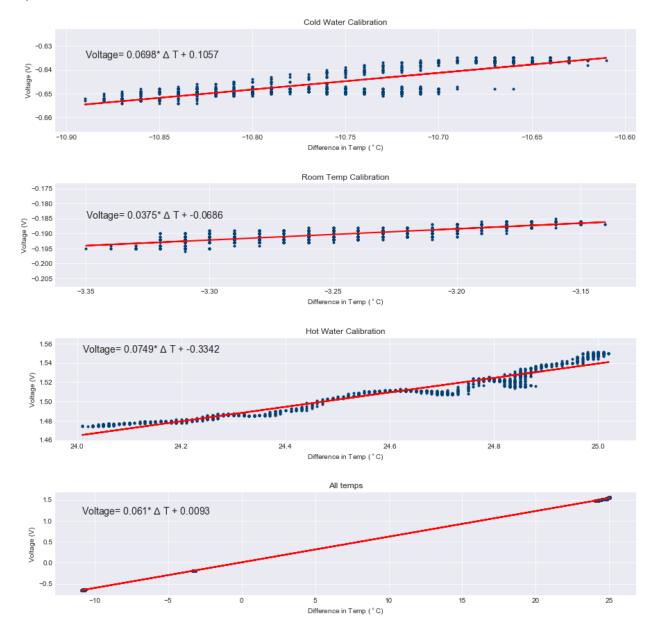
34404160

$\label{lem:calculation} \textbf{Calculation for static calibration of Type E thermocouple}$

1,2 and 3:



Lab 4 ATSC 303

4. The coefficient values represent the slope(m) and y-intercept(b) of the best fit line. The plots generated gave the following coefficients:

Cold Water Calibration

$$c0 = -1.5135$$

$$c1 = 14.325$$

Transfer Eq: Voltage= $0.0698*\Delta T + 0.106$

Room Temp Calibration

$$c0 = 1.8318$$

$$c1 = 26.701$$

Transfer Eq: Voltage= $0.0375*\Delta T + -0.069$

Hot Water Calibration

$$c0 = 4.4595$$

$$c1 = 13.343$$

Transfer Eq: Voltage= $0.0749*\Delta T + -0.334$

All temps

c0 = -0.1531

c1 = 16.401

Transfer Eq: Voltage= $0.061*\Delta T + 0.0093$

The transfer equation equation generated using these coefficients, was used to find a predicted value for the output voltage and is compared in the table below with the NIST Standards value.

According to the table this is the values for output voltage:

ΔΤ	Predicted Voltage out	NIST value
-11	-0.6622	-0.639
-3.35	-0.181	-0.176
25	1.5394	1.495

Therefore these compare to each other closely, although not perfectly.

5. The plots generated gave the following calibration equations:

<u>Cold Water Calibration</u>: $\Delta T = 14.325*$ Voltage + -1.5135

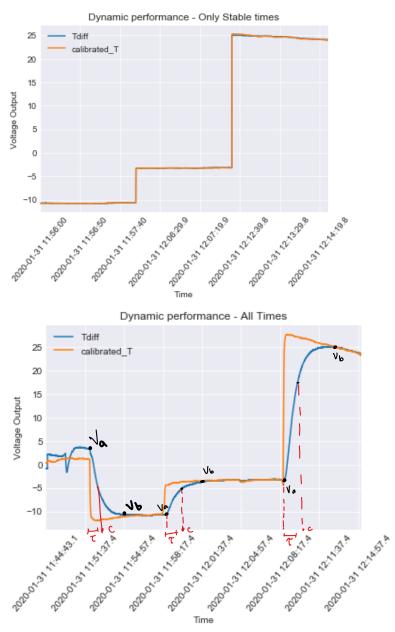
Room Temp Calibration: $\Delta T = 26.701*$ Voltage + 1.8318

Hot Water Calibration: $\Delta T = 13.343*$ Voltage + 4.4595

All Temps: $\Delta T = 16.401 * Voltage + -0.1531$

6. We have not used perfect calibration methods such as using ice baths or boiling water. Additionally, the sensors that were exposed to air still felt effects of their surrounding and their temperature was not entirely constant. Over the time span, the water temperatures also changed. We assumed that the response was step response too. I would used more regulated water temperatures to improve the experiment, in order to increase precision.

