## Homework 6

Due: 8:00pm (PT) **Tuesday**, Nov 22nd, 2022

- 1. Let  $X \sim \mathcal{N}(0, \sigma^2)$  and  $Y \sim \mathcal{N}(0, \nu^2)$  be independent random variables and Z = X + Y.
  - (a) Find the LMMSE estimator of X given Z.
  - (b) Find the conditional distribution  $f_{Z|X}(z \mid x)$ .
  - (c) Using the previous part, find the conditional distribution  $f_{X|Z}(x|z)$ .
  - (d) Find the MMSE estimator of X given Z and show that it is the same as the LMMSE estimator in Part (a).
- 2. Let  $X, Y \sim U(0,1)$  be independent random variables uniformly distributed over (0,1) and  $Z = X + \frac{1}{2}Y$ .
  - (a) Find the LMMSE estimator of X given Z.
  - (b) Find the MMSE estimator of X given Z. Is LMMSE and MMSE estimator the same?
- 3. Consider an additive noise channel Y = X + Z, where the signal  $X \sim \mathcal{N}(0, \sigma^2)$  and the noise Z has zero mean and variance  $\nu^2$ . Assume X and Z are independent. Find a distribution of Z that maximizes the minimum MSE of estimating X given Y, i.e., the distribution of the worst noise Z that has the given mean and variance. Justify your answer.
- 4. Using the definition of conditional expectation using the projection, show that for any variables  $Y_1, \ldots, Y_k, Z \in L_2(\Omega, \mathcal{F}, \mathbf{P}(\cdot))$  and any (measurable) function  $h : \mathbb{R}^k \to \mathbb{R}$ ,

$$\mathbb{E}[Zh(Y_1,\ldots,Y_k)\mid Y_1,\ldots,Y_k] = \mathbb{E}[Z\mid Y_1,\ldots,Y_k]h(Y_1,\ldots,Y_k).$$

This is called the product rule for conditional expectation.

5. Consider a discrete time finite state Markov chain  $\{X_k\}$  on three states  $S_1, S_2, S_3$  with the transition matrix

$$P = \begin{pmatrix} \frac{1}{4} & \frac{3}{4} & 0\\ \frac{1}{4} & 0 & \frac{3}{4}\\ 0 & \frac{1}{2} & \frac{1}{2} \end{pmatrix}.$$

- (a) Find a stationary distribution  $\pi$  for P. Is it unique?
- (b) Is this Markov chain aperiodic? Is it irreducible?
- (c) Suppose that  $x_0 = (\mathbf{P}(X_0 = S_1), \mathbf{P}(X_0 = S_2), \mathbf{P}(X_0 = S_3))^T = (\frac{1}{3}, \frac{1}{3}, \frac{1}{3})^T$  is the probability mass function at time 0. What is the probability that by time T = 4 we visit state  $S_3$ ?
- (d) What is the probability that we visit state  $S_2$  or  $S_3$  by time T=4?