## 线性代数试题参考解答

(2013.11)

-, 1. 
$$-\frac{1}{8}$$
; 2.  $\begin{pmatrix} \mathbf{0} & \mathbf{C}^{-1} \\ \mathbf{B}^{-1} & -\mathbf{B}^{-1}\mathbf{A}\mathbf{C}^{-1} \end{pmatrix}$ ; 3. D;

4.  $\alpha_1, \alpha_2, \alpha_4 ( \mathfrak{R} \alpha_1, \alpha_3, \alpha_4);$  5. n-2; 6. -1, 3;

7. B; 8. t < 0.

二、
$$D_n$$
 接第1行展开 $(a+b)D_{n-1}+1\cdot(-1)^{1+2}$   $\begin{vmatrix} ab & 1 \\ & a+b & 1 \\ & ab & a+b & \ddots \\ & & \ddots & \ddots & 1 \\ & & ab & a+b \end{vmatrix}_{n-1}$ 

按第1列展开
$$(a+b)D_{n-1}-abD_{n-2}$$

变形为

$$D_n - aD_{n-1} = b(D_{n-1} - aD_{n-2})$$

由于 $D_1 = a + b$ , $D_2 = (a + b)^2 - ab = a^2 + ab + b^2$ ,利用上述递推公式得

$$D_n = aD_{n-1} + b^n = a^2D_{n-2} + ab^{n-1} + b^n = \dots = a^{n-1}D_1 + a^{n-2}b^2 + \dots + ab^{n-1} + b^n$$
$$= a^n + a^{n-1}b + a^{n-2}b^2 + \dots + ab^{n-1} + b^n = \frac{a^{n+1} - b^{n+1}}{a - b}$$

三、可求得 $\det A = 4$ ,于是 $A^* = 4A^{-1}$ ,代入矩阵方程得

$$4A^{-1}XA = 8A^{-1}X - 4E$$

上式左乘 $\frac{1}{4}$ *A* 得 XA = 2X - A,从而

四、设 $\boldsymbol{\beta} = x_1 \boldsymbol{\alpha}_1 + x_2 \boldsymbol{\alpha}_2 + x_3 \boldsymbol{\alpha}_3 + x_4 \boldsymbol{\alpha}_4$ , 比较分量得

$$\begin{cases}
-x_2 + ax_3 = 0 \\
-ax_1 + x_2 + ax_4 = 1
\end{cases}$$

$$\begin{cases}
x_1 - x_3 - x_4 = 1 \\
x_2 - ax_3 = b
\end{cases}$$

增广矩阵

$$\begin{pmatrix}
0 & -1 & a & 0 & 0 \\
-a & 1 & 0 & a & 1 \\
1 & 0 & -1 & -1 & 1 \\
0 & 1 & -a & 0 & b
\end{pmatrix}
\xrightarrow{\text{institute}}
\begin{pmatrix}
1 & 0 & -1 & -1 & 1 \\
0 & 1 & -a & 0 & 1+a \\
0 & 0 & 0 & 0 & b
\end{pmatrix}$$

当  $\boldsymbol{\beta}$  可由  $\boldsymbol{\alpha}_1, \boldsymbol{\alpha}_2, \boldsymbol{\alpha}_3, \boldsymbol{\alpha}_4$  线性表示时上述线性方程组有解,所以1 + a = 0, b = 0,故 a = -1, b = 0.代入上式得同解方程组

$$\begin{cases} x_1 = 1 + x_3 + x_4 \\ x_2 = -x_3 \end{cases}$$

通解为

$$x_1 = 1 + k_1 + k_2$$
,  $x_2 = -k_1$ ,  $x_3 = k_1$ ,  $x_4 = k_2$   $k_1, k_2$  任意

于是

$$\boldsymbol{\beta} = (1 + k_1 + k_2)\boldsymbol{\alpha}_1 - k_2\boldsymbol{\alpha}_2 + k_1\boldsymbol{\alpha}_3 + k_2\boldsymbol{\alpha}_4$$
  $k_1, k_2$ 任意

五、1) 因为

$$(\beta_1, \beta_2, \beta_3) = (\alpha_1, \alpha_2, \alpha_3) \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & -1 \\ 1 & -1 & 0 \end{pmatrix}, (\gamma_1, \gamma_2, \gamma_3) = (\alpha_1, \alpha_2, \alpha_3) \begin{pmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{pmatrix}$$

