



LEC007 Inventory Management II

VG441 SS2020

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Wagner-Whitin Model

INPUT:

- Deterministic demand (non-stationary) over T periods
 $(d_1, d_2, d_3, \dots, d_{T-1}, d_T)$ 
- No stockout is allowed
- Lead time L (setting $L = 0$ WLOG) 
- Fixed cost $K > 0$ per order
- Purchase cost c per unit (setting $c = 0$ WLOG)
- Inventory hold cost $h > 0$ per unit per unit of time

OUTPUT:

The optimal ordering strategy

Mixed Integer Linear Program (MILP)

Decision Variables

- q_t = the number of units ordered in period
- $y_t = 1$ if we order in period t , 0 otherwise
- x_t = the inventory level at the end of period, with $x_0 \equiv 0$

Math. Program
 1. Decision Variables
 2. Objective
 3. Constraints
 ≡ 0

$q_t \leq M y_t$, if $y_t = 1$ (order)
 $q_t \leq 0$, if $y_t = 0$ (do not order)
 (a common trick)

Inventory-balance constraint

$$\begin{aligned}
 &\text{minimize} && \sum_{t=1}^T (\underline{K} y_t + \underline{h} x_t) \\
 &\text{subject to} && x_t = x_{t-1} + q_t - d_t \quad \forall t = 1, \dots, T \\
 & && q_t \leq \underline{M} y_t \quad \forall t = 1, \dots, T \\
 & && x_t \geq 0 \quad \forall t = 1, \dots, T \\
 & && q_t \geq 0 \quad \forall t = 1, \dots, T \\
 & && y_t \in \{0, 1\} \quad \forall t = 1, \dots, T
 \end{aligned}$$

Linking constraint
 ("a common trick")

ZIO Property

- It is optimal to place orders only in time periods in which the inventory level is zero.
- This suggests that each order is of a size equal to the total demand in an integer number of subsequent periods, i.e., in period t , we either order d_t ,
or $d_t + d_{t+1}$,
or $d_t + d_{t+1} + d_{t+2}$,
and so on.

Dynamic Programming

- Define θ_t to be the optimal cost in periods $[t, T]$ if we place optimal orders over $[t, T]$.

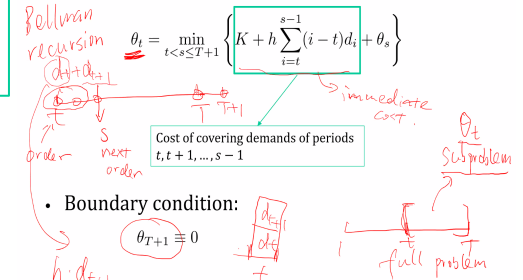
$$\theta_t = \min_{t < s \leq T+1} \left\{ K + h \sum_{i=t}^{s-1} (i - t) d_i + \theta_s \right\}$$

Cost of covering demands of periods $t, t + 1, \dots, s - 1$

- Boundary condition:

$$\theta_{T+1} \equiv 0$$

- Define θ_t to be the optimal cost in periods $[t, T]$ if we place optimal orders over $[t, T]$.



Dynamic Programming

- Backward induction

$$\theta_t = \min_{t < s \leq T+1} \left\{ K + h \sum_{i=t}^{s-1} (i - t) d_i + \theta_s \right\}. \quad (3.39)$$

Algorithm 3.1 Wagner–Whitin algorithm

1: $\theta_{T+1} \leftarrow 0$	▷ Initialization
2: for $t = T, \dots, 1$ do	▷ Main loop
3: $\theta_t \leftarrow$ right-hand side of (3.39)	▷ Minimization over s
4: $s(t) \leftarrow$ argmin in right-hand side of (3.39)	
5: end for	
6: return $\theta_t, s(t)$ for all $t = 1, \dots, T$	

Numerical Example

$K = 500, h = 2$ per period. The demands are 90, 120, 80, and 70.

