
Data Link Protocol

(1st Lab Work)

FEUP

Computer Networks

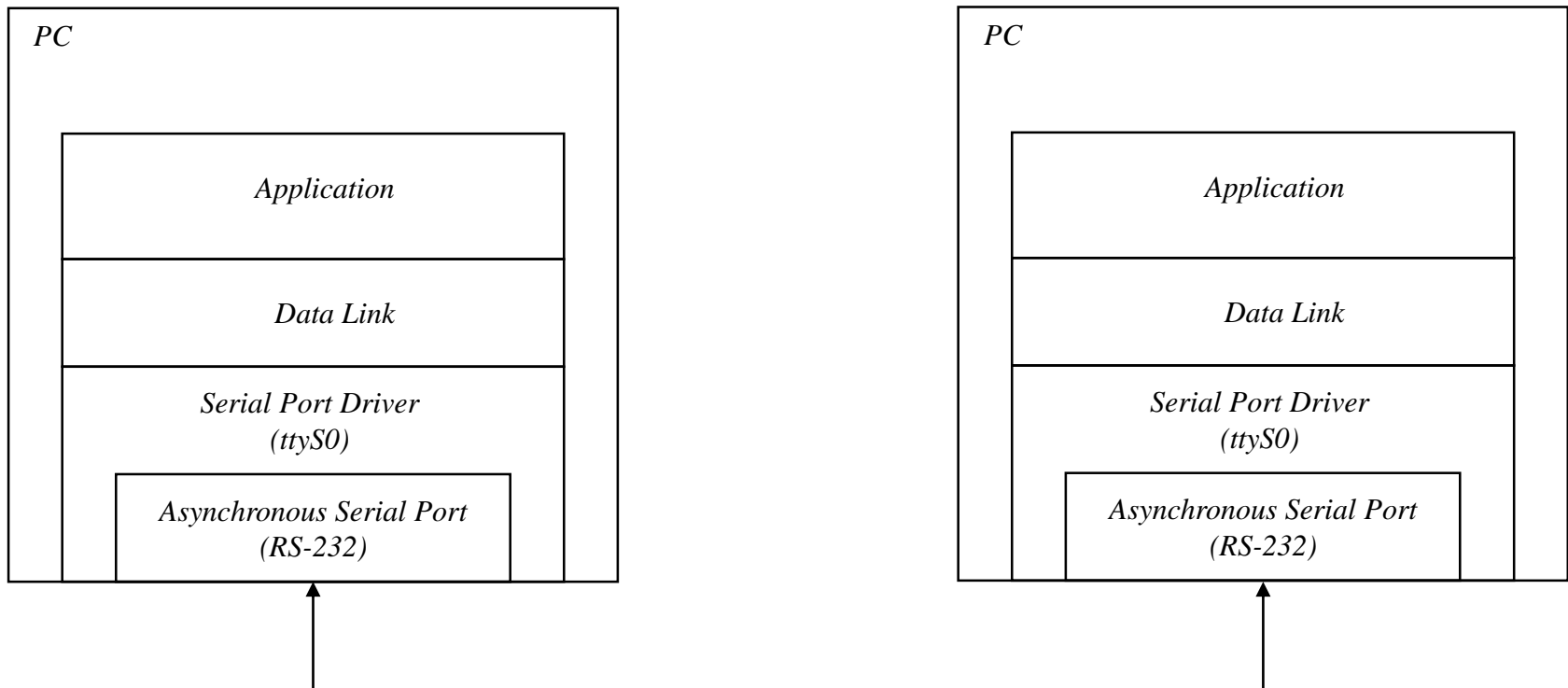
Work overview

- Goals
 - » Implement a data link protocol, according to the specification provided in this document
 - » Test the protocol with a simple data transfer application, according to the specification provided in this document
- Development environment
 - » PC running LINUX
 - » Programming language – C
 - » Serial port RS-232 (asynchronous communication)

Evaluation

- Organization
 - » Groups of 2 elements
 - » Each group develops the transmitter and receiver
- Evaluation criteria
 - » Participation during class (continuous evaluation)
 - » Presentation and demonstration of the work
 - » Final report

Test configuration



Data Link Protocols - Functions

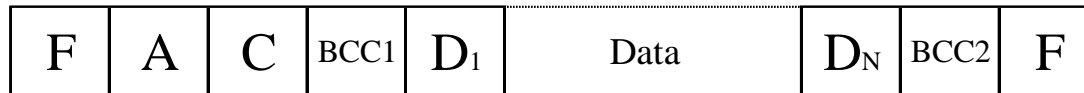
- Goal of the Data Link Protocol
 - » Provide reliable communication between two systems connected by a communication medium – in this case, a serial cable
- Generic functions of data link protocols
 - » Frame synchronization (delimitation) – data organized in frames (framing)
 - Main alternatives: characters / flags to delimit start and end of frame
 - Data size may be implicit or explicitly indicated in the frame header
 - » Connection establishment and termination
 - » Frame numbering
 - » Positive Acknowledgement
 - After a frame is received without errors and in the right sequence
 - » Error control (e.g.: Stop-and-Wait, Go-back-N, Selective Repeat)
 - Timers (time-out) – retransmission decided by the transmitter
 - Negative acknowledgement (out of sequence frames) – receiver requests the retransmission
 - Retransmissions may originate duplicates (which should be detected and discarded)
 - » Flow control

Data Link Protocol - Specification

- The protocol to implement combines characteristics of existing data link protocols
 - » The protocol guarantees code-independent data transmission (transparency)
 - » The transmission is organized into frames, which can be of three types - Information (I), Supervision (S) and Unnumbered (U)
 - » Frames have a header with a common format
 - Only Information frames have a field for data transport (this field transports a packet generated by the application, but its content is not processed by the data link protocol – independence between layers)
 - » Frame delimiting is done by means of a special eight-bit sequence (flag) and transparency is ensured by the byte stuffing technique
 - » The frames are protected by an error detection code
 - In frames S and U there is simple frame protection (since they do not carry data)
 - In I frames there is double and independent protection of the header and the data field (which allows to use a valid header, even if an error occurs in the data field)
 - » The Stop and Wait variant is used (unit window and modulo 2 numbering)

Format and types of frames

» Information Frames (I)

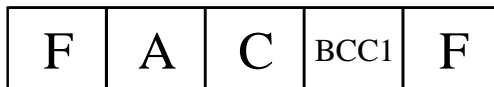


(before stuffing and
after destuffing)

F **Flag**
A **Address Field**
C **Control Field**
D₁ ... D_N **Information Field (contains packets generated by Application)**
BCC_{1,2} **Independent Protection Fields (1 – header, 2 – data)**

