# The Why and How of Nonnegative Matrix Factorization Topic Presentation

Group 2 — Aurlie de Borman, Jennifer Leclipteur, Gilles Peiffer, and Minh-Phuong Tran

LINMA2380 — Matrix computations

December 10, 2020

### Summary

**Use**: Analysis of high-dimensional data by automatically extracts sparse and meaningful features from a set of nonnegative data vectors

- What : Definitions as introduction
- Why : Applications
- How: Formal view and algorithmic difficulties
- What next : Connections to other problems
- Conclusion

### What: Definitions and properties

Nonnegative matrix factorization (NMF) is a Linear dimensionality reduction (LDR)

**NMF** : decomposing a given nonnegative data matrix X as  $X \approx WH$  where  $W \geq 0$  and  $H \geq 0$ 

#### LDR:

- From a set of data points  $x_j \in \mathbb{R}^p$  for  $1 \leq j \leq n$
- To a set of dimension r < min(p, n)
- Thanks to  $w_k \in R^p$  for  $1 \le k \le r$
- Such that :  $\forall j, x_j \approx \sum_{k=1}^r w_k h_j(k)$ , for some weights  $h_j \in R^r$

Equivalent to low-rank matrix approximation :  $X \approx WH$ 



### Applications - Image processing

Goal: Facial Feature Extraction



Data matrix :  $X \in \mathbb{R}^{p \times n}_+$ 

- lacksquare p: total number of pixels
- $\blacksquare$  n : number of faces
- lacksquare X(i,j) : the gray-level of the i-th pixel in the j-th face

### Applications - Image processing

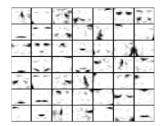






W(:,k)

facial features



H(k,j)

importance of features in jth image

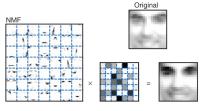


WH(:,j)

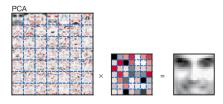
approximation of jth image



### Applications - Image processing



NMF decomposition



PCA decomposition

### Applications - Text Mining

Goal: Topic Recovery and Document Classification

Data matrix :  $X \in \mathbb{R}^{n \times m}_+$ 

- each column : a document
- each line: a word
- lacksquare X(i,j) : number of times the i-th word appears in the j-th document

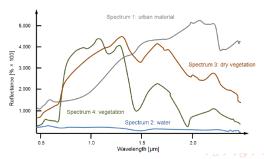
$$\underbrace{X(:,j)}_{j\text{th document}} \approx \sum_{k=1}^r \underbrace{W(:,k)}_{k\text{th topic}} \underbrace{\underbrace{H(k,j)}}_{\text{importance of $k$th topic}}, \quad \text{with $W \geq 0$ and $H \geq 0$.}$$

### Applications - Hyperspectral Unmixing

#### Goal:

- Identify the constitutive materials present in an image
- Classify the pixels according to their constitutive materials

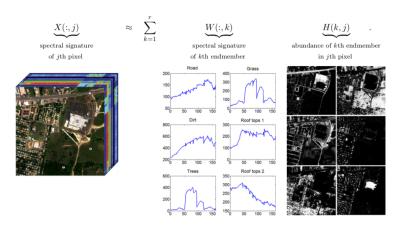
**Spectral signature** of a pixel: fraction of incident light being reflected by that pixel at different wavelengths



### Applications - Hyperspectral Unmixing

Data matrix :  $X \in \mathbb{R}^{n \times p}$ 

each column: spectral signature of a pixel



### Optimization Problem

■ Mathematical formulation:  $\min_{W \in \mathbb{R}^{p \times r}, H \in \mathbb{R}^{r \times n}} \|X - WH\|_{\mathsf{F}}^2$ , such that  $W \ge 0$ .  $H \ge 0$ .

### Optimization Problem

- Mathematical formulation:  $\min_{W \in \mathbb{R}^{p \times r}, H \in \mathbb{R}^{r \times n}} \|X WH\|_{\mathsf{F}}^2$ , such that  $W \geqslant 0$ ,  $H \geqslant 0$ .
- Frobenius norm **assumption**: noise is *Gaussian*.

