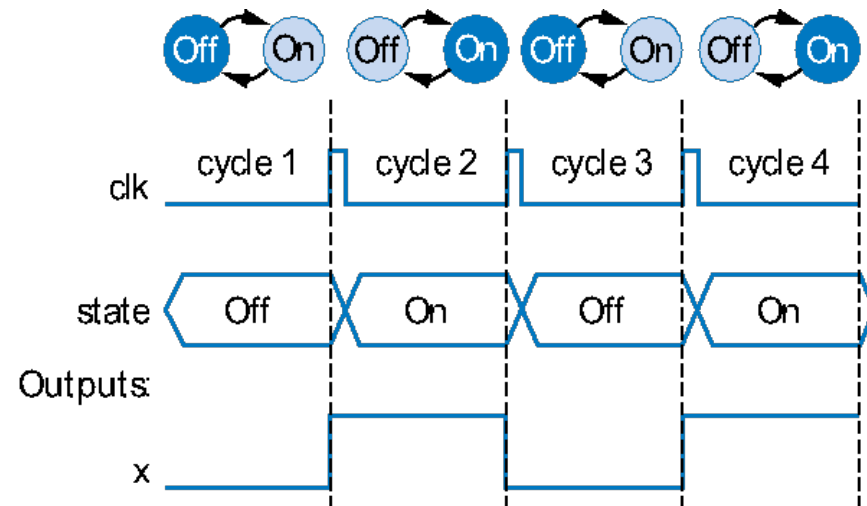
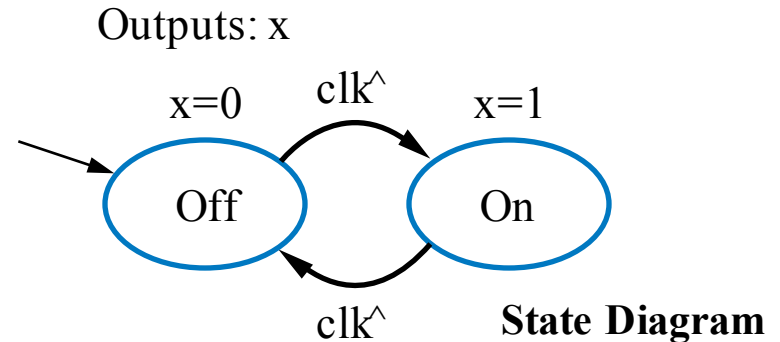


Topic 10

Finite State Machine

Describing Behavior of Sequential Circuit

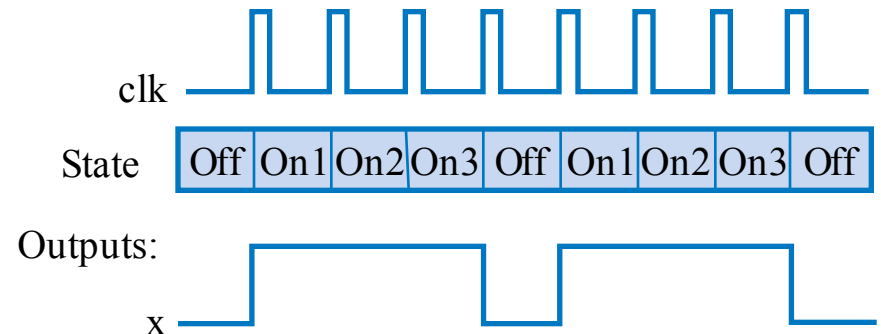
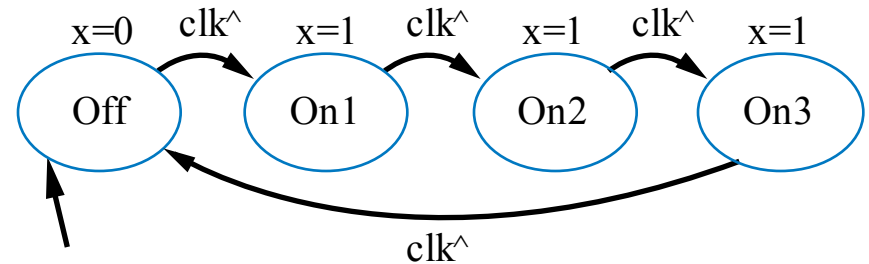
- Finite-State Machine (FSM)
 - A way to describe **desired behavior** of a sequential circuit
 - Consists of a set of states, transitions between states, and maybe inputs and outputs
 - **present state**: currently happening
 - **next state**: next to happen
 - Example: Toggle output x every clock cycle
 - Two states: “Off” and “On”
 - Corresponding outputs: $x=0$ or 1
 - No input
 - Transition from Off to On, or On to Off, on rising clock edge
 - Arrow with no starting state points to initial state



Example: Output Special Pattern

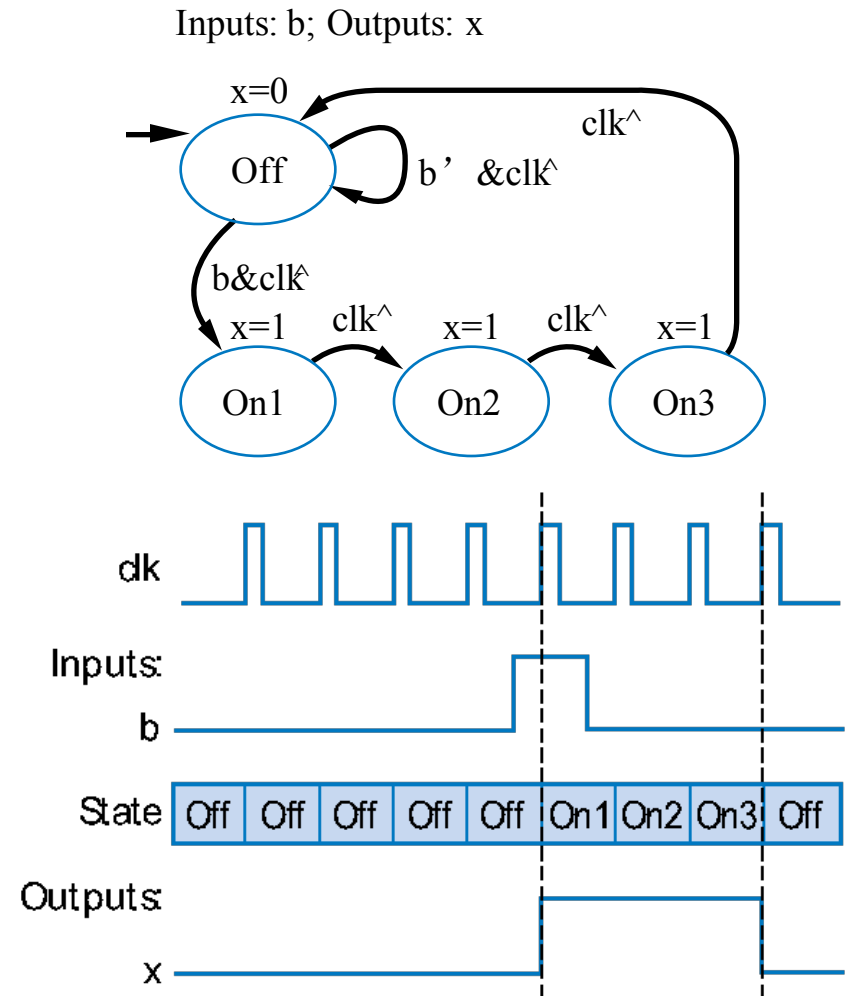
- Want a circuit to output 0, 1, 1, 1, 0, 1, 1, 1, ...
 - One bit at a time
 - Each bit for one clock cycle
- Can be described as FSM
 - Four states
 - Each state corresponds to an output, 0, 1, 1, 1
 - Then repeat
 - Transition on rising clock edge to next state

Outputs: x



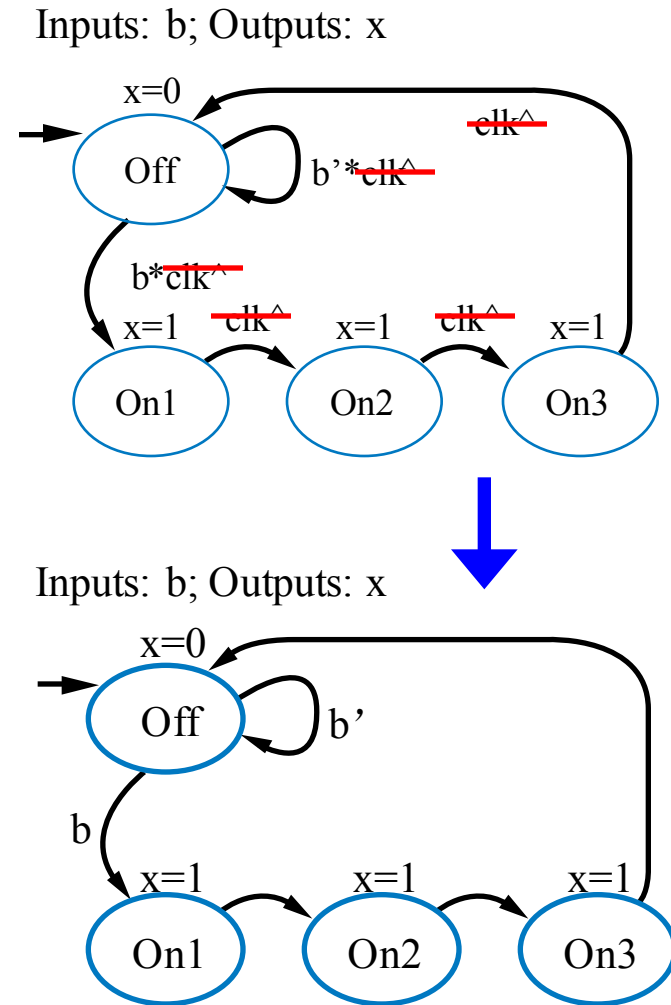
Example: FSM with Input

- b is a push button, output x to stay on for exactly 3 clock cycles no matter how long b is pushed
- Wait in “Off” state while b is 0 (b')
- When b is 1 (and rising clock edge), transition to On1
 - Sets $x=1$
 - On next two clock edges, transition to On2, then On3, which also set $x=1$
- So $x=1$ for three cycles after button pressed
- Potential issue: if button b stays on, what will happen?



