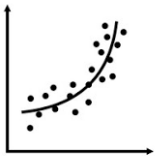


## Original Mapping

Input  
space  $\mathbf{X}$

nonlinear



limited  
samples



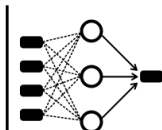
Mapping  $f$

Output  
Space  $\mathbf{Y}$

## Knowledge-Informed Mapping (KIM)

Sub-input space  
 $\mathbf{X}_j^S \in \mathbf{X}$

Mapping  $f$



Each output  
 $Y_j \in \mathbf{Y}$

**1. Filtering by global sensitivity analysis**  
 $\mathbf{X}_j^{S_1} = \{X_i: X_i \not\propto Y_j \text{ with } X_i \in \mathbf{X} \text{ and } Y_j \in \mathbf{Y}\}$

**2. Filtering by redundancy check**  
 $\mathbf{X}_j^S = \{X_i: X_i \not\propto Y_j \mid \mathbf{X}_j^{S_1} \setminus X_i \text{ with } X_i \in \mathbf{X}_j^{S_1}\}$

**3. Training ensemble neural networks (NN)**  
accounting for NN structure uncertainty