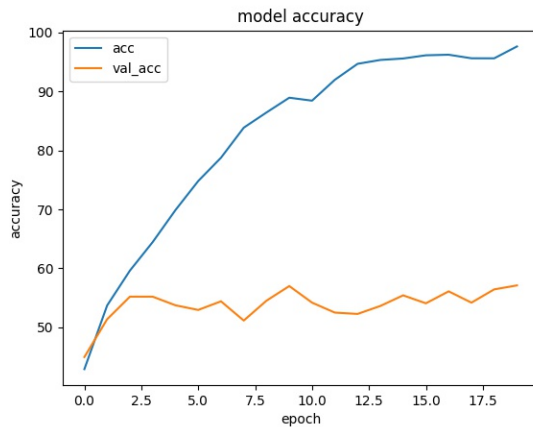


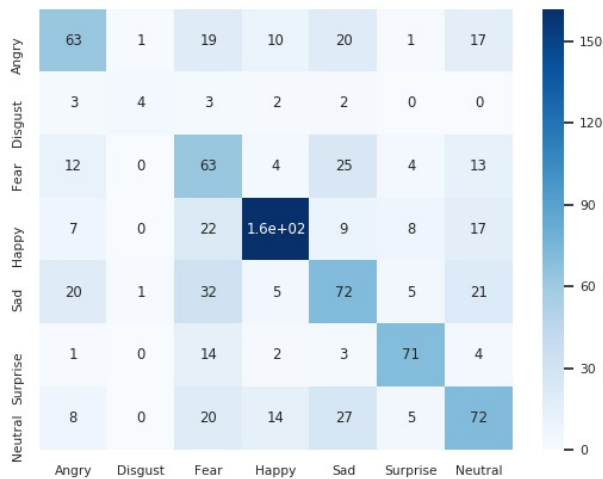
1. (1%) 請說明這次使用的**model**架構，包含各層維度及連接方式。

我的model架構是四層convolution加一層全連接層，其中四層的convolution filter 數分別是32、64、128、128，convolution的kernel大小只有第一層是5*5，其他皆是3*3，激勵函數使用leakyReLu，此外每層我都有做batch normalize跟maxpooling。

2. (1%) 請附上**model**的**training/validation history (loss and accuracy)**。

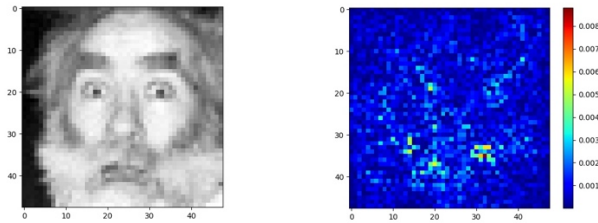


3. (1%) 畫出**confusion matrix**分析哪些類別的圖片容易使**model**搞混，並簡單說明。



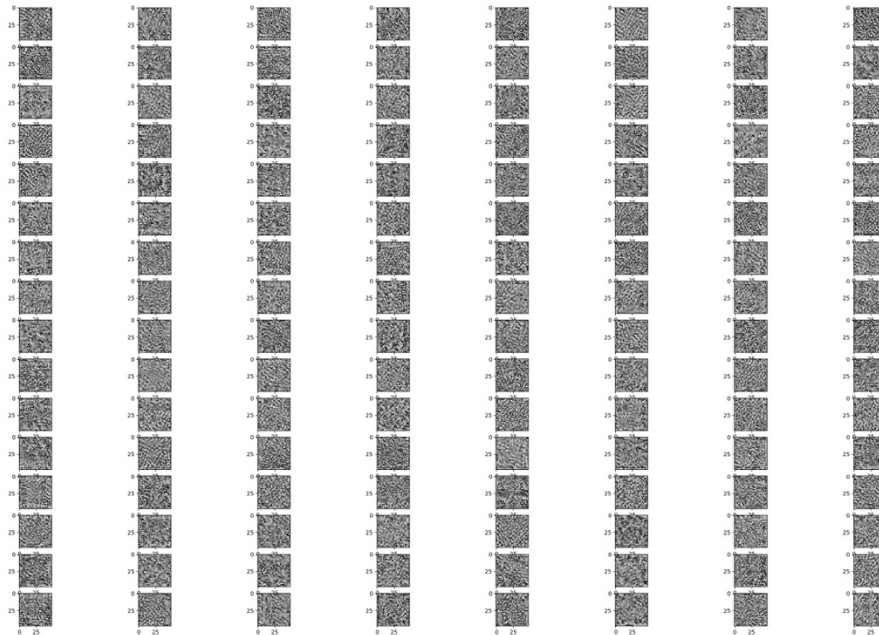
從confusion matrix 中可以看出” Neutral” 比要容易跟其他表情搞混，例如：Neutral被判別成Fear、Happy、Sad的Accuracy都稍微高了點，其中Sad判別成Fear的分數也比較高，但基本上除了Disgust之外，其他心情的判別度大多正確。

