



Optimization in Machine Learning: Lecture 1 **Tutorial**

by Xiaolin Huang

xiaolinhuang@sjtu.edu.cn

SEIEE 2-429

Institute of Image Processing and Pattern Recognition

<http://www.pami.sjtu.edu.cn/>



上海交通大學

SHANGHAI JIAO TONG UNIVERSITY

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What is Optimization

2

History of Optimization

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Optimization in Machine Learning

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Course Information



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Definition of Optimization



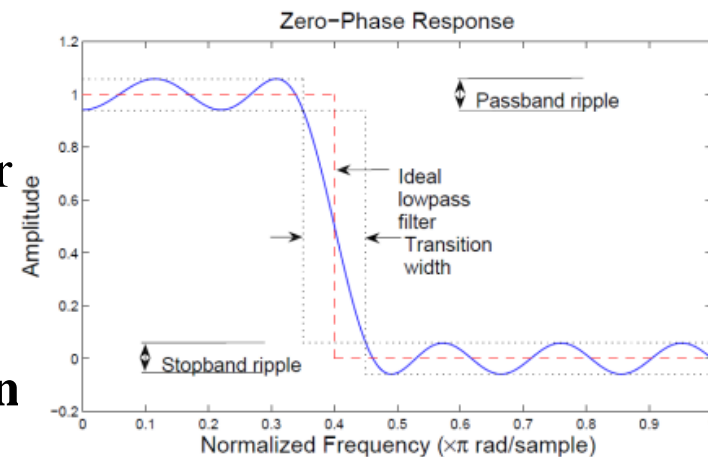
- **Optimization** includes finding "best available" values of some objective function given a defined domain (or input), including a variety of different types of objective functions and different types of domains^[wikipedia]
- “*Since 1990 many applications have been discovered in areas such as automatic control systems, estimation and signal processing, communications and networks, electronic circuit design, data analysis and modeling, statistics, and finance.*” — S. Boyd and L. Vendenberghe

Applications of Optimization



Automatic Control Systems

- **Optimal Control** deals with the problem of finding a control law for a given system such that a certain optimality criterion is achieved.
- **Stability condition** of continuous-time linear systems could be modeled as an linear matrix inequality, a convex constraint.
- **Filter Design** is to find a discrete FIR filter by minimizing the integral of the square of the error to an ideal frequency function of the filter
- **Model Predictive Control, Network Allocation**



Applications of Optimization

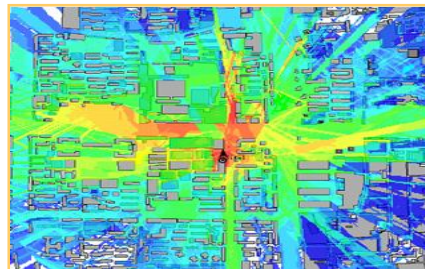
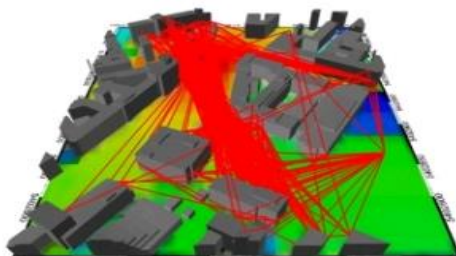
Signal Processing

Compressive/Compressed Sensing

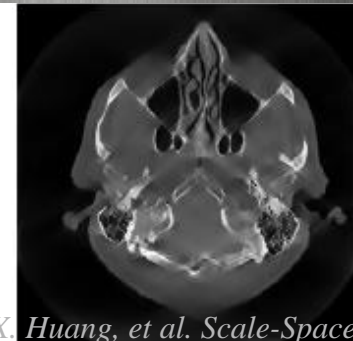
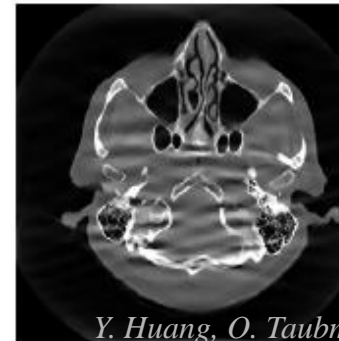
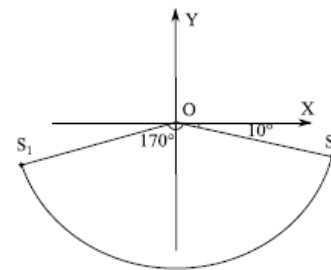
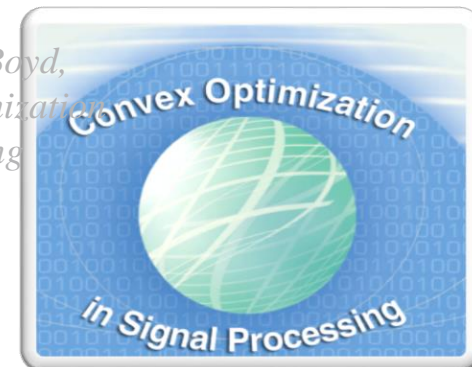
By minimizing the l_1 regularization term, one could recover sparse signals with relatively fewer measurements

Parameters Setting

- Antenna/Cell/District/City



*J. Mattingley and S. Boyd,
Real-time Convex Optimization
in Signal Processing*

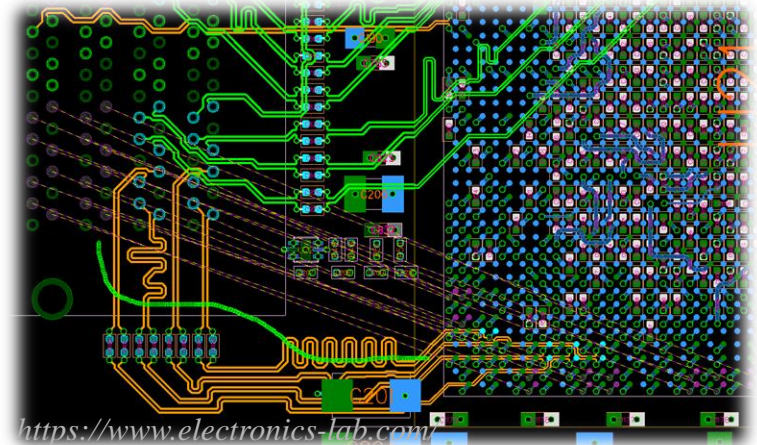


*Y. Huang, O. Taubmann, X. Huang, et al. Scale-Space
Anisotropic Total Variation for Limited Angle Tomography*

Applications of Optimization



- **Electronic Circuit Design**
 - Device sizing (EDA)
- **Finance**
 - Prediction
 - Portfolio optimization
 - Risk control
- **Route Planning**
- **Scheduling**





Applications of Optimization



- Route Planning
- Scheduling



Other Words



- **Optimization** includes finding "best available" values of some objective function given a defined domain (or input), including a variety of different types of objective functions and different types of domains^[wikipedia]
- **Operations Research/Operational Research**
- **Mathematical Programming**

$$\begin{array}{ll}\min_{\mathbf{x}} & f_0(\mathbf{x}) \\ \text{s.t.} & f_i(x) \leq 0, i = 1, \dots, m, \\ & h_i(\mathbf{x}) = 0, i = 1, \dots, p.\end{array}$$

- 优化/运筹学/数学规划
- 优选法/统筹法

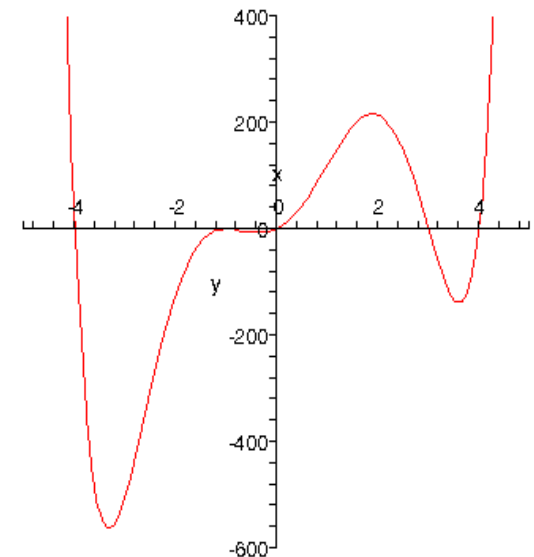


Optimization Problem



$$\begin{array}{ll}\min_x & f_0(x) \\ \text{s. t.} & f_i(x) \leq 0, i = 1, \dots, m \\ & h_i(x) = 0, i = 1, \dots, p\end{array}$$

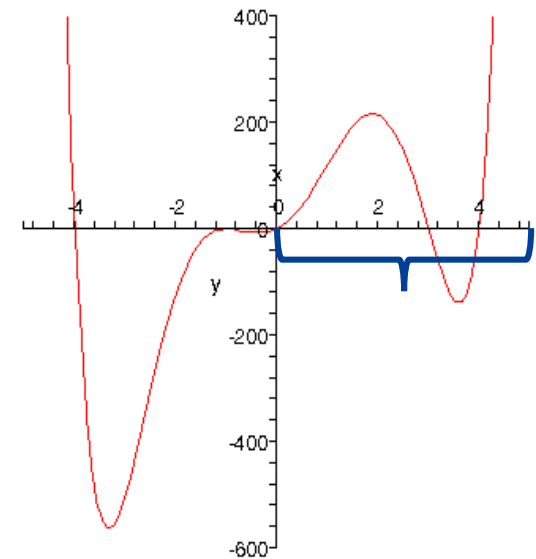
- $f_0(x)$: objective function
 - loss/cost function
 - (minus) utility/fitness/energy function
 - $f_0(x): R^n \rightarrow R$
 - $f_0(x)$ could be a vector function \rightarrow multiple-criterion problem



Optimization Problem



$$\begin{array}{ll}\min_x & f_0(x) \\ \text{s. t.} & f_i(x) \leq 0, i = 1, \dots, m \\ & h_i(x) = 0, i = 1, \dots, p\end{array}$$



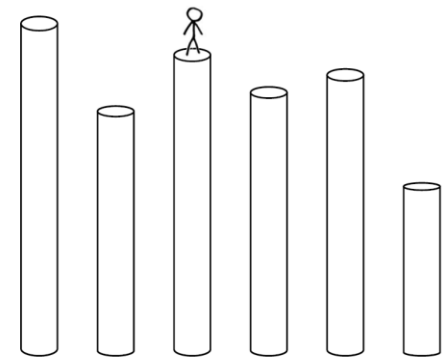
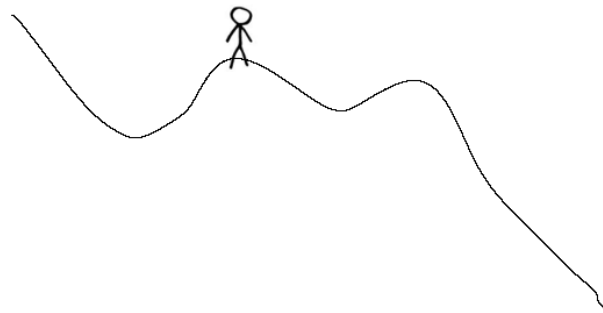
- $f_i(x), h_i(x)$: constraints
 - $f_i(x)$ inequality constraints
 - $h_i(x)$ equality/equation constraints
 - any x satisfying $f_i(x) \leq 0, h_i(x) = 0$ is called a *feasible solution*
 - all the feasible solutions form the *feasible set/feasible domain*
 - the feasible set is not empty, the problem is *feasible*
- optimal solution $x^* = \underset{x}{\operatorname{argmin}}\{f_0(x), \text{s. t. } \dots\}$: no better feasible solution

