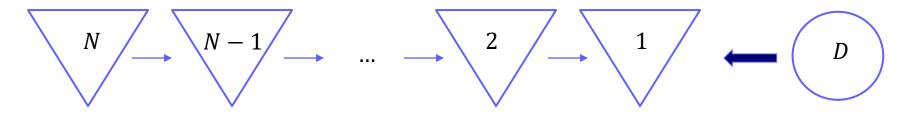
LEC009 Inventory Management IV

VG441 SS2020

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Multi-Echelon Problem

- N stages of a (serial) supply chain
- Demand rate is λ deterministically only at stage 1
- Stockouts are not allowed



```
k_j = fixed cost for orders of stage j
h'_j = inventory holding-cost rate for stage j
I'_j(t) = (local) inventory of stage j at time t
L'_j = leadtime for stage-j orders = 0 W.L.O.G.
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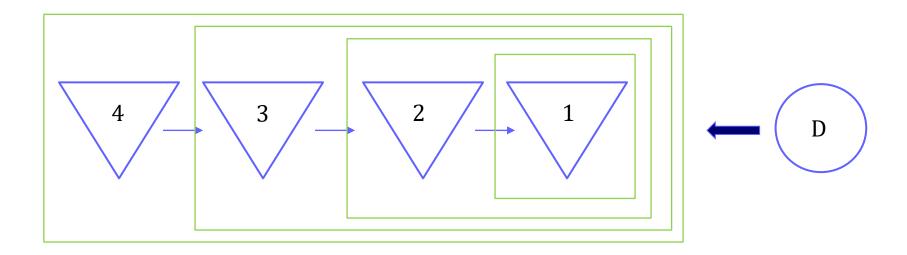
Question: what is the optimal ordering strategy?

Echelons and Echelon Inventories

 $k_j =$ fixed cost for orders of stage j

 h'_{j} = inventory holding-cost rate for stage j

 $I'_{j}(t) = (local)$ inventory of stage j at time t



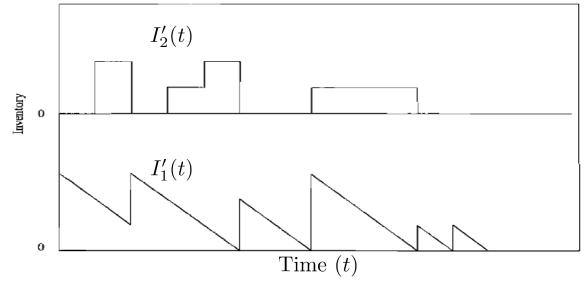
$$I_j(t) = \text{echelon inventory of stage } j \text{ at time } t = \sum_{i \leq j} I'_i(t)$$

 h_j = echelon-inventory holding-cost rate for stage $j = h'_j - h'_{j+1} \ge 0$

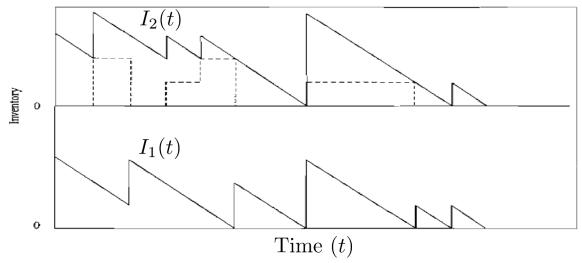
$$\Sigma_j h'_i I_j(t) = \Sigma_j h_j I_j(t)$$
 for all t

Why Echelon Inventories?

Local inventories over time



Echelon inventories over time



Policy Structures

• A policy is nested if for all j, whenever stage j orders, so does stages j-1.

• A policy is **ZIO** (zero-inventory-ordering) if order occurs only when its echelon inventory is zero.

Convince yourself that nested and ZIO are optimal.

Stationary-Interval Policies