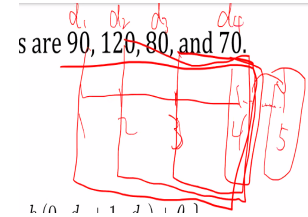
$$\theta_5 = 0$$

$$\begin{aligned}\theta_4 &= K + h(0 \cdot d_4) + \theta_5 \\ &= 500 \quad [s(4) = 5]\end{aligned}$$

$$\begin{aligned}\theta_3 &= \min \{K + h(0 \cdot d_3) + \theta_4, K + h(0 \cdot d_3 + 1 \cdot d_4) + \theta_5\} \\ &= \min\{1000, 640\} \\ &= 640 \quad [s(3) = 5]\end{aligned}$$

$$\begin{aligned}\theta_2 &= \min \{K + h(0 \cdot d_2) + \theta_3, K + h(0 \cdot d_2 + 1 \cdot d_3) + \theta_4, \\ &\quad K + h(0 \cdot d_2 + 1 \cdot d_3 + 2 \cdot d_4) + \theta_5\} \\ &= \min\{1140, 1160, 940\} \\ &= 940 \quad [s(2) = 5]\end{aligned}$$

$$\begin{aligned}\theta_1 &= \min \{K + h(0 \cdot d_1) + \theta_2, K + h(0 \cdot d_1 + 1 \cdot d_2) + \theta_3, \\ &\quad K + h(0 \cdot d_1 + 1 \cdot d_2 + 2 \cdot d_3) + \theta_4, \\ &\quad K + h(0 \cdot d_1 + 1 \cdot d_2 + 2 \cdot d_3 + 3 \cdot d_4) + \theta_5\} \\ &= \min\{1440, 1380, 1560, 1480\} \\ &= 1380 \quad [s(1) = 3]\end{aligned}$$



If you think about this...