0 S 0 0 0 0 0 0 S = N(s)

» Supervision (S) and Unnumbered (U) Frames



F **Flag**
A **Address Field**
C **Control Field**
 SET (set up)
 DISC (disconnect)
 UA (unnumbered acknowledgment)
 RR (receiver ready / positive ACK)
 REJ (reject / negative ACK)
BCC₁ **Protection Field (header)**

0 0 0 0 0 0 1 1
0 0 0 0 1 0 1 1
0 0 0 0 0 1 1 1
R 0 0 0 0 1 0 1
R 0 0 0 0 0 0 1 R = N(r)

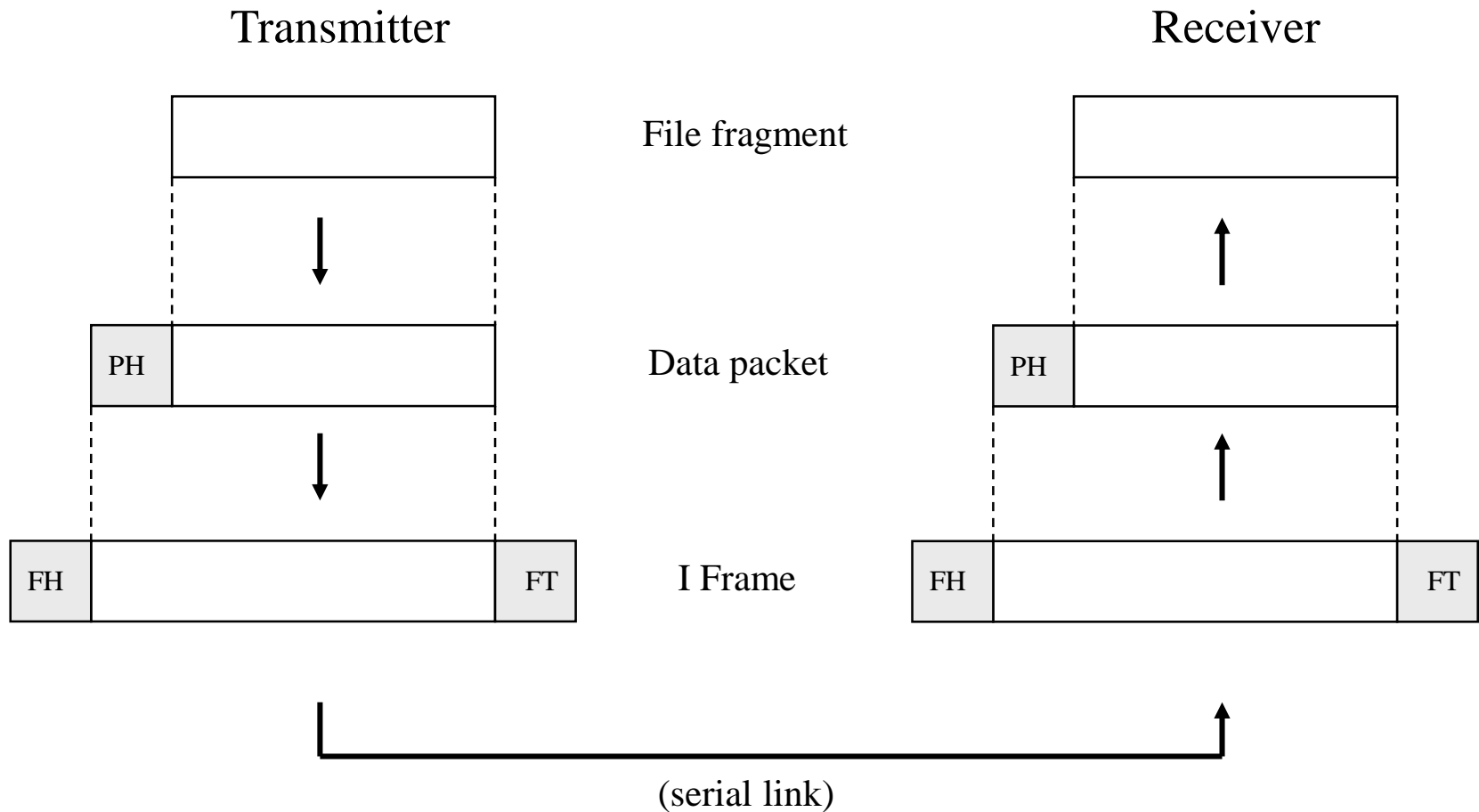
Packets and frames

- » The file to be transmitted is fragmented - the fragments are encapsulated in data packets and these are carried in the I frames data field
 - In addition to data packets (which contain file fragments), the Application protocol uses control packets
 - The format of the packets (data and control) is defined ahead

- » The Transmitter is the machine that sends the file and the Receiver is the machine that receives the file
 - Only the Transmitter transmits packets (data or control) and therefore only the Transmitter transmits I frames

- » Both the Transmitter and the Receiver send and receive frames

Data packets and I frames



PH – *Packet Header*
FH – *Frame Header*
FT – *Frame Trailer*

Control packets are also transported in I frames

Frames - Delimitation and header

- » All frames are delimited by flags (**01111110**)
- » A frame can be started with one or more flags, which must be taken into account by the frame reception mechanism
- » Frames I, SET and DISC are designated Commands and the rest (UA, RR and REJ) are called Answers
- » Frames have a header with a common format
 - A (Address Field)
 - **00000011 (0x03)** in Commands sent by the Transmitter and Replies sent by the Receiver
 - **00000001 (0x01)** in Commands sent by the Receiver and Replies sent by the Transmitter
 - C (Control Field) – defines frame type and carries sequence numbers N(s) in I frames and N(r) in Supervision frames (RR, REJ)
 - BCC (Block Check Character) - error detection based on the generation of an octet (BCC) such that there is an even number of 1s in each position (bit), considering all octets protected by the BCC (header or data, as appropriate) and the BCC itself (before stuffing)

Reception of frames - Procedures

- » I, S or U frames with wrong header are ignored without any action
- » The data field of the I frames is protected by its own BCC (even parity on each bit of the data octets and the BCC)
- » I frames received with no errors detected in the header and data field are accepted for processing
 - If it is a new frame, the data field is accepted (and passed to the Application), and the frame must be confirmed with RR
 - If it is a duplicate, the data field is discarded, but the frame must be confirmed with RR
- » I frames with no header error detected but error detected (by the respective BCC) in the data field – the data field is discarded, but the control field can be used to trigger an appropriate action
 - If it is a new frame, it is convenient to make a retransmission request with REJ, which allows to anticipate the occurrence of time-out in the transmitter
 - If it is a duplicate, it must be confirmed with RR
- » I, SET and DISC frames are protected by a timer
 - In the event of a time-out, a maximum number of retransmission attempts must be made (the value must be configurable; for example, three)

