

## Peiliang LI

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CONTACT INFORMATION	Clear Water Bay, Kowloon, Hong Kong	+852 5224 9248 pliap@connect.ust.hk
RESEARCH INTERESTS	Visual-inertial State Estimation, UAV navigation, Augmented Reality Computer Vision, Machine Learning, 3D Object Detection and Tracking	
EDUCATION	<b>Hong Kong University of Science and Technology</b> , Hong Kong, China Ph.D., Electronic & Computer Engineering, Sep 2016 - Jun 2021 ( <i>Expected</i> ) <ul style="list-style-type: none"><li>• Advisors: Prof. Shaojie SHEN</li></ul> <b>University of Science and Technology of China</b> , Hefei, China B.S., Electronics Science and Technology, Sep 2012 - Jun 2016 <ul style="list-style-type: none"><li>• Thesis of Bachelor: Design and Implementation of Visual-Inertial Odometry</li><li>• Advisor: Prof. Bensheng Qiu, Wei Lu</li></ul>	
EXPERIENCE	<b>Teaching Assistant</b> Mar 2017 - Jun 2017 & Mar 2018 - Present Hong Kong University of Science and Technology, ELEC 1110: Introduction to Electronic Robot Design <b>Teaching Assistant</b> Sep 2017 - Dec 2017 Hong Kong University of Science and Technology, ELEC 5660: Introduction to Aerial Robotics <b>Algorithm Intern</b> Jul 2015 to Aug 2016 DJI-Innovations Ltd, Shenzhen Moving object estimation and following, GPS-IMU fusion on mobile phone	
PUBLICATIONS & PREPRINT	<ol style="list-style-type: none"><li>1. <b>P. Li</b>, T. Qin, S. Shen. "Stereo Vision-based Semantic 3D Object and Ego-motion Tracking for Autonomous Driving." <i>In Proc. of the European Conference on Computer Vision (ECCV), Munich, Sep, 2018.</i></li><li>2. T. Qin, <b>P. Li</b>, S. Shen. "VINS-Mono: a Robust and Versatile Monocular Visual-Inertial State Estimator." <i>IEEE Transactions on Robotics (TR-O 2018).</i></li><li>3. T. Qin, <b>P. Li</b>, S. Shen. "Relocalization, global optimization and map merging for monocular visual-inertial SLAM." To appear in <i>In Proc. of the IEEE International Conference on Robotics and Automation (ICRA)</i>, Brisbane, Australia, May 2018.</li><li>4. <b>P. Li</b>, T. Qin, B. Hu, F. Zhu, S. Shen. "Monocular Visual-inertial State Estimation for Mobile Augmented Reality." <i>In Proc. of the IEEE International Symposium on Mixed and Augmented Reality (ISMAR)</i>, pages 11-21, Nantes, France, October 2017.</li></ol>	
AWARDS	Travel Awards <ul style="list-style-type: none"><li>• ISMAR conference, Nantes, France. Oct 2017</li></ul> Student Awards — University of Science and Technology of China <ul style="list-style-type: none"><li>• The Best Creative Award for DJI Developer Challenge Feb 2015</li><li>• The first Prize for USTC Electric Design Game Oct 2014</li><li>• "Guosheng Sun" Leadership Scholarship Sep 2014</li><li>• "Li Liu" Leadership Scholarship Sep 2013</li><li>• The Runner-Up for USTC RoboGame Oct 2013</li></ul>	