Название документа

Спецификация на A7105, 2.4ГГц FSK/GFSK Приемопередатчик со скоростью передачи данных 2 Кбит/с ~ 500 Кбит/с

История изменений

Изм. No.	История	Дата выпуска	Замечание
0.0	Первоначальный выпуск.	Дек 27, 2007	Предварительный
0.1	Изменена спецификация и добавлен раздел для настройки мощности TX	Фев 20, 2008	Предварительный
0.2	Добавлена информацию о маркировке, профиль оплавления, размеры ленты и катушки для транспортировки	Окт. 9 , 2008	Предварительный
0.3	Изменено описание состояния и режима FIFO Переименовано IRQS1/IRQS2 в GIO1S/GIO2S Переименовано GPIO1/GPIO2 в GIO1/GIO2 Добавлены Легкий режим FIFO, Сегментный режим FIFO Удалена функция термодатчика / измерение внешнего напряжения Удалена функция TWWS Добавлена диаграмма состояния быстрого/нормального/энергосберегающего режима FIFO Добавлена диаграмма состояния прямого режима Переименовать MAster Clock F_{CSCK} в F_{MCLK} Измените поддержку скорости передачи данных с 1K~500K на 2K ~ 500K	Янв. 7, 2009	Предварительный
1.0	Пересмотрено описание статуса и режима FIFO Удалены ненужные компоненты схемы в приложении Добавлена кривая RSSI Добавлено руководство по макету	Август, 2009	Полный Производство
1.1	Пересмотрено мин. рабочее напряжение от 1.9V до 2.0V и типичный ток TX (0dBm) с 19мА до 20мА	Фев., 2010	Полный Производство
1.2	Добавлено примечание 9 в главу 8, спецификация. Исправлена опечатка на страницах (51, 52, 57, 62, 66, 78, 79).	Ноя., 2010	Полный Производство
1.3	Изменено Английское Название Компании	Ноя. 30, 2010	Полный Производство
1.4	Пересмотрено описание контактов VDA1, VDA2, VDA3 в Ch5. и изменена информация о катушке ленты и добавлен адрес офиса Shenzhen.	Янв., 2011	Полный Производство

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Содержание

1. Общее описание

A7105 - это высокопроизводительный и недорогой беспроводной приемопередатчик диапазона ISM 2,4 ГГц. Это устройство объединяет в себе как высокочувствительный приемник (-95дБм при 500 Кбит/с), так и высокоэффективный усилитель мощности (до 1 дБм). При низкой скорости передачи данных A7105 обладает особой устойчивостью на дальнем расстоянии прямой видимости из-за своей сверхвысокой чувствительности (-107дБм при 2 Кбит/с, -104дБм при 25 Кбит/с) без необходимости внешней LNA или PA. Регистр скорости передачи данных (0x0E) позволяет пользователю настроить скорость передачи данных от 2 Кбит/с до 500 Кбит/с.

A7105 имеет быстрое время настройки (130 мкс) для систем скачкообразной перестройки частоты. Для обработки пакетов A7105 имеет встроенный разделенный 64-байтовый TX/RX FIFO (может быть расширен до 256 байт) для буферизации данных и пакетной передачи, CRC для обнаружения ошибок, FEC для 1-битной коррекции данных на кодовое слово, RSSI для оценки качества канала, отсеивание данных для шифрования / дешифрования данных. Эти функции очень просты в использовании при разработке беспроводной системы. Все функции интегрированы в небольшой чип QFN 4X4 20 контактов.

К управляющим регистрам A7105 можно легко получить доступ через 3-проводную или 4-проводную шину SPI. Для экономии энергии A7105 поддерживает спящий режим, режим ожидания. Для удобства использования A7105 имеет уникальный набор команд SPI под названием Strobe commAnd, которые используются для управления. Основываясь на стробоскопических командах через шину SPI, MCU может управлять всем: от энергосбережения, отправки TX, приема RX, мониторинга каналов, скачкообразной перестройки частоты до автоматической калибровки. Кроме того, A7105 поддерживает две линии ввода-вывода общего назначения, GIO1 и GIO2, чтобы сообщить MCU его статус, чтобы MCU мог использовать либо опрос, либо схему прерывания для выполнения радиоуправления. Следовательно, очень легко контролировать радиопередачу между MCU и A7105 из-за его цифрового интерфейса.

2. Типичные области применения

- Беспроводные клавиатуры и мыши
- Дистанционное управление
- Радиоуправление вертолетом и самолетом

- 2400 ~ 2483.5 МГц ISM система
- Беспроводное измерение и автоматизация зданий
- Беспроводные игрушки и игровые контроллеры

3. Характеристики

- Малый размер (QFN4 X4, 20 контактов).
- Частотный диапазон: 2400 ~ 2483.5МГц.
- FSK или GFSK модуляция
- Низкое потребление тока: RX 16мА, TX 20мА (при выходной мощности 0 дБм).
- Низкий ток сна (1.5 мкА).
- Имеет регулятор напряжения, поддерживаемое напряжение 2.0 ~ 3.6 В.
- Программируемая скорость передачи данных от 2 Кбит/с до 500 Кбит/с.
- Программируемый уровень мощности TX – от 20 дБм до 1 дБм.
- Сверхвысокая чувствительность:
    - -95дБм при скорости передачи данных 500Кбит/с.
    - -97дБм при скорости передачи данных 250Кбит/с
    - -104дБм при скорости передачи данных 25Кбит/с
    - -107дБм при скорости передачи данных 2Кбит/с
- Быстрое время настройки (130 us) для системы скачкообразной перестройки частоты.
- Встроенный детектор батареи.
- Поддержка недорогого генератора (6 / 8 /12 / 16 / 20 / 24МГц).
- Поддержка совместного использования генератора, (1 / 2 / 4 / 8МГц) с MCU.
- Поддержка частотной компенсации.
- Простота использования.
    - Поддержка 3-проводного или 4-проводного SPI.
    - Уникальная стробоскопическая команда через SPI.
    - Настройка ОДНОГО регистра для новой частоты канала.
    - 8-битный цифровой RSSI для четкой индикации канала.
    - Режим быстрого обмена при переключении ролей TRX.
    - Автоматическое измерение RSSI.
    - Автоматическая калибровка.
    - Автоматическая функция IF.
    - Автоматическая проверка CRC.
    - Авто FEC (7, 4) код Хэмминга (1 бит коррекции ошибок/кодовое слово).

◆ Отсеивание данных для шифрования и дешифрования.
◆ Разделенные 64 байта RX и TX FIFO.
◆ Простое расширение FIFO / Segment FIFO / FIFO (до 256 байт).
◆ Поддержка прямого режима тактового выхода на MCU.
◆ Поддержка режима FIF с сигналом синхронизации кадров с MCU.

4. Конфигурация контактов
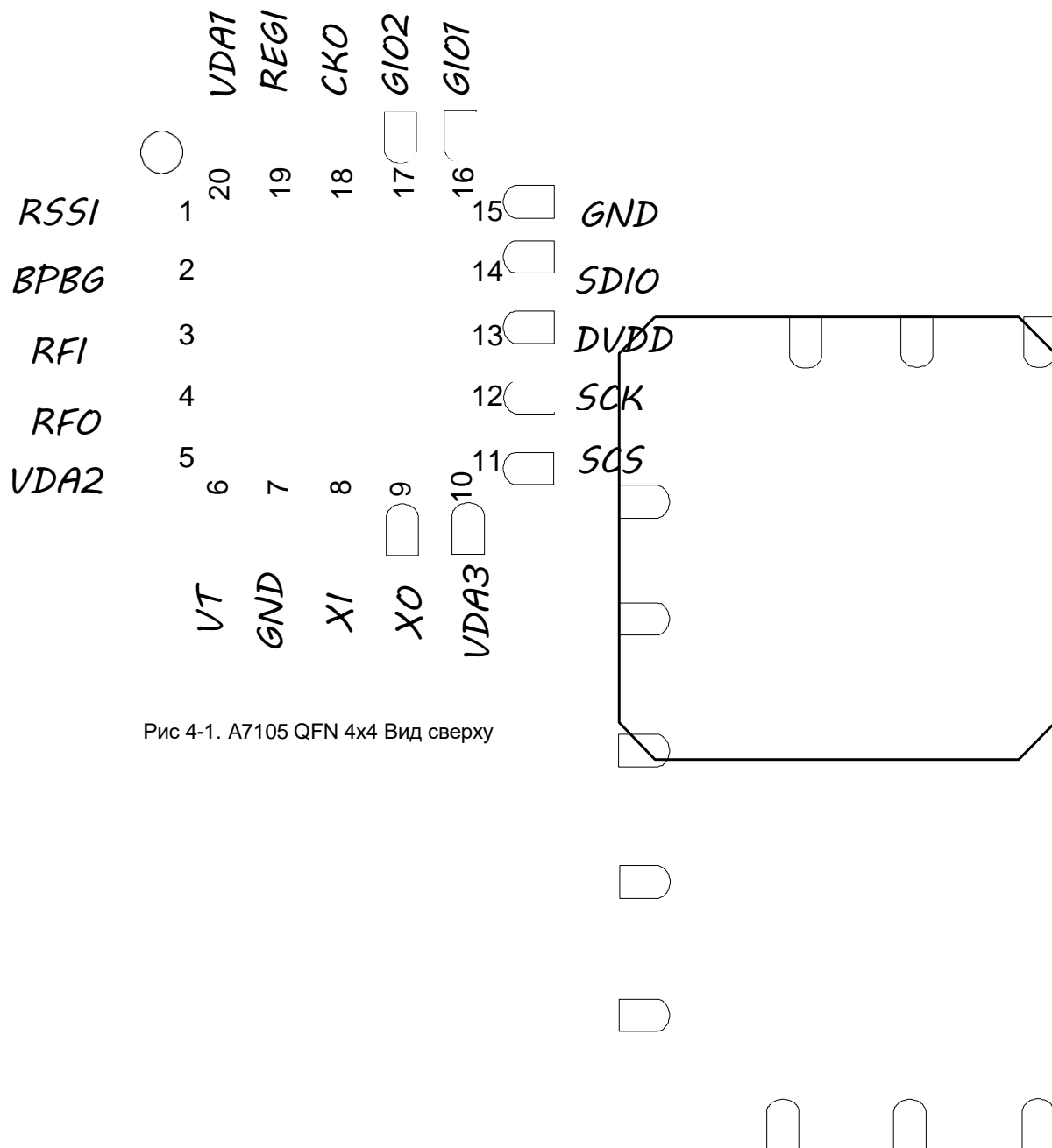
Рис 4-1. A7105 QFN 4x4 Вид сверху

5. Описание контактов (I: ввод; O: вывод, I/O: ввод и вывод)

Контакт No.	Обозначение	I/O	Описание функции
1	RSSI	O	Подключен к байпасному конденсатору для считывания RSSI.
2	BPBG	O	Соединен с байпасным конденсатором для внутренней точки смещения регулятора
3	RFI	I	Вход усилителя с низким уровнем шума.
4	RFO	O	Выход усилителя мощности. (питается от VDA1)
5	VDA2	I/O	Источник напряжения TRX **(от внутреннего аналогового регулятора IC)**, подключенный к байпасному конденсатору.
6	VT	I	Вход управления частотой VCO
7	GND	G	Земля
8	XI	I	Входной узел кварцевого генератора
9	XO	O	Выходной узел кварцевого генератора
10	VDA3	I	Источник напряжения **(от VDA1, конт. 20)** для PLL
11	SCS	I	3-проводный SPI выбор чипа.
12	SCK	I	3-проводный SPI тактирование.
13	DVDD	I	Источник напряжения TRX (от внутреннего цифрового регулятора IC), подключенный к байпасному конденсатору.
14	SDIO	I/O	3-проводный SPI для чтения/записи данных SPI.
15	GND	G	Земля
16	GIO1	I/O	Многофункциональный GIO 1 / 4-проводной вывод данных SPI.
17	GIO2	I/O	Многофункциональный GIO 2 / 4-проводной вывод данных SPI.
18	CKO	O	Многофункциональный тактовый выход.
19	REGI	I	Вход внутреннего регулятора **(Внешний Вход Питания)**
20	VDA1	I/O	Выход внутреннего аналогового регулятора для питания **RFO (конт. 4) и VDA3 (конт. 10)**.
	Задняя пластина	G	Земля. Задняя пластина должна быть хорошо припаяна к земле; в противном случае это повлияет на радиочастотные характеристики.

6. Блок-схема чипа
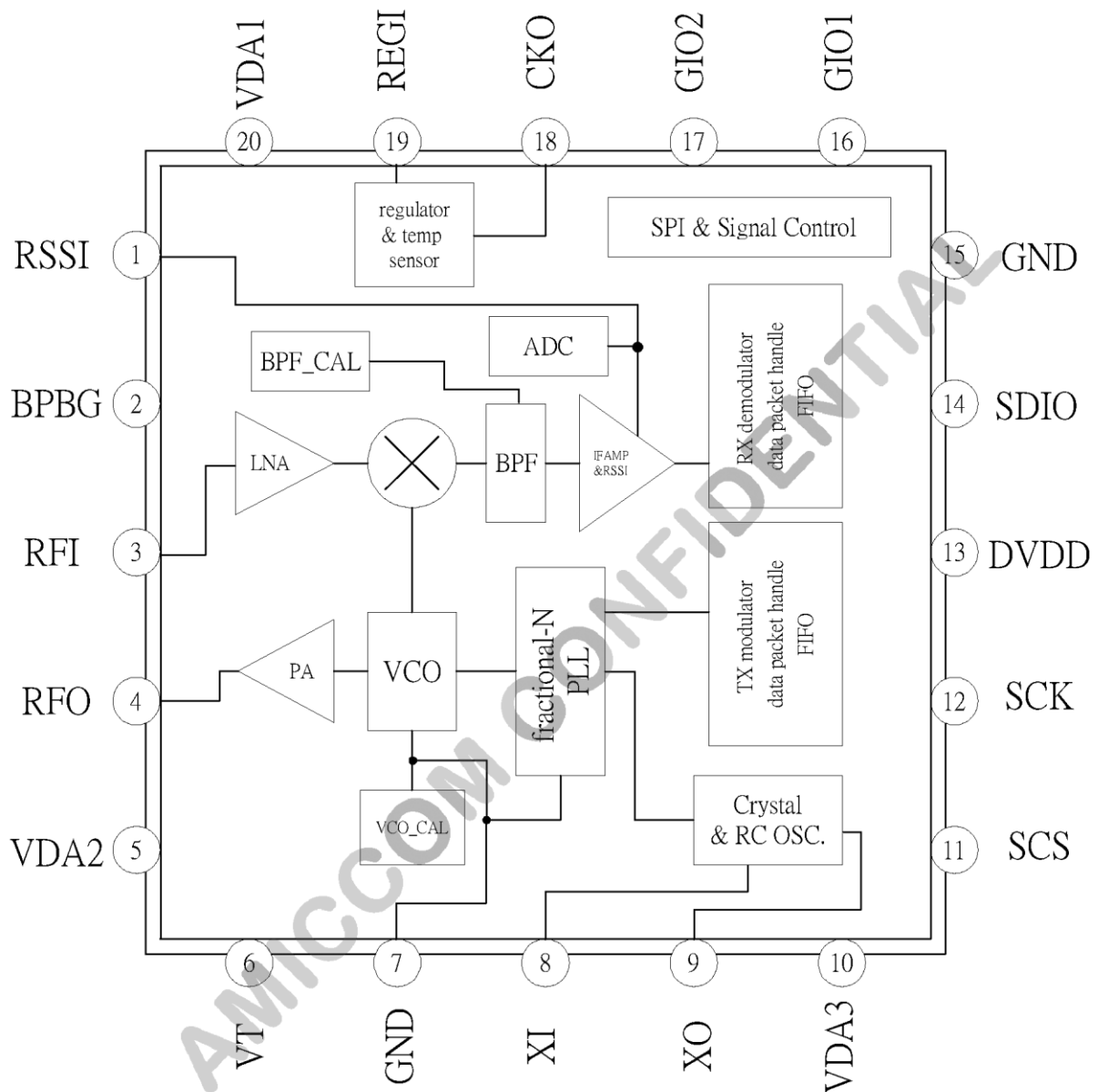
Рис 6-1. A7105 Блок-схема

7. Абсолютный максимум номинальных параметров

Параметр	Относительно	Номинальное значение	Единица измерения
Питающее напряжение (VDD)	GND	-0.3 ~ 3.6	В
Цифровые IO выводы	GND	-0.3 ~ VDD+0.3	В
Напряжение на аналоговых выводах	GND	-0.3 ~ 2.1	В
Входной RF уровень		5	дБм
Температура хранения		-55 ~ 125	°C
ESD	HBM	± 2K	В
	MM	± 100	В

*Напряжения, превышающие значения, указанные в разделе " Абсолютный максимум номинальных параметров", могут привести к необратимому повреждению устройства. Это только номинальные напряжения; функциональная работа устройства при этих или любых других условиях, превышающих указанные в эксплуатационных разделах настоящей спецификации, не подразумевается. Воздействие абсолютных максимальных номинальных условий в течение длительного периода времени может повлиять на надежность устройства.

* Устройство чувствительно к ESD. Используйте соответствующие меры предосторожности при ESD. HBM (Режим человеческого тела) тестируется по методу MIL-STD-883FMethod 3015.7. MM (Машинный режим) тестируется по методуJEDEC EIA/JESD22-A115-A.
* Прибор имеет уровень чувствительности к влаге III (MSL 3).

8. Электрические характеристики

(Ta=25℃, VDD=3.0В, скорость передачи данных = 500Кбит/с, IF пропускная способность = 500кГц, F_{XTAL} =16МГц, с матчевой сетью и фильтром нижних частот, регулятор в чипе = 2.1В, если не указано иное.)

Параметр	Описание	Мин.	Типичное	Макс.	Единица измерения
Общие					
Рабочая температура		-40		85	°C
Напряжение питания (VDD)	с внутренним регулятором	2.0		3.6	В
Потребляемый ток	Спящий режим (RC OSC off)		1.5[*1]		мкА
	Холостой ход (Regulator on)		0.3[*1]		мА
	Режим ожидания (XOSC on,clock generator on)		1.9		мА
	PLL mode		9		мА
	RX Mode		16		мА
	TX Mode (@0дБм output)		20		мА
	TX Mode (@-3дБм output)		16		мА
	TX Mode (@-6дБм output)		14.5		мА
	TX Mode (@-11дБм output)		13.9		мА
	TX Mode (@-20дБм output)		12.5		мА
PLL блок					
Время запуска [*2]			0.6		мс
Частота			6, 8, 12, **16**, 20, 24		МГц
Допуск	без FW FC		±10		ppm
	с FW FC		±20		ppm
ESR				80	Ом
VCO Рабочая частота		2400		2483.5	МГц
PLL фазовый шум	Смещение 10k Смещение 100K Смещение 1M		80 85 90		дБн
PLL время успокоения [*3]	@Loop BW = 500КГц		70		мкс
Передатчик					
Диапазон выходной мощности		-20	0		дБм
Внеполосное паразитное излучение [*4]	30МГц~1ГГц			-36	дБм
	1ГГц~12.75ГГц			-30	дБм
	1.8ГГц~ 1.9ГГц			-47	дБм
	5.15ГГц~ 5.3ГГц			-47	дБм
Отклонение частоты [*5]	Data rate > 50КБит/с		186K		Гц
	Date rate <=50КБит/с		124K		Гц
Скорость передачи данных		2K		500K	Бит/с
Время готовности TX [*6] (PLL к WPLL + WPLL к TX)	@Loop BW = 500 КГц, LO fixed		10+60		мкс
	@Loop BW = 500 КГц, Hopping		70+60		мкс
Приемник					
Чувствительность приемника @ BER = 0.1%	Data rate 500K (F_{IF} = 500КГц)		-95		дБм
	Data rate 250K (F_{IF} = 500КГц)		-97		дБм

	Data rate 25K (F$_{IF}$ = 500КГц)			-104		дБм
	Data rate 2K (F$_{IF}$ = 500КГц)			-107		дБм
IF полоса пропускания частоты				250/500		КГц
IF центральная частота				250/500		КГц
Вмешательство [7]	Co-Channel (C/I$_0$)			11		дБ
	±1МГц Adjacent Channel			- 20		дБ
	±2МГц Adjacent Channel			- 30		дБ
	> ±5МГц Adjacent Channel			- 40		дБ
	ImAge (C/I$_{IM}$)			- 12		дБ
Максимальная рабочая входная мощность	@RF input (BER=0.1%)				0	дБм
Паразитная эмиссия [4]	30МГц~1ГГц				-57	дБм
	1ГГц~12.75ГГц				-47	
RSSI Диапазон	@RF input		-105		-50	дБм
Время готовности RX [8] (PLL к WPLL + WPLL к RX)	LO fixed	Data rate < = 125 КБит/с		10+40		мкс
		Data rate = 250 КБит/с		10+100		мкс
		Data rate = 500 КБит/с		10+60		мкс
	Hopping	Data rate < = 125 КБит/с		70+40		мкс
		Data rate = 250 КБит/с		70+100		мкс
		Data rate = 500 КБит/с		70+60		мкс
RX Паразитная эмиссия	свыше 1ГГц				-47	дБм
Регулятор						
Время установления регулятора	Вывод 2 соединить с 1.5 нФ			500[9]		мкс
Опорное напряжение				1.23		В
Выходное напряжение регулятора			1.8	2.1	2.3	В
Линейное регулирование	Ток нагрузки 30мА		35	40		дБн
Характеристики уровней цифрового ввода-вывода						
Высокий Входное напряжение (V$_{IH}$)			0.8*VDD		VDD	В
Низкий Входное напряжение (V$_{IL}$)			0		0.2*VDD	В
Высокий Выходное напряжение (V$_{OH}$)	@I$_{OH}$= -0.5мА		VDD-0.4		VDD	В
Низкий Выходное напряжение (V$_{OL}$)	@I$_{OL}$= 0.5мА		0		0.4	В

Примечание 1: Когда цифровые контакты ввода-вывода сконфигурированы на ввод, эти контакты НЕ должны быть плавающими, а должны подтягиваться либо питанию, либо к земле (SCS должен подтягиваться только к питанию); в противном случае будет индуцирован ток утечки.
Примечание 2: Обратитесь к Регистру задержки II (17h), чтобы настроить задержку успокоения.
Примечание 3: Обратитесь к Регистру задержки I (17h) для настройки PDL (PLL settling delay).
Примечание 4: С внешним радиочастотным фильтром, который обеспечивает минимальное затухание 17 дБ в диапазоне: 30МГц~2ГГц и 3ГГц~12,75ГГц.
Примечание 5: Обратитесь к регистру TX II (15h) для настройки FD [4:0].
Примечание 6: Для настройки задержки PDL и TDL обратитесь к Регистру задержки I (17h).
Примечание 7: Уровень мощности искомого сигнала устанавливается на уровне чувствительности +3 дБ. Данные модуляции для искомого сигнала и интерферометра PN9 и PN15 соответственно. Расстояние между каналами составляет 500 кГц.
Примечание 8: Для 250К/500КБит/с установите DCM[1:0]= [10b] по ID, (29h). Для <= 125Кбит/с установите DCM[1:0]= [01b] по преамбуле (29h).
Примечание 9: При VDD < 2,1В и температуре < -30°C время установления регулятора составит до 20мс.

9. Управляющие регистры

A7105 содержит 51 x 8-бит управляющий регистр. MCU может получить доступ к этим управляющим регистрам через 3-проводный (SCS, SCK, SDIO) или 4-проводный (SCS, SCK, SDIO, GIO1/GIO2) SPI-интерфейс (поддержка макс. скорость передачи данных SPI до 10 Мбит/с). Пользователь может обратиться к главе 10 для получения подробной информации о временных задержках SPI. A7105 управляется просто регистрами и выводит свое состояние на микроконтроллер выводами GIO1 и GIO2.

9.1 Таблица управляющих регистров

Адрес / Имя	R/W	Бит 7	Бит 6	Бит 5	Бит 4	Бит 3	Бит 2	Бит 1	Бит 0
00h Mode	W	RESETN	RESETN	RESETN	RESETN	RESETN	RESETN	RESETN	RESETN
	R	--	FECF	CRCF	CER	XER	PLLER	TRSR	TRER
01h Mode control I	W	DDPC	ARSSI	AIF	DFCD	WWSE	FMT	FMS	ADCM
	R	DDPC	ARSSI	AIF	CD	WWSE	FMT	FMS	ADCM
02h Mode control II	R/W	--	--	--	--	--	VCC	VBC	FBC
03h FIFO I	W	FEP7	FEP6	FEP5	FEP4	FEP3	FEP2	FEP1	FEP0
04h FIFO II	W	FPM1	FPM0	PSA5	PSA4	PSA3	PSA2	PSA1	PSA0
05h FIFO Data	R/W	FIFO7	FIFO6	FIFO5	FIFO4	FIFO3	FIFO2	FIFO1	FIFO0
06h ID Data	R/W	ID7	ID6	ID5	ID4	ID3	ID2	ID1	ID0
07h RC OSC I	W	WWS_SL7	WWS_SL6	WWS_SL5	WWS_SL4	WWS_SL3	WWS_SL2	WWS_SL1	WWS_SL0
	R	--	--	RCOC5	RCOC4	RCOC3	RCOC2	RCOC1	RCOC0
08h RC OSC II	W	WWS_SL9	WWS_SL8	WWS_AC5	WWS_AC4	WWS_AC3	WWS_AC2	WWS_AC1	WWS_AC0
09h RC OSC III	W	BBCKS1	BBCKS0	--	--	--	RCOSC_E	TSEL	TWWS_E
0Ah CKO Pin	W	ECKOE	CKOS3	CKOS2	CKOS1	CKOS0	CKOI	CKOE	SCKI
0Bh GPIO1 Pin I	W	--	--	GIO1S3	GIO1S2	GIO1S1	GIO1S0	GIO1I	GIO1OE
0Ch GPIO2 Pin II	W	--	--	GIO2S3	GIO2S2	GIO2S1	GIO2S0	GIO2I	GIO2OE
0Dh Clock	R/W	GRC3	GRC2	GRC1	GRC0	CSC1	CSC0	CGS	XS
0Eh Data rate	R/W	SDR7	SDR6	SDR5	SDR4	SDR3	SDR2	SDR1	SDR0
0Fh PLL I	R/W	CHN7	CHN6	CHN5	CHN4	CHN3	CHN2	CHN1	CHN0
10h PLL II	R/W	DBL	RRC1	RRC0	CHR3	CHR2	CHR1	CHR0	IP8
11h PLL III	R/W	IP7	IP6	IP5	IP4	IP3	IP2	IP1	IP0
12h PLL IV	W	FP15	FP14	FP13	FP12	FP11	FP10	FP9	FP8
	R	--	AC14	AC13	AC12	AC11	AC10	AC9	AC8
13h PLL V	W	FP7	FP6	FP5	FP4	FP3	FP2	FP1	FP0
	R	AC7	AC6	AC5	AC4	AC3	AC2	AC1	AC0
14h TX I	W	TXSM1	TXSM0	TXDI	TME	FS	FDP2	FDP1	FDP0
15h TX II	W	--	PDV1	PDV0	FD4	FD3	FD2	FD1	FD0
16h Delay I	W	DPR2	DPR1	DPR0	TDL1	TDL0	PDL2	PDL1	PDL0
17h Delay II	W	WSEL2	WSEL1	WSEL0	AGC_D1	AGC_D0	RS_DLY2	RS_DLY1	RS_DLY0

Addr	R/W							
18h RX	W	--	RXSM1	RXSM0	FC	RXDI	DMG	BWS	ULS
19h RX Gain I	R/W	MVGS	--	IGC	MGC1	MGC0	LGC2	LGC1	LGC0
1Ah RX Gain II	W	RH7	RH6	RH5	RH4	RH3	RH2	RH1	RH0
1Bh RX Gain III	W	RL7	RL6	RL5	RL4	RL3	RL2	RL1	RL0
1Ch RX Gain IV	W	ENGC	--	--	--	MHC	LHC1	LHC0	VGCE
1Dh RSSI Threshold	W	RTH7	RTH6	RTH5	RTH4	RTH3	RTH2	RTH1	RTH0
	R	ADC7	ADC6	ADC5	ADC4	ADC3	ADC2	ADC1	ADC0
1Eh ADC	W	RSM1	RSM0	ERSS	FSARS	--	XADS	RSS	CDM
1Fh Code I	W	--	MCS	WHTS	FECS	CRCS	IDL	PML1	PML0
20h Code II	W	--	DCL2	DCL1	DCL0	ETH1	ETH0	PMD1	PMD0
21h Code III	W	--	WS6	WS5	WS4	WS3	WS2	WS1	WS0
22h IF Calibration I	W	--	--	--	MFBS	MFB3	MFB2	MFB1	MFB0
	R	--	--	--	FBCF	FB3	FB2	FB1	FB0
23h IF Calibration II	R	--	--	--	FCD4	FCD3	FCD2	FCD1	FCD0
24h VCO current Calibration	W	--	--	VCCS	MVCS	VCOC3	VCOC2	VCOC1	VCOC0
	R	--	--	--	FVCC	VCB3	VCB2	VCB1	VCB0
25h VCO Single band Calibration I	W	--	--	--	--	MVBS	MVB2	MVB1	MVB0
	R	--	--	DVT1	DVT0	VBCF	VB2	VB1	VB0
26h VCO Single band Calibration II	W	--	--	VTH2	VTH1	VTH0	VTL2	VTL1	VTL0
27h Battery detect	W	RGS	RGV1	RGV0	--	BVT2	BVT1	BVT0	BDS
	R	RGS	RGV1	RGV0	BDF	BVT2	BVT1	BVT0	BDS
28h TX test	W	--	--	TXCS	PAC1	PAC0	TBG2	TBG1	TBG0
29h Rx DEM test I	W	DMT	DCM1	DCM0	MLP1	MLP0	SLF2	SLF1	SLF0
2Ah Rx DEM test II	W	DCV7	DCV6	DCV5	DCV4	DCV3	DCV2	DCV1	DCV0
2Bh CPC	W	--	--	--	--	--	--	CPC1	CPC0
2Ch Crystal test	W	--	--	--	--	DBD	XCC	XCP1	XCP0
2Dh PLL test	W	--	PMPE	PRRC1	PRRC0	PRIC1	PRIC0	SDPW	NSDO
2Eh VCO test I	W	--	--	--	TLB	TLB	RLB	RLB	VCBS
2Fh VCO test II	W	--	--	--	--	RFT3	RFT2	RFT1	RFT0
30h IFAT	W	IGFI2	IGFI1	IGFI0	IGFQ2	IGFQ1	IGFQ0	IFBC	LIMC
31h RScale	R/W	RSC7	RSC6	RSC5	RSC4	RSC3	RSC2	RSC1	RSC0
32h Filter test	W	FT7	FT6	FT5	FT4	FT3	FT2	FT1	FT0

Обозначение: -- = зарезервировано

9.2 Описание управляющих регистров

9.2.1 Регистр Mode   (Адрес: 00h)

Имя	R/W	Бит 7	Бит 6	Бит 5	Бит 4	Бит 3	Бит 2	Бит 1	Бит 0
Mode	R	--	FECF	CRCF	CER	XER	PLLER	TRSR	TRER
	W	RESETN	RESETN	RESETN	RESETN	RESETN	RESETN	RESETN	RESETN
Сброс		--	--	--	--	--	--	--	--

RESETN: Запись в этот регистр 0x00 приведет к выдаче команды сброса, после регистр автоматически очистится

FECF: FEC флаг.
[0]: FEC пройдено. **[1]:** FEC ошибка. (FECF доступен только для чтения, обновляется при приеме каждого пакета.)