Transparency - Necessity

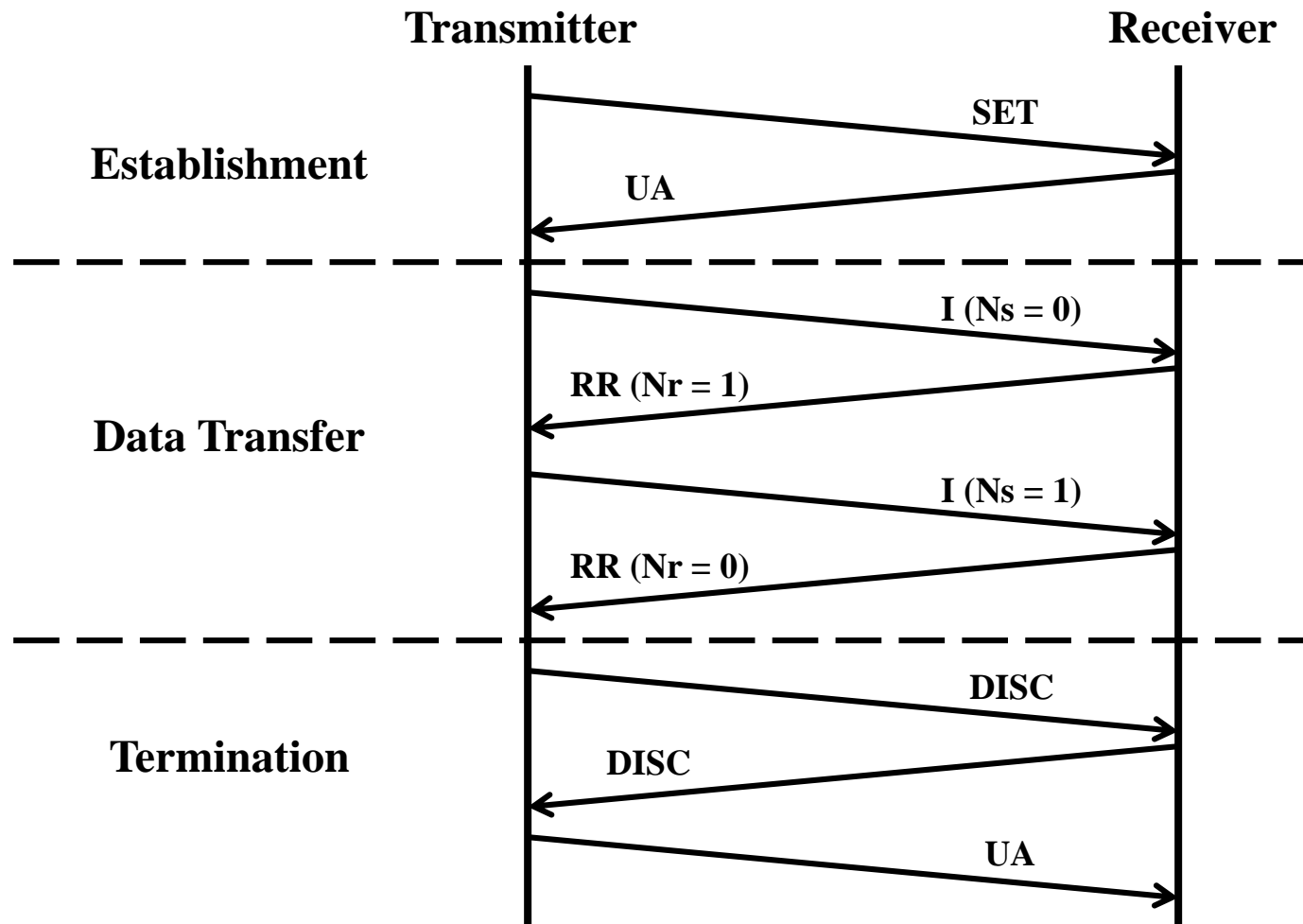
- » The transmission between the two computers is, in this work, based on a technique called asynchronous transmission
 - This technique is characterized by the transmission of "characters" (short string of bits, whose number can be configured) delimited by Start and Stop bits
 - Some protocols use characters (words) of a code (for example ASCII) to delimit and identify the fields that constitute the frames and to support the execution of the protocol mechanisms
 - In these protocols, the transmission of data transparently (regardless of the code used by the protocol) requires the use of escape mechanisms
- » The protocol to be implemented is not based on the use of any code, so the transmitted characters (consisting of 8 bits) must be interpreted as simple octets (bytes), and any of the 256 possible combinations can occur
- » To avoid the false recognition of a flag inside a frame, a mechanism that guarantees transparency is needed

Transparency – Byte stuffing mechanism

- » In the protocol to be implemented, the mechanism used in PPP is adopted, which uses the escape octet **01111101 (0x7d)**
 - If the octet **01111110 (0x7e)** occurs inside the frame, i.e., the pattern that corresponds to a flag, the octet is replaced by the sequence **0x7d 0x5e** (escape octet followed by the result of the exclusive or of the octet replaced with the octet 0x20)
 - If the octet 01111101 (0x7d) occurs inside the frame, i.e., the pattern that corresponds to the escape octet, the octet is replaced by the sequence **0x7d 0x5d** (escape octet followed by the result of the exclusive or of the octet replaced with the octet 0x20)
 - In the BCC generation, only the original octets are considered (before the stuffing operation), even if some octet (including the BCC itself) has to be replaced by the corresponding escape sequence
 - The verification of the BCC is carried out in relation to the original octets, i.e., after the inverse operation (destuffing) has been performed, if the replacement of any of the special octets by the corresponding escape sequence has occurred

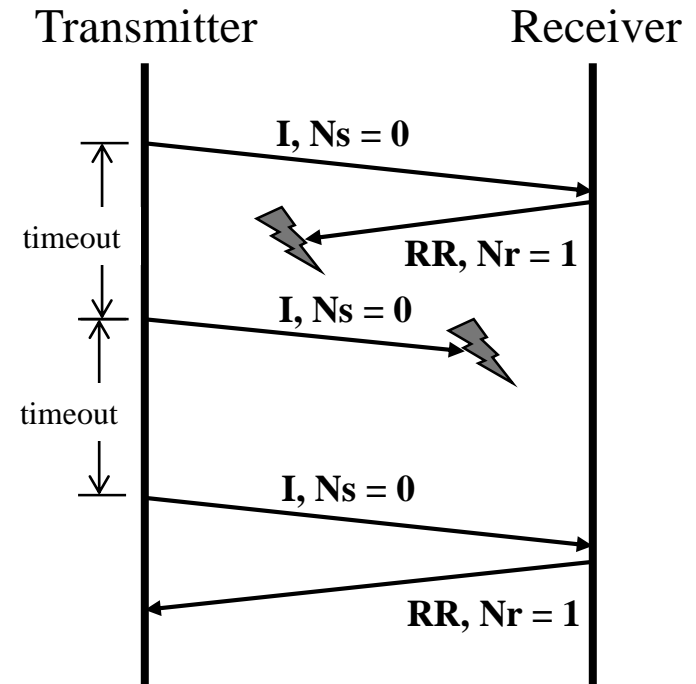
Data Link Protocol phases

» Example of a typical frame sequence (without errors)