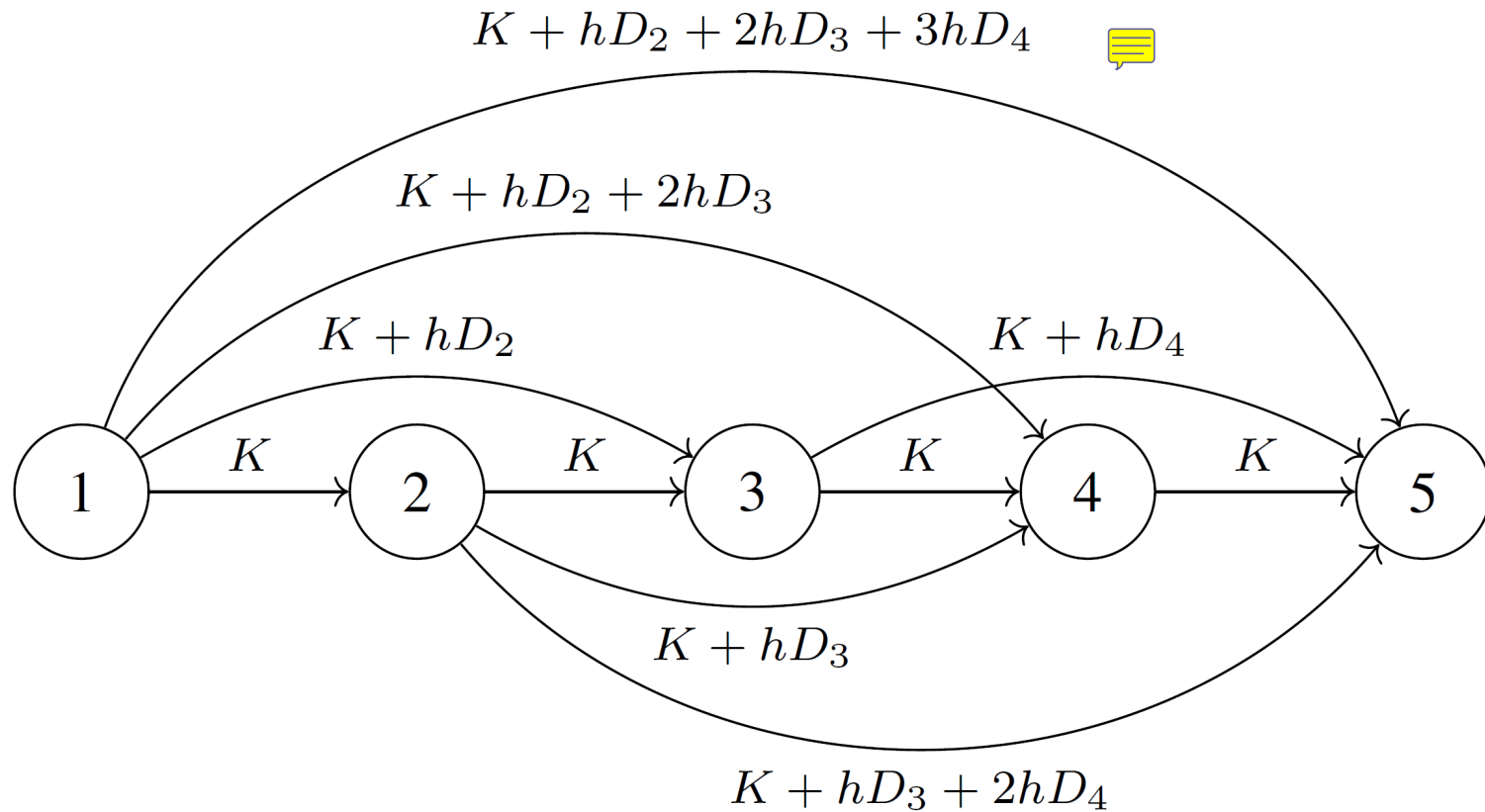


Figure 3.12 Wagner-Whitin network.

Shortest Path Problem

Input:

- Directed Graph $G(V, E)$ with $|V| = n, |E| = m$
- Each edge $e \in E$ has non-negative length $l_e \geq 0$
- Source vertex s

Output:

For each $v \in V$, compute

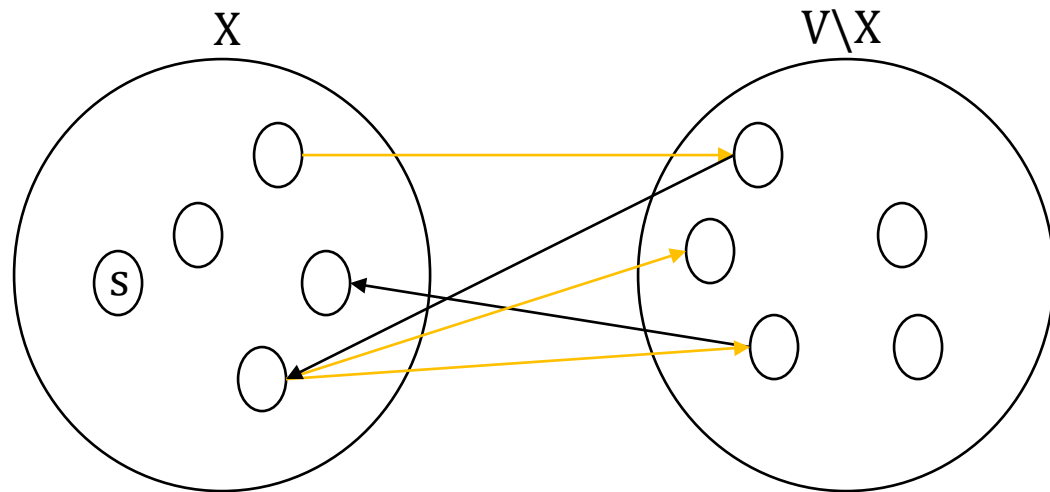
$L(v)$ = length of a shortest s - v path in G

Fastest algorithm is called **Dijkstra's Algorithm**

Caveat: length/weight/travel time $l_e \geq 0$!

Dijkstra's Algorithm

- Initialize $X = \{s\}$, $A[s] = 0$, $B[s] = \emptyset$
- Main loop
 - While $X \neq V$