CRCF: CRC флаг.
[0]: CRC пройдено. **[1]:** CRC ошибка. (CRCF доступен только для чтения, обновляется при приеме каждого пакета.)

CER: Статус включения радиочастотного(RF) чипа.
[0]: RF чип выключен. **[1]:** RF чип включен.

XER: Статус включения внутреннего кварцевого генератора.
[0]: Кварцевого генератора выключен. **[1]:** Кварцевого генератора включен.

PLLE: Статус включения PLL.
[0]: PLL выключено. **[1]:** PLL включено.

TRER: Состояние включения TRX.
[0]: TRX выключено. **[1]:** TRX включено.

TRSR: Регистр состояния TRX.
[0]: Прием(RX). **[1]:** Передача(TX).
Пригодный, если TRER=1 (TRX включено).

9.2.2 Регистр Mode Control   (Адрес: 01h)

Имя	R/W	Бит 7	Бит 6	Бит 5	Бит 4	Бит 3	Бит 2	Бит 1	Бит 0
Mode Control I	R	DDPC	ARSSI	AIF	DFCD	WWSE	FMT	FMS	ADCM
	W	DDPC	ARSSI	AIF	CD	WWSE	FMT	FMS	ADCM
Сброс		0	0	0	0	0	0	0	0

DDPC: В прямом режиме, если DDPC=1, MCU отправляет/получает необработанные данные пакета через SDIO контакт вместо GIO1 или GIO2 пинов.

[0]: **Выключено.** [1]: **Включено.**

ARSSI: Автоматическое измерение RSSI при входе в режим RX.
[0]: Выключено. **[1]:** Включено.

AIF (Авто смещение IF): LO частота RF будет автоматически смещаться на одну IF частоту при входе в режим RX.
[0]: Выключено. **[1]:** Включено.

CD / DFCD: DFCD (Фильтр данных по CD): Полученный пакет будет отфильтрован, если CD неактивен.
[0]: Выключено. **[1]:** Включено.

CD (Только для чтения): Сигнал детектора несущей.
[0]: Входная мощность ниже порога. **[1]:** Входная мощность выше порога.

WWSE: Зарезервировано для внутренних нужд. Должно быть установлено значение [0].

FMT: Зарезервировано для внутренних нужд. Должно быть установлено значение [0].

FMS: Выбор режима Direct/FIFO.
[0]: Direct режим. **[1]:** FIFO режим.

ADCM: ADC measurement enable (Auto clear when done).
[0]: Disable measurement or measurement finished. **[1]:** Enable measurement.

ADCM	A7105 @ Standby mode	A7105 @ RX mode
[0]	Disable ADC	Disable ADC
[1]	No function	Measure RSSI, carrier detect

Refer to chapter 17 for details.

9.2.3 Calibration Control Register   (Address: 02h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Mode Control II	R/W	--	--	--	--	--	VCC	VBC	FBC
Reset		--	--	--	--	--	0	0	0

VCC: VCO Current calibration enable (Auto clear when done).
[0]: Disable. **[1]:** Enable.

VBC: VCO Bank calibration enable (Auto clear when done).
[0]: Disable. **[1]:** Enable.

FBC: IF Filter Bank calibration enable (Auto clear when done).
[0]: Disable. **[1]:** Enable.

9.2.4 FIFO Register I   (Address: 03h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
FIFO I	W	FEP7	FEP6	FEP5	FEP4	FEP3	FEP2	FEP1	FEP0
Reset		0	0	1	1	1	1	1	1

FEP [7:0]: FIFO End Pointer for TX FIFO and Rx FIFO.
Refer to chapter 16 for details.

9.2.5 Адрес FIFO Register II   (Address: 04h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
FIFO II	W	FPM1	FPM0	PSA5	PSA4	PSA3	PSA2	PSA1	PSA0
Reset		0	1	0	0	0	0	0	0

FPM [1:0]: FIFO Pointer MArgin

PSA [5:0]: Used for Segment FIFO.
Refer to chapter 16 for details.

9.2.6 Регистр FIFO DATA   (Address: 05h)

Имя	R/W	Бит 7	Бит 6	Бит 5	Бит 4	Бит 3	Бит 2	Бит 1	Бит 0
FIFO DATA	R/W	FIFO7	FIFO6	FIFO5	FIFO4	FIFO3	FIFO2	FIFO1	FIFO0
Reset		0	0	0	0	0	0	0	0

FIFO [7:0]: Данные FIFO. TX FIFO (Только запись) и RX FIFO (Только чтение).
TX FIFO и RX FIFO общий адрес (05h)
Подробности см. в главе 16.

9.2.7 Регистр ID DATA (Address: 06h)

Имя	R/W	Бит 7	Бит 6	Бит 5	Бит 4	Бит 3	Бит 2	Бит 1	Бит 0
ID DATA	R/W	ID7	ID6	ID5	ID4	ID3	ID2	ID1	ID0
Сброс		0	0	0	0	0	0	0	0

ID [7:0]: Идентификатор.

При обращении к этому регистру идентификационные данные вводятся или выводятся последовательно (байт идентификатора 0,1, 2 и 3). Рекомендуется установить 0 байт идентификатора равный 5xh или Axh. Подробности см. в разделе 10.6.

9.2.8 RC OSC Register I (Address: 07h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
RC OSC I	R			RCOC5	RCOC4	RCOC3	RCOC2	RCOC1	RCOC0
	W	WWS_SL7	WWS_SL6	WWS_SL5	WWS_SL4	WWS_SL3	WWS_SL2	WWS_SL1	WWS_SL0
Reset		0	0	0	0	0	0	0	0

RCOC [5:0]: Reserved for internal usage only.

9.2.9 RC OSC Register II (Address: 08h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
RC OSC II	W	WWS_SL9	WWS_SL8	WWS_AC5	WWS_AC4	WWS_AC3	WWS_AC2	WWS_AC1	WWS_AC0
Reset		0	0	0	0	0	0	0	0

WWS_AC [5:0]: Reserved for internal usage only.

WWS_SL [9:0]: Reserved for internal usage only.

9.2.10 RC OSC Register III (Address: 09h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
RC OSC III	W	BBCKS1	BBCKS0	--	--	--	RCOSC_E	TSEL	TWWS_E
Reset		0	0	--	--	--	1	0	1

BBCKS [1:0]: Clock select for internal digital block Recommend BBCKS = [00]
[00]: F_{SYCK} / 8. **[01]:** F_{SYCK} / 16. **[10]:** F_{SYCK} / 32. **[11]:** F_{SYCK} / 64.

RCOSC_E: RC-oscillator enable. Reserved for internal usage only.
[0]: Disable. **[1]:** Enable.

TSEL: Timer select for TWWS function. Reserved for internal usage only.
[0]: Use WWS_AC. **[1]:** Use WWS_SL.

TWWS_E: Enable TWWS function. Reserved for internal usage only.
[0]: Disable. **[1]:** Enable.

9.2.11 CKO Pin Control Register (Address: 0Ah)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
CKO Pin Control	W	ECKOE	CKOS3	CKOS2	CKOS1	CKOS0	CKOI	CKOE	SCKI
Reset		1	0	1	1	1	0	1	0

ECKOE: External Clock Output Enable for CKOS [3:0]= [0100] ~ [0111].
[0]: Disable. **[1]:** Enable.

CKOS [3:0]: CKO pin output select.
[0000]: DCK (TX data clock) in TX mode, RCK (RX recovery clock) in RX mode.
[0001]: DCK (TX data clock) in TX mode, RCK (RX recovery clock) in RX mode.
[0010]: FPF (FIFO pointer flag).
[0011]: EOP, EOVBC, EOFBC, EOADC, EOVCC, OKADC (Internal usage only).
[0100]: External clock output= F_{SYCK}.
[0101]: External clock output / 2= F_{SYCK} / 2.
[0110]: External clock output / 4= F_{SYCK} / 4.
[0111]: External clock output / 8= F_{SYCK} / 8.
[1xxx]: Reserved.

CKOI: CKO pin output signal invert.
[0]: Non-inverted output. [1]: Inverted output.

CKOE: CKO pin Output Enable.
[0]: High Z. [1]: Enable.

SCKI: SPI clock input invert.
[0]: Non-inverted input. [1]: Inverted input.

9.2.12 Регистр GIO1 Pin Control I (Address: 0Bh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
GIO1 Pin Control I	W	--	--	GIO1S3	GIO1S2	GIO1S1	GIO1S0	GIO1I	GIO1OE
Reset		--	--	0	0	0	0	0	1

GIO1S [3:0]: GIO1 pin function select.

GIO1S [3:0]	TX state	RX state
[0000]	WTR (Ожидание, пока TX или RX не окончится)	
[0001]	EOAC (end of access code)	FSYNC (frame sync)
[0010]	TMEO (TX modulation enable)	CD (carrier detect)
[0011]	Preamble Detect Output (PMDO)	
[0100]	(Reserved.)	
[0101]	In phase demodulator input (DMII)	
[0110]	SDO (4 wires SPI data out)	
[0111]	TRXD In/Out (Direct mode)	
[1000]	RXD (Direct mode)	
[1001]	TXD (Direct mode)	
[1010]	In phase demodulator external input (EXDI0)	
[1011]	External FSYNC input in RX direct mode	
[11xx]	(Inhibited.)	

GIO1I: GIO1 pin output signal invert.
[0]: Non-inverted output. [1]: Inverted output.

GIO1OE: GIO1pin output enable.
[0]: High Z. [1]: Enable.

9.2.13 Регистр GIO2 Pin Control II (Address: 0Ch)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
GIO2 Pin Control II	W	--	--	GIO2S3	GIO2S2	GIO2S1	GIO2S0	GIO2I	GIO2OE
Reset		--	--	0	1	0	0	0	1

GIO2S [3:0]: GIO2 pin function select.

GIO2S	TX state	RX state
[0000]	WTR (Wait until TX or RX finished)	
[0001]	EOAC (end of access code)	FSYNC (frame sync)
[0010]	TMEO (TX modulation enable)	CD (carrier detect)
[0011]	Preamble Detect Output (PMDO)	
[0100]	(Reserved.)	
[0101]	Quadrature phase demodulator input (DMIQ)	
[0110]	SDO (4 wires SPI data out)	
[0111]	TRXD In/Out (Direct mode)	
[1000]	RXD (Direct mode)	
[1001]	TXD (Direct mode)	
[1010]	Quadrature phase demodulator external input (EXDI1)	
[1011]	External FSYNC input in RX direct mode	
[11xx]	(Inhibited.)	

GIO2I: GIO2 pin output signal invert.
[0]: Non-inverted output. **[1]:** Inverted output.

GIO2OE: GIO2 pin Output Enable.
[0]: High Z. **[1]:** Enable.

In TX mode
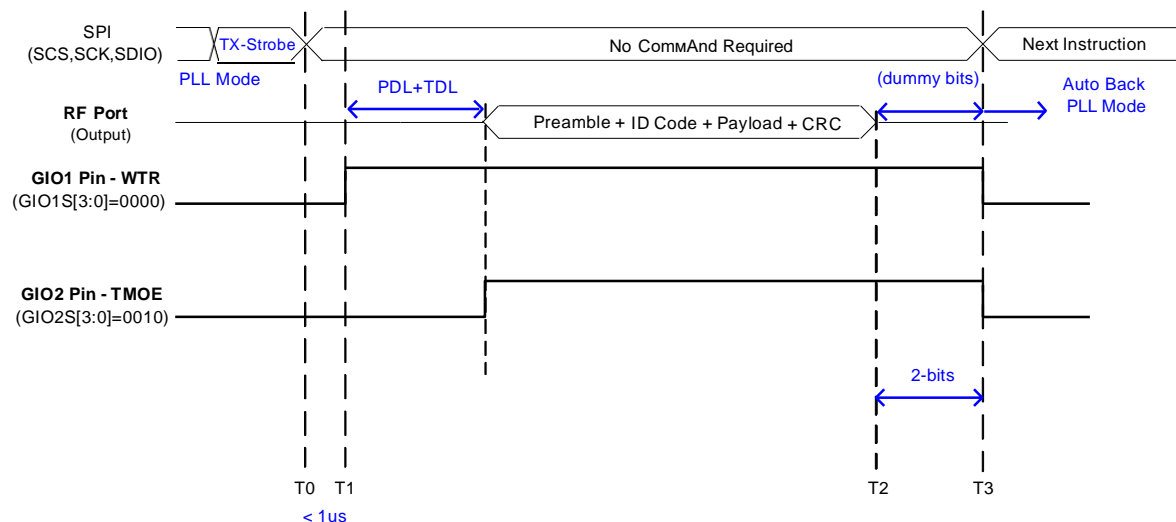
In RX mode
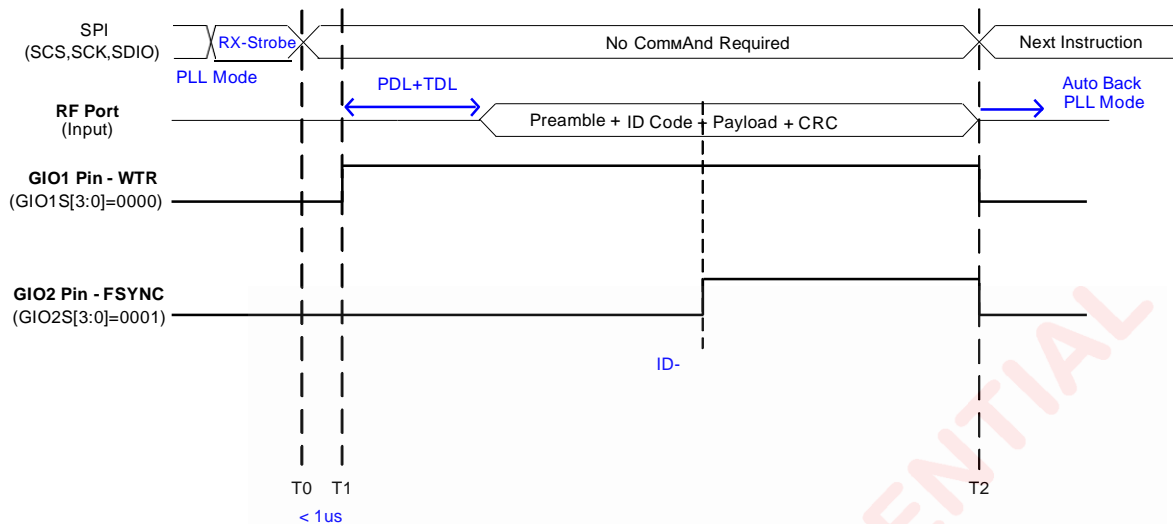
9.2.14 Clock Register (Address: 0Dh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Clock	R/W	GRC3	GRC2	GRC1	GRC0	CSC1	CSC0	CGS	XS
Reset		1	1	1	1	0	1	0	1

Refer to chapter 14 for details.

CGS: Clock generator enable. Recommend CGS = [0]
[0]: Disable. **[1]:** Enable.

CGS = 0 (recommend)	CGS = 1
Disable internal 32МГцPLL clock	F_{MCLK} = 32 MHz

XS: Crystal oscillator select. Recommend XS = [1]
[0]: External clock. **[1]:** Crystal.

GRC [3:0]: Clock generation reference counter.

GRC[3:0]	Note
Don't care	**Recommend when CGS = 0**
F_{XTAL} x (DBL+1) / (GRC+1) = 2M	When CGS = 1

CSC [1:0]: system clock F_{SYCK} divider select.

CSC [1:0]	System Clock F_{SYCK}	Note
00	F_{MCLK}	F_{SYCK} is used to determine
01 (Recommend)	F_{MCLK} / 2	1. Data rate (0Eh)
10	F_{MCLK} / 2	2. ADC clock (1Eh)
11	F_{MCLK} / 4	3. Internal digital clock (09h)
		4. CKO pin (0Ah)

9.2.15 Data Rate Register (Address: 0Eh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Data Rate	R/W	SDR7	SDR6	SDR5	SDR4	SDR3	SDR2	SDR1	SDR0
Reset		0	0	0	0	0	0	0	0

SDR [7:0]: Data rate division selection.
Data rate = F_{SYCK} / 32 / (SDR [7:0]+1). Refer to chapter 13 for details.

9.2.16 Регистр PLL I (Адрес: 0Fh)

Имя	R/W	Бит 7	Бит 6	Бит 5	Бит 4	Бит 3	Бит 2	Бит 1	Бит 0
PLL I	R/W	CHN7	CHN6	CHN5	CHN4	CHN3	CHN2	CHN1	CHN0
Сброс		0	0	0	0	0	0	0	0

CHN [7:0]: Выбор номера канала LO.
Подробности см. в главе 14.

9.2.17 PLL Register II (Address: 10h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLL II	R	DBL	RRC1	RRC0	CHR3	CHR2	CHR1	CHR0	IP8
	W	DBL	RRC1	RRC0	CHR3	CHR2	CHR1	CHR0	BIP8
Reset		1	0	0	1	1	1	1	0

DBL: Crystal frequency doubler selection. Recommend DBL = [1]
[0]: Disable. $F_{XREF} = F_{XTAL}$. **[1]:** Enable. $F_{XREF} = 2 * F_{XTAL}$.

RRC [1:0]: RF PLL reference counter setting.

CHR [3:0]: PLL channel step setting.

Refer to chapter 14 for details.

9.2.18 PLL Register III (Address: 11h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLL III	R	IP7	IP6	IP5	IP4	IP3	IP2	IP1	IP0
	W	BIP7	BIP6	BIP5	BIP4	BIP3	BIP2	BIP1	BIP0
Reset		0	1	0	0	1	0	1	1

BIP [8:0]: LO base frequency integer part setting. Recommend BIP[8:0] = [0x04B]
BIP [8:0] are from address (0Fh) and (10h),

IP [8:0]: LO frequency integer part value.
IP [8:0] are from address (0Fh) and (10h),

Refer to chapter 14 for details.

9.2.19 PLL Register IV (Address: 12h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLL IV	R	--/FP15	AC14/FP14	AC13/FP13	AC12/P12	AC11/ FP11	AC10/FP10	AC9/FP9	AC8/FP8
	W	BFP15	BFP14	BFP13	BFP12	BFP11	BFP10	BFP9	BFP8
Reset		0	0	0	0	0	0	0	0

9.2.20 PLL Register V   (Address: 13h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLL V	R	AC7/FP7	AC6/FP6	AC5/FP5	AC4/FP4	AC3/FP3	AC2/FP2	AC1/FP1	AC0/FP0
	W	BFP7	BFP6	BFP5	BFP4	BFP3	BFP2	BFP1	BFP0
Reset		0	0	0	0	0	0	1	1

BFP [15:0]: LO base frequency fractional part setting. Recommend BFP[15:0] = [0x0002]
BFP [15:0] are from address (11h) and (12h),

AC [14:0] (Read): Auto Frequency compensation value (if FC (18h) =1).

FP [15:0] (Read): LO frequency fractional part setting.

Refer to chapter 14 for details.

9.2.21 TX Register I (Address: 14h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
TX I	W	TXSM1	TXSM0	TXDI	TME	FS	FDP2	FDP1	FDP0
Reset		0	0	0	1	0	1	1	0

TXSM [1:0]: Moving average for non-filter select. Recommend TXSM = [00]
[00]: not average. **[01]:** 2 bit average. **[10]:** 4 bit average. **[11]:** 8 bit average

TXDI: TX data invert. Recommend TXDI = [0].
[0]: Non-invert. **[1]:** Invert.

TME: TX modulation enable.
[0]: Disable. **[1]:** Enable.

FS: Filter select. Recommend FS = [0]
Gaussian filter (BT=0.7).
[0]: disable. **[1]:** enable.

FDP [2:0]: Frequency deviation power setting. Refer to control register (15h). Recommend FDP = [110].

9.2.22 TX Register II (Address: 15h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
TX II	W	--	PDV1	PDV0	FD4	FD3	FD2	FD1	FD0
Reset		--	0	0	0	1	0	1	1

PDV [1:0]: Reserved for internal usage only. Shall be set to [01].
FD [4:0]: Frequency deviation setting.
$F_{DEV} = F_{PFD} \times 127 \times (FD[4:0] + 1) \times 2^{(FDP[2:0])} / 2^{24}$.
Where $F_{PFD} = F_{XTAL} \times (DBL+1) / (RRC[1:0]+1)$, PLL comparison frequency.

Data Rate (КБит/с)	F_{PFD}	FDP [2:0]	PDV [1:0]	FD[4:0]	Fdev (КГц)
<= 50КБит/с	12MHz	110b	01b	10110b (0x16)	122
	16MHz			01111b (0x0F)	124
	24MHz			01010b (0x0A)	127
	32MHz			00111b (0x07)	124
Data Rate (КБит/с)	F_{PFD}	FDP [2:0]	PDV [1:0]	FD[4:0]	Fdev (КГц)
> 50КБит/с	16MHz	110b	01b	10111b (0x17)	186
	24MHz			01111b (0x0F)	
	32MHz			01011b (0x0B)	

9.2.23 Delay Register I (Address: 16h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Delay	W	DPR2	DPR1	DPR0	TDL1	TDL0	PDL2	PDL1	PDL0
Reset		0	0	0	1	0	0	1	0

DPR [2:0]: Delay scale. Recommend DPR = [000].

TDL [1:0]: Delay for TX settling from WPLL to TX.
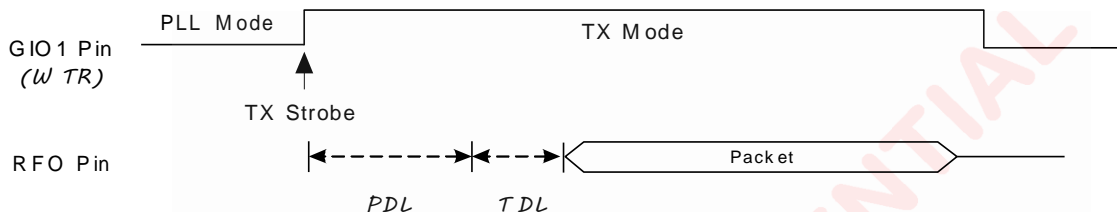Delay= 20 * (TDL [1:0]+1)*(DPR [2:0]+1) us.

DPR [2:0]	TDL [1:0]	WPLL to TX	Note
000	00	20 us	
000	01	40 us	
000	10	60 us	**Recommend**
000	11	80 us	

PDL [2:0]: Delay for TX settling from PLL to WPLL.
Delay= 10+20 * (PDL [2:0]+1)*(DPR [2:0]+1) us.

DPR [2:0]	PDL [2:0]	PLL to WPLL (LO freq. fixed)	PLL to WPLL (LO freq changed)	Note
000	001	10 us	50 us	
000	010	10 us	70 us	**Recommend**
000	011	10 us	90 us	
000	100	10 us	110 us	

9.2.24 Delay Register II (Address: 17h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Delay	W	WSEL2	WSEL1	WSEL0	AGC_D1	AGC_D0	RS_DLY2	RS_DLY1	RS_DLY0
Reset		0	1	0	0	0	0	0	1

WSEL [2:0]: XTAL settling delay setting (200us ~ 2.5ms). Recommend WSEL = [010].
[000]: 200us. **[001]:** 400us. **[010]:** 600us. **[011]:** 800us.
[100]: 1ms. **[101]:** 1.5ms. **[110]:** 2ms. **[111]:** 2.5ms.
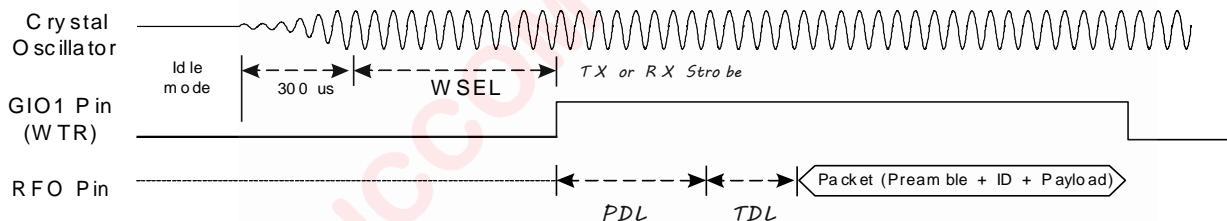
AGC_D [1:0]: AGC delay settling Recommend AGC_D[1:0] = [00].
[00]: 10us. **[01]:** 20us. **[10]:** 30us. **[11]:** 40us.

RS_DLY [2:0]: RSSI measurement delay (10us ~ 80us)· Recommend RS_DLY =
[000].[000]: 10us. **[001]:** 20us. **[010]:** 30us. **[011]:** 40us.
[100]: 50us. **[101]:** 60us. **[110]:** 70us. **[111]:** 80us.