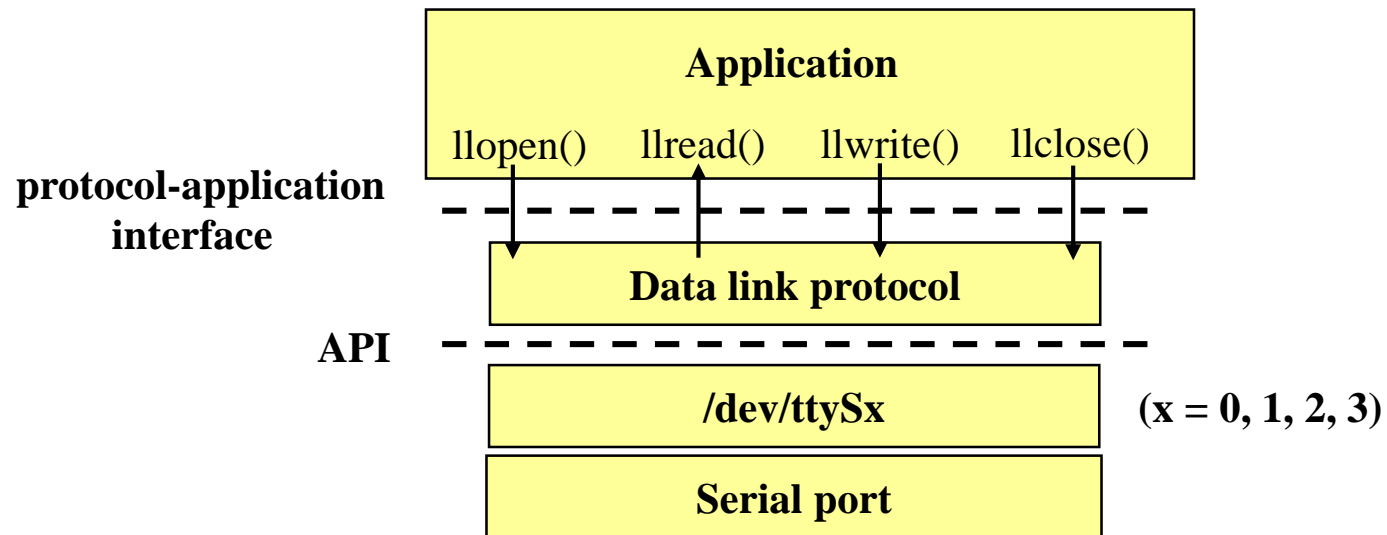


Data transfer – Retransmissions

- Acknowledgement / Error Control
 - » Stop-and-Wait
- Timer
 - » Enabled after an I, SET or DISC frame
 - » Disabled after a valid acknowledgement
 - » If acceded (timeout), forces retransmission
- I frames retransmission
 - » After a time-out, due to loss of the I frame or its acknowledgement
 - Maximum number of predefined (configured) retransmission attempts
 - » After a receiving a negative acknowledgement (REJ)
- Frame protection
 - » Generation and verification of the protection fields (BCC)



Protocol-Application interface



Protocol-Application interface

- Examples of data structures

- » Application

```
struct applicationLayer {  
    int fileDescriptor;    /*Serial port descriptor*/  
    int status;            /*TRANSMITTER | RECEIVER*/  
}
```

- » Protocol

```
struct linkLayer {  
    char port[20];          /*Device /dev/ttySx, x = 0, 1*/  
    int baudRate;           /*Speed of the transmission*/  
    unsigned int sequenceNumber; /*Frame sequence number: 0, 1*/  
    unsigned int timeout;    /*Timer value: 1 s*/  
    unsigned int numTransmissions; /*Number of retries in case of  
                                failure*/  
    char frame[MAX_SIZE];    /*Frame*/  
}
```

Protocol-Application interface – open

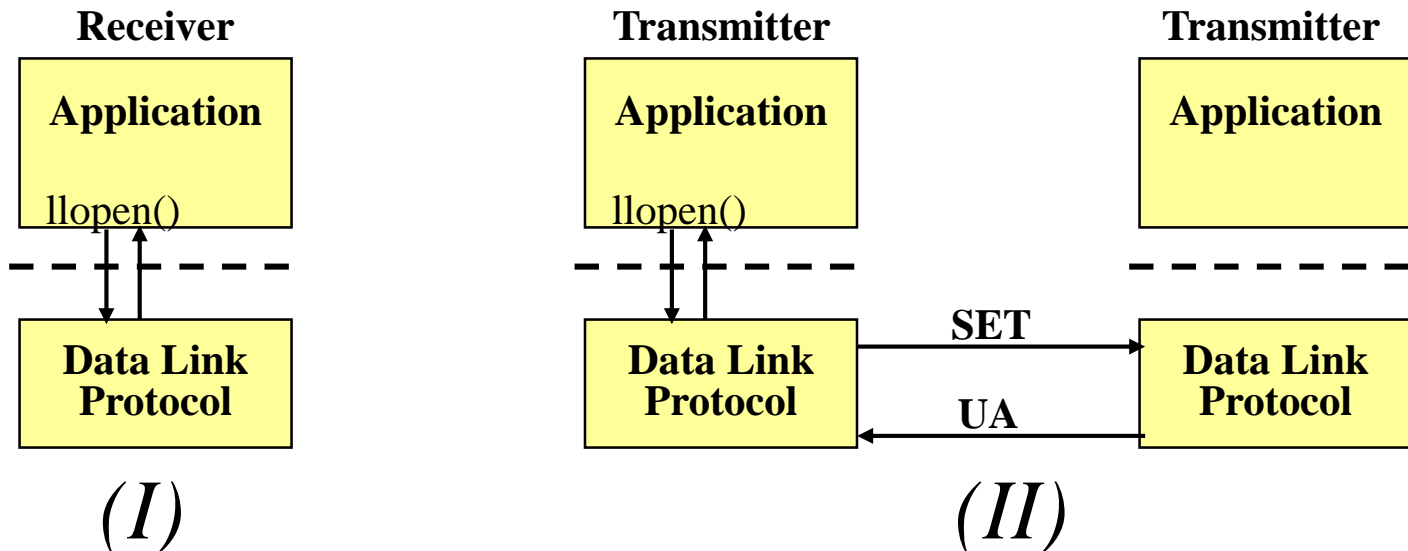
`int llopen(int porta, TRANSMITTER | RECEIVER)`

