ST451 - Lent term Bayesian Machine Learning

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Clusters/Mixture Models and EM algorithm

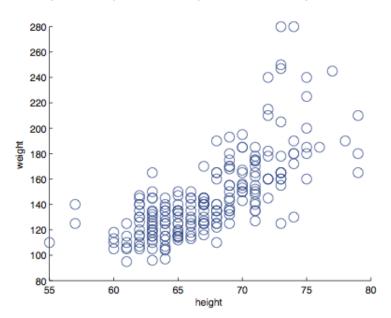
Outline

- Introduction
- Mixture models
- 3 EM algorithm
- Fully Bayesian mixture models

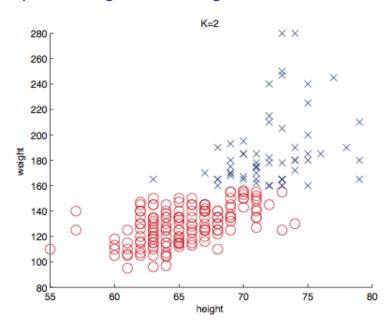
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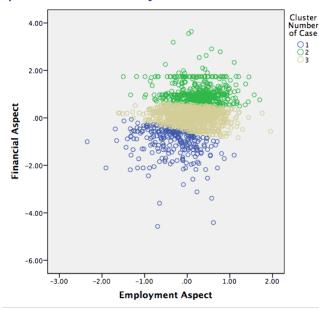
Motivating Example 1: Heights and weights



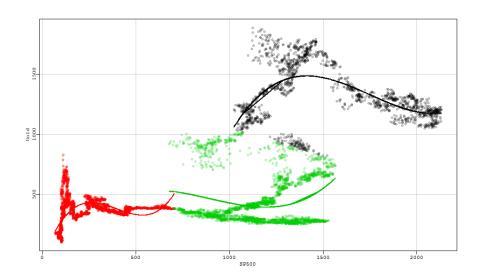
Example 1: Heights and weights



Example 2: Job Quality Definition/Measurement



Example 3: Financial Modelling



Example 4: Image Compression

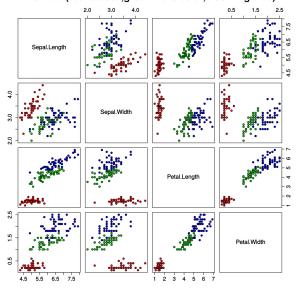


Example 5: Distinguishing Iris flower species



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Iris Data (red=setosa,green=versicolor,blue=virginica)



Example 6: Bayesian non-parametric density models

Recall the VIX index and the model we used to capture some of its stylised facts

$$Y_t = Y_{t-1} + \kappa(\mu - Y_{t-1})\delta + \sigma\epsilon_t$$

where Y_t is VIX at time t, δ is the time interval, and ϵ_t are independent error terms.

The distribution of each ϵ_t may assumed to be a mixture of Normal distributions.

Such model is very flexible; in this case corresponds to a model with jumps.

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Data augmentation

Often we want to draw inference on parameters θ based on data x from a likelihood $f(x|\theta)$ that is either intractable or expensive to compute.

Introduce an unobserved latent variable z to extend the model defining $f(z, x|\theta)$

We can then work directly with $f(z, x|\theta)$ (variational Bayes, MCMC) or approximate the integral $f(x|\theta) = \int f(z, x|\theta) dz$ in some way (simulated likelihood, EM).

Many famous examples, e.g. Ising model, factor analysis, random effects, hidden Markov models and mixtures.

Cluster/mixture analysis

- The populations consists of K clusters/groups, each with distribution $f(x_i|\theta_k)$, $k=1,\ldots,K$.
- Each individual i = 1, ..., n, belongs to one of these K clusters.
- Cluster indicator z_i is an unobserved/latent categorical variable with Multinoulli distribution $\pi(z_i|\pi_k)$, where $\sum_k \pi_k = 1$.
- The aim is to classify individuals, by and draw inference on $\theta = (\pi_k, \theta_k)_{k=1}^K$.

Likelihood and augmented likelihood

Define also the z_{ik} indicator that takes the value 1 if the individual i is in cluster k and 0 otherwise. So if $z_i = 2$, $z_{i2} = 1$ and $z_{ik} = 0$ for $k \neq 2$.

