

Optimization in Machine Learning: Lecture 3

Convex Functions

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Definitions and Properties

Operations that Preserve Convexity

Conjugate Functions





Convex Set



- convex optimization is to minimize a convex function over a convex set
 - convex combination
 - convex sets
 - operations that preserve convexity
 - separating hyperplane
 - supporting hyperplane



Convex Function



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1 Definitions and Properties

Operations that Preserve Convexity

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Definition



• $f: \mathbb{R}^n \to \mathbb{R}$ is convex, if **dom** f is a convex set and

$$f(\theta x + (1 - \theta)y) \le \theta f(x) + (1 - \theta)f(y) \quad \forall x, y \in \text{dom } f, \theta \in [0, 1]$$

"line is above the curve":



- strictly convex if strict inequality holds for $x \neq y$ and $\theta \in (0,1)$
- concave function: f is concave iff -f is convex.

Convex Function and Convex Sets

- $f: R^n \to R$ is convex, if **dom** f is a convex set and $f(\theta x + (1 \theta)y) \le \theta f(x) + (1 \theta)f(y) \quad \forall x, y \in \mathbf{dom} \ f, \theta \in [0, 1]$
- if f(x) is convex, then $\{x: f(x) \le 0\}$ is a convex set

• if *C* is a convex set, then it could be represented as the solution of a system of (maybe infinite number of) convex inequalities

supporting hyperplanes





Equivalent Conditions



• $f: \mathbb{R}^n \to \mathbb{R}$ is convex, if **dom** f is a convex set and

$$f(\theta x + (1 - \theta)y) \le \theta f(x) + (1 - \theta)f(y) \quad \forall x, y \in \text{dom } f, \theta \in [0, 1]$$

extension to multiple points

$$f\left(\sum_{i=1}^{m}\theta_{i}x_{i}\right)\leq\sum_{i=1}^{m}\theta_{i}f(x_{i}),\forall x_{i}\in\operatorname{dom}f,\theta_{i}\geq0,\sum_{i=1}^{m}\theta_{i}=1.$$

restriction on R:

g(t) = f(x + tv), dom $g = \{t: x + tv \in \text{dom } f\}$ is convex for $\forall x \in \text{dom } f, v \in \mathbb{R}^n$





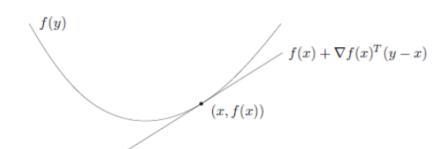
Equivalent Conditions



First-order condition

$$f(y) \ge f(x) + \nabla f(x)^{\mathsf{T}} (y - x) \quad \forall x, y \in \operatorname{dom} f$$

"tangent plane is below the surface" proof. consider univariate functions given by the gradient.





Gradient and Sub-Gradient

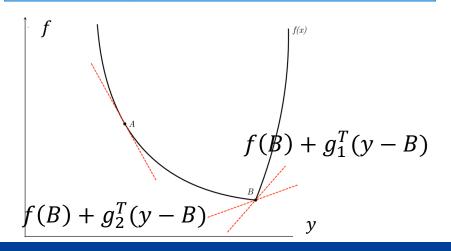


First-order condition

$$f(y) \ge f(x) + \nabla f(x)^{\mathsf{T}} (y - x) \quad \forall x, y \in \operatorname{dom} f$$

- consider a convex set $\{x: f(x) \le 0\}$
- $\nabla f(x)$ gives a supporting hyperplane
- how about non-smooth function?
 - there are multiple hyperplanes
 - the set containing the vectors of all supporting hyperplanes is called sub-gradient $\partial f(x)$

$$f(x) = |x|, \ \partial f(x) = \begin{cases} 1, & x > 0 \\ [-1,1], & x = 0 \\ -1, & x < 0 \end{cases}$$





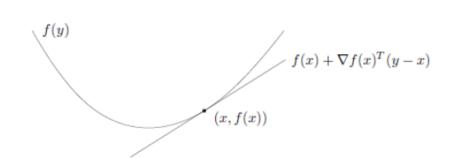
Equivalent Conditions



First-order condition

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"tangent plane is below the surface" proof. consider univariate functions given by the gradient.



