

# Linux capable RISC-V CPU for IOb-SoC

Thesis to obtain the Master of Science Degree in  
**Electrical and Computer Engineering**

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- ▶ Introduction
  - ▶ Motivation and problem
  - ▶ Proposed solution and thesis objectives
- ▶ Hardware platform (IOb-SoC)
  - ▶ Integrate additional peripherals
  - ▶ Profile Tiny YOLOv3 application
- ▶ VersatCNN acceleration
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- ▶ Results and Conclusions
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- ▶ Object detection is useful in multiple areas of application (navigation, medical, security)
  - ▶ Most accurate methods use CNN inference.
  - ▶ **Problem:** Computationally demanding process.
- ▶ Current solutions based on GPU acceleration.
  - ▶ Oversized and power-hungry.
- ▶ Alternative accelerators also have limitations:
  - ▶ FPGA: better size/power efficiency than GPU, with configuration overhead and increased development time.
  - ▶ ASIC: dedicated accelerators lack hardware programmability.
- ▶ **Proposed solution:** CGRA
  - ▶ Optimized area and power.
  - ▶ Faster reconfiguration for FPGA implementation.
  - ▶ Adds hardware programmability for ASIC implementation.

Main thesis goals:

- ▶ Accelerate a Convolutional Neural Network (CNN) for object detection, using the VersatCNN CGRA
  - ▶ Configure CGRA dataflow to efficiently implement the Tiny YOLOv3 application
- ▶ Target real-time processing (30 FPS)

Open source RISC-V SoC platform by IObundle.

Main components:

- ▶ PicoRV32 RISC-V CPU
- ▶ Internal memory
- ▶ External memory
  - ▶ Single level cache
- ▶ UART
- ▶ Integrated Peripherals:
  - ▶ **Timer**
  - ▶ **Ethernet**
  - ▶ **VersatCNN**

Continuous integration of system and new components.  
Development of testing environment.

Embedded version of Tiny YOLOv3 application:

- ▶ Executed exclusively on RISC-V CPU
- ▶ 143 MHz system clock.

Tiny YOLOv3 Part	Execution Time (s)
Pre-CNN	1.040
CNN	967.746
Post-CNN	0.014
Total	968.800
<b>Target (30 FPS)</b>	<b>0.033</b>

**Table:** Tiny YOLOv3 RISC-V-only performance.

**Conclusion:** all parts of the application require acceleration.