9.2.25 RX Register (Address: 18h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
RX	W	--	RXSM1	RXSM0	FC	RXDI	DMG	BWS	ULS
Reset		--	1	0	0	0	0	1	0

RXSM0: Reserved for internal usage only. Shall be set to [1].

RXSM1: Reserved for internal usage only. Shall be set to [1].

FC: Frequency compensation select.

[0]: Disalbe . **[1]:** Enable.
Refer to section 14.4 for details.

RXDI: RX data output invert. Recommend RXDI = [0].
[0]: Non-inverted output. **[1]:** Inverted output.

DMG: Reserved for internal usage only. Shall be set to [0].

BWS: BPF bandwidth select. Recommend BWS = [1].
[0]: 250КГц. **[1]:** 500КГц.

Data Rate (КБит/с)	BWS	Note
2~ 500	1	F_{IF}= 500КГц

ULS: RX Up/Low side band select.
[0]: Up side band, **[1]:** Low side band.
Refer to section 14.2 for details.

9.2.26 RX Gain Register I (Address: 19h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
RX Gain I	R/W	MVGS	--	IGC	MGC1	MGC0	LGC2	LGC1	LGC0
Reset		0	--	1	0	0	0	0	0

MVGS: MAnual VGA calibrate. Recommend MVGS =
[1].[0]: Auto. **[1]:** MAnual

IGC: Reserved for internal usage only. Shall be set to [0].

MGS [1:0]: Mixer gain. Recommend MGS = [00].
[00]: 24dB. **[01]:** 18dB. **[10]:** 12dB. **[11]:** 6dB.

LGS [2:0]: LNA gain. Recommend LGS = [000].
[000]: 24dB. **[001]:** 18dB. **[010]:** 12dB. **[011]:** 6dB. **[1XX]:** 0dB.

9.2.27 RX Gain Register II (Address: 1Ah)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
RX Gain II	R/W	RH7	RH6	RH5	RH4	RH3	RH2	RH1	RH0
Reset		0	0	0	0	1	0	1	0

RH [7:0]: Reserved for internal usage only.

9.2.28 RX Gain Register III (Address: 1Bh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
RX Gain III	W	RL7	RL6	RL5	RL4	RL3	RL2	RL1	RL0
Reset		1	0	1	1	0	1	0	0

RL [7:0]: Reserved for internal usage only.

9.2.29 RX Gain Register IV (Address: 1Ch)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
RX Gain III	W	ENGC				MHC	LHC1	LHC0	VGCE
Reset		1				1	1	1	0

ENGC: Reserved for internal usage only. Shall be set to [0]

MHC: Reserved for internal usage only. Shall be set to [1].

LHC: Reserved for internal usage only. Shall be set to [01].

VGCE: Reserved for internal usage only. Shall be set to [0]

9.2.30 RSSI Threshold Register (Address: 1Dh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
RSSI Threshold	R	ADC7	ADC6	ADC5	ADC4	ADC3	ADC2	ADC1	ADC0
	W	RTH7	RTH6	RTH5	RTH4	RTH3	RTH2	RTH1	RTH0
Reset		1	0	0	1	0	0	0	1

RTH [7:0]: Carrier detect threshold.
Refer to Chapter 17 for details.

ADC [7:0]: ADC output value for RSSI measurement.
ADC input voltage= 1.2 * ADC [7:0] / 256 V.
Refer to chapter 17 for details.

9.2.31 ADC Control Register (Address: 1Eh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
ADC Control	W	RSM1	RSM0	ERSS	FSARS	--	XADS	RSS	CDM
Reset		0	1	0	1	--	0	1	1

RSM [1:0]: RSSI мArgin = RTH – RTL. Recommend RSM = [11].
[00]: 5. **[01]:** 10. **[10]:** 15. **[11]:** 20.
Refer to Chapter 17 for details.

ERSS: End for RSSI measurement
[0] : RSSI measurement continues until leave off RX mode.
[1] : RSSI measurement will end when carrier detected and ID code word received.

FSARS: ADC clock select. Recommend FSARS = [0].
[0]: 4MHz. **[1]:** 8MHz.

XADS: ADC input signal select.
[0]: Convert RSS signal. **[1]:** Reserved for internal usage.

RSS: RSSI measurement select.
[0]: Reserved for internal usage. **[1]:** RSSI or carrier-detect measurement.

CDM: RSSI measurement mode.
[0]: Single mode. **[1]:** Continuous mode.

9.2.32 Code Register I (Address: 1Fh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Code I	W	--	MCS	WHTS	FECS	CRCS	IDL	PML1	PML0
Reset		--	0	0	0	0	1	1	1

WHTS: Data whitening (Data Encryption) select.
[0]: Disable. **[1]:** Enable.

FECS: FEC select.
[0]: Disable. **[1]:** Enable.

CRCS: CRC select.
[0]: Disable. **[1]:** Enable.

IDL: ID code length select. Recommend IDL= [1].
[0]: 2 bytes. **[1]:** 4 bytes.

PML [1:0]: Preamble length select. Recommend PML= [11].
[00]: 1 byte. **[01]:** 2 bytes. **[10]:** 3 bytes. **[11]:** 4 bytes.
Refer to chapter 16 for details.

9.2.33 Code Register II (Address: 20h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Code II	W	--	DCL2	DCL1	DCL0	ETH1	ETH0	PMD1	PMD0
Reset		--	1	1	1	0	1	1	1

DCL [2:0]: Demodulator DC estimAtion average mode. Recommend DCL[2:0] = [001]

ETH [1:0]: ID code error tolerance. Recommend ETH = [01].
[00]: 0 bit, **[01]:** 1 bit. **[10]:** 2 bits. **[11]:** 3 bits.

PMD [1:0]: Preamble pattern detection length.
[00]: 0bit. **[01]:** 4bits. **[10]:** 8bits. **[11]:** 16bits.

Data Rate (КБит/с)	PMD[1:0]	Note
2 ~ 125	11	Also refer to addr. 29h
250 / 500	10	

Refer to chapter 16 for details.

9.2.34 Code Register III (Address: 21h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Code III	W	--	WS6	WS5	WS4	WS3	WS2	WS1	WS0
Reset		--	0	1	0	1	0	1	0

WS [6:0]: Data Whitening seed setting (data encryption key).
Refer to chapter 16 for details.

9.2.35 IF Calibration Register I (Address: 22h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
IF Calibration I	R				FBCF	FB3	FB2	FB1	FB0
	W	--	--	--	MFBS	MFB3	MFB2	MFB1	MFB0
Reset		--	--	--	0	0	1	1	0

MFBS: IF filter calibration value select. Recommend MFBS = [0].
[0]: Auto calibration value. **[1]:** MAnual calibration value.

MFB [3:0]: IF filter мAnual calibration value.

FBCF: IF filter auto calibration flag.
[0]: Pass. **[1]:** Fail.

FB [3:0]: IF filter calibration value.
MFBS= 0: Auto calibration value (AFB),
MFBS= 1: MAnual calibration value (MFB).

Refer to chapter 15 for details.

9.2.36 IF Calibration Register II (Address: 23h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
IF Calibration II	R	--	--		FCD4	FCD3	FCD2	FCD1	FCD0
Reset		--	--	--	--	--	--	--	--

FCD [4:0]: IF filter calibration deviation from goal (Read only).

9.2.37 VCO current Calibration Register (Address: 24h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
VCO current	R				FVCC	VCB3	VCB2	VCB1	VCB0
Calibration	W	--	--	VCCS	MVCS	VCOC3	VCOC2	VCOC1	VCOC0

		Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Reset		--	--	0	0	1	0	0	0

VCCS: Reserved for internal usage only. Shall be set [0].

MVCS: VCO current calibration value select. Recommend MVCS = [1].
[0]: Auto calibration value. **[1]:** MAnual calibration value.

VCOC [3:0]: VCO current мAnual calibration value. Recommend VCOC = [011].

FVCC: VCO current auto calibration flag.
[0]: Pass. **[1]:** Fail.

VCB [3:0]: VCO current calibration value.
MVCS= 0: Auto calibration value (VCB).
MVCS= 1: MAnual calibration value (VCOC).

Refer to chapter 15 for details.

9.2.38 VCO Single band Calibration Register I (Address: 25h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
VCO Single band Calibration I	R	--	--	DVT1	DVT0	VBCF	VB2	VB1	VB0
	W	--	--	--	--	MVBS	MVB2	MVB1	MVB0
Reset		--	--	--	--	0	1	0	0
Reset		--	--	--	--	0	1	0	0

MVBS: VCO bank calibration value select. Recommend MVBS = [0].
[0]: Auto calibration value. **[1]:** MAnual calibration value.

MVB [2:0]: VCO band мAnual calibration value.
DVT [1:0]: digital VCO tuning voltage output.
[00]: VT<VTL<VTH. **[01]:** VTL<VT<VTH. **[10]:** No used. **[11]:** VTL<VTH<VT.

VBCF: VCO band auto calibration flag.
[0]: Pass. **[1]:** Fail.

VB [2:0]: VCO bank calibration value.
MVBS= 0: Auto calibration value (AVB).
MVBS= 1: MAnual calibration value (MVB).

Refer to chapter 15 for details.

9.2.39 VCO Single band Calibration Register II (Address: 26h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
VCO Single band Calibration II	W	--	--	VTH2	VTH1	VTH0	VTL2	VTL1	VTL0
Reset		--	--	1	1	1	0	1	1

VTH [2:0]: VCO tuning voltage upper threshold level setting. Recommend VTH = [111].
[000]: VDD_A – 0.6V. **[001]:** VDD_A – 0.7V. **[010]:** VDD_A – 0.8V. **[011]:** VDD_A – 0.9V
[100]: VDD_A – 1.0V. **[101]:** VDD_A – 1.1V. **[110]:** VDD_A – 1.2V. **[111]:** VDD_A – 1.3V

VDD_A is on chip analog regulator output voltage

VTL [2:0]: VCO tuning voltage lower threshold level setting. Recommend VTL = [011].
[000]: 0.1V. **[001]:** 0.2V. **[010]:** 0.3V. **[011]:** 0.4V.
[100]: 0.5V. **[101]:** 0.6V. **[110]:** 0.7V. **[111]:** 0.8V

9.2.40 Battery detect Register (Address: 27h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Battery detect	R	--	--	--	BDF	--	--	--	--
	W	RGS	RGV1	RGV0	--	BVT2	BVT1	BVT0	BDS

Reset		0	0	0	--	0	1	1	0

RGS: VDD_D voltage setting in Sleep mode.
[0]: 3/5 * REGI. **[1]:** 3/4 * REGI.

RGV [1:0]: VDD_D and VDD_A voltage setting in non-Sleep mode. Recommend RGV = [00].
[00]: 2.1V. **[01]:** 2.0V. **[10]:** 1.9V. **[11]:** 1.8V.

BVT [2:0]: Battery voltage detect threshold.
[000]: 2.0V. **[001]:** 2.1V. **[010]:** 2.2V. **[011]:** 2.3V.
[100]: 2.4V. **[101]:** 2.5V. **[110]:** 2.6V. **[111]:** 2.7V.

BDS: Battery detect select.
[0]: Disable. **[1]:** Enable. It will be clear after battery detection done.

BDF: Battery detection flag.
[0]: Battery voltage less than threshold. **[1]:** Battery voltage greater than threshold.

Refer to chapter 18 for details.

9.2.41 TX test Register (Address: 28h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
TX test	W	--	--	TXCS	PAC1	PAC0	TBG2	TBG1	TBG0
Reset		--	--	0	1	0	1	1	1

TXCS: TX Current Setting. [0]

PAC [1:0]: PA Current Setting. [10]

TBG [2:0]: TX Buffer Setting. [111]

Typical Output Power (dBm)	Recommend setting			Typical TX current (мА)
	TXCS	TBG	PAC	
1	0	7	3	21
0	0	7	1	19
-10	0	3	1	14
-20	0	1	0	13

Refer to chapter 19 and A7105 App. Note for more settings.

9.2.42 Rx DEM test Register I (Address: 29h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Rx DEM test I	W	DMT	DCM1	DCM0	MLP1	MLP0	SLF2	SLF1	SLF0
Reset		0	1	1	0	0	1	0	0

DMT: Reserved for internal usage only. Shall be set to [0].

DCM [1:0]: Demodulator DC estimAtion mode.
[00] : Fix mode (For testing only). DC level is set by DCV [7:0].
[01] : Preamble hold mode. DC level is preamble average value.
[10] : Average and hold mode. DC level is the average value hold about 8 bit data rate later if preamble is detected.
[11]: Payload average mode (For internal usage). DC level is payload data average.

DCM [1:0]	Data Rate (КБит/с)	DCL[2:0] (20h)	Note
01	2 ~ 125	001	By Preamble
10	250 / 500	001	By ID

MLP [1:0]: Reserved for internal usage only. Shall be set to [00].

SLF [2:0]: Reserved for internal usage only. Shall be set to [111].

9.2.43 Rx DEM test Register II (Address: 2Ah)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Rx DEM test II	W	DCV7	DCV6	DCV5	DCV4	DCV3	DCV2	DCV1	DCV0
Reset		1	0	0	0	0	0	0	0

DCV [7:0]: Demodulator fix mode DC value. Recommend DCV = [0x80].

9.2.44 Charge Pump Current Register (Address: 2Bh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Charge Pump Current	W	--	--	--	--	--	--	CPC1	CPC0
Reset		--	--	--	--	--	--	0	1

CPC [1:0]: Charge pump current setting. Recommend CPC = [11].
[00]: 0.5мА. **[01]:** 1.0мА. **[10]:** 1.5мА. **[11]:** 2.0мА

9.2.45 Crystal test Register (Address: 2Ch)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Crystal test	W	--	--	--	--	DBD	XCC	XCP1	XCP0
Reset		--	--	--	--	0	1	0	1

DBD: Reserved for internal usage only. Shall be set to [0].

XCC: Reserved for internal usage only. Shall be set to [0].

XCP [1:0]: Reserved for internal usage only. Shall be set to [01].

9.2.46 PLL test Register (Address: 2Dh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLL test	W	--	PMPE	PRRC1	PRRC0	PRIC1	PRIC0	SDPW	NSDO
Reset		--	1	1	0	1	0	0	0

PMPE: Reserved for internal usage only. Shall be set to [1].

PRRC [1:0]: Reserved for internal usage only. Shall be set to [00].

PRIC [1:0]: Reserved for internal usage only. Shall be set to [01].

SDPW: Reserved for internal usage only. Shall be set to [0].

NSDO: Reserved for internal usage only. Shall be set to [1].

9.2.47 VCO test Register I (Address: 2Eh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
VCO test I	W	--	--	--	TLB1	TLB0	RLB1	RLB0	VCBS
Reset		--	--	--	1	1	0	1	0

TLB [1:0]: Reserved for internal usage only. Shall be set to [11].

RLB [1:0]: Reserved for internal usage only. Shall be set to [00].

VCBS: Reserved for internal usage only. Shall be set to [0].

9.2.48 VCO test Register II (Address: 2Fh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
VCO test II	W	--	--	--	--	RFT3	RFT2	RFT1	RFT0
Reset		--	--	--	--	0	0	0	0

RFT [3:0]: RF analog pin configuration for testing. Recommend RFT= [0000].

9.2.49 IFAT Register (Address: 30h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
VCO test II	W	IGFI2	IGFI1	IGFI0	IGFQ2	IGFQ1	IGFQ0	IFBC	LIMC
Reset		1	0	0	1	0	0	1	1

IGFI [2:0]: Reserved for internal usage only. Shall be set to [000].

IGFQ [2:0]: Reserved for internal usage only. Shall be set to [000].

IFBC: Reserved for internal usage only. Shall be set to [0].

LIMC: Reserved for internal usage only. Shall be set to [1].

9.2.50 RScale Register (Address: 31h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Rscale	W	RSC7	RSC6	RSC5	RSC4	RSC3	RSC2	RSC1	RSC0
Reset		0	0	0	0	1	1	1	1

RSC [7:0]: Reserved for internal usage only. Shall be set to = [0x0F].

9.2.51 Filter test Register (Address: 32h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Filter test	W	FT7	FT6	FT5	FT4	FT3	FT2	FT1	FT0
Reset									

FT [7:0]: Reserved for internal usage only. Shall be set to = [0x00].

10. <u>SPI</u>

A7105 only supports one SPI interface with мAximum data rate up to 10Mbps. MCU should assert SCS pin low (SPI chip select) to active accessing of A7105. Via SPI interface, user can access **control registers** and issue **Strobe commAnd**. Figure 10.1 gives an overview of SPI access мAnners.

3-wire SPI (SCS, SCK and SDIO) or 4-wire SPI (SCS, SCK, SDIO and GIO1/GIO2) configuration is provided. For 3-wire SPI, SDIO pin is configured as bi-direction to be data input and output. For 4-wire SPI, SDIO pin is data input and GIO1 (or GIO2) pin is data output. In such case, GIO1S (0bh) or GIO2S (0ch) should be set to [0110].

For SPI write operation, SDIO pin is latched into A7105 at the rising edge of SCK. For SPI read operation, if input address is latched by A7105, data output is aligned at falling edge of SCK. Therefore, MCU can latch data output at the rising edge of SCK.

To control A7105's internal state мAchine, it is very easy to send Strobe commAnd via SPI interface. The Strobe commAnd is a unique commAnd set with total 8 commAnds. See section 10.3, 10.4 and 10.5 for details.

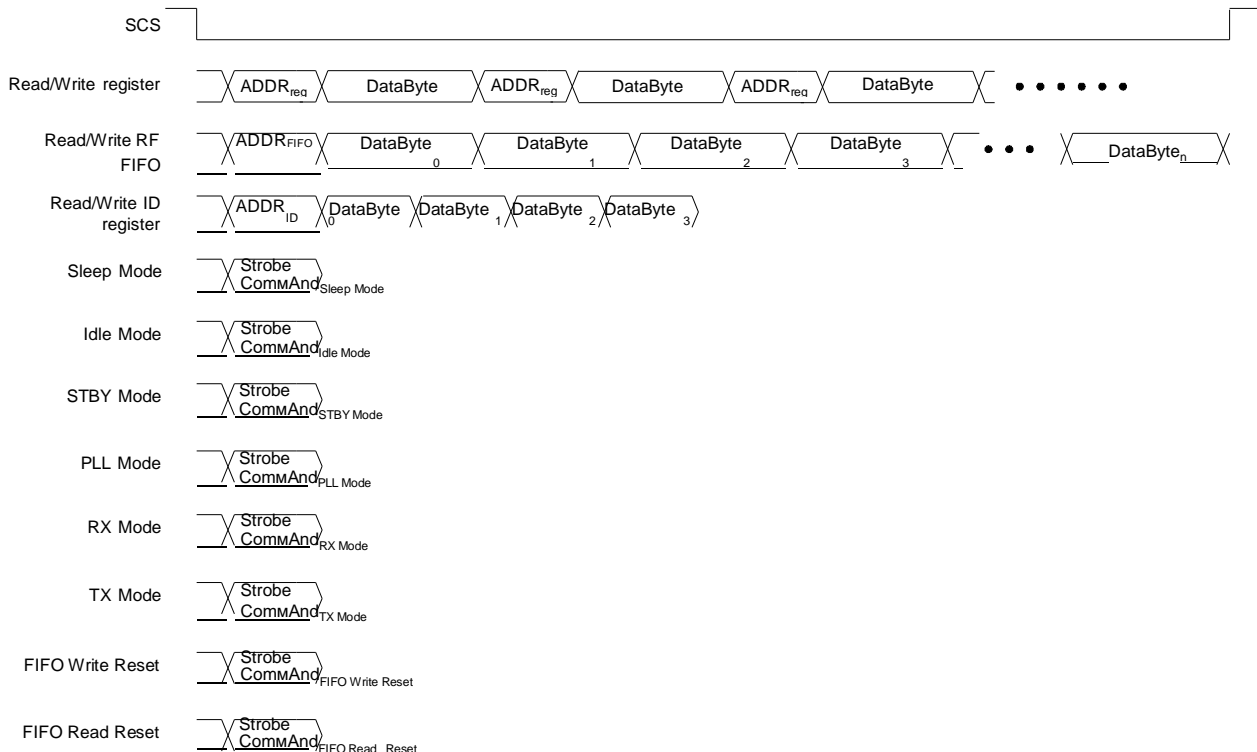|	SPI chip select	Data In	Data Out
3-Wire SPI	SCS pin = 0	SDIO pin	SDIO pin
4-Wire SPI	SCS pin = 0	SDIO pin	GIO1 (GIO1S=0110) / GIO2 (GIO2S=0110)

Figure 10.1 SPI Access MAnners

10.1 Формат SPI

Первый бит (А7) указывает для А7105 тип инструкции - "Управляющие регистры" или "Стробоскопическая команда". См. Таблицу 10.1 для формата SPI. Исходя из таблицы 10.1, для доступа к управляющим регистрам достаточно установить А7=0, затем бит А6, который используется для обозначения операции чтения (А6=1) или записи (А6=0). Подробнее см. Рис. 10.2 (3-проводный SPI) и рис. 10.3 (4-проводный SPI).

Байт адреса (8 бит)								Байт данных (8 bits)							
CMD	R/W	Адрес						Данные							
A7	A6	A5	A4	A3	A2	A1	A0	7	6	5	4	3	2	1	0

Таблица 10.1 Формат SPI

Байт адреса:

Bit 7: бит инструкции

[0] : Управляющие регистры.

[1] : Стробоскопическая команда.

Bit 6: R/W бит

[0]: Запись данных в управляющий регистр. [1]: Чтение данных из управляющего регистра.

Bit [5:0]: Address of control register

Байт данных:

Bit [7:0]: Входные или выходные данные SPI см. рис. 10.2 и рис. 10.3 для получения более подробной информации.

10.2 Временные характеристики SPI

Независимо от того, настроен ли 3-проводной или 4-проводной интерфейс SPI, максимальная скорость передачи данных SPI составляет 10 Мбит/с. Для активации интерфейса SPI вывод CS должен быть установлен в низкий уровень. Для правильной фиксации данных пользователь должен позаботиться о времени удержания и времени настройки между SCK и SDIO. См. Таблицу 10.2 Временные характеристики SPI.
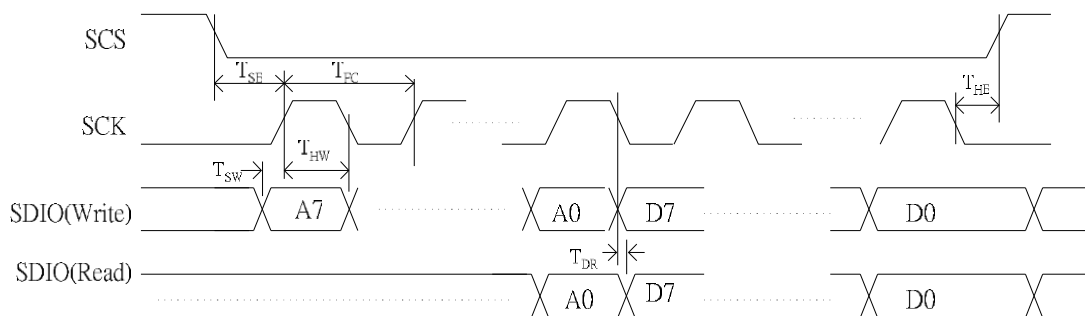
Параметр	Описаное	Мин.	Макс.	Единица измерения
F$_C$	Тактовая частота FIFO.		10	MHz
T$_{SE}$	Время установки активности.	50		ns
T$_{HE}$	Время установки неактивности.	50		ns
T$_{SW}$	TX Время настройки данных.	50		ns
T$_{HW}$	TX Время удержания данных.	50		ns
T$_{DR}$	RX Время задержки данных.	0	50	ns

Табл. 10.2 Временные характеристики SPI

10.3 Временные диаграммы SPI

В этом разделе описаны диаграммы чтения/записи 3-проводного и 4-проводного интерфейса SPI.

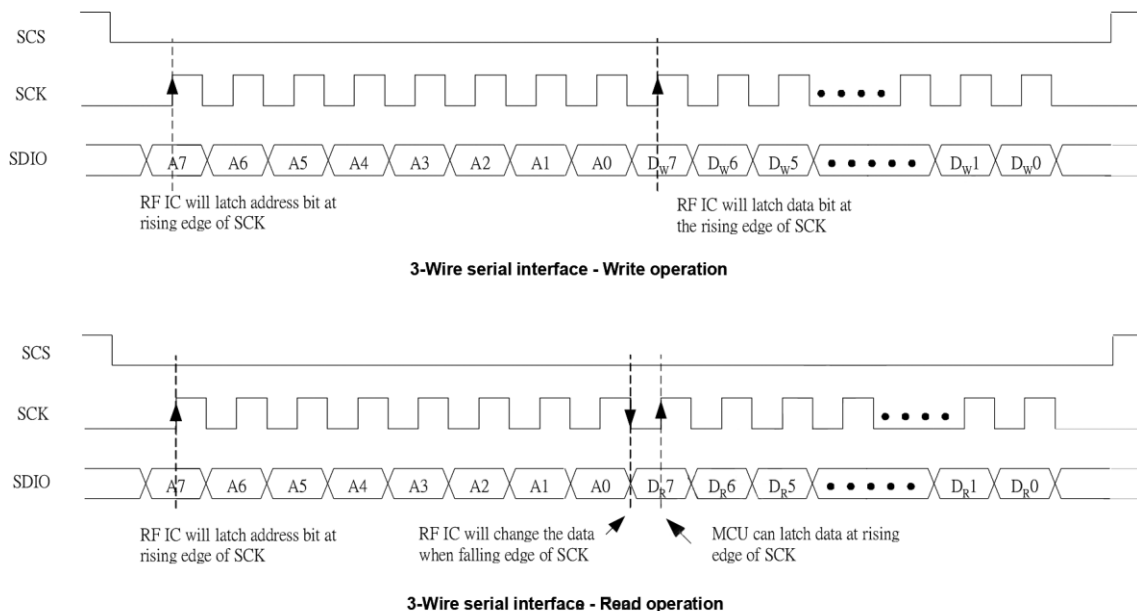### 10.1.1 Временные диаграммы 3-проводного SPI

Рис. 10.2 Диаграмма Чтение/Запись 3-проводного SPI
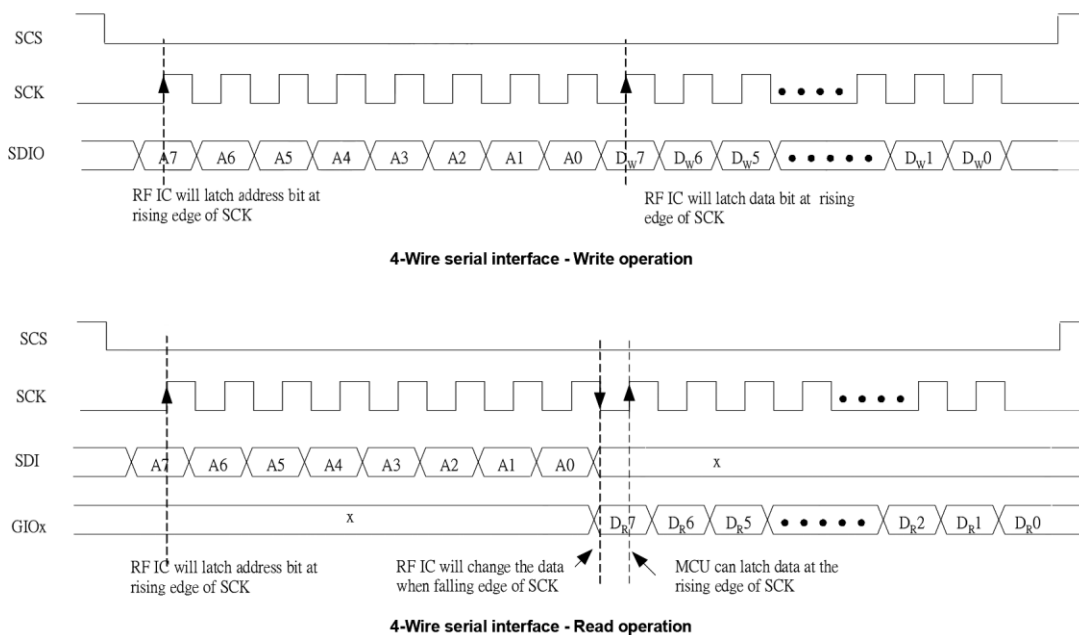
10.1.2 Временные диаграммы 4-проводного SPI

Рис. 10.3 Диаграмма Чтение/Запись 4-проводного SPI

10.2 Стробоскопические команды

A7105 поддерживает 8 строб-команд для управления внутренними настройками чипа. Таблица 10.3 отображает их.