```
u_j = \text{order interval for item } j

\mathbf{u} = \text{the vector } (u_j)_j

g_j = h_j \lambda

C(\mathbf{u}) = \text{average cost of the policy specified by } \mathbf{u}
```

$$C(\mathbf{u}) = \sum_{j} \left[\frac{k_j}{u_j} + \frac{1}{2} g_j u_j \right]$$

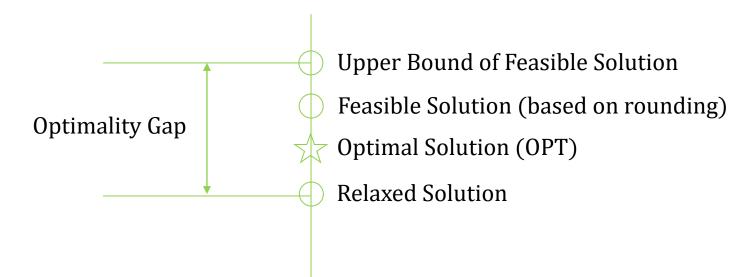
Minimize
$$C(\mathbf{u})$$

subject to $u_j = \xi_j u_{j-1}$, for all $j = 2, \dots, J$
 $\xi_j \in \mathbb{Z}^+$, for all $j = 2, \dots, J$

Caveat: This MILP may be difficult to solve.

Here is the Plan

- First, we solve a simpler "relaxed" problem.
- Solution of the relaxed problem is a lower bound.
- We round off this relaxed solution to obtain a feasible solution.
- We get an upper bound on this feasible solution.
- Show that the two bounds are close together.



Stationary-Interval Policies

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u_j = \text{order interval for item } j

\mathbf{u} = \text{the vector } (u_j)_j

g_j = h_j \lambda

C(\mathbf{u}) = \sum_j \left[ \frac{k_j}{u_j} + \frac{1}{2} g_j u_j \right]
```

Minimize
$$C(\mathbf{u})$$

subject to $u_j = \xi_j u_{j-1}$, for all $j = 2, \dots, J$
 $\xi_j \in \mathbb{Z}^+$, for all $j = 2, \dots, J$

Relax the constraints ...

Minimize
$$C(\mathbf{u})$$

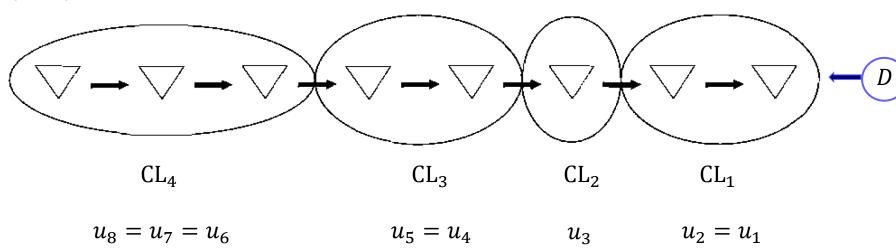
subject to $u_j \ge u_{j-1}$, for all $j = 2, ..., J$

Relaxed and Feasible Solutions

Minimize
$$C(\mathbf{u})$$

subject to $u_j \ge u_{j-1}$, for all $j = 2, ..., J$

Clusters.



Feasible solution: round to the nearest power-of-2

Gap between this feasible solution and the relaxed solution: ~ 1.06

Deterministic Demand (Nonstationary)

Input: T period demands $d_1, ..., d_T$ Decisions: $q_i(t), I_i(t)$

min $\sum_{j} \sum_{t} I_{j}(t)h_{j} + \sum_{j} \sum_{t} k_{j} \mathbb{1} (q_{j}(t) > 0)$ s.t. $I_{j}(t) = I_{j}(t-1) + q_{j}(t) - d_{t} \qquad \forall t, \ \forall j$ $I_{j}(t-1) + q_{j}(t) \ge I_{j-1}(t-1) + q_{j-1}(t) \qquad \forall t, \ \forall j$ $I_{j}(t) \ge 0 \qquad \qquad \forall t, \ \forall j$ $I_{j}(0) = 0 \qquad \qquad \forall j$

Dynamic Programming

- Define F(i, s, t) as the optimal cost of subproblem defined for stages i, ..., 1 and periods [s, t)
- ZIO: $I_i(s-1) = I_i(t-1) = 0$
- Nested: $I_j(s-1) = I_j(t-1) = 0$, for all j < i
- Goal: F(N, 1, T + 1)
- Boundary Conditions:

$$F(0,\cdot,\cdot) = 0$$

$$F(\cdot,T+1,\cdot) = 0$$

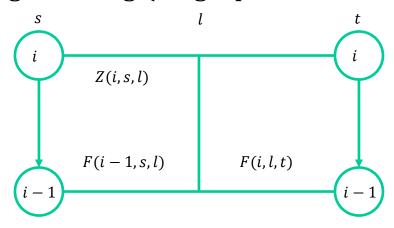
$$F(i,s,s+1) = \sum_{j=1}^{i} K_j \text{ for all } i$$

DP (Graphical Model)

• For each time s < t and stage j, the cost of covering d_s , ..., d_{t-1}

$$Z_{s,t}^{i} = K_{i} + \sum_{a=s}^{t-2} h_{a} \sum_{b=a-1}^{t-1} d_{b}$$

• Dynamic Programming (on graphical models)



$$F(i, s, t) = \min_{s < l < t - 1} \left\{ Z_{s, l}^{i} + F(i - 1, s, l) + F(i, l, t) \right\}$$

Stochastic Model

- Stage 1 faces stochastic demand D per period and penalty p
- Lead times $L_1, ..., L_N$ and lead time demand $D_1, ..., D_N$
- Echelon base-stock policy is optimal.

