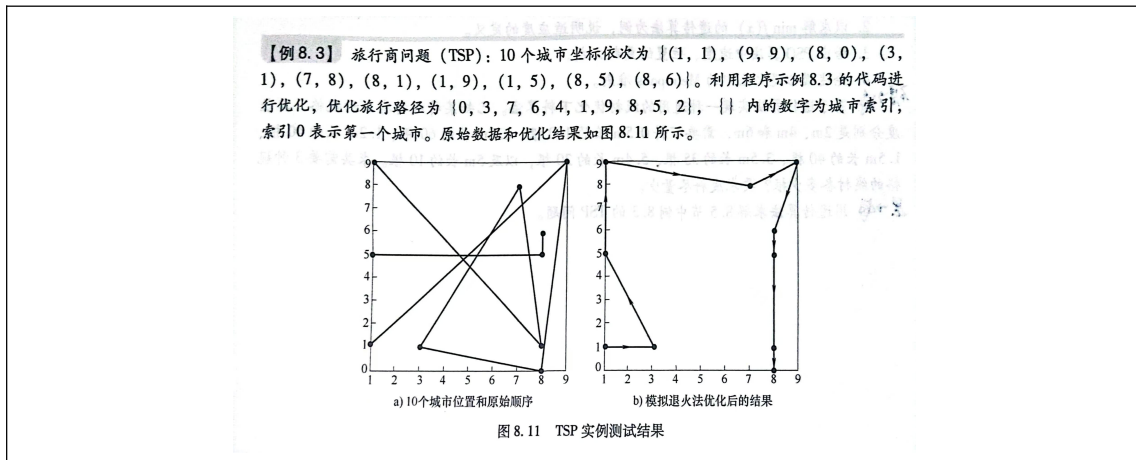


理论分析



用遗传算法解决 TSP 问题, 编码选择城市序号即可。

算法设计

编码方式:
每个城市对应一个序号, $i \in \{0, 1, \dots, n-1\}$, 每个个体为 n 个城市的一个序号串

适应度:
$$f(s) = \frac{1}{\sum_{i=1}^n d(u_i, u_{i+1})}$$
 $d(u_i, u_{i+1})$ 为 u_i 到 u_{i+1} 的距离。

选择算子:
轮盘赌, $f_i = \frac{F_i}{\sum F_j}$

交叉算子:
对父 1 和父 2, 产生随机数, 子代得到父 1 几个位置基因。
再从父 2 中不重复基因按顺序给子代。

变异算子:
随机产生 2 个变异位, 交换位。

编程实现

```
#include <stdio.h>
#include <stdlib.h>
#include <math.h>
#include <time.h>

#define NUM_CITIES 10
#define POPULATION_SIZE 100
#define GENERATIONS 100000
#define MUTATION_RATE 0.05

// 城市坐标
```

```

int cities[NUM_CITIES][2] = {
    {1, 1}, {9, 9}, {8, 0}, {3, 1}, {7, 8},
    {8, 1}, {1, 9}, {1, 5}, {8, 5}, {8, 6}
};

// 计算两点之间的距离
double distance(int x1, int y1, int x2, int y2) {
    return sqrt(pow(x2 - x1, 2) + pow(y2 - y1, 2));
}

// 适应度函数：计算路径总长度的倒数
double fitness(int individual[]) {
    double total_distance = 0.0;
    int visited[NUM_CITIES] = {0}; // 记录城市是否已经访问过
    visited[0] = 1; // 起点城市被访问过

    for (int i = 0; i < NUM_CITIES - 1; i++) {
        int city1 = individual[i];
        int city2 = individual[i + 1];
        if (visited[city2]) { // 如果城市已经被访问过，说明路径出现重复
            return 0.0; // 返回 0 表示不合法的路径
        }
        total_distance += distance(cities[city1][0], cities[city1][1], cities[city2][0],
cities[city2][1]);
        visited[city2] = 1; // 将城市标记为已访问
    }

    return 1.0 / total_distance;
}

// 选择函数：基于适应度选择一个个体（轮盘赌选择）
int select_individual(double fitness_values[]) {
    double sum_fitness = 0.0;
    for (int i = 0; i < POPULATION_SIZE; i++) {
        sum_fitness += fitness_values[i];
    }
    double r = ((double) rand() / (RAND_MAX)) * sum_fitness;
    double partial_sum = 0.0;
    for (int i = 0; i < POPULATION_SIZE; i++) {
        partial_sum += fitness_values[i];
        if (partial_sum >= r) {
            return i;
        }
    }
}