Обратите внимание, что строб может быть 4-битный или 8-битный (A7~A0). Если 8-битный, то последние 4 бита (A3~A0) учитываться не будут. В таком случае, вывод SCS может оставаться низким для принятия следующих команд.

Стробоскопические команды

Строб-команды								Описание
A7	A6	A5	A4	A3	A2	A1	A0	
1	0	0	0	x	X	x	x	Sleep mode (Спящий режим)
1	0	0	1	x	X	x	x	Idle mode (Режим простоя)
1	0	1	0	x	X	x	x	Standby mode (Дежурный режим)
1	0	1	1	x	X	x	x	PLL mode (Фазовая автоподстройка частоты)
1	1	0	0	x	X	x	x	RX mode (Режим приемника)
1	1	0	1	x	X	x	x	TX mode (Режим передатчика)
1	1	1	0	x	X	x	x	FIFO write pointer reset
1	1	1	1	x	X	x	x	FIFO read pointer reset

Табл. 10.3 Стробоскопические команды по интерфейсу SPI

10.2.1 Строб-команда - Sleep Mode (Спящий режим)

Ссылаясь на таблицу 10.3, пользователь может отправить 4 битный (1000) строб, который устанавливает A7105 в режим сна. Ниже приведены сводная таблица и временная диаграмма.

Стробоскопические команды

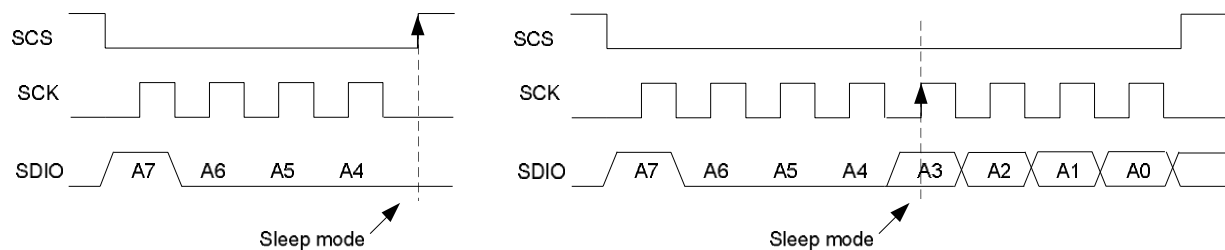| Строб-команды								Описание
A7	A6	A5	A4	A3	A2	A1	A0	
1	0	0	0	x	X	x	x	Sleep mode (Спящий режим)

Рис. 10.4 Диаграмма команды спящего режима

10.2.2 Строб-команда - Idle Mode

Ссылаясь на таблицу 10.3, пользователь может отправить 4 битный (1001) строб, который устанавливает A7105 в режим простоя. Ниже приведены сводная таблица и временная диаграмма.

Стробоскопические команды

Строб-команды	Описание

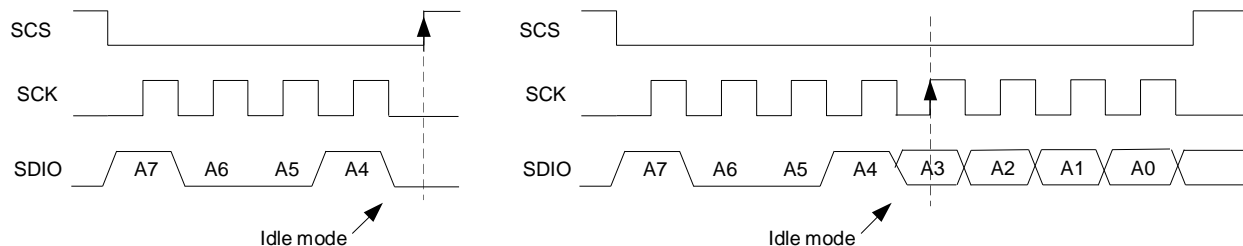| A7	A6	A5	A4	A3	A2	A1	A0	
1	0	0	1	x	X	x	x	Idle mode (Режим простоя)

Рис. 10.5 Диаграмма команды режима простоя

10.2.3 Строб-команда - Standby Mode

Ссылаясь на таблицу 10.3, пользователь может отправить 4 битный (1010) строб, который устанавливает A7105 в дежурный режим. Ниже приведены сводная таблица и временная диаграмма.

Стробоскопические команды

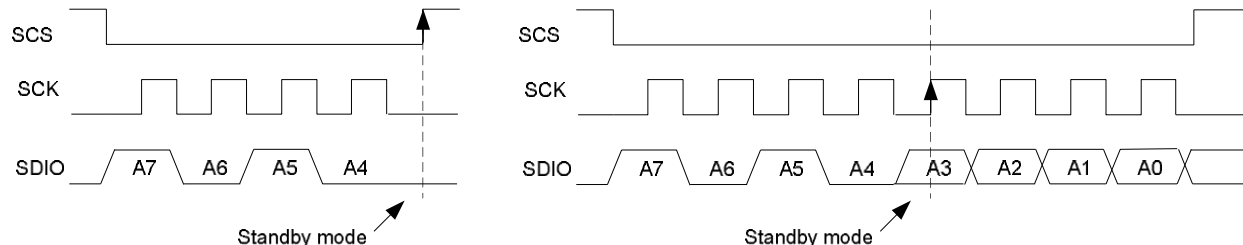| Строб-команды								Описание
A7	A6	A5	A4	A3	A2	A1	A0	
1	0	1	0	x	X	x	x	Standby mode (Дежурный режим)

Рис. 10.6 Диаграмма команды дежурного режима

10.2.4 Строб-команда - PLL Mode

Ссылаясь на таблицу 10.3, пользователь может отправить 4 битный (1011) строб, который устанавливает A7105 в режим фазовой автоподстройки частоты. Ниже приведены сводная таблица и временная диаграмма.

Стробоскопические команды

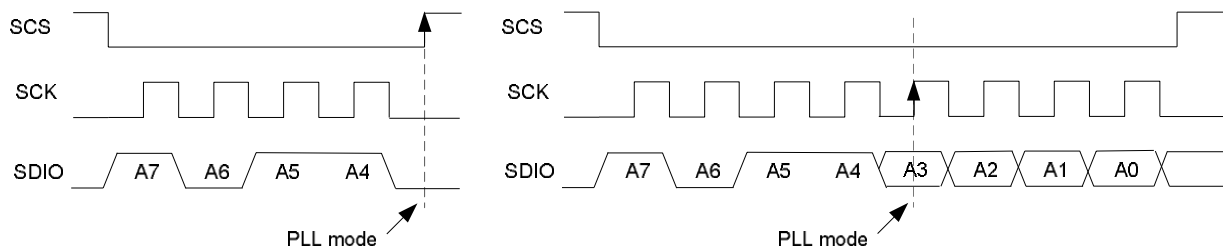| Строб-команды								Описание
A7	A6	A5	A4	A3	A2	A1	A0	
1	0	1	1	x	X	x	x	PLL mode (Фазовая автоподстройка частоты)

Рис. 10.7 Диаграмма команды фазовой автоподстройки частоты

10.2.5 Строб-команда - RX Mode

Ссылаясь на таблицу 10.3, пользователь может отправить 4 битный (1100) строб, который устанавливает A7105 в режим приемника. Ниже приведены сводная таблица и временная диаграмма.

Стробоскопические команды

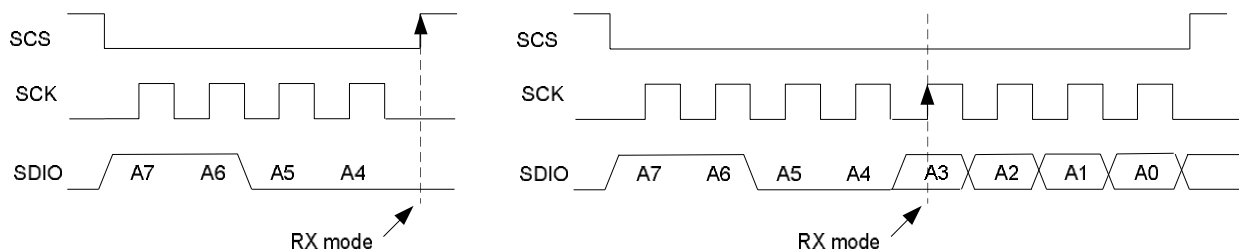| Строб-команды								Описание
A7	A6	A5	A4	A3	A2	A1	A0	
1	1	0	0	x	X	x	x	RX mode (Режим приемника)

Рис. 10.8 Диаграмма команды режима приемника

10.2.6 Строб-команда - TX Mode

Ссылаясь на таблицу 10.3, пользователь может отправить 4 битный (1101) строб, который устанавливает A7105 в режим передатчика. Ниже приведены сводная таблица и временная диаграмма.

Стробоскопические команды

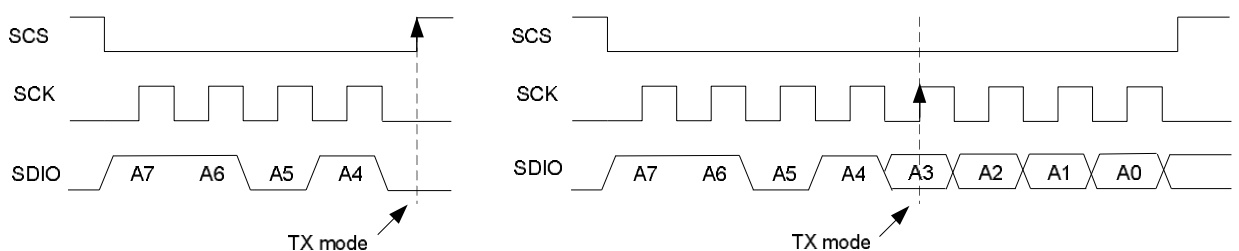| Строб-команды								Описание
A7	A6	A5	A4	A3	A2	A1	A0	
1	1	0	1	x	x	x	x	TX mode (Режим передатчика)

Рис. 10.9 Диаграмма команды режима передатчика

10.2.7 Строб-команда – FIFO Write Pointer Reset

Ссылаясь на таблицу 10.3, пользователь может отправить 4 битный (1110) строб, который устанавливает А7105 в режим FIFO Write Pointer Reset. Ниже приведены сводная таблица и временная диаграмма.

Стробоскопические команды

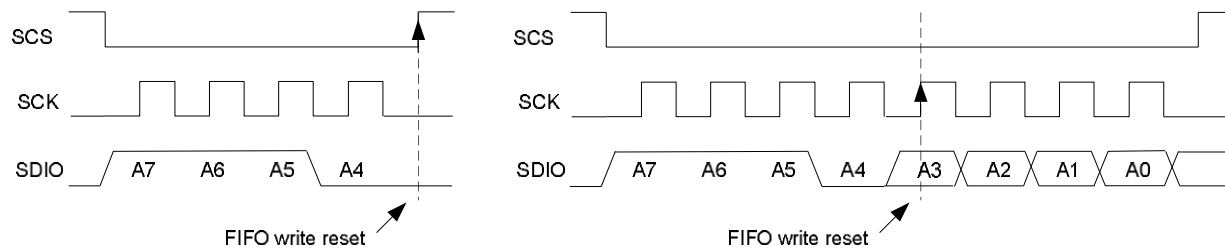| Строб-команды								Описание
A7	A6	A5	A4	A3	A2	A1	A0	
1	1	1	0	x	x	x	x	FIFO write pointer reset

Рис. 10.10 Диаграмма команды FIFO write pointer reset

10.2.8 Строб-команда – FIFO Read Pointer Reset

Ссылаясь на таблицу 10.3, пользователь может отправить 4 битный (1111) строб, который устанавливает А7105 в режим FIFO Read Pointer Reset. Ниже приведены сводная таблица и временная диаграмма.

Стробоскопические команды

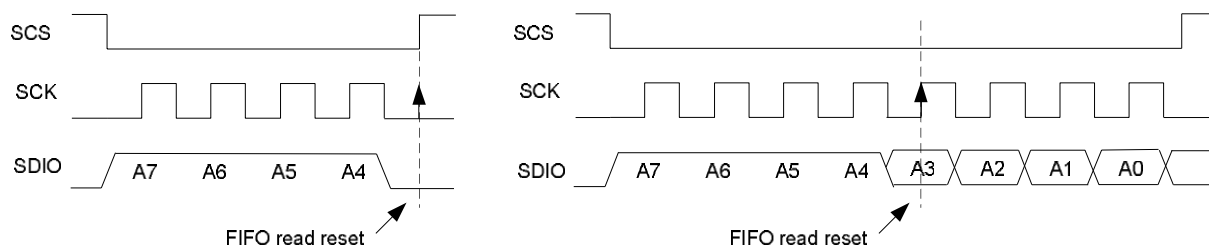| Строб-команды								Описание
A7	A6	A5	A4	A3	A2	A1	A0	
1	1	1	1	x	x	x	x	FIFO read pointer reset

Рис. 10.11 Диаграмма команды FIFO read pointer reset

10.3 Команда сброса

В дополнение к сбросу питания (POR) MCU может выполнить программный сброс А7105, установив регистр (00h) через интерфейс SPI, как показано ниже. До тех пор, пока 8-битный адрес (A7~A0) равен нулю, и данные (D7~D0) равны нулю, А7105 получает информацию для генерации внутреннего сигнала "RESETN" для инициализации самого себя. После команды сброса А7105 находится в режиме ожидания (standby mode), и процедура калибровки должна быть выполнена снова.
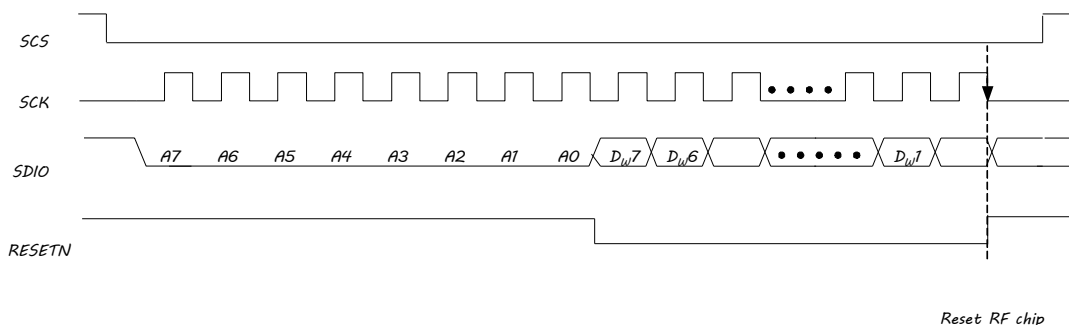
Рис 10.12 Диаграмма команды Сброса

10.4 Команды доступа к ID

A7105 имеет встроенный 32-битный идентификационный регистр для индивидуального идентификатора. Доступ к нему осуществляется через интерфейс SPI. Длину идентификатора рекомендуется оставлять 32 бита, установив IDL (регистр 1Fh). Пользователь может переключить вывод SCS на высокий, чтобы завершить команду доступа к ID, когда данные ID полностью переданы.

На рис.10.13 и 10.14 представлены временные диаграммы обращения к 32-битному ID через 3-проводный SPI.

10.4.1 Команда записи ID

Пользователь может подробно ознакомиться с временной диаграммой записи SPI на рис.10.2. Ниже приведена процедура выполнения команды записи ID.

Шаг 1: Передайте A7~A0 = 00000110 (A6=0 для записи, A5~A0 = 000110 регистр ID DATA, 06h).
Шаг 2: Через вывод SDIO передайте 32-битный идентификатор в A7105 в последовательности байтов данных 0 **(рекомендуется 5xh или Axh)**, 1, 2 и 3.
Шаг 3: Переключите вывод SCS на высокий уровень, когда шаг 2 будет завершен.

Рис.10.13 Временная диаграмма команды записи идентификатора

10.4.2 Команда чтения ID

Пользователь может подробно ознакомиться с временной диаграммой записи SPI на рис.10.2. Ниже приведена процедура выполнения команды чтения ID.

Шаг 1: Передайте A7~A0 = 01000110 (A6=1 для чтения, A5~A0 = 000110 регистр ID DATA, 06h).
Шаг 2: Вывод SDIO выводит 32-битный идентификатор в последовательности байтов данных 0, 1, 2 и 3.
Шаг 3: Переключите вывод SCS на высокий уровень, когда шаг 2 будет завершен.

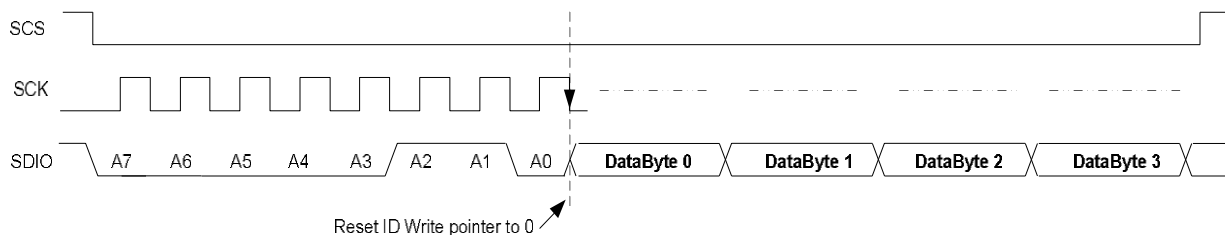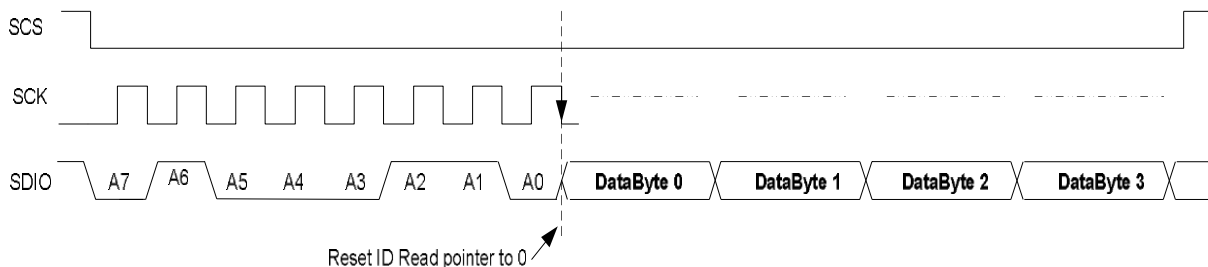Рис.10.14 Временная диаграмма команды чтения идентификатора

10.5 Команды доступа к FIFO

To use A7105's FIFO mode, enable FMS (01h) =1 via SPI interface. Before TX delivery, just write wanted data into TX FIFO (05h) then issue TX Strobe commAnd. Similarly, user can read RX FIFO (05h) once payload data is received.

MCU can use polling or interrupt scheme to do FIFO accessing. FIFO status can output to GIO1 (or GIO2) pin by setting GIO1S (0Bh) or GIO2S (0Ch).

Figure 10.15 and 10.16 are timing charts of FIFO accessing via 3-wire SPI.

10.5.1 Команда записи TX FIFO

Пользователь может подробно ознакомиться с временной диаграммой записи SPI на рис.10.2. Ниже приведена процедура записи TX FIFO.

Шаг 1: Поставьте A7~A0 = 00000101 (A6=0 управляющий регистр для записи FIFO по адресу 05h).
Шаг 2: С помощью вывода SDIO отправьте (n+1) байтов данных TX в TX FIFO последовательно байтами данных от 0, 1, 2 до n.
Шаг 3: Переключите вывод SCS на высокий уровень, когда шаг 2 будет завершен.
Шаг 4: Отправьте стробоскопическую команду режима TX (рис. 10.9), чтобы выполнить отправку TX.
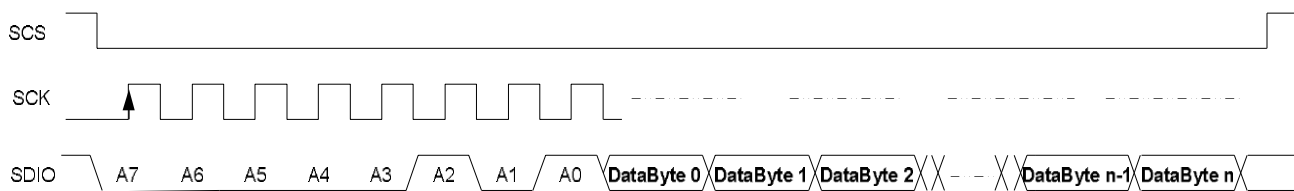
Рис 10.15 Временная диаграмма записи TX FIFO

10.5.2 Команда чтения Rx FIFO

Пользователь может подробно ознакомиться с временной диаграммой чтения SPI на рис.10.2. Ниже приведена процедура чтения RX FIFO.

Шаг 1: Поставьте A7~A0 = 01000101 (A6=1 управляющий регистр для чтения FIFO по адресу 05h).
Шаг 2: Вывод SDIO выводит данные RX из RX FIFO последовательно по байтам данных от 0, 1, 2 до n.
Шаг 3: Переключите вывод SCS на высокий уровень, когда RX FIFO будет полностью считан.
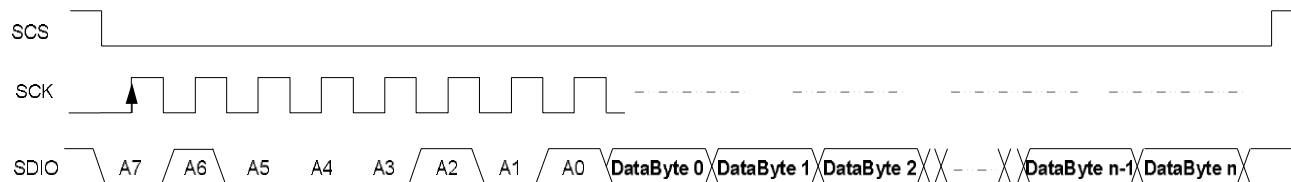
Рис. 10.16 Временная диаграмма чтения RX FIFO

11. <u>State мAchine</u>

In chapter 9 and chapter 10, user can not only learn A7105's control registers but also know how to issue Strobe commAnd. From section 10.2 ~ 10.6, it is clear to know configurations of 3-wire SPI and 4-wire SPI, Strobe commAnd, software reset, and how to access ID Registers as well as TX/RX FIFO.

Section 11.1 introduces 7 states of built-in state мAchine. Combined with Strobe commAnd and accessing control registers, section 11.2, 11.3 and 11.4 demonstrate 3 state diagrams to explain how transitions of A7105's operation.

From accessing data point of view, if FMS=1 (01h), FIFO mode is enabled, otherwise, A7105 is in direct mode. If FMS=1 and FIFO Read/Write in Standby mode, we call it NormAl FIFO mode. Otherwise, If FMS=1 and FIFO Read/Write in PLL mode, we called it Quick FIFO mode due to the time reduction of PLL settling. If FMS=1 and FIFO Read/Write in IDLE mode, we called it Power Saving FIFO mode due to the reduction of average current.

	SPI chip select	Data In	Data Out	Operation Mode	Clock Recovery for Direct Mode
3-Wire SPI	SCS pin = 0	SDIO pin	SDIO pin	FIFO (FMS=1) Direct (FMS=0)	CKO pin (CKOS = 0001)
4-Wire SPI	SCS pin = 0	SDIO pin	GIO1 (GIO1S=0110) / GIO2 (GIO2S=0110)	FIFO (FMS=1) Direct (FMS=0)	CKO pin (CKOS = 0001)

(1) NormAl FIFO Mode   (FMS=1 and FIFO R/W @ Standby mode)
(2) Quick FIFO Mode   (FMS=1 and FIFO R/W @ PLL mode)
(3) Power Saving FIFO Mode (FMS=1 and FIFO R/W @ IDLE mode)
(4) Quick Direct Mode   (FMS=0 and FIFO ignored, write packet @ TX mode, read packet @ RX mode)

11.1 Key states

A7105 supports 7 key operation states. Those are,
(1) Standby mode
(2) Sleep mode
(3) Idle mode
(4) PLL mode
(5) TX mode
(6) RX mode
(7) CAL mode

After power on reset or software reset, A7105 is in standby mode. User has to do calibration process because all control registers are in initial values. The calibration process is very easy, user only needs to issue Strobe commAnds and enable calibration registers. Then, check the calibration flag because it is done automAtic by internal state мAchine. Refer to 11.2, 11.3, 11.4 and chapter 15 for details. After calibration, A7105 is ready to do TX and RX operation.

11.1.1 Standby mode

If Standby Strobe commAnd is issued, A7105 enters standby mode automAtically. Internal power мAnagement is listed below. Be notice, A7105 is in standby mode once power on reset or software reset occurs.

Standby mode						Strobe CommAnd
On Chip Regulator	Crystal Oscillator	VCO	PLL	RX Circuitry	TX Circuitry	
ON	ON	OFF	OFF	OFF	OFF	1010xxxxb See Figure 10.6

11.1.2 Sleep mode

If Sleep Strobe commAnd is issued, A7105 enters sleep mode autoмAtically. In sleep mode, A7105 still can accept MCU's commAnds via SPI interface. But, NOT support to Read/Write FIFO. Internal power мAnagement is listed below.

Sleep mode						Strobe CommAnd
On Chip Regulator	Crystal Oscillator	VCO	PLL	RX Circuitry	TX Circuitry	
OFF	OFF	OFF	OFF	OFF	OFF	1000xxxxb See Figure 10.4

11.1.3 Idle mode

If Idle Strobe commAnd is issued, A7105 enters idle mode autoмAtically. In idle mode, A7105 can accept MCU's commAnds via SPI interface as well as supporting Read/Write FIFO. Internal power мAnagement is listed below.

Idle mode						Strobe CommAnd
On Chip Regulator	Crystal Oscillator	VCO	PLL	RX Circuitry	TX Circuitry	
ON	OFF	OFF	OFF	OFF	OFF	1001xxxxb See Figure 10.5

11.1.4 PLL mode

If PLL Strobe commAnd is issued, A7105 enters PLL mode autoмAtically. In PLL mode, internal PLL and VCO are both turned on to generate LO (local oscillator) frequency before TX and RX operation. Internal power мAnagement is listed below. According to PLL Register I, II, III, IV and V, PLL circuitry is easy to be controlled by user's definition.

PLL mode						Strobe CommAnd
On Chip Regulator	Crystal Oscillator	VCO	PLL	RX Circuitry	TX Circuitry	
ON	ON	ON	ON	OFF	OFF	1011xxxxb See Figure 10.7

11.1.5 TX mode

If TX Strobe commAnd is issued, A7105 enters TX mode autoмAtically for data delivery. Internal power мAnagement is listed below.

(1)   In FIFO mode, once TX data packet (Preamble + ID + Payload) is delivered, A7105 supports auto-back function to previous state for next delivered packet.

(2)   In Direct mode, once TX data packet is delivered, A7105 stays in TX mode. User has to issue Strobe commAnd to back to previous state.

TX mode						Strobe CommAnd
On Chip Regulator	Crystal Oscillator	VCO	PLL	RX Circuitry	TX Circuitry	
ON	ON	ON	ON	OFF	ON	(1101xxxx)b See Figure 10.9

11.1.6 RX mode

If RX Strobe commAnd is issued, A7105 enters RX mode autoмAtically for data receiving. Internal power мAnagement is listed below.

(1)   In FIFO mode, once RX data packet (Preamble + ID + Payload) is received completely, A7105 supports auto-back function to previous state for next receiving packet.

(2)   In Direct mode, once RX data packet is received, A7105 stays in RX mode. User has to issue Strobe commAnd to back to previous state.

