

Homework 2 Solutions

1. .

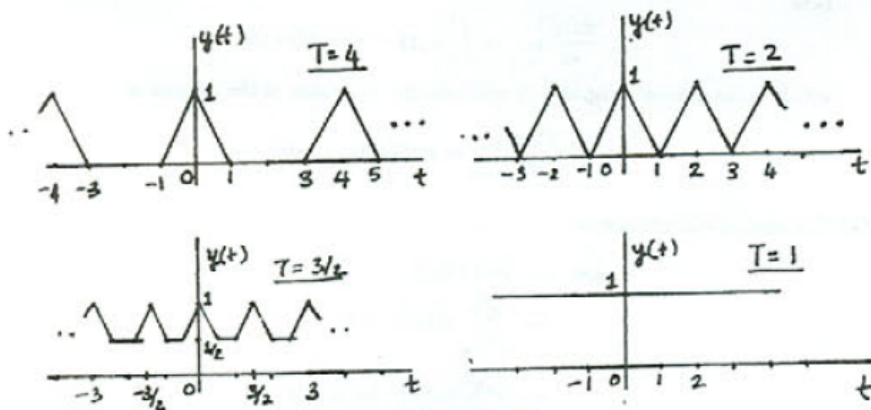
(a) Correct statement: If $y(t) = h(t) * x(t)$ then $y(t-3) = h(t) * x(t-3)$.Proof: $y(t) = \int_{-\infty}^{\infty} h(\tau)x(t-\tau) d\tau$ so $y(t-3) = \int_{-\infty}^{\infty} h(\tau)x(t-3-\tau) d\tau = h(t) * x(t-3)$.(b) Incorrect statement: If $y(t) = h(t) * x(t)$ then $y(t-3) \stackrel{\text{not!}}{=} h(t-3) * x(t-3)$. Example: $h(t) = x(t) = \delta(t)$. Then $y(t) = \delta(t)$ so $y(t-3) = \delta(t-3)$. But $h(t-3) * x(t-3) = \delta(t-3) * \delta(t-3) = \delta(t-6) \neq \delta(t-3)$.(c) Correct statement: If $y(t) = h(t) \cdot x(t)$ then $y(t-3) = h(t-3) \cdot x(t-3)$, by definition of the product of two signals. But $y(t-3) \neq h(t) \cdot x(t-3)$ again by considering $h(t) = x(t) = \delta(t)$.

2. .

(a) $h(t-\tau)$ is nonzero over $t-a < \tau < t-b$ and $x(\tau)$ is nonzero over $c < \tau < d$. The integral of their product is nonzero when $t-a > c$ and $t-b < d$, so that the intervals overlap. Thus $a+c < t < b+d$ is the range of values of t for which $y(t)$ is possibly nonzero.(b) $a=1, b=3, c=-5, d=-1$ so $-4 < t < +2$.For $t-1 > -5$ but $t-3 < -5$, $y(t) = \int_{-5}^{t-1} 1 dt = t+4$. For $t-3 > -5$ but $t-1 < -1$, $y(t) = \int_{t-3}^{t-1} 1 dt = 2$.For $t-3 < -1$ but $t-1 > -1$, $y(t) = \int_{t-3}^{-1} 1 dt = 2-t$. So

$$y(t) = \begin{cases} t+4, & -4 < t < -2 \\ 2, & -2 < t < 0 \\ 2-t, & 0 < t < 2 \\ 0, & \text{otherwise.} \end{cases}$$

3. The sketches are shown below:



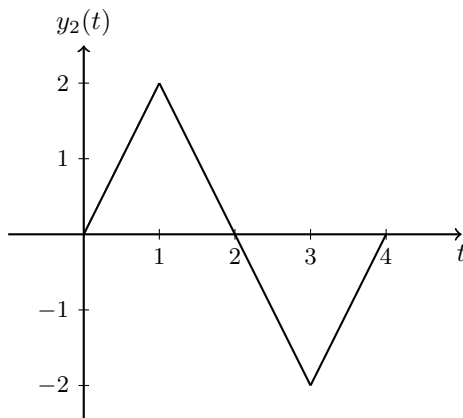
$$4. \quad (a) \int_{-\infty}^{\infty} y(t) dt = \int_{-\infty}^{\infty} \left[\int_{-\infty}^{\infty} h(\tau)x(t-\tau) d\tau \right] dt = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} h(\tau)x(t-\tau) dt d\tau = \int_{-\infty}^{\infty} h(\tau) \left[\int_{-\infty}^{\infty} x(t-\tau) dt \right] d\tau = \int_{-\infty}^{\infty} h(\tau) \left[\int_{-\infty}^{\infty} x(t^*) dt^* \right] d\tau = \left[\int_{-\infty}^{\infty} x(t) dt \right] \left[\int_{-\infty}^{\infty} h(\tau) d\tau \right].$$

$$(b) \frac{d}{dt} y(t) = \frac{d}{dt} \left[\int_{-\infty}^{\infty} h(\tau)x(t-\tau) d\tau \right] = \int_{-\infty}^{\infty} h(\tau) \frac{d}{dt} x(t-\tau) d\tau = h(t) * \left(\frac{d}{dt} x(t) \right).$$