### Optimization Problem

- Mathematical formulation:  $\min_{W \in \mathbb{R}^{p \times r}, H \in \mathbb{R}^{r \times n}} ||X WH||_{\mathsf{F}}^2$ , such that  $W \ge 0, H \ge 0$ .
- Frobenius norm assumption: noise is Gaussian.
- Other possibilities:
  - Kullback-Leibler divergence, used in text mining;
  - Itakura-Saito distance, used in music analysis;
  - $\ell_1$  norm to improve robustness against outliers;
  - etc.

#### Issues

- NMF is NP-hard.
  - Because of nonnegativity constraints.
  - Unconstrained case can be solved efficiently using SVD.
  - Usually, NMF algorithms make certain assumptions and use heuristics to be faster.

#### Issues

- NMF is NP-hard.
  - Because of nonnegativity *constraints*.
  - Unconstrained case can be solved efficiently using SVD.
  - Usually, NMF algorithms make certain assumptions and use heuristics to be faster.
- NMF is **ill-posed**. Several "solutions" exist:
  - Using *priors* on the factors W and H (e.g. sparsity).
  - Appropriate *regularization* in the objective function.
  - Finding application-specific solutions is a very active area of research!

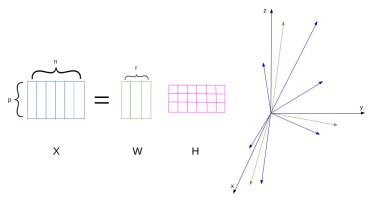
#### Issues

- NMF is NP-hard.
  - Because of nonnegativity constraints.
  - Unconstrained case can be solved efficiently using SVD.
  - Usually, NMF algorithms make certain assumptions and use heuristics to be faster.
- NMF is **ill-posed**. Several "solutions" exist:
  - Using *priors* on the factors W and H (e.g. sparsity).
  - Appropriate *regularization* in the objective function.
  - Finding application-specific solutions is a very active area of research!
- Choice of factorization rank r.
  - Trial and error.
  - Based on SVD.
  - Using expert knowledge (e.g. number of endmembers for HU application).

### Nonnegative rank

### Definition (Nonnegative rank)

Given  $X \in \mathbb{R}^{p \times n}_+$ , the nonnegative rank of X, denoted  $\operatorname{rank}_+(X)$  is the minimum r s.t.  $\exists W \in \mathbb{R}^{p \times r}_+, H \in \mathbb{R}^{r \times n}_+$  with X = WH.



### Graph Theory: Bipartite dimension

Let  $G(X) = (V_1 \cup V_2, E)$  be a bipartite graph induced by X (i.e.  $(i, j) \in E \Leftrightarrow X_{ij} \neq 0$ ).

#### Definition (Biclique and bipartite dimension)

- A biclique (or a complete bipartite graph) is a bipartite graph s.t. every vertex in  $V_1$  is connected to every vertex in  $V_2$ .
- The bipartite dimension (or the minimum biclique cover) bc(G(X)) is the minimum number of bicliques needed to cover all edges in E.

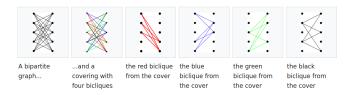


Figure: Example for biclique edge cover [biclique]

### Theorem (Rectangle covering bound)

$$bc(G(X)) \leq rank_{+}(X)$$

### Linear Optimization : Extended formulation

(LP) max 
$$c^T x$$
  $s.t.$   $Ax \leq b$   $x \in \mathbb{R}^n > 0$ 

#### Definition (Extended formulation)

The extended formulation of a polytope P is a higher dimensional polytope Q and a linear projection  $\pi$  s.t.  $\pi(Q) = P$ .

In our LP problem, an extended formulation of the polytope  $P \subset \mathbb{R}^n$  defined by the constraints  $Ax \leq b$ , is a polytope  $Q \subset \mathbb{R}^{n+r}$  defined by  $Cx + Dy \leq d$  with  $y \in \mathbb{R}^r$ , s.t.  $\pi(Q) = P$ .

The slack matrix  $X(i,j) = b_i - A_i v_j$ . With  $v_j$ , the  $j^{th}$  vertex of P and  $\{x \in \mathbb{R}^n | b_i - A_i x \geq 0\}$  its  $i^{th}$  facet. The (i,j) entry measures the slack of the  $i^{th}$  inequality for the  $j^{th}$  vertex.

### Theorem (Yannakis)

The minimum size of an extended formulation Q of P is equal to  $rank_+(X)$ .

When P has exponentially many facets, finding extended formulations allows to solve the LP in polynomial time.

## Thanks for listening!

Any questions?