State Diagram Simplification: Clock Implicit

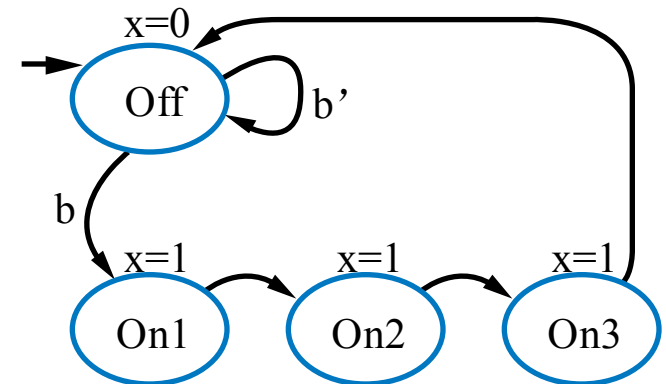
- **Synchronous** FSMs – FSM behaviors synchronized to active edge of clock
 - Asynchronous FSMs -- less common, advanced topic
- Make implicit – all state transitions are triggered by rising edge of clock
- Make implicit – Unlabeled path means transition is triggered only by clock, inputs don't matter



FSM Definition

- FSM consists of
 - Set of states
 - Ex: {Off, On1, On2, On3}
 - Set of inputs, set of outputs
 - Ex: Inputs: {b}, Outputs: {x}
 - Initial state
 - Ex: "Off"
 - Set of transitions
 - Describes next states
 - Ex: Has 5 transitions
 - Set of actions (outputs)
 - Sets outputs while in states
 - Ex: $x=0$, $x=1$, $x=1$, and $x=1$

Inputs: b; Outputs: x



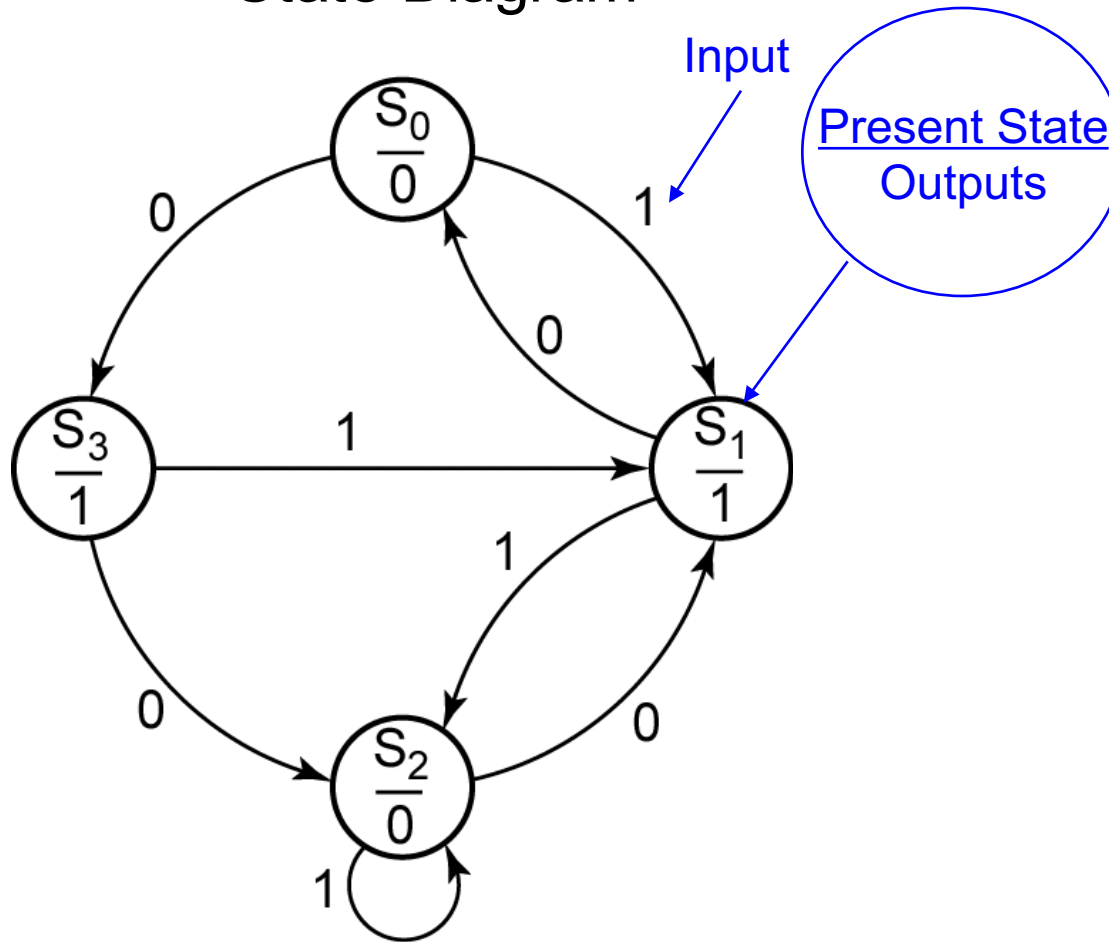
FSM can be represented graphically, known as **state diagram**

| | Inputs | | | Outputs | | |
|-----|--------|----|---|---------|----|----|
| | s1 | s0 | b | x | n1 | n0 |
| Off | 0 | 0 | 0 | 0 | 0 | 0 |
| | 0 | 0 | 1 | 0 | 0 | 1 |
| On1 | 0 | 1 | 0 | 1 | 1 | 0 |
| | 0 | 1 | 1 | 1 | 1 | 0 |
| On2 | 1 | 0 | 0 | 1 | 1 | 1 |
| | 1 | 0 | 1 | 1 | 1 | 1 |
| On3 | 1 | 1 | 0 | 1 | 0 | 0 |
| | 1 | 1 | 1 | 1 | 0 | 0 |

FSM can also be represented in tabular form, known as **state table**

State Diagram and State Table

State Diagram



Outputs

Or

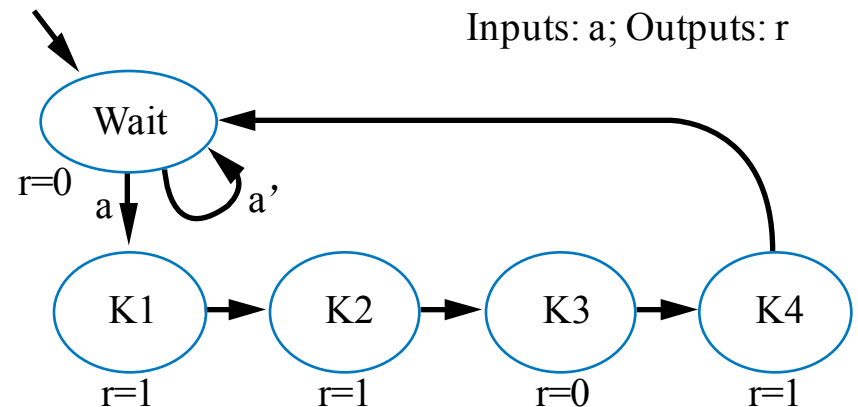
Present State

State Table

| In | P.S. | N.S. | Out |
|----|------|------|-----|
| 0 | S0 | S3 | 0 |
| 1 | S0 | S1 | 0 |
| 0 | S1 | S0 | 1 |
| 1 | S1 | S2 | 1 |
| 0 | S2 | S1 | 0 |
| 1 | S2 | S2 | 0 |
| 0 | S3 | S2 | 1 |
| 1 | S3 | S1 | 1 |

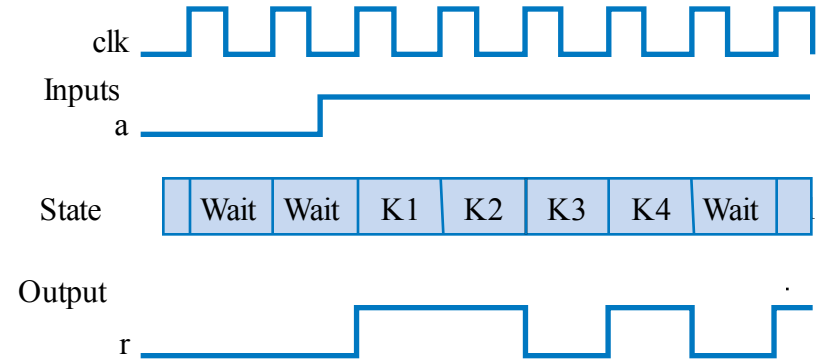
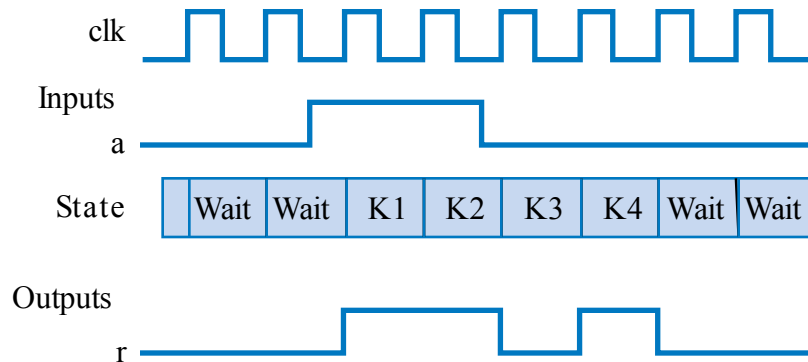
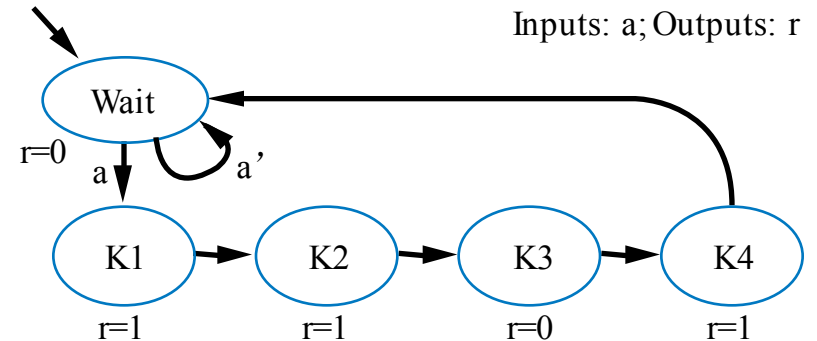
Example: Secure Car Key

- All new car keys contain a tiny computer chip
 - When car starts, car's computer (under engine hood) requests identifier from key
 - Key transmits identifier
 - If not, computer shuts off car
- FSM
 - Wait until computer requests ID ($a=1$)
 - Transmit ID (in this case, 1101)



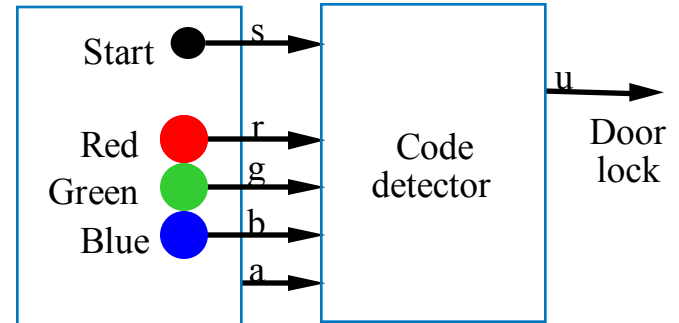
FSM Example: Secure Car Key (cont.)

