Formulário

Fórmula fundamental dos erros $\left| \delta_f \leq M_{x_1} \delta_{x_1} + M_{x_2} \delta_{x_2} + ... + M_{x_n} \delta_{x_n} \right|$ em que $\left|\frac{\partial f}{\partial x_i}(\xi)\right| \le M_{x_i}$ com $\xi \in [x_1 - \delta_{x_1}, x_1 + \delta_{x_1}] \times \cdots \times [x_n - \delta_{x_n}, x_n + \delta_{x_n}].$

Uma equação não linear		
Método da Secante	Método de Newton	
$x_{k+1} = x_k - \frac{(x_k - x_{k-1})f(x_k)}{f(x_k) - f(x_{k-1})}, k = 2, 3, \dots$	$x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k)}, k = 1, 2, \dots$	
$G \cup G \cup G$		

Critério de Paragem: $\frac{|x_{k+1} - x_k|}{|x_{k+1}|} \le \epsilon_1 e |f(x_{k+1})| \le \epsilon_2$

Método de Newton para sistemas de equações não lineares

Equação iterativa	Jacobiano	Critério de Paragem
$J(x^{(k)})\Delta_x = -f(x^{(k)}) x^{(k+1)} = x^{(k)} + \Delta_x$	$J = \begin{pmatrix} \frac{\partial f_1(x_1, x_2, \dots, x_n)}{\partial x_1} & \cdots & \frac{\partial f_1(x_1, x_2, \dots, x_n)}{\partial x_n} \\ \vdots & \vdots & \ddots \\ \frac{\partial f_n(x_1, x_2, \dots, x_n)}{\partial x_1} & \cdots & \frac{\partial f_n(x_1, x_2, \dots, x_n)}{\partial x_n} \end{pmatrix}$	$\frac{\ \Delta_x\ }{\ x^{(k+1)}\ } \le \epsilon_1$ e $\ f(x^{(k+1)})\ \le \epsilon_2$

Tabela das diferenças divididas

Tabela das diferenças divididas
$$[x_j, x_{j+1}] = \frac{f_j - f_{j+1}}{x_j - x_{j+1}}, \qquad j = 0, \dots, n-1 \qquad \text{(diferença dividida de ordem 1) } (dd1)$$

$$[x_j, x_{j+1}, x_{j+2}] = \frac{[x_j, x_{j+1}] - [x_{j+1}, x_{j+2}]}{x_j - x_{j+2}}, \qquad j = 0, \dots, n-2 \qquad (dd2)$$

$$[x_0, x_1, \dots, x_{n-1}, x_n] = \frac{[x_0, x_1, \dots, x_{n-2}, x_{n-1}] - [x_1, x_2, \dots, x_{n-1}, x_n]}{x_0 - x_n} \qquad (ddn)$$

$$[x_0, x_1, \dots, x_n] = \frac{f^{(n)}(\xi)}{n!}$$

Polinómio interpolador de Newton

$$p_n(x) = f_0 + (x - x_0) [x_0, x_1] + (x - x_0)(x - x_1) [x_0, x_1, x_2] + \dots + (x - x_0) \dots (x - x_{n-1}) [x_0, \dots, x_n]$$
Erro de truncatura $R_n(x) \le |(x - x_0)(x - x_1) \dots (x - x_n) dd_{n+1}|$

Expressão do segmento i da spline cúbica

$$s_{3}^{i}(x) = \frac{M_{i-1}}{6(x_{i}-x_{i-1})}(x_{i}-x)^{3} + \frac{M_{i}}{6(x_{i}-x_{i-1})}(x-x_{i-1})^{3} + \left[\frac{f(x_{i-1})}{(x_{i}-x_{i-1})} - \frac{M_{i-1}(x_{i}-x_{i-1})}{6}\right](x_{i}-x) + \left[\frac{f(x_{i})}{(x_{i}-x_{i-1})} - \frac{M_{i}(x_{i}-x_{i-1})}{6}\right](x-x_{i-1}) \text{ para } i = 1, 2, \dots, n$$

Spline Natural	Spline Completa
$M_0 = 0$	$2(x_1 - x_0)M_0 + (x_1 - x_0)M_1 = \frac{6}{(x_1 - x_0)}(f(x_1) - f(x_0)) - 6f'(x_0)$
$M_n = 0$	$2(x_n - x_{n-1})M_n + (x_n - x_{n-1})M_{n-1} = 6f'(x_n) - \frac{6}{(x_n - x_{n-1})}(f(x_n) - f(x_{n-1}))$

Erro de truncatura *spline* cúbica
$$|f(x) - s_3(x)| \le \frac{5}{384}h^4M_4$$
 $|f'(x) - s_3'(x)| \le \frac{1}{24}h^3M_4$ com $\max_{\xi \in [x_0, x_n]} |f^{(iv)}(\xi)| \le M_4$ $h = \max_{0 \le i \le n-1} (x_{i+1} - x_i)$

