

KEY

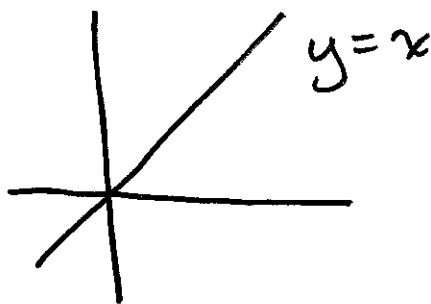
### Warm-up: Subspaces

Recall from Lesson 7...

Vector Subspace Theorem: a nonempty subset  $W$  of a vector space  $V$  is a subspace of  $V$  if it is closed under addition and scalar multiplication:

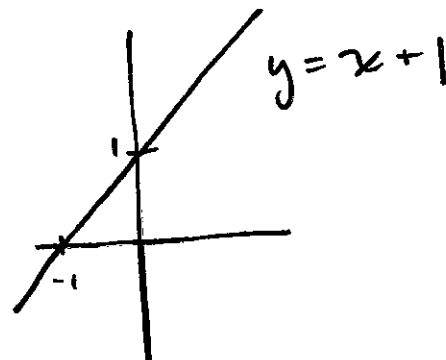
- (i) If  $\vec{x}, \vec{y} \in W$ , then  $\vec{x} + \vec{y} \in W$       (ii) If  $\vec{x} \in W$  and  $c \in \mathbb{R}$ , then  $c\vec{x} \in W$

1) Sketch the lines:  $y = x$  and  $y = x + 1$ . One line is a subspace of  $\mathbb{R}^2$ , one is not. Decide, then explain your reasoning.



subspace

includes  $(0,0)$ ; any  
vector that lies on  
the line is also a  
multiple of the others



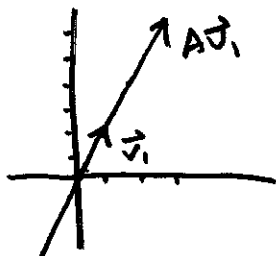
not a subspace

doesn't contain the  
origin

## Eigenspaces

2)a) In Activity 10 you had:  $A = \begin{bmatrix} 1 & 1 \\ 4 & 1 \end{bmatrix}$  which had eigenvectors:  $\vec{v}_1 = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$ , and  $\vec{v}_2 = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$ .

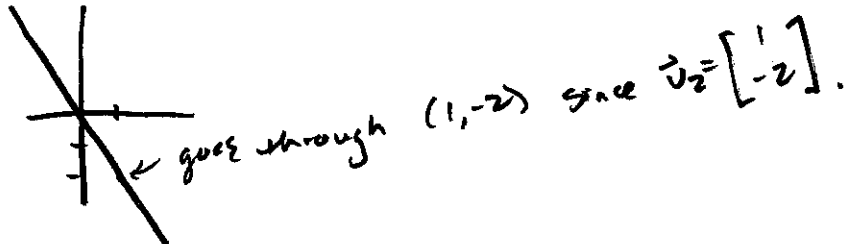
You also found that  $A\vec{v}_1 = \begin{bmatrix} 3 \\ 6 \end{bmatrix}$ . Sketch  $A\vec{v}_1$  and  $\vec{v}_1$  (on the same graph).



b) Looking back at (1), what can you say about  $\text{span}\{\vec{v}_1\}$ ?

It's the line that  $\vec{v}_1$  and  $A\vec{v}_1$  lie upon.

c) Sketch  $\text{span}\{\vec{v}_2\}$ . Is  $\text{span}\{\vec{v}_2\}$  a subspace of  $\mathbb{R}^2$ ?



We call the  $\text{span}\{\vec{v}_i\}$  the eigenspace  $E_\lambda$ .

3) What is the dimension of each eigenspace?

one, since there's one vector in each basis.

## Repeated Eigenvalues

4) What are the eigenvalues and eigenvectors of:  $H = \begin{bmatrix} 3 & 0 \\ 5 & 3 \end{bmatrix}$

e-values:  $\lambda = 3, 3$  (repeated)

e-vectors:  $A - 3I = \begin{bmatrix} 0 & 0 \\ 5 & 0 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$   $x=0$   
 $y$  is free  $\vec{v} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

only 1 e-vec  
linearly indep.  
For a  $2 \times 2$  matrix!