- Timing diagrams show states and output values for different input waveforms



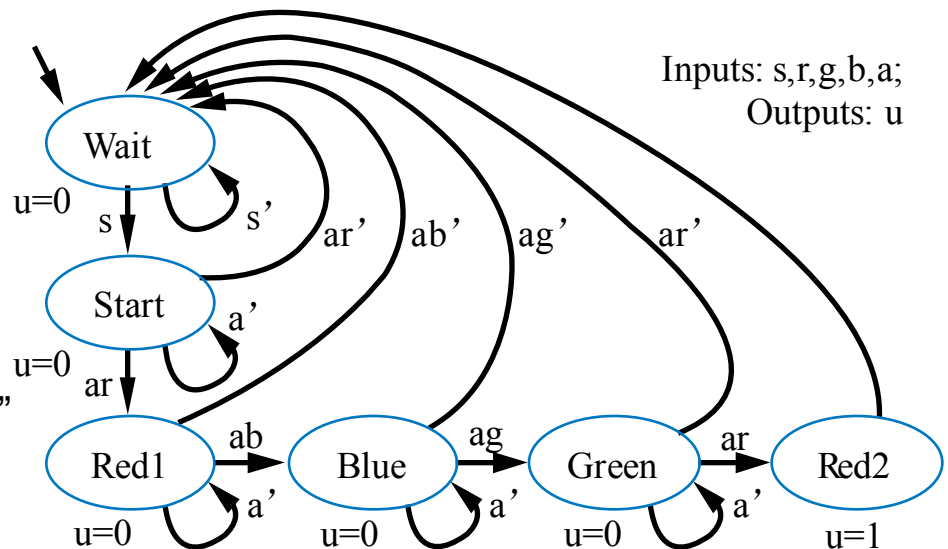
Example: Digital Lock

- Unlock door ($u=1$) only when buttons pressed in sequence:
- start, then red, blue, green, red
- Input buttons: s, r, g, b
- Input a indicates that some color button pressed



- FSM

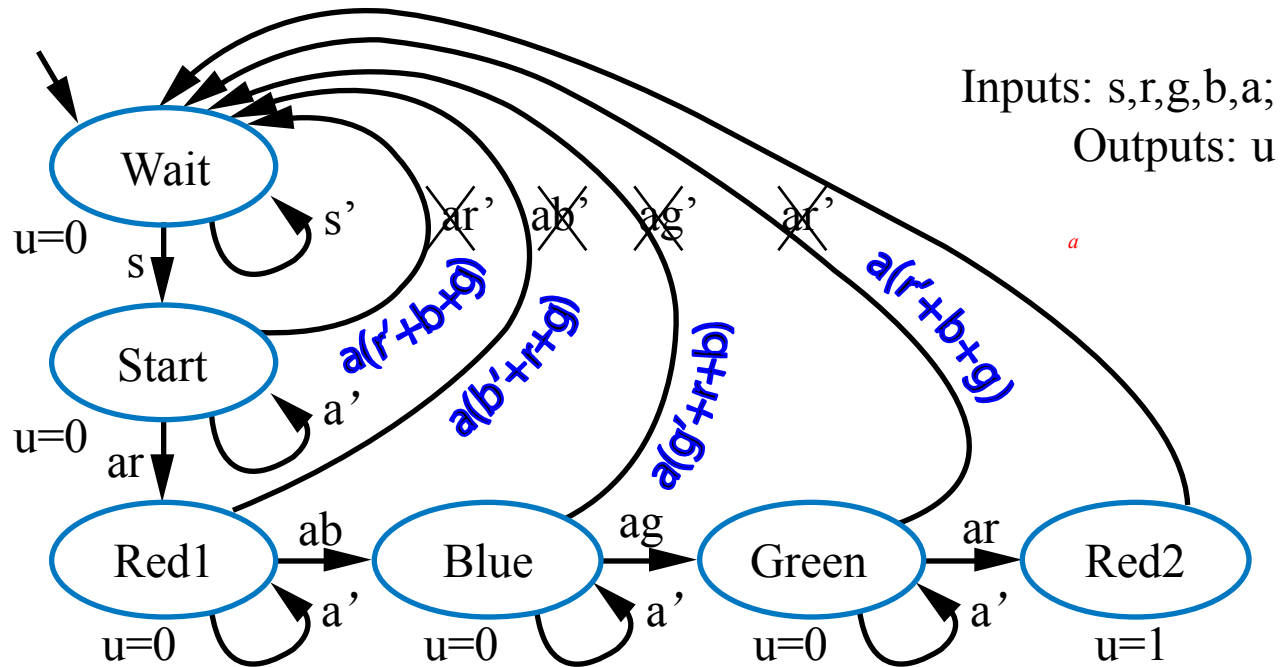
- Wait for start ($s=1$) in “Wait”
- Once started, go to “Start”, then
 - If see red, go to “Red1”
 - Then, if see blue, go to “Blue”
 - Then, if see green, go to “Green”
 - Then, if see red, go to “Red2”, and $u=1$
 - Wrong button at any step, return to “Wait”, without opening door



Q: Can you trick this FSM to open the door, without knowing the code?

A: Yes, hold all buttons simultaneously

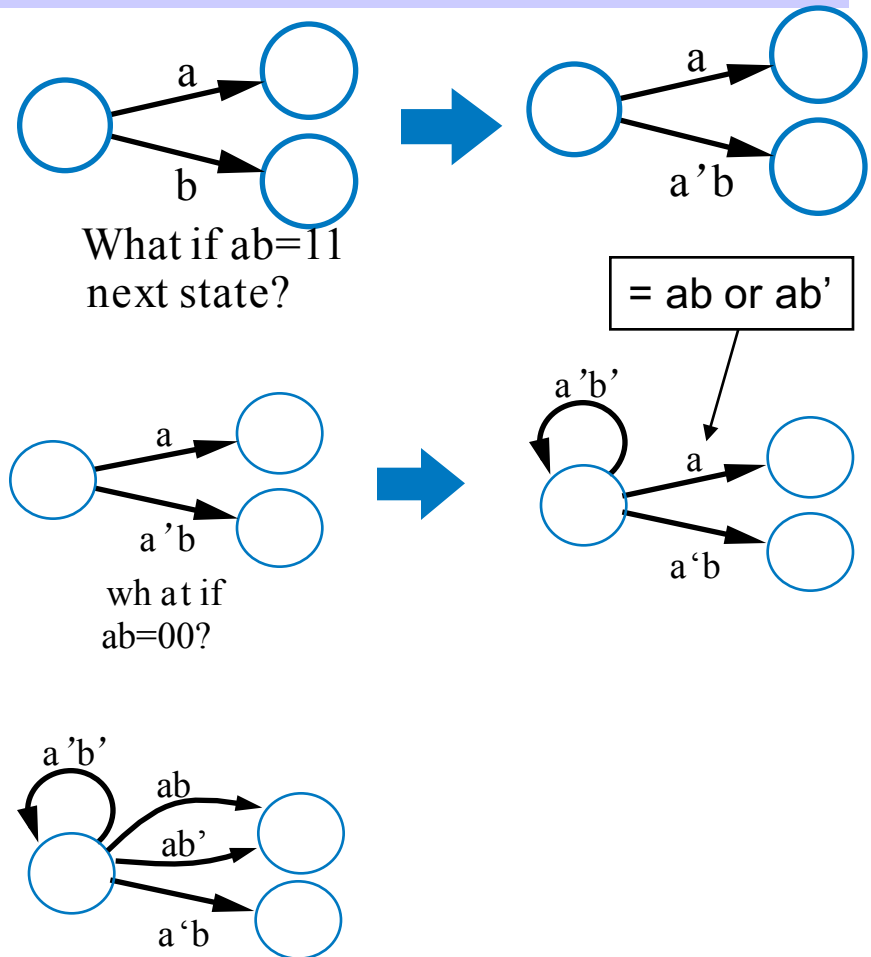
Improve FSM for Code Detector



- **New transition conditions** detect if wrong button pressed, returns to “Wait”

Common State Transition Property

- *Only* one condition should be true, among all transitions leaving a state
- *One* condition must be true
 - For any input combination
- All conditions must be considered when leaving a state



Pitfall is Common

- Recall code detector FSM

- Do the transitions obey the two required transition properties?

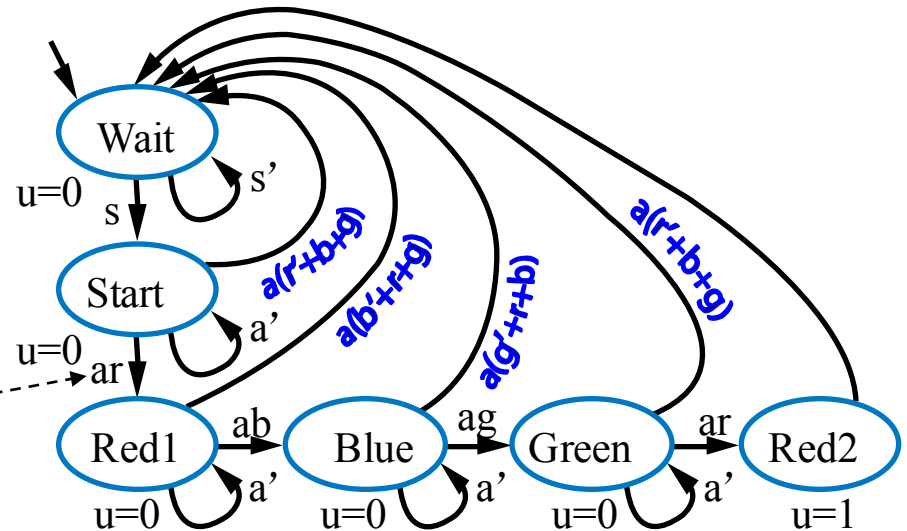
NO!

- How would it go wrong?

E.g. $arbg = 1111$

How to solve?

