# (Towards) A pervasive real-time blood pressure system:

Estimation Models and Events Detector

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### 1. Context

¼ of adult population suffers from hypertension.

 Current BP devices can not be used continuously on a daily basis.

 A solution would be very useful for managing hypertension and prevent cardiovascular disease.

### 2. BP Estimation Models

Model 1- PTT only:

$$BP = a \cdot PTT + b$$

Model 2- PTT and HR (Reference model):

$$BP = a \cdot PTT + b \cdot HR + c$$

More robust to noisy measurements than other models derived from the Moens-Korteweg equation.

**PTT** — Pulse Transit Time (time duration between ECG peak and PPG peak/foot/max\_slope)

**HR** – Instantaneous heart rate

{a,b,c} — Unknown model parameters

### 3. Parameter Estimation

Dataset containing 69 records of invasive BP, ECG and PPG.

- Offline Methods Access all values of invasive BP to calculate the unknown parameters and study their behaviour.
- Online Methods Access only the necessary values of invasive BP to calibrate the system.

Study of BP is focused on Systolic BP (SBP) as it conveys more medical information than Diastolic BP (DBP).

## 3. Parameter estimation Offline methods

#### **Least Squares Fitting (LSF):**

 Determines the {a,b,c} set that minimizes the Squared Error (MSE).

#### **Recursive Least Squares (RLS):**

- Unknown parameters are re-calculated each iteration;
- Requires an observed value of SBP.

#### **Exponentially Weighted Regression (EWR):**

- Extension of the RLS;
- Greater weight is given to more recent data;
- Forgetting factor,  $\lambda \in ]0,1]$ .



### 3. Parameter estimation Online methods

**Exponentially-Weighted Regression** (EWR) with calibration period T:

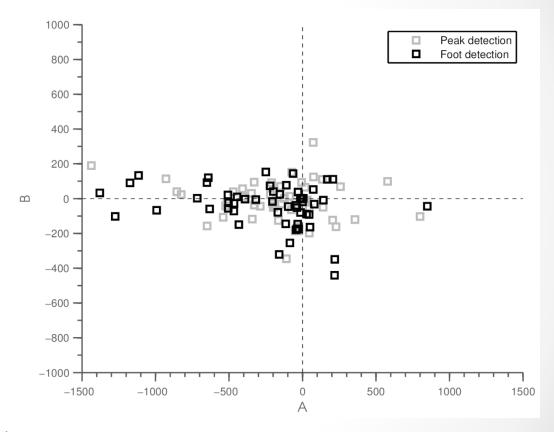
- Initial calibration is conducted in the first 5 minutes.
- EWR is applied every T minutes to re-calculate {a,b,c}.
- Requires an observation of SBP.
- Simulates the real operating environment.



## 4. Results Offline methods

#### LSF method:

- 17 out of 69 records did not meet AAMI's clinical requirement †.
- No strong relantionship between a and b (ρ = -0.190).
- Not enough data to explain bad performance cases.



**†** - AAMI's requirement: Measurements' error means between [-5,5] mmHg and standard deviations below 8 mmHg.

**Fig 1.** Distribution of pairs *a*, *b* obtained by LSF, using Model 2, for records that met AAMI's requirement.



## 4. Results Online methods

- STD and MSE increase considerably with T.
- Parameters become less meaningful within 30 to 60 minutes of operation.

	EWR with period T – Estimation errors				
Calibration period	Mean (mmHg)	St.D. (mmHg)	MSE (mmHg <sup>2</sup> )		
T=1 min	-0.17	4.63	36.94		
T = 5 min	-0.51	6.76	105.65		
T = 15 min	-0.48	7.96	163.81		
T = 30 min	-0.77	8.68	228.23		
$T = \infty$	-1.48	9.96	373.64		

**Table 1.** Estimation errors for Model 2, averaged over all records, applying the EWR algorithm with different periods of calibration T,  $T = \infty$  denotes that no re-calibration is performed after the initial calibration.