Theorem: Let
$$\underline{g}_0(x) = (p + h'_1) x^-$$
. For $j = 1, ..., N$, let
$$\hat{g}_j(x) = h_j x + \underline{g}_{j-1}(x)$$
$$g_j(y) = \mathbb{E} \left[\hat{g}_j \left(y - D_j \right) \right]$$
$$S_j^* = \operatorname{argmin} \left\{ g_j(y) \right\}$$
$$\underline{g}_j(x) = g_j \left(\min \left\{ S_j^*, x \right\} \right)$$

Then $\mathbf{S}^* = \left(S_j^*\right)_{j=1}^N$ is the optimal base-stock vector and $g_N\left(S_N^*\right)$ is the corresponding optimal cost

Stochastic Model

Use the following heuristics:

Theorem 6.4 (Shang and Song (2003): For any j and y

(a)
$$g_j^l(y) \le g_j(y) \le g_j^u(y)$$

(b)
$$S_j^l \le S_j^* \le S_j^u$$

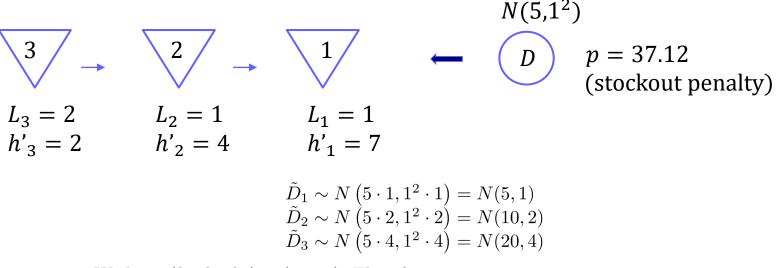
$$S_{j}^{l} = \tilde{F}_{j}^{-1} \left(\frac{p + \sum_{i=j+1}^{N} h_{i}}{p + \sum_{i=1}^{N} h_{i}} \right) \leq S_{j}^{*} \leq S_{j}^{u} = \tilde{F}_{j}^{-1} \left(\frac{p + \sum_{i=j+1}^{N} h_{i}}{p + \sum_{i=j}^{N} h_{i}} \right)$$

$$\tilde{D}_j = \sum_{i=1}^j D_i$$

Lead-time demand with lead time $\sum_{i=1}^{j} L_i$

Computational optimality gap $\leq 1\%$

A Simple Example



We have $(h_1, h_2, h_3) = (3, 2, 2)$. Therefore:

$$S_1^u = \tilde{F}_1^{-1} \left(\frac{37.12+4}{37.12+7} \right) = 6.49 \qquad S_1^l = \tilde{F}_1^{-1} \left(\frac{37.12+4}{37.12+7} \right) = 6.49$$

$$S_2^u = \tilde{F}_2^{-1} \left(\frac{37.12+2}{37.12+4} \right) = 12.35 \qquad S_2^l = \tilde{F}_2^{-1} \left(\frac{37.12+2}{37.12+7} \right) = 11.71$$

$$S_3^u = \tilde{F}_3^{-1} \left(\frac{37.12+0}{37.12+2} \right) = 23.27 \qquad S_3^l = \tilde{F}_3^{-1} \left(\frac{37.12+0}{37.12+7} \right) = 22.00$$

Taking the mean, we have

$$\tilde{S}_1 = \frac{1}{2}(6.49 + 6.49) = 6.49$$

 $\tilde{S}_2 = \frac{1}{2}(12.35 + 11.71) = 12.03$
 $\tilde{S}_3 = \frac{1}{2}(23.27 + 22.00) = 22.63$

These values are very close to $S^* = (6.49, 12.02, 22.71)$ and indeed their costs are very similar: $g(\tilde{\mathbf{S}}) = 47.66$, compared to $g(\mathbf{S}^*) = 47.65$