Calculations for dynamic performance of the thermocouples



2. Response time:

- a. Eyeballed time: about 3 mins. At point 'Va' labelled on the graph, the voltage can be approximated at 4V, and the time at Va (vertical line to the x-axis) can be approximated at 11:45 am. The point 'Vb' is the new Voltage output after the change in temperature (-10V), and therefore can be approximated at 11:50 am. The time response is however, the time interval after which 63% of the change that has to be done, is done. So if the change was from 4 V to -10V, 63% of this change is (0.63)(-10-4) = -8.82 V. So 4-8.82 = -4.82 V. This point is marked with a red vertical line, and point 'c'. The time interval between c and 11:54am is approximated 3 mins.
- b. $T_a = 25^{\circ}C$ Then $\tau = \frac{(T1 - T_{air})}{\frac{T1 - T_0}{t_1 - t_0}} = \frac{(4 - 25)}{\frac{4 - (-10)}{11:51: -11:44}} = \frac{-21^{\circ}C}{\frac{14^{\circ}C s^{-1}}{11:50 - 11:45}} = -270s = 4.5 \ mins$
- 3. Two different thermocouples would have different densities, surface areas and heat resistance, and therefore different τ values
- 4. We would assume there was no human error and the step inputs occurred at the same time. We would also assume all static effects have been excluded or compensated for. Also we assume that instruments have no errors. My results had similar step increase/decrease but I would assume, if it wasn't similar, that it was human error (touching the thermocouple or the water baths changing temperature fast, etc).
- 5. Because the temperature of the water baths changes fast so we want to minimize the error by having more data points in a shorter time span

Further lab questions (based on lectures and readings)

1.
$$\tau = \frac{(T_S - T_{air})}{\frac{dT_S}{dt}}$$
 $\tau = \frac{(T_1 - T_{air})}{\frac{T_1 - T_0}{t_1 - t_0}}$

2. Assume: The system is linear and that the contributions of the 2 different frequencies are independent.

$$T_{filtered} = A_1 R_1 \sin\left(\frac{2\pi t}{P1}\right) + A_2 R_2 \sin\left(\frac{2\pi t}{P2}\right)$$

$$3 \sin(2t) + 5 \sin(7t) = A_1 R_1 \sin\left(\frac{2\pi t}{P1}\right) + A_2 R_2 \sin\left(\frac{2\pi t}{P2}\right)$$

$$A_1 = 3$$

$$A_2 = 5$$

$$\left(\frac{2\pi}{P1}\right) = 2 \rightarrow P1 = \pi \rightarrow f_1 = \frac{1}{\pi}$$

$$\left(\frac{2\pi t}{P2}\right) = 7 \rightarrow P2 = \frac{2\pi}{7} \rightarrow f_2 = \frac{7}{2\pi}$$

$$R = \frac{1}{\sqrt{1 + 4\pi^2 f^2 \tau^2}}$$

$$R_1 = \frac{1}{\sqrt{1 + 4\pi^2 f_1^2 \tau^2}} = \frac{1}{\sqrt{1 + 4\pi^2 \frac{1}{\pi}^2 \tau^2}} = \frac{1}{\sqrt{1 + 4\pi^2 \frac{1}{\pi}^2 \tau^2}}$$

$$R_{2} = \frac{1}{\sqrt{1 + 4\pi^{2} f_{2}^{2} \tau^{2}}} = \frac{1}{\sqrt{1 + 4\pi^{2} \left(\frac{7}{2\pi}\right)^{2} \tau^{2}}} = \frac{1}{\sqrt{1 + 49 \tau^{2}}}$$

$$T_{filtered} = 3 * \frac{1}{\sqrt{1 + 4\pi \tau^{2}}} \sin\left(\frac{2\pi t}{\pi}\right) + 5 * \frac{1}{\sqrt{1 + 49 \tau^{2}}} \sin\left(\frac{2\pi t}{\frac{2\pi}{7}}\right)$$

$$T_{filtered} = 3 * \frac{1}{\sqrt{1 + 4\pi \tau^{2}}} \sin(2t) + 5 * \frac{1}{\sqrt{1 + 49 \tau^{2}}} \sin(7t)$$

- 3. Yes it could approach 0 when the input frequency and response time align so that phase lag is 180°, and the system crosses the mean sinusoidal value.
- 4. Dynamic error = $-a\tau$ and Dynamic lag = τ
- 5. 700 and 1100 hPa. After fitting a straight-line equation, the transfer coefficients are ao = -7.00 V and a1 = 0.0100 V hPa-1. Average and standard deviation of the residual errors are 0.00 hPa and 0.25 hPa respectively. Evalua
 - a. Bias: True Value Mean Measured value. Since residual averages are 0, bias is 0 hPa
 - b. Imprecision: Spread of the points(range) = standard deviation of residual = 0.25 hPa
 - c. Inaccuracy = 0 because it is a measure of how close the mean is to the average.
 - d. Span: 3 standard deviations = $0.75 \rightarrow \text{span} = 0.75 \text{ hPa}$
 - e. Sensitivity: Slope of transfer equation = 0.01 V hPa⁻¹
 - f. $3V = -7.00 V + (0.01 V hPa^{-1})(input) \rightarrow input = 1000 hPa$
- 6. a. 5
 - b. 3
 - c. 1
 - d. 2