arguments

- port: COM1, COM2, ...
- flag: TRANSMITTER / RECEIVER

return

- data link identifier
- Negative value in case of error



Protocol-Application interface – read / write

`int llwrite(int fd, char * buffer, int length)`

arguments

- fd: data link identifier
- buffer: array of characters to transmit
- length: length of the characters array

return

- number of writer characters
- negative value in case of error

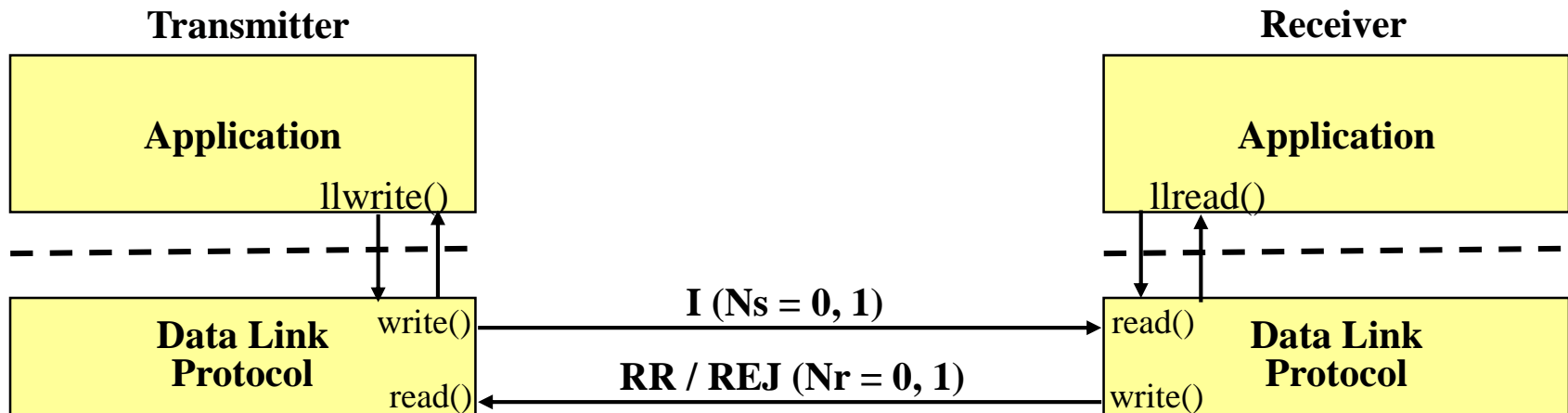
`int llread(int fd, char * buffer)`

arguments

- fd: data link identifier
- buffer: array of characters read

return

- array length (number of characters read)
- negative value in case of error



Protocol-Application interface – close

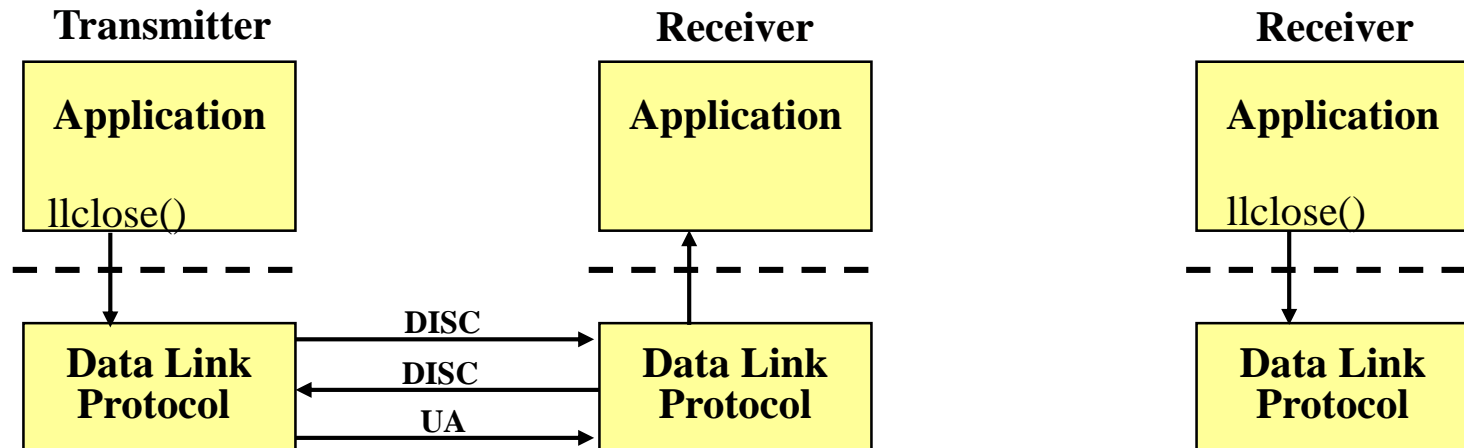
`int llclose(int fd)`

arguments

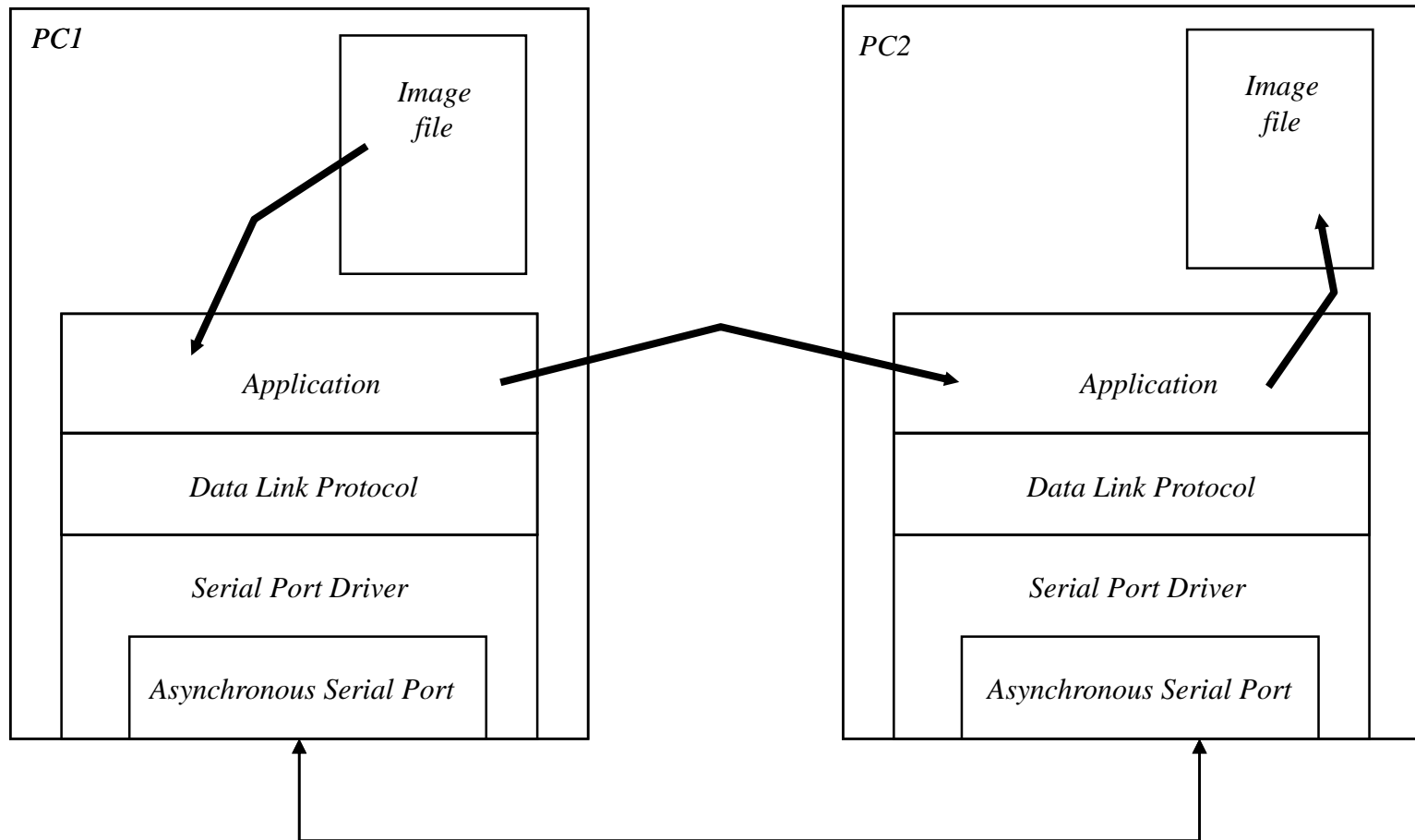
- `fd`: data link identifier

return

- positive value in case of success
- Negative value in case of error



Test application

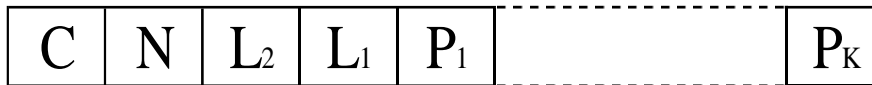


Test application - Specification

- The goal is to develop a very simple application protocol for transferring a file, using the reliable service offered by the data link protocol
- The application must support two types of packets sent by the Transmitter
 - » Control packages to signal the start and end of file transfer
 - » Data packets containing fragments of the file to be transmitted
- The control package that signals the beginning of the transmission (start) must have a field with the file size and optionally a field with the file name (and possibly other fields)
- The control packet that signals the end of transmission (end) shall repeat the information contained in the start packet
- Data packets must contain a field (one octet) with a sequence number and a field (two octets) that indicates the size of the respective data field
 - » This size depends on the maximum size of the Information field of frames I
 - » These fields allow for additional checks regarding data integrity
 - » The numbering of data packets is independent of the numbering of frames I

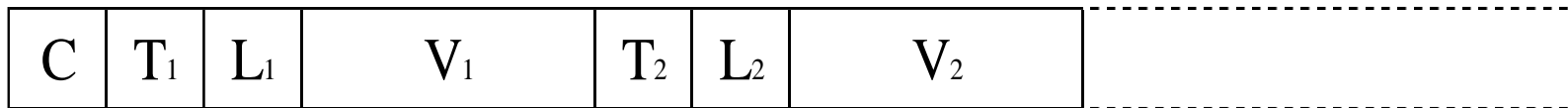
Application layer packets

- Data packet



- » C – control field (value: 1 – data)
- » N – sequence number (modulo 255)
- » L₂ L₁ – number of octets (K) in the data field (K = 256 * L₂ + L₁)
- » P₁ ... P_K – packet data field (K octets)

- Control packet



- » C – control field (values: 2 – start; 3 – end)
- » Each parameter (size, file name or other) is coded as TLV (Type, Length, Value)
 - T (one octet) – indicates the parameter (0 – file size, 1 – file name, other values – to be defined, if necessary)
