Performance of large batch training

```
agent0, reward 000.197
agent1, reward 000.300
agent2, reward 000.295
agent3, reward 000.350
agent4, reward 000.271
agent5, reward 000.361
agent6, reward 000.431
agent7, reward 000.423
agent8, reward 000.451
agent9, reward 000.166
agent10, reward 000.439
agent11, reward 000.469
agent12, reward 000.293
agent13, reward 000.358
agent14, reward 000.224
agent15, reward 000.424
  agent0 agent4 agent6 agent10agent11agent13
  agent1 agent2 agent3 agent5 agent7 agent8
  agent9 agent12agent14agent15
```

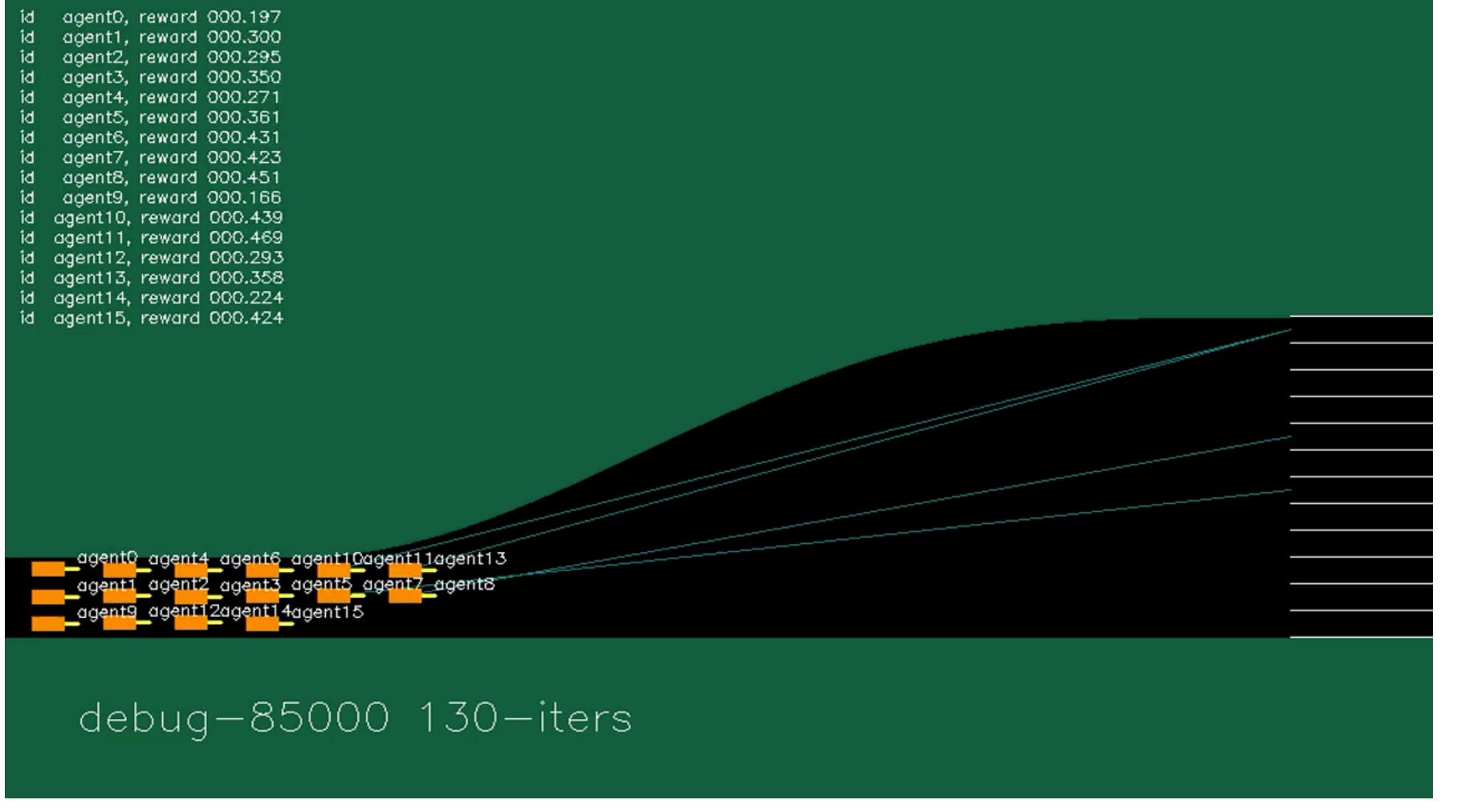
Waiting and observing behaviors emerge! But still easy to collide.

Metric	Value	
iteration	132	
performance		
agent collision	0.0121	
boundary col. rate	0	
gate collision rate	0	
pass rate	0.98796	
success rate	0.16492	
policy loss	-0.00010	
value loss	0.68666	
episode reward	1653.808	
single reward	103.3630	
episode length	194.8668	
configuration		
num workers	2	
env per worker	16	
cpu per worker	26	
sample batch size	200	
train batch size	85000	

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Discussion of large batch training



