

Storage Benchmarking with Deep Learning Workloads

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Introduction



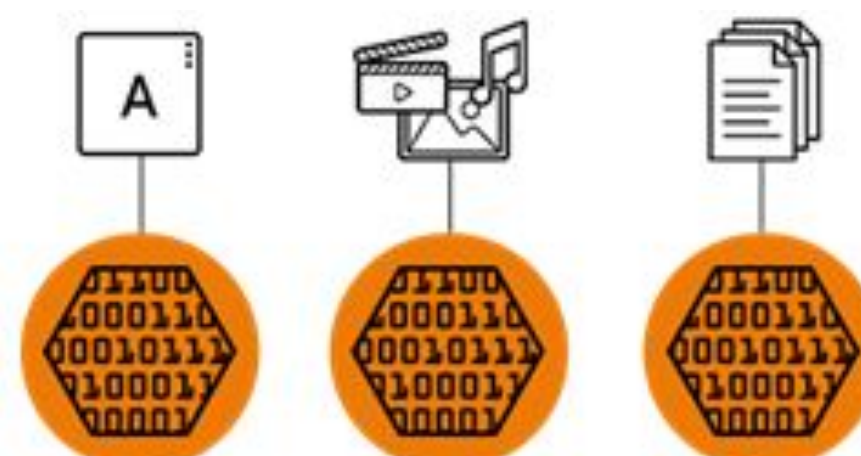
- In this AI-driven era, while computer infrastructure is often the focus, **storage** is equally important.
- Loading the dataset is the basic step in model training.
- Trend of **decoupled storage and compute** in datacenters.
 - Cost
 - Scalability
 - Availability

Motivation:

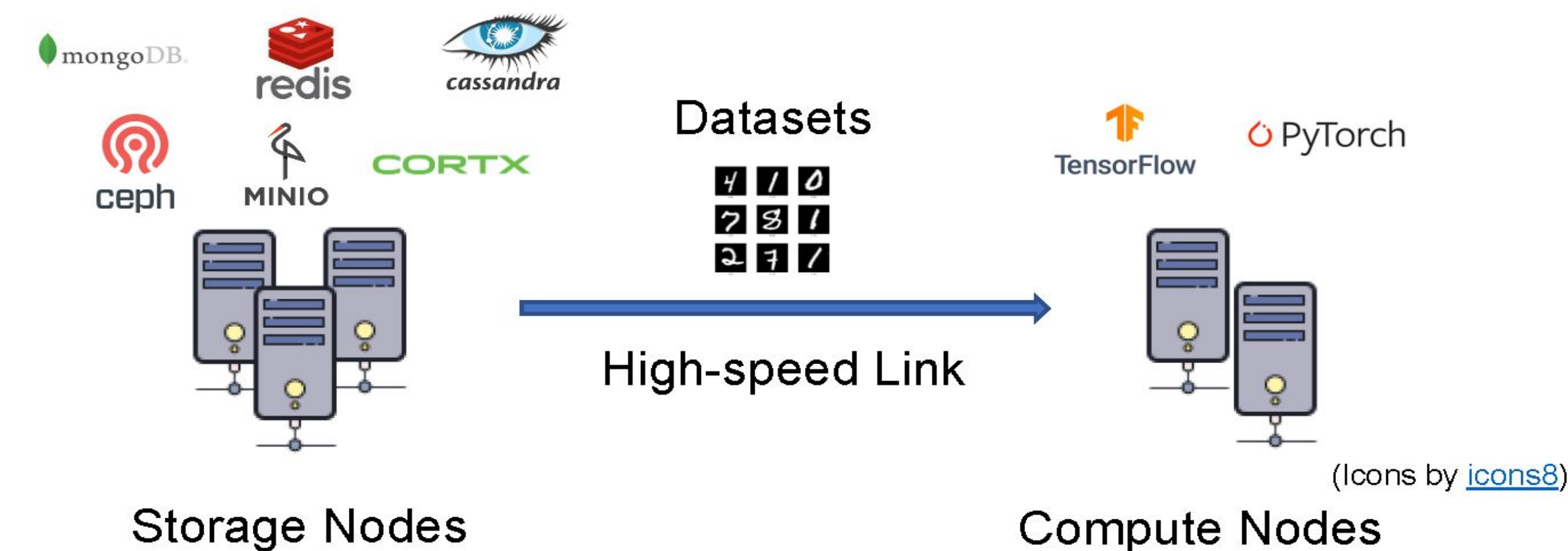
Explore the optimal storage system and data format to store DL data and the underlying trade-offs in it.