Fórmulas simples Newton-Cotes		
Trapézio	$\int_{a}^{b} f(x)dx \approx \frac{(b-a)}{2} \left[f(a) + f(b) \right]$	$ET = -\frac{(b-a)^3}{12}f''(\xi) , \ \xi \in [a,b]$
Simpson	$\int_{a}^{b} f(x)dx \approx \frac{(b-a)}{6} \left[f(a) + 4f(\frac{a+b}{2}) + f(b) \right]$	$ET = -\frac{(b-a)^5}{2880}f^{(iv)}(\xi) , \ \xi \in [a,b]$
$\frac{3}{8}$	$\int_{a}^{b} f(x)dx \approx \frac{(b-a)}{8} \left[f(a) + 3f(\frac{2a+b}{3}) + 3f(\frac{a+2b}{3}) + f(b) \right]$	$ET = -\frac{(b-a)^5}{6480}f^{(iv)}(\xi) , \ \xi \in [a,b]$

Fórmulas compostas Newton-Cotes		
Trapézio	$\int_{a}^{b} f(x)dx \approx \frac{h}{2} \left[f_0 + 2f_1 + 2f_2 + \dots + 2f_{n-2} + 2f_{n-1} + f_n \right]$	
	$ ET = -\frac{h^2}{12}(b-a)f''(\eta) , \ \eta \in [a,b]$	
Simpson	$\int_{a}^{b} f(x)dx \approx \frac{h}{3} \left[f_0 + 4f_1 + 2f_2 + 4f_3 + \dots + 4f_{n-3} + 2f_{n-2} + 4f_{n-1} + f_n \right]$	
	$ET = -\frac{h^4}{180}(b-a)f^{(iv)}(\eta) , \ \eta \in [a,b]$	
$\left\lceil \frac{3}{8} \right\rceil$	$\int_{a}^{b} f(x)dx \approx \frac{3h}{8} \left[f_0 + 3f_1 + 3f_2 + 2f_3 + \dots + 2f_{n-3} + 3f_{n-2} + 3f_{n-1} + f_n \right]$	
	$ET = -\frac{h^4}{80}(b-a)f^{(iv)}(\eta) , \ \eta \in [a,b]$	

Mínimos Quadrados (amostra m)

Polinómios ortogonais

$$p_n(x) = c_0 P_0(x) + c_1 P_1(x) + \ldots + c_n P_n(x)$$

$$P_{i+1} = A_i(x - B_i) P_i(x) - C_i P_{i-1}(x), P_0(x) = 1, P_{-1}(x) = 0$$

$$A_i = 1$$

$$B_i = \frac{\sum_{j=1}^m x_j P_i(x_j) P_i(x_j)}{\sum_{j=1}^m P_i(x_j) P_i(x_j)} C_0 = 0 \text{ e } C_i = \frac{\sum_{j=1}^m P_i(x_j) P_i(x_j)}{\sum_{j=1}^m P_{i-1}(x_j) P_{i-1}(x_j)}$$
Coeficientes do modelo polinomial
$$c_i = \frac{\sum_{j=1}^m f_j P_i(x_j)}{\sum_{j=1}^m P_i(x_j)^2}, \quad i = 0, \ldots, n$$

$$c_i = \frac{\sum_{j=1}^{j=1} J_j \Gamma_i(x_j)}{\sum_{j=1}^{m} P_i(x_j)^2}, \quad i = 0, \dots, n$$

Modelo não polinomial linear

$$M(x; c_{1}, c_{2}, \dots, c_{n}) = c_{1}\phi_{1}(x) + c_{2}\phi_{2}(x) + \dots + c_{n}\phi_{n}(x)$$

$$\begin{pmatrix} \sum_{j=1}^{m} \phi_{1}^{2}(x_{j}) & \dots & \sum_{j=1}^{m} \phi_{1}(x_{j})\phi_{n}(x_{j}) \\ \dots & \dots & \dots \\ \sum_{j=1}^{m} \phi_{n}(x_{j})\phi_{1}(x_{j}) & \dots & \sum_{j=1}^{m} \phi_{n}^{2}(x_{j}) \end{pmatrix} \begin{pmatrix} c_{1} \\ \dots \\ c_{n} \end{pmatrix} = \begin{pmatrix} \sum_{j=1}^{m} f_{j}\phi_{1}(x_{j}) \\ \dots \\ \sum_{j=1}^{m} f_{j}\phi_{n}(x_{j}) \end{pmatrix}$$

$$\mathbf{Resíduo} \left[\sum_{j=1}^{m} (f_{j} - M(x_{j}))^{2} \right]$$

Resíduo
$$\sum_{j=1}^{m} (f_j - M(x_j))^2$$