Optimization Variable



$$\begin{array}{ll}\min_x & f_0(x) \\ \text{s. t.} & f_i(x) \leq 0, i = 1, \dots, m \\ & h_i(x) = 0, i = 1, \dots, p\end{array}$$

- $x \in D$: it is very important to distinguish the possible value of x
 - real
 - Boolean (0/1)
 - integer



continuity is very important

Sudoku problem



- requirement

- each column
- each row,
- each 3×3 subregion

have different values but equal summarization

- if the item chooses value from real

- very easy

- if it can only take integer $1, 2, \dots, 9$

- a complicated problem
- could solved by continuous optimization

5	3			7				
6			1	9	5			
	9	8					6	
8				6				3
4			8		3			1
7				2				6
	6					2	8	
			4	1	9			5
				8			7	9

Optimization Variable



$$\begin{array}{ll}\min_x & f_0(x) \\ \text{s. t.} & f_i(x) \leq 0, i = 1, \dots, m \\ & h_i(x) = 0, i = 1, \dots, p\end{array}$$

- $x \in D$: it is very important to distinguish the possible value of x
 - if the variables can take any real values, the problem is relatively easy
many machine learning tasks can be modeled as continuous problems, which will be our main focus
- some or all variables are constrained to take on integer values, it is called *integer programming*, usually results in a *combination programming*
combination programming becomes more and more important in machine learning, e.g., alpha-GO, auto-ML, network architecture search (NAS),

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Linear Programming



- General Problem

$$\begin{array}{ll}\min_{\mathbf{x}} & f_0(\mathbf{x}) \\ \text{s.t.} & f_i(x) \leq 0, i = 1, \dots, m, \\ & h_i(\mathbf{x}) = 0, i = 1, \dots, p.\end{array}$$

- Linear Programming

$$\begin{array}{ll}\min_{\mathbf{x}} & \mathbf{f}_0^\top \mathbf{x} \\ \text{s.t.} & \mathbf{f}_i^\top \mathbf{x} + a_i \leq 0, i = 1, \dots, m, \\ & \mathbf{h}_i^\top \mathbf{x} + b_i = 0, i = 1, \dots, p.\end{array}$$

$$x^\top y = \langle x, y \rangle = \sum_i x(i)y(i)$$

Linear Programming



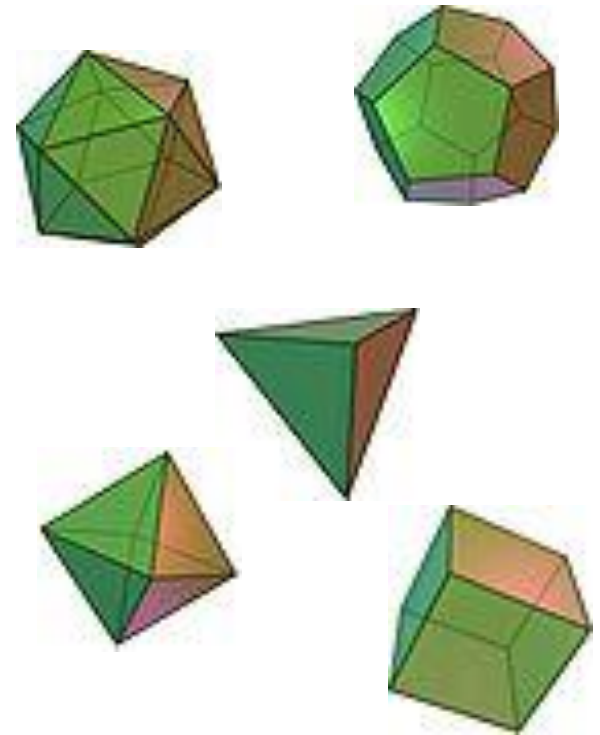
■ General Problem

$$\begin{aligned} \min_{\mathbf{x}} \quad & f_0(\mathbf{x}) \\ \text{s.t.} \quad & f_i(\mathbf{x}) \leq 0, i = 1, \dots, m, \\ & h_i(\mathbf{x}) = 0, i = 1, \dots, p. \end{aligned}$$

■ Linear Programming

$$\begin{aligned} \min_{\mathbf{x}} \quad & \mathbf{f}_0^\top \mathbf{x} \\ \text{s.t.} \quad & \mathbf{f}_i^\top \mathbf{x} + a_i \leq 0, i = 1, \dots, m, \\ & \mathbf{h}_i^\top \mathbf{x} + b_i = 0, i = 1, \dots, p. \end{aligned}$$

- minimize a linear function with linear constraints
- minimize a linear function over a **polyhedron**

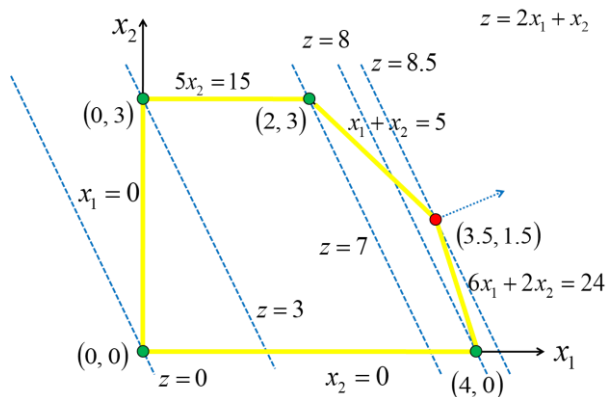


Simplex Method

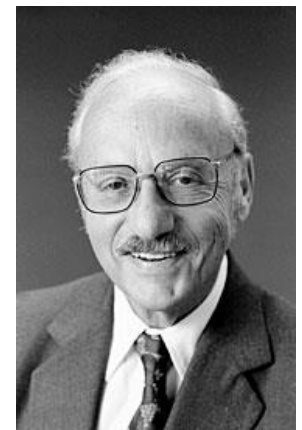
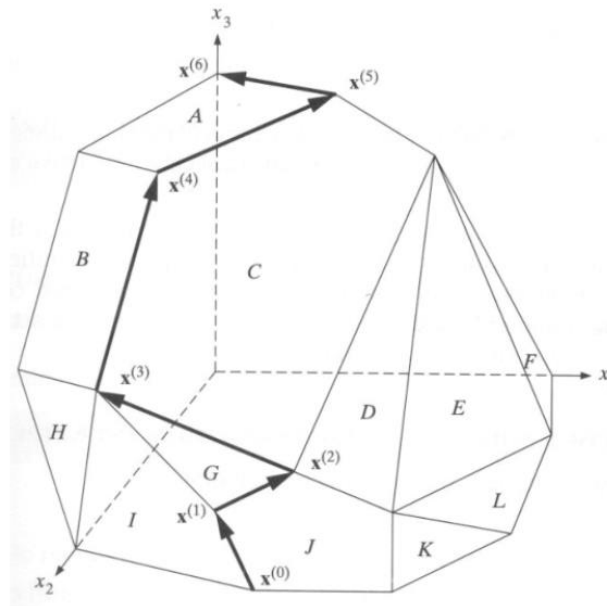


- **Dantzig: simplex method**
 - one of the vertices is optimal
 - search along the edges

"A few days later I apologized to Neyman for taking so long to do the homework — the problems seemed harder to do than usual"
George B. Dantzig (1914-2005)



$$\begin{aligned}
 \max \quad & z = 2x(1) + x(2) \\
 \text{s.t.} \quad & x(1) + x(2) \leq 5 \\
 & 6x(1) + 2x(2) \leq 24 \\
 & 5x(2) \leq 15 \\
 & x(1) \geq 0, x(2) \geq 0
 \end{aligned}$$



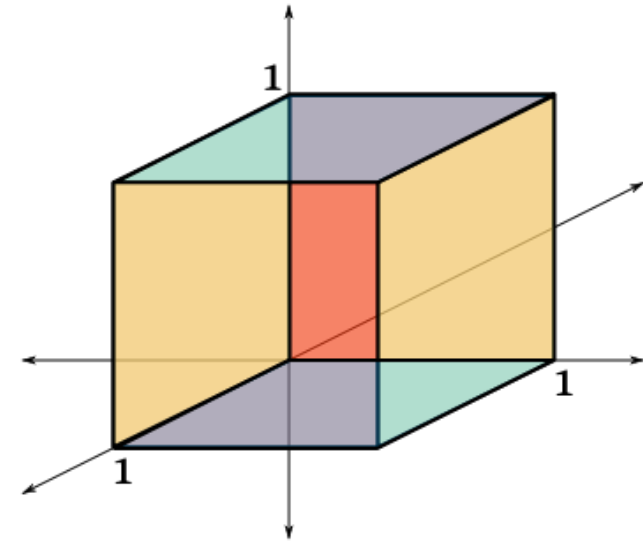
Discussion from Complexity Theory



- **1972, Klee-Minty cube**

Simplex Method is NP-hard
(non-deterministic polynomial-time)

- **1979, Khachain** designed **Ellipsoid Method**,
which is proved that LP could be solved in polynomial time.