Storage Systems

- **Key-Value Databases**
 - A more traditional storage solution that only provides limited metadata.
- **Object Storage**
 - Each object contains:
 - Data (binary file)
 - Object ID
 - Metadata that describes the data
 - More scalable: stored in flat hierarchy
 - More searchable: extensible metadata.



Methodology



Overview

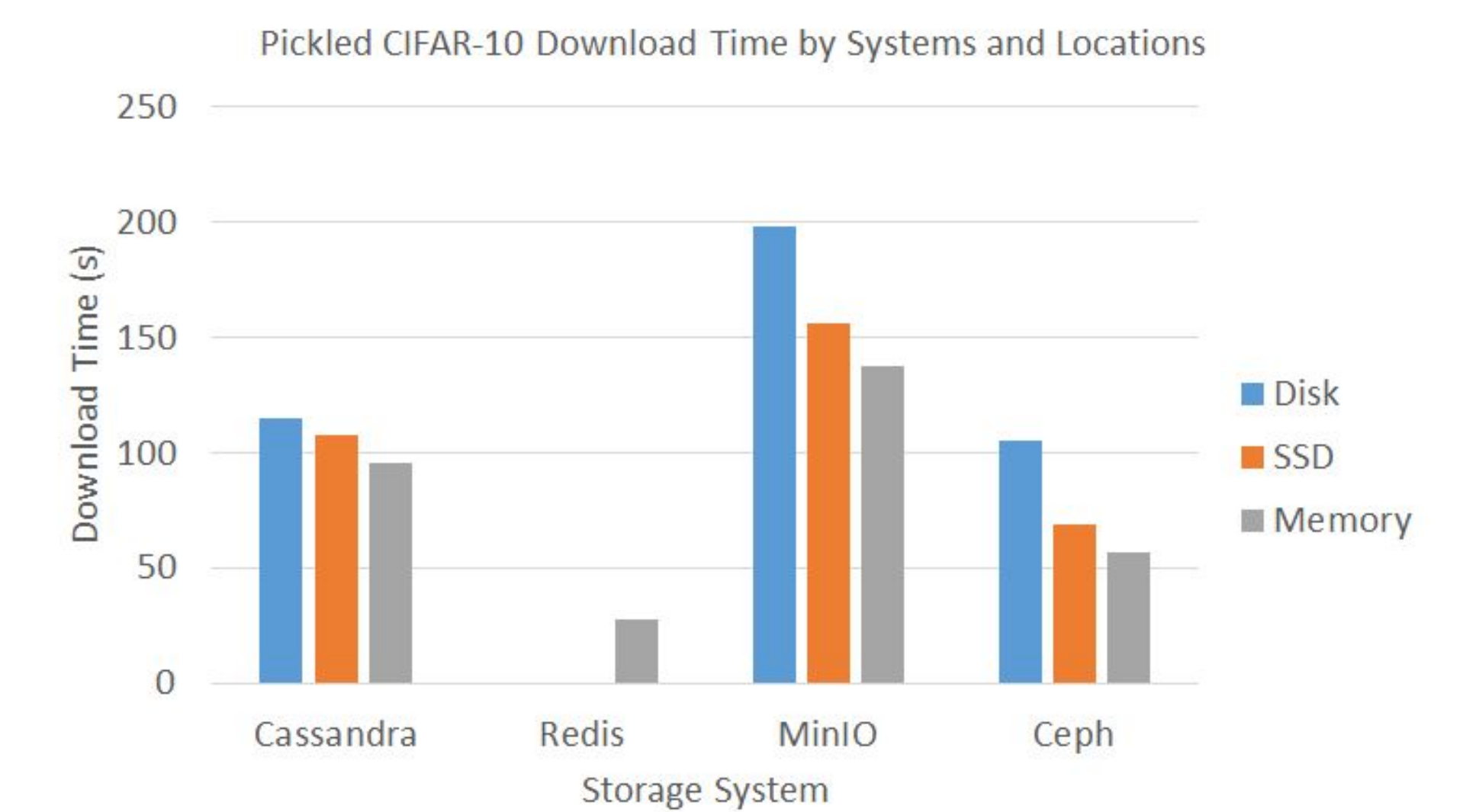
- **Storage Disaggregation for DL**
 - We parsed datasets raw files and stored each image with its label as a single object.
- **Decoupled Storage and Compute**
 - Objects are stored in different systems in storage nodes.
 - The client download them in different batch sizes.

