

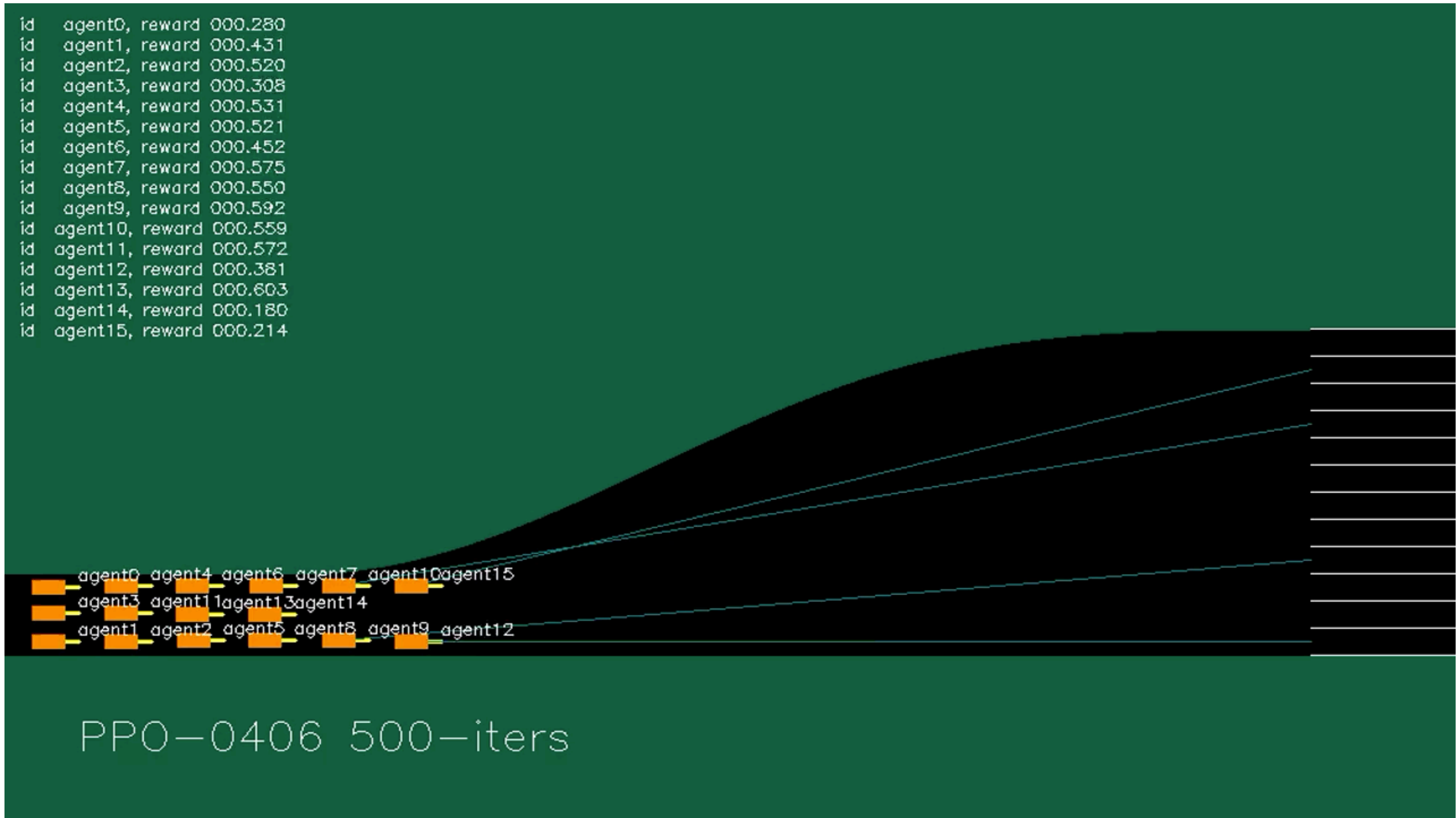
# Implementation with Ray (RLlib)

In last two weeks, I have

- implemented our environment with RLlib by modifying environments to fit RLlib standard input / output.
- conducted experiments using desktop computer using small batches.
- setup the cluster and configured Ray properly, with the help of Mingyang and cluster-managing stuffs.
- conducted experiments using cluster using large batches (learned how to use cluster for the first time...).

# Performance of small batch training

Waiting and observing behaviors emerge! But still easy to collide.



Metric	Value
iteration	500
— performance —	
agent collision	0.3075
boundary col. rate	0.0275
gate collision rate	0.1917
pass rate	0.4669
success rate	0.0756
episode reward	826.8
single reward	51.68
episode length	227.6
— configuration —	
num gpus	1
num workers	10
num env per worker	2
train batch size	4000