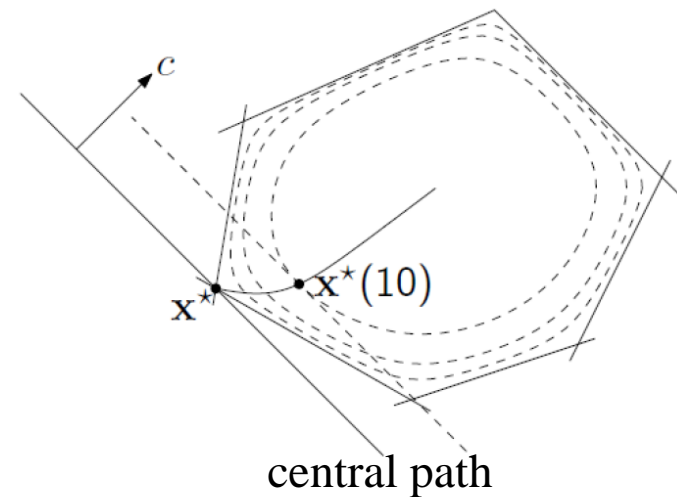
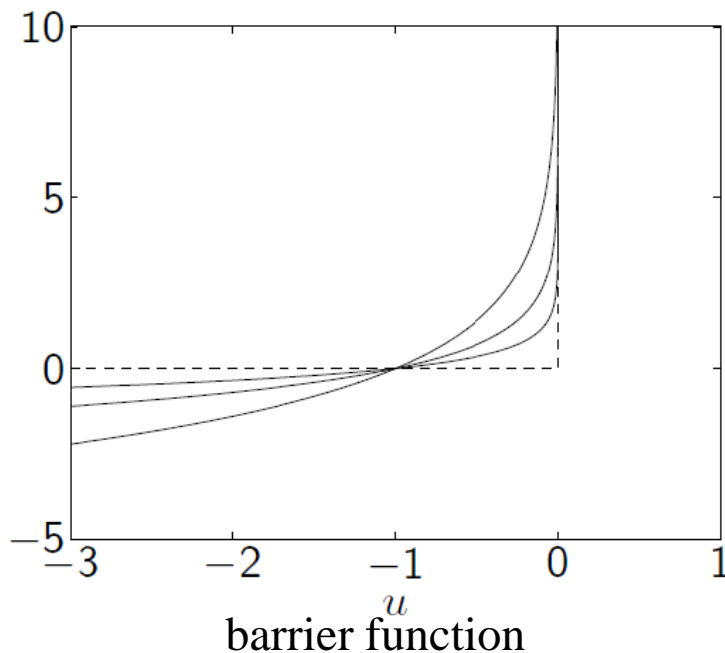


- Simplex method has **high complexity**, but is **quite efficient** in practice
Ellipsoid method has low complexity, but is not efficient in practice

Interior-point-method



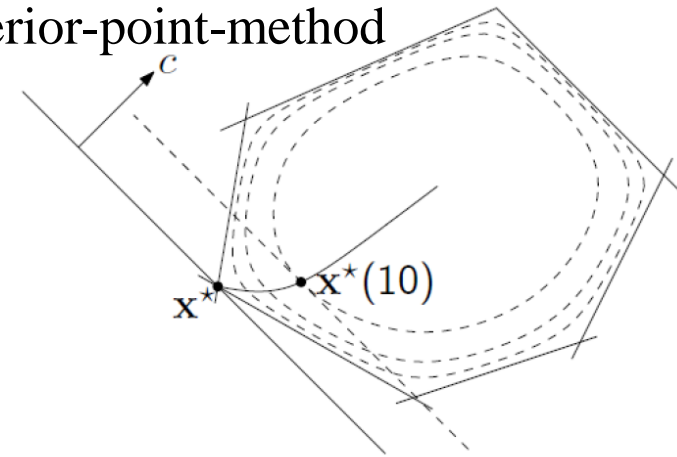
- 1984, Karmarkar designed interior-point-method
 - von Neumann 1940s
 - low complexity & efficient



Interior-point-method for Convex Optimization

- Polynomial property seems less important in interior-point-method

- 1994, **Nemirovski** and **Nesterov** gave the interior-point-method for **Convex Optimization**



- Convex Optimization:
minimize a **convex function**
over a **convex set**



Convex Optimization



“convex optimization is an important enough topic that everyone who uses computational mathematics should know at least a little bit about it is a natural next topic after advanced linear algebra, and linear programming.”

—— S. Boyd and L. Vandenberghe

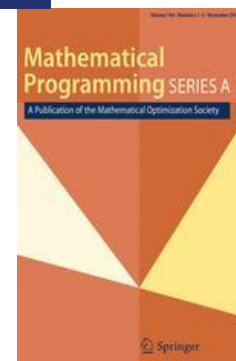


Trend in Optimization



From convex to non-convex problems; Towards large scale; Towards applications

- Convergence analysis: condition, speed, acceleration
- Parallel computing
- Stochastic optimization
- Robust optimization
- Discrete optimization
- Intelligent optimization



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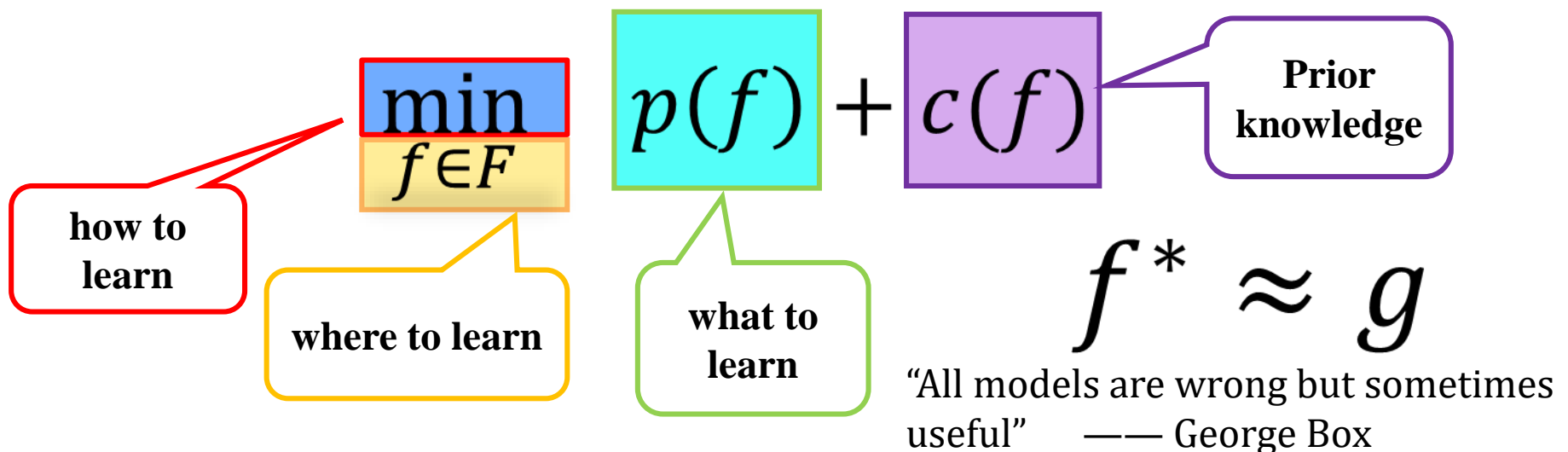
Course Information



Basic Learning Framework



- *“Machine learning is at the core of artificial intelligence and data science.”*
—— Michael I. Jordan
- Machine learning is to establish f from data generated by unknown g
- $f(x)$ and $g(x)$ could be similar but the structures of f and g generally are totally different

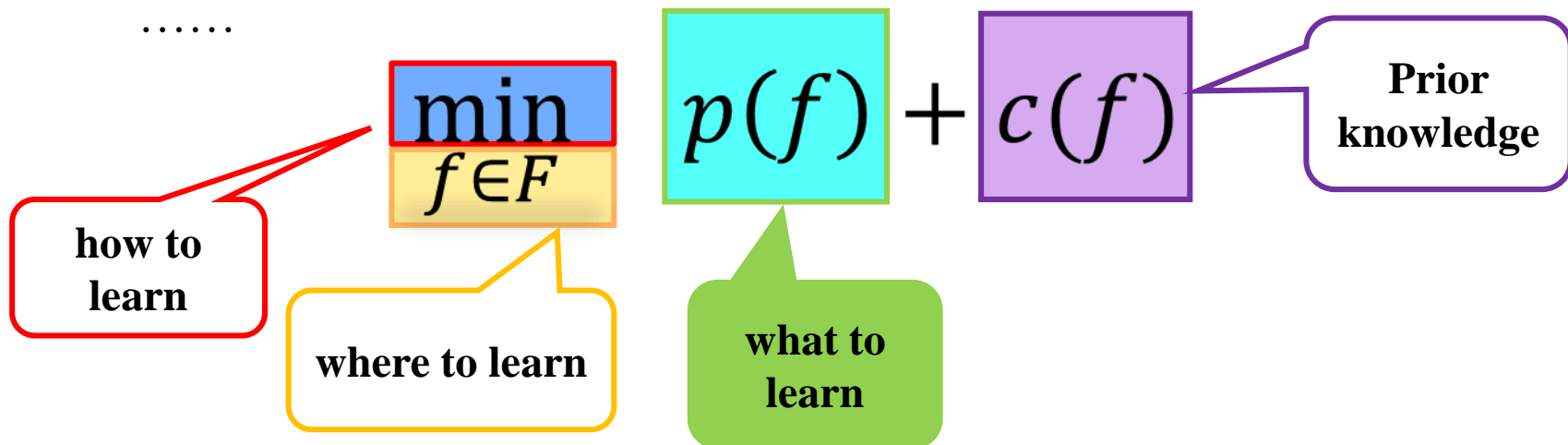


Loss Function



- Regression
- Classification
- Clustering
- Dimension reduction

.....

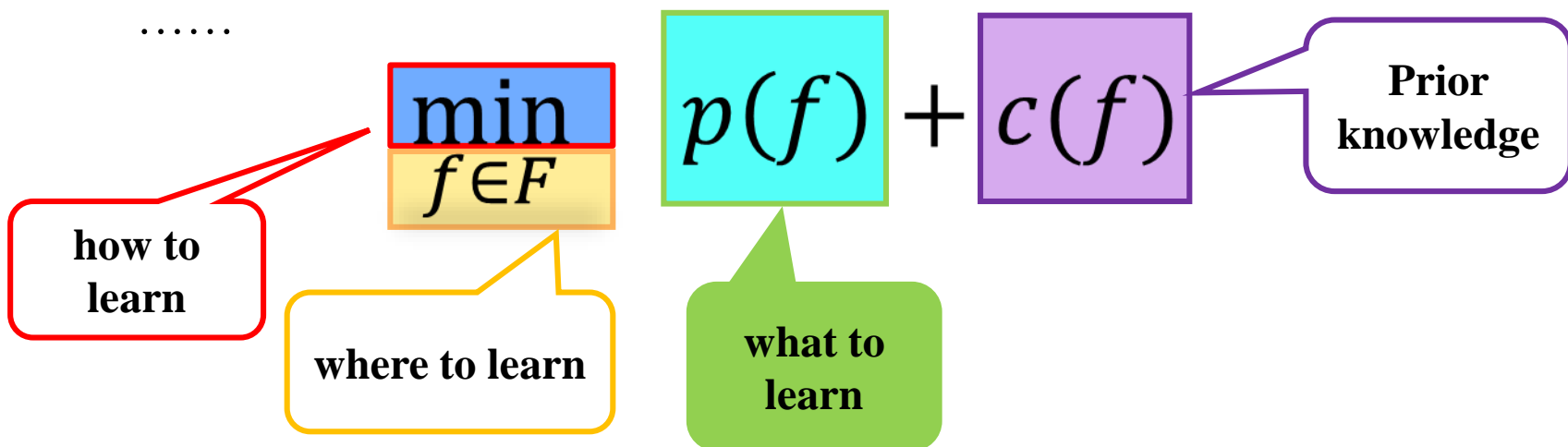
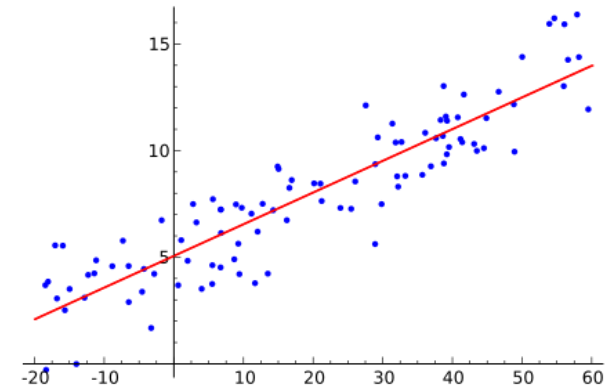


Loss Function

- Regression
- Classification
- Clustering
- Dimension reduction

$$\sum_i (f(x_i) - y_i)^2$$

- other requirements?
- why squares?
- why sum?