## 4. Results Online methods

- Large variability of parameters between calibrations.
- That may be due to noisy measurements of SBP, PTT and HR.
- Robustness enhancement may be applied.

	EWR with period $T$ - Parameters			
Calibration period	Mean(a)	Std(a)	Mean(b)	Std(b)
T = 1 min	-206.87	252.49	-26.66	88.70
T = 5 min	-229.95	260.41	-46.79	95.06
T = 15 min	-178.25	263.23	-47.00	90.91
T = 30 min	-144.33	300.74	-28.00	83.69
$T = \infty$	-283.46	0.00	-46.99	0.00

**Table 2.** Mean and standard deviation of the unknown parameters calculated initially and re-calculated at every point of calibration.  $T = \infty$  denotes that no re-calibration is performed after the initial one.

## 5. BP Event Detector (BED) Motivation

- Full to partial similarity in 71% of the records.
- BP event:
  - Variation of amplitude 20 mmHg or higher.
  - o 20 minutes time windows.
- Can the estimation models detect the majority of BP events?

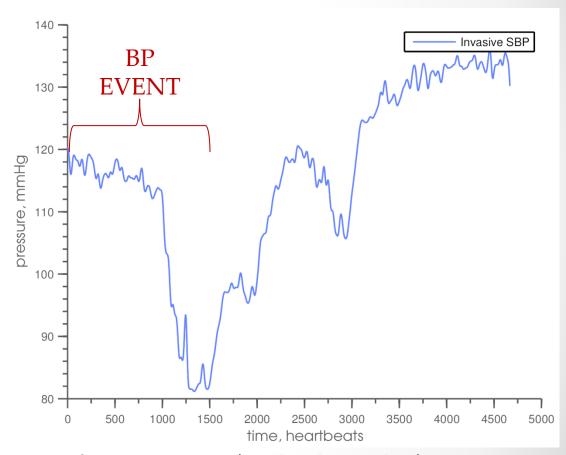


Fig 3. BP event example on invasive SBP signal.





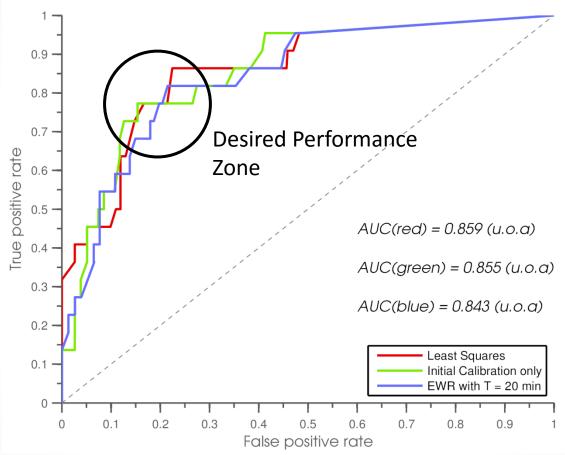
## 5. BP Event Detector (BED) Steps

STEPS in a BP event detection sequence:

- 1. Generation of Ground Truth
- 2. Get estimated SBP signals and detection of events
- 3. Processing of events
- 4. Comparison of events and performance metrics
- 5. Generation of a ROC curve by applying steps 2-4 repeatedly for threshold values varying from [0, 80], with  $\Delta = 0.5$



## 5. BP Event Detector (BED) Results



**Fig 3.** ROC performance curves for SBP event detection using three methods of estimating SBP.



### Conclusions

#### In overall, a PTT-based model:

- Does not meet requirements for continuous BP measurement.
- Can detect BP events.
- Provides reasonable performance for online methods, using a threshold of 12.5 mmHg.
- Can be integrated with current technology for ABPM for BP event detection.

### Future Work

- Circadian study of parameters.
- Objective method to measure signal resemblance.
- Enhance robustness in online methods.
- Use a larger clinically marked dataset for BP event detection.