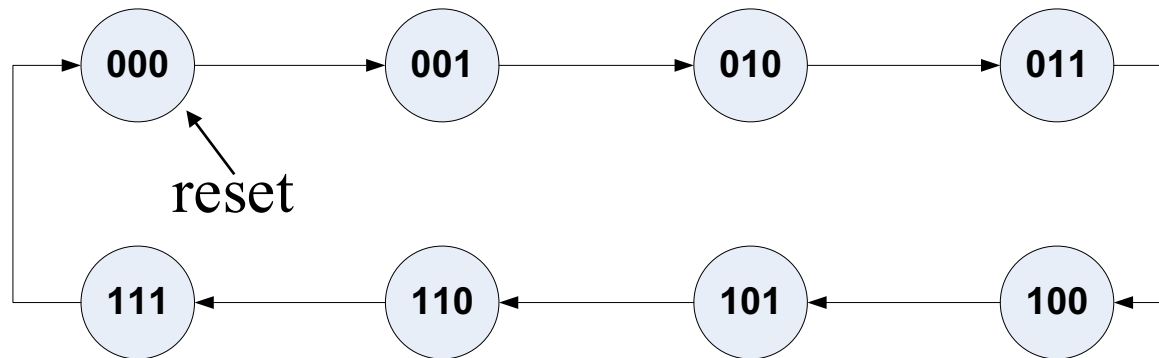
Answer: ar should be $arb'g'$
(likewise for ab , ag , ar)



Implementation of FSM

Example: Synchronous Binary Counter

- FSM that counts binary numbers – counter
- An n -bit binary counter can count in binary from 0 up to 2^n-1 and repeat
- An n -bit binary counter consists of n flip-flops
- All the flip-flops are synchronized to the same clock – synchronous counter
- May be implemented by different type of flip-flops
- Example: a 3-bit binary counter can count through this sequence



Synchronous Binary Counter Design

- An FSM (without external inputs)
 - State Table

| Present State | | | Next State | | |
|---------------|----|----|-----------------|-----------------|-----------------|
| Q2 | Q1 | Q0 | Q2 ⁺ | Q1 ⁺ | Q0 ⁺ |
| 0 | 0 | 0 | 0 | 0 | 1 |
| 0 | 0 | 1 | 0 | 1 | 0 |
| 0 | 1 | 0 | 0 | 1 | 1 |
| 0 | 1 | 1 | 1 | 0 | 0 |
| 1 | 0 | 0 | 1 | 0 | 1 |
| 1 | 0 | 1 | 1 | 1 | 0 |
| 1 | 1 | 0 | 1 | 1 | 1 |
| 1 | 1 | 1 | 0 | 0 | 0 |

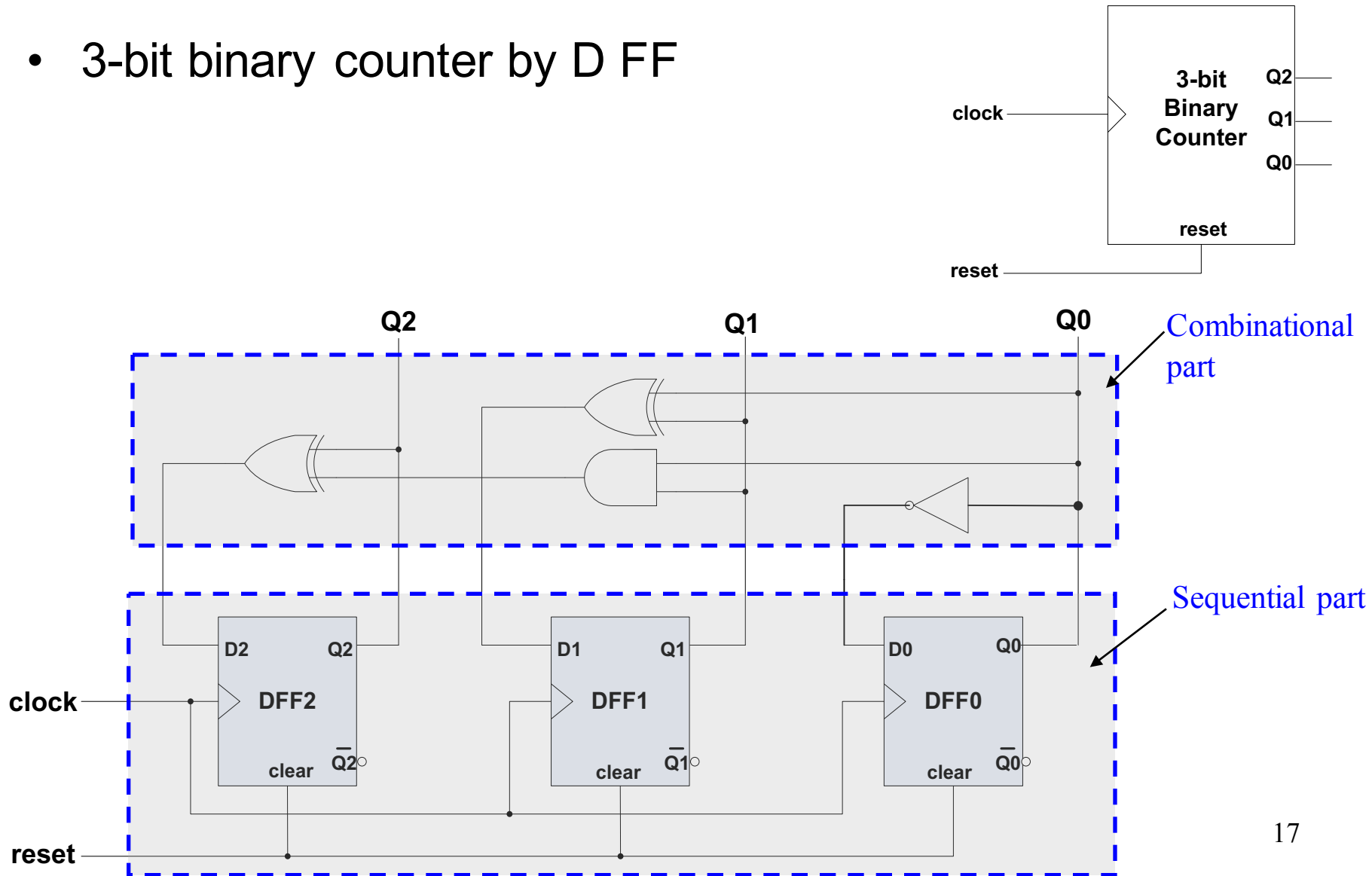
Counter Implemented with D Flip-Flop

- Use D flip flops to hold values: **$Q^+ = D$ upon active edge**
- Next state equations

| Present State | | | Next State | | | D flip flop input | | |
|---------------|----|----|-----------------|-----------------|-----------------|-------------------|----|----|
| Q2 | Q1 | Q0 | Q2 ⁺ | Q1 ⁺ | Q0 ⁺ | D2 | D1 | D0 |
| 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 1 |
| 0 | 0 | 1 | 0 | 1 | 0 | 0 | 1 | 0 |
| 0 | 1 | 0 | 0 | 1 | 1 | 0 | 1 | 1 |
| 0 | 1 | 1 | 1 | 0 | 0 | 1 | 0 | 0 |
| 1 | 0 | 0 | 1 | 0 | 1 | 1 | 0 | 1 |
| 1 | 0 | 1 | 1 | 1 | 0 | 1 | 1 | 0 |
| 1 | 1 | 0 | 1 | 1 | 1 | 1 | 1 | 1 |
| 1 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 |

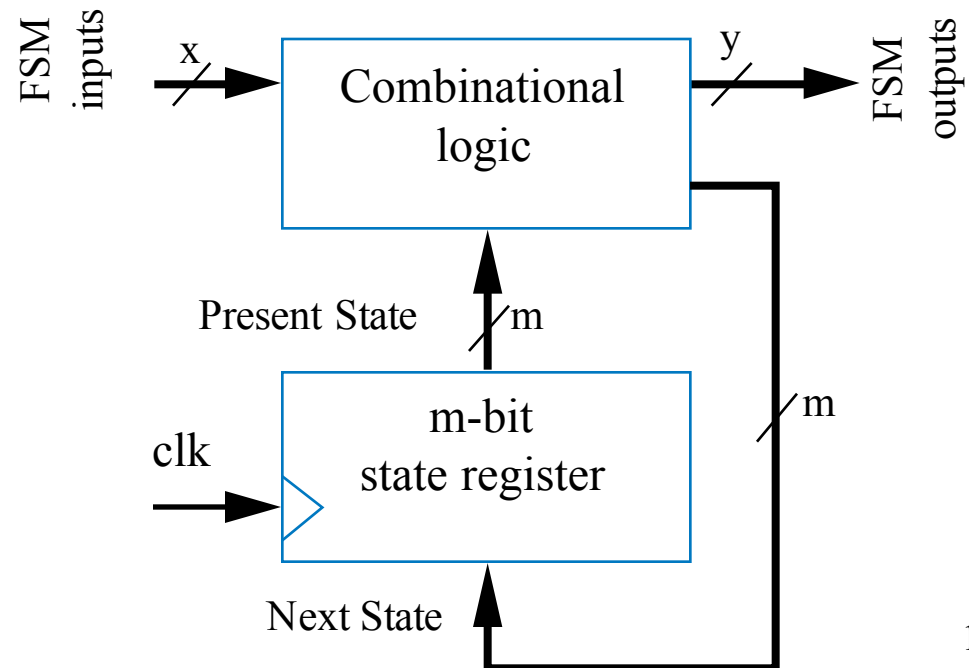
Synchronous Binary Counter with D Flip-Flop

- 3-bit binary counter by D FF



Standard FSM Architecture

- How to design sequential circuit?
 - Design as FSM
 - Use standard architecture
 - **State register** -- to store the present state
 - **Combinational logic** -- to compute outputs, and next state
 - Known as **controller**



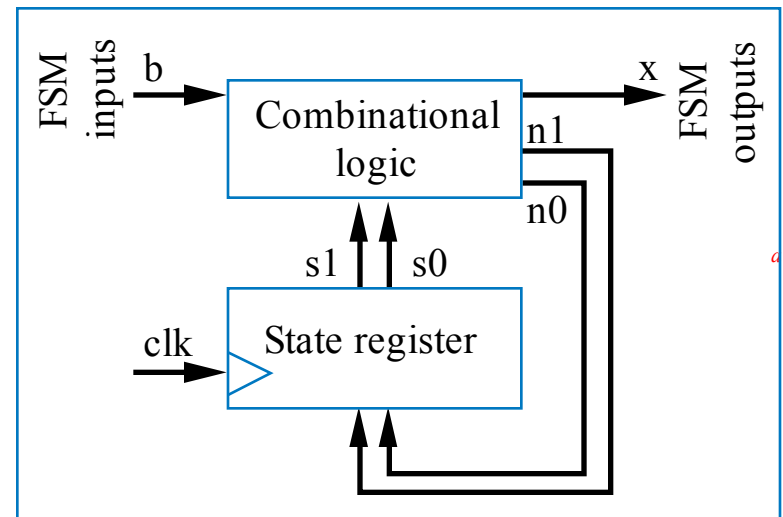
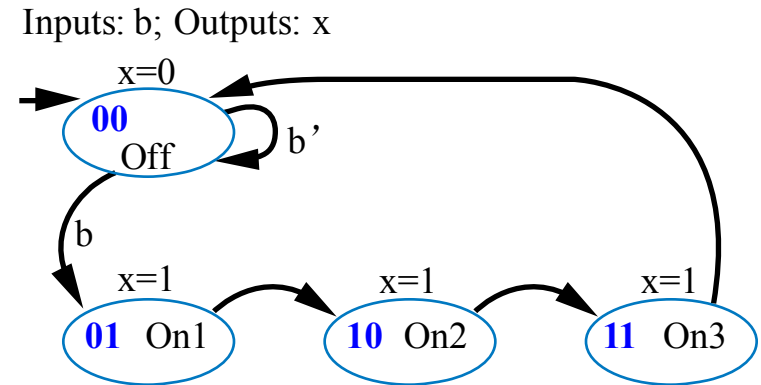
FSM (Controller) Design

