```
void ION_Motion_setPosition(ion_command_t command,
                            position_t pos)
```

Buffered Drive M1 with signed Speed, Accel, Deccel and Position
Buffered Drive M2 with signed Speed, Accel, Deccel and Position

```
void setEncoderValue(ion_command_t command,
                     int value)
```

Set Quadrature Encoder 1 Value

Set Quadrature Encoder 2 Value

```
void setMotorSpeed(ion_command_t command,
                   int speed)
```

Drive Forward Motor 1
Drive Backwards Motor 1
Drive Forward Motor 2
Drive Backwards Motor 2

```
void getMotorCurrent(void)
```

Read Motor Currents