Experiment Setup

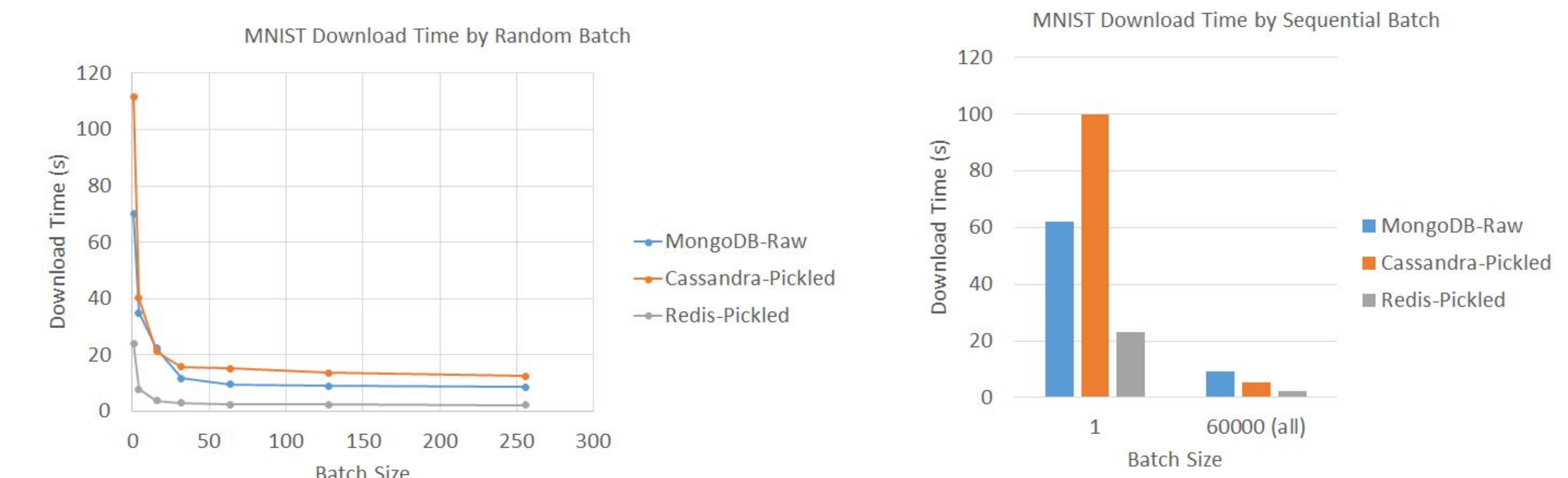
- **Storage Systems:**
 - **Key-Value Databases:** Cassandra, Redis, MongoDB
 - **Object Storage Systems:** MinIO, Ceph
- **Testbed:** d430 nodes @ Emulab
- **Network:** LAN with 1Gbps link speed
- **Datasets:**
 - **MNIST (236 MB):** 60,000 images of handwritten digits
 - **CIFAR-10 (952 MB):** 60,000 32 * 32 images in 10 classes
- **Location:** memory, disk, SSD
- **Access pattern:** single, batch size, full batch object(s)
- **Data Format:** raw, blob, pickled
- **Storage Disaggregation Granularity**

Selected Results

- **System choice matters, memory > SSD > disk.**



- **Download time decreases as batch size increases.**



- **Data format influences space used in storage systems.**