- Five step FSM design process

| | Step | Description |
|--------|--|---|
| Step 1 | <i>Capture the FSM</i> | Create an FSM that describes the desired behavior of the controller. |
| Step 2 | <i>Create the architecture</i> | Create the standard architecture by using a state register of appropriate width, and combinational logic with inputs being the state register bits and the FSM inputs and outputs being the next state bits and the FSM outputs. |
| Step 3 | <i>Encode the states</i> | Assign a unique binary number to each state. Each binary number representing a state is known as an <i>encoding</i> . Any encoding will do as long as each state has a unique encoding. |
| Step 4 | <i>Create the state table</i> | Create a truth table for the combinational logic such that the logic will generate the correct FSM outputs and next state signals. Ordering the inputs with state bits first makes this truth table describe the state behavior, so the table is a state table. |
| Step 5 | <i>Implement the combinational logic</i> | Implement the combinational logic using any method. |

FSM Design Example: Push Button

- Step 1: Capture the FSM
 - Already done
- Step 2: Create architecture
 - 2-bit state register (for 4 states)
 - Input b, output x
 - Present state signals (s1, s0)
 - Next state signals (n1, n0)
- Step 3: Encode the states
 - Any encoding with unique representation for each state will work



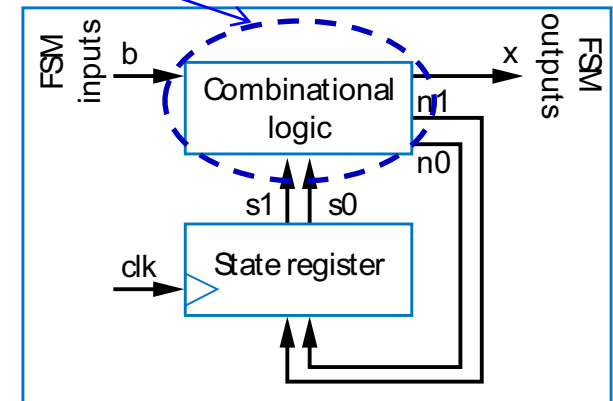
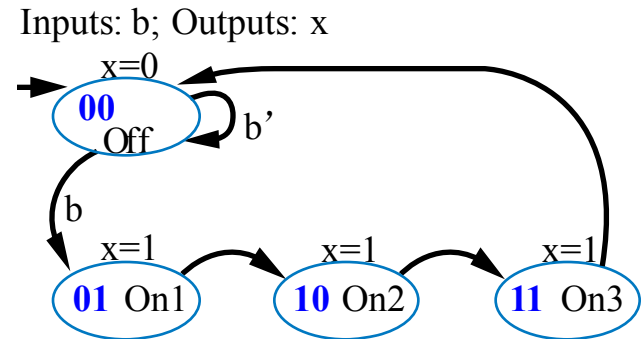
FSM Design Example: Push Button (cont.)

- Step 4: Create state table

| | Inputs | | | Outputs | | |
|------------|---------------|---|---|---------|------------|---|
| | Present state | | b | x | Next state | |
| <i>Off</i> | 0 | 0 | 0 | 0 | 0 | 0 |
| | 0 | 0 | 1 | 0 | 0 | 1 |
| <i>On1</i> | 0 | 1 | 0 | 1 | 1 | 0 |
| | 0 | 1 | 1 | 1 | 1 | 0 |
| <i>On2</i> | 1 | 0 | 0 | 1 | 1 | 1 |
| | 1 | 0 | 1 | 1 | 1 | 1 |
| <i>On3</i> | 1 | 1 | 0 | 1 | 0 | 0 |
| | 1 | 1 | 1 | 1 | 0 | 0 |

Combinational Logic
Inputs

Combinational Logic
Outputs



FSM Design Example: Push Button (cont.)

- Step 5: Implement combinational logic

| Inputs | | | | Outputs | | |
|------------|----|----|---|---------|----|----|
| | s1 | s0 | b | x | n1 | n0 |
| <i>Off</i> | 0 | 0 | 0 | 0 | 0 | 0 |
| | 0 | 0 | 1 | 0 | 0 | 1 |
| <i>On1</i> | 0 | 1 | 0 | 1 | 1 | 0 |
| | 0 | 1 | 1 | 1 | 1 | 0 |
| <i>On2</i> | 1 | 0 | 0 | 1 | 1 | 1 |
| | 1 | 0 | 1 | 1 | 1 | 1 |
| <i>On3</i> | 1 | 1 | 0 | 1 | 0 | 0 |
| | 1 | 1 | 1 | 1 | 0 | 0 |

$$x = s1 + s0$$

$$n1 = s1's0 + s1s0'$$

$$n0 = s0'b + s1s0'$$

x

| | | | | |
|----|----|----|----|----|
| | s0 | b | | |
| s1 | 00 | 01 | 11 | 10 |
| 0 | 0 | 0 | 1 | 1 |
| 1 | 1 | 1 | 1 | 1 |

n1

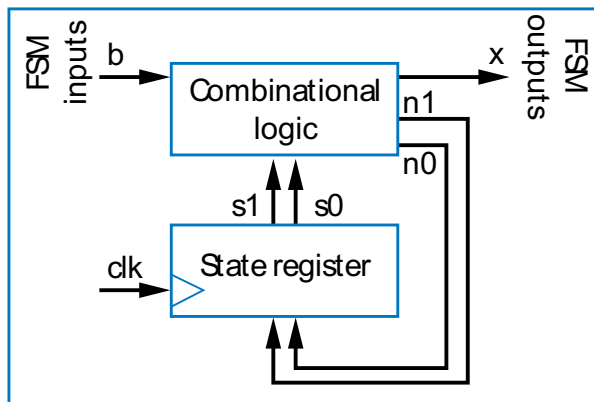
| | | | | |
|----|----|----|----|----|
| | s0 | b | | |
| s1 | 00 | 01 | 11 | 10 |
| 0 | 0 | 0 | 1 | 1 |
| 1 | 1 | 1 | 0 | 0 |

n0

| | | | | |
|----|----|----|----|----|
| | s0 | b | | |
| s1 | 00 | 01 | 11 | 10 |
| 0 | 0 | 1 | 0 | 0 |
| 1 | 1 | 1 | 0 | 0 |

FSM Design Example: Push Button (cont.)

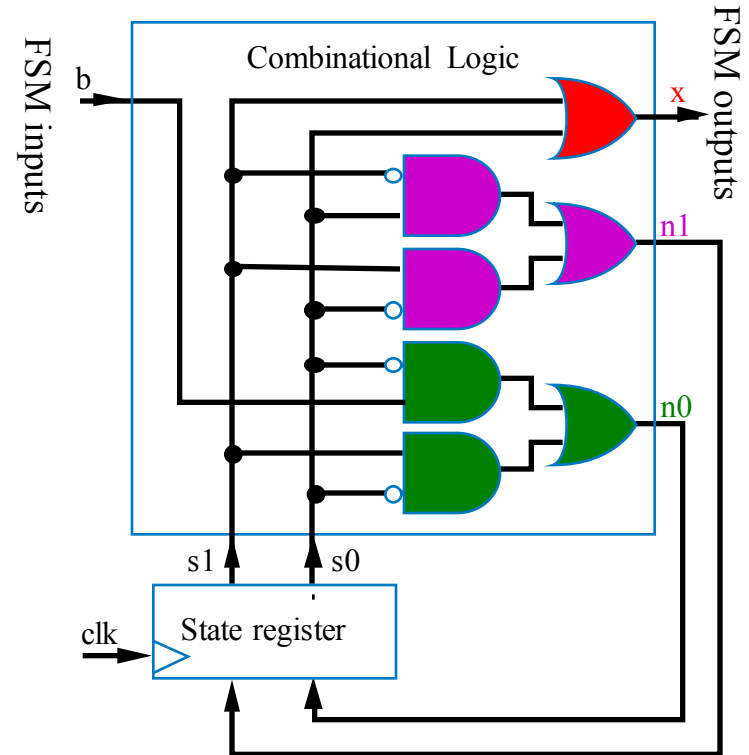
- Step 5: Implement combinational logic (cont)