The augmented likelihood also includes z_i for each x_i .

$$f(z_i,x_i|\theta)=\pi(z_i|\pi_k)f(x_i|z_i,\theta_k)=\prod_{k=1}^K\pi_k^{z_{ik}}f(x_i|\theta_k)^{z_{ik}}.$$

Note that $f(z_i = k, x_i | \theta) = \pi_k f(x_i | \theta_k)$. Summing out z_i gives

$$f(x_i|\theta) = \sum_{k=1}^{K} f(z_i = k, x_i|\theta) = \sum_{k=1}^{K} \pi_k f(x_i|\theta_k)$$

Overall we have $f(x|\theta) = \prod_{i=1}^n f(x_i|\theta)$ and $f(z, x|\theta) = \prod_{i=1}^n f(x_i, z_i|\theta)$

Example: Gaussian Mixture Models

In Gaussian mixture models, we have $x_i|z_i = k \sim N(\mu_k, \Sigma_k)$

Hence

$$f(x_i|\theta) = \sum_{k=1}^K \pi_k N(x_i|\mu_k, \Sigma_k)$$

so the parameters to be estimated are $\theta = (\pi_k, \mu_k, \Sigma_k)_{k=1}^K$.

Due to the large number of parameters, especially for large K, restrictions are often placed on Σ_k , e.g. diagonal or tied.

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Main idea

Complete Data: If we knew the cluster each person is, z_i , then MLE is straightforward: split the data into clusters do MLE in each cluster separately.

But we don't, so we need a modified approach. The algorithm used most frequently is the EM.

A rough sketch is the one below

- **1** Start with a θ .
- **E step:** Use Bayes theorem to find the responsibilities $\gamma_{ik} = \pi(z_i = k|x,\theta)$ to get the expected log likelihood.
- **3** M step: Maximise the expected log-likelihood and update θ .
- Continue until convergence.

log-likelihood and augmented log-likelihod

First write down the augmented log-likelihood. Remember that

$$f(z_i, x_i | \theta) = \prod_{k=1}^K \pi_k^{z_{ik}} f(x_i | \theta_k)^{z_{ik}},$$

so considering all individuals and taking log gives

$$\log f(z, x|\theta) = \sum_{i=1}^{n} \sum_{k=1}^{K} z_{ik} \left(\log \pi_k + \log f(x_i|\theta_k)\right)$$

By contrast the log-likelihood is

$$\log f(x|\theta) = \log \left[\sum_{k=1}^{K} \pi_k f(x_i|\theta_k) \right]$$

Notes

- Can view the augmentation as way to bring log within the sum.
- 2 Easy to maximise the augmented log-likelihood given the z_{ik} 's.

E step

In the EM algorithm we update θ^{old} to θ^{new} . In the E step we define the expected log likelihood

$$Q(\theta, \theta^{old}) = \mathbb{E}_{\pi(z|x, \theta^{old})} \left[\sum_{i=1}^{n} \sum_{k=1}^{K} z_{ik} \left(\log \pi_k + \log f(x_i|\theta_k) \right) \right]$$

Note that

$$\mathbb{E}_{\pi(z|x,\theta^{old})}[z_{ik}] = \frac{\pi_k^{old} f(x|\theta_k^{old})}{\sum_{j=1}^K \pi_j^{old} f(x|\theta_j^{old})} = \gamma(z_{ik}),$$

where the $\gamma(z_{ik}) = \pi(z_{ik} = 1 | x, \theta^{old})$ are known as the responsibilities.

Hence we can write

$$Q(\theta, \theta^{old}) = \sum_{i=1}^{n} \sum_{k=1}^{K} \gamma(z_{ik}) \left(\log \pi_k + \log f(x_i | \theta_k) \right)$$

M step

The M step: consists of simply maximising $Q(\theta, \theta^{old})$ wrt to θ . Note that the $\gamma(z_{ik})$ are known numbers based on x and θ^{old} so it is usually an easy task.

To maximising $Q(\theta, \theta^{old})$ wrt to π_k 's we can use Lagrange multipliers to satisfy the restriction that they sum to one. So we set

$$L = Q(\theta, \theta^{old}) + \lambda \left(\sum_{k} \pi_{k} - 1 \right),$$

$$\frac{\partial L}{\partial \pi_{k}} = 0 \quad \leftrightarrow \quad \pi_{k} = \frac{\sum_{i} \gamma(z_{ik})}{-\lambda}$$

$$\frac{\partial L}{\partial \lambda} = 0 \quad \leftrightarrow \quad \sum_{k} \pi_{k} = 1 \leftrightarrow \lambda = -n$$

so we get that $Q(\theta, \theta^{old})$ is maximised at

$$\pi_k^{new} = \frac{\sum_i \gamma(z_{ik})}{n} = \frac{n_k}{n}$$

Example: Gaussian Mixure models

The remaining parameters depend on which type of $f(x_i|\theta_k)$ we have.