Repeated eigenvalues sometimes have more than one eigenvector though.

5) The eigenvalues for this matrix are  $\lambda_{1,2} = 1$  and  $\lambda_3 = 2$ . Find the eigenvectors associated

with these eigenvalues for the matrix:  $R = \begin{bmatrix} 0 & 0 & 2 \\ -1 & 1 & 2 \\ -1 & 0 & 3 \end{bmatrix}$

$$\lambda = 1, 1, 2$$

$$\lambda = 1: \vec{v}_1 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \quad \vec{v}_2 = \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix}$$

$$\lambda = 2: \vec{v}_3 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

We know that eigenvectors always satisfy the 2nd property of vector subspaces (you should be able to explain why!). We also found above that the eigenspace from a single eigenvector is a valid subspace. However, notice that we wrote our eigenspace as  $E_\lambda$ . But there are TWO eigenvectors with our double eigenvalue.

Let's denote the double eigenvalue, and its eigenvectors  $\lambda_1, \lambda_2$  and  $\vec{v}_1, \vec{v}_2$  respectively.

6) State all the eigenspaces and their corresponding dimension for R?

$$E_1 = \text{span} \left\{ \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix} \right\}$$

$$\dim(E_1) = 2$$

$$E_2 = \text{span} \left\{ \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right\}$$

$$\dim(E_2) = 1$$

7) Give a geometric interpretation of  $\text{span}\{\vec{v}_1, \vec{v}_2\}$  in  $\mathbb{R}^3$  (3-d space).

*Hint: this is a special shape in  $\mathbb{R}^3$*

A plane.

The algebraic multiplicity of an eigenvalue is the number of times it is a root (e.g.  $a$  in  $(\lambda - \lambda_i)^a$ )

The geometric multiplicity of an eigenvalue is the dimension of its corresponding eigenspace.

8) a) Give the algebraic and geometric multiplicity for the eigenvalues of R.

$$\lambda = 1: \begin{array}{l} \text{alg. mult.} = 2 \\ \text{geom. mult.} = 2 \end{array}$$

$$\lambda = 2: \begin{array}{l} \text{alg. mult.} = 1 \\ \text{geom. mult.} = 1 \end{array}$$

b) Give the algebraic and geometric multiplicity for the eigenvalues of H.

$$\lambda = 3: \begin{array}{l} \text{alg. mult.} = 2 \\ \text{geom. mult.} = 1 \end{array}$$

c) How do the algebraic and geometric multiplicity compare to each other?

$$1 \leq \text{geom. mult.} \leq \text{alg. mult.} \leq n$$

## Distinct Eigenvalues

There is very useful theorem about distinct eigenvalues:

**Distinct Eigenvalue Theorem:** Let  $A$  be an  $n \times n$  matrix. If  $\lambda_1, \lambda_2, \dots, \lambda_p$  are distinct eigenvalues with corresponding eigenvectors  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p$  then  $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_p\}$  is a set of linearly independent vectors.

9)a) Find the eigenvalues and an eigenvectors for each value for:  $W = \begin{bmatrix} 3 & 0 \\ 5 & 2 \end{bmatrix}$

$$\lambda = 3, 2$$

$$\lambda = 3: \vec{v}_1 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\lambda = 2: \vec{v}_2 = \begin{pmatrix} 1 \\ 5 \end{pmatrix}$$

b) Show that the eigenvectors are linearly independent.

$$\det \begin{pmatrix} 0 & 1 \\ 1 & 5 \end{pmatrix} = -1 \neq 0$$

10) There's something to be careful of with this theorem though... You found the eigenvectors for  $R$  in (3). Are the eigenvectors of  $R$  linearly independent?

Yes.

11) If the eigenvectors are linearly independent are you guaranteed to have distinct eigenvalues?

No, as seen in  $R$ , we don't have distinct eigenvalues as  $\lambda = 1$  is a double root.