 - L (one octet) – indicates the V field size in octets (parameter value)
 - V (number of octets indicated in L) – parameter value

Layer Independency

- Layered architectures are based on the principle of independence between layers.
- The application of this principle has the following consequences in the scope of this work:
 - » At the data link layer, no processing is done that affects the header of packets to be transported in Information frames - this information is considered inaccessible to the data link protocol
 - At the data link level there is no distinction between control and data packets, nor is the numbering of data packets relevant (nor taken into account).
 - » The application layer does not know the details of the data link protocol, only how it accesses the service.
 - The application protocol does not know the structure of the frames and the respective delineation mechanism, the existence of stuffing (and which option is adopted), the protection mechanism of the frames, any eventual retransmissions of Information frames, etc.
 - All these functions are exclusively performed in the data link layer.
 - » In particular, the I frame and data packet numbering mechanisms are totally independent and no relationship should be established between them.

Evaluation

- Data link protocol
 - » Frame synchronization process
 - » Retransmission process
 - » Robustness to errors
 - » Error control
- Application protocol
 - » Control packets
 - » Data packet numbering
- Code organization
 - » Interface between layers (functions)
 - » Layer independency
- Statistical characterization of the protocol efficiency (see next slide)
- Demonstration and report
- Penalties
 - » Delays on the demo and / or report submission

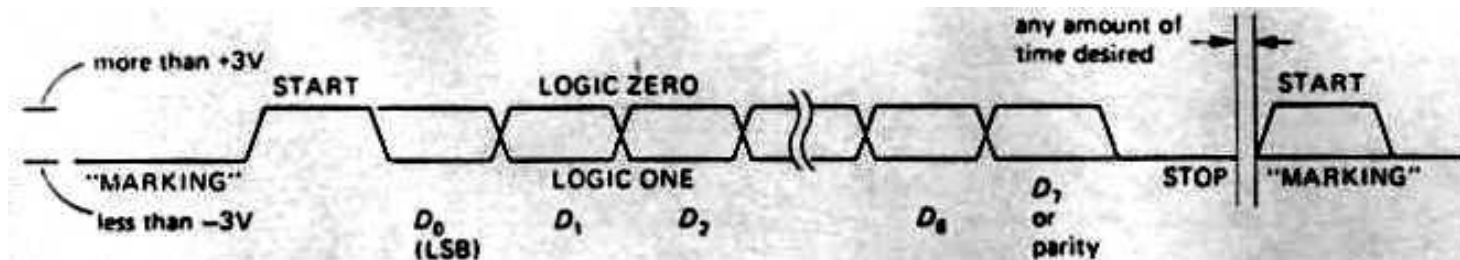
Evaluation – protocol efficiency

- Statistical characterization of efficiency S (FER, a). Suggestions:
 - » 1) vary FER, T_{prop} , C , size of I frame (C = link capacity, bit/s)
 - » 2) measure the obtained transference time $S = R/C$ (R =received bitrate, bit/s)
 - » 3) plot S (FER, a) and check the validity of the known formulas for efficiency
 - » 4) repeat measurements
- To vary FER: random error generation on Information frames
 - » Suggestion – for each I frame correctly received, simulate (at the receiver) the occurrence of a header error and on the data field with pre-defined (and independent) probabilities, and proceed as a normal error
- To vary T_{prop} : generation of a simulated propagation delay
 - » Suggestion – use alarm.c to include a processing delay on each received frame

