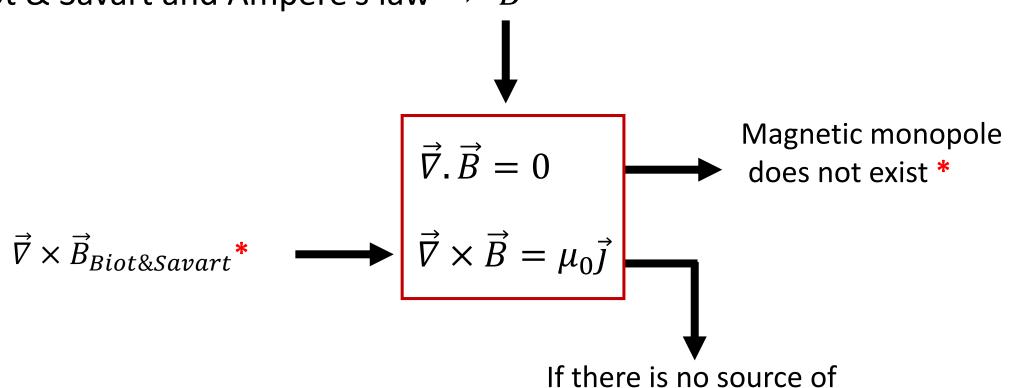
Magnetostatic: What next beyond Biot & Savart law?

The two Maxwell equations for magnetostatic

Biot & Savart and Ampere's law $\Rightarrow \vec{B}$



If there is no source of current (mobile charges)

$$\vec{\nabla} \times \vec{B} = \vec{0}$$

Waiting Maxwell's correction

Coulomb versus Biot & Savart law

Electrostatic

Constant
$$arepsilon_0$$
 and μ_0

$$\vec{E} = \frac{1}{4\pi \epsilon_0} \frac{q}{r^2} \vec{e}_r$$



Derived from experiments

Magnetostatic



$$\vec{B} = \frac{\mu_0}{4\pi} \frac{q}{r^2} \vec{v} \times \vec{e}_r$$

Deduced from measurements involving

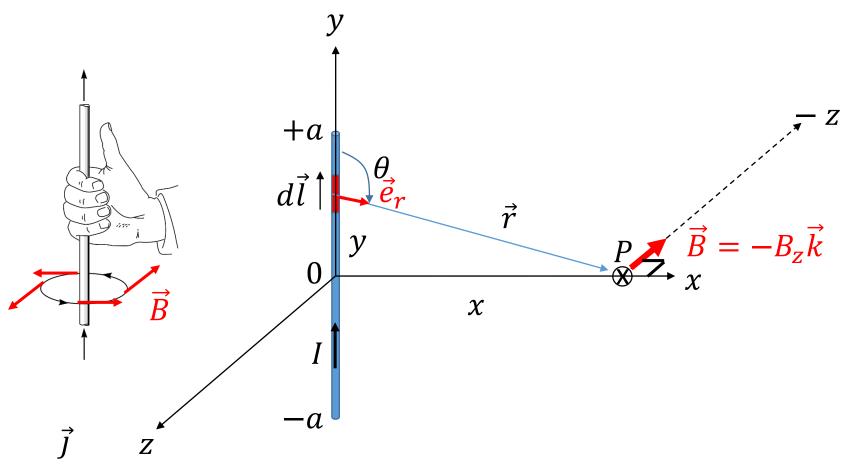
- Charged spheres
- Batteries
- wires

Measurements having nothing to do with <u>light</u> and <u>electromagnetic waves</u>

Maxwell
$$\frac{1}{c^2} = \varepsilon_0 \mu_0$$

Applications of Biot & Savart law

Magnetic field of a wire 2a long



$$d\vec{l} = 0\vec{i} + dy\vec{j} + 0\vec{k}$$

$$\vec{e}_r = \sin(\pi - \theta)\vec{i} + \cos\theta\vec{j} + 0\vec{k}$$





 \vec{B} lies in the plan zOx

At point P, $\overrightarrow{B} \perp x$ —axis $B_x = 0$

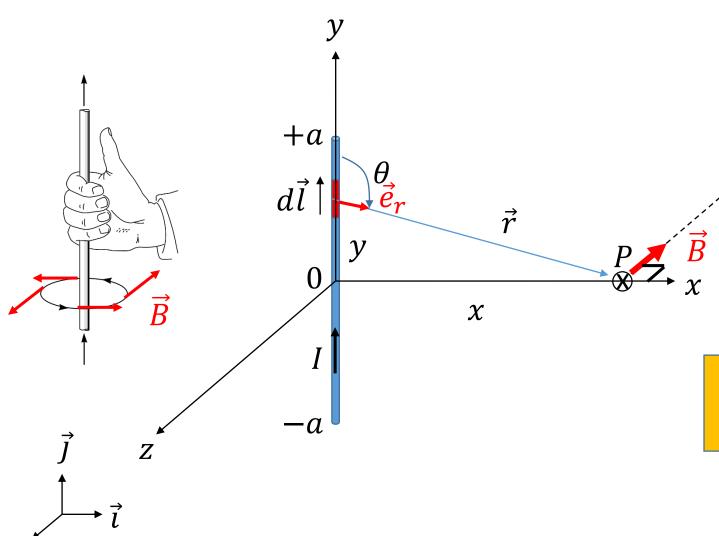


$$\overrightarrow{B} = -B_z \overrightarrow{k}$$



Cross product

Magnetic field of a wire 2a long



$$d\vec{l} \times \vec{e}_r = -\sin\theta dy \vec{k}$$

$$r = \sqrt{x^2 + y^2}$$



Biot & Savart

$$\vec{B} = \frac{\mu_0}{4\pi} \int \frac{I}{r^2} d\vec{l} \times \vec{e}_r$$

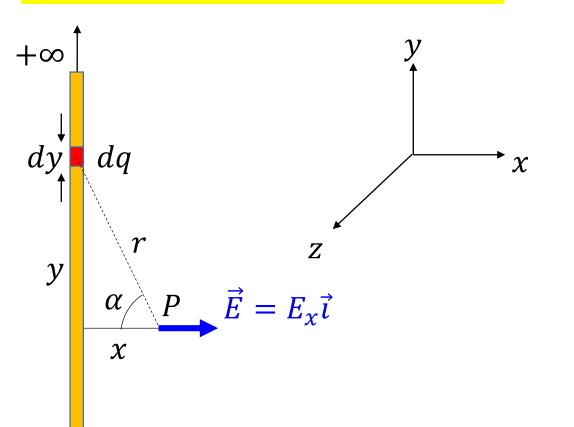
$$\vec{B} = -B_z \vec{k} \Rightarrow \vec{B} = -\frac{\mu_0 I}{4\pi x} \frac{2a}{\sqrt{x^2 + a^2}} \vec{k}$$

$$2a \gg x$$

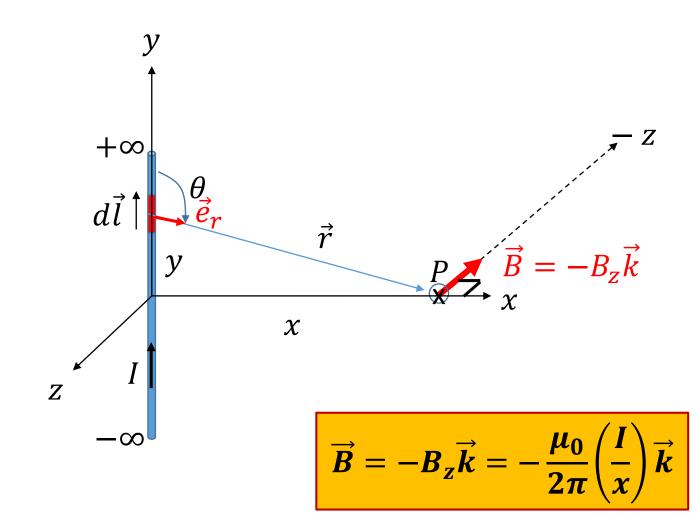
$$B = B_z(P) = \frac{\mu_0 I}{2\pi x}$$

Static charges along an infinite wire

Steady moving charges along an infinite wire

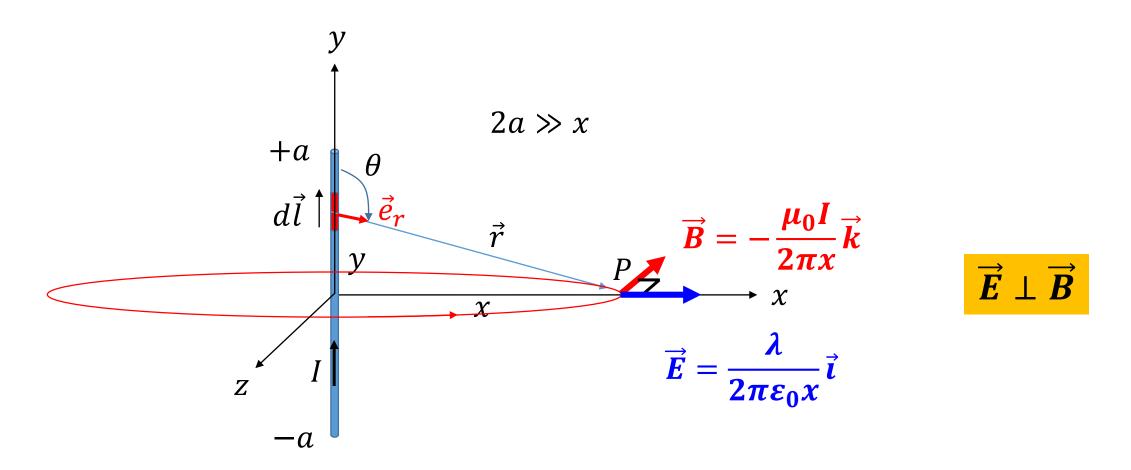


$$\vec{E} = \vec{E}_x = \frac{1}{2\pi\varepsilon_0} \left(\frac{\lambda}{x}\right) \vec{\iota}$$

