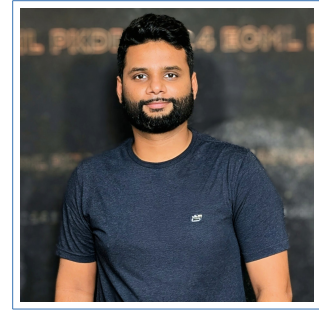# Abhijeet Pendyala

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✉ abhijeet.pendyala@gmail.com   ●   🖥 Portfolio

Work Experience

Theory of ML Group, Ruhr-Universität Bochum   **Germany**
PhD Candidate in Machine Learning   *Feb '21 – Present*

- Developed a deep reinforcement learning (RL) solution using PPO and curriculum learning to optimize a complex industrial control system with sparse rewards and conflicting objectives.
- Designed a novel hybrid RL-planning architecture that integrates an offline-trained XGBoost collision model at inference time, significantly reducing safety-limit violations.
- Authored and released `ContainerGym`, an open-source RL benchmark, and published research providing actionable guidelines for industrial system design and scalability.
- **Achievements:** Published twice at the prestigious European Conference on Machine Learning (ECML '24 & '25).
- **Skills:** `Python, PyTorch, OpenAI-Gymnasium, scikit-learn, Matplotlib`

Ecoki.de   **Germany**
Software Developer (Fullstack)   *Feb '21 – Present*

- Spearheaded the design of core architectural frameworks for a low-code ML platform, including a microservices architecture and modular `BuildingBlock` and `Pipeline` systems for energy efficiency applications.
- Engineered and implemented end-to-end ML workflows, from data preprocessing, feature engineering, regression, time-series forecasting, and optimization modules.
- Integrated ML pipeline results into interactive Django-based dashboards for visualization and user input.
- **Achievements:** Led the initiative to standardize engineering practices, creating the platform's first comprehensive automated testing protocols and Sphinx-based technical documentation.
- **Leadership:** Requirements collection, User story mapping, Sprint rituals
- **Skills:** `Python, Tensorflow, scikit-learn, XGBoost, Sphinx, Docker, Kubernetes, Panel, Django`

Perception Team, Kopernikus Automotive GmbH — Berlin, Germany
Machine Learning Engineer — *Aug '19 – Apr '20*

- Developed and optimized perception models for autonomous driving, focusing on 2D/3D object detection and localization using models like `RetinaNet`, `YOLO` and `EfficientDet`.
- Designed and maintained data pipelines for perception tasks, including synthetic dataset generation (images and LiDAR) from the `CARLA` simulator.
- Implemented model compression and latency reduction techniques with `TensorRT` for efficient deployment on edge devices (NVIDIA Jetson).
- **Achievements:** Significantly improved the vehicle perception stack by training object localization models on custom-generated synthetic datasets of masked cars and traffic cones.
- **Leadership:** Event Coordinator for the Autonomous Mobility Meetup, Berlin.
- **Skills:** `Python, TensorFlow, Keras, TensorRT, CARLA Simulator`

ICAMS, Ruhr-Universität Bochum — Germany
Assistant Researcher — *Aug '18 – May '19*

- Developed surrogate ML models to replace costly material simulations, focusing on damage prediction (regression) and stress hotspot detection (classification).
- Trained and evaluated a suite of regression models (Random Forest, SVR, DNNs) to predict material damage values from micro-mechanical features.
- Engineered a classification pipeline using Random Forest and oversampling techniques (ADASYN) to predict stress hotspots in a highly imbalanced dataset.
- **Skills:** `Python, scikit-learn, Pytorch, fastai, pandas`

Theory of Machine Learning Group, INI, Ruhr-Universität Bochum — Germany
Master Thesis — *Apr '18 – Jan '19*

- Designed and implemented a novel algorithm (ACF-BDCA) in C++ to accelerate the training of non-linear Support Vector Machines (SVMs) on large-scale datasets.
- Combined an adaptive coordinate frequency (ACF) optimization method with a budget maintenance strategy to reduce model complexity and improve convergence speed.
- **Achievements:** Developed a new, robust stopping criterion for the non-convex problem based on the logarithmic gap of pseudo-gradients, achieving a >30% training speed-up.
- **Skills:** `C++, Convex Optimization, Latex`

Fiat Chrysler Automobiles (FCA) — Pune, India
Research and Development Engineer — *Jul '13 – Sep '15*

- Analyzed high-dimensional sensor data from engine dynamometers to diagnose performance anomalies and optimize engine efficiency. Designed and programmed test cycles for durability testing, and performed engine software calibration.
- **Leadership:** Lead a team of 15 associates and was responsible for engine and transmission durability testing.
- **Skills:** `Engineering leadership,Data Analysis,Matlab,ETAS-INCA`

Education

Ruhr-Universität Bochum — Germany
M.Sc. Computational Engineering (Splz. in Machine Learning) — *Oct '15 – Dec '18*
Grade: 1.3/4.0 (Distinction)

BITS Pilani, Hyderabad Campus **India**
B.E. (Honors) Mechanical Engineering (Splz. in Computational) *Aug '09 – May '13*
CGPA: 8.1 / 10

Knowledge & Skills

Languages: English (Native Speaker, C2), German (Intermediate, B2), Hindi (Native), Telugu (Mother Tongue)

MLOps Tools: Weights & Biases, MLflow, DVC, Poetry, pre-commit, GitHub Actions

Core Programming: Python (Advanced), C++ (Intermediate)

Activities

Organization: Organizer of the weekly seminar talks at the computer science department, Ruhr-Universität Bochum (2021-2025)

Co-supervision: Co-supervised a bachelor thesis on the topic of AutoML library evaluation and the pseudo-anonymisation of sensitive data in ML processes.

Peer reviews: LOD 2025, ICANN 2025, ECML 2025

Publications

1. **Curriculum RL meets Monte Carlo Planning: Optimization of a Real World Container Management Problem**, *To appear in European conference for Machine Learning (ECML). Applied Data Science Track* , 2025
   A. Pendyala, T. Glasmachers

2. **Solving a Real-World Optimization Problem Using Proximal Policy Optimization with Curriculum Learning and Reward Engineering**, *European conference for Machine Learning (ECML). Applied Data Science Track*, 2024
   A. Pendyala, A. Atamna, T. Glasmachers

3. **ContainerGym: A Real-World Reinforcement Learning Benchmark for Resource Allocation**, *International Conference on Machine Learning, Optimization, and Data Science (LOD)*, 2023
   A. Pendyala, J. Dettmer, T. Glasmachers, A. Atamna

4. **Online Budgeted Stochastic Coordinate Ascent for Large-Scale Kernelized Dual Support Vector Machine Training**, *International Conference on Pattern Recognition Applications and Methods (ICPRAM)*, 2020
   S. Qaadan, A. Pendyala, M. Schüler, T. Glasmachers