Annexes

Asynchronous serial transmission

- » Each character is delimited by
 - Start bit
 - Stop bit (typically 1 or 2)
- » Each character consists of 8 bits (D0 – D7)
- » Parity
 - Even – even number of 1s
 - Odd – uneven number of 1s
 - Inhibited (D7 bit used for data) – option adopted in this link layer protocol
- » Transmission rate: 300 a 115200 bit/s



RS-232 Signals

- Physical layer protocol between a computer or terminal (DTE) and modem (DCE)
 - » DTE (*Data Terminal Equipment*)
 - » DCE (*Data Circuit-Terminating Equipment*)

Connectors DB25 e DB9

Active signal

Control signal ($> + 3 \text{ V}$)

Data signal ($< - 3 \text{ V}$)

DTR (Data Terminal Ready) – Computer on

DSR (Data Set Ready) – Modem on

DCD (Data Carrier Detected) – Modem detects phone line carrier

RI (Ring Indicator) – Modem detects ring

RTS (Request to Send) – Computer ready to communicate

CTS (Clear To Send) – Modem ready to communicate

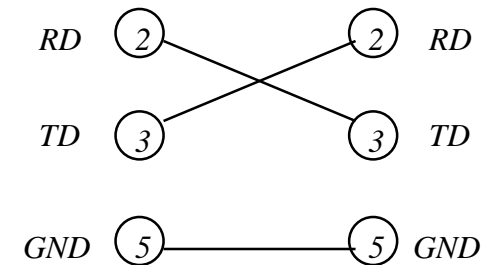
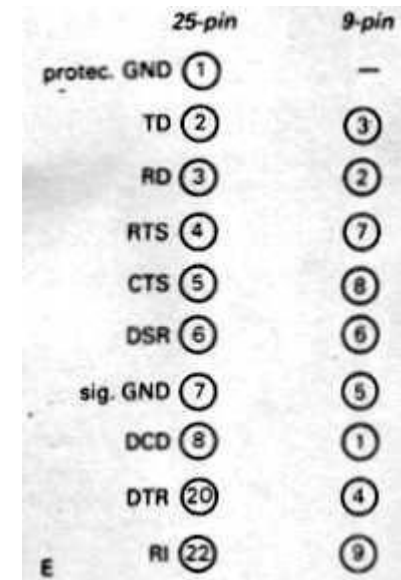
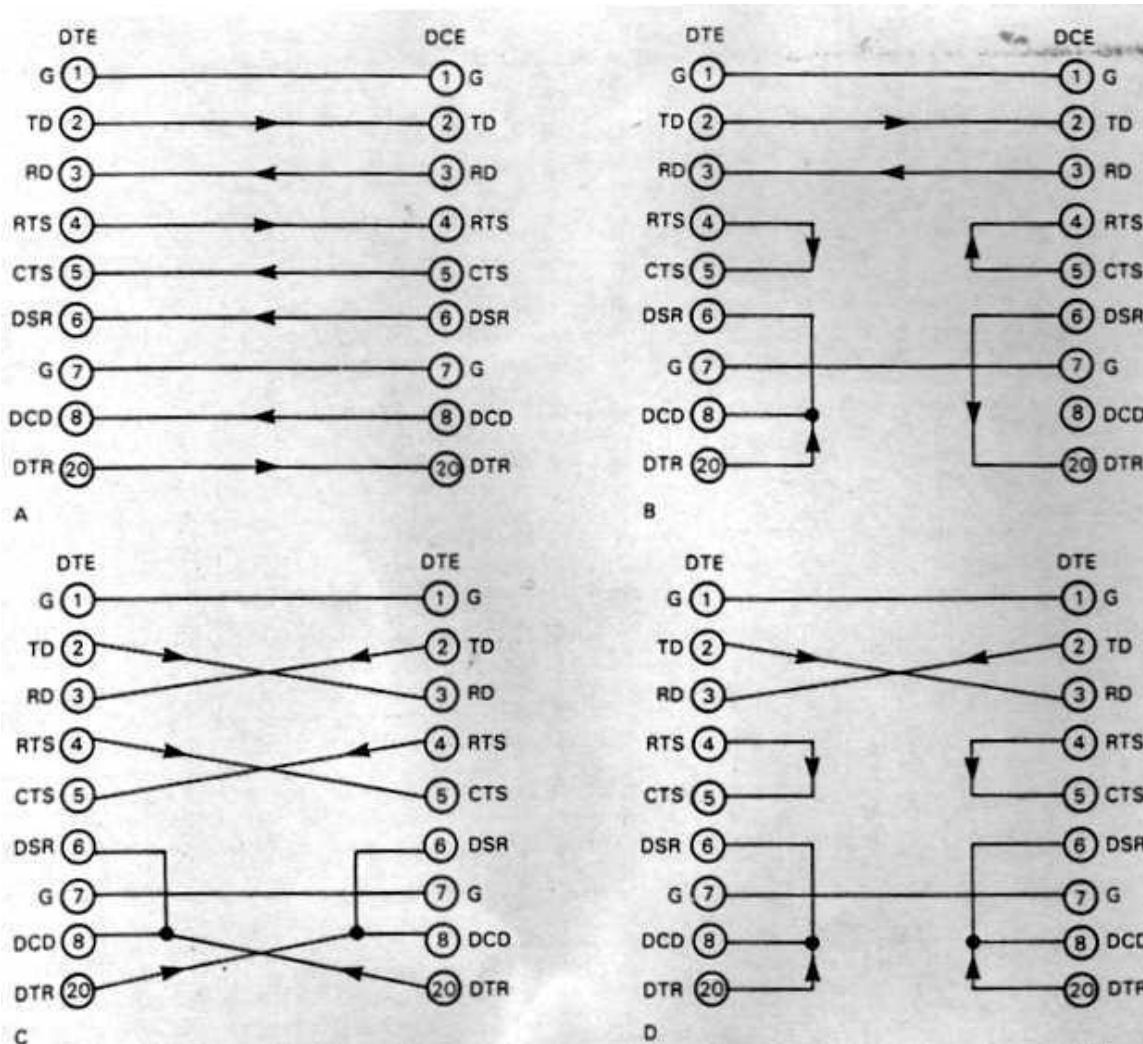
TD (Transmit data) – Data transmission