RX mode						Strobe CommAnd
On Chip Regulator	Crystal Oscillator	VCO	PLL	RX Circuitry	TX Circuitry	
ON	ON	ON	ON	ON	OFF	(1101xxxx)b See Figure 10.9

11.1.7 CAL mode

Calibration process shall be done after power on reset or software reset. Calibration items include VCO and IF Filter. It is easy to implement calibration process by Strobe commAnd and enable CALC (02h) control register. See chapter 15 for details.

Be notice, VCO Calibration is only executable in PLL mode. However, IF Filter Calibration can be executed in Standby or PLL mode.

11.2 NorмAl FIFO Mode

This mode is suitable for requirement of general purpose applications. After calibration flow, user can issue Strobe commАnd to enter standby mode where write TX FIFO or read RX FIFO. From standby mode to packet transmission, only one Strobe commАnd is needed. Once transmission is done, A7105 is auto back to standby mode. If all packets are finished and deeper power saving is necessary, user can issue Strobe commАnd to ask A7105 staying in sleep mode. Figure 11.1 is the state diagram of NorмAl FIFO mode.

CAL CMD	CMD Value	Calibration	Section
AK	CALC.0=1,	IF Filter	15.2
	CALC.1=1,	VCO Band	15.3
	CALC.2=1,	VCO Current	15.4
Strobe	CMD Value	Note	Section
ST1	1011b	Enter to PLL	10.4.4
ST2	1010b	Enter to Standby	10.4.3
ST3	1000b	Enter to SLEEP	10.4.1
ST4	1001b	Enter to IDLE	10.4.2
ST5-TX	1101b	Enter to TX	10.4.6
ST5-RX	1100b	Enter to RX	10.4.5
RST-CMD	00000000b	Software Reset	10.5
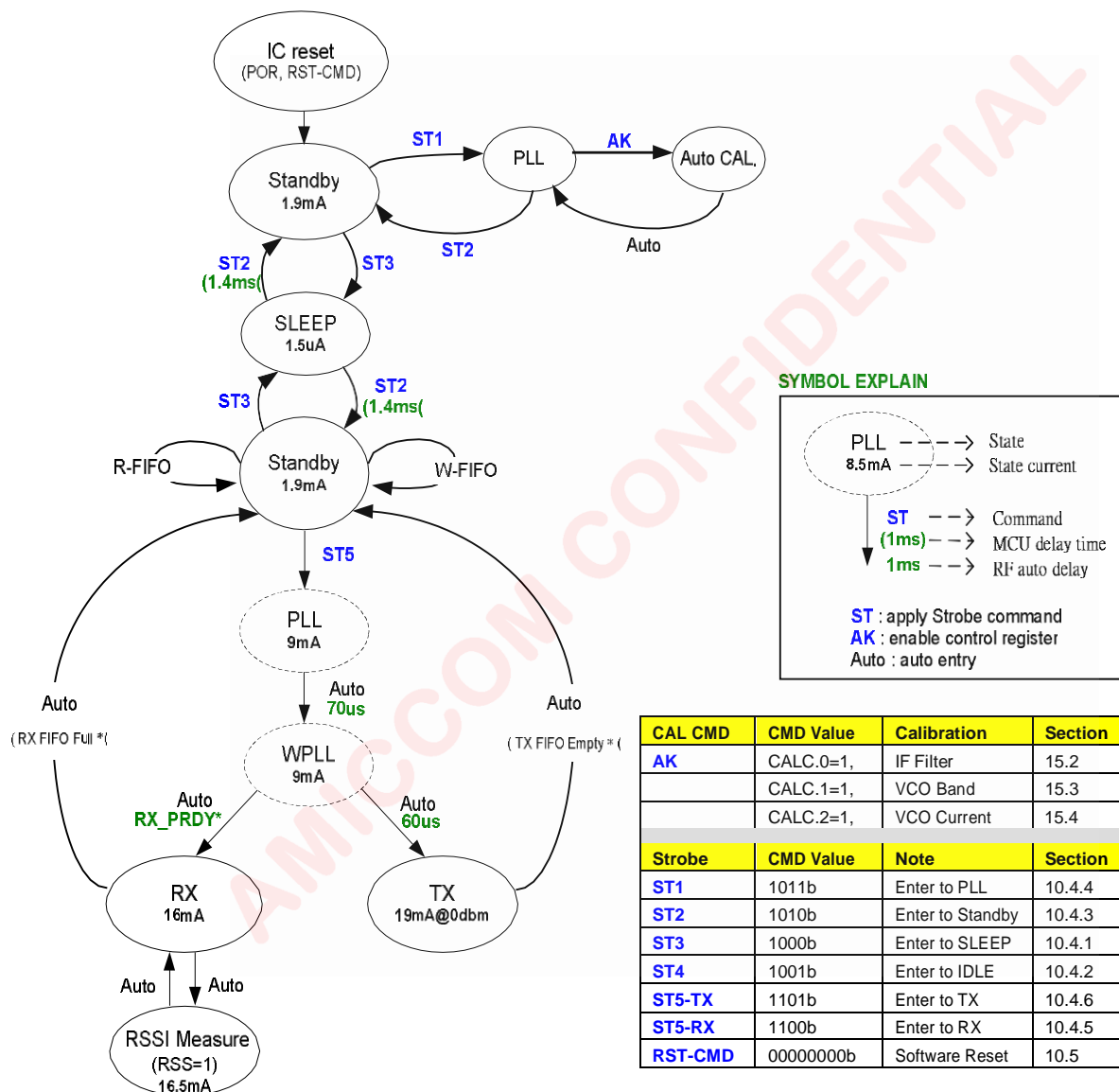
- Refer to chapter 16 for definition of RX FIFO Full and TX FIFO Empty.
- See Table 11.3 (next page) for RX-PRDY.

Figure 11.1 State diagram of NorмAl FIFO Mode

From Figure 11.1, when ST5 commAnd is issued for TX operation, see Figure 11.2 for detailed timing. A7105 status can be represented to GIO1 or GIO2 pin to MCU for timing control.

T0-T1: Auto Delay by Register setting
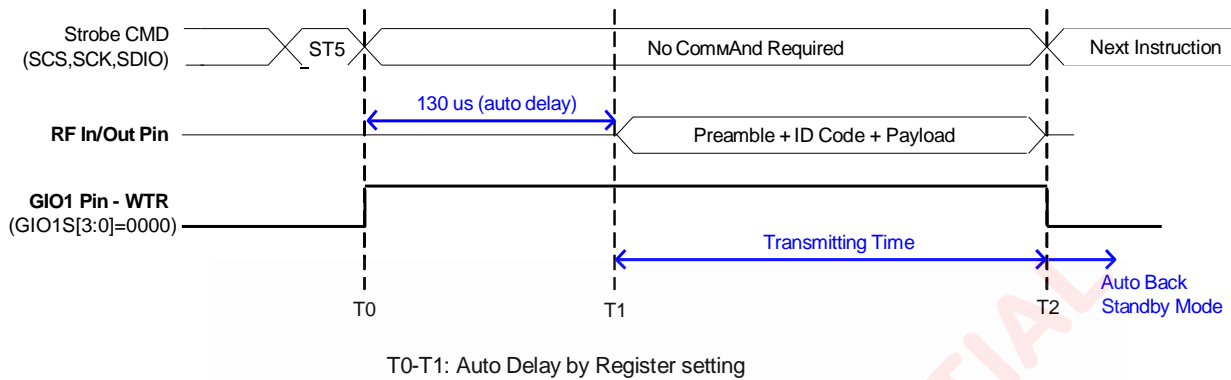
LO Freq.	Standby to WPLL	WPLL to TX	TX Ready Time
Changed	70 us	60 us	130 us
No Changed	70 us	60 us	130 us

Figure 11.2 Transmitting Timing Chart of NormAl FIFO Mode

From Figure 11.1, when ST5 commAnd is issued for RX operation, see Figure 11.3 for detailed timing. A7105 status can be represented to GIO1 or GIO2 pin to MCU for timing control.

T0-T1: Delay by MCU
T1-T2: RX is ready, Wait for valid packet
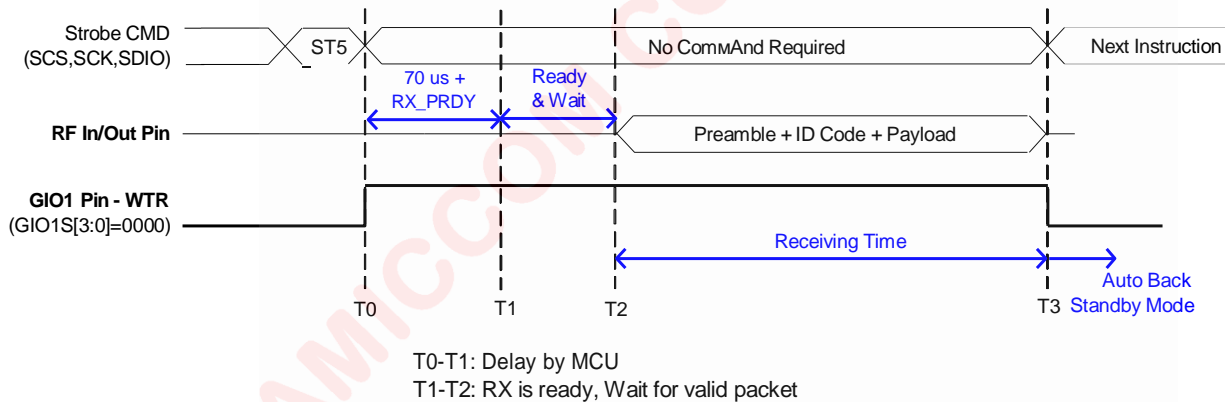
LO Freq.	Date Rate (bps)	DCM[1:0] (29h)	Standby to WPLL	WPLL to RX (RX-PRDY)	RX Ready Time (Delay by MCU)
Changed / Fixed	<=125K	By preamble (01b)	70 us	40 us	110 us
Changed /Fixed	250K	By ID (10b)	70 us	100 us	170 us
Changed / Fixed	500K	By ID (10b)	70 us	60 us	130 us

Figure 11.3 Receiving Timing Chart of NormAl FIFO Mode

11.3 Quick FIFO Mode

This mode is suitable for requirement of fast transceiving. After calibration flow, user can issue Strobe commAnd to enter PLL mode where write TX FIFO or read RX FIFO. From PLL mode to packet data transceiving, only one Strobe commAnd is needed. Once transceiving is finished, A7105 is auto back to PLL mode.

When packets are finished and deeper power saving is necessary, user can issue Strobe commAnd to ask A7105 staying in sleep mode. Figure 11.4 is the state diagram of Quick FIFO mode.


SYMBOL EXPLAIN

CAL CMD	CMD Value	Calibration	Section
AK	CALC.0=1,	IF Filter	15.2
	CALC.1=1,	VCO Band	15.3
	CALC.2=1,	VCO Current	15.4

Strobe	CMD Value	Note	Section
ST1	1011b	Enter to PLL	10.4.4
ST2	1010b	Enter to Standby	10.4.3
ST3	1000b	Enter to SLEEP	10.4.1
ST4	1001b	Enter to IDLE	10.4.2
ST5-TX	1101b	Enter to TX	10.4.6
ST5-RX	1100b	Enter to RX	10.4.5
RST-CMD	00000000b	Software Reset	10.5

- Refer to chapter 16 for definition of RX FIFO Full and TX FIFO Empty.
- See Table 11.6 (next page) for RX-PRDY.
- From PLL to WPLL, it is either 70 us (LO frequency changed) or 10 us (LO frequency NOT changed)

Figure 11.4 State diagram of Quick FIFO Mode

From Figure 11.4, when ST5 commAnd is issued for TX operation, see Figure 11.5 for detailed timing. A7105 status can be represented to GIO1 or GIO2 pin to MCU for timing control.
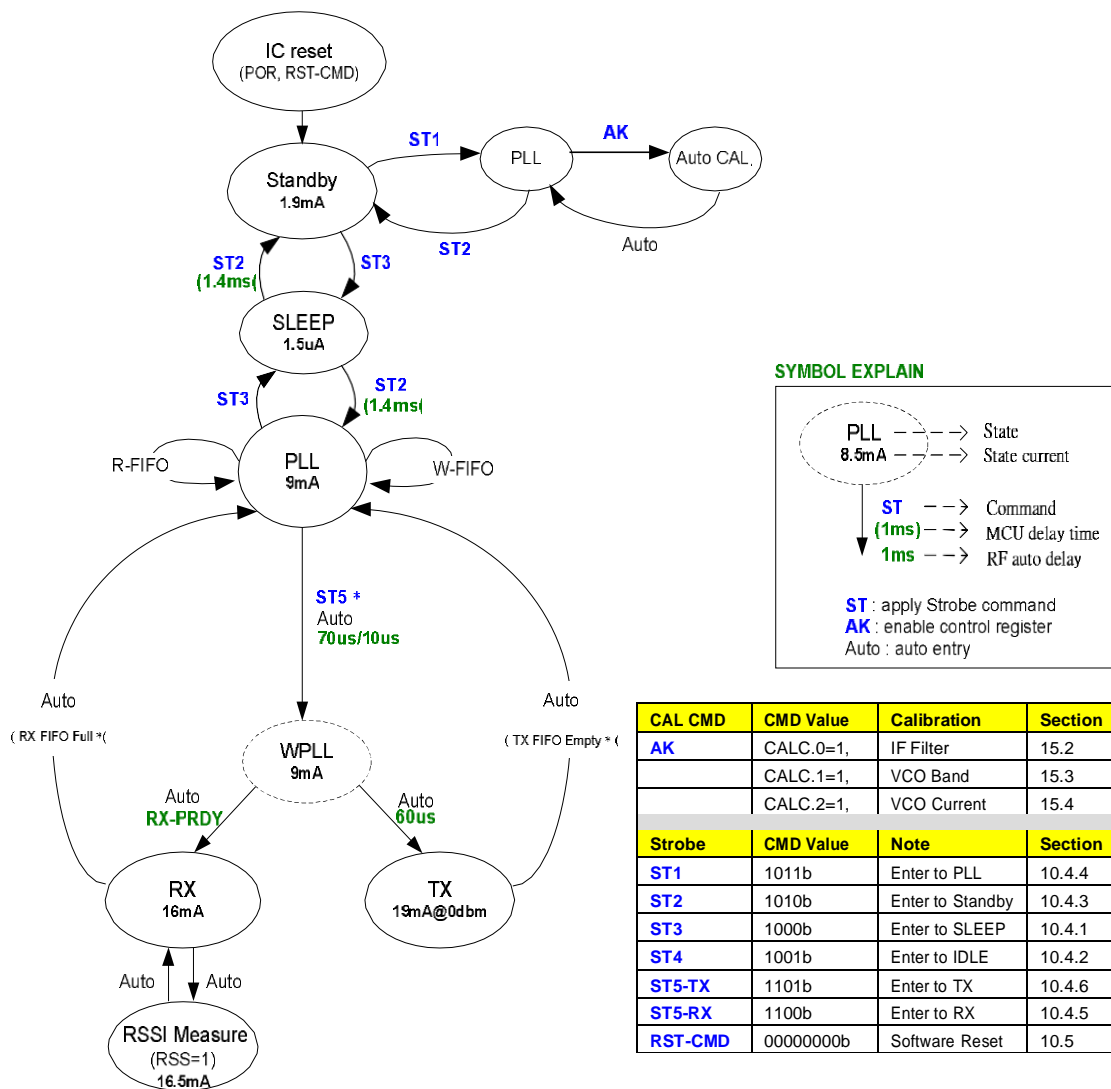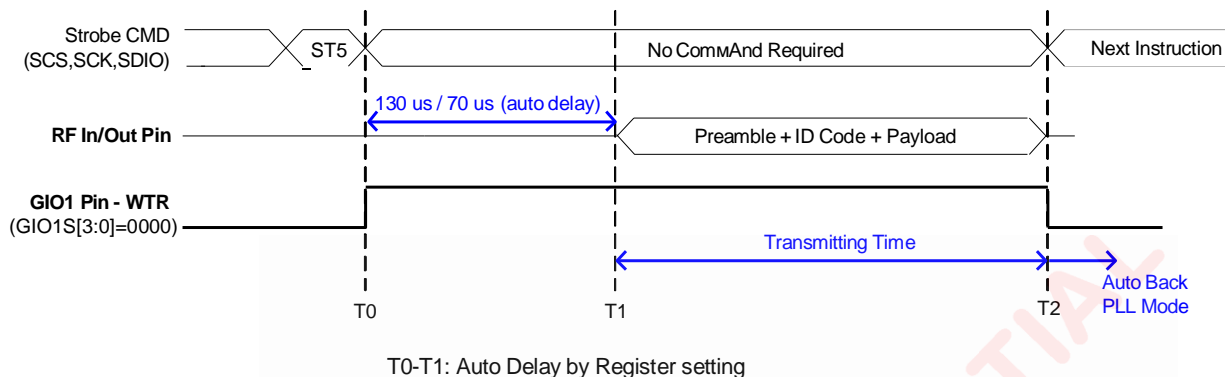

T0-T1: Auto Delay by Register setting

LO Freq.	PLL to WPLL	WPLL to TX	TX Ready Time
Changed	70 us	60 us	130 us
No Changed	10 us	60 us	70 us

Figure 11.5 Transmitting Timing Chart of Quick FIFO Mode

From Figure 11.4, when ST5 commAnd is issued for RX operation, see Figure 11.6 for detailed timing. A7105 status can be represented to GIO1 or GIO2 pin to MCU for timing control.

T0-T1: Delay by MCU
T1-T2: RX is ready, Wait for valid packet
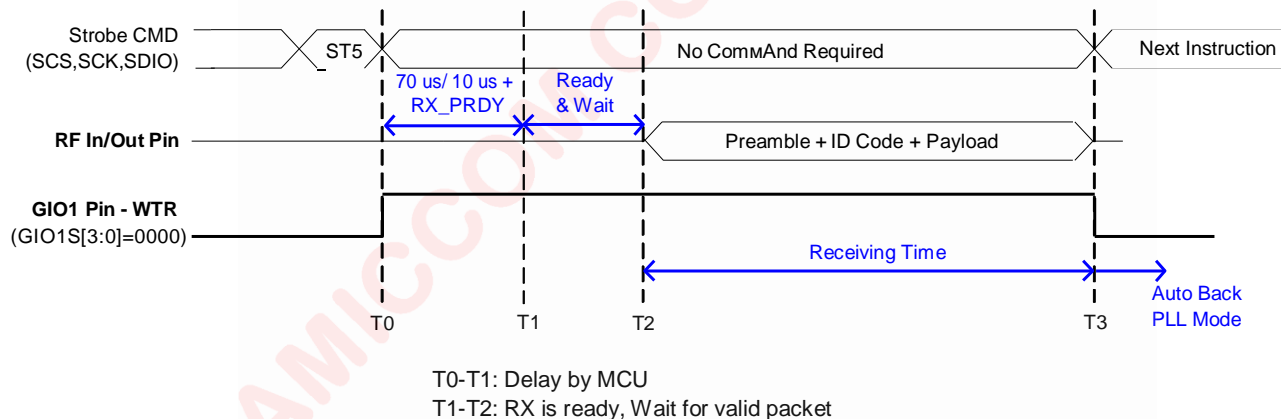
LO Freq.	Date Rate (bps)	DCM[1:0] (29h)	PLL to WPLL	WPLL to RX (RX-PRDY)	RX Ready Time (Delay by MCU)
Changed	<=125K	By preamble (01b)	70 us	40 us	110 us
Changed	250K	By ID (10b)	70 us	100 us	170 us
Changed	500K	By ID (10b)	70 us	60 us	130 us
Fixed	<=125K	By preamble (01b)	10 us	40 us	50 us
Fixed	250K	By ID (10b)	10 us	100 us	110 us
Fixed	500K	By ID (10b)	10 us	60 us	70 us

Figure 11.6 Receiving Timing Chart of Quick FIFO Mode

11.4 Power Saving FIFO Mode

This mode is suitable for requirement of low power consumption. After calibration flow, user can issue Strobe commAnd to enter idle mode where write TX FIFO or read RX FIFO. From idle mode to packet data transceiving, only one Strobe commAnd is needed. Once transmission is done, A7105 is auto back to idle mode.

When packets are finished and deeper power saving is necessary, user can issue Strobe commAnd to ask A7105 staying in sleep mode. Figure 11.7 is the state diagram of Power Saving FIFO mode.

CAL CMD	CMD Value	Calibration	Section
AK	CALC.0=1,	IF Filter	15.2
	CALC.1=1,	VCO Band	15.3
	CALC.2=1,	VCO Current	15.4

Strobe	CMD Value	Note	Section
ST1	1011b	Enter to PLL	10.4.4
ST2	1010b	Enter to Standby	10.4.3
ST3	1000b	Enter to SLEEP	10.4.1
ST4	1001b	Enter to IDLE	10.4.2
ST5-TX	1101b	Enter to TX	10.4.6
ST5-RX	1100b	Enter to RX	10.4.5
RST-CMD	00000000b	Software Reset	10.5

- Refer to chapter 16 for definition of RX FIFO Full and TX FIFO Empty.
- See Table 11.9 (next page) for RX-PRDY..

Figure 11.7 State diagram of Power Saving FIFO Mode

From Figure 11.7, when ST5 commAnd is issued for TX operation, see Figure 11.8 for detailed timing. A7105 status can be represented to GIO1 or GIO2 pin to MCU for timing control.
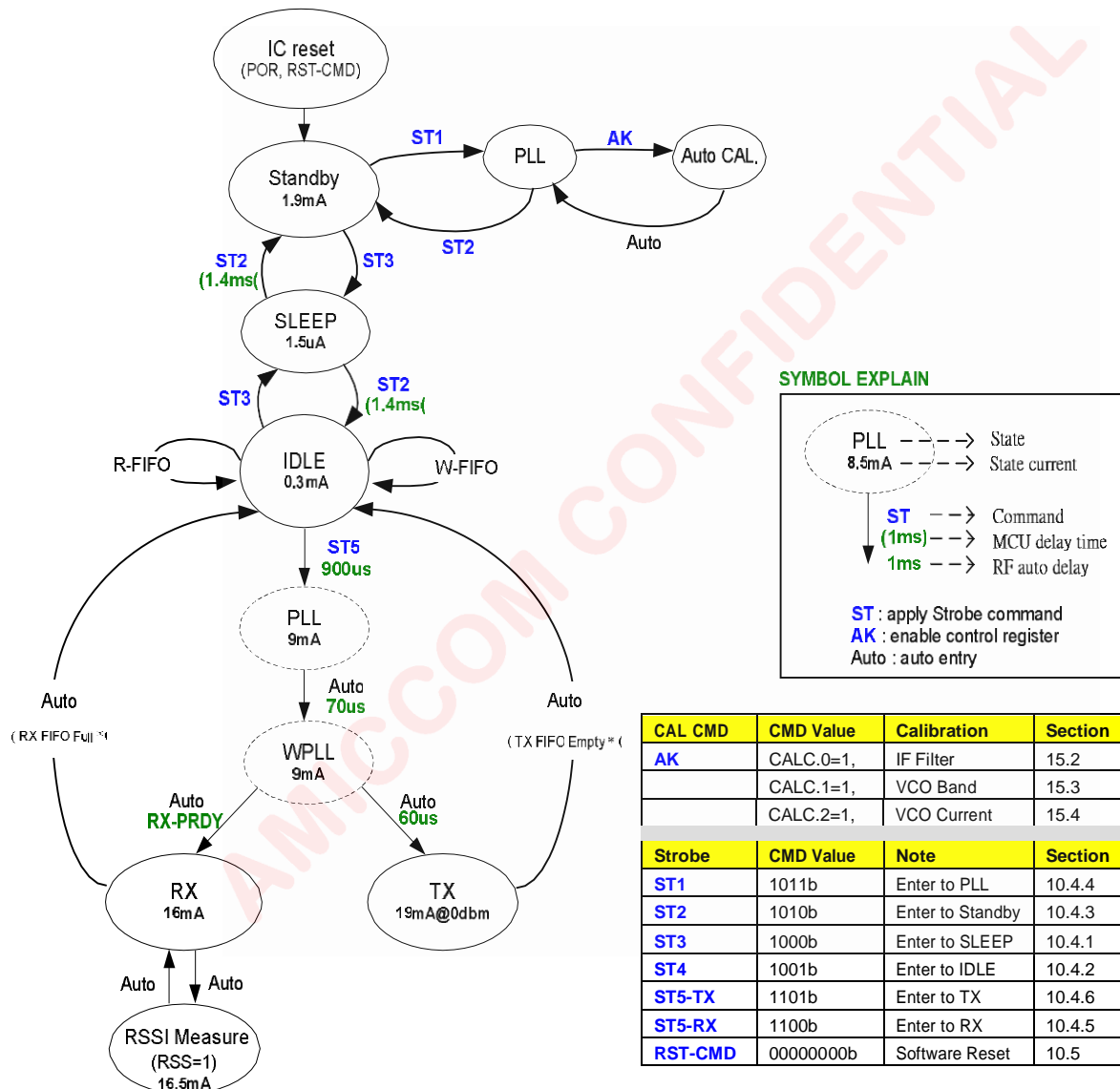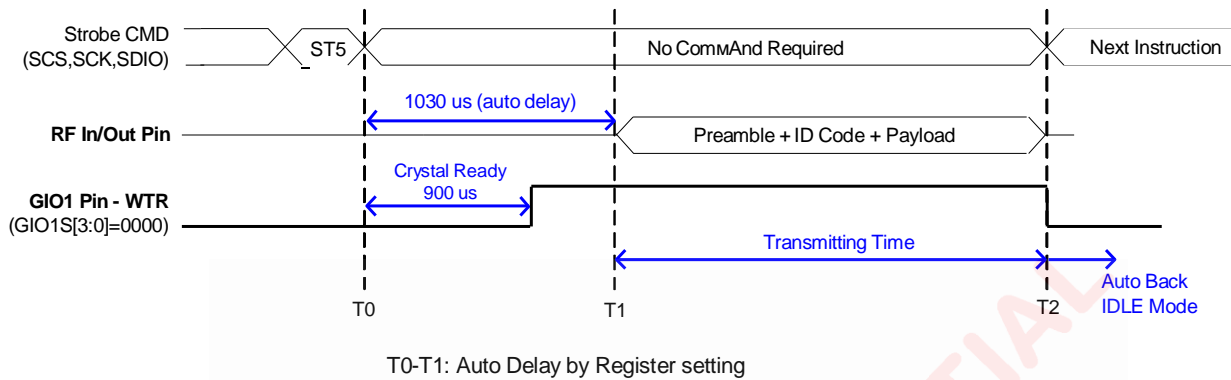

T0-T1: Auto Delay by Register setting

LO Freq.	IDLE to WPLL	WPLL to TX	TX Ready Time
Changed	970 us	60 us	1030 us
No Changed	970 us	60 us	1030 us

Figure 11.8 Transmitting Timing Chart of Power Saving FIFO Mode
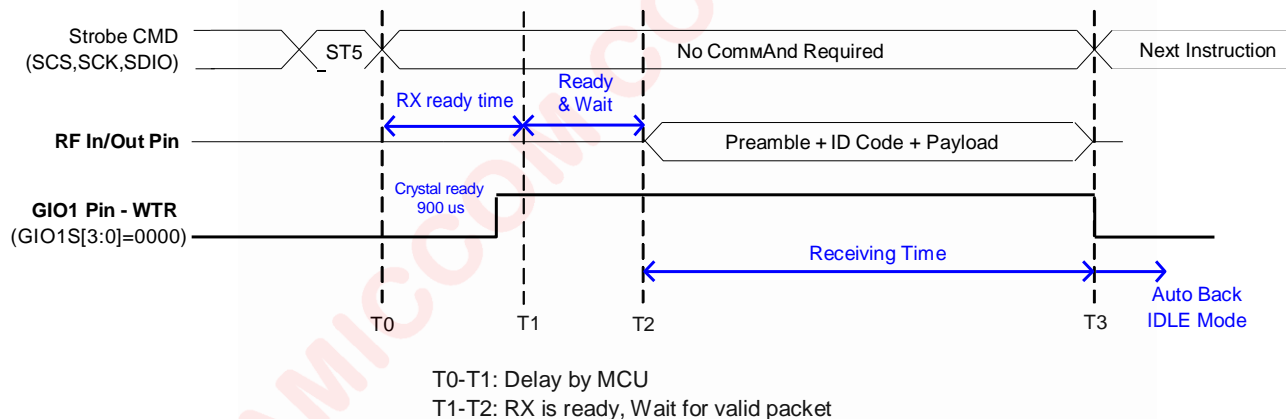
From Figure 11.7, when ST5 commAnd is issued for RX operation, see Figure 11.9 for detailed timing. A7105 status can be represented to GIO1 or GIO2 pin to MCU for timing control.