4. (1%) 畫出**CNN model**的**saliency map**，並簡單討論其現象。



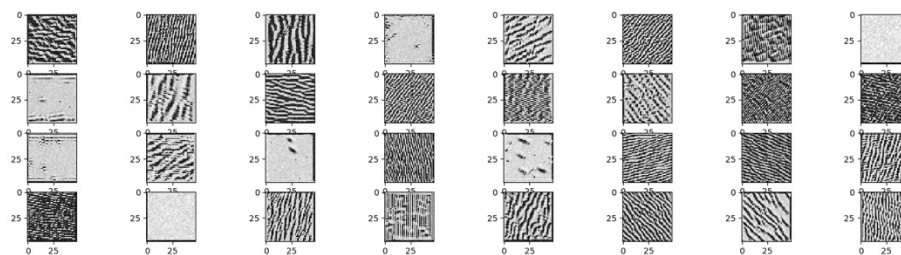
Saliency Map利用圖像分割的方式將相似的pixel分配成同個標籤，所以可以透過Saliency Map看出該圖的特徵，我隨意挑了一張圖畫了Saliency Map，可以看到眼睛的位置有些微的亮點，以及嘴巴鬍子特為明顯。

5. (1%) 畫出最後一層的**filters**最容易被哪些**feature activate**。



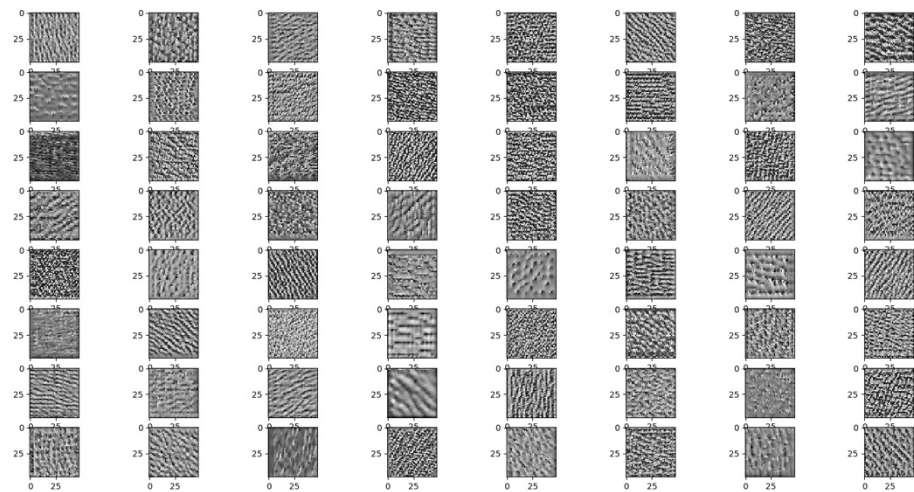
conv4

我架了四層convolution，其中最後一層filter數為128，kernel大小為3*3，filter 的feature activation 如上圖所示，可以看出大多filter中央都有些微的扭曲，疑似臉蛋的樣子，但不是很顯著，因此我回頭畫了其他層的filters。

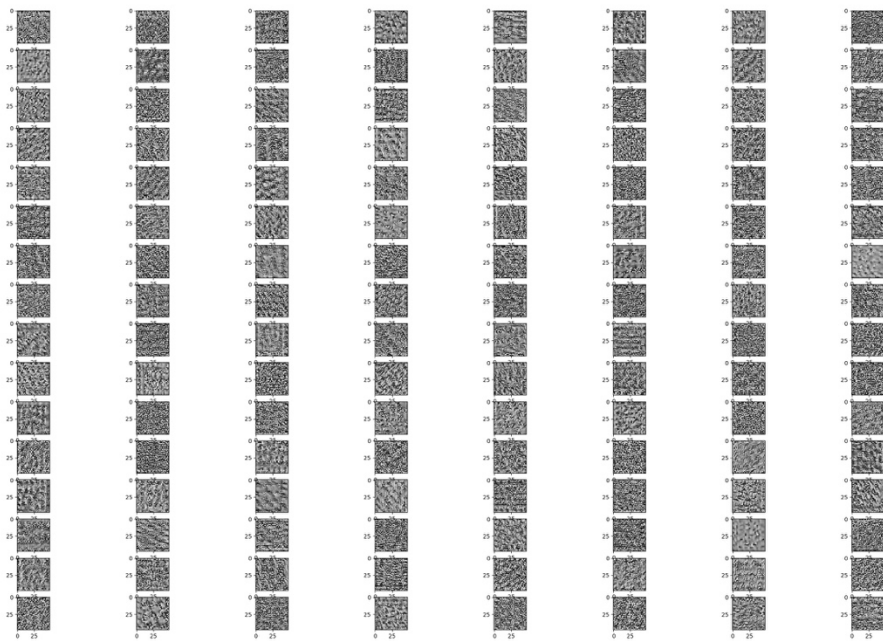


conv1

上圖為conv1的filter，總共有32個，kernelsize為5*5，可以看出conv1主要識別一些紋理圖案，有橫條紋、直條紋、波浪紋等等。



conv2



conv3

6. (3%)Refer to math problem

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1. kernel size = (k_1, k_2) original : $(B, W, H, \text{input-channels})$