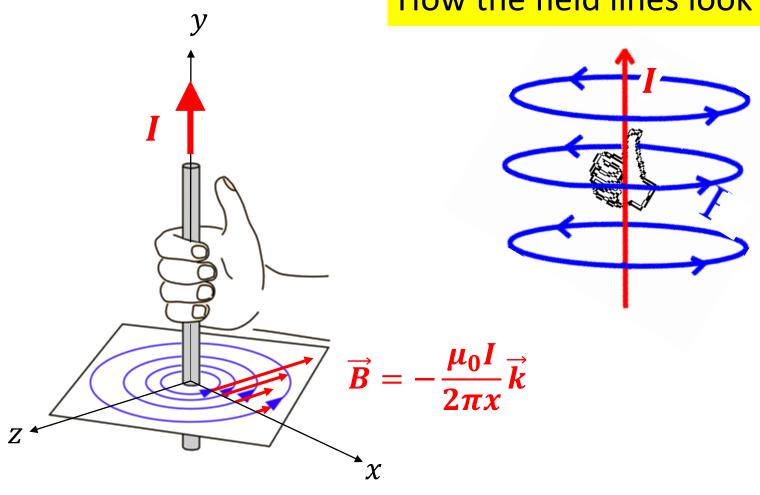


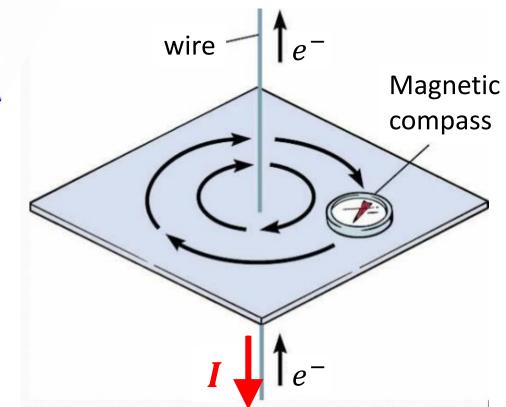
Electrostatic and Magnetostatic at once

Charges moving upwards along a conducting wire

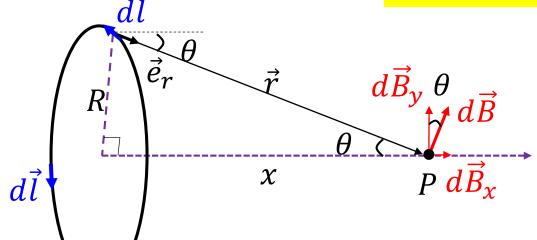


How the field lines look like?





Single carrying current loop



$$sin\theta = \frac{R}{\sqrt{R^2 + x^2}}$$

$$r = \sqrt{R^2 + x^2}$$

$$d\vec{B} = \frac{\mu_0}{4\pi} \frac{I}{r^2} d\vec{l} \times \vec{e}_r \qquad d\vec{l} \perp \vec{e}_r$$

$$d\vec{B} = d\vec{B}_x + d\vec{B}_y$$

By symmetry component along y —axis cancels

$$dB_{x} = dBsin(\theta)$$

$$B_{x} = \frac{\mu_{0}}{4\pi} \oint \frac{I}{r^{2}} dlsin\theta$$

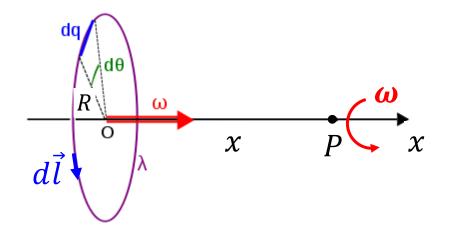
$$\Gamma = 2\pi R$$

Magnetic field along
$$x$$
 —axis $\vec{B}_x = \frac{\mu_0 I R^2}{2(R^2 + x^2)^{3/2}} \vec{i}$

At the center of the loop (x = 0) $\vec{B}_x = \frac{\mu_0 I}{2R} \vec{i}$

Charged loop: mechanical rotation

A closed loop of radius R rotates mechanically around the z-axis at constant angular speed ω . The loop is charged with a uniform linear charge λ . What is the magnetic field along x?



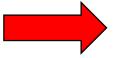
The key issue is to connect I to ω

$$I = \frac{dq}{dt}$$

$$dq = \lambda dl = \lambda R d\theta$$

$$I = \frac{dq}{dt} = \lambda R \frac{d\theta}{dt} = \lambda R \omega$$

$$\vec{B}_{x} = \frac{\mu_{0} R^{2}}{2(R^{2} + x^{2})^{3/2}} \vec{i}$$



$$\vec{B}_{x} = \frac{\mu_{0}(\lambda \omega R) R^{2}}{2(R^{2} + x^{2})^{3/2}} \vec{t}$$

Interaction of wires conducting electric current with magnetic field

Lorentz force

(single charge q)

$$\vec{F} = q\vec{v} \times \vec{B}$$

Lorentz force

(charge element dq)

$$d\vec{F} = \frac{dq\vec{v}}{\vec{v}} \times \vec{B}$$

$$dq\vec{v} = nvAd\vec{l} = Id\vec{l}$$

$$dq = nAdl$$

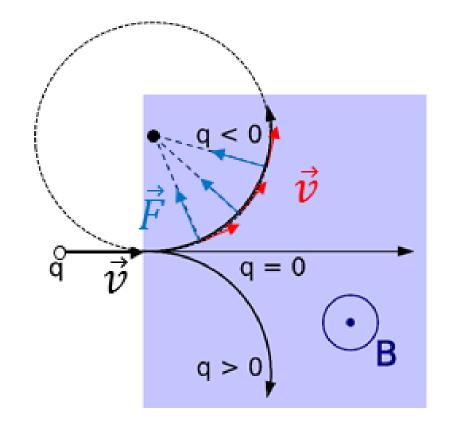
charges/unit volume

Laplace force

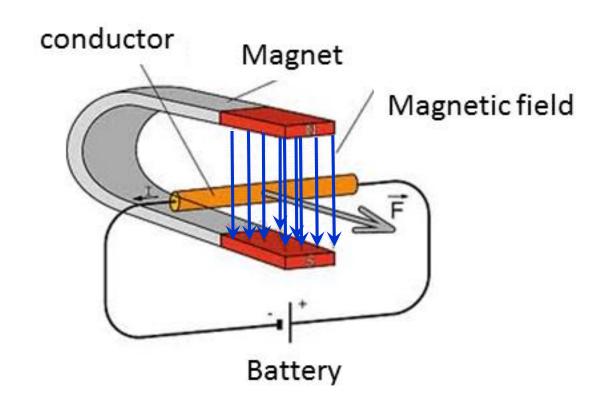
(wire carrying current)

$$d\vec{F} = Id\vec{l} \times \vec{B}$$

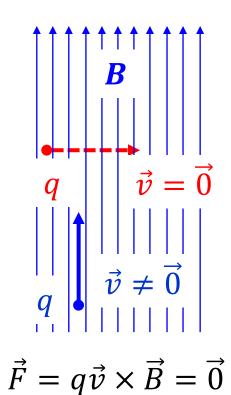
Lorentz force: $\vec{F} = q\vec{v} \times \vec{B}$



Laplace force: $\vec{F} = I\vec{l} \times \vec{B}$



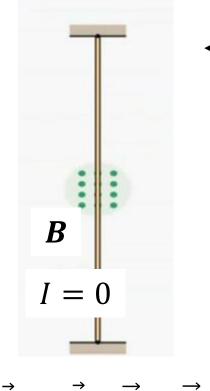
Case where Lorentz and Laplace forces are zero