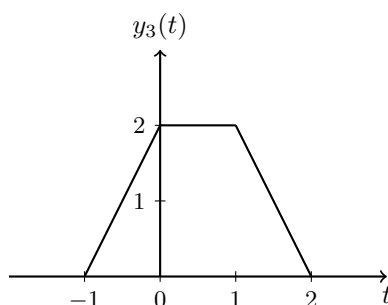
The other part of the statement was very similar.

$$(c) h(t) = \frac{d}{dt} s(t). \text{ Sketch } s(t) \text{ and we easily get from graph that } h(t) = 3\delta(t) - \delta(t-2) - \text{rect}\left(\frac{t-1}{2}\right).$$

$$5. \quad (a) x_2(t) = x_1(t) - x_1(t-2) \Rightarrow y_2(t) = y_1(t) - y_1(t-2)$$

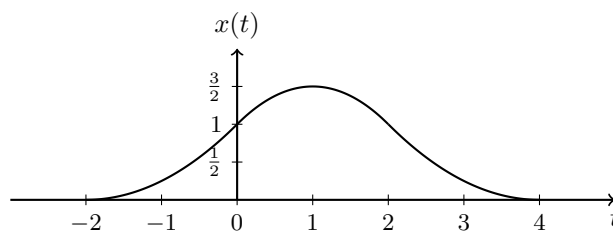


(b) $x_3(t) = x_1(t) + x_1(t+1) \Rightarrow y_3(t) = y_1(t) + y_1(t+1)$



6. $x(t) = (1 - |\tau/2|)\text{rect}(\tau/4)$, so graphically,

$$x(t) = \begin{cases} \int_{-2}^t (1 + \tau/2) d\tau & -2 < t < 0 \\ \int_{t-2}^0 (1 + \tau/2) d\tau + \int_0^t (1 - \tau/2) d\tau & 0 < t < 2 \\ \int_{t-2}^2 (1 - \tau/2) d\tau & 2 < t < 4 \\ 0 & \text{otherwise} \end{cases} = \begin{cases} 1 + t + t^2/4 & -2 < t < 0 \\ 1 + t - t^2/2 & 0 < t < 2 \\ 4 - 2t + t^2/4 & 2 < t < 4 \\ 0 & \text{otherwise} \end{cases}$$



7. (a) $y(t) = \int_{-\infty}^t (t - \tau) e^{-(t-\tau)} x(\tau) d\tau = \int_{-\infty}^{\infty} (t - \tau) u(t - \tau) e^{-(t-\tau)} x(\tau) d\tau \Rightarrow \boxed{h(t) = t e^{-t} u(t)}$

Causal: $h(t) = 0$ for $t < 0$.

Stable: $\int_{-\infty}^{\infty} |h(t)| dt = \int_0^{\infty} t e^{-t} dt = -(t+1)e^{-t} \Big|_0^{\infty} = 1$.

Dynamic: $h(t) \neq 0$ for $t > 0$.

(b) $y(t) = \int_{t-1}^{t+1} e^{-2(t-\tau)} x(\tau) d\tau = \int_{-\infty}^{\infty} \text{rect}\left(\frac{t-\tau}{2}\right) e^{-2(t-\tau)} x(\tau) d\tau \Rightarrow \boxed{h(t) = \text{rect}(t/2) e^{-2t}}$

Non-causal: $h(t) \neq 0$ for $t < 0$.

Stable: $\int_{-\infty}^{\infty} |h(t)| dt = \int_{-1}^1 e^{-2t} dt = \frac{e^2 - e^{-2}}{2}$.

Dynamic: $h(t) \neq 0$ for $t > 0$.

8.

$$\frac{dx(t)}{dt} = -6e^{-3t}u(t-1) + 2e^{-3t}\delta(t-1) = -3x(t) + 2e^{-3}\delta(t-1) \rightarrow -3y(t) + e^{-2t}u(t)$$

Thus we know

$$2e^{-3}\delta(t-1) \rightarrow e^{-2t}u(t) \Rightarrow \delta(t) \rightarrow \frac{1}{2}e^{-2t+1}u(t+1)$$

and it follows $\boxed{h(t) = \frac{1}{2}e^{-2t+1}u(t+1)}$.9. Plug $y(t) = Ce^{st}$ into the equation, and we get $s = -10$. Hence the homogeneous solution is

$$y_h(t) = Ce^{-10t}$$

For the particular solution, when $t > 0$

$$y_p(t) = P_0x(t) + P_1\frac{d}{dt}x(t) + \cdots = P_0$$

Thus

$$y(t) = y_h(t) + t_p(t) = Ce^{-10t} + P_0 \quad \text{for } t > 0$$

Plugging into the differential equation, we get

$$-10Ce^{-10t} + 10Ce^{-10t} + 10P_0 = 2 \Rightarrow P_0 = \frac{1}{5}$$

Moreover, with the initial condition, we have

$$y(0) = C + P_0 = 1 \Rightarrow C = \frac{4}{5}$$

Thus $\boxed{y(t) = \left(\frac{4}{5}e^{-10t} + \frac{1}{5}\right)u(t)}$.