T0-T1: Delay by MCU
T1-T2: RX is ready, Wait for valid packet

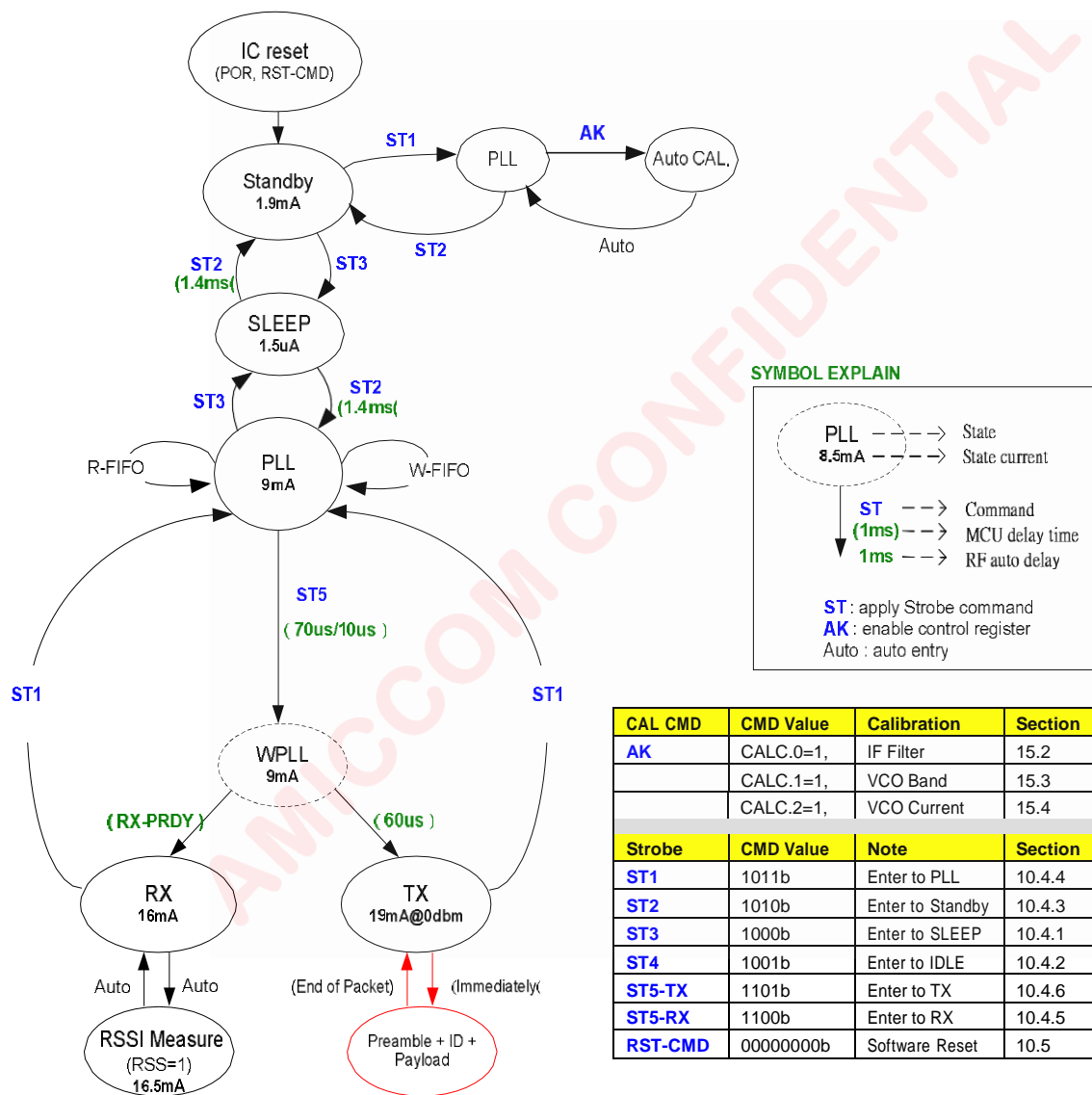| LO Freq.	Date Rate (bps)	DCM[1:0] (29h)	IDLE to WPLL	WPLL to RX (RX-PRDY)	RX Ready Time (Delay by MCU)
Changed / Fixed	<=125K	By preamble (01b)	970 us	40 us	1010 us
Changed / Fixed	250K	By ID (10b)	970 us	100 us	1080 us
Changed / Fixed	500K	By ID (10b)	970 us	60 us	1030 us

Figure 11.9 Receiving Timing Chart of Power Saving FIFO Mode

11.5 Quick Direct Mode

This mode is suitable for fast transceiving. After calibration flow, for every state transition, user has to issue Strobe commАnd to A7105.This mode is also suitable for the requirement of versatile packet formАt. Noted that user needs to take care the transition time by MCU's timer.

When packets are finished and deeper power saving is necessary, user can issue Strobe commАnd to ask A7105 staying in idle mode (or sleep mode). Figure 11.3 is the state diagram of Quick Direct mode.

CAL CMD	CMD Value	Calibration	Section
AK	CALC.0=1,	IF Filter	15.2
	CALC.1=1,	VCO Band	15.3
	CALC.2=1,	VCO Current	15.4

Strobe	CMD Value	Note	Section
ST1	1011b	Enter to PLL	10.4.4
ST2	1010b	Enter to Standby	10.4.3
ST3	1000b	Enter to SLEEP	10.4.1
ST4	1001b	Enter to IDLE	10.4.2
ST5-TX	1101b	Enter to TX	10.4.6
ST5-RX	1100b	Enter to RX	10.4.5
RST-CMD	00000000b	Software Reset	10.5

- See Table 11.12 (next page) for RX-PRDY..
- From PLL to WPLL, it is either 70 us (LO frequency changed) or 10 us (LO frequency NOT changed)

Figure 11.10 State diagram of Quick Direct Mode

From Figure 11.10, After A7105 enters TX mode, MCU should immediately deliver preamble. Therefore, user can send dummy preamble since WTR goes high or plus a delay loop to мAke sure dummy preamble is 10 bits at least before DCK is active. See below figure for detail timing.

A7105 Data Rate	Dummy Preamble	Packet			Note
		Preamble	**ID (06h)**	**MAx Payload**	
2K~500КБит/с	**≧ 10 bits**	32 bits	32 bits	512 bytes	Total Preamble = **42 bits**

Table 11.2 FormAt of dummy preamble and packet.
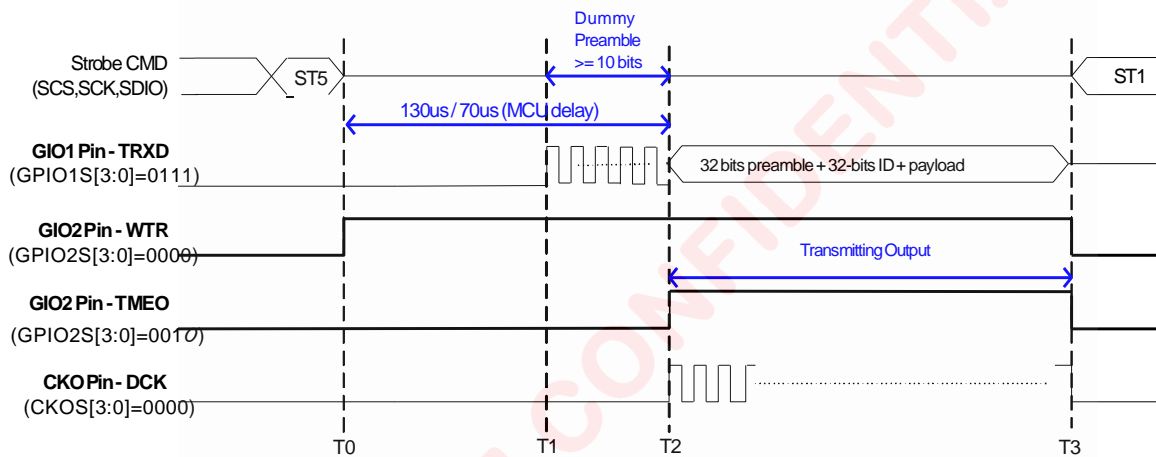
T0-T1: MCU delay loop
T1-T2: Dummy Preamble.
T2:   TMEO (TX Modulation Enable) is auto triggered
T2-T3: Transmitting Time

LO Freq.	PLL to WPLL	WPLL to TX	TX Ready Time
Changed	70 us	60 us	130 us
No Changed	10 us	60 us	70 us

Figure 11.11 Transmitting Timing Chart of Quick Direct Mode

From Figure 11.10, in RX mode, A7105 will check received ID compared to ID register (06h). If ID is мAtched, FSYNC will be output. MCU can decode received ID and payload from GIO1 pin (TRXD) via rising edge of RCK (recovery clock). Then, GIO2 pin can be used to inform MCU reference timing by PMDO (Preamble Detect Output) or FSYNC (Frame Sync).
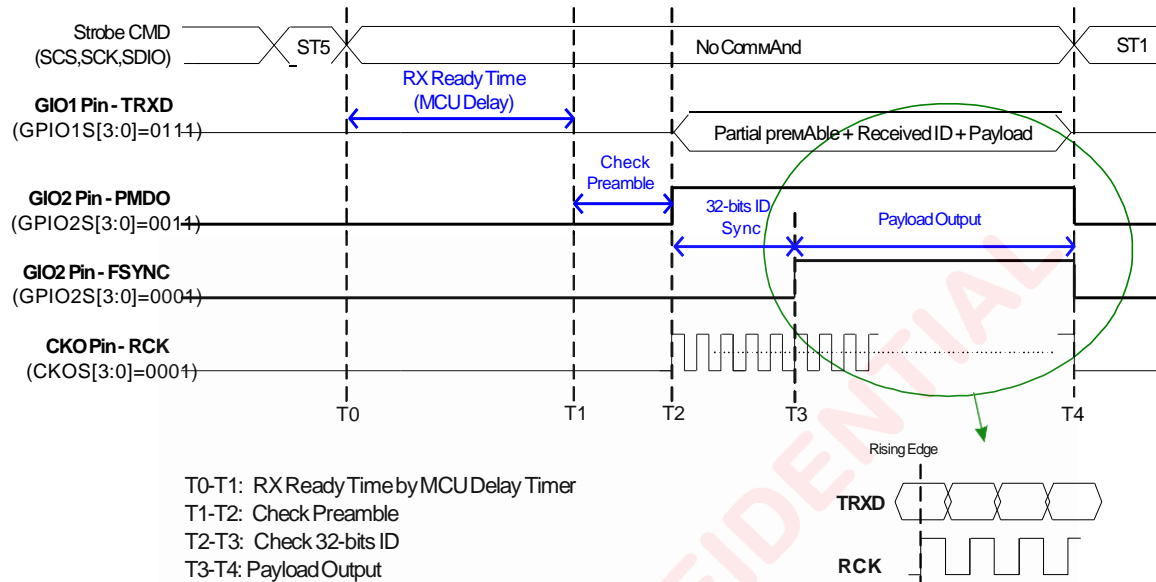
T0-T1: RX Ready Time by MCU Delay Timer
T1-T2: Check Preamble
T2-T3: Check 32-bits ID
T3-T4: Payload Output

LO Freq.	Date Rate (bps)	DCM[1:0] (29h)	PLL to WPLL	WPLL to RX (RX-PRDY)	RX Ready Time (Delay by MCU)
Changed	<=125K	By preamble (01b)	70 us	40 us	110 us
Changed	250K	By ID (10b)	70 us	100 us	170 us
Changed	500K	By ID (10b)	70 us	60 us	130 us
No Changed	<=125K	By preamble (01b)	10 us	40 us	50 us
No Changed	250K	By ID (10b)	10 us	100 us	110 us
No Changed	500K	By ID (10b)	10 us	60 us	70 us

Figure 11.12 Receiving Timing Chart of Quick Direct Mode

12 Crystal Oscillator

A7105 needs external crystal or external clock that is either 6 or 8/12/16/20/24 МГцto generate internal wanted clock. Be noted if external clock is equal or lower than 8MHz, A7105 only supports data rate up to 250K.

Relative Control Register

Clock Register (Address: 0Dh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Clock	R/W	GRC3	GRC2	GRC1	GRC0	CSC1	CSC0	CGS	XS
Reset		1	1	1	1	0	1	0	1

12.1 Use External Crystal

Figure 12.1 shows the connection of crystal network between XI and XO pins. C1 and C2 capacitance are used to adjust different crystal loading. A7105 supports crystal accuracy within ±20 ppm under firmware frequency compensation. Be noted that crystal accuracy requirement includes initial tolerance, temperature drift, aging and crystal loading.

A7105	Crystal Accuracy	Crystal ESR
Firmware FC = On	±20 ppm	≦ 80 ohm
Firmware FC = Off	±10 ppm	≦ 80 ohm
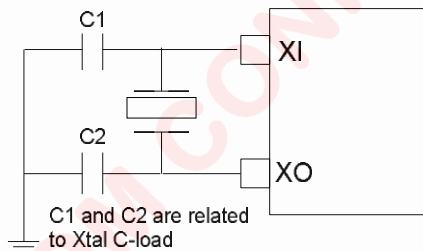
Fig12.1 Crystal oscillator circuit, refer to A7105 App. Note for C1 and C2.

12.2 Use external clock

A7105 has built-in AC couple capacitor to support external clock input. Figure 12.2 shows how to connect. In such case, XI pin is left opened. XS shall be low (0Dh) for selecting external clock. The frequency accuracy of external clock shall be controlled within ± 20 ppm, and the amplitude of external clock shall be within 1.2 ~ 1.8 V peak-to-peak.

Fig12.2 External clock source. R is used to tune Vpp = 1.2~1.8V

13. System Clock

A7105 supports different crystal frequency by programмАble "Clock Register" (0Dh). Based on this, three important internal clocks F_{CGR} , F_{DR} and F_{SYCK} are generated.

   (1) F_{XTAL}: Crystal frequency.
   (2) F_{XREF}: Crystal Ref. Clock = F_{XTAL} * (DBL+1).
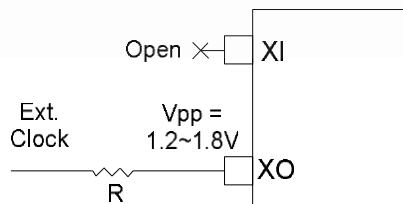   (3) F_{CGR}: Clock Generation Reference = 2МГц= F_{XREF} / (GRC+1), where F_{CGR} is used to generate 32M PLL.
   (4) F_{MCLK}: MAster Clock is either F_{XREF}: or 32M PLL, where F_{MCLK} is used to generate F_{SYCK}.
   (5) F_{SYCK}: System Clock = 16MHz=F_{MCLK} / CSC= 32 * F_{IF}, where F_{IF} is recommended to set 500КГц.
   (6) F_{DR}: Data Rate Clock = F_{IF} / (SDR+1).
   (7) F_{FPD}: VCO Compared Clock = = F_{XREF} / (RRC+1).

Relative Control Register

Clock Register (Address: 0Dh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Clock	R/W	GRC3	GRC2	GRC1	GRC0	CSC1	CSC0	CGS	XS
Reset		1	1	1	1	0	1	0	1

Data Rate Register (Address: 0Eh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Data Rate	R/W	SDR7	SDR6	SDR5	SDR4	SDR3	SDR2	SDR1	SDR0
Reset		0	0	0	0	0	0	0	0

PLL Register II (Address: 10h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLL II	W	DBL	RRC1	RRC0	CHR3	CHR2	CHR1	CHR0	BIP8
	R	DBL	RRC1	RRC0	CHR3	CHR2	CHR1	CHR0	IP8
Reset		1	0	0	1	1	1	1	0

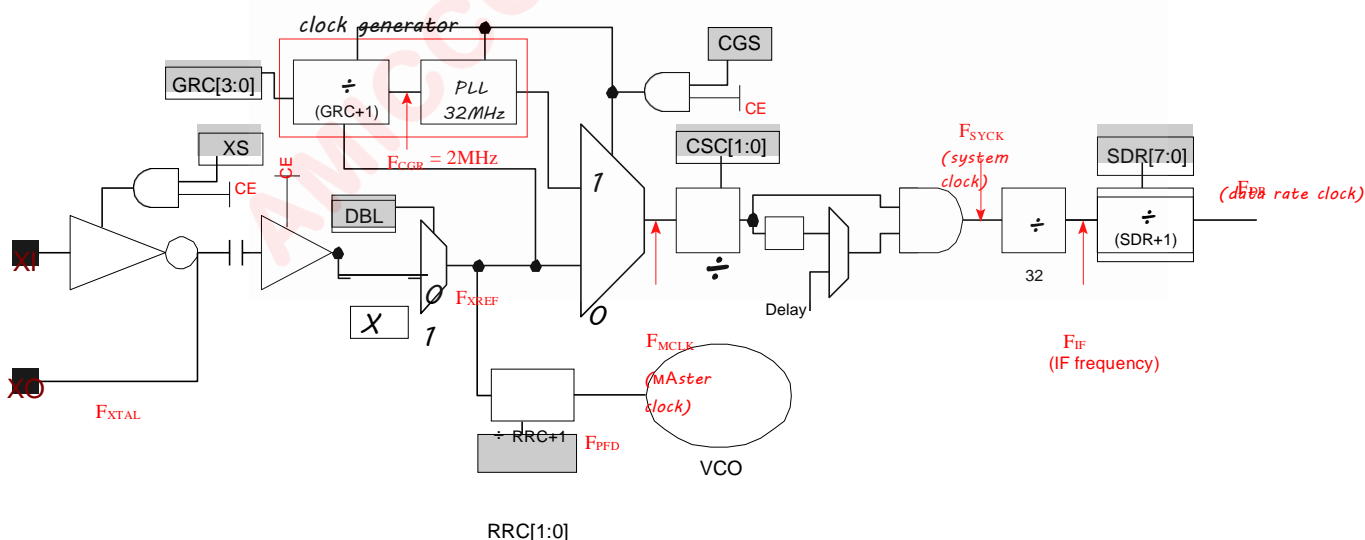
Fig13.1 System clock block diagram

As show in Fig 13.1, F_{MCLK}, the мАster clock either come from F_{XREF} (CGS = 0) or PLL 32МГц(CGS = 1). The relation between F_{SYCK} (the system clock) and F_{MCLK} (мАster clock) show in table 13.1

F$_{SYCK}$ (MAster Clock)		
	CGS = 0	CGS = 1
DBL=0	F$_{XTAL}$	32 MHz
DBL=1	2 * F$_{XTAL}$ (Recommend)	32 MHz

CSC [1:0]	F$_{SYCK}$ (system clock)	Note
00	F$_{MCLK}$	F$_{SYCK}$ is used to determine
01	F$_{MCLK}$/2	1. Data rate clock (0Eh)
10	F$_{MCLK}$/2	2. ADC clock (1Eh)
11	F$_{MCLK}$/4	3. Internal digital clock (09h)
		4. CKO pin (0Ah)

Table 13.1   System clock and мAster clock

13.1 Bypass clock generation

If crystal frequency is multiplier of 8MHz, the clock generator block can be turned off by setting CGS = 0.The relation between F$_{XTAL}$ (crystal frequency) and data rate show below:

$F_{XREF} = F_{XTAL} * (DBL+1)$
$F_{PFD} = F_{XREF} / (RRC [1:0]+1)$
$F_{DR} = F_{XREF} / (CSC [1:0]+1) / 32 / (SDR+1)$

Fig13.2 By pass clock generator to get system clock

For various data rate application, list some examples below.
For more data rate options, please contact AMICCOM FAE team.

Data rate 500КБит/с

Crystal source	CGS (0Dh)	DBL (10h)	CSC[1:0] (0Dh)	GRC [3:0] (0Dh)	F$_{IF}$ (КГц)	BWS (18h)	RRC [1:0] (10h)	F$_{PFD}$ (MHz)	CHR [3:0] (10h)	F$_{CHSP}$ (MHz)	SDR [7:0]
16MHz	0	1	01	Don't care	500	1	00	32	1111	0.5	0x00

Data rate = 250K / 125K / 100K / 50K / 25K / 10K / 2КБит/с

Crystal source	CGS (0Dh)	DBL (10h)	CSC[1:0] (0Dh)	GRC [3:0] (0Dh)	F$_{IF}$ (КГц)	BWS (18h)	RRC [1:0] (10h)	F$_{PFD}$ (MHz)	CHR [3:0] (10h)	F$_{CHSP}$ (MHz)	SDR [7:0]
8MHz	0	1	01	Don't care	500	1	00	16	0111	0.5	See next table
16MHz								32	1111		

SDR Table

	250КБит/с	125КБит/с	100КБит/с	50КБит/с	25КБит/с	10КБит/с	2КБит/с
SDR [7:0]	0x01	0x03	0x04	0x09	0x13	0x31	0xF9

13.2 Enable clock generation

If crystal frequency is the multiplier of 2МГцand larger than 6MHz, set CGS = 1 to enable F_{SYCK}= 32МГц(internal 32МГцPLL). The comparison frequency of clock generator F_{CGR} shall be 2МГцby setting GRC[3:0] to meets the below equations.

$F_{CRG} = F_{XTAL} * (1+DBL) / (GRC+1) = 2MHz.$
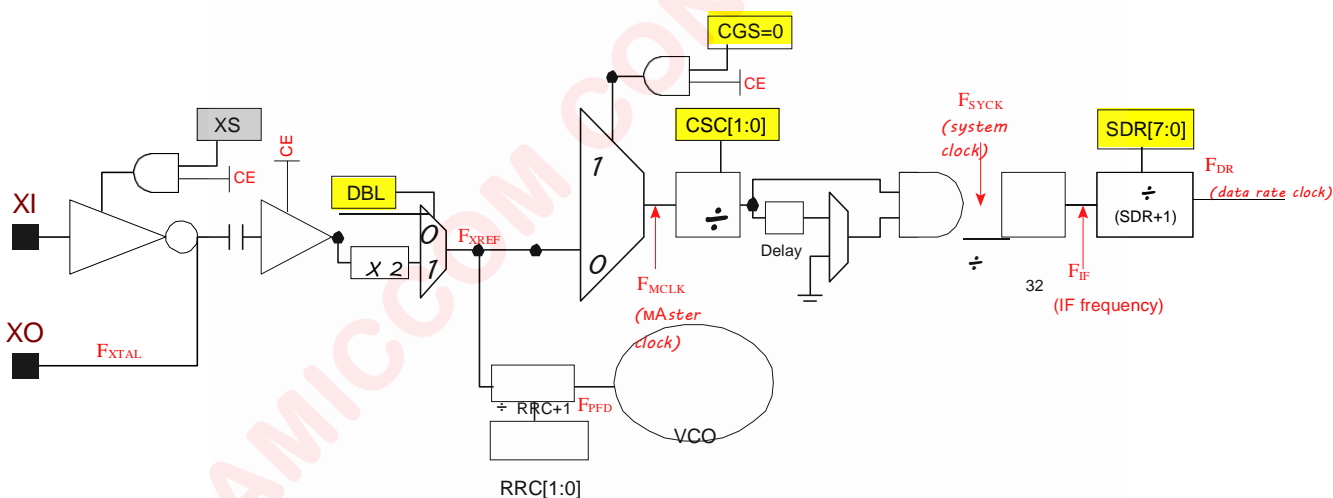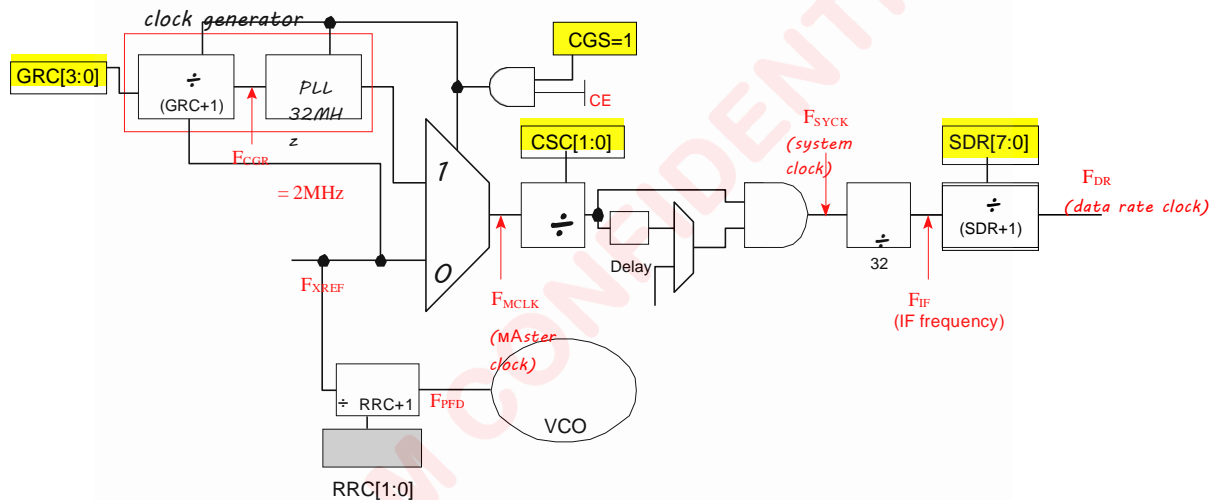$F_{DR} = F_{SYCK} / 32 / (SDR+1).$

Fig13.3 Enable clock generator to get system clock

For various data rate application, list some examples below. For more data rate options, please contact AMICCOM FAE team.

Data rate 500КБит/с

Crystal source	CGS (0Dh)	DBL (10h)	CSC[1:0] (0Dh)	GRC [3:0] (0Dh)	F_{IF} (КГц)	BWS (18h)	RRC [1:0] (10h)	F_{PFD} (MHz)	CHR [3:0] (10h)	F_{CHSP} (MHz)	SDR [7:0]
12MHz	1	1	01	1011	500	1	00	24	1011	0.5	0x00
16MHz		1		1111				32	1111		
24MHz		0		1011				24	1011		

Data rate = 250K / 125K / 100K / 50K / 25K / 10K / 2КБит/с

Crystal source	CGS (0Dh)	DBL (10h)	CSC[1:0] (0Dh)	GRC [3:0] (0Dh)	F_{IF} (КГц)	BWS (18h)	RRC [1:0] (10h)	F_{PFD} (MHz)	CHR [3:0] (10h)	F_{CHSP} (MHz)	SDR [7:0]
6MHz	1	1	01	0101	500	1	00	12	0101	0.5	See next table
8MHz		1		0111				16	0111		
12MHz		1		1011				24	1011		
16MHz		1		1111				32	1111		
24MHz		0		1011				24	1011		

SDR Table

	250КБит/с	125КБит/с	100КБит/с	50КБит/с	25КБит/с	10КБит/с	2КБит/с
SDR [7:0]	0x01	0x03	0x04	0x09	0x13	0x31	0xF9

14. Transceiver LO Frequency

A7105 is a half-duplex transceiver with embedded PA and LNA. For TX or RX frequency setting, user just needs to set up LO (Local Oscillator) frequency for two ways radio transmission.