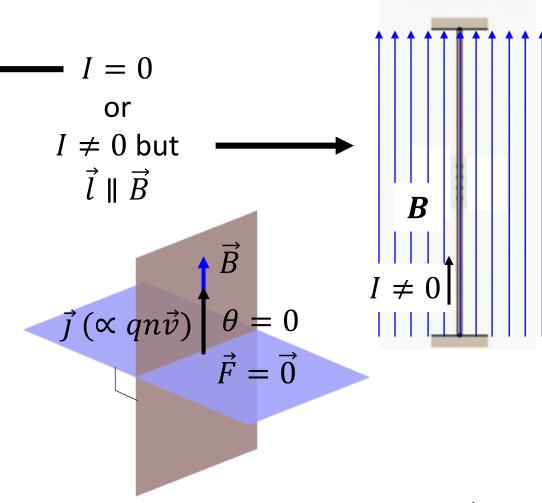
 $\vec{v} = \vec{0}$

or

 $\vec{v} \neq \vec{0}$ but $\vec{v} \parallel \vec{B}$

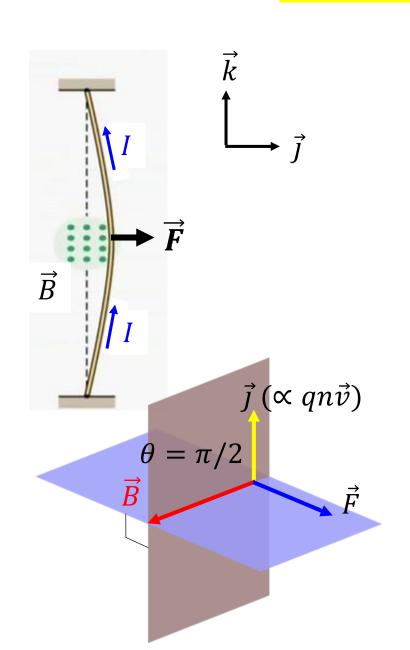


$$\vec{F} = I\vec{l} \times \vec{B} = \vec{0}$$



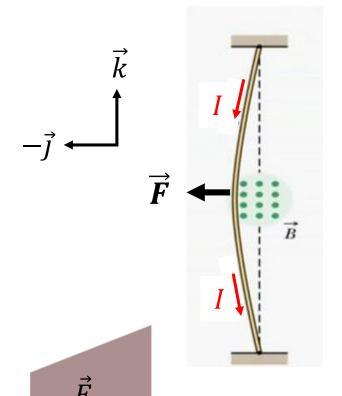
From University of physics (11rd edition)

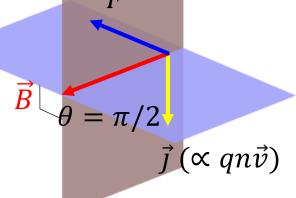
Magnetic force on current NOT parallel to \vec{B}

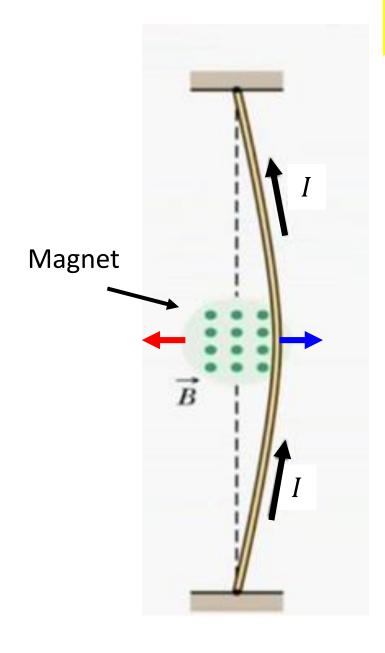


Laplace force (wire carrying current)

$$d\vec{F} = Id\vec{l} \times \vec{B}$$

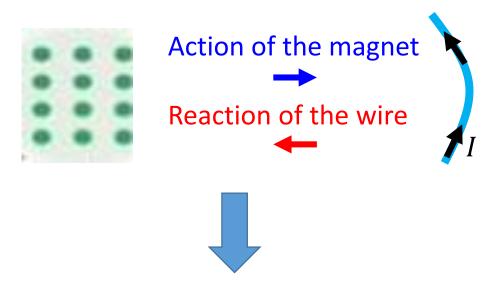






The action – reaction principle

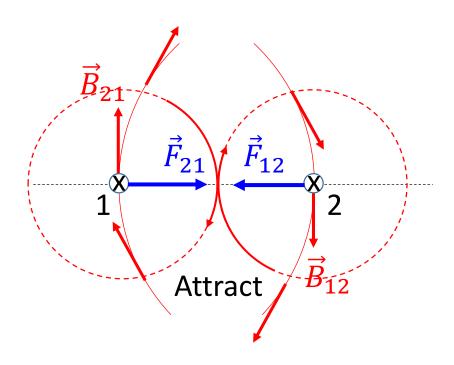
Action of the magnet on the wire where charges are flowing



- Two magnetic fields
- One due to the magnet
- One due to the current in the wire

Two parallel wires carrying currents

Currents in the same direction



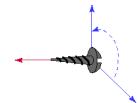
Opposite charges





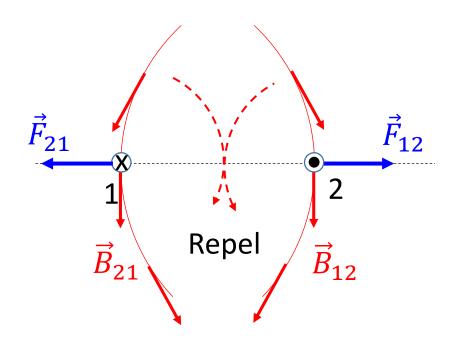
Determine the direction of \vec{B}





Determine the direction of \vec{F}

Currents in opposite direction



Alike charges





Ampere's law

From Biot & Savart law...
$$\vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \int \frac{I}{r^2} d\vec{l} \times \vec{e}_r$$
 ... To ampere's law

Slides #40 | Lecture 15&16 Magnetostatic

$$\vec{\nabla} \times \vec{B}(\vec{r}) = \frac{\mu_0 I}{4\pi} \vec{\nabla} \times \left(\int d\vec{l'} \times \frac{(\vec{r} - \vec{r'})}{(\vec{r} - \vec{r'})^3} \right) \qquad \qquad \vec{\nabla} \times \vec{B}(\vec{r}) = \mu_0 \vec{J}(\vec{r})$$

Slides #45-47 I_Lecture 15&16_Magnetostatic

Ampere's law is for magnetostatic what Gauss law is for electrostatic



It exploits symmetry in relating \vec{B} to source (current)

Electrostatic

Magnetostatic

Calculating electric field produced by symmetric charge distribution

Gauss Law

- <u>Closed</u> surface
- Flux through volume

$$\iint \vec{E} \cdot d\vec{A} = \frac{Q_{enclosed}}{\varepsilon_0}$$

Closed surface

Gaussian surface



Perfect Symmetry

Calculating magnetic field produced by symmetric current distribution

Ampere's Law

- <u>Closed</u> path
- Flux through open surface

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enclosed}$$

Closed path

Amperian loop

Particular case where Ampere's path is a circle

Using Biot & Savart law with a long wire

$$B = \frac{\mu_0 I}{2\pi r}$$

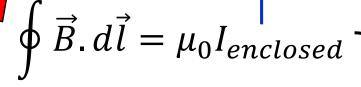
Slide #6

Using Ampere's law around the circle

$$\oint \vec{B} \cdot d\vec{l} = B \cdot \oint dl = B \cdot 2\pi r$$

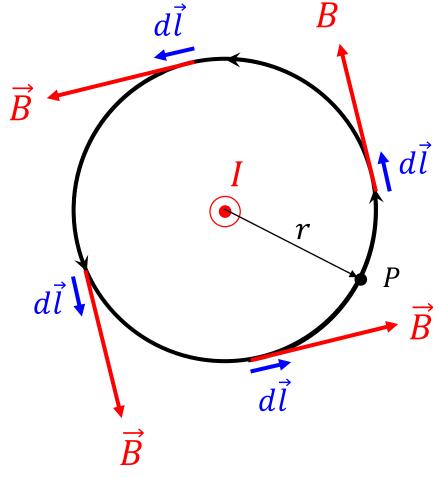
Closed circle

Amperian loop



Closed circle

Slide #90 D_Lectures 4-7 Coordinate system Scalar versus Vector fields Operators



Stokes theorem

$$\vec{\nabla} \times \vec{B}(\vec{r}) = \mu_0 \vec{J}(\vec{r})$$

Case where the closed path has any shape

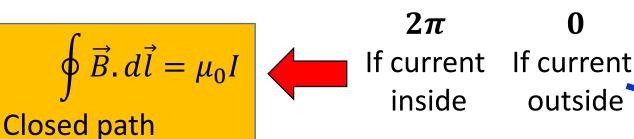
$$\oint \vec{B}.\,d\vec{l} = \oint \frac{\mu_0 I}{2\pi r} \,.\,d\vec{l}$$
 Closed path

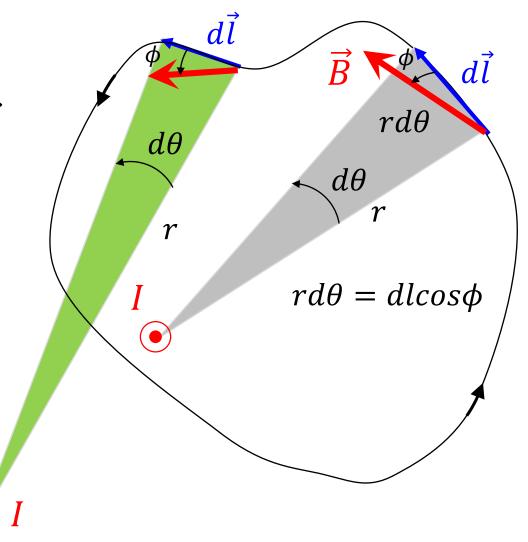
$$\vec{B} \cdot d\vec{l} = Bdlcos\phi = Brd\theta$$