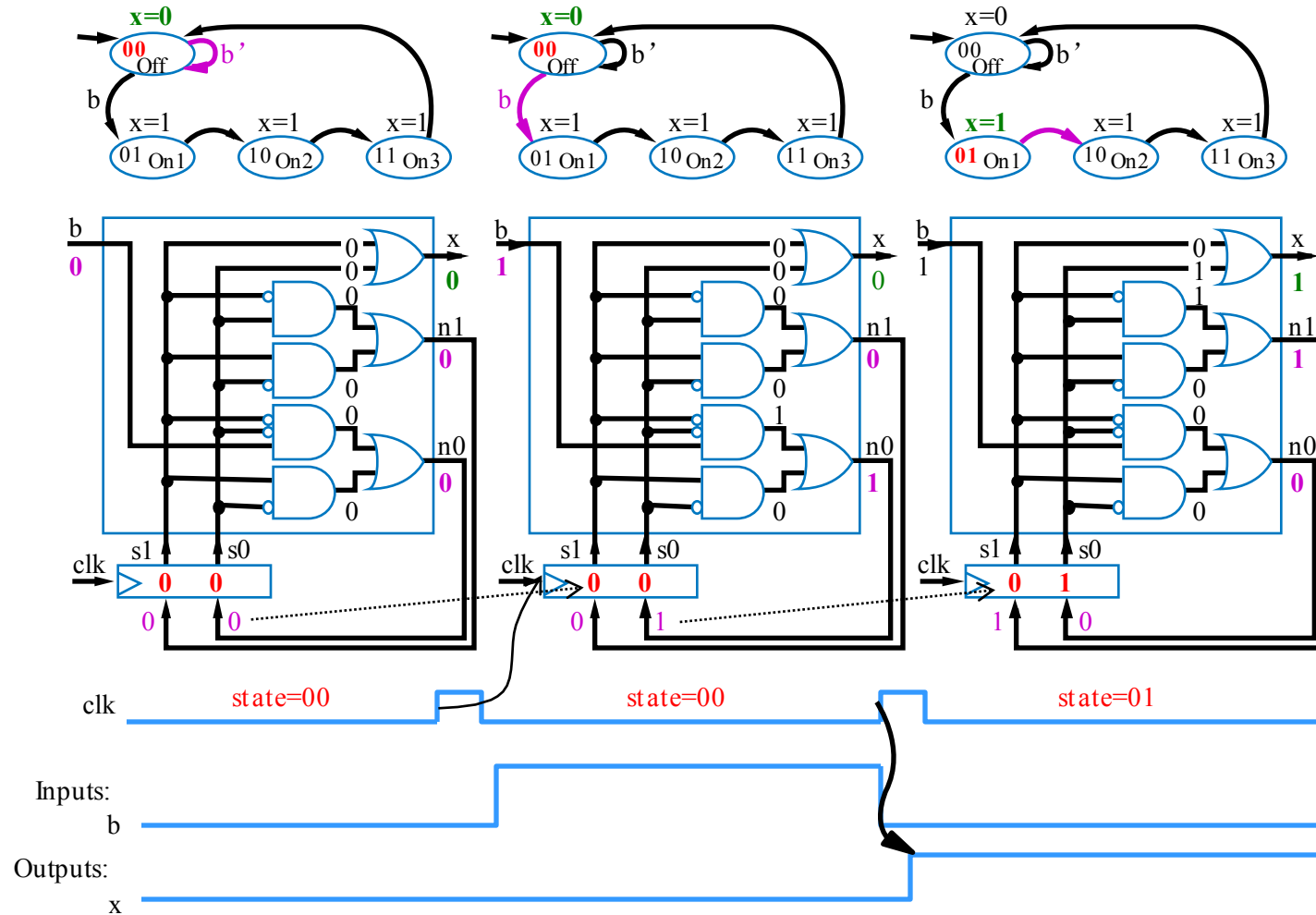
$$x = s1 + s0$$

$$n1 = s1's0 + s1s0'$$

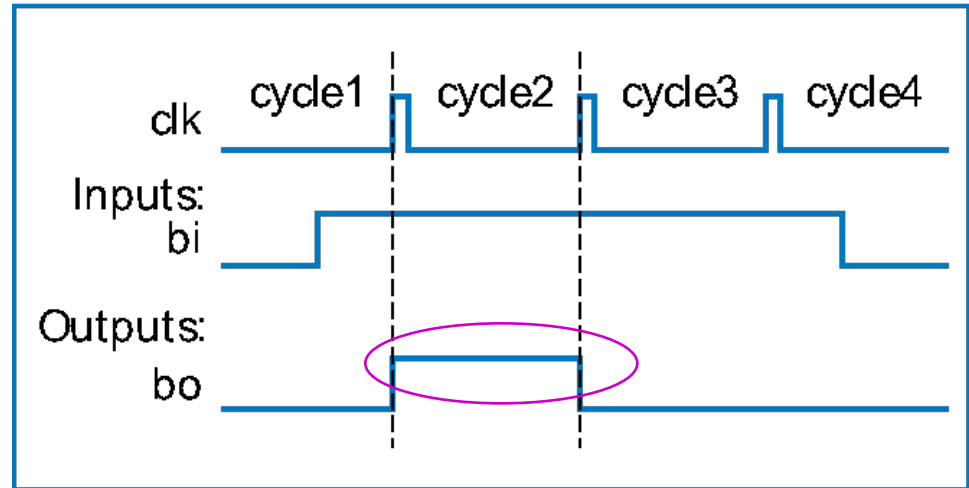
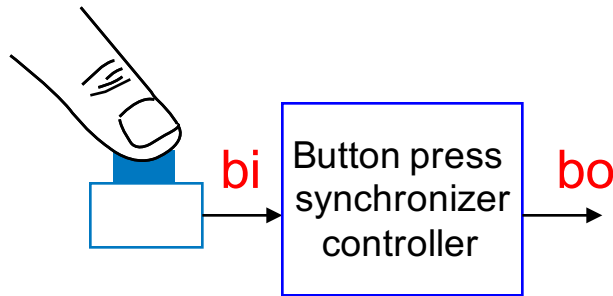
$$n0 = s0'b + s1s0'$$



Understanding the Controller's Behavior

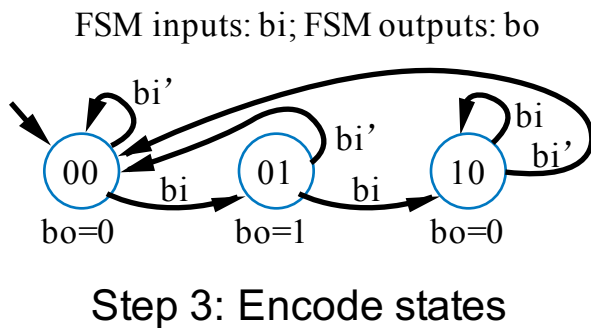
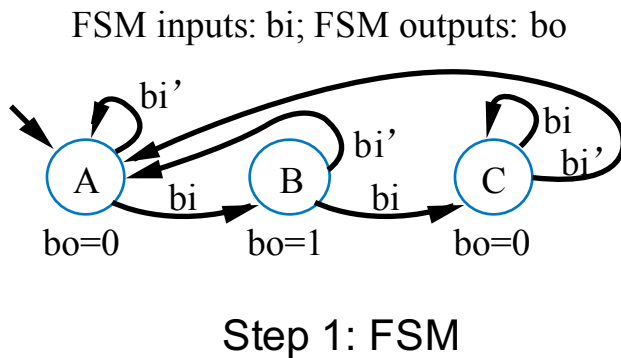


FSM Design Example: Button Press Synchronizer



- Want simple sequential circuit that converts button press to single clock cycle duration, regardless of length of time that button actually pressed

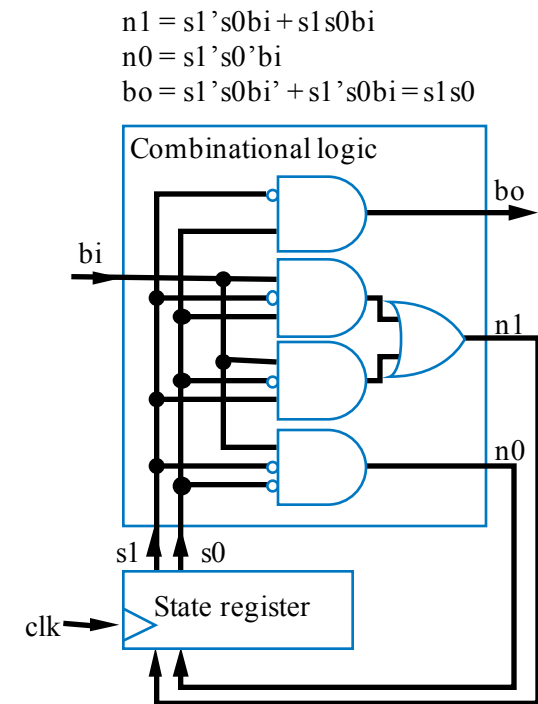
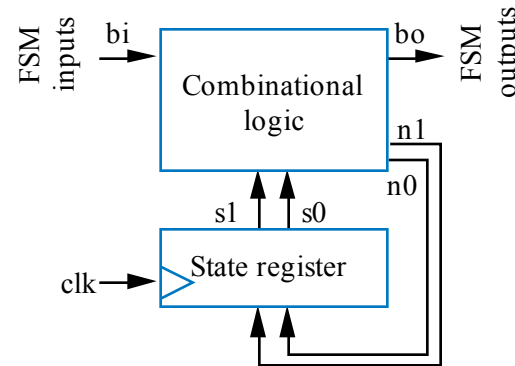
FSM Design Example: Button Press Synchronizer (cont.)



| | Combinational logic Inputs | | | Outputs | | |
|--------|-------------------------------|------|------|---------|------|------|
| | $s1$ | $s0$ | bi | $n1$ | $n0$ | bo |
| A | 0 | 0 | 0 | 0 | 0 | 0 |
| | 0 | 0 | 1 | 0 | 1 | 0 |
| B | 0 | 1 | 0 | 0 | 0 | 1 |
| | 0 | 1 | 1 | 1 | 0 | 1 |
| C | 1 | 0 | 0 | 0 | 0 | 0 |
| | 1 | 0 | 1 | 1 | 0 | 0 |
| unused | 1 | 1 | 0 | 0 | 0 | 0 |
| | 1 | 1 | 1 | 0 | 0 | 0 |

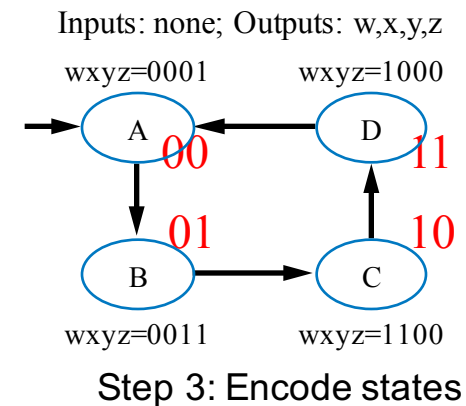
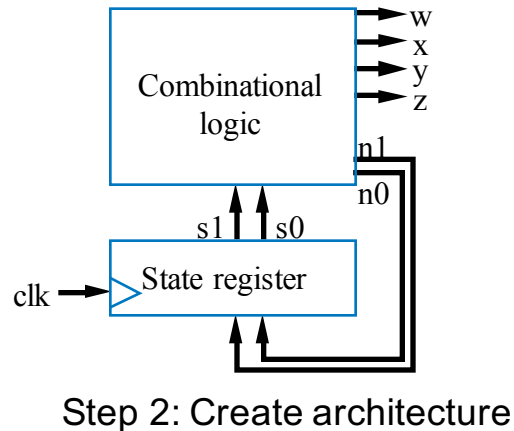
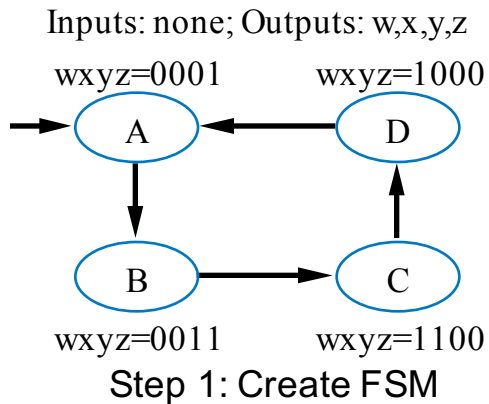
Step 4: State table

may be 'x'