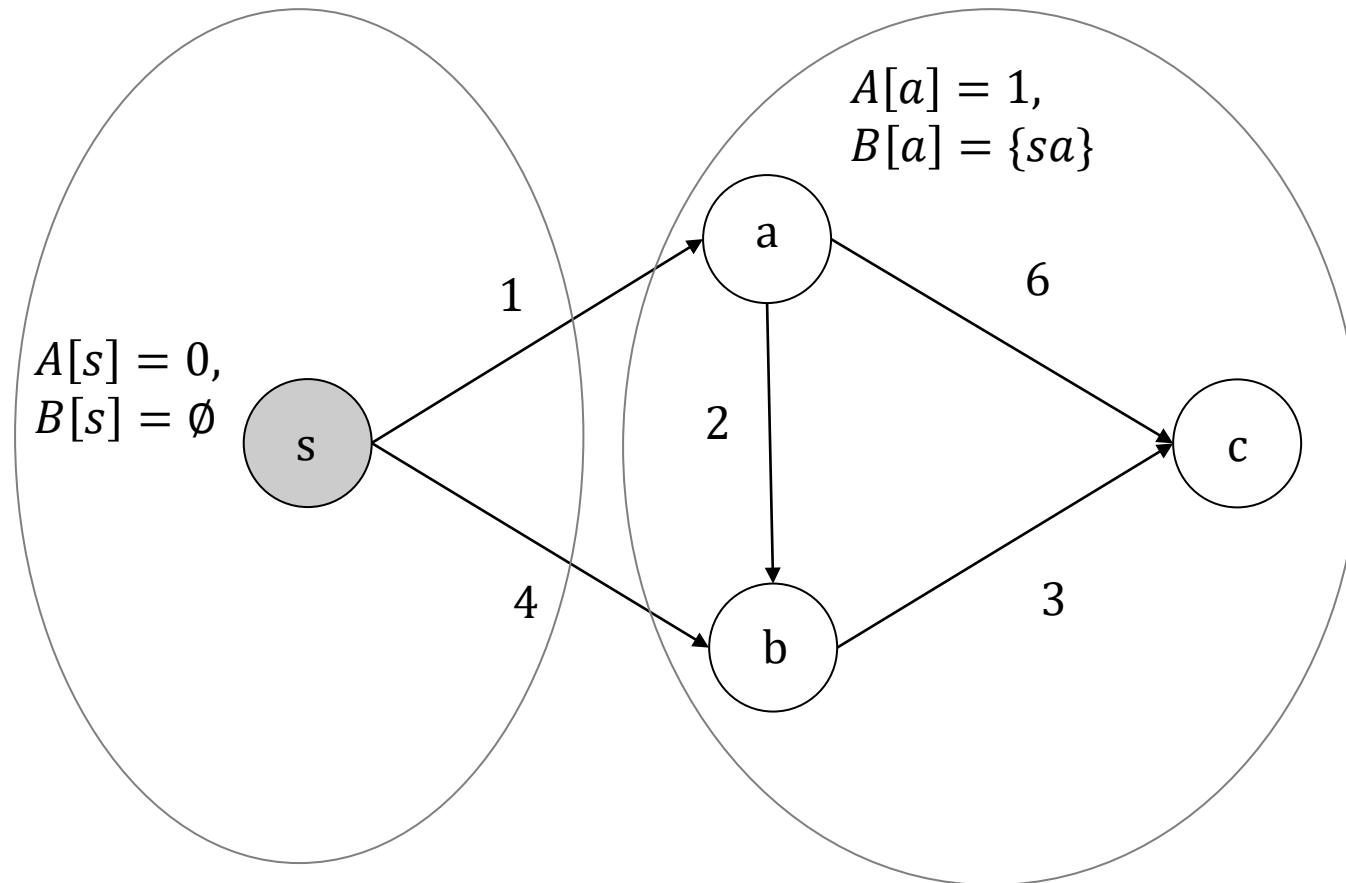


- ▶ Of all edges $(v, w) \in E$ with $v \in X$ and $w \notin X$, pick the one that minimizes $A[v] + l_{vw}$ (Dijkstra's greedy criterion)
- ▶ Call the minimizing edge (v^*, w^*) and add vertex w^* to X
- ▶ Set $A[w^*] = A[v^*] + l_{v^*w^*}$
- ▶ Set $B[w^*] = B[v^*] \cup (v^*, w^*)$

An Example

$A[v] + l_{vw}$ (Dijkstra's greedy criterion)