Projection of $d\vec{l}$ on \vec{B} , see HW#2

$$\oint \vec{B} \cdot d\vec{l} = \oint \frac{\mu_0 I}{2\pi r} \cdot r d\theta = \frac{\mu_0 I}{2\pi} \oint d\theta$$

Closed path



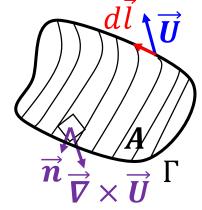


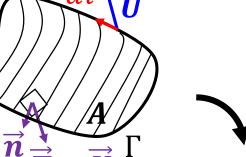
Use polar coordinate to demonstrate this

Ampere's law expressed in differential form

Stoke's theorem: The integral around any closed path $m{\Gamma}$ of any vector $\dot{m{U}}$ is equal to the surface integral of the normal component of $\overrightarrow{m{V}} imes \overrightarrow{m{U}}$

$$\oint_{\Gamma} \overrightarrow{U} \cdot d\overrightarrow{l} = \int_{A} (\overrightarrow{\nabla} \times \overrightarrow{U}) \cdot \overrightarrow{n} dA$$





A = Flux through an open surface (Amperian surface: Not necessarily flat)

$$\oint \vec{B} \cdot d\vec{l} = \int (\vec{\nabla} \times \vec{B}) \cdot \vec{n} dA = \int \mu_0 \vec{J} \cdot \vec{n} dA$$

$$\Gamma \qquad A \qquad A$$

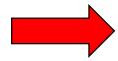


Ampere's law for magnetostatic

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$$

Caution not to misinterpret Ampere's law

$$\oint \vec{E} \cdot d\vec{l} = 0$$



$$\vec{E}$$
 is conservative $\vec{E}(\mathbf{r}) = -\vec{\nabla}V(r)$

Closed path Γ

$$\vec{F}_{E}(r) = q\vec{E}(r) = -q\vec{\nabla}V(r) = -\vec{\nabla}U(r)$$

$$\oint \vec{E} \cdot d\vec{l} \rightarrow \oint q\vec{E} \cdot d\vec{l} = \oint \vec{F} \cdot d\vec{l} = 0$$
Work

This **electrostatic** force does **no work** on a charge that moves around a **closed path** \Leftrightarrow returns to its the starting point

The force depends on the **position only** and derives from a potential energy U(r) which depends on position only

This is not necessarily the same for the magnetostatic field

 $\oint \vec{B}.\,d\vec{l}$

Is it related to the question whether \vec{B} is conservative?

Closed path Γ

$$\oint \vec{B} \cdot d\vec{l} = 0$$

Closed path Γ

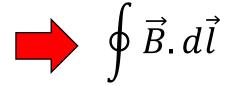
$$\vec{F}_B(\vec{r}, \vec{v}) = q\vec{v} \times \vec{B}$$

$$\vec{F}_B \perp \vec{v}$$
 and $\vec{F}_B \perp \vec{B}$

$$\oint \vec{B} \cdot d\vec{l}$$
 Closed path Γ



$$\oint \vec{F}_B . \, d\vec{l}$$
 Closed path Γ



IS NOT RELATED TO THE WORK DONE BY THE MAGNETIC FORCE

Caution



$\oint \vec{B} \cdot d\vec{l}$ States the Ampere's law only

The magnetic force on moving charge is **NOT** conservative

A conservative force depends **ONLY** on the **position** of the body on which the force is acting

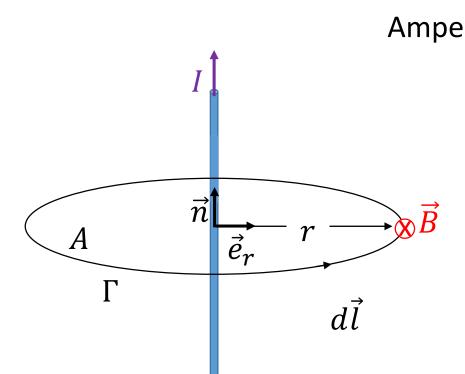
The magnetic force on moving charge depends on the **position BU**T also on the **velocity**

$$\vec{F}_B(\vec{r}, \vec{v}) = q\vec{v} \times \vec{B}$$

The magnetic vector force is NOT parallel to the vector magnetic field!

Applications of Ampere's law

Magnetic field of a straight wire



Ampere's law
$$\oint_{\Gamma} \vec{B} \cdot d\vec{l} = B \cdot 2\pi r = \mu_0 I_{enclosed}$$

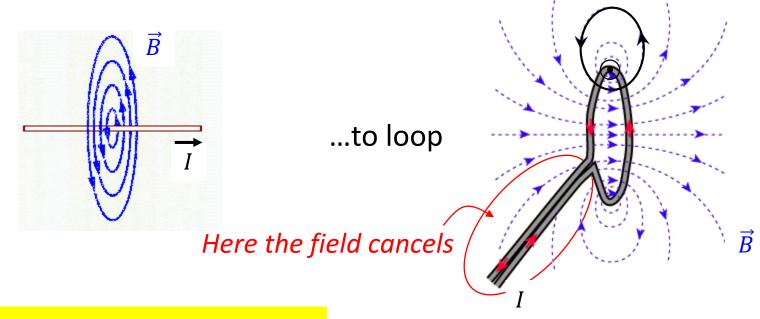
$$I_{enclosed} = I$$

$$B = \frac{\mu_0 I}{2\pi r} \qquad \blacksquare \qquad B = \frac{\mu_0}{4\pi} \frac{2I}{r}$$

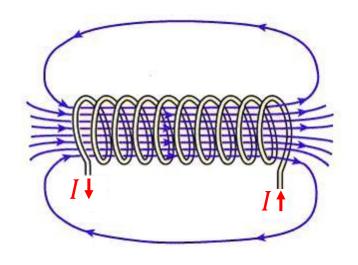
$$\vec{B} = \frac{\mu_0}{4\pi} \frac{2I}{r} \vec{n} \times \vec{e}_r \qquad |\vec{n} \times \vec{e}_r| = 1$$

Much easier than using Biot & Savart law: see slide # 5 and 6

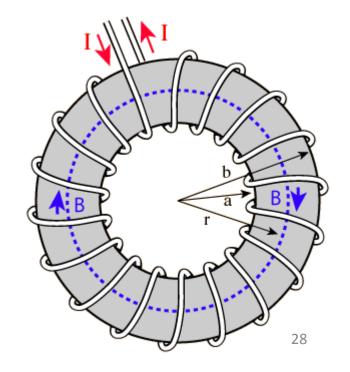




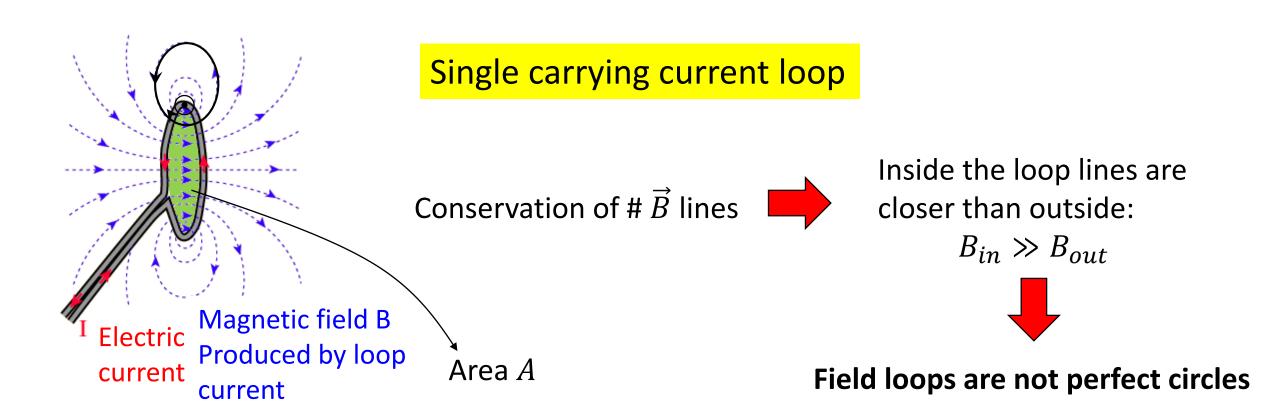
... to straight solenoid



... to toroidal solenoid



Ve230: A. Mesli AMU-CNRS (FRANCE) Fall 2018 (UM-SJTU)



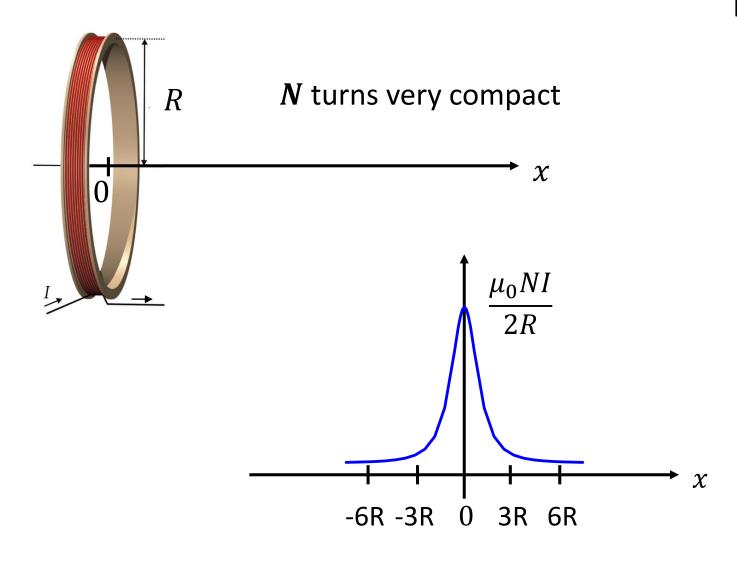
Flux through a cross-sectional area

$$\Phi = \int \vec{B} \cdot d\vec{A}$$
 = Flux of the same lines through the rest of the area outside covering the whole universe



Far outside the loop \vec{B} is very weak!