FSM Example: Sequence Generator

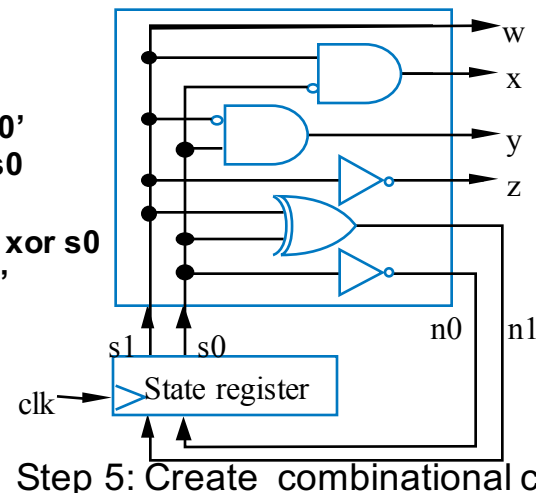
- Want generate sequence 0001, 0011, 1100, 1000, (repeat)
 - Each value for one clock cycle



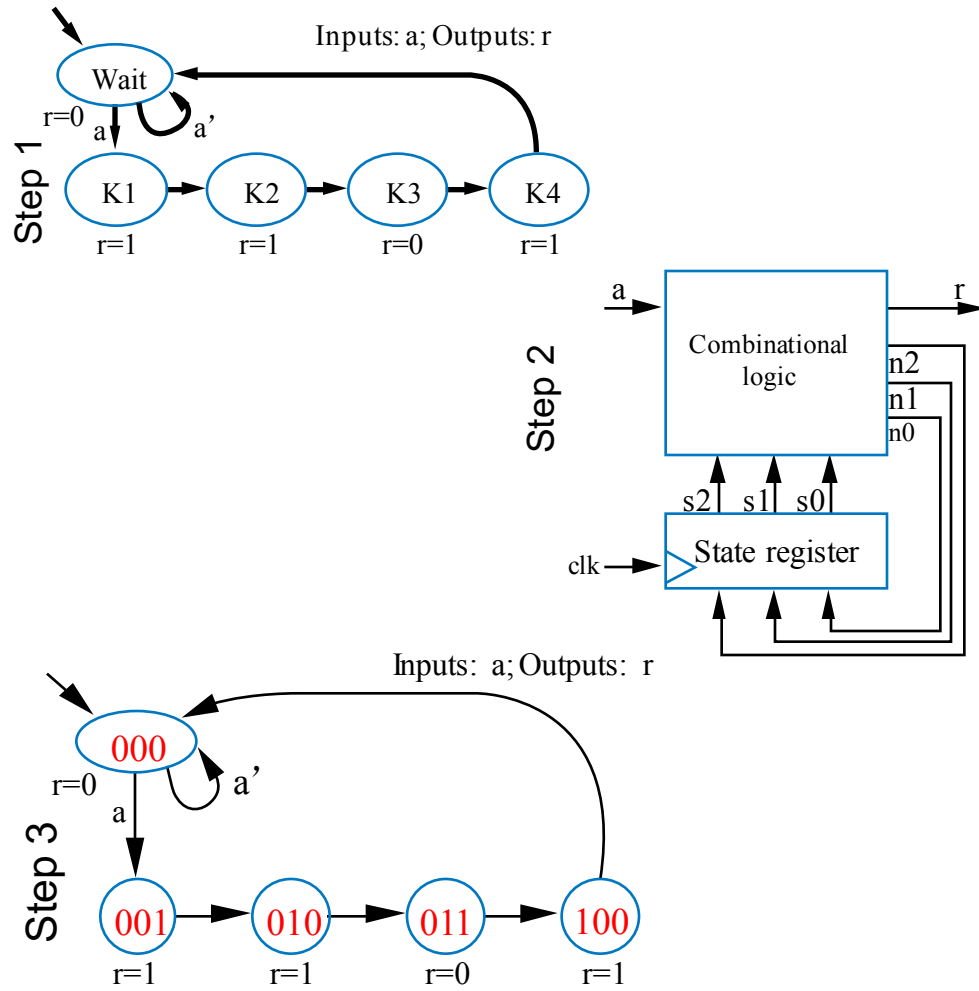
| | Inputs | | Outputs | | | | | |
|---|--------|----|---------|---|---|---|----|----|
| | s1 | s0 | w | x | y | z | n1 | n0 |
| A | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 1 |
| B | 0 | 1 | 0 | 0 | 1 | 1 | 1 | 0 |
| C | 1 | 0 | 1 | 1 | 0 | 0 | 1 | 1 |
| D | 1 | 1 | 1 | 0 | 0 | 0 | 0 | 0 |

Step 4: Create state table

$$\begin{aligned}
 w &= s1 \\
 x &= s1s0' \\
 y &= s1's0 \\
 z &= s1' \\
 n1 &= s1 \text{ xor } s0 \\
 n0 &= s0'
 \end{aligned}$$



FSM Example: Secure Car Key



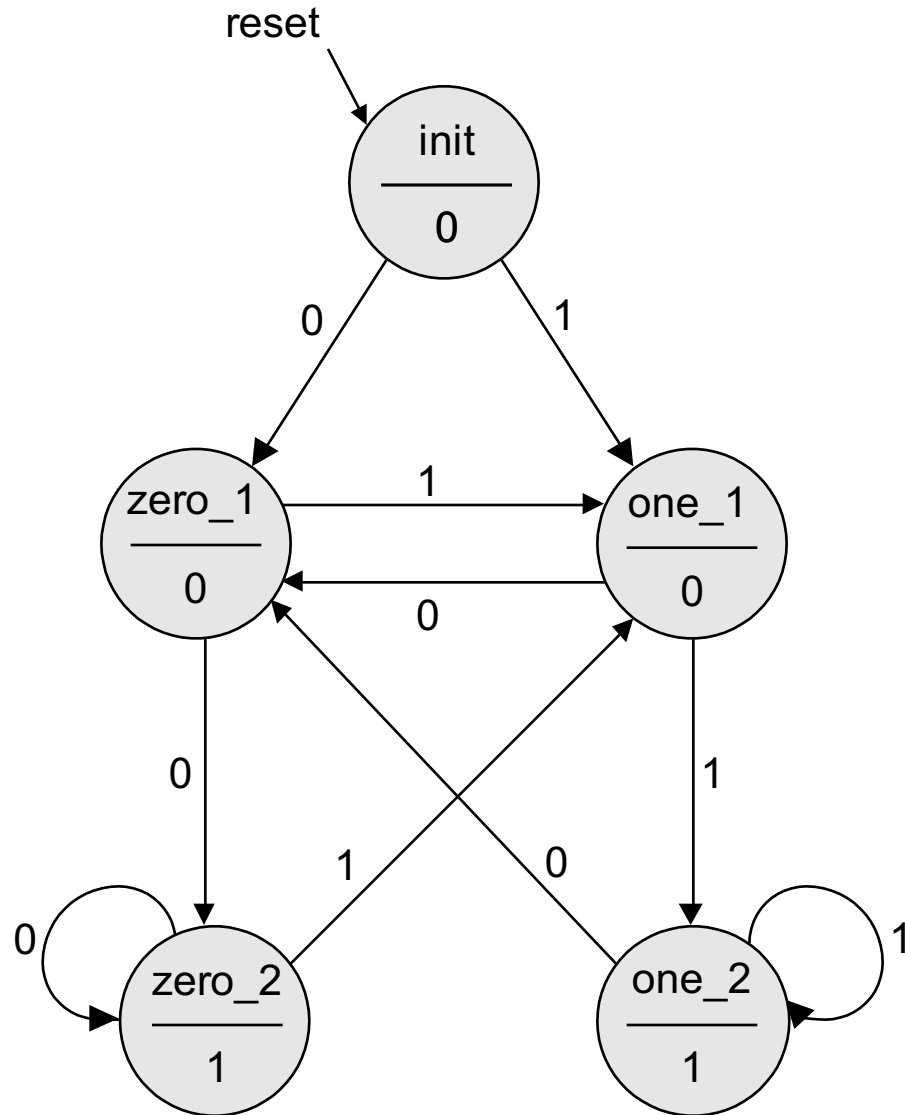
We omit Step 5

| | Inputs | | | | Outputs | | | |
|--------|--------|----|----|---|---------|----|----|----|
| | s2 | s1 | s0 | a | r | n2 | n1 | n0 |
| Wait | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 1 |
| K1 | 0 | 0 | 1 | 0 | 1 | 0 | 1 | 0 |
| | 0 | 0 | 1 | 1 | 1 | 0 | 1 | 0 |
| K2 | 0 | 1 | 0 | 0 | 1 | 0 | 1 | 1 |
| | 0 | 1 | 0 | 1 | 1 | 0 | 1 | 1 |
| K3 | 0 | 1 | 1 | 0 | 0 | 1 | 0 | 0 |
| | 0 | 1 | 1 | 1 | 0 | 1 | 0 | 0 |
| K4 | 1 | 0 | 0 | 0 | 1 | 0 | 0 | 0 |
| | 1 | 0 | 0 | 1 | 1 | 0 | 0 | 0 |
| Unused | 1 | 0 | 1 | 0 | 0 | 0 | 0 | 0 |
| | 1 | 0 | 1 | 1 | 0 | 0 | 0 | 0 |
| | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 |
| | 1 | 1 | 0 | 1 | 0 | 0 | 0 | 0 |
| | 1 | 1 | 1 | 0 | 0 | 0 | 0 | 0 |
| | 1 | 1 | 1 | 1 | 0 | 0 | 0 | 0 |

Step 4

may be 'x'

Verilog Modeling of FSM



```

Module example_FSM (clock, reset, in_bit, out_bit);
  input          clock, reset, in_bit;
  output         out_bit;

  reg [2:0]      curr_state, next_state;

  parameter     init      = 3'b000;
  parameter     zero_1    = 3'b001;
  parameter     one_1     = 3'b010;
  parameter     zero_2    = 3'b011;
  parameter     one_2     = 3'b100;

```

```

always @ (posedge clock or posedge reset)
  if (reset == 1) curr_state <= init;
  else
    curr_state <= next_state;

```

State register

```

always @ (curr_state or in_bit)
  case (curr_state)
    init: if (in_bit == 0) next_state <= zero_1; else
      if (in_bit == 1) next_state <= one_1; else
        next_state <= init;

```

Combinational logic
for next state

```

zero_1: if (in_bit == 0) next_state <= zero_2; else
        if (in_bit == 1) next_state <= one_1; else
                next_state <= init;
zero_2: if (in_bit == 0) next_state <= zero_2; else
        if (in_bit == 1) next_state <= one_1; else
                next_state <= init;
one_1:  if (in_bit == 0) next_state <= zero_1; else
        if (in_bit == 1) next_state <= one_2; else
                next_state <= init;
one_2:  if (in_bit == 0) next_state <= zero_1; else
        if (in_bit == 1) next_state <= one_2; else
                next_state <= init;
default:
        next_state <= init;
endcase

```

```

assign out_bit = ((curr_state==zero_2) || (curr_state==one_2))
                  ? 1 : 0;