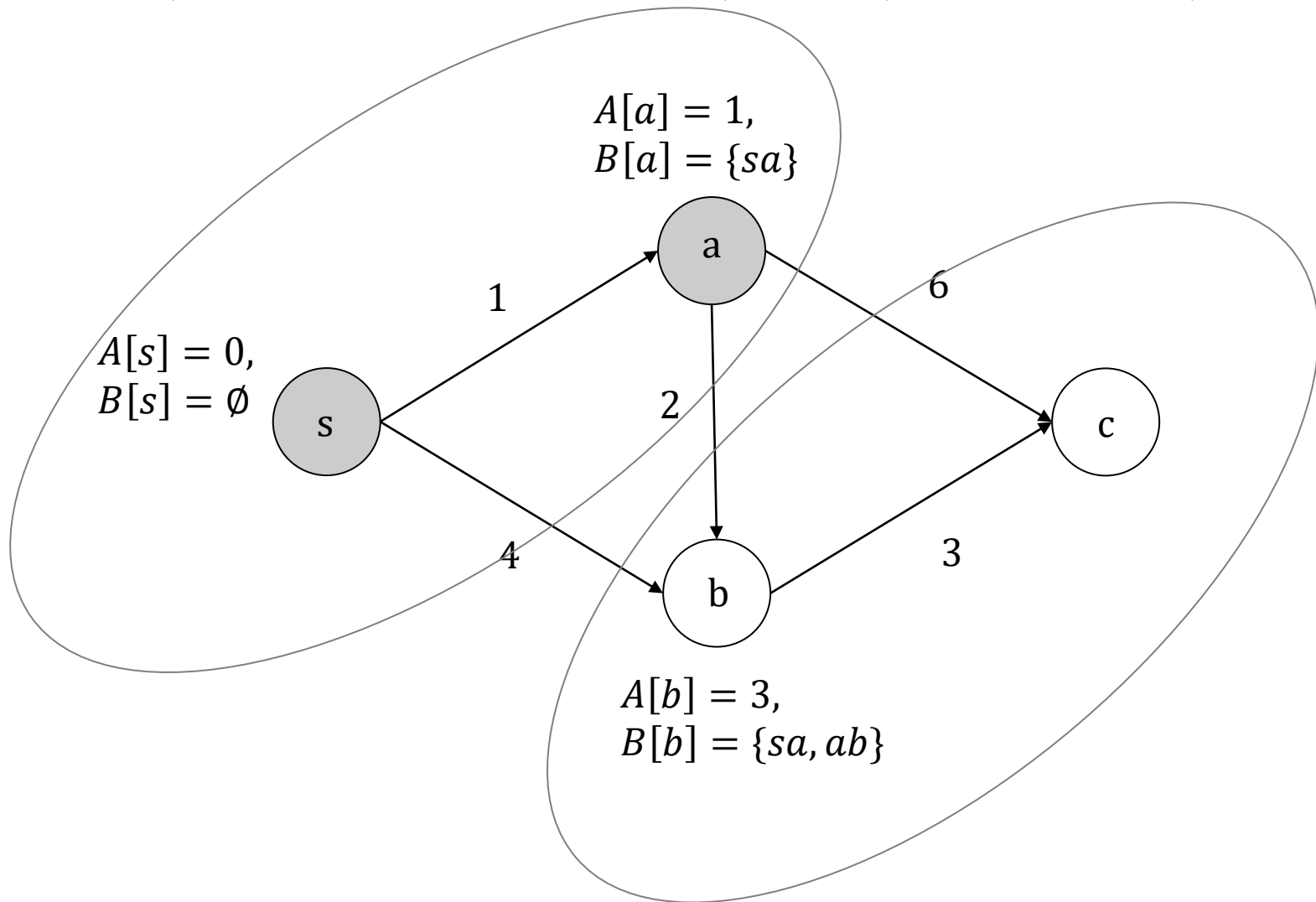
$$\min (A[s] + l_{sa}, A[s] + l_{sb}) = \min (0 + 1, 0 + 4) = 1$$



An Example

$A[v] + l_{vw}$ (Dijkstra's greedy criterion)