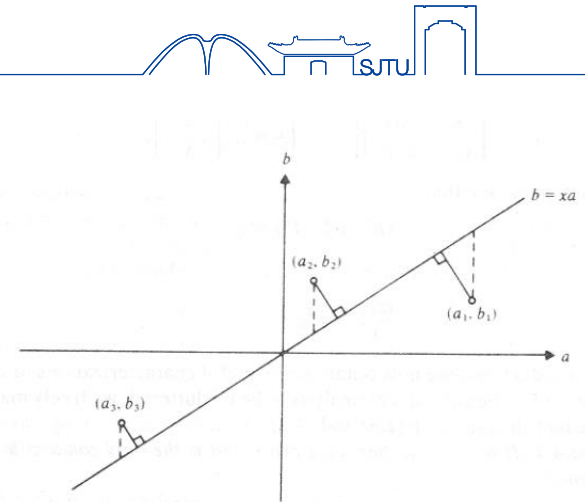


Loss Function

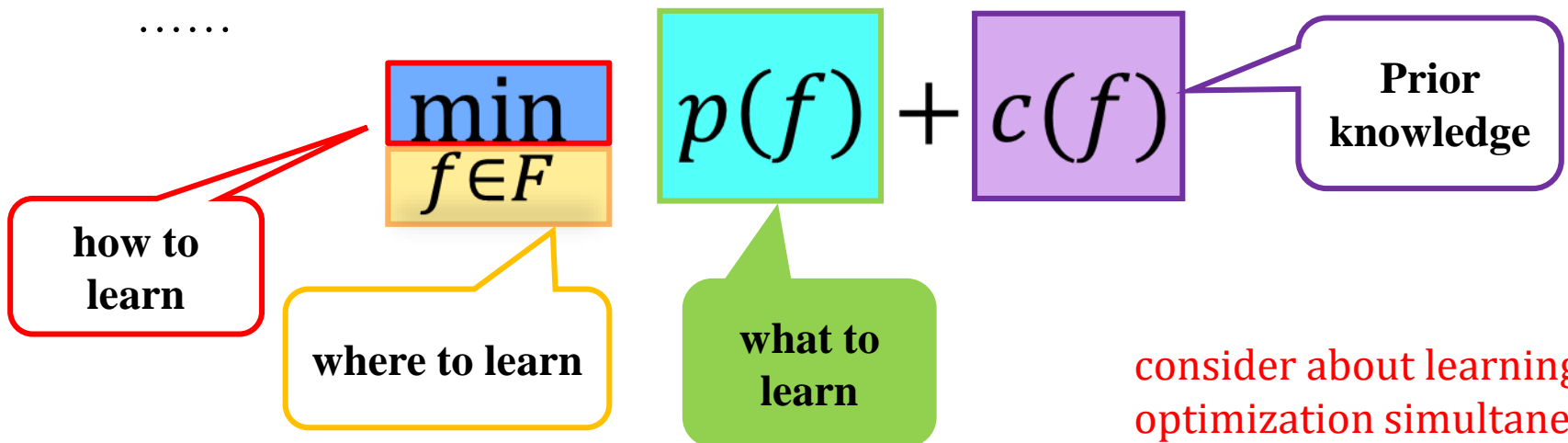
- Regression
- Classification
- Clustering
- Dimension reduction

$$\sum_i (f(x_i) - y_i)^2$$

- other requirements?
- why squares?
- why sum?



.....



Loss Function



▪ Regression

▪ **Classification**

▪ Clustering

▪ Dimension reduction

$$\sum_i I(f(x_i) \neq y_i)$$

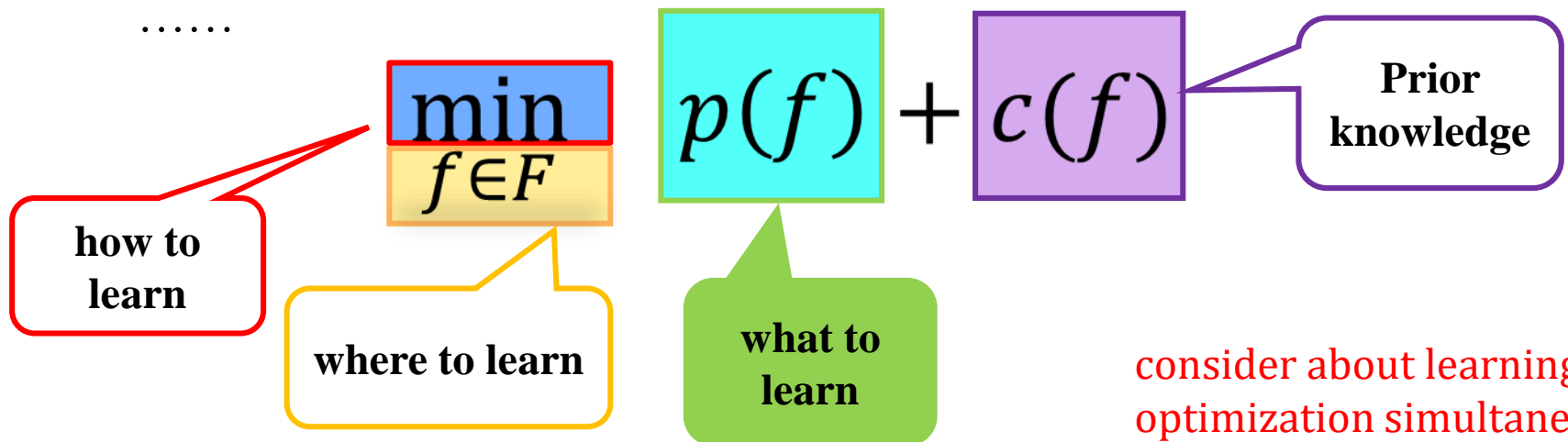
- misclassification loss
- however discontinues

$$\sum_i \max\{0, 1 - y_i f(x_i)\}$$

- hinge loss

- quadratic cost
- cross-entropy
- softmax (log-likelihood)

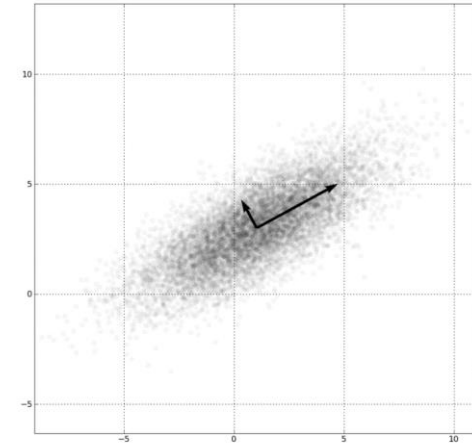
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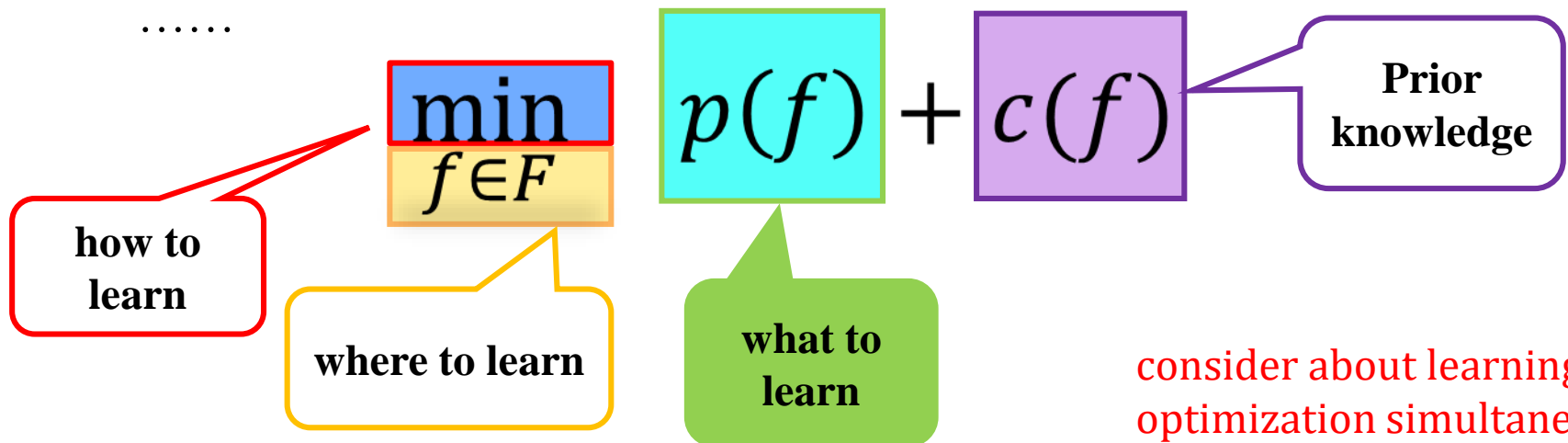
Loss Function

- Regression
- Classification
- Clustering
- **Dimension reduction**

Project data in to one direction
 $w^T x$
 to reserve information



.....