stride = (s_1, s_2)

padding = (p_1, p_2)

$$\left\{ \begin{array}{l} \text{width: } \text{floor} \left(\frac{W + 2 \times p_1 - k_1}{s_1} \right) + 1 \# \end{array} \right.$$

$$\left\{ \begin{array}{l} \text{height: } \text{floor} \left(\frac{H + 2 \times p_2 - k_2}{s_2} \right) + 1 \# \end{array} \right.$$

output-channels : the number of filters. \neq

2. Input : Values of x over a mini-batch: $B = \{x_1, \dots, x_m\}$;

Parameters to be learned : γ, β

Output : $\{y_i = \text{BN}_{\gamma, \beta}(x_i)\}$

$$\mu_B \leftarrow \frac{1}{m} \sum_{i=1}^m x_i$$

$$\sigma_B^2 \leftarrow \frac{1}{m} \sum_{i=1}^m (x_i - \mu_B)^2$$

$$\hat{x}_i \leftarrow \frac{x_i - \mu_B}{\sqrt{\sigma_B^2 + \epsilon}}$$

$$y_i \leftarrow \gamma \hat{x}_i + \beta \equiv \text{BN}_{\gamma, \beta}(x_i)$$

$$\frac{\partial l}{\partial \hat{x}_i} = \frac{\partial l}{\partial y_i} \cdot \gamma$$

$$\frac{\partial l}{\partial \sigma_B^2} = \sum_{i=1}^m \frac{\partial l}{\partial \hat{x}_i} \cdot (x_i - \mu_B)$$

$$\frac{\partial l}{\partial \mu_B} = \left(\sum_{i=1}^m \frac{\partial l}{\partial \hat{x}_i} \cdot \frac{-1}{\sqrt{\sigma_B^2 + \epsilon}} \right) + \frac{\partial l}{\partial \sigma_B^2} \cdot \frac{\sum_{i=1}^m -2(x_i - \mu_B)}{m}$$

$$\frac{\partial l}{\partial x_i} = \frac{\partial l}{\partial \hat{x}_i} \cdot \frac{1}{\sqrt{\sigma_B^2 + \epsilon}} + \frac{\partial l}{\partial \sigma_B^2} \cdot \frac{2(x_i - \mu_B)}{m} + \frac{\partial l}{\partial \mu_B} \cdot \frac{1}{m}$$

$$\frac{\partial l}{\partial \gamma} = \sum_{i=1}^m \frac{\partial l}{\partial y_i} \cdot \hat{x}_i$$

$$\frac{\partial l}{\partial \beta} = \sum_{i=1}^m \frac{\partial l}{\partial y_i}$$

#

$$3. \text{softmax}(\mathbf{z}_t) = \frac{e^{z_t}}{\sum_i e^{z_i}}$$

$$\text{cross-entropy} = L(y, \hat{y}) = - \sum_i y_i \log(\hat{y}_i)$$

$$\text{cross-entropy} = L_t(y_t, (\hat{y}_t)) = -y_t \log(\hat{y}_t)$$

$$\hat{y}_t = \text{softmax}(\mathbf{z}_t)$$

$$\text{Derive that } \frac{\partial L_t}{\partial z_t} = \hat{y}_t - y_t$$

(sl)

$$L_t(y_t, \hat{y}_t) = -y_t \log\left(\frac{e^{z_t}}{\sum_i e^{z_i}}\right) = -y_t (\log e^{z_t} - \log \sum_i e^{z_i})$$

$$\frac{\partial L_t}{\partial z_t} = \frac{\partial (-y_t \log(\hat{y}_t))}{\partial z_t} \overset{\substack{\uparrow \\ \because \hat{y}_t = \text{softmax}(\mathbf{z}_t)}}{=} -y_t \cdot \frac{1}{\hat{y}_t} \frac{\partial \hat{y}_t}{\partial z_t} = -y_t \cdot \frac{1}{\hat{y}_t} \cdot \frac{\partial}{\partial z_t} \left(\frac{e^{z_t}}{\sum_i e^{z_i}} \right)$$

$$= -\frac{y_t}{\hat{y}_t} \left[\frac{e^{z_t} (\sum_i e^{z_i}) - e^{z_t} \cdot e^{z_t}}{(\sum_i e^{z_i})^2} \right] \quad \swarrow \hat{y}_t = \frac{e^{z_t}}{\sum_i e^{z_i}}$$

$$= -\frac{y_t}{\hat{y}_t} \left[\hat{y}_t - (\hat{y}_t)^2 \right]$$

$$= -y_t + \hat{y}_t \cdot y_t$$

$$\because y_t = 1 \\ \text{if } y_t = 0$$

$$\therefore -y_t + \hat{y}_t \cdot y_t = \hat{y}_t - y_t \quad \# \\ \Rightarrow \hat{y}_t - y_t \quad \#$$