Magnetic field of a coil (= short solenoid)



Field produced by one loop

$$\vec{B}_{x} = \frac{\mu_0 I R^2}{2(R^2 + x^2)^{3/2}} \vec{i}$$
 Slide #10



Field produced by N loops

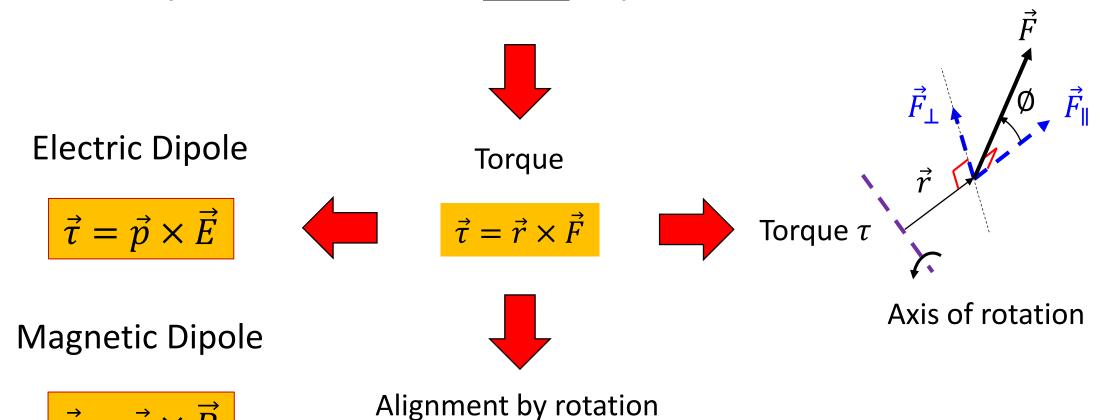
Superposition principle

$$\vec{B}_{x} = \frac{\mu_0 N I R^2}{2(R^2 + x^2)^{3/2}} \vec{i}$$

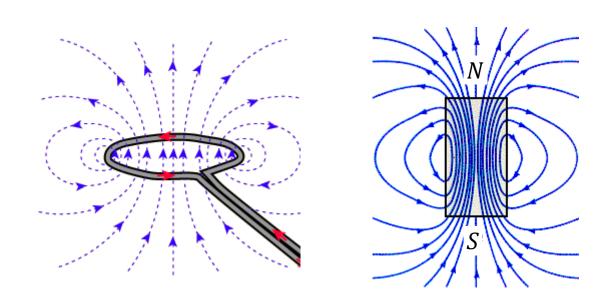
Magnetic Dipole: Force and torque on a current loop

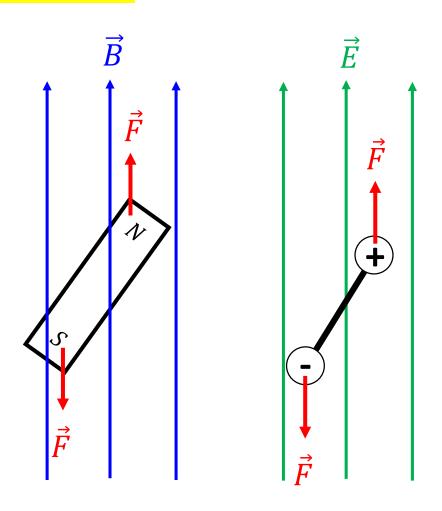
We know from mechanics that **Torque** is a master piece in physics

We know from electrostatics that **Dipole** subject to uniform force



Current loop produces a dipole

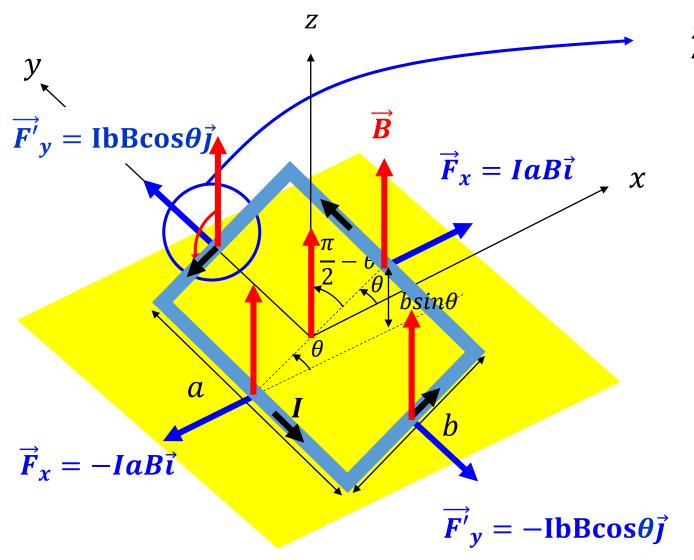


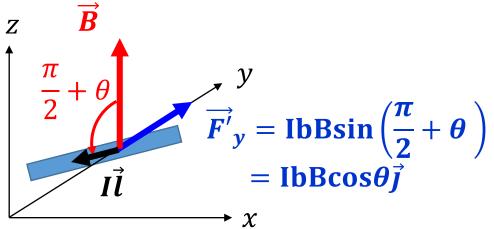


Alignment by rotation

Uniform magnetic field

Laplace force: $\vec{F} = I\vec{l} \times \vec{B}$





TOTAL NET FORCE = 0

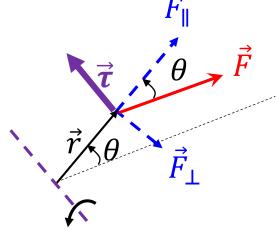
WHAT ABOUT THE NET TORQUE?

 θ

Torque au

$$\vec{\tau} = \vec{r} \times \vec{F}$$

$$\vec{\tau} = \vec{r} \times \vec{F}_{\perp} = rFsin\theta \vec{J}$$



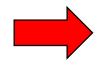
Axis of rotation (y - axis)

$$ab = area$$

$$\vec{\mu} = I\vec{A}$$

Magnetic dipole moment

$$\tau = \left[\left(\frac{b}{2} \right) IaBsin\theta \right] \times 2$$



 $\tau = \underbrace{Iab}_{\alpha} B sin\theta$

 $\alpha \downarrow \beta$ or magnetic moment $\gamma = \alpha \beta \sin \phi \Rightarrow \vec{\gamma} = \vec{\alpha} \times \vec{\beta} \longrightarrow \vec{\tau} = \vec{\mu} \times \vec{B}$

 \times 2 because both \vec{F} and $-\vec{F}$ give rise to the torque

$$\theta = 0 \Leftrightarrow \underline{\textbf{Stable}}$$
 equilibrium position

$$\theta = \pi \Leftrightarrow \underline{\mathbf{Unstable}}$$
 equilibrium position

Electrostatic

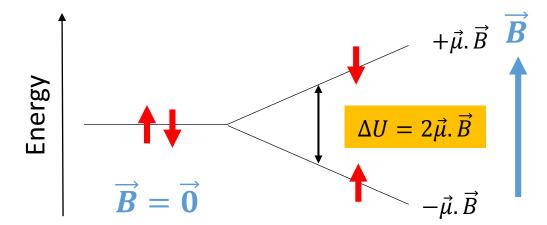
$$\vec{\tau} = \vec{p} \times \vec{E}$$

$$\vec{p} = q\vec{d}$$

Mgnetostatic

$$\vec{\tau} = \vec{\mu} \times \vec{B}$$

$$\vec{\mu} = I\vec{A}$$



Work done on a dipole

$$dW = -dU = \tau . d\theta$$

$$dU = -\tau . d\theta = -(-\mu B \sin \theta) d\theta$$

$$Because (\vec{\mu}, \vec{B}) = -\theta$$

 θ is counterclockwise and $(\vec{\mu}, \vec{B})$ is clockwise

$$dU = \mu B \sin \theta d\theta$$

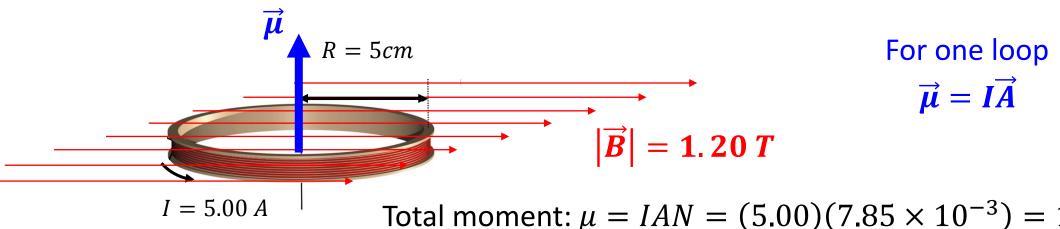
$$U = -\mu B cos(\theta) + constant$$

Potential energy is minimum when the dipole is aligned with the field

$$\Delta U = -\vec{\mu}.\vec{B}$$

Coil in a magnetic field: Magnetic moment and torque

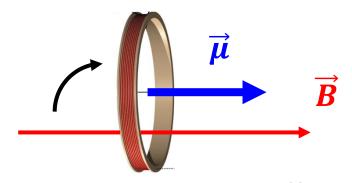
Find the direction of the moment of the torque.... And its magnitude



Total moment: $\mu = IAN = (5.00)(7.85 \times 10^{-3}) = 1.18 A.m^2$

Torque: $\tau = \mu B \sin \theta = (1.18)(1.20) \sin \pi / 2 = 1.41 N.m$

What is the most stable position of the coil?