For Gaussian mixture models standard MLE methods provide

$$\mu_k^{\text{new}} = \frac{\sum_i \gamma(z_{ik}) x_i}{\sum_i \gamma(z_{ik})} = \frac{\sum_i \gamma(z_{ik}) x_i}{n_k}$$

$$\Sigma_k^{\text{new}} = n \frac{1}{n_k} \sum_i \gamma(z_{ik}) (x_i - \mu_k^{\text{new}}) (x_i - \mu_k^{\text{new}})^T$$

Hence the EM algorithm initiates θ and iteratively updates from θ^{old} to θ^{new} until the log likelihood or the parameters converge.

Similar results exist for other distributions such as Bernoulli, Exponential etc.

Connection with k-means

- Mixture models classify individuals to clusters based on the responsibilities $\gamma(\zeta_{ik})$'s, i.e. the posterior probabilities of z, rather than with certainty, aka soft allocation.
- This is reflected on the estimate of θ_k that are weighted averages based on how likely an individual is in cluster k.
- In Gaussian mixture models if we set $\Sigma_k = \sigma^2 I_d$ and let $\sigma^2 \to 0$ we get the same solution as with the k-means approach for μ_k . Note that in this case we have hard allocation.
- If we have general $\Sigma'_k s$ the approach coincide with the elliptical k-means.

Selecting the number of clusters

- In both mixture models and k-means it is not easy to select the number of classes.
- The default criterion in the mixture models is the BIC.
- Nevertheless the approach is very sensitive to starting values as the objective is multimodal and is very likely to get trapped in local maxima.
- It is recommended to initialise parameters based on intuition, try out multiple starting points or initialise with the results of another method.

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Fully Bayesian approach

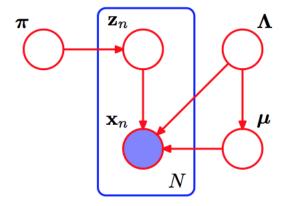
The approach so far was Bayesian with respect to z but not θ . For a fully Bayesian approach priors on θ should be specified.

In Gaussian mixture models example the conjugate priors can be used

$$\mu_k | \Lambda_k \sim N\left(m_0, (\beta_0 \Lambda)^{-1}\right)$$
 $\Lambda \sim \text{Wishart}(W_0, \nu_0)$
 $\pi \sim \text{Dirichlet}(\alpha_0)$

The posterior is not available in closed form. We can therefore consider a variational approximation.

Graph of Bayesian Gaussian Mixtures Model



Variational Inference for Gaussian Mixtures

We can apply mean field approximation of the form

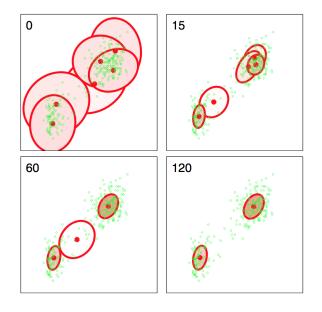
$$q(z, \pi, \mu, \Lambda) = q(z)q(\pi, \mu, \Lambda)$$

The outcome is analogous to the EM case.

- q(z) requires some tedious calculations that provide the responsibilities r_{ik} 's
- ② Given r_{ik} 's $q(\pi, \mu, \Lambda)$ can be recognised as a product of a Dirichlet, Normal and Wishart distributions, the moments of which can be used to update r_{ik} 's. See Bishop 478-79 for details.
- The above are repeated until convergence.

The prior parameter α_0 , in the Dirichlet(α_0) prior on π , is critical in selecting the number of clusters. Large values favour equal π_k 's but under values close to 0 only the important clusters will get individuals.

Variational Inference - no overfit



Latent Dirichlet allocation

Consider M documents each with N_i words. The model is defined as:

• Each of word w_{ij} , i = 1, ..., M and $j = 1, ..., N_i$ may belong to different topics k = 1, ..., K, that indicate the word distribution ϕ_k :

$$w_{ij}|z_{ij} \sim \text{Multinoulli}(\phi_k)$$

• Let z_{ij} denote the topic indicator (latent) of w_{ij} , with distribution θ_i varying across documents:

$$z_{ij} \sim \text{Multinoulli}(\theta_i)$$

• The word and topic distributions (θ_i, ϕ_k) are given Dirichlet distribution priors with α, β respectively, both < 1 for sparsity:

$$\theta_i \sim \mathsf{Dirichlet}(\alpha) \quad \phi_k \sim \mathsf{Dirichlet}(\beta)$$

Today's lecture - Reading

Bishop: 9.1 to 9.4, 10.2.1 10.2.2

Murphy: 11.1 11.2 11.4.1 11.4.2 21.6 27.3