consider about learning and optimization simultaneously

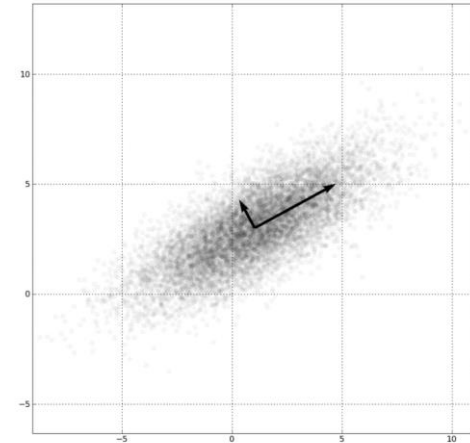
Loss Function

- Regression
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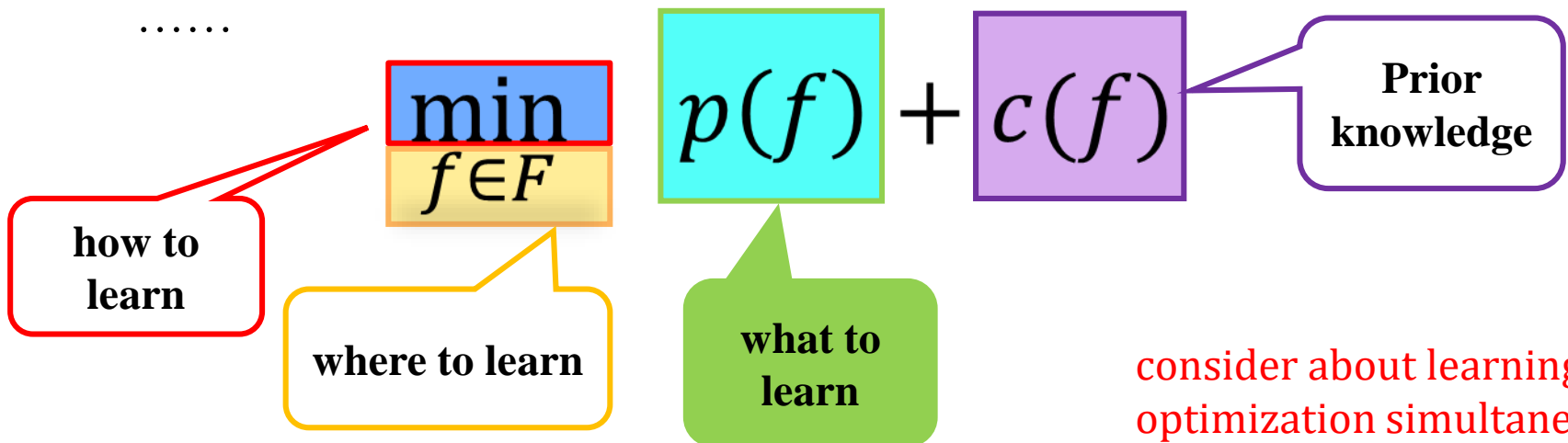
Project data in to one direction
 $w^T x$
 to reserve information

maximize the covariance of
 the (centralized) projected data

$$-w^T X^T X w$$



.....



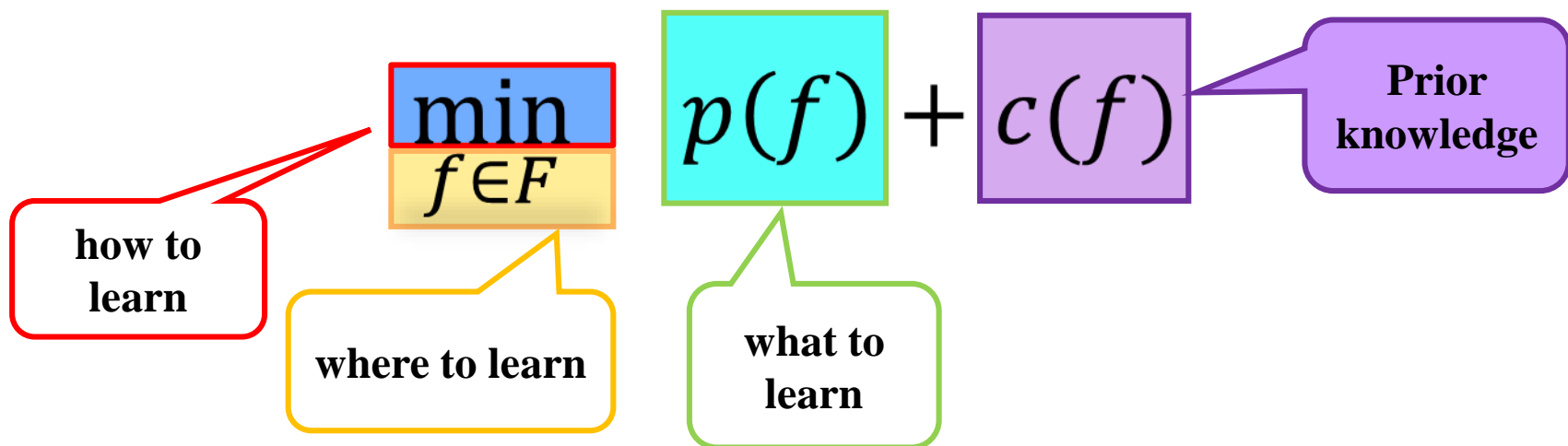
Regularization Term



- the minimizer of empirical loss (loss on the training data) is not necessarily optimal to expected loss (loss on the unknown distribution/new data)

$$R_{\rho}(f) \leq R_{\text{empirical}}(f) + R_{\text{structural}}(f)$$

- this general inequality implies the importance of complexity control



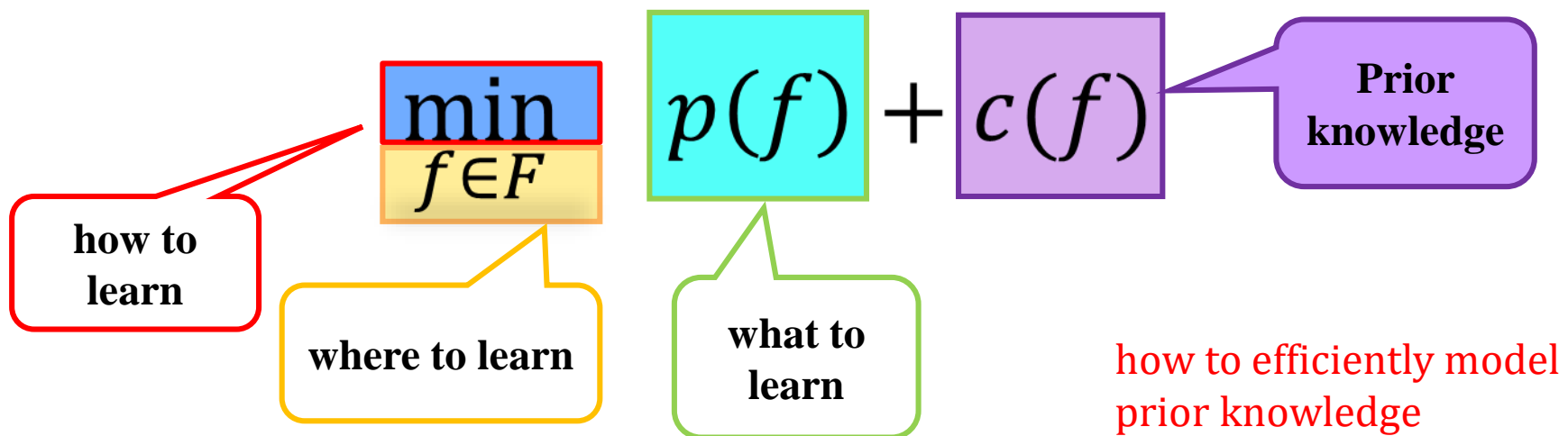
Regularization Term



- we want to decompose foreground and background,



X. Liu et al. "Background Subtraction Based on Low-Rank and Structured Sparse Decomposition", IEEE-TIP 2015

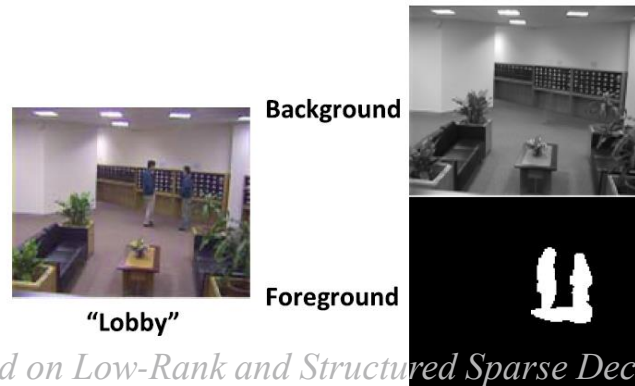


Regularization Term



- we want to decompose foreground and background,

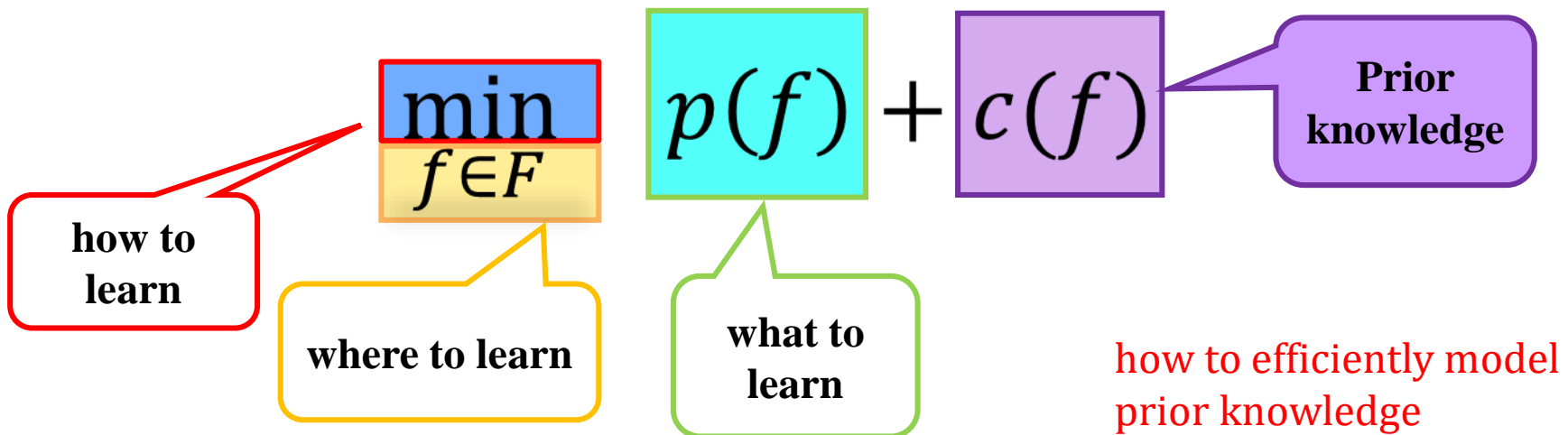
$$\min_{F, B} \|H - (F + B)\|_2 + \lambda \|F\|_1 + \gamma \|B\|_*$$