```

```

    }
    return POPULATION_SIZE - 1; // 备用返回值
}

// 交叉函数（顺序交叉）
void crossover(int parent1[], int parent2[], int child[]) {
    int start = 1 + rand() % (NUM_CITIES - 1); // 确保起点不是 0
    int end = start + (rand() % (NUM_CITIES - start));

    // 复制父代 1 的城市到子代
    for (int i = start; i <= end; i++) {
        child[i] = parent1[i];
    }

    // 从父代 2 中选择未选择的城市添加到子代中
    int current = (end + 1) % NUM_CITIES;
    for (int i = 0; i < NUM_CITIES; i++) {
        int candidate = parent2[(end + 1 + i) % NUM_CITIES];
        int found = 0;
        for (int j = start; j <= end; j++) {
            if (child[j] == candidate) {
                found = 1;
                break;
            }
        }
        if (!found) {
            child[current] = candidate;
            current = (current + 1) % NUM_CITIES;
        }
    }
    child[0] = 0; // 确保起点为城市 0
}

// 变异函数（交换变异）
void mutation(int individual[]) {
    if (rand() % 100 < MUTATION_RATE) { // MUTATION_RATE 百分比的变异概率
        int idx1 = 1 + rand() % (NUM_CITIES - 1); // 确保不变异起点 0
        int idx2 = 1 + rand() % (NUM_CITIES - 1);
        // 确保 idx1 和 idx2 不同
        while (idx1 == idx2) {
            idx2 = 1 + rand() % (NUM_CITIES - 1);
        }
        // 交换城市
        int temp = individual[idx1];

```

```

        individual[idx1] = individual[idx2];
        individual[idx2] = temp;
    }
}

// 初始化种群
void initialize_population(int population[][NUM_CITIES]) {
    for (int i = 0; i < POPULATION_SIZE; i++) {
        population[i][0] = 0; // 确保起点为城市 0
        for (int j = 1; j < NUM_CITIES; j++) {
            population[i][j] = j;
        }
        // 打乱除起点城市 0 以外的其他城市
        for (int j = 1; j < NUM_CITIES; j++) {
            int swap_idx = 1 + rand() % (NUM_CITIES - 1);
            int temp = population[i][j];
            population[i][j] = population[i][swap_idx];
            population[i][swap_idx] = temp;
        }
    }
}

int main() {
    srand(time(NULL)); // 初始化随机种子

    int population[POPULATION_SIZE][NUM_CITIES];
    int new_population[POPULATION_SIZE][NUM_CITIES];
    double fitness_values[POPULATION_SIZE];

    // 初始化种群
    initialize_population(population);

    // 进化种群
    for (int generation = 0; generation < GENERATIONS; generation++) {
        // 计算每个个体的适应度
        for (int i = 0; i < POPULATION_SIZE; i++) {
            fitness_values[i] = fitness(population[i]);
        }

        // 创建新种群
        for (int i = 0; i < POPULATION_SIZE; i += 2) {
            int parent1_idx = select_individual(fitness_values);
            int parent2_idx = select_individual(fitness_values);

```

```

        crossover(population[parent1_idx], population[parent2_idx], new_population[i]);
        crossover(population[parent2_idx], population[parent1_idx], new_population[i +
1]);

        mutation(new_population[i]);
        mutation(new_population[i + 1]);
    }

    // 将新种群复制到当前种群
    for (int i = 0; i < POPULATION_SIZE; i++) {
        for (int j = 0; j < NUM_CITIES; j++) {
            population[i][j] = new_population[i][j];
        }
    }

    // 每 10000 代打印一次最佳适应度
    if (generation % 10000 == 0) {
        double best_fitness = fitness_values[0];
        for (int i = 1; i < POPULATION_SIZE; i++) {
            if (fitness_values[i] > best_fitness) {
                best_fitness = fitness_values[i];
            }
        }
        printf("Generation %d: Best Fitness = %.5f\n", generation, best_fitness);
    }
}

// 找到最终种群中最好的个体并打印
int best_individual_idx = 0;
double best_fitness = fitness_values[0];
for (int i = 1; i < POPULATION_SIZE; i++) {
    if (fitness_values[i] > best_fitness) {
        best_fitness = fitness_values[i];
        best_individual_idx = i;
    }
}

printf("Best Path Length: %.2f\n", 1.0 / best_fitness);
printf("Best Path Sequence: ");
for (int i = 0; i < NUM_CITIES; i++) {
    printf("%d ", population[best_individual_idx][i]);
}
printf("\n");

```

```
return 0;
}
```

测试分析

采用以下条件时，某次运行得到结果为{0, 3, 7, 6, 4, 1, 9, 8, 5, 2}，与教材结论相同，是最短路径。

```
#define NUM_CITIES 10
#define POPULATION_SIZE 100
#define GENERATIONS 100000
#define MUTATION_RATE 0.05

Generation 40000: Best Fitness = 0.03454
Generation 41000: Best Fitness = 0.03454
Generation 42000: Best Fitness = 0.03454
Generation 43000: Best Fitness = 0.03454
Generation 44000: Best Fitness = 0.03454
Generation 45000: Best Fitness = 0.03454
Generation 46000: Best Fitness = 0.03454
Generation 47000: Best Fitness = 0.03454
Generation 48000: Best Fitness = 0.03454
Generation 49000: Best Fitness = 0.03454
Best Path Length: 28.95
Best Path Sequence: 0 3 7 6 4 1 9 8 2 5
```

在测试时发现，有时无法得到最优解，这与个体数量、繁衍代数、变异概率的设置有关。后来发现增加繁衍代数可以解决，或者增加个体数量，调整变异概率。另外还与代码中使用了当前时间作为伪随机数种子有关，所以不同时间运行得到结果也可能不一样。

结论

遗传算法是一种比较经典的启发式算法，在求解复杂问题时有很大的优点。但是在编码方式与各算子的设置以及种群数量、繁衍代数、变异概率等方面需要注意。