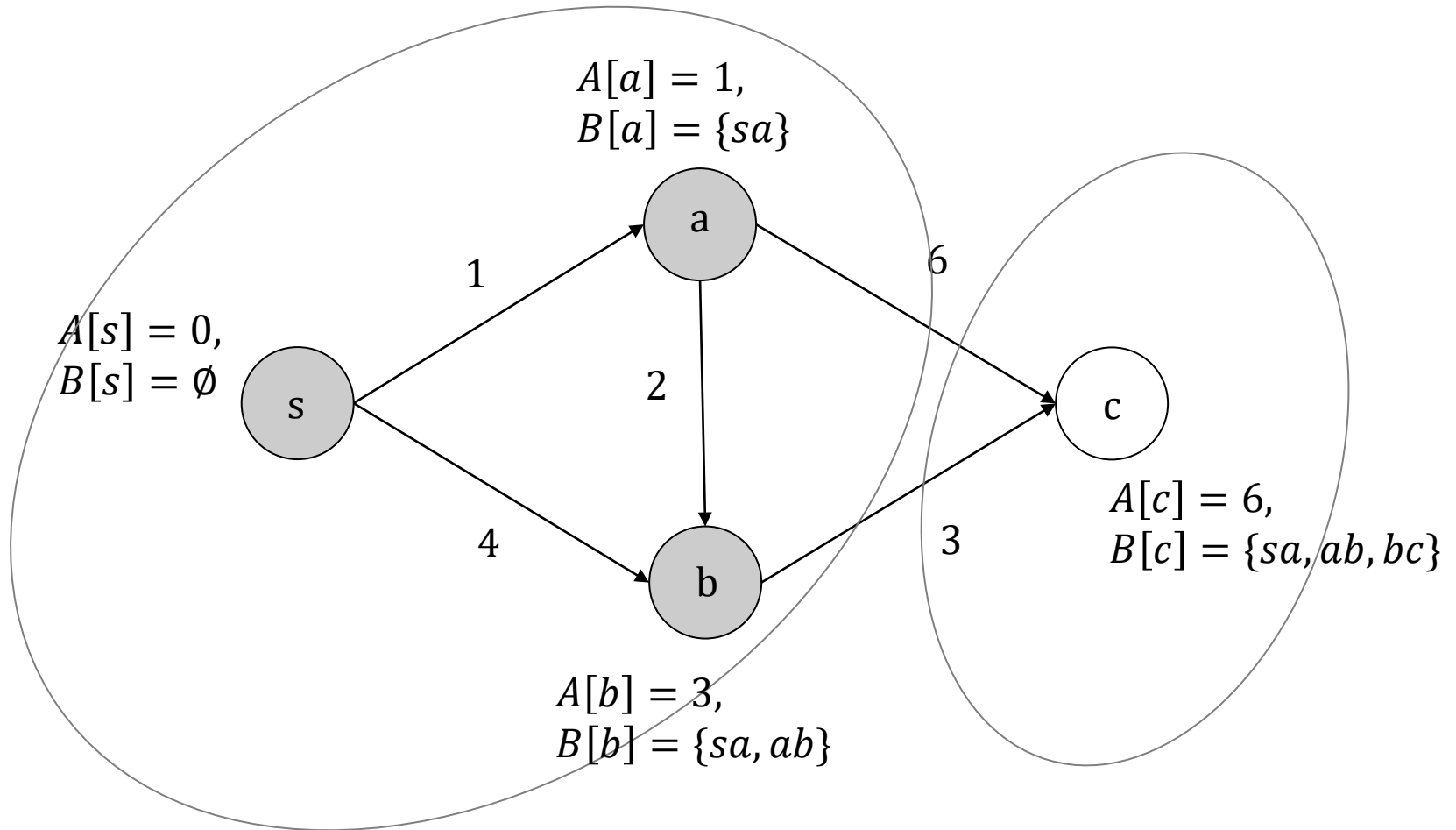
$$\min (A[s] + l_{sb}, A[a] + l_{ab}, A[a] + l_{ac}) = \min (0 + 4, 1 + 2, 1 + 6) = 3$$



An Example

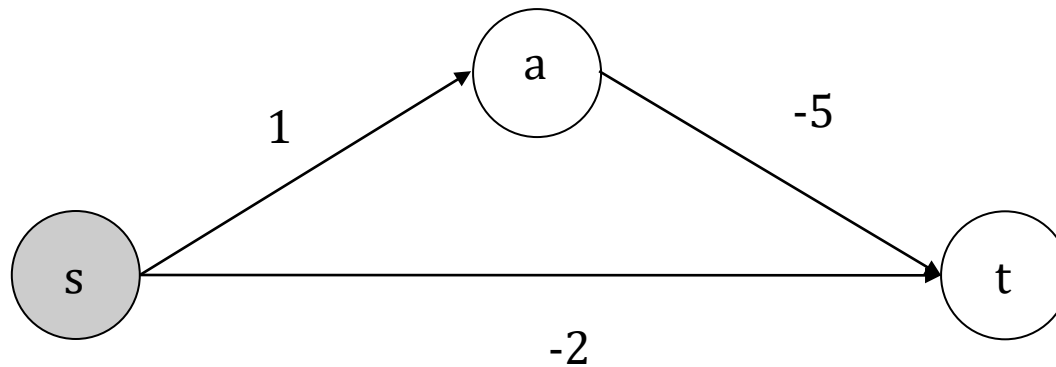
$A[v] + l_{vw}$ (Dijkstra's greedy criterion)

