} - s)^n$,

$$(\mathcal{D} - s)^{n+1} (e^{rx} h) = (\mathcal{D} - s)^n (\mathcal{D} - s) (e^{rx} h)$$

Applying the base case, that is equation (4),

$$(\mathcal{D} - s)^{n+1} (e^{rx} h) = (\mathcal{D} - s)^n e^{rx} (\mathcal{D} + r - s) (h)$$

Let $h^* = (\mathcal{D} + r - s) (h)$, use the assumption that it is true $k = n$,

$$(\mathcal{D} - s)^{n+1} (e^{rx} h) = (\mathcal{D} - s)^n (e^{rx} h^*) = e^{rx} (\mathcal{D} + r - s)^n h^*$$

Proof

We complete the induction by plugging $h^* = (\mathcal{D} + r - s)^k (h)$ back,

$$(\mathcal{D} - s)^{n+1} (e^{rx} h) = e^{rx} (\mathcal{D} + r - s)^{n+1} (h)$$

Therefore the following equation is true for all integer k ,

$$(\mathcal{D} - s)^k (e^{rx} h) = e^{rx} (\mathcal{D} + r - s)^k (h) \quad (5)$$

Then successively apply the above equation for different operator $(\mathcal{D} - s_i)^{k_i}$,

$$(\mathcal{D} - s_1)^{k_1} \cdots (\mathcal{D} - s_m)^{k_m} (e^{rx} h) = e^{rx} (\mathcal{D} - s_1 + r)^{k_1} \cdots (\mathcal{D} - s_m + r)^{k_m} (h)$$

Lastly, by the fundamental theorem of algebra, every polynomial of degree n has exactly n roots, thus can be factored into the following form

$$p(\mathcal{D}) = (\mathcal{D} - s_1)^{k_1} (\mathcal{D} - s_2)^{k_2} \cdots (\mathcal{D} - s_m)^{k_m}$$

where $s_i \in \mathbb{C}$, are the roots of the polynomial p . □

Theorem

If λ_i is a root of multiplicity k_i of the characteristic polynomial

$$p(\lambda) = a_n \lambda^n + a_{n-1} \lambda^{n-1} + \cdots + a_1 \lambda + a_0$$

of the linear differential operator $p(\mathcal{D})$ with constant coefficients, then

$$x^\gamma e^{\lambda_i x}, \quad \text{where } \gamma = 0, 1, \dots, (k_i - 1).$$

are solution of

$$p(\mathcal{D})(y) = 0$$

Proof

- By the exponential shift law,

$$p(\mathcal{D})(e^{rx}h) = e^{rx}p(\mathcal{D} + r)(h)$$

- it follows that

$$(\mathcal{D} - \lambda_i)^{k_i} (x^\gamma e^{\lambda_i x}) = e^{\lambda_i x} (\mathcal{D} - \lambda_i + \lambda_i)^{k_i} (x^\gamma) = e^{\lambda_i x} D^{k_i} x^\gamma$$

Proof

- For $\gamma = 0, 1, 2, \dots, (k_i - 1)$.

$$(\mathcal{D} - \lambda_i)^{k_i} \left(x^\gamma e^{\lambda_i x} \right) = e^{\lambda_i x} D^{k_i} x^\gamma = 0$$

- On the other hand, $p(\mathcal{D})$ must contain the factor

$$(\mathcal{D} - \lambda_i)^{k_i}$$

- We can factor $p(\mathcal{D}) = (\mathcal{D} - \lambda_i)^{k_i} q(\mathcal{D})$, where $q(\mathcal{D}) = \prod_{\lambda_j \neq \lambda_i} (\mathcal{D} - \lambda_j)^{k_j}$
- Now apply the differential operator $p(\mathcal{D})$ to

$$x^\gamma e^{\lambda_i x}$$

- By the theorem on [L910](#), we can interchange the order

$$p(\mathcal{D}) \left(x^\gamma e^{\lambda_i x} \right) = q(\mathcal{D}) \left[(\mathcal{D} - \lambda_i)^{k_i} \left(x^\gamma e^{\lambda_i x} \right) \right] = 0 \quad \text{for } \gamma = 0, \dots, (k_i - 1).$$