RD (Receive data) – Data reception

TABLE 10.4. RS-232 SIGNALS

Name	Pin number		Direction (DTE↔DCE)	Function (as seen by DTE)	
	25-pin	9-pin			
TD	2	3	→	transmitted data	} data pair
RD	3	2	←	received data	
RTS	4	7	→	request to send (= DTE ready)	} handshake pair
CTS	5	8	←	clear to send (= DCE ready)	
DTR	20	4	→	data terminal ready	} handshake pair
DSR	6	6	←	data set ready	
DCD	8	1	←	data carrier detect	} enable DTE input
RI	22	9	←	ring indicator	
FG	1	–		frame ground (= chassis)	
SG	7	5		signal ground	

Connections between equipment



Null Modem (9 pinos)

Unix Drivers

» Characteristics

- Software that manages a hardware controller
- Set of low level routines with privileged execution access
- Reside in memory (they are part of the kernel)
- Hardware interruption associated

» Access method

- Mapped into Unix file system (`/dev/hda1`, `/dev/ttyS0`)
- Offered services similar to files (*open*, *close*, *read*, *write*)

» Driver types

- Character
 - Read and write from the controlled as multiple characters
 - Direct access (data is not stored in buffers)
- Block
 - Read/write as multiples of a block (block = 512 or 1024 octets)
 - Data sorted in buffers and random access
- Network
 - Read and write variable size packets
 - Sockets interface

Serial Port Driver – API

termios data structure – allows to configure and store the serial port configuration parameters

```
struct termios {
    tcflag_t    c_iflag;    /*reception configuration flags*/
    tcflag_t    c_oflag;    /*transmission configuration flags*/
    tcflag_t    c_cflag;    /*control flags*/
    tcflag_t    c_lflag;    /*local configuration flags*/
    cc_t        c_line;     /*not used*/
    cc_t        c_cc[NCCS]  /*control characteres; NCCS = 19*/
};
```

Example:

```
#define BAUDRATE B38400
struct termios newtio;

/* CS8:      8n1 (8 bits, without parity bit, 1 stopbit)*/
/* CLOCAL:   local connection, without modem*/
/* CREAD:    enables the reception of characters*/
newtio.c_cflag = BAUDRATE | CS8 | CLOCAL | CREAD;

/* IGNPAR:   Ignores parity bits errors*/
/* ICRNL:    Converts CR into NL*/
newtio.c_iflag = IGNPAR | ICRNL;

newtio.c_oflag = 0;    /*Output not processed*/

/* ICANON:   enables the canonic reception */
newtio.c_lflag = ICANON;
```

Serial port reception types

- **Canonic**
 - » *read()* returns only full lines (ended by ASCII LF, EOF, EOL)
 - » Used for terminals
- **Non-canonic**
 - » *read ()* returns up to a maximum number of characters
 - » Enables the configuration of a maximum time between each character read
 - » Suitable for reading groups of characters
- **Asynchronous**
 - » *read()* returns immediately
 - » Uses a *signal handler*

Code examples

Canonic Reception

```
main() {

int fd,c, res;
struct termios oldtio,newtio;
char buf[255];

fd = open(/dev/ttyS1,O_RDONLY|O_NOCTTY);
tcgetattr(fd,&oldtio);

bzero(&newtio, sizeof(newtio));
newtio.c_cflag = B38400|CS8|CLOCAL|CREAD;
newtio.c_iflag = IGNPAR|ICRNL;
newtio.c_oflag = 0;
newtio.c_lflag = ICANON;
tcflush(fd, TCIFLUSH);
tcsetattr(fd,TCSANOW,&newtio);

res = read(fd,buf,255);

tcsetattr(fd,TCSANOW,&oldtio);
close(fd);
}
```

Non-canonic Reception

```
main() {

int fd,c, res;
struct termios oldtio,newtio;
char buf[255];

fd = open(argv[1], O_RDWR | O_NOCTTY );
tcgetattr(fd,&oldtio);

bzero(&newtio, sizeof(newtio));
newtio.c_cflag = B38400 | CS8 | CLOCAL | CREAD;
newtio.c_iflag = IGNPAR;
newtio.c_oflag = 0;
newtio.c_lflag = 0;
newtio.c_cc[VTIME] = 0; /* timer between characters
newtio.c_cc[VMIN] = 5; /* block until 5 characters
are read */

tcflush(fd, TCIFLUSH);
tcsetattr(fd,TCSANOW,&newtio);

res = read(fd,buf,255); /* at least 5 characters */

tcsetattr(fd,TCSANOW,&oldtio);
close(fd);
}
```

Code examples

Asynchronous Reception

```
void signal_handler_IO (int status); /* signal
handler definition */
main() {
    /* variables declaration and serial port open */
    saio.sa_handler = signal_handler_IO;
    saio.sa_flags = 0;
    saio.sa_restorer = NULL; /* obsolete */
    sigaction(SIGIO,&saio,NULL);
    fcntl(fd, F_SETOWN, getpid());
    fcntl(fd, F_SETFL, FASYNC);
    /* serial port configuration through the termios
    structure */
    while (loop) {
        write(1, ".", 1);usleep(100000);
        /* after SIGIO signal, wait_flag = FALSE, data
        available to read */
        if (wait_flag==FALSE) {
            read(fd,buf,255); wait_flag = TRUE; /*
            waiting for new data to be read */
        }
    }
    /* configure the serial port with the initial
    values and close */
}
void signal_handler_IO (int status) { wait_flag =
FALSE; }
```

Multiple Reception

```
main(){
    int fd1, fd2; /*input sources 1 and 2*/
    fd_set readfs; /*file descriptor set */
    int maxfd, loop = 1; int loop=TRUE;
    /* open_input_source opens a device, sets the
    port correctly, and returns a file descriptor */
    fd1 = open_input_source("/dev/ttyS1"); /*
    COM2 */
    fd2 = open_input_source("/dev/ttyS2"); /*
    COM3 */
    maxfd = MAX (fd1, fd2)+1; /*max bit entry
    (fd) to test*/
    while (loop) { /* loop for input */
        FD_SET(fd1, &readfs); /* set testing for
        source 1 */
        FD_SET(fd2, &readfs); /* set testing for
        source 2 */
        /* block until input becomes available */
        select(maxfd, &readfs, NULL, NULL, NULL);
        if (FD_ISSET(fd1)) /* input from
        source 1 available */
            handle_input_from_source1();
        if (FD_ISSET(fd2)) /* input from
        source 2 available */
            handle_input_from_source2();
    }
}
```