```

```

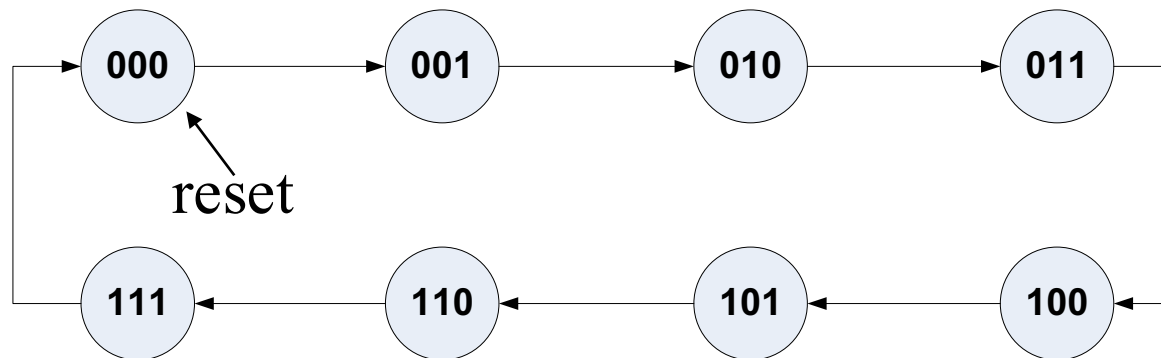
endmodule

```

Combinational logic for FSM outputs

Revisit: Binary Counter as an FSM

- FSM that counts binary numbers – counter
- An n -bit binary counter can count in binary from 0 up to 2^n-1 and repeat
- An n -bit binary counter consists of n flip-flops
- All the flip-flops are synchronized to the same clock – synchronous counter
- May be implemented by different type of flip-flops
- Example: a 3-bit binary counter can count through this sequence



Implement FSM with T Flip-Flop


- Characteristic table and equation of T-FF

| T | Q ⁺ | |
|---|----------------|------------|
| 0 | Q | No Change |
| 1 | Q' | Complement |

$$Q^+ = T \oplus Q$$

- Excitation table of T-FF

| Q | Q ⁺ | | T |
|---|----------------|-----------|---|
| 0 | 0 | No Change | 0 |
| 0 | 1 | Toggle | 1 |
| 1 | 0 | Toggle | 1 |
| 1 | 1 | No Change | 0 |



| Q | Q ⁺ | | T |
|---|----------------|-----------|---|
| X | Q | No Change | 0 |
| X | Q' | Toggle | 1 |

Implement FSM with T Flip-Flop

- State Table with T input

Intermediate columns

| Present State | | | Next State | | | T Input | | |
|---------------|----|----|-----------------|-----------------|-----------------|---------|----|----|
| Q2 | Q1 | Q0 | Q2 ⁺ | Q1 ⁺ | Q0 ⁺ | T2 | T1 | T0 |
| 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 1 |
| 0 | 0 | 1 | 0 | 1 | 0 | 0 | 1 | 1 |
| 0 | 1 | 0 | 0 | 1 | 1 | 0 | 0 | 1 |
| 0 | 1 | 1 | 1 | 0 | 0 | 1 | 1 | 1 |
| 1 | 0 | 0 | 1 | 0 | 1 | 0 | 0 | 1 |
| 1 | 0 | 1 | 1 | 1 | 0 | 0 | 1 | 1 |
| 1 | 1 | 0 | 1 | 1 | 1 | 0 | 0 | 1 |
| 1 | 1 | 1 | 0 | 0 | 0 | 1 | 1 | 1 |

Implement FSM with T Flip-Flop

- T input equations in terms of Qs can be found from the state table

T2

| Q2 | Q1Q0 | | | |
|----|------|----|----|----|
| | 00 | 01 | 11 | 10 |
| 0 | 0 | 0 | 1 | 0 |
| 1 | 0 | 0 | 1 | 0 |

$$T2 = Q1Q0$$

T1

| Q2 | Q1Q0 | | | |
|----|------|----|----|----|
| | 00 | 01 | 11 | 10 |
| 0 | 0 | 1 | 1 | 0 |
| 1 | 0 | 1 | 1 | 0 |

$$T1 = Q0$$

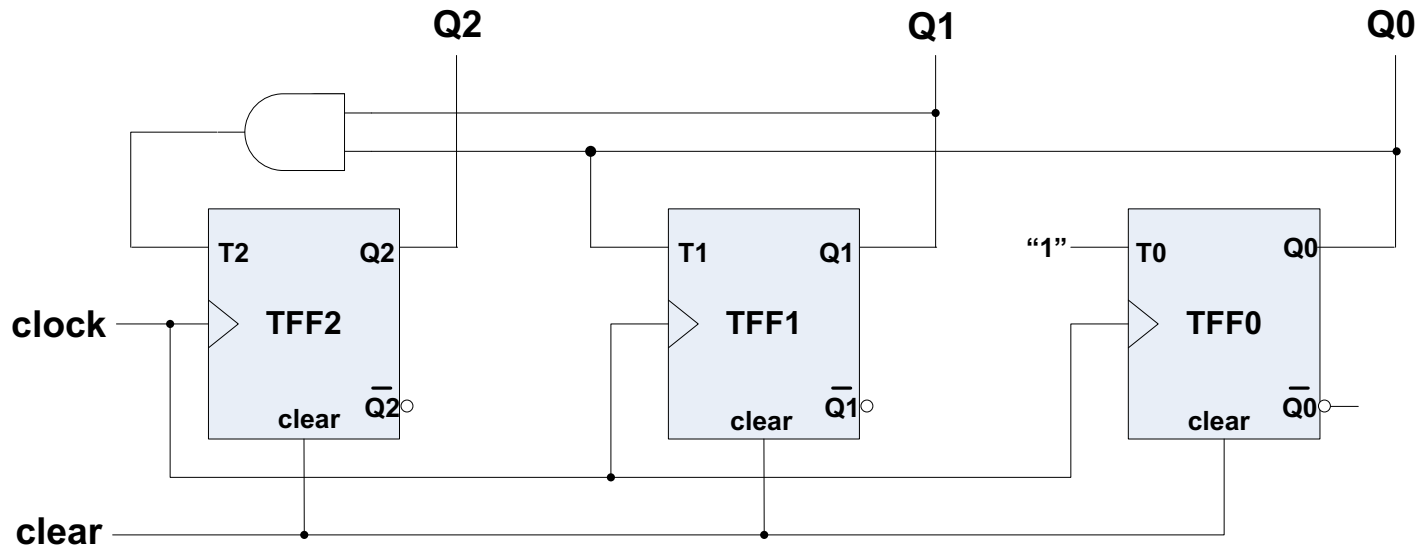
T0

| Q2 | Q1Q0 | | | |
|----|------|----|----|----|
| | 00 | 01 | 11 | 10 |
| 0 | 1 | 1 | 1 | 1 |
| 1 | 1 | 1 | 1 | 1 |

$$T0 = 1$$

Implement FSM with T Flip-Flop

- 3-bit binary counter by T FF



Implement FSM with JK Flip-Flop

- Characteristic table and equation of JK-FF

| J | K | Q ⁺ | Action |
|---|---|----------------|--------|
| 0 | 0 | Q | Hold |
| 0 | 1 | 0 | Reset |
| 1 | 0 | 1 | Set |
| 1 | 1 | Q' | Toggle |

$$Q^+ = JQ' + K'Q$$

- Excitation table of JK-FF

| Q | Q ⁺ | Action | J | K | J | K |
|---|----------------|--------------|-----|-----|---|---|
| 0 | 0 | Reset/Hold | 0/0 | 1/0 | 0 | X |
| 0 | 1 | Set/Toggle | 1/1 | 0/1 | 1 | X |
| 1 | 0 | Reset/Toggle | 0/1 | 1/1 | X | 1 |
| 1 | 1 | Set/Hold | 1/0 | 0/0 | X | 0 |

Implement FSM with JK Flip-Flop

- State Table with JK input

Intermediate columns

| Present State | | | Next State | | | JK Inputs | | | | | |
|---------------|----|----|-----------------|-----------------|-----------------|-----------|----|----|----|----|----|
| Q2 | Q1 | Q0 | Q2 ₊ | Q1 ₊ | Q0 ₊ | J2 | K2 | J1 | K1 | J0 | K0 |
| 0 | 0 | 0 | 0 | 0 | 1 | 0 | X | 0 | X | 1 | X |
| 0 | 0 | 1 | 0 | 1 | 0 | 0 | X | 1 | X | X | 1 |
| 0 | 1 | 0 | 0 | 1 | 1 | 0 | X | X | 0 | 1 | X |
| 0 | 1 | 1 | 1 | 0 | 0 | 1 | X | X | 1 | X | 1 |
| 1 | 0 | 0 | 1 | 0 | 1 | X | 0 | 0 | X | 1 | X |
| 1 | 0 | 1 | 1 | 1 | 0 | X | 0 | 1 | X | X | 1 |
| 1 | 1 | 0 | 1 | 1 | 1 | X | 0 | X | 0 | 1 | X |
| 1 | 1 | 1 | 0 | 0 | 0 | X | 1 | X | 1 | X | 1 |

Implement FSM with JK Flip-Flop

- J-K Input equations

J2

| | | Q1Q0 | | | |
|----|---|------|----|----|----|
| | | 00 | 01 | 11 | 10 |
| Q2 | 0 | 0 | 0 | 1 | 0 |
| | 1 | X | X | X | X |

$$J2 = Q1Q0$$

J1

| | | Q1Q0 | | | |
|----|---|------|----|----|----|
| | | 00 | 01 | 11 | 10 |
| Q2 | 0 | 0 | 1 | X | X |
| | 1 | 0 | 1 | X | X |

$$J1 = Q0$$

J0

| | | Q1Q0 | | | |
|----|---|------|----|----|----|
| | | 00 | 01 | 11 | 10 |
| Q2 | 0 | 1 | X | X | 1 |
| | 1 | 1 | X | X | 1 |

$$J0 = 1$$

K2

| | | Q1Q0 | | | |
|----|---|------|----|----|----|
| | | 00 | 01 | 11 | 10 |
| Q2 | 0 | X | X | X | X |
| | 1 | 0 | 0 | 1 | 0 |

$$K2 = Q1Q0 = J2$$

K1

| | | Q1Q0 | | | |
|----|---|------|----|----|----|
| | | 00 | 01 | 11 | 10 |
| Q2 | 0 | X | X | 1 | 0 |
| | 1 | X | X | 1 | 0 |

$$K1 = Q0 = J1$$

K0

| | | Q1Q0 | | | |
|----|---|------|----|----|----|
| | | 00 | 01 | 11 | 10 |
| Q2 | 0 | X | 1 | 1 | X |
| | 1 | X | 1 | 1 | X |

$$K0 = 1 = J0$$

Implement FSM with JK Flip-Flop

- Circuit diagram