Exercise

(a) Find the general solution of

$$y^{(5)} - 3y^{(4)} + 3y''' - y'' = 0$$

(b) What is the general solution for

$$\mathcal{L}(y) = 0$$

where \mathcal{L} has a characteristic polynomial of

$$(\lambda^2 + 1)^3(\lambda + 1)^2$$

Definition

If f is a sufficiently differentiable function and \mathcal{L} is a linear differential operator with constant coefficients such that

$$\mathcal{L}(f) = 0$$

then \mathcal{L} is said to be an **annihilator** of the function.

- Clearly, the differential operator \mathcal{D}^n annihilates each of the function

$$x^k, \quad \text{for } k = 0, 1, \dots, (n-1)$$

- The functions that are annihilated by a polynomial operator \mathcal{L} are simply those functions that can be obtained from the general solution of

$$\mathcal{L}(y) = 0$$

Exercise

Find a differential operator that annihilates each of the functions

$$e^{\lambda t}, \quad te^{\lambda t}, \quad t^2e^{\lambda t}, \quad \dots, \quad t^{n-1}e^{\lambda t}$$

- When R and θ , $\theta > 0$ are real numbers, the quadratic formula reveals

$$\lambda^2 - 2R\lambda + (R^2 + \theta^2) = 0$$

has complex roots $\lambda = R \pm i\theta$, and clearly

$$[\lambda^2 - 2R\lambda + (R^2 + \theta^2)]^n = 0$$

has $\lambda = R \pm i\theta$ of multiplicity of n .

- Hence the differential operator $[\mathcal{D}^2 - 2R\mathcal{D} + (R^2 + \theta^2)]^n$ annihilates

$$e^{Rt} \cos \theta t, \quad te^{Rt} \cos \theta t, \quad t^2 e^{Rt} \cos \theta t, \quad \dots, \quad t^{n-1} e^{Rt} \cos \theta t$$

$$e^{Rt} \sin \theta t, \quad te^{Rt} \sin \theta t, \quad t^2 e^{Rt} \sin \theta t, \quad \dots, \quad t^{n-1} e^{Rt} \sin \theta t$$

Exercise

Find a differential operator that annihilates $f(t) = 5e^{-t} \cos 2t - 9e^{-t} \sin 2t$.

Theorem

Suppose \mathcal{L} is a linear differential operator with constant coefficients, then

$$\mathcal{L}(c_1\phi_1 + c_2\phi_2) = 0 \quad \text{where} \quad \mathcal{L}(\phi_1) = 0 \quad \text{and} \quad \mathcal{L}(\phi_2) = 0$$

Let \mathcal{L}_1 and \mathcal{L}_2 be linear differential operators with constant coefficients, then

$$\mathcal{L}_1\mathcal{L}_2(c_1\phi_1 + c_2\phi_2) = 0 \quad \text{where} \quad \mathcal{L}_1(\phi_1) = 0 \quad \text{and} \quad \mathcal{L}_2(\phi_2) = 0$$

Proof

- Note \mathcal{L}_1 annihilates ϕ_1 and \mathcal{L}_2 annihilates ϕ_2 , but they do not necessarily

$$\mathcal{L}_1(\phi_2) \neq 0 \quad \text{and} \quad \mathcal{L}_2(\phi_1) \neq 0$$

- However, for constant coefficients, we can change the order of \mathcal{L}_1 and \mathcal{L}_2 ,

$$\begin{aligned}\mathcal{L}_1\mathcal{L}_2(c_1\phi_1 + c_2\phi_2) &= c_1\mathcal{L}_1\mathcal{L}_2(\phi_1) + c_2\mathcal{L}_1\mathcal{L}_2(\phi_2) \\ &= 0 + 0 = 0\end{aligned}$$

Exercise

- (a) Solve the following nonhomogeneous equation

$$y'' + 3y' + 2y = 4t^2$$

- (b) Solve the following nonhomogeneous equation

$$y''' - 4y'' + 4y' = 5t^2 - 6t + 4t^2e^{2t} + 3e^{5t}$$