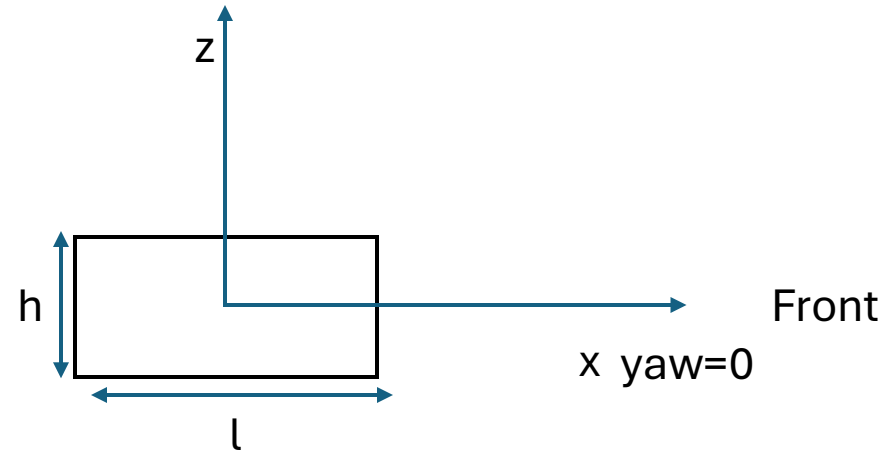
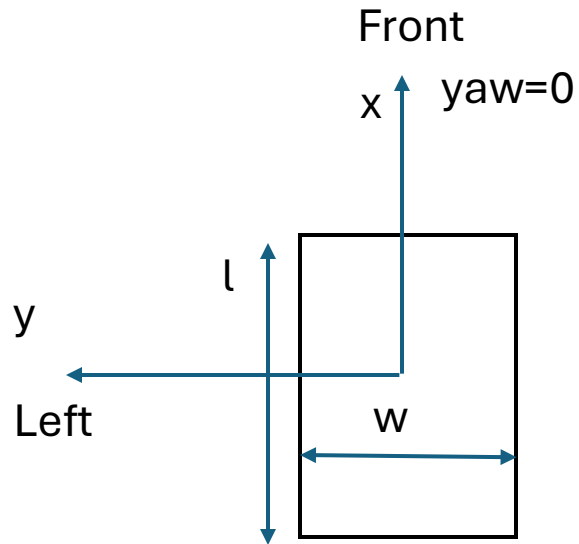


LiDAR SCAN Data

- Saved in Binary format. Each scan has 5 columns. The columns are X,Y,Z, Intensity, LiDAR Channel.
- To read each scan use

```
scan = np.fromfile(scan_path, dtype=np.float32)  
scan = scan.reshape((-1, 5))
```

3D Bounding Box Format



Label Name,

X, Y, Z,

Center

w , l , h ,

Dimension

yaw

Angle at Z axis