所以

$$(\boldsymbol{\gamma}_{1}, \boldsymbol{\gamma}_{2}, \boldsymbol{\gamma}_{3}) = (\boldsymbol{\beta}_{1}, \boldsymbol{\beta}_{2}, \boldsymbol{\beta}_{3}) \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & -1 \\ 1 & -1 & 0 \end{pmatrix}^{-1} \begin{pmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{pmatrix}$$

$$= (\boldsymbol{\beta}_{1}, \boldsymbol{\beta}_{2}, \boldsymbol{\beta}_{3}) \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{pmatrix} = (\boldsymbol{\beta}_{1}, \boldsymbol{\beta}_{2}, \boldsymbol{\beta}_{3}) \begin{pmatrix} 2 & 2 & 2 \\ 2 & 1 & 1 \\ 1 & 0 & 1 \end{pmatrix}$$

故由基 $\boldsymbol{\beta}_1, \boldsymbol{\beta}_2, \boldsymbol{\beta}_3$ 到基 $\boldsymbol{\gamma}_1, \boldsymbol{\gamma}_2, \boldsymbol{\gamma}_3$ 的过渡矩阵为 $\boldsymbol{C} = \begin{pmatrix} 2 & 2 & 2 \\ 2 & 1 & 1 \\ 1 & 0 & 1 \end{pmatrix}$ .

2) 
$$\boldsymbol{\alpha} = (\boldsymbol{\alpha}_{1}, \boldsymbol{\alpha}_{2}, \boldsymbol{\alpha}_{3}) \begin{pmatrix} 1 \\ 2 \\ -3 \end{pmatrix} = (\boldsymbol{\gamma}_{1}, \boldsymbol{\gamma}_{2}, \boldsymbol{\gamma}_{3}) \begin{pmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{pmatrix}^{-1} \begin{pmatrix} 1 \\ 2 \\ -3 \end{pmatrix}$$

$$= (\boldsymbol{\gamma}_{1}, \boldsymbol{\gamma}_{2}, \boldsymbol{\gamma}_{3}) \frac{1}{2} \begin{pmatrix} 1 & 1 & -1 \\ -1 & 1 & 1 \\ 1 & -1 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \\ -3 \end{pmatrix} = (\boldsymbol{\gamma}_{1}, \boldsymbol{\gamma}_{2}, \boldsymbol{\gamma}_{3}) \begin{pmatrix} 3 \\ -1 \\ -2 \end{pmatrix}$$

故向量 $\alpha$ 在基 $\gamma_1,\gamma_2,\gamma_3$ 下的坐标为 $(3,-1,-2)^T$ .

六、线性无关. 设

$$k_1\boldsymbol{\alpha}_1 + k_2\boldsymbol{\alpha}_2 + k_3\boldsymbol{\alpha}_3 + k_4(b\boldsymbol{\beta}_1 + \boldsymbol{\beta}_2) = \mathbf{0}$$

由题设 $\boldsymbol{\beta}_1 = l_1 \boldsymbol{\alpha}_1 + l_2 \boldsymbol{\alpha}_2 + l_3 \boldsymbol{\alpha}_3$ ,代入上式并整理得

$$(k_1 + bl_1k_4)\alpha_1 + (k_2 + bl_2k_4)\alpha_2 + (k_3 + bl_3k_4)\alpha_3 + k_4\beta_2 = \mathbf{0}$$

由于 $\boldsymbol{\beta}$ ,不能由 $\boldsymbol{\alpha}_1,\boldsymbol{\alpha}_2,\boldsymbol{\alpha}_3$ 线性表示,所以 $\boldsymbol{\alpha}_1,\boldsymbol{\alpha}_2,\boldsymbol{\alpha}_3,\boldsymbol{\beta}_2$ 线性无关,故由上式得

$$\begin{cases} k_1 & +bl_1k_4 = 0 \\ k_2 & +bl_2k_4 = 0 \\ k_3 +bl_3k_4 = 0 \\ k_4 = 0 \end{cases}$$

该齐次线性方程组的系数行列式

$$\det \mathbf{A} = \begin{vmatrix} 1 & 0 & 0 & bl_1 \\ 0 & 1 & 0 & bl_2 \\ 0 & 0 & 1 & bl_3 \\ 0 & 0 & 0 & 1 \end{vmatrix} = 1$$

故只有 $k_1 = k_2 = k_3 = k_4 = 0$ ,从而向量组 $\boldsymbol{\alpha}_1, \boldsymbol{\alpha}_2, \boldsymbol{\alpha}_3, b\boldsymbol{\beta}_1 + \boldsymbol{\beta}_2$ 线性无关.