Second-order condition

$$\nabla^2 f(x) \ge 0, \forall x \in \operatorname{dom} f \iff f \text{ is convex}$$

$$\nabla^2 f(x) > 0, \forall x \in \operatorname{dom} f$$
 is strictly convex

Examples



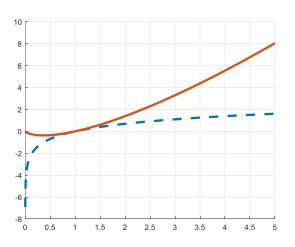
- affine functions $f(x) = a^{\mathsf{T}}x + b$
- exponential $f(x) = e^{ax}$
- powers $f(x) = x^{\alpha}$, with x > 0, $\alpha > 1$ or $\alpha \le 0$
- negative entropy $f(x) = x \log x$ with x > 0
- (minus powers) $f(x) = x^{\alpha}, 0 \le \alpha \le 1$
- (minus logarithm) $f(x) = \log x$ with x > 0



Examples



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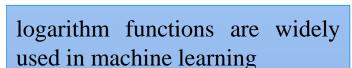


Examples

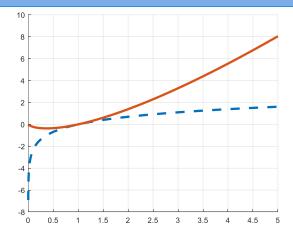
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$$(x\log x)' = \log x + 1$$
 $(x\log x)'' = 1/x > 0$

$$(\log x)' = 1/x \qquad (\log x)'' = -1/x^2 < 0$$



- for independent data, the joint probability will be in the form of multiplication, which could be transformed to sum by log
- entropy, a good measure for information/uncertainty, is in the form of logarithm





Measure of Uncertainty



$$\Rightarrow$$
 case 1: $x \in \{0,1,2,3\}, x_1 = 1$

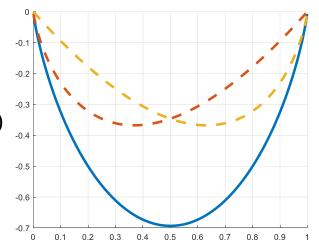
- case 2: $x \in \{0,1\}, x_1 = 1$
- the information of case 1 is larger
- quantitative measurement
 - no uncertainty, equal zero
 - proportional to uncertainty
 - consider case 2: $p \triangleq p(x = 0)$, 1 p = p(x = 1)

negative entropy = $p \log p + (1 - p) \log (1 - p)$



logarithm functions are widely used in machine learning

- for independent data, the joint probability will be in the form of multiplication, which could be transformed to sum by log
- entropy, a good measure for information/uncertainty, is in the form of logarithm





Sublevel Set and Epigraph



- **sublevel set** of $f: \mathbb{R}^n \to \mathbb{R}$ $C_\alpha = \{x \in \operatorname{dom} f: f(x) \le \alpha\}$
- sublevel sets of convex functions are convex



Sublevel Set and Epigraph

- **sublevel set** of $f: \mathbb{R}^n \to \mathbb{R}$ $C_\alpha = \{x \in \operatorname{dom} f: f(x) \le \alpha\}$
- sublevel sets of convex functions are convex
- **epigraph** of $f: \mathbb{R}^n \to \mathbb{R}$

epi
$$f = \{(x, t) \in \mathbb{R}^{n+1} \ x \in \text{dom } f : f(x) \le t\}$$



- from first order condition $f(y) \ge f(x) + \nabla f(x)^{\mathsf{T}} (y x)$
- for $(y, t) \in \operatorname{epi} f$ $t \ge f(y) \ge f(x) + \nabla f(x)^{\mathsf{T}} (y x)$



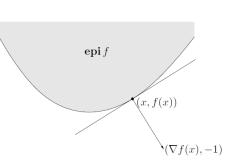
Sublevel Set and Epigraph

- **sublevel set** of $f: \mathbb{R}^n \to \mathbb{R}$ $C_\alpha = \{x \in \operatorname{dom} f: f(x) \le \alpha\}$
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epi
$$f = \{(x, t) \in \mathbb{R}^{n+1} \ x \in \text{dom } f : f(x) \le t\}$$

- f is convex iff **epi** f is a convex set
 - from first order condition $f(y) \ge f(x) + \nabla f(x)^{\mathsf{T}} (y x)$
 - for $(y, t) \in \operatorname{epi} f$ $t \ge f(y) \ge f(x) + \nabla f(x)^{\mathsf{T}} (y x)$

$$\begin{bmatrix} \nabla f(x) \\ -1 \end{bmatrix}^{-1} \left(\begin{bmatrix} y \\ t \end{bmatrix} - \begin{bmatrix} x \\ f(x) \end{bmatrix} \right) \le 0 \quad \text{supporting hyperplane}$$