To target full range of 2.4ГГц ISM band (2400 МГцto 2483.5 MHz), A7105 applies offset concept by LO frequency $F_{LO} = F_{LO\_BASE} + F_{OFFSET}$. Therefore, this device is easy to implement frequency hopping and multi-channels by just **ONE** register setting, **PLL Register I (CHN [7:0], 0Eh).**
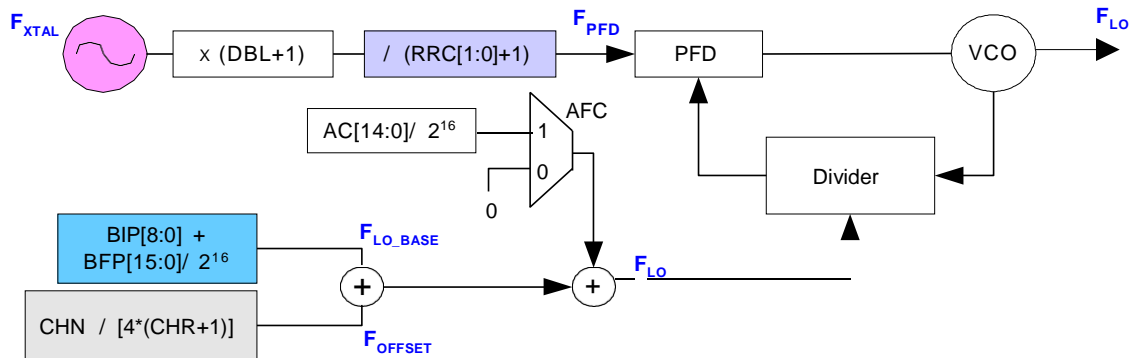
Below is the LO frequency block diagram.

Fig14.1 Frequency synthesizer block diagram

Relative Control Register
PLL Register I (Address: 0Fh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLL I	R/W	CHN7	CHN6	CHN5	CHN4	CHN3	CHN2	CHN1	CHN0
Reset		0	0	0	0	0	0	0	0

PLL Register II (Address: 10h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLL II	W	DBL	RRC1	RRC0	CHR3	CHR2	CHR1	CHR0	BIP8
	R	DBL	RRC1	RRC0	CHR3	CHR2	CHR1	CHR0	IP8
Reset		1	0	0	1	1	1	1	0

PLL Register III (Address: 11h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLL III	W	BIP7	BIP6	BIP5	BIP4	BIP3	BIP2	BIP1	BIP0
	R	IP7	IP6	IP5	IP4	IP3	IP2	IP1	IP0
Reset		0	1	0	0	1	0	1	1

PLL Register IV (Address: 12h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLL IV	W	BFP15	BFP14	BFP13	BFP12	BFP11	BFP10	BFP9	BFP8
	R	--/FP15	AC14/FP14	AC13/FP13	AC12/P12	AC11/ FP11	AC10/FP10	AC9/FP9	AC8/FP8
Reset		0	0	0	0	0	0	0	0

PLL Register V (Address: 13h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0

PLL V	W	BFP7	BFP6	BFP5	BFP4	BFP3	BFP2	BFP1	BFP0
	R	AC7/FP7	AC6/FP6	AC5/FP5	AC4/FP4	AC3/FP3	AC2/FP2	AC1/FP1	AC0/FP0
Reset		0	0	0	0	0	0	1	1

RX Register (Address: 18h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
RX	W	--	RXSM1	RXSM0	FC	RXDI	DMG	BWS	ULS
Reset		--	1	0	0	0	0	1	0

Mode Control Register   (Address: 01h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Mode Control I	W	R	DDPC	ARSSI	AIF	CD	WWSE	FMT	FMS
	R	W	DDPC	ARSSI	AIF	DFCD	WWSE	FMT	FMS
Reset		0	0	0	0	0	0	0	0

14.1 LO Frequency Setting

From Figure 14.1, F_{LO} is not only for TX radio frequency but also to be RX LO frequency. To set up F_{LO}, it is easy to implement by below 4 steps.

1. Set the base frequency (F_{LO_BASE}) by PLL Register II, III, IV and V (10h, 11h, 12h and 13h).
   Recommend to set $F_{LO\_BASE} \sim 2400.001MHz.$
2. Set the channel step (F_{CHSP}) by PLL Register II (10h).
   $F_{CHSP} = F_{XTAL} * (DBL+1) / 4 / (CHR+1)$, Recommend $F_{CHSP} = 500$ КГц.
3. Set CHN [7:0] to get offset frequency by PLL Register I (0Fh).
   $F_{OFFSET} = CHN [7:0] \times F_{CHSP}$
4. LO frequency is equal to base frequency plus offset frequency.
   $F_{LO} = F_{LO\_BASE} + F_{OFFSET}$

F_{LO}

F_{LO_BASE}

F_{OFFSET}

F_{LO_BASE}

$$F_{LO\_BASE} = F_{PFD} \cdot (BIP[8:0] + \frac{BFP[15:0]}{2^{16}}) = (DBL+1) \cdot \frac{F_{XTAL}}{RRC[1:0]+1} \cdot (BIP[8:0] + \frac{BFP[15:0]}{2^{16}})$$

Base on the above formula, for example, if F_{XTAL} = 16 МГцand set channel step F_{CHSP} = 500 КГц, to get **F_{LO_BASE} and F_{LO}**, see Table 14.1, 14.2, and Figure 14.2 for details.

STEP	ITEMS	VALUE	NOTE
1	F_{XTAL}	16 MHz	Crystal Frequency
2	DBL	1	Enable double function
3	RRC	0	If so, F_{PFD}= 32MHz
4	BIP	0x4B	To get F_{LO_BASE} =2400 MHz
5	BFP	0x0002	To get $F_{LO\_BASE} \sim$ 2400.001 MHz
6	**F_{LO_BASE}**	**~2400.001 MHz**	LO Base frequency

Table 14.1 How to set F_{LO_BASE}

How to set $F_{TXRF} = F_{LO} = F_{LO\_BASE} + F_{OFFSET} \sim 2405.001$ MHz

STEP	ITEMS	VALUE	NOTE
1	F_{LO_BASE}	~2400.001 MHz	After set up BIP and BFP
2	CHR	0x0F	To get F_{CHSP}= 500 КГц
3	F_{CHSP}	500 КГц	Channel step = 500КГц
4	CHN	0x0A	Set channel number = 10
5	F_{OFFSET}	5 MHz	F_{OFFSET}= 500 КГц * (CHN) = 5MHz
6	F_{LO}	~2405.001 MHz	Get F_{LO}= F_{LO_BASE} + F_{OFFSET}
7	**F_{TXRF}**	**~2405.001 MHz**	F_{TXRF} = F_{LO}

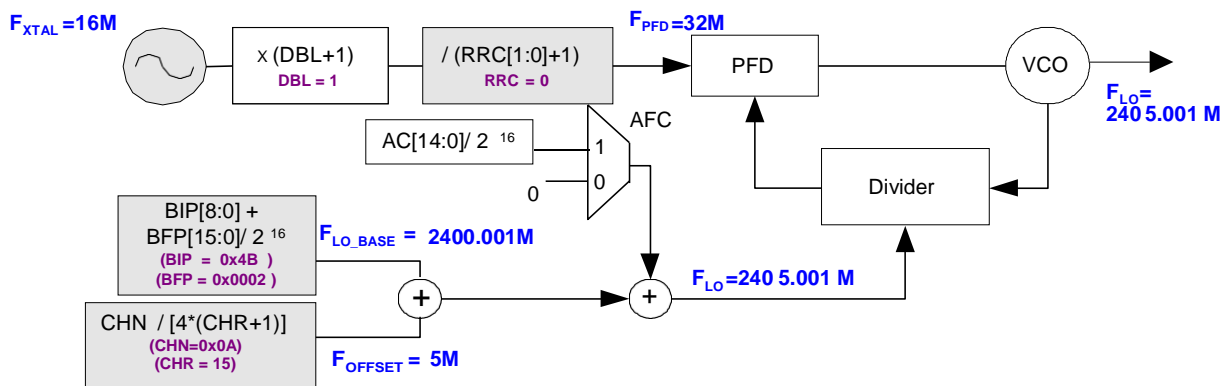Table 14.2 How to set F_{TXRF}

Figure 14.2 Block Diagram of set up $F_{LO} \sim 2405.001$ MHz

For different crystal frequency, 24МГц/ 16МГц/ 12 МГц/ 8МГц/ 6MHz, below are calculation details for F_{FPD} and F_{CHSP}

$$F_{PFD} = \frac{(DBL+1) \cdot f_{XTAL}}{RRC[1:0]+1}$$

F_{XTAL} (MHz)	DBL	RRC	F_{PFD} (MHz)	Note
24	0	0	24	
16	1	0	32	(reference design)
12	1	0	24	
8	1	0	16	
6	1	0	12	

$$F_{CHSP} = \frac{F_{PFD}}{4 \cdot (CHR[3:0]+1)}$$

F_{XTAL} (MHz)	F_{PFD} (MHz)	CHR [3:0]	F_{CHSP} (КГц)	CHN [7:0]	F_{OFFSET} (MHz)	F_{LO} (MHz)
24	24	1011	500	0x00 ~ 0xA8	0 ~ 84	2400 ~ 2484
16	32	1111	500	0x00 ~ 0xA8	0 ~ 84	2400 ~ 2484
12	24	1011	500	0x00 ~ 0xA8	0 ~ 84	2400 ~ 2484
8	16	0111	500	0x00 ~ 0xA8	0 ~ 84	2400 ~ 2484
6	12	0101	500	0x00 ~ 0xA8	0 ~ 84	2400 ~ 2484

14.2 IF Side Band Select

In two ways radio, both мAster and slave have two roles, TX and RX. In general, slave usually has to reply an ACK-packet or status update. In such case, A7105 offers two methods to set up F_{LO} while TRX exchanging.

(1) Auto IF exchange
(2) Fast exchange

Relative Control Register

Mode Control Register (Address: 01h)

Bit	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Name	R	DDPC	ARSSI	AIF	CD	WWSE	FMT	FMS	ADCM
	W	DDPC	ARSSI	AIF	DFCD	WWSE	FMT	FMS	ADCM
Reset		0	0	0	0	0	0	0	0

RX Register (Address: 18h)

Bit	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Name	W	--	RXSM1	RXSM0	FC	RXDI	DMG	BWS	ULS
Reset		--	1	0	0	0	0	1	0

| Register Setting	AIF Function	F_{RXLO} Formula
ULS=0	Disable	$F_{RXLO} = F_{LO}$
ULS=1	(AIF=0)	$F_{RXLO} = F_{LO}$
ULS=0	Enable	$F_{RXLO} = F_{LO} - 500КГц$
ULS=1	(AIF=1)	$F_{RXLO} = F_{LO} + 500Kz$

Table 14.3 F_{RXLO} Formula

14.2.1 Auto IF Exchange

A7105 supports Auto IF offset function (AIF, 01h). If AIF is enabled, only one on-air occupied frequency (Fcarrier). In this case, user has no need to change F_{RXLO} while TRX exchanging because F_{RXLO} is auto shifted F_{IF}. See below Figures and Table 14.4 for details.
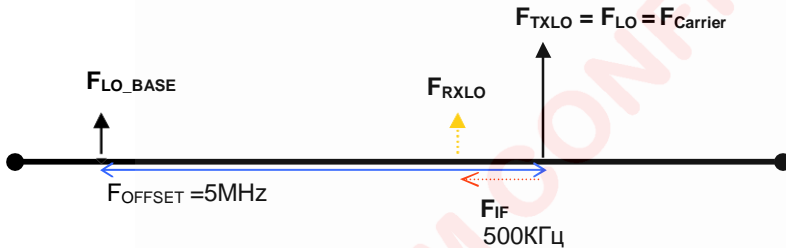
<MAster>
AIF=1 and ULS=0, F_{RXLO} is auto shifted lower than F_{TXLO} for 500КГц (F_{IF}).
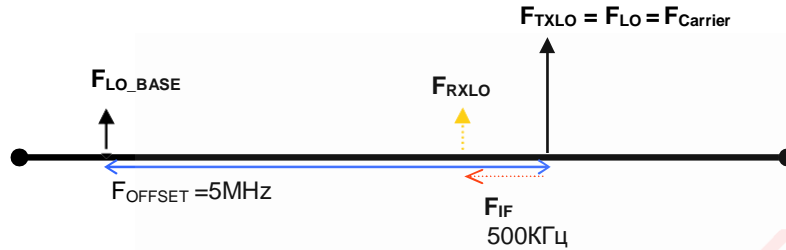
<Slave>
AIF=1 and ULS=0, F_{RXLO} is auto shifted lower than F_{TXLO} for 500КГц (F_{IF}).

Item	Role	AIF	ULS	CHN[7:0]	F_{CHSP} (КГц)	F_{TXLO} (КГц)	F_{RXLO} (MHz)	NOTE
MAster	TX	1	0	**10**	500	2405.001	-	
	RX	1	0	**10**	500	-	2404.501	Up side band F_{RXLO} is auto shifted
Slave	TX	1	0	**10**	500	2405.001	-	
	RX	1	0	**10**	500	-	2404.501	Up side band F_{RXLO} is auto shifted

Table 14.4 AIF function while TRX exchanging
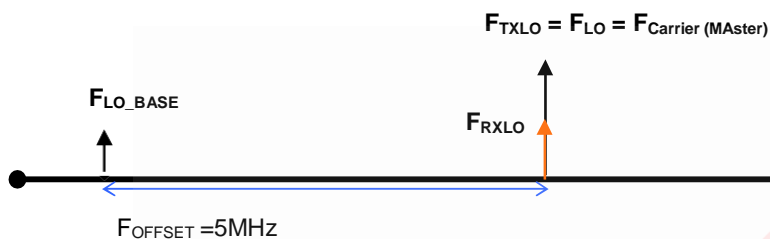
14.2.2 Fast Exchange

To reduce PLL settling time, user can disable AIF function. If AIF is disabled, two On-air frequency ($F_{Carrier (MAster)}$, $F_{Carrier (slave)}$) are occupied. In this case, user has to control ULS =0 (MAster side) and ULS = 1 (Slave side) for fast exchange in two-way radio. See below Figures and Table 14.5 for details.
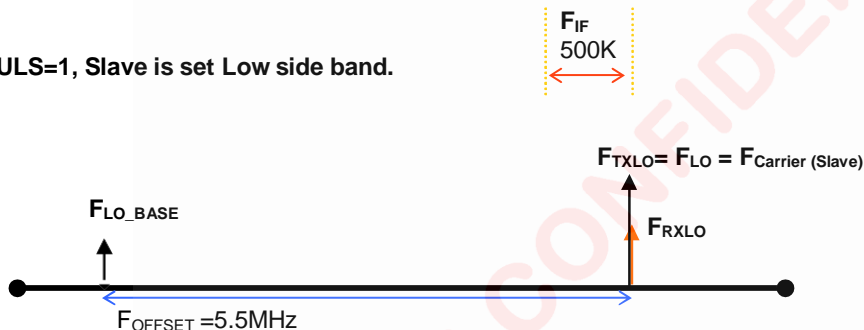
\<MAster\>
AIF=0 and ULS=0, MAster is set Up side band.

$F_{TXLO} = F_{LO} = F_{Carrier (MAster)}$

F_{LO_BASE}

F_{RXLO}

F_{OFFSET} =5MHz

F_{IF} 500K

\<Slave\>
AIF=0 and ULS=1, Slave is set Low side band.

$F_{TXLO}= F_{LO} = F_{Carrier (Slave)}$

F_{LO_BASE}

F_{RXLO}

F_{OFFSET} =5.5MHz

Item	Role	AIF	ULS	CHN[7:0]	F_{CHSP} (КГц)	F_{TXLO} (КГц)	F_{RXLO} (MHz)	NOTE
MAster	TX	0	**0**	**10**	500	2405.001	-	
	RX	0	**0**	**10**	500	-	2405.001	Up side band
Slave	TX	0	**1**	**14**	500	2405.501	-	
	RX	0	**1**	**14**	500	-	2405.501	Low side band

Table 14.5 Fast exchange function while TRX exchanging

14.3 Frequency Compensation

Frequency Compensation function (FC) supports low accuracy crystal (±20 ppm) without sensitivity degradation. The FC concept is to fine tune RX LO frequency (F_{RXLO}). MCU can read AC[14:0], (12h) and (13h), to executes frequency drift calculation and update new setting to PLL IV (12h) and PLL V (13h) to adjust the best RX LO frequency (F_{RXLO}).
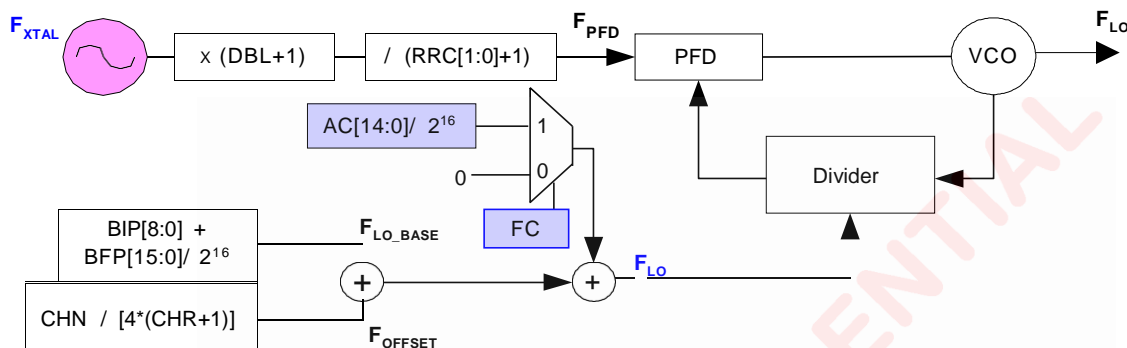

Figure 14.3 Block Diagram of enabling FC function

Relative Control Register

RX Register (Address: 18h)

Bit	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Name	W	--	RXSM1	RXSM0	FC	RXDI	DMG	RAW	ULS
Reset		--	1	0	0	0	0	1	0

PLL Register IV (Address: 12h)

Bit	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Name	R	--/FP15	AC14/FP14	AC13/FP13	AC12/P12	AC11/ FP11	AC10/FP10	AC9/FP9	AC8/FP8
	W	BFP15	BFP14	BFP13	BFP12	BFP11	BFP10	BFP9	BFP8
Reset		0	0	0	0	0	0	0	0

PLL Register V (Address: 13h)

Bit	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Name	R	AC7/FP7	AC6/FP6	AC5/FP5	AC4/FP4	AC3/FP3	AC2/FP2	AC1/FP1	AC0/FP0
	W	BFP7	BFP6	BFP5	BFP4	BFP3	BFP2	BFP1	BFP0
Reset		0	0	0	0	0	1	0	0

For Frequency Compensation procedure, please refer to AMICCOM's reference code and contact AMICCOM FAE team for details.

15. Calibration

A7105 needs calibration process after power on reset or software reset by 3 calibration items, they are, VCO Current, VCO Bank, and IF Filter Bank.

1. VCO Current Calibration (Standby or PLL mode) is used to find adequate VCO current.
2. VCO Bank Calibration (PLL mode) is used to select best VCO frequency bank for the calibrated frequency.
3. IF Filter Bank Calibration (Standby or PLL mode) is used to calibrate IF filter bandwidth and center frequency.

15.1 Calibration Procedure

1. Initialize all control registers (refer to A7105 reference code).
2. Select calibration mode (set MFBS=0, MVCS =1, MVBS = 0).
3. Set A7105 in PLL mode.
4. Enable IF Filter Bank (set FBC = 1),
   VCO Current (VCC = 1), and VCO Bank (VBC = 1).
5. After calibration done, FBC, VCC and VBC is auto clear.
6. Check pass or fail by reading calibration flag.
   (FBCF) and (VCCF, VBCF).

15.2 IF Filter Bank Calibration

Relative Control Register

Calibration Control Register   (Address: 02h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Mode Control II	W/R	--	--	--	--	--	VCC	VBC	**FBC**
Reset		--	--	--	--	--	0	0	0

IF Calibration Register I (Address: 22h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
IF Calibration I	R				FBCF	FB3	FB2	FB1	FB0
	W	--	--	--	**MFBS**	MFB3	MFB2	MFB1	MFB0
Reset		--	--	--	0	0	1	1	0

1. Initialize all control registers (refer to A7105 reference code).
2. Set MFBS = 0 for auto calibration.
3. Set A7105 in PLL mode.
4. Set FBC= 1 (02h).
5. The мAximum calibration time for this calibration is about 256us.
6. FBC is auto clear after calibration done.
7. User can read calibration flag (FBCF, 22h) to check pass or fail.
8. User can read FB [3:0] (22h) to get the auto calibration value.

15.3 VCO Current Calibration

Relative Control Register

Calibration Control Register   (Address: 02h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Mode Control II	W/R	--	--	--	--	--	VCC	VBC	FBC
Reset		--	--	--	--	--	0	0	0

VCO current Calibration Register (Address: 24h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
VCO current	R				FVCC	VCB3	VCB2	VCB1	VCB0
Calibration	W	--	--	VCCS	**MVCS**	VCOC3	VCOC2	VCOC1	VCOC0
Reset		--	--	0	0	1	0	0	0

1. Initialize all control registers (refer to A7105 reference code).
2. Set MVCS= 1 for мAnual calibration.
3. Set VCOC[3:0] = [0011] (24h).

15.4 VCO Bank Calibration

Relative Control Register

Calibration Control Register   (Address: 02h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Mode Control II	W/R	--	--	--	--	--	VCC	VBC	FBC
Reset		--	--	--	--	--	0	0	0

VCO Single band Calibration Register I (Address: 25h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
VCO Single band	R	--	--	DVT1	DVT0	VBCF	VB2	VB1	VB0
Calibration I	W	--	--	--	--	**MVBS**	MVB2	MVB1	MVB0
Reset		--	--	--	--	0	1	0	0

VCO Single band Calibration Register II (Address: 26h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
VCO Single band Calibration II	W	--	--	VTH2	VTH1	VTH0	VTL2	VTL1	VTL0
Reset		--	--	1	1	1	0	1	1

1. Initialize all control registers (refer to A7105 reference code).
2. Set MVBS= 0 for auto calibration.
3. Set A7105 in PLL mode.
4. Set VBC= 1 (02h). Set VCO tuning upper threshold voltage VH and lower threshold voltage VL. The recommended voltage is VTH [2:0] = [111], VTL[2:0] = [011].
5. The мAximum calibration time for VCO Bank Calibration is about 240 us (4 * PLL settling time).
6. VBC is auto clear after calibration done.
7. User can read calibration flag (VBCF, 25h) to check pass or fail.
8. User can read VB [2:0] (25h) to get the auto calibration value.

16. FIFO (First In First Out)

A7105 supports separated 64-bytes TX and RX FIFO by enabling FMS =1 (01h). For FIFO accessing, TX FIFO (write-only) and RX FIFO (read-only) share the same register address 05h. TX FIFO represents transmitted payload. On the other hand, once RX circuitry synchronizes ID Code, received payload is stored into RX FIFO.

In chapter 10 and 11, user can also find listed FIFO informAtion below.
(1) Figure 10.15 and 10.16 for FIFO accessing via 3-wire SPI.
(2) Section 10.4.7 and 10.4.8 for FIFO pointer reset commAnd.
(3) Figure 11.2 and Figure 11.3 for NormAl/Quick FIFO mode.

16.1 Packet FormAt
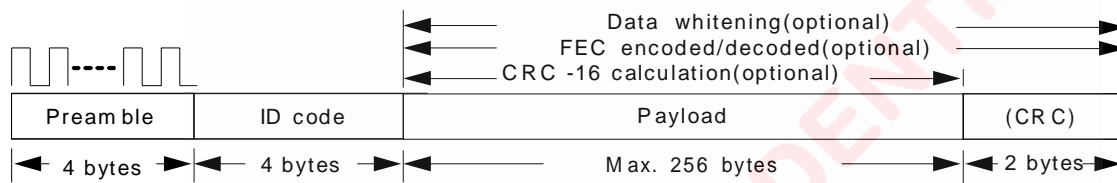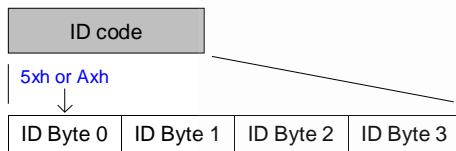
Figure 16.1 Packet FormAt of FIFO mode

Figure 16.2 ID Code FormAt

Preamble:
The packet is led by preamble composed of alternate 0 and 1. If the first bit of ID code is 0, preamble shall be 0101…0101. In the contrast, if the first bit of ID code is 1, preamble shall be 1010…1010.
Preamble length is recommended to set 4 bytes by PML [1:0] (1Fh).

ID code:
ID code is recommended to set 4 bytes by IDL=1 (1Fh). ID Code is sequenced by Byte 0, 1, 2 and 3 (Recommend to set ID Byte 0 = 5xh or Axh). If RX circuitry checks the ID code correct, received payload will be stored into RX FIFO. In special case, ID code could be set error tolerance (0~ 3bit error) by ETH [1:0] (20h) for ID synchronization check.

Payload:
Payload length is programmAble by FEP [7:0] (03h) from 1 byte to 64 bytes. The physical FIFO depth is 64 bytes. A7105 also supports logical FIFO extension up to 256 bytes. See section 16.4.3 for details.

CRC (option):
In FIFO mode, if CRC is enabled (CRCS=1, 1Fh), 2-bytes of CRC value is transmitted automAtically after payload. In the same way, RX circuitry will check CRC value and show the result to CRC Flag (00h).

Relative Control Register

Mode Register   (Address: 00h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Mode	R	--	FECF	CRCF	CER	XER	PLLER	TRSR	TRER
	W	RESETN	RESETN	RESETN	RESETN	RESETN	RESETN	RESETN	RESETN
Reset		--	--	--	--	--	--	--	--

FIFO Register I (Address: 03h)

Bit	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Name	W	FEP7	FEP6	FEP5	FEP4	FEP3	FEP2	FEP1	FEP0
Reset		0	0	1	1	1	1	1	1

Code Register I (Address: 1Fh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Code I	W	--	MCS	WHTS	FECS	CRCS	IDL	PML1	PML0
Reset		--	0	0	0	0	1	1	1

Code Register II (Address: 20h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Code II	W	--	DCL2	DCL1	DCL0	ETH1	ETH0	PMD1	PMD0
Reset		--	1	1	1	0	1	1	1

Code Register III (Address: 21h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Code III	W	--	WS6	WS5	WS4	WS3	WS2	WS1	WS0
Reset		--	0	1	0	1	0	1	0

16.2 Bit Stream Process

A7105 supports 3 optional bit stream process for payload, they are,
(1) CCITT-16 CRC ($x^{16} + x^{15} + x^2 + 1$)
(2) (7, 4) Hamming FEC
(3) Data Whitening by XOR PN7 (7-bits Pseudo Random Sequence).

CRC (Cyclic Redundancy Check):
1.   CRC is enabled by CRCS= 1 (1Fh). TX circuitry calculates the CRC value of payload (preamble, ID code excluded) and transmits 2-bytes CRC value after payload.
2.   RX circuitry checks CRC value and shows the result to CRC Flag (00h). If CRCF=0, received payload is correct, else error occurred. (CRCF is read only, it is revised internally while receiving every packet.)

FEC (Forward Error Correction):
1.   FEC is enabled by FECS= 1 (1Fh). Payload and CRC value (if CRCS=1) are encoded by (7, 4) Hamming code.
2.   Each 4-bits (nibble) of payload is encoded into 7-bits code word as well as delivered out autoмAtically.
     (ex. 64 bytes payload will be encoded to 128 code words, each code word is 7 bits.)
3.   RX circuitry decodes received code words autoмAtically. FEC supports 1-bit error correction each code word. Once 1-bit error occurred, FEC flag=1 (00h). (FECF is read only, it is revised internally while receiving every packet.)

Data Whitening:
1.   Data whitening is enabled by WHTS= 1 (1Fh). The initial seed of PN7 is WS [6:0] (21h). Payload is always encrypted by bit XOR operation with PN7. CRC and/or FEC are also encrypted if CRCS=1 and/or if FECS=1.
2.   RX circuitry decrypts received payload and 2-bytes CRC (if CRCS=1) autoмAtically. Be notice, user shall set the same WS [6:0] (21h) to TX and RX.

16.3 Transmission Time

Based on CRC and FEC options, the transmission time are different. See table 16.1 for details.

Data Rate = 500 КБит/с

Preamble (bits)	ID Code (bits)	Payload (bits)	CRC (bits)	FEC	Transmission Time / Packet
32	32	512	Disable	Disable	576 bit X 2 us = 1.152 ms
32	32	512	16 bits	Disable	592 bit X 2 us = 1.184 ms
32	32	512	Disable	512 x 7 / 4	960 bit X 2 us = 1.920 ms
32	32	512	16 x 7 / 4	512 x 7 / 4	988 bit X 2 us = 1.976 ms

Data Rate = 250 КБит/с

Preamble (bits)	ID Code (bits)	Payload (bits)	CRC (bits)	FEC	Transmission Time / Packet
32	32	512	Disable	Disable	576 bit X 4 us = 2.304 ms
32	32	512	16 bits	Disable	592 bit X 4 us = 2.368 ms
32	32	512	Disable	512 x 7 / 4	960 bit X 4 us = 3.840 ms
32	32	512	16 x 7 / 4	512 x 7 / 4	988 bit X 4 us = 3.952 ms

Data Rate = 125 КБит/с

Preamble (bits)	ID Code (bits)	Payload (bits)	CRC (bits)	FEC	Transmission Time / Packet
32	32	512	Disable	Disable	576 bit X 8 us = 4.608 ms
32	32	512	16 bits	Disable	592 bit X 8 us = 4.736 ms
32	32	512	Disable	512 x 7 / 4	960 bit X 8 us = 7.580 ms
32	32	512	16 x 7 / 4	512 x 7 / 4	988 bit X 8 us = 7.904 ms

Data Rate = 50 КБит/с

Preamble (bits)	ID Code (bits)	Payload (bits)	CRC (bits)	FEC	Transmission Time / Packet
32	32	512	Disable	Disable	576 bit X 20 us = 11.52 ms
32	32	512	16 bits	Disable	592 bit X 20 us = 11.84 ms
32	32	512	Disable	512 x 7 / 4	960 bit X 20 us = 19.20 ms
32	32	512	16 x 7 / 4	512 x 7 / 4	988 bit X 20 us = 19.76 ms

Data Rate = 2 КБит/с

Preamble (bits)	ID Code (bits)	Payload (bits)	CRC (bits)	FEC	Transmission Time / Packet
32	32	512	Disable	Disable	576 bit X 0.5 ms = 0.288 s
32	32	512	16 bits	Disable	592 bit X 0.5 ms = 0.296 s
32	32	512	Disable	512 x 7 / 4	960 bit X 0.5 ms = 0.480 s
32	32	512	16 x 7 / 4	512 x 7 / 4	988 bit X 0.5 ms = 0.494 s

Table 16.1 Transmission time

16.4 Usage of TX and RX FIFO

In application points of view, A7105 supports 3 options of FIFO arrangement.
(1) Easy FIFO
(2) Segment FIFO
(3) FIFO Extension

For FIFO operation, A7105 supports Strobe commAnd to reset TX and RX FIFO pointer as shown below. User can refer to section 10.5 for FIFO write pointer reset and FIFO read pointer reset.

Переведено Penguin096
https://github.com/Penguin096

Strobe CommAnd

A7	A6	A5	A4	A3	A2	A1	A0	Description
1	1	1	0	x	x	X	x	FIFO write pointer reset (for TX FIFO)
1	1	1	1	x	x	X	x	FIFO read pointer reset (for RX FIFO)

FIFO Register I (Address: 03h)

Bit	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Name	W	FEP7	FEP6	FEP5	FEP4	FEP3	FEP2	FEP1	FEP0
Reset		0	0	1	1	1	1	1	1

FIFO Register II (Address: 04h)

Bit	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Name	W	FPM1	FPM0	PSA5	PSA4	PSA3	PSA2	PSA1	PSA0
Reset		0	1	0	0	0	0	0	0

FIFO DATA Register (Address: 05h)

Bit	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Name	R/W	FIFO7	FIFO6	FIFO5	FIFO4	FIFO3	FIFO2	FIFO1	FIFO0
Reset		0	0	0	0	0	0	0	0

16.4.1 Easy FIFO

In Easy FIFO, мАx FIFO length is 64 bytes. FIFO length is equal to **(FEP [7:0] +1)**. User just needs to control FEP [7:0] (03h) and disable PSA and FPM as shown below.

Register setting

TX	RX	Control Registers		
FIFO Length (byte)	FIFO Length (byte)	FEP[7:0] (03h)	PSA [5:0] (04h)	FPM [1:0] (04h)
1	1	0x00	0	0
8	8	0x07	0	0
16	16	0x0F	0	0
32	32	0x1F	0	0
64	64	0x3F	0	0

Table 16.2 Control registers of Easy FIFO

Procedures of TX FIFO Transmitting
1.　　Initialize all control registers (refer to A7105 reference code).
2.　　Set FEP [7:0] = 0x3F for 64-bytes FIFO.
3.　　Refer to section 11.2 ~ 11.4.
4.　　Send Strobe commAnd – TX FIFO write pointer reset.
5.　　MCU writes 64-bytes data to TX FIFO.
6.　　Send TX Strobe CommAnd.
7.　　Done.

Procedures of RX FIFO Reading
1.　　When RX FIFO is full, WTR (or FSYNC) can be used to trigger MCU for RX FIFO reading.
2.　　Send Strobe commAnd – RX FIFO read pointer reset.
3.　　MCU read 64-bytes from RX FIFO.
4.　　Done
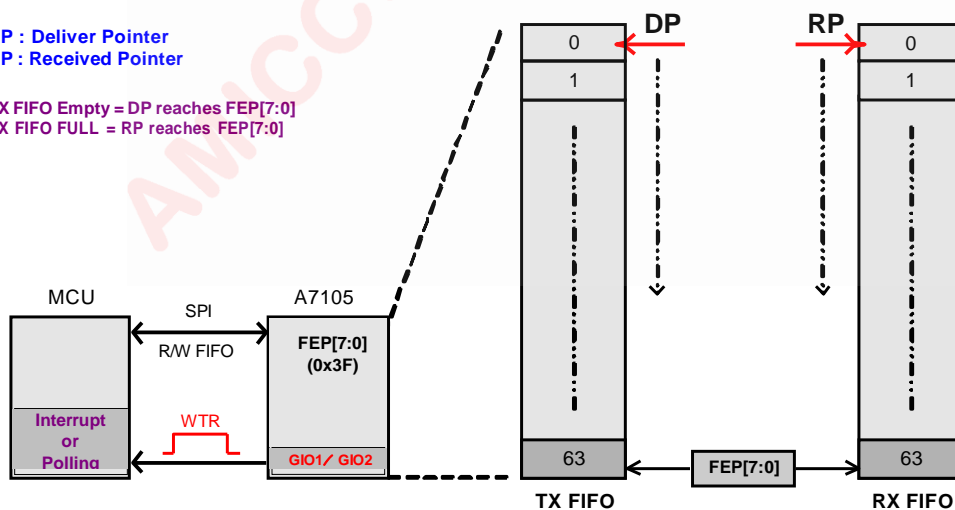
Figure 16.3 Easy FIFO

16.4.2 Segment FIFO

In Segment FIFO, TX FIFO length is equal to (FEP [7:0] − PSA [5:0] + 1). FPM [1:0] should be zero. This function is very useful for button applications. In such case, each button is used to transmit fixed code (data) every time. During initialization, each fixed code is written into corresponding segment FIFO once and for all. Then, if button is triggered, MCU just assigns corresponding segment FIFO (PSA [5:0] and FEP [7:0]) and issues TX strobe commAnd.

If TX FIFO is arranged into 8 segments, each TX segment and RX FIFO length are 8 bytes

TX				Control Registers		
Segment	PSA	FEP	FIFO Length (byte)	PSA[5:0] (04h)	FEP[7:0] (03h)	FPM[1:0] (04h)
1	PSA1	FEP1	8	0x00	0x07	0
2	PSA2	FEP2	8	0x08	0x0F	0
3	PSA3	FEP3	8	0x10	0x17	0
4	PSA4	FEP4	8	0x18	0x1F	0
5	PSA5	FEP5	8	0x20	0x27	0
6	PSA6	FEP6	8	0x28	0x2F	0
7	PSA7	FEP7	8	0x30	0x37	0
8	PSA8	FEP8	8	0x38	0x3F	0

RX	Control Registers		
FIFO Length (byte)	PSA [5:0] (04h)	FEP [7:0] (03h)	FPM[1:0] (04h)
8	0	0x07	0

Table 16.3 Segment FIFO is arranged into 8 segments

Procedures of TX FIFO Transmitting
1. Initialize all control registers (refer to A7105 reference code).
2. Refer to section 11.2 ~ 11.4.
3. Send Strobe commAnd – TX FIFO write pointer reset.
4. MCU writes fixed code into corresponding segment FIFO once and for all.
5. To consign Segment 1, set PSA = 0x00 and FEP= 0x07
   To consign Segment 2, set PSA = 0x08 and FEP= 0x0F
   To consign Segment 3, set PSA = 0x10 and FEP= 0x17
   To consign Segment 4, set PSA = 0x18 and FEP= 0x1F
   To consign Segment 5, set PSA = 0x20 and FEP= 0x27
   To consign Segment 6, set PSA = 0x28 and FEP= 0x2F
   To consign Segment 7, set PSA = 0x30 and FEP= 0x37
   To consign Segment 8, set PSA = 0x38 and FEP= 0x3F
6. Send TX Strobe CommAnd.
7. Done.

Procedures of RX FIFO Reading
1. When RX FIFO is full, WTR (or FSYNC) is used to trigger MCU for RX FIFO reading.
2. Send Strobe commAnd – RX FIFO read pointer reset.
3. MCU read 8-bytes from RX FIFO.
4. Done.

Definitions

DP : Deliver Pointer
RP : Received Pointer

TX FIFO Empty = DP reaches FEP[7:0]
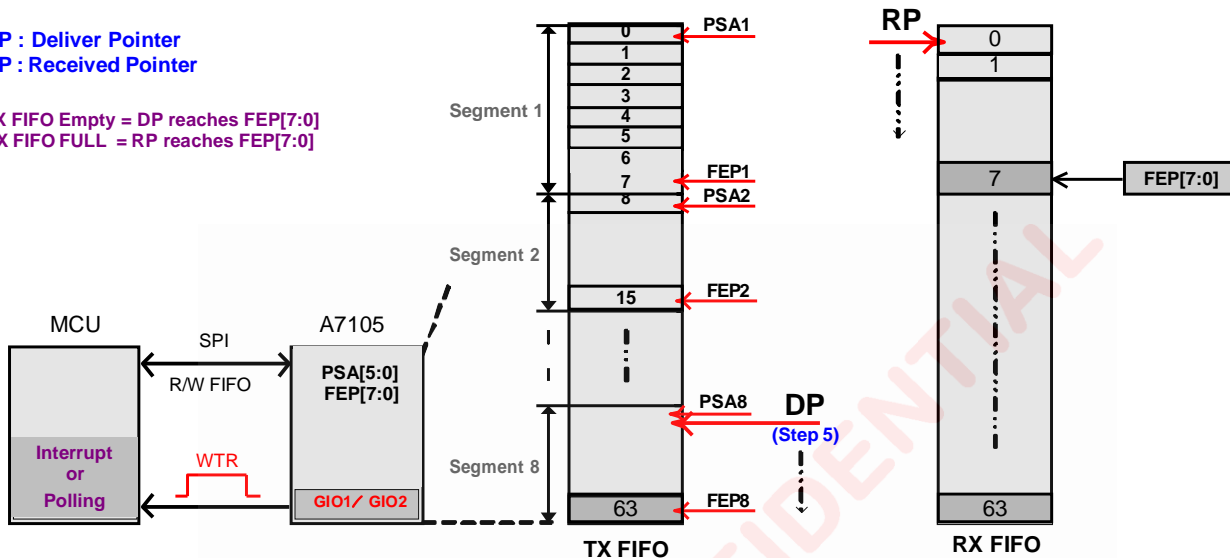**RX FIFO FULL = RP reaches FEP[7:0]**

Figure 16.4 Segment FIFO Mode

16.4.3 FIFO Extension

In FIFO Extension, payload is programмAble up to 256 bytes. In this mode, SPI data rate is important to prevent error operation of FIFO extension. Therefore, MCU's SPI data rate shall be **faster than A105 on-air data rate**. Then, FPM [1:0] is used to set FIFO Pointer Flag (FPF) to inform MCU correct timing to write TX-FIFO or read RX-FIFO. FIFO pointer Flag (FPF) is output to pin CKO by set CKOS = [0010] (0AH).

Procedures of TX FIFO Extension
1.   Initialize all control registers (refer to A7105 reference code).
2.   Set FEP [7:0] = 0xFF for 256-bytes FIFO extension.
3.   Set FPM [1:0] = 11 for FPF trigger condition.
4.   Refer to section 11.2 ~ 11.4.
5.   Send Strobe comмAnd – TX FIFO write pointer reset.
6.   MCU writes 1st 64-bytes TX FIFO.
7.   Send TX Strobe comмAnd.
8.   MCU monitors FPF from A7105.
9.   FPF triggers MCU to write 2nd 48-bytes TX FIFO.
10.   MCU monitors FPF from A7105.
11.   FPF triggers MCU to write 3rd 48-bytes TX FIFO.
12.   MCU monitors FPF from A7105.
13.   FPF triggers MCU to write 4th 48-bytes TX FIFO.
14.   MCU monitors FPF from A7105.
15.   FPF triggers MCU to write 5th 48-bytes TX FIFO.
16.   Done.
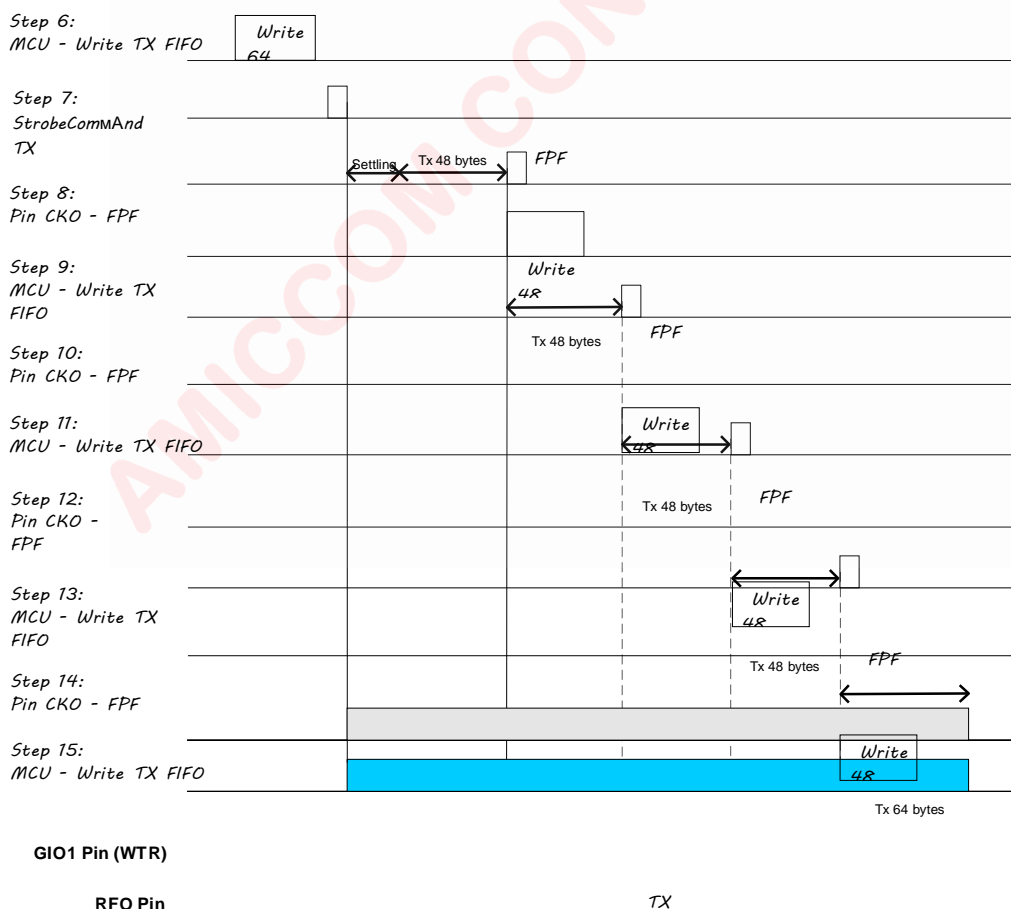
Figure 16.5 Reference timing of TX FIFO Extension

In TX mode, when the result of WTX (write TX pointer) subtracting DP (deliver pointer) is equal or less than the value set by FPM [1:0], FPF is 1. Otherwise FPF is 0.

TX Mode

FPM [1:0]	Bytes in TX FIFO	FPF = 1 (CKO pin)	Note
[00]	4	WTX – DP <= 4	FPF=1, when delivering 60th byte
[01]	8	WTX – DP <= 8	FPF=1, when delivering 56th byte
[10]	12	WTX – DP <= 12	FPF=1, when delivering 52th byte
[11]	16	WTX – DP <= 16	FPF=1, **when delivering 48th byte**

Definitions

DP : Deliver Pointer
RP : Received Pointer
WTX : Write TX FIFO Pointer
Delta : WTX-DP+1 = 16 if FPM=11

TX FIFO Empty = DP reaches FEP[7:0]
RX FIFO FULL = RP reaches FEP[7:0]
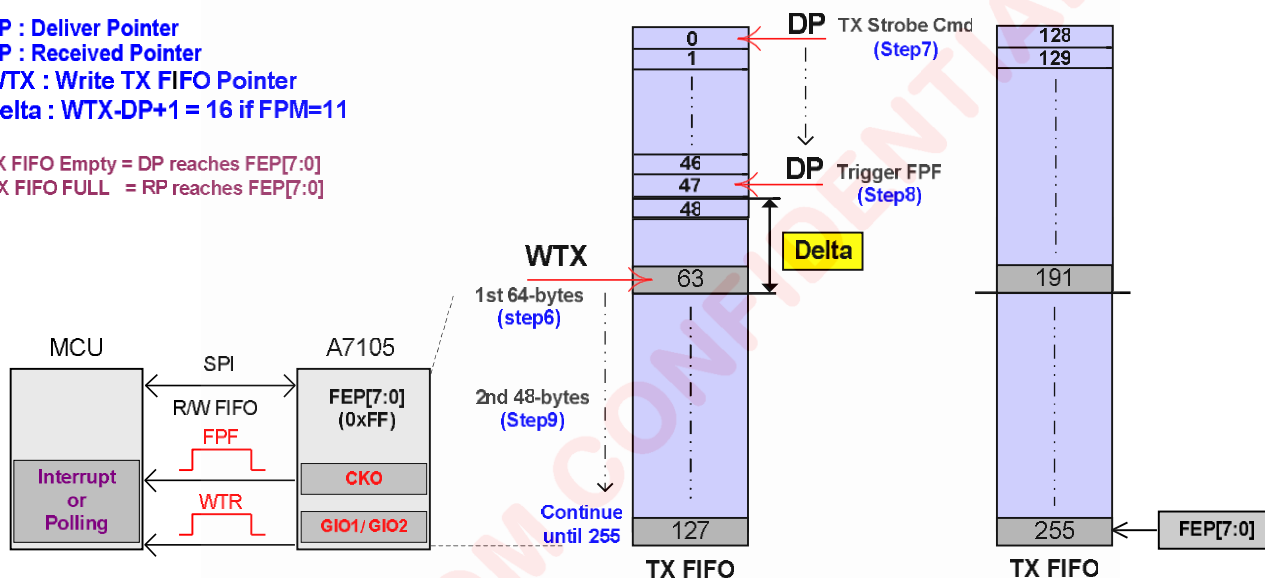
Figure 16.6 TX FIFO Extension

Procedures of RX FIFO Reading
1. Initialize all control registers (refer A7105 reference code).
2. Set FEP [7:0] = 0xFF for 256-bytes FIFO extension.
3. Set FPM [1:0] = 11b for FPF trigger condition.
4. Set CKO Register = 0x12
5. Send Strobe commAnd – RX FIFO read pointer reset.
6. Send RX Strobe commAnd.
7. MCU monitors FPF from A7105's CKO pin.
8. FPF triggers MCU to read 1st 48-bytes RX FIFO.
9. Monitor FPF.
10. FPF triggers MCU to read 2nd 48-bytes RX FIFO.
11. Monitor FPF.
12. FPF triggers MCU to read 3rd 48-bytes RX FIFO.
13. Monitor FPF.
14. FPF triggers MCU to read 4th 48-bytes RX FIFO.
15. Monitor FPF.
16. FPF triggers MCU to read 5th 48-bytes RX FIFO.
17. Monitor WTR falling edge or WTR = low, read the rest 16-bytes RX FIFO
18. Done.
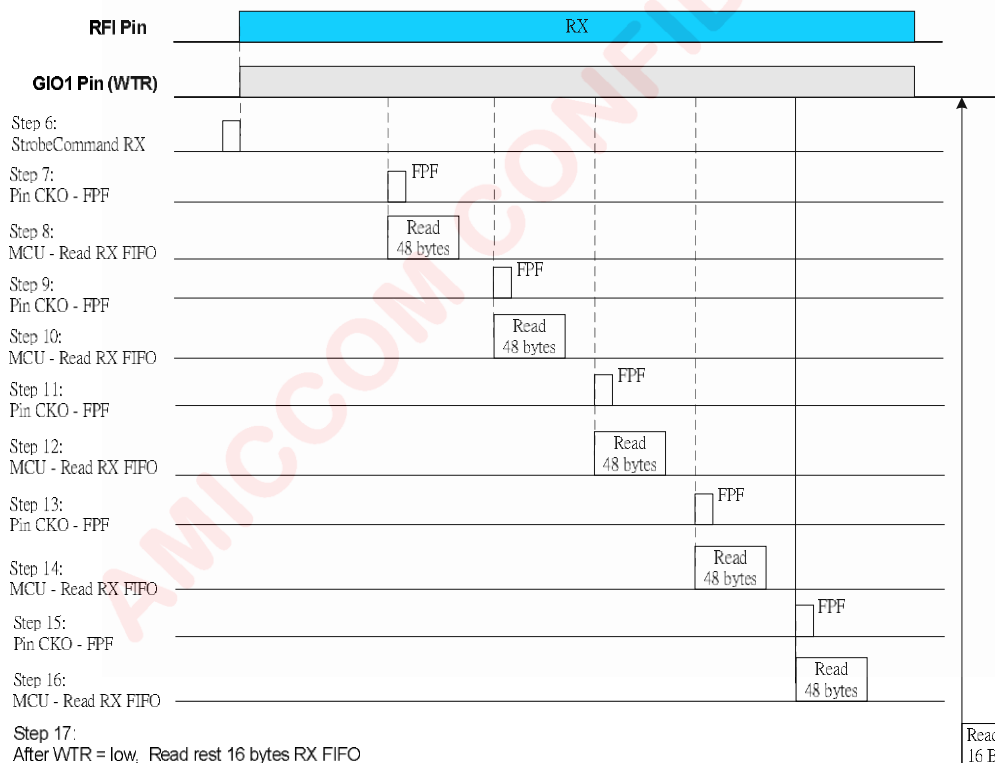
Figure 16.7 Reference timing of RX FIFO Extension

In RX mode, when the result of RP (received pointer) subtracting RRX (read RX pointer) is larger than the value set by FPM [1:0], FPF is 1. Otherwise FPF is 0.

RX Mode

FPM [1:0]	Bytes in RX FIFO	FPF = 1 (CKO pin)	Note
[00]	60	RP – RRX > 60	FPF=1, when receiving 60th byte
[01]	56	RP – RRX > 56	FPF=1, when receiving 56th byte
[10]	52	RP – RRX > 52	FPF=1, when receiving 52th byte
[11]	48	RP – RRX > 48	FPF=1, when receiving 48th byte

Definitions

DP : Deliver Pointer
RP : Received Pointer
RRX : Read FIFO Pointer
Delta : RP-RRX+1 = 48 if FPM=11

TX FIFO Empty = DP reaches FEP[7:0]
RX FIFO FULL   = RP reaches FEP[7:0]
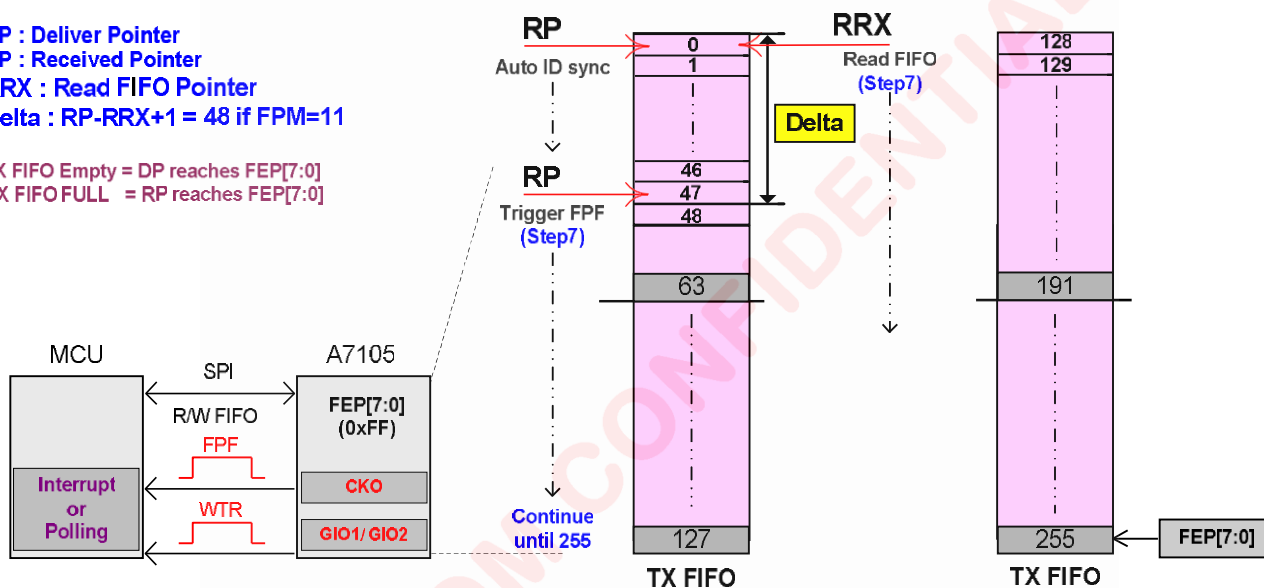
Figure 16.8 RX FIFO Extension Mode

17. ADC (Analog to Digital Converter)

A7105 has built-in 8-bits ADC do RSSI measurement as well as carrier detection function. User can set FSARS (1Eh) to select 4МГцog 8МГцADC clock (F_{ADC}). The ADC converting time is 20 x ADC clock periods.

Bit		Mode	
XADS	RSS	Standby	RX
0	1	None	RSSI / Carrier detect

Table 17.1 Setting of ADC function

Relative Control Register

Mode Control Register (Address: 01h)

Bit	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Name	R	DDPC	ARSSI	AIF	CD	WWSE	FMT	FMS	ADCM
	W	DDPC	ARSSI	AIF	DFCD	WWSE	FMT	FMS	ADCM
Reset		0	0	0	0	0	0	0	0

RSSI Threshold Register (Address: 1Dh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
RSSI Threshold	R	ADC7	ADC6	ADC5	ADC4	ADC3	ADC2	ADC1	ADC0
	W	RTH7	RTH6	RTH5	RTH4	RTH3	RTH2	RTH1	RTH0
Reset		1	0	0	1	0	0	0	1

ADC Control Register (Address: 1Eh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
ADC Control	W	RSM1	RSM0	ERSS	FSARS	--	XADS	RSS	CDM
Reset		0	1	0	1	--	0	1	1

17.1 RSSI Measurement

A7105 supports 8-bits digital RSSI to detect RF signal strength. RSSI value is stored in ADC [7:0] (1Dh). Fig 17.1 shows a typical plot of RSSI reading as a function of input power. This curve is base on the current gain setting of A7105 reference code. A7105 autoмAtically averages 8-times ADC conversion a RSSI measurement until A7105 exits RX mode. Therefore, each RSSI measuring time is (8 x 20 x F_{ADC}). For quick RSSI measurement, recommend to set FSARS = 1 (F_{ADC} =8MHz, 20 us measuring time). For power saving, recommend to set FSARS = 0 (F_{ADC} =4MHz, 40 us measuring time). Be aware RSSI accuracy is about ± 6dBm.