$$\min (A[a] + l_{ac}, A[b] + l_{bc}) = \min (1 + 6, 3 + 3) = 6$$



Non-Example

- Dijkstra is incorrect on this G



- Use dynamic programming in this case

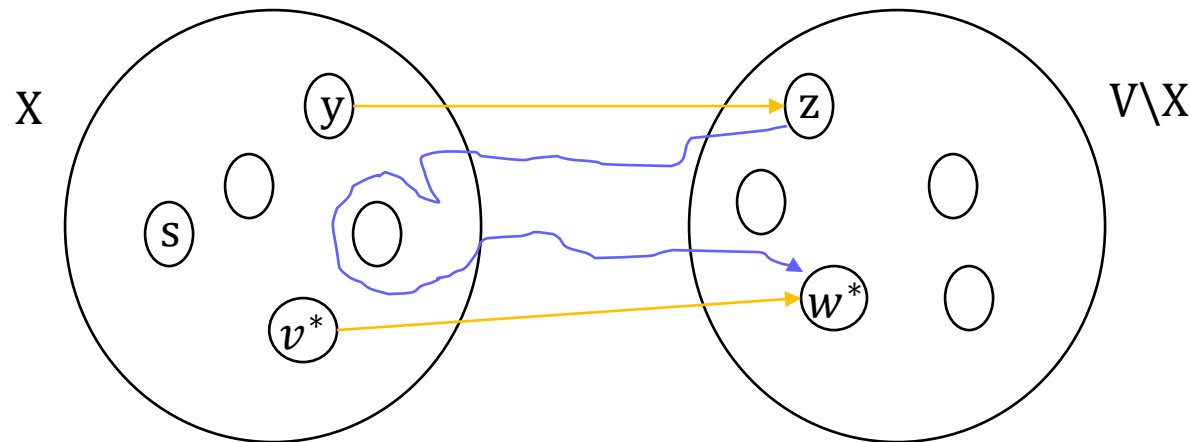
Proof of Correctness

Claim: $A[v] = L[v]$ where A is the output of Dijkstra and L is true shortest distance

Proof: By induction, base case $A[s] = L[s] = 0$ is true.

Inductive Hypothesis (I.H.): all previous iterations are correct, i.e.,

$\forall v \in X, A[v] = L[v]$ and $B[v]$ gives the shortest path



In the current iteration, Dijkstra have chosen v^*w^* , we have $A[w^*] = A[v^*] + l_{v^*w^*}$

Now let P be any $s \rightarrow w^*$ path and it must “cross the frontier”



Length of $P \geq L(y) + l_{yz} + 0 = A(y) + l_{yz} + 0$, note that $L(y) = A(y)$ by I.H.

Also, by Dijkstra’s greedy criterion,

Our length $= A[v^*] + l_{v^*w^*} \leq A(y) + l_{yz} \leq \text{Length of } P$

General Graph Search

- Let q be an abstract queue object
 - $\text{add}(\text{node})$, which adds a node into q
 - $\text{popFirst}()$, which pops the first node from q
- General graph search
 - While q is not empty:
 - ▶ $v \leftarrow q.\text{popFirst}()$
 - ▶ For all neighbors u of v such that $u \notin q$:
 - $\text{add}(u)$

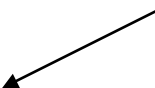
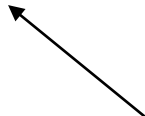
General Graph Search

- General graph search

While q is not empty:

- ▶ $v \leftarrow q.popFirst()$
 - ▶ For all neighbors u of v such that $u \notin q$:
 - $add(u)$
- If q is a standard LIFO stack, then DFS
- If q is a standard FIFO queue, then BFS
- If q is a priority queue, then Dijkstra
- If q is a priority queue with a heuristic, then A^*

Priority Queue Implementation

- $A[s] \leftarrow 0$, and $A[v] \leftarrow \infty$ for all $v \in V \setminus \{s\}$
- $q.add(s)$
- While q is not empty:
 - ▶ $v \leftarrow q.popFirst()$  Extract min-q
 - ▶ For all neighbors u of v such that $A[v] + l_{vu} \leq A[u]$
 - $A[u] \leftarrow A[v] + l_{vu}$
 - $q.update(u, A[u])$  Decrease-key(q)

Runtime: If using binary minheap, $O((|E| + |V|)\log V)$
If using Fibonacci minheap, $O(|E| + |V|\log V)$

Summary

- Wagner-Whitin model
- Dynamic Programming
- Shortest Path (Dijkstra's Algorithm)
- Next Up: Stochastic Inventory Model