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Nonnegative Weighted Sum and Composition

- nonnegative weighted sum $f = w_1 f_1 + \dots + w_m f_m$, $w_m \ge 0$
 - nonnegative multiple: αf is convex with $\alpha \geq 0$
 - integral $\int w(y)f(x,y)dy$
 - the set of convex function is a conic
- composition with affine function f(Ax + b)
 - residual $r_i = b_i a_i^{\mathsf{T}} x$
 - measuring residual by convex loss is convex
 - minus log (MLE) $-\sum_{i=1}^{m} \log(b_i a_i^{\mathsf{T}} x)$
 - $||Ax b||_2^2$

Nonnegative Weighted Sum and Composition

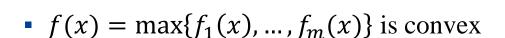
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 - measuring residual by convex loss is convex
 - minus log (MLE) $-\sum_{i=1}^{m} \log(b_i a_i^{\mathsf{T}} x)$
 - norm $||Ax b||_2^2$

$$r_i = b_i - a_i^\mathsf{T} \phi(x)$$

composition of $g: \mathbb{R}^n \to \mathbb{R}$ and $h: \mathbb{R} \to \mathbb{R}$ f(x) = h(g(x)) is convex, if

- g convex, h convex and non-decreasing
- g concave, h convex and non-increasing

Pointwise Maximum/Supremum





- piecewise-linear function: $f(x) = \max_{i} \{a_i^{\mathsf{T}} x + b_i\}$
- largest error: $f(x) = \max_{i} \left\{ \left\| a_i^{\mathsf{T}} x b_i \right\|_2^2 \right\}$
- sum of *r* largest errors

- robust learning
- risk control
- robust control

• sum of
$$r$$
 largest components: $x_{[r_1]} \ge x_{[r_2]}$ if $r_1 \le r_2$

$$f(x) = x_{[1]} + x_{[2]} + \cdots x_{[r]}$$

• f(x, y) is convex in x for each $y \in Y$, then $\sup_{y} f(x, y)$ is convex



- distance to farthest point in a set $f(x) = \sup_{y \in C} ||x y||$
- maximum eigenvalue $\lambda_{\max}(X) = \sup_{\|y\|_2=1} y^{\mathsf{T}} X y$





Minimization and Schur Complement

- if f(x, y) is convex w.r.t. (x, y) and C is a convex set, then the minimization $g(x) = \inf_{y \in C} f(x, y)$ is convex
- distance to a convex set S

$$dist(x,S) \triangleq g(x) = \inf_{y \in S} ||x - y||$$

difference to
$$f(x) = \sup_{y \in C} ||x - y||$$

- Shur complement
 - $f(x,y) = x^{\mathsf{T}}Ax + 2x^{\mathsf{T}}By + y^{\mathsf{T}}Cy$ with $\begin{bmatrix} A & B \\ B^{\mathsf{T}} & C \end{bmatrix} \ge 0, C > 0$

$$C^{\uparrow} = C^{\dagger}$$

- minimizing over y, i.e., $g(x) = \inf_{y} f(x, y) = x^{T} (A BC^{\uparrow}B^{T})x$, is convex widely used in matrix in
- Shur complement $A BC^{\uparrow}B^{\top} \ge 0$

widely used in matrix inverse, and related tasks, e.g., control, SLAM, etc.



Perspective Function and KL Divergence

• for a function $f(x): \mathbb{R}^n \to \mathbb{R}$, its perspective function is defined as

$$g(x,t) = t f(x/t)$$

- if f(x) is convex (concave), so is g(x,t)
- relative entropy

proof:

- epigraph
- perspective function preserves convexity

$$\sum_{i=1}^{n} \left(\frac{u_i \log(u_i/v_i)}{v_i} \right)$$

• $f(x) = -\log x$ is convex and its perspective function is

$$g(x,t) = tf(x/t) = -t\log\frac{x}{t} = t\log t - t\log x$$

Kullback-Leibler divergence

$$D_{kl}(u, v) = \sum_{i}^{n} (u_i \log(u_i/v_i) - u_i + v_i)$$

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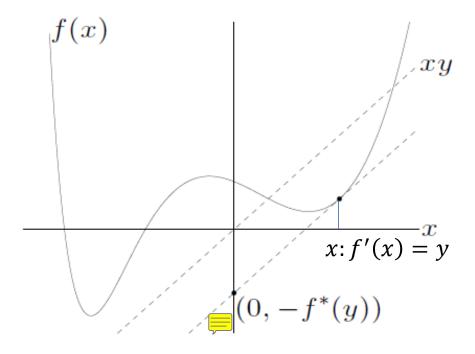