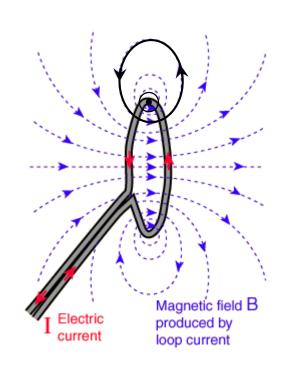


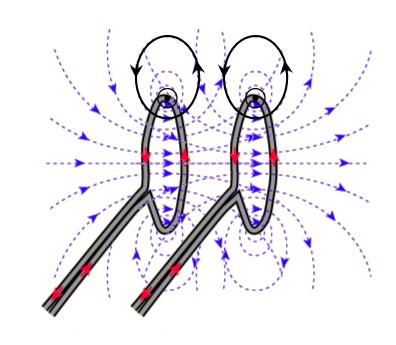
Magnetic field of a solenoid

From single loop ...

to

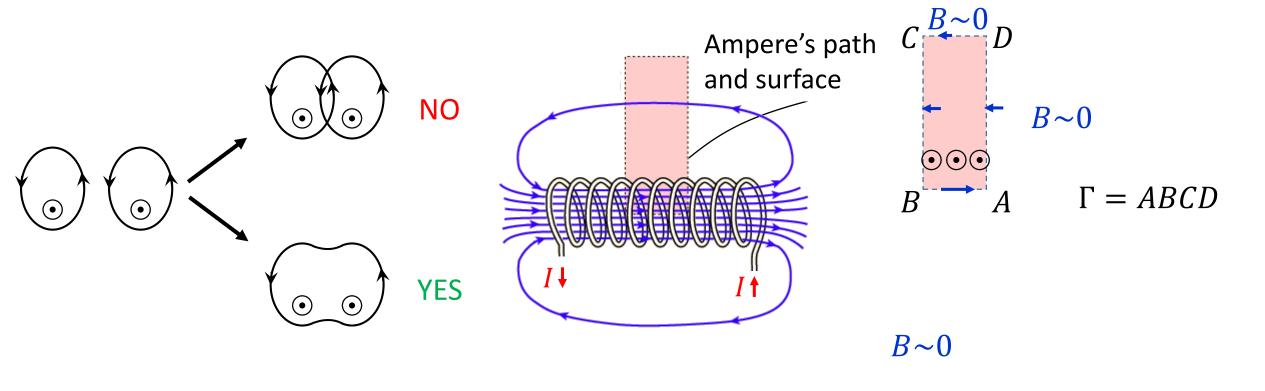
... two neighboring loops...



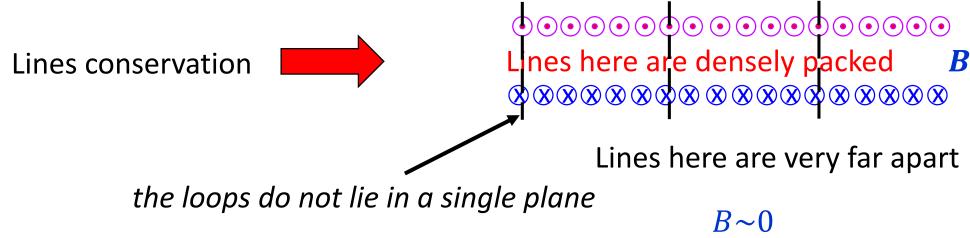


This configuration is forbidden

Field lines emerging from different sources **cannot** cross



Lines here are very far apart



Why is the field almost zero outside the solenoid?

• Conservation of # field lines: The # of lines inside the solenoid is equal to the # lines outside

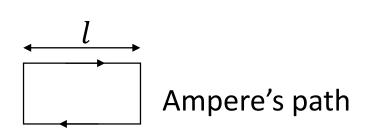
• Flux through a cross-sectional area inside $\Phi = \int \vec{B} \cdot d\vec{A} =$ Flux of the same lines through the rest of the area outside covering the whole universe



The lines outside are **MUCH** more dispersed while highly confined inside

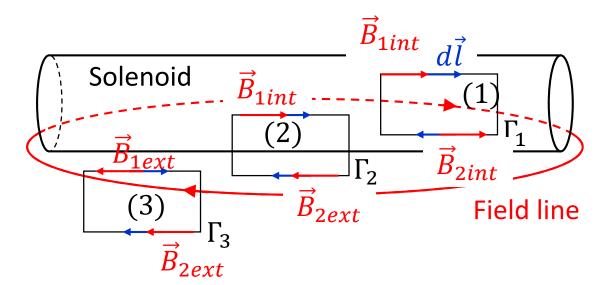


$$\vec{B}$$
 outside = $\vec{0}$



Ampere's law applied in 3 different situations





Path
$$\Gamma_1$$
 $I_{enclosed} = 0$

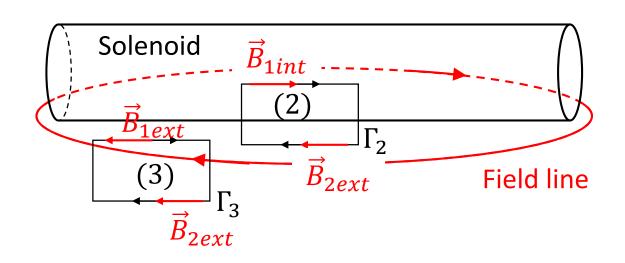
Path
$$\Gamma_2$$
 $I_{enclosed} = NI$

Path
$$\Gamma_3$$
 $I_{enclosed} = 0$

$$\oint \vec{B} \cdot d\vec{l} = 0 \qquad \qquad B_{1int} - B_{2int}$$

Field uniform everywhere in the solenoid

Ampere's law applied in 3 different situations



Path
$$\Gamma_3$$
 $I_{enclosed} = 0$

Path
$$\Gamma_2$$
 $I_{enclosed} = NI$

$$\oint \vec{B} \cdot d\vec{l} = 0 \qquad (B_{1ext} - B_{2ext})l = 0 \qquad B_{1ext} = B_{2ext}$$

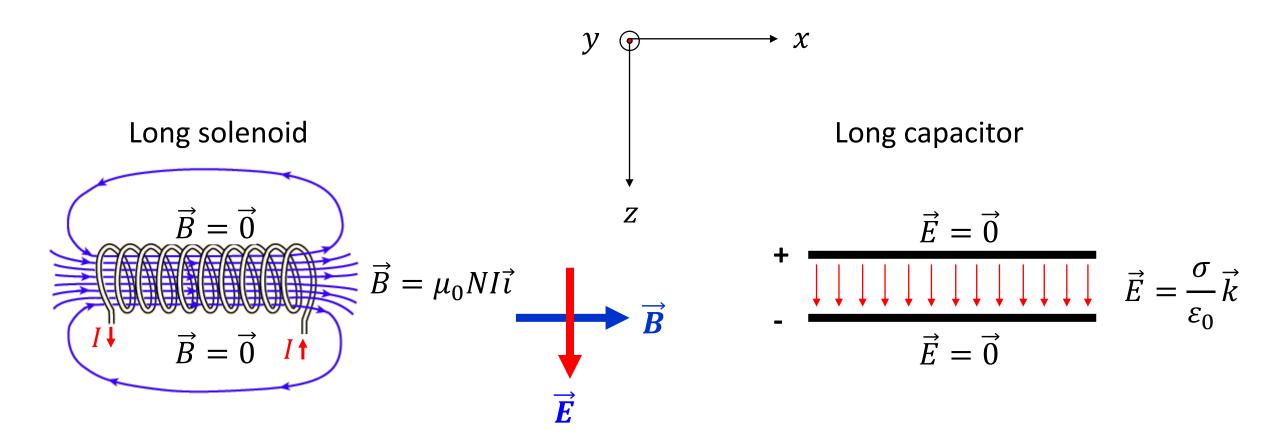
But
$$B(\infty) = 0$$

Field outside solenoid = 0

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 NI \qquad (B_{1int} - B_{2ext})l = \mu_0 NI$$