Background is **low-rank**

Foreground is **sparse**

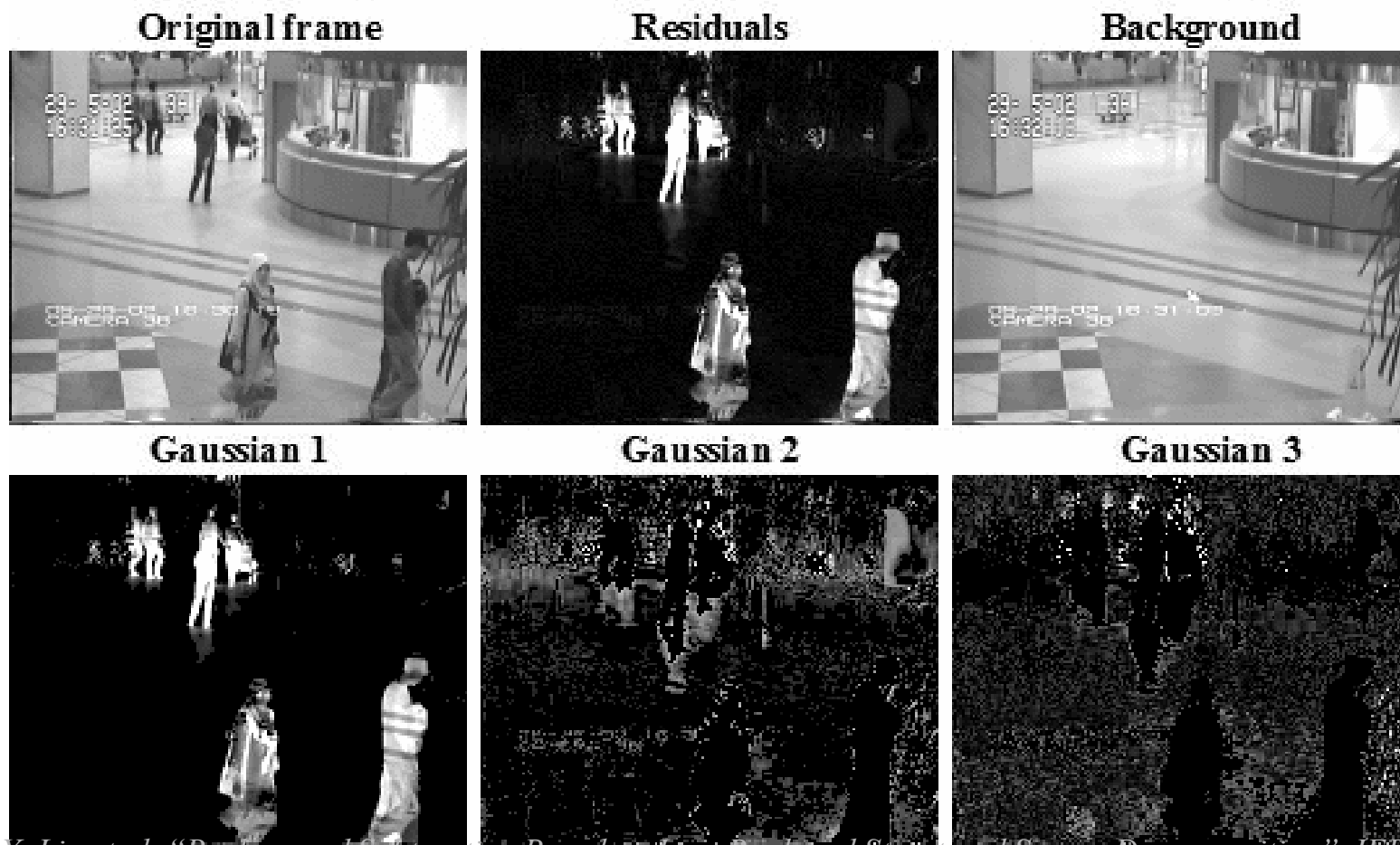
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Regularization Term

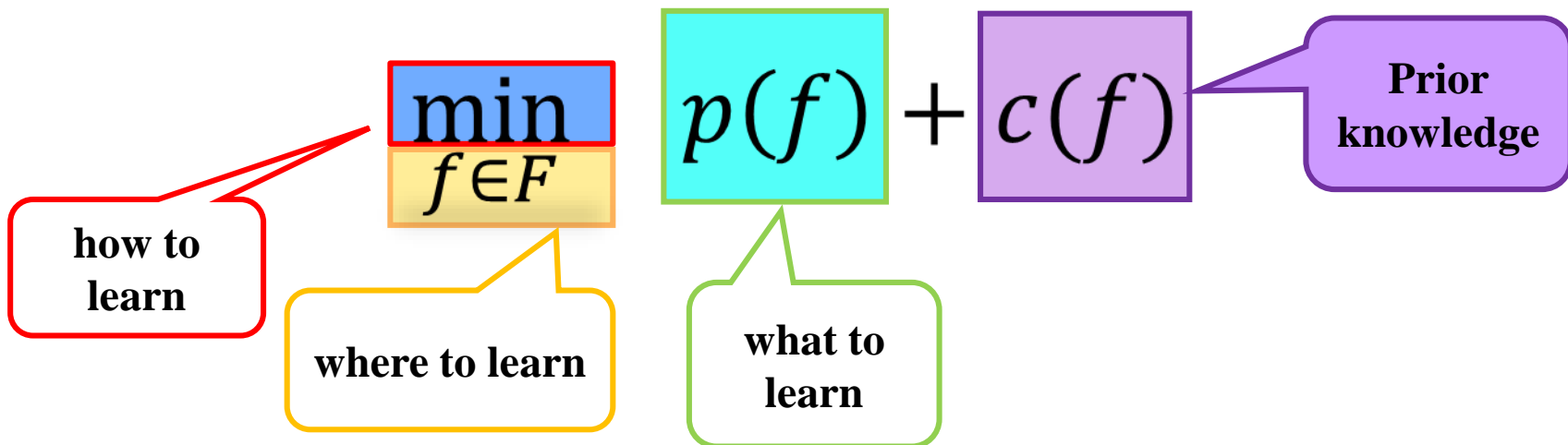
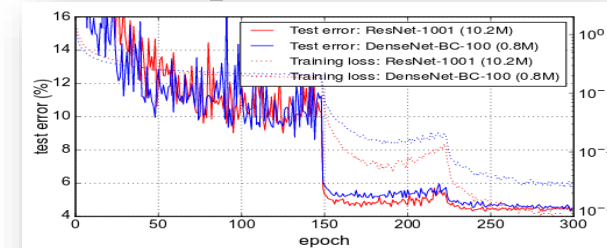
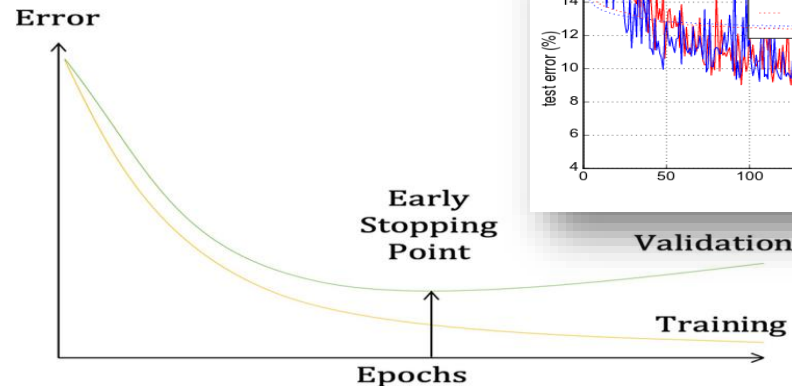


- we want to decompose foreground and background,



Regularization Term

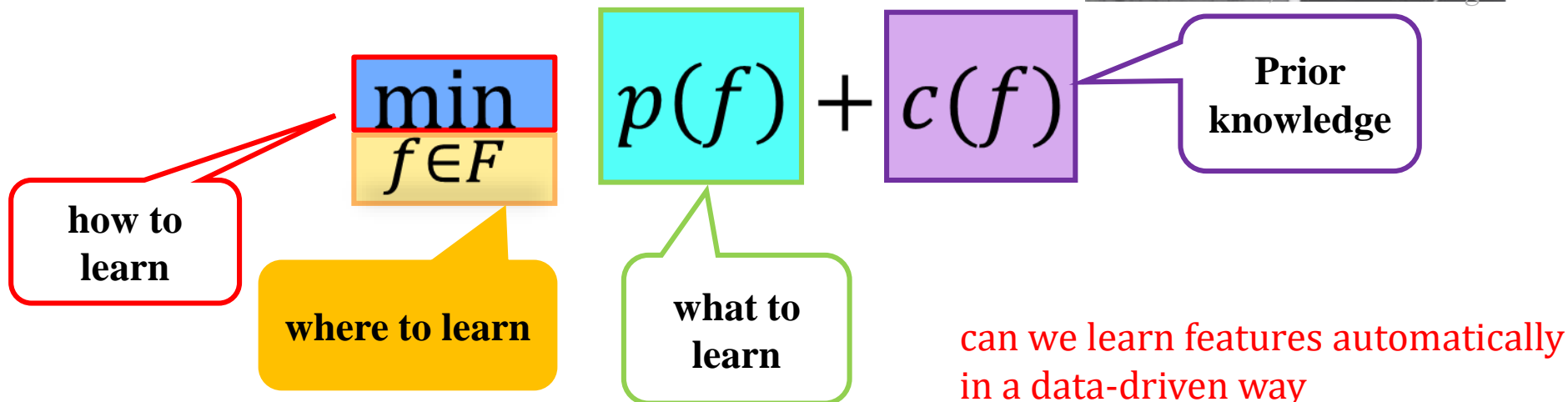
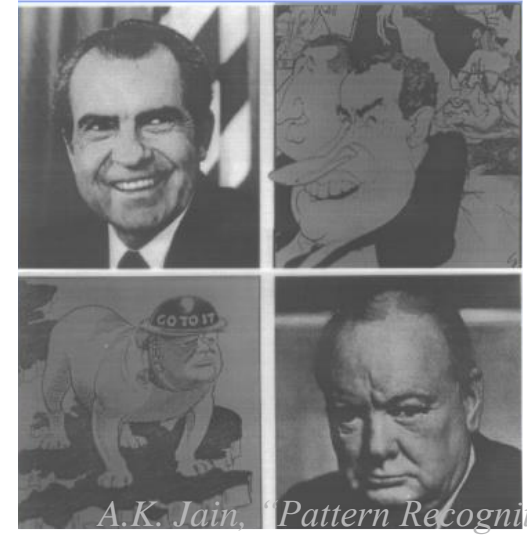
- The essence of regularization term is to control the functional space
 - Transfer learning
 - Manifold constraint
 - Early Stop
 - **Overparametrization**



Functional Space



- Functional space becomes more and more complex :
 - linear model $f(x) = w^T x + b$
 - basis function $f(x) = w^T \phi(x) + b$
 - kernel method
 - neural networks



Functional Space



- Convolution operator:



$$\ast \frac{1}{8} \begin{bmatrix} 0 & 1 & 0 \\ 1 & 4 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$



$$\ast \begin{bmatrix} 0 & -1 & 0 \\ -1 & 4 & -1 \\ 0 & -1 & 0 \end{bmatrix}$$



PARRSLAB "Convolutional Neural Networks"

$$\min_{f \in F}$$

how to learn

where to learn

$$p(f)$$

what to learn

$$+$$

$$c(f)$$

Prior knowledge

can we learn features automatically in a data-driven way

Functional Space



- Convolution operator:



$$\ast \frac{1}{8} \begin{bmatrix} 0 & 1 & 0 \\ 1 & 4 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$



$$\ast \begin{bmatrix} 0 & -1 & 0 \\ -1 & 4 & -1 \\ 0 & -1 & 0 \end{bmatrix}$$



$$\ast \begin{bmatrix} 1 & 0 & -1 \\ 2 & 0 & -2 \\ 1 & 0 & -1 \end{bmatrix}$$

PARRSLAB "Convolutional Neural Networks"

can you image the result?

$$\min_{f \in F}$$

how to learn

where to learn

$$p(f)$$

what to learn

$$+$$

$$c(f)$$

Prior knowledge

can we learn features automatically in a data-driven way

Functional Space



- Convolution operator:



$$\ast \frac{1}{8} \begin{bmatrix} 0 & 1 & 0 \\ 1 & 4 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$



$$\ast \begin{bmatrix} 0 & -1 & 0 \\ -1 & 4 & -1 \\ 0 & -1 & 0 \end{bmatrix}$$



why it should be 2? How about 1.99 and 2.01



*

$$\begin{bmatrix} 1 & 0 & -1 \\ 2 & 0 & -2 \\ 1 & 0 & -1 \end{bmatrix}$$



can you image the result?

