

Control Computer

2016/2017

first Test

November 9, 2016, 20 hours - V1.16 rooms, v1.15, v1.14, V1.12

Quotation: P1a) 1b), 2c) 1d) 1e) 1f) 1 P2a) 3b) 1c) 1d) P3a) 1) 3b) P4a) 1) 1b), 1c) 1

Duration: 2 hours. Not any elements of consultation is allowed.



P1. In a given case the manipulated variable u and output are related the following transfer function

$$u(z) = \frac{1}{1 + 0.5z^{-1}} y(z)$$

- Write a difference equation relating the samples u with of the y .
- Taking as an initial condition $u(0) = 0$, use the difference equation to calculate $u(k)$ When $k = 1, \dots, 5$, suposing that $y(k) = 1, k \geq 0$.
- Under the conditions of b), to determine the exact value \bar{u} whose $u(k)$ if when approaching k tends to infinity.
- In order to control the process, causing the output y . Have a next value of the reference r , the process is connected to a controller full as shown in Figure P1-1. Determine the function of system closed chain transfer, $u(z) / r(z)$.

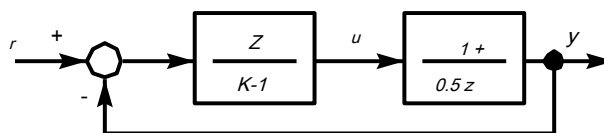


Fig. P1-1. Problem P1. Interconnection between the process and the controller.

- is constant, so when • tends to infinity, • (•) tends to Setpoint •.

-

$$\bullet(\bullet) = \bullet \pm \frac{1}{\bullet + 2}$$

(Consider a generic value $h > 0$).

- Help:* $1, (\overset{\bullet}{\text{for } Z^{(0)}} \cdot \frac{\quad}{ZZK1} \text{ and }^{khT} \cdot \cdot \frac{Z}{\overset{\bullet}{ez} \cdot \cdot T} \mathcal{L}(\cdot \dots) = \underline{1} \dots)$

$$(\cdot) \cdot \cdot \quad \cdot 1(\cdot) \cdot TVT \quad \cdot 1(\cdot) \cdot \quad b\psi \quad (P2-1)$$
$$\begin{array}{ccccc} \overset{999}{\bullet} & \overset{2}{\cdot} & \overset{999}{i\mathfrak{p}}_1() & \cdot & 30 \\ \overset{999}{\bullet} & \overset{2}{\cdot} & \overset{999}{i\mathfrak{u}}_1() & \cdot & 50 \\ \overset{999}{\bullet} & & () & \cdot & \overset{999}{i\mathfrak{y}}_1() \cdot 1 \\ \hline \overset{999}{\bullet} & \cdot & \overset{999}{1}() & \cdot & \overset{999}{i\mathfrak{u}}_1() \cdot 20 \\ \overset{999}{\bullet} & & () & \cdot & \overset{999}{i\mathfrak{y}}_1() \cdot 36 \end{array}$$

a) Determine the estimated least squares parameter \hat{A} and \hat{B} .

Present intermediate calculations.

b) Suppose that $\hat{y}(k) = \hat{y}(k) + \hat{y}(k-1)$. Explain the minimum algorithm square extended to estimate \hat{y} , \hat{A} and \hat{B} . Write the equations define the algorithm but not the need to apply for estimates.



P4. The temperature θ a heat accumulator for heating water

satisfies the following difference equation

$$\theta(k+1) = \alpha \theta(k) + (1 - \alpha) \theta_d$$

on what θ_d It is a constant and α is a constant parameter which verifies $0 < \alpha < 1$.

a) Determine the value of the equilibrium temperature (ie, a value temperature such that if the initial condition is equal to it, so temperature always remains constant) θ^* in function of α and θ_d .

b) Suppose that the initial state is not stable temperature.

Obtain a difference equation for the deviation

$$\tilde{\theta}(k) = \theta(k) - \theta^*$$

W) Without use the concept of pole nor the transformed Z, show that $\tilde{\theta}(k)$

tends to zero when k tends to infinity, meaning that the balance θ^* is asymptotically stable.