$$B_{1int} = B = \mu_0 NI$$

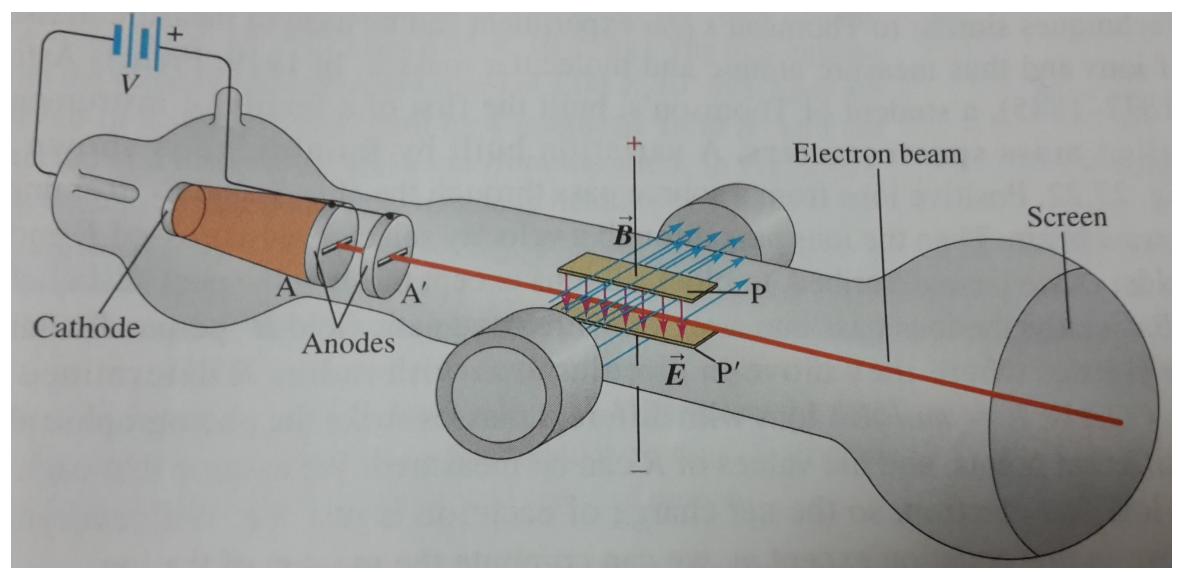


In both cases the fields are zero outside

Why should the field lines go parallel inside the solenoid?

Because $\vec{\nabla} \cdot \vec{B} = 0$

Thomson's e/m Experiment



From University of physics (11rd edition)

Field inside and outside a long cylinder conductor

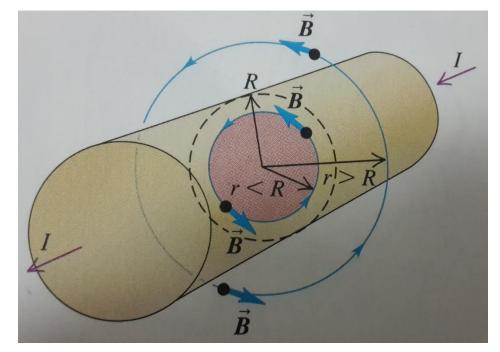
A cylindrical conductor of radius R carries a current I. The current is uniformly distributed over the cross-sectional area of the conductor. Find the magnetic field as a function of distance r for points inside and outside the conductor

Circular symmetry



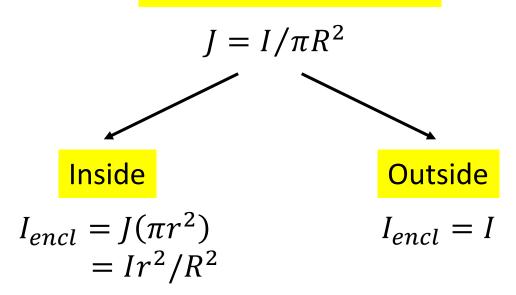
Field inside \Leftrightarrow ampere's path (circle) with radius r < R

Field outside \Leftrightarrow ampere's path (circle) with radius r > R



From University of physics (11rd edition)

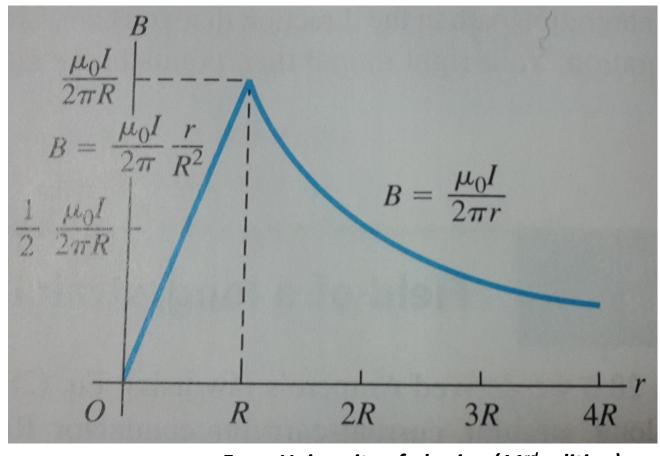
Current per unit area



$$B = \frac{\mu_0 I}{2\pi} \frac{r}{R^2}$$

$$B = \frac{\mu_0 I}{2\pi r}$$

Any comment?



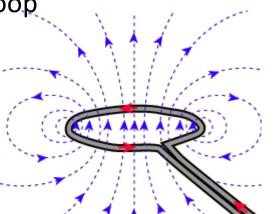
From University of physics (11rd edition)

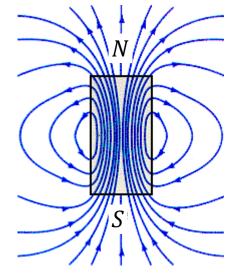
Field outside is the same irrespective of R: Cylinder, Rod or Wire

Slide #78 E_Lectures 8&9 Gauss law in Electrostatics

What is a magnet

The current is clearly responsible for the magnetic field in a loop





- BUT what about magnet?
- Where does the current come from in a magnet?

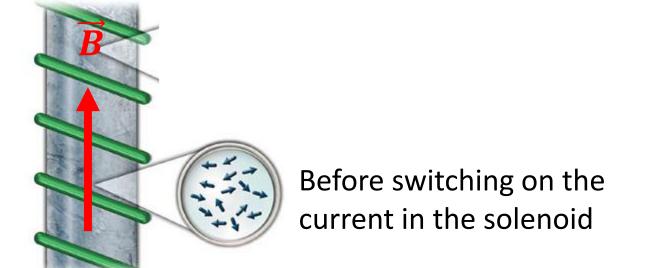
Origin of magnetism in matter: electron produces two dipoles

- Orbiting around nucleus
- Spin (quantum effect)

In magnets the current is for free

What happens if a iron bar is inserted in a solenoid?

Magnetic moment



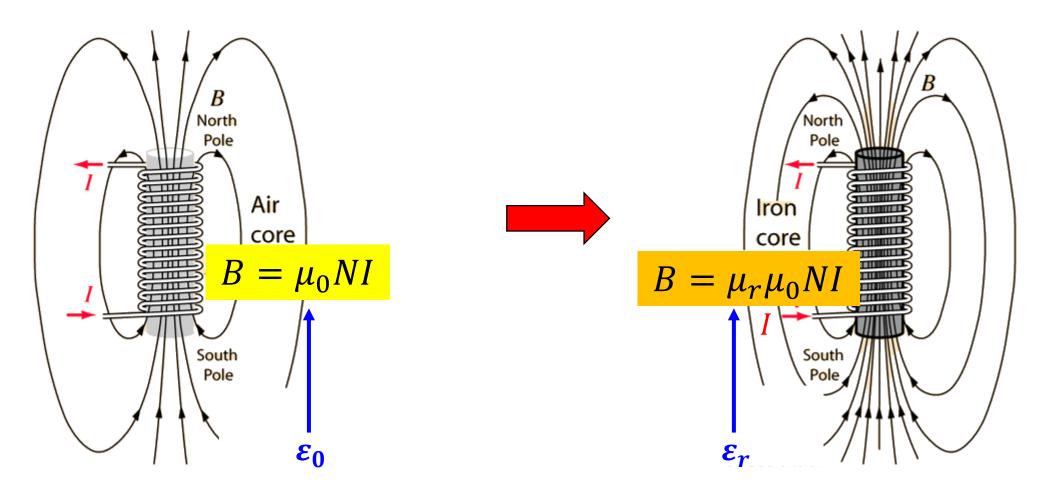
Enhances the field inside iron



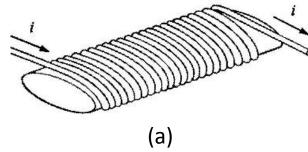
In the case of a dielectric, the field inside is **reduced**

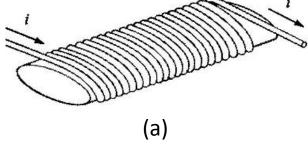
Any clue of how to make magnet?

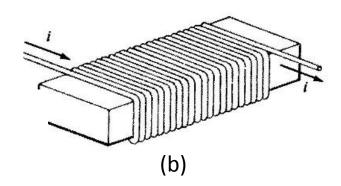
The iron core is for a solenoid what a dielectric is for a capacitor



Similarity with capacitor plates separated by vacuum or dielectric except that the net field inside the dielectric is smaller than the applied field



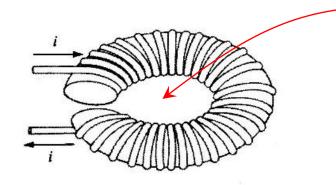




Does the internal field depend on the cross-sectional shape of the solenoid?

