

Para la desviación cuadrática media, obtenemos:

(4)

$$\langle \hat{x}^2(t) \rangle = \langle \psi(t) | \hat{x}^2 | \psi(t) \rangle$$

$$= \frac{1}{3} \langle \varphi_0 | \hat{x}^2 | \varphi_0 \rangle + \frac{2}{3} \langle \varphi_1 | \hat{x}^2 | \varphi_1 \rangle$$

$$+ 2 \sqrt{\frac{2}{3}} \operatorname{Im} \left(e^{\frac{i}{\hbar} (\epsilon_1 - \epsilon_0) t} \langle \varphi_1 | \hat{x}^2 | \varphi_0 \rangle \right)$$

Usando:

$$\langle \varphi_n | \hat{x}^2 | \varphi_n \rangle = \frac{\hbar}{2m\Omega} \left(\sqrt{n(n-1)} \delta_{n',n-2} + \sqrt{(n+1)(n+2)} \delta_{n',n+2} + (2n+1) \delta_{n',n} \right)$$

se tiene:

$$\langle \varphi_0 | \hat{x}^2 | \varphi_0 \rangle = \frac{\hbar}{2m\Omega}, \quad \langle \varphi_1 | \hat{x}^2 | \varphi_1 \rangle = \frac{3\hbar}{2m\Omega},$$

$$\langle \varphi_1 | \hat{x}^2 | \varphi_0 \rangle = 0$$

luego,

$$\langle \hat{x}^2(t) \rangle = \frac{1}{3} \frac{\hbar}{2m\Omega} + \frac{2}{3} \cdot \frac{3\hbar}{2m\Omega} = \frac{7}{6} \frac{\hbar}{m\Omega}$$

$$\Delta X(t) = \sqrt{\langle \hat{x}^2(t) \rangle - \langle x(t) \rangle^2} = \sqrt{\frac{7}{6} \frac{\hbar}{m\Omega} - \frac{8}{9} \frac{\hbar}{m\Omega} \sin^2(\Omega t)}$$