PARRSLAB "Convolutional Neural Networks"

$$\min_{f \in F}$$

how to learn

where to learn

$$p(f)$$

what to learn

$$+$$

$$c(f)$$

Prior knowledge

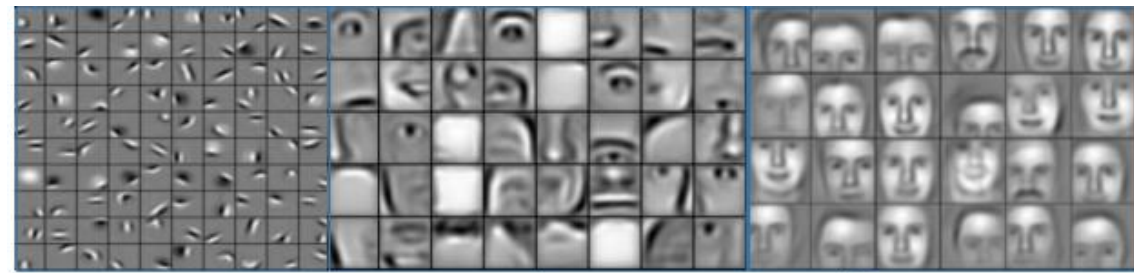
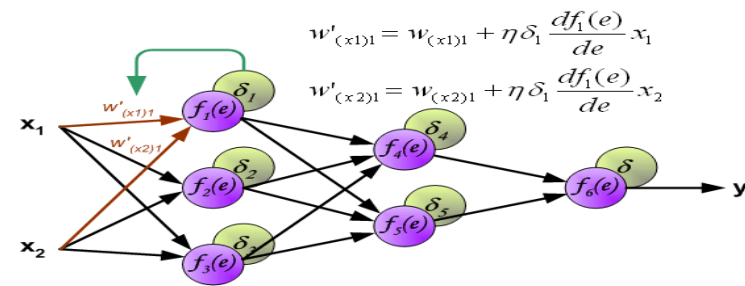
can we learn features automatically in a data-driven way

Functional Space

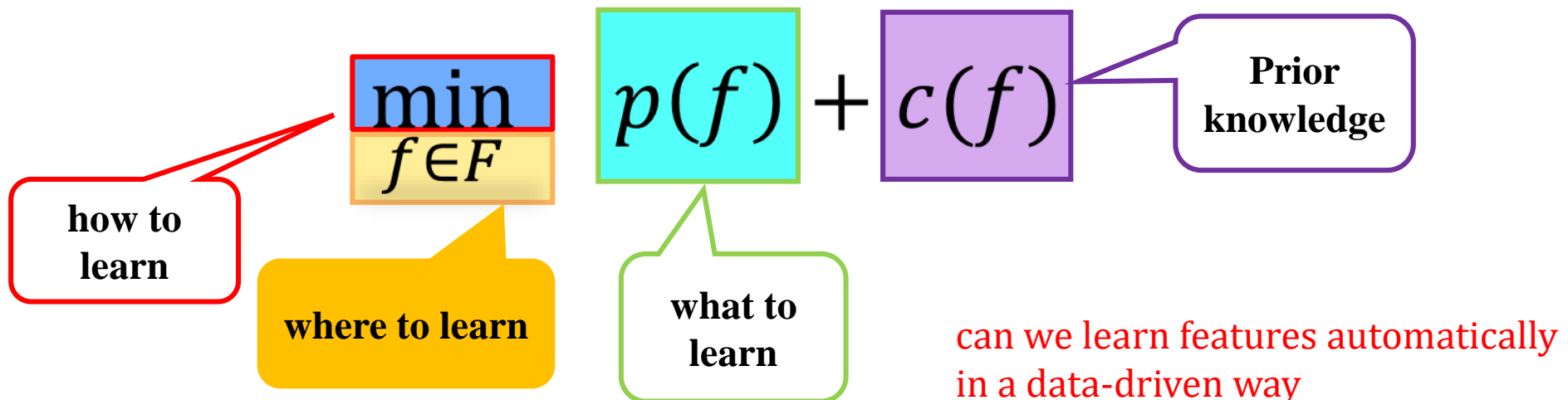


- by backpropagation, we can optimize the parameters and learn features

<http://www.rsipvision.com/exploring-deep-learning/>



hidden layer 1 hidden layer 2 hidden layer 3

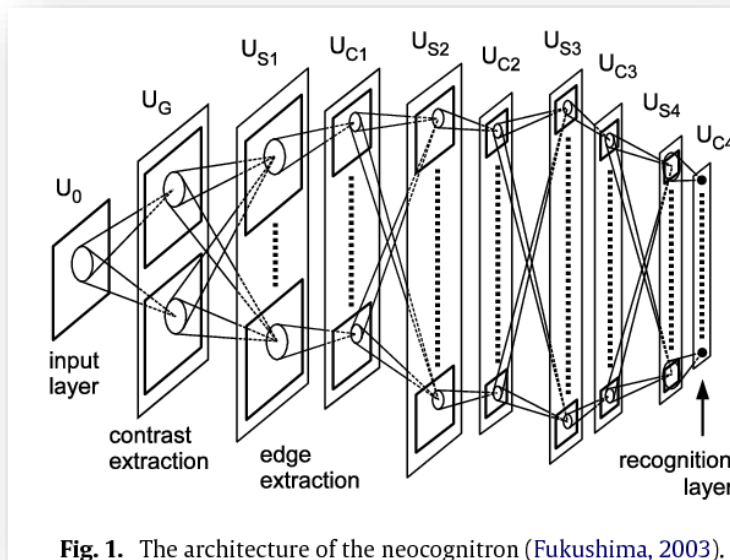
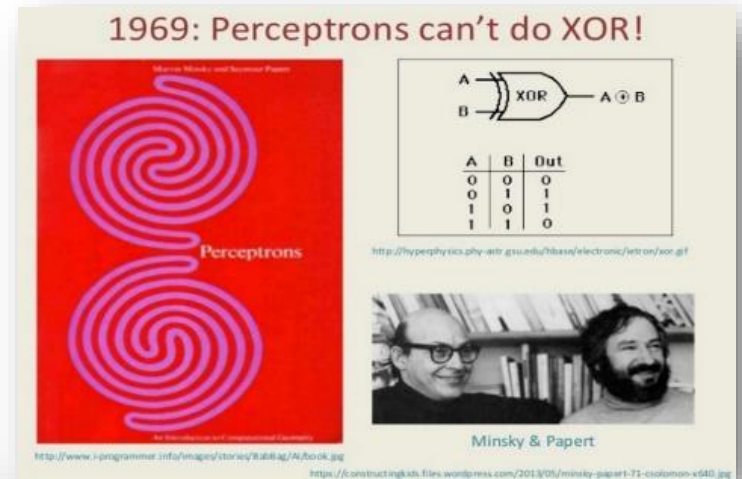


Optimization



Recall the development of neural networks

- 1950's Perceptrons
- 1980's CNN, RNN (original)



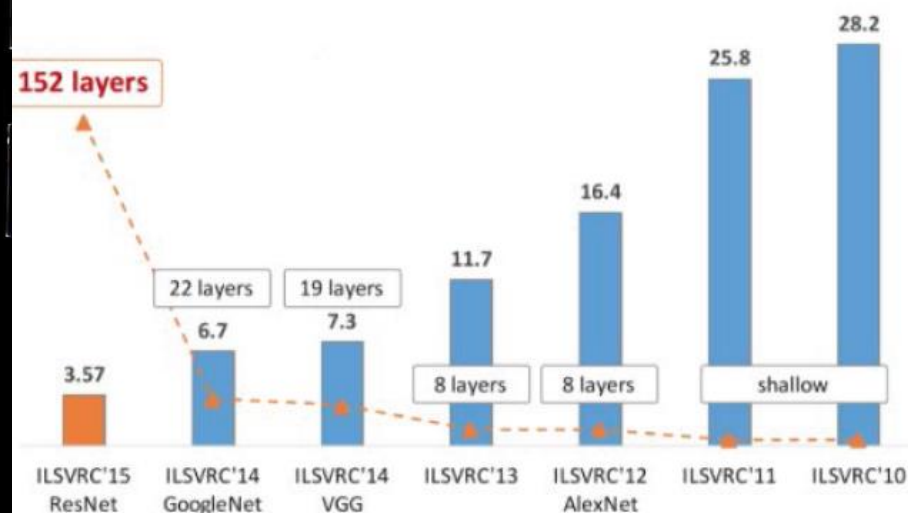
Kunihiro Fukushima
福島 邦彦

Optimization



Recall the development of neural networks

- 1950's Perceptrons
- 1980's CNN, RNN
- 2005- Deep Neural Networks



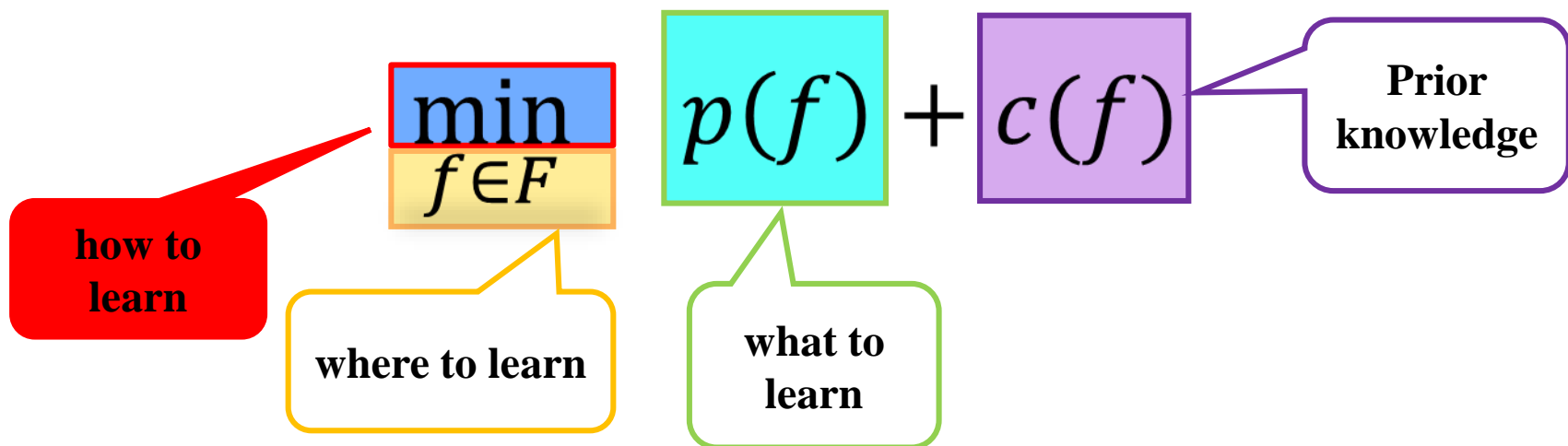
Optimization



Recall the development of neural networks

- 1950's Perceptrons
- 1980's CNN, RNN
- **2005- Deep Neural Networks**

when we can efficiently optimize
the parameters, we can use more
and more complicated models

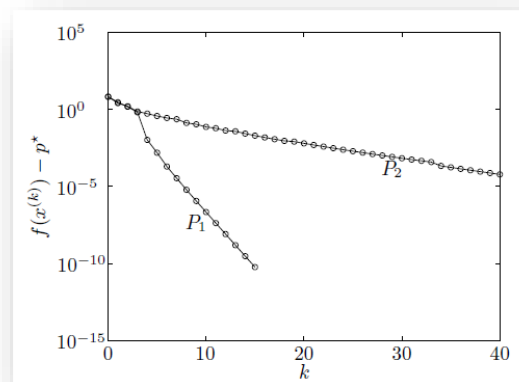


Optimization in Machine Learning



For the same problem, the difference between different algorithms could be vast.

- Solving accuracy
- Computational time
- Different operations
 - GPU
 - CPU
 - vector-friend
 - matrix/tensor-friend



S. Boyd and L. Vandenberghe,
Convex Optimization

TABLE I
AVERAGE COMPUTATIONAL TIME WITH DIFFERENT M , N WHEN
 $K = 100$, $s_n = 10$, $s = 10\%$.

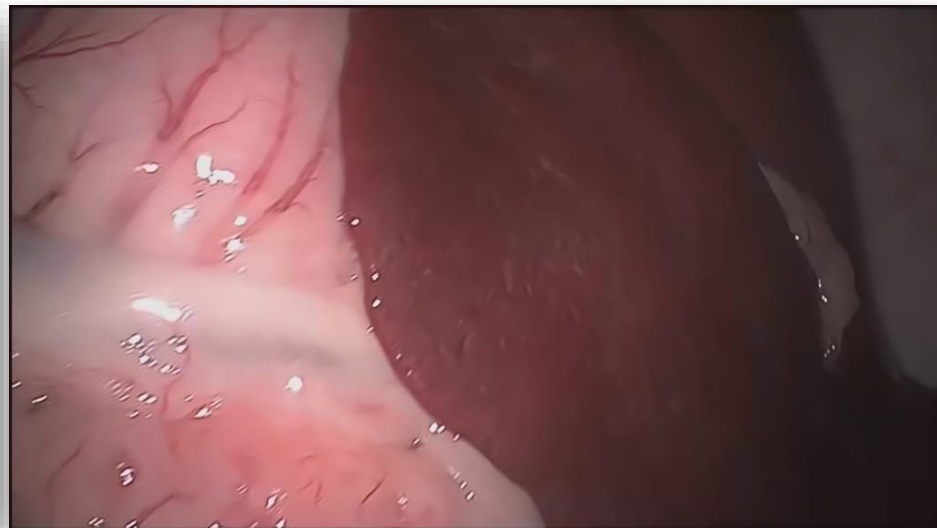
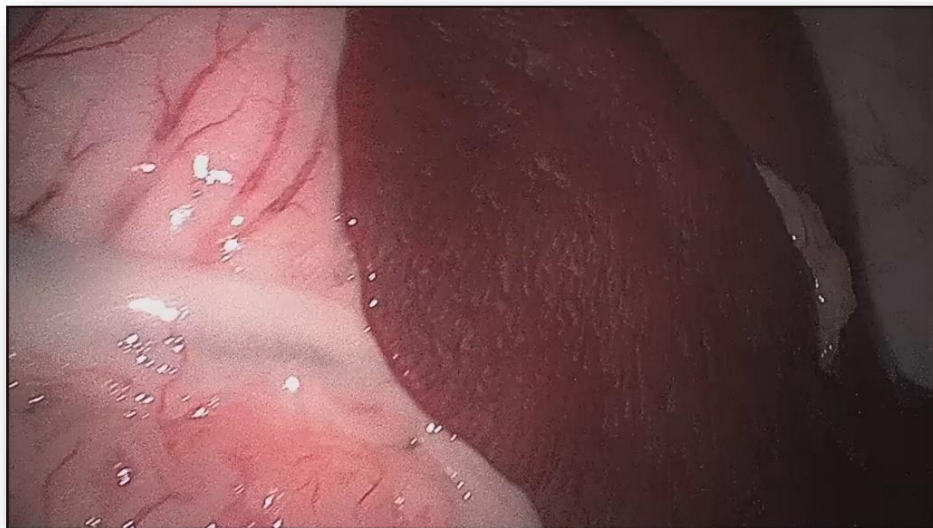
Methods	M=500 N=1000	M=1000 N=1000	M=500 N=2000	M=1000 N=2000	M=1500 N=2000
LASSO	0.0121 s	0.0436 s	0.0296 s	0.1333 s	0.1563 s
RDGS	0.9355 s	0.5129 s	8.5300 s	7.9630 s	5.5730 s
MIbit-CSC	0.9627 s	1.0500 s	8.5410 s	9.2600 s	8.7560 s
Alg.1-sL1	0.0929 s	0.1340 s	0.3713 s	0.5177 s	0.7089 s
Alg.1-MCP	0.1306 s	0.1663 s	0.5907 s	0.7127 s	0.7265 s
Alg.1-L0	0.1073 s	0.1430 s	0.5604 s	0.6758 s	0.6958 s
Alg.1-L1	0.1004 s	0.1375 s	0.5548 s	0.6671 s	0.6854 s

F. He, X. Huang, Y. Ming, Fast Signal
Recovery from Saturated Measurements

Optimization in Machine Learning



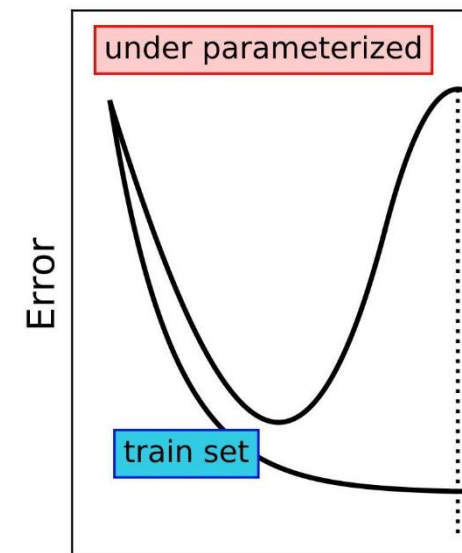
- Accuracy requirement is **not** very high, especially for **large-scale problem**
 - modeling has error, e.g., image quality evaluation itself is a challenging problem



Optimization in Machine Learning



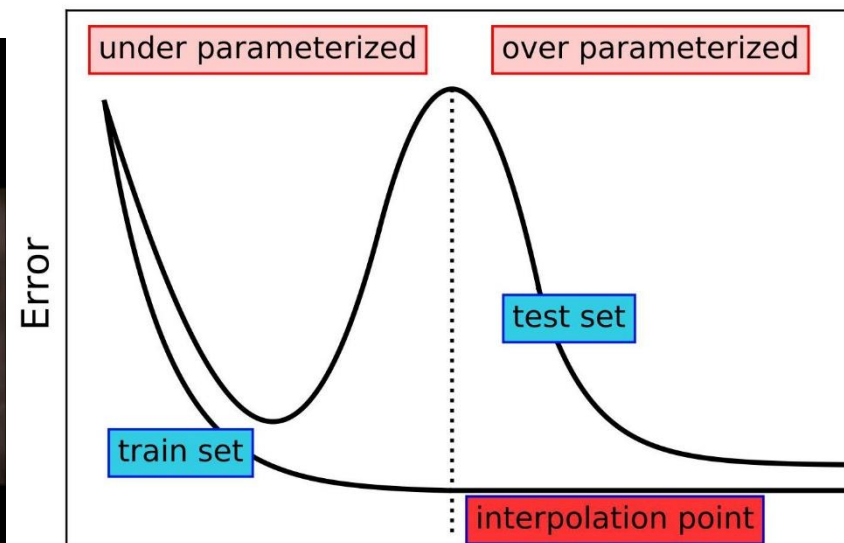
- Accuracy requirement is **not** very high, especially for **large-scale problem**
 - modeling has error, e.g., image quality evaluation itself is a challenging problem
 - there is gap between training and test



Optimization in Machine Learning



- Accuracy requirement is **not** very high, especially for **large-scale problem**
 - modeling has error, e.g., image quality evaluation itself is a challenging problem
 - there is gap between training and test
 - in other topics, e.g., scheduling, signal processing, accuracy is **very important**



Optimization in Machine Learning



- Accuracy requirement is **not**

- modeling has error, e.g., in
- there is gap between training and testing
- in other topics, e.g., scheduling

Problem Scale	Operations
small size	any, e.g., Hessian matrix
medium size	inverse A^{-1}
large size	multiplication Ax
huge size	addition $x + y$

n

— Yurri Nesterov

- Scale could be **very large**

$$\min_x \sum_{i=1}^m (f(x_i) - y_i)^2$$

- Objective function usually could be **decomposed** in some way
- Objective function is usually **non-convex**



- Many things need to consider when put into **practical application**

1

What is Optimization

2

History of Optimization

3

Optimization in Machine Learning

4

Course Information



Course Information



- Lecturer
 - Xiaolin Huang, Department of Automation, SEIEE
 - xiaolinhuang@sjtu.edu.cn www.pami.sjtu.edu.cn
- TAs: Kaijie Wang, kaijie_wang@sjtu.edu.cn
Yingwen Wu, yingwen_wu@sjtu.edu.cn
- Text Book:

Stephen Boyd, Lieven Vandenbergh :

Convex Optimization

Cambridge (free download)

王书宁, 许鋈, 黄晓霖 [译] 凸优化 清华大学出版社 2013



Course Information



- Full score: 100

class performance/quiz (20) + homework (30) + project (10) + examination (40)

- Schedule (planed)

1. **Tutorial** (2)
2. **Convex Set** (3) **Convex Function** (3) **Convex Optimization** (4) **Convex Machine Learning Models** (4)
3. **Solving Algorithm for Non-constrained Problems** (6) **Large-scale Algorithm I** (6) **Nonconvex Models** (4)
4. **Duality** (6) **Large-scale Algorithm II** (6)
5. **Report Presentation** (2) **Outlook and Conclusion** (2)

THANKS