No because
$$B = \mu_0 NI$$

Irrespective of the shape of the solenoid



What is the field inside?

Field of a toroidal solenoid

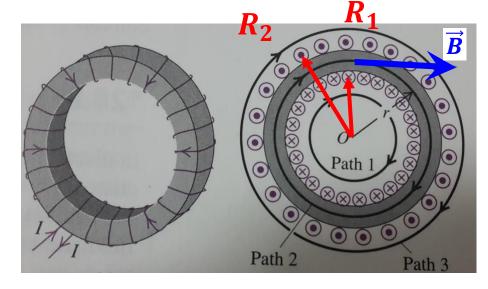
We consider a toroidal solenoid (toroid). N turns very tight carrying a current I.

Find the magnetic field every where

Circular symmetry



Field inside \Leftrightarrow ampere's path 1 (circle) $r < R_1$



From University of physics (11rd edition)

Field inside loops \Leftrightarrow ampere's path 2 (circle) $R_1 < r < R_2$

Field outside \Leftrightarrow ampere's path 3 (circle) $r > R_2$

Field inside
$$\Leftrightarrow$$
 ampere's path 1 (circle) $r < R_1$

$$I_{encl} = 0$$
 $\oint \vec{B} \cdot d\vec{l} = B2\pi r = 0$

Equivalence in Electrostatic: see slide #20 in E_Lectures 8&9 Gauss law in Electrostatics slide #16 in F_Lecture 10&11_Conductors and Dipoles

Field outside
$$\Leftrightarrow$$
 ampere's path 3 (circle) $r > R_2$

$$I_{encl} = 0$$
 $\oint \vec{B} \cdot d\vec{l} = B2\pi r = 0$

Field inside toroid
$$\Leftrightarrow$$
 ampere's path 2 (circle) $R_1 < r < R_2$

$$I_{encl} = NI \qquad \oint \vec{B} \cdot d\vec{l} = B2\pi r = \mu_0 NI$$

$$R_1 < r < R_2$$

$$R_1 < r < R_2 \qquad B = \frac{\mu_0 NI}{2\pi r}$$

Any comment?

$$B = \frac{\mu_0 NI}{2\pi r}$$

Field is **NOT** uniform over a cross section of the core

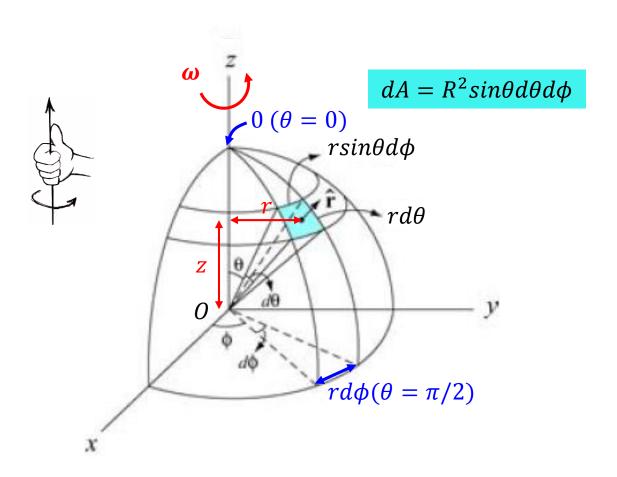
$$\frac{N}{2\pi r} = n$$
 Number of turns per unit length

$$B = \mu_0 nI$$

Field at the center of a straight solenoid, Slide #41

Surface charged sphere: mechanical rotation

A Sphere of radius R is uniformly charged on the surface with a surface density σ . The sphere is rotating around its z — axis. What is the magnetic field at the center of the sphere?



Elementary area $dA = R^2 sin\theta d\theta d\phi$

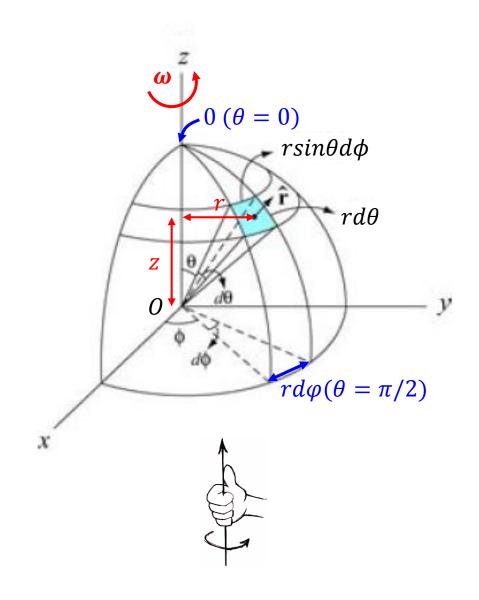


The charge on dA is $dq = R^2 \sigma sin\theta d\theta d\phi$

This elementary area in rotation behaves like a loop

$$dI = \frac{dq}{dt} = R^2 \sigma sin\theta d\theta \frac{d\phi}{dt} = R^2 \omega \sigma sin\theta d\theta$$

From slide #11
$$\Rightarrow d\vec{B}_z(0) = \frac{\mu_0 r^2 dI}{2(r^2 + z^2)^{3/2}} \vec{k}$$



$$dI = R^2 \omega \sigma sin\theta d\theta$$

$$d\vec{B}_z(0) = \frac{\mu_0 r^2 dI}{2(r^2 + z^2)^{3/2}} \bar{k}$$

$$r = Rsin\theta$$

$$z = R\cos\theta$$

$$d\vec{B}_{z}(0) = \frac{\mu_{0}r^{2}dI}{2(r^{2} + z^{2})^{3/2}}\vec{k}$$

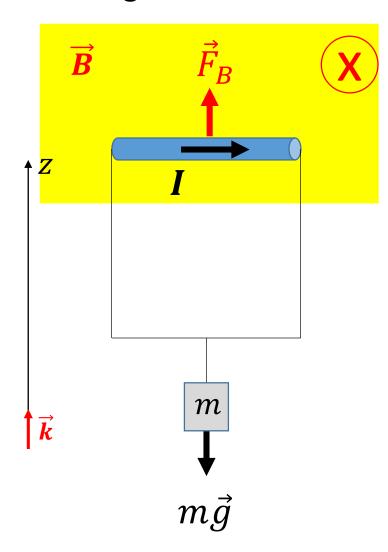
$$r = Rsin\theta$$

$$d\vec{B}_{z}(0) = \frac{\mu_{0}\omega\sigma Rsin^{3}(\theta)}{2}\vec{k}$$

$$\vec{B}_z(0) = -\int_0^\pi \frac{\mu_0 \omega \sigma R}{2} [1 - \cos^2(\theta)] d[\cos(\theta)] \vec{k}$$

$$\vec{B}_z(0) = \frac{2}{3}\mu_0\omega\sigma R\vec{k}$$

What should be the direction of the magnetic field to overcome gravitation allowing thus to hang the mass in air?



For what current *I* in the loop would the magnetic force balance exactly the gravitational force?

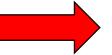
(mass of the circuit negligible)

$$F_B = \int I(dl \times B) = IBa = mg$$

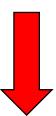
$$I = \frac{mg}{Ba}$$

What happens if we increase the current?

The loop rises lifting the weight

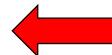


Somebody is doing work: Who?



Magnetic force?

BUT magnetic force never does work!



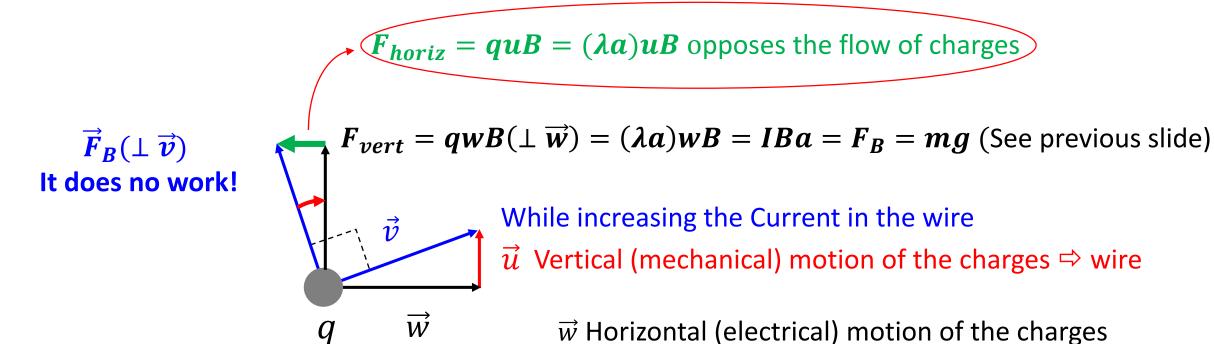
$$W_B = F_B h = IBah$$

 $F_B \parallel h$

What is happening?

When the wire starts to rise, the charges in that wire are moving Horizontally BUT NOT ONLY. They also move vertically!

$$\vec{v} = \vec{w} + \vec{u}$$



Steady current in the wire $I = \lambda w (C/s)$

The **BATTERY** must do work to keep the charges moving to the right

- In a time dt, the charges move a horizontal distance wdt.
- The BATTERY does work against the horizontal force

The magnetic force is passive