Definition and Understanding



• the **conjugate** of a function $f: \mathbb{R}^n \to \mathbb{R}$ is

$$f^*(y) = \sup_{x \in \mathbf{dom}\, f} (y^\mathsf{T} x - f(x))$$



for a given y, $f^*(y)$ is the largest gap between the affine function xyand the function f(x)

when f is differentiable, the optimality condition tells

$$\nabla(y^{\mathsf{T}}x - f(x)) = y - f'(x) = 0$$



Definition and Understanding



• the **conjugate** of a function $f: \mathbb{R}^n \to \mathbb{R}$ is

$$f^*(y) = \sup_{x \in \mathbf{dom}\, f} (y^\mathsf{T} x - f(x))$$

- examples
 - affine functions:

$$f(x) = ax + b \to f^*(y) = \sup_{x \in \mathbf{dom} \, f} (x^{\mathsf{T}}(y - a) - b) = \begin{cases} -b, & y = a \\ +\infty, & y \neq a \end{cases}$$

exponential functions

$$f(x) = e^x \to f^*(y) = \sup_{x \in \mathbf{dom} \, f} (xy - e^x) = \begin{cases} y \log y - y, & y > 0 \\ \infty, & y < 0 \end{cases}$$

indicator function

$$f(x) = \begin{cases} \infty, & x \notin S \\ 0, & x \in S \end{cases} \to f^*(y) = \sup_{x \in S} y^{\mathsf{T}} x \qquad \text{supporting of } S$$

Properties



• the **conjugate** of a function $f: \mathbb{R}^n \to \mathbb{R}$ is

$$f^*(y) = \sup_{x \in \mathbf{dom}\, f} (y^\mathsf{T} x - f(x))$$

- a conjugate function is convex, even when *f* is not.
- Fenchel inequality: $f(x) + f^*(y) \ge x^T y$
 - example $x^{\mathsf{T}}Qx + y^{\mathsf{T}}Q^{-1}y \ge 2x^{\mathsf{T}}y$, when $Q \in S_{++}^n$
- conjugate of conjugate: when f is convex, proper, and closed, then $f^{**} = f$

Conjugate and sub-Gradient



• the **conjugate** of a function $f: \mathbb{R}^n \to \mathbb{R}$ is

$$f^*(y) = \sup_{x \in \mathbf{dom}\, f} (y^\mathsf{T} x - f(x))$$

for a convex, proper, and closed function f, the following three are equal

•
$$(1) f(x) + f^*(y) = x^T y$$

- (2) $y \in \partial f(x)$
- (3) $x \in \partial f^*(y)$
- sub-gradient by conjugation

$$\partial f(x) = \operatorname{argmax}_y \{ x^{\mathsf{T}} y - f^*(y) \}$$

$$\partial f^*(y) = \operatorname{argmax}_{x} \{ x^{\mathsf{T}} y - f(x) \}$$

Proof: $(1) \rightarrow (2)$

-
$$y^{\mathsf{T}}x - f(x) = f^*(y) = \sup_{x \in \text{dom } f} (y^{\mathsf{T}}x - f(x))$$

-
$$y^{\mathsf{T}}x - f(x) \ge y^{\mathsf{T}}z - f(z), \forall z \in \mathbf{dom} \ f$$

-
$$f(z) \ge f(x) + y^{\mathsf{T}}(z - x), \forall z \in \operatorname{dom} f$$

- $y \in \partial f(x)$

Proof: $(2) \rightarrow (1)$

- definition of sub-Gradient + Fenchel inequality

Proof: $(1) \leftarrow \rightarrow (3)$

-
$$f^{**} = f$$
, denote f^* as g , then $g^*(x) + g(y) = x^T y$

- by (2), $x \in \partial g(y) = \partial f^*(y)$

1 Definitions and Properties

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Conclusion and Home Work



- convex optimization is to minimize a convex function over a convex set
 - definition of convex functions
 - first-, second condition
 - operations that preserve convexity
 - conjugate functions
 - subgradient and the use of conjugate function

• Excise 3.1: convexity proof

Excise 3.20: convexity preservation practice

Excise 3.38: understating conjugate

THANKS