七、二次型  $f = x^2 + 3y^2 + z^2 + 2axy + 2xz + 2yz$  的矩阵

$$\mathbf{A} = \begin{pmatrix} 1 & a & 1 \\ a & 3 & 1 \\ 1 & 1 & 1 \end{pmatrix}$$
正交相似于对角矩阵
$$\begin{pmatrix} 0 & & \\ & 1 & \\ & & 4 \end{pmatrix}$$

所以 A 的特征值为  $\lambda_1 = 0$ ,  $\lambda_2 = 1$ ,  $\lambda_3 = 4$ , 再由  $\det A = -(a-1)^2 = \lambda_1 \lambda_2 \lambda_3 = 0$  得 a=1.

可求得对应的特征向量分别为

$$\boldsymbol{p}_{1} = (-1,0,1)^{\mathrm{T}}, \quad \boldsymbol{p}_{2} = (1,-1,1)^{\mathrm{T}}, \quad \boldsymbol{p}_{3} = (1,2,1)^{\mathrm{T}}$$
单位化得正交矩阵  $\boldsymbol{Q} = \begin{pmatrix} -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{6}} \\ 0 & -\frac{1}{\sqrt{3}} & \frac{2}{\sqrt{6}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{6}} \end{pmatrix}$ .

八、1)  $\boldsymbol{P}^{\mathrm{T}}\boldsymbol{M}\boldsymbol{P} = \begin{pmatrix} \boldsymbol{A} - \boldsymbol{B}\boldsymbol{C}^{-1}\boldsymbol{B}^{\mathrm{T}} & \boldsymbol{O} \\ \boldsymbol{O} & \boldsymbol{C} \end{pmatrix} = \boldsymbol{D}; \quad (2 \ \%)$ 

八、1) 
$$\mathbf{P}^{\mathrm{T}}\mathbf{M}\mathbf{P} = \begin{pmatrix} \mathbf{A} - \mathbf{B}\mathbf{C}^{-1}\mathbf{B}^{\mathrm{T}} & \mathbf{O} \\ \mathbf{O} & \mathbf{C} \end{pmatrix} = \mathbf{D}; \quad (2 \%)$$

2)  $\mathbf{h} \mathbf{M}$  正定知  $\mathbf{A}$  和  $\mathbf{C}$  均为正定矩阵,从而它们是对称矩阵,于是

$$(A - BC^{-1}B^{T})^{T} = A^{T} - B(C^{-1})^{T}B^{T} = A - BC^{-1}B^{T}$$

即  $\mathbf{A} - \mathbf{B} \mathbf{C}^{-1} \mathbf{B}^{\mathrm{T}}$  是对称矩阵. (2 分)

又由 1)知M与D合同,从而由M正定知D为正定矩阵,且对任意m维非 零列向量x和n维零向量0有

$$\boldsymbol{x}^{\mathrm{T}}(\boldsymbol{A} - \boldsymbol{B}\boldsymbol{C}^{-1}\boldsymbol{B}^{\mathrm{T}})\boldsymbol{x} = (\boldsymbol{x}^{\mathrm{T}},\boldsymbol{0}^{\mathrm{T}}) \begin{pmatrix} \boldsymbol{A} - \boldsymbol{B}\boldsymbol{C}^{-1}\boldsymbol{B}^{\mathrm{T}} & \boldsymbol{O} \\ \boldsymbol{O} & \boldsymbol{C} \end{pmatrix} \begin{pmatrix} \boldsymbol{x} \\ \boldsymbol{0} \end{pmatrix} = (\boldsymbol{x}^{\mathrm{T}},\boldsymbol{0}^{\mathrm{T}})\boldsymbol{D} \begin{pmatrix} \boldsymbol{x} \\ \boldsymbol{0} \end{pmatrix} > 0$$

故 $\mathbf{A} - \mathbf{B}\mathbf{C}^{-1}\mathbf{B}^{\mathrm{T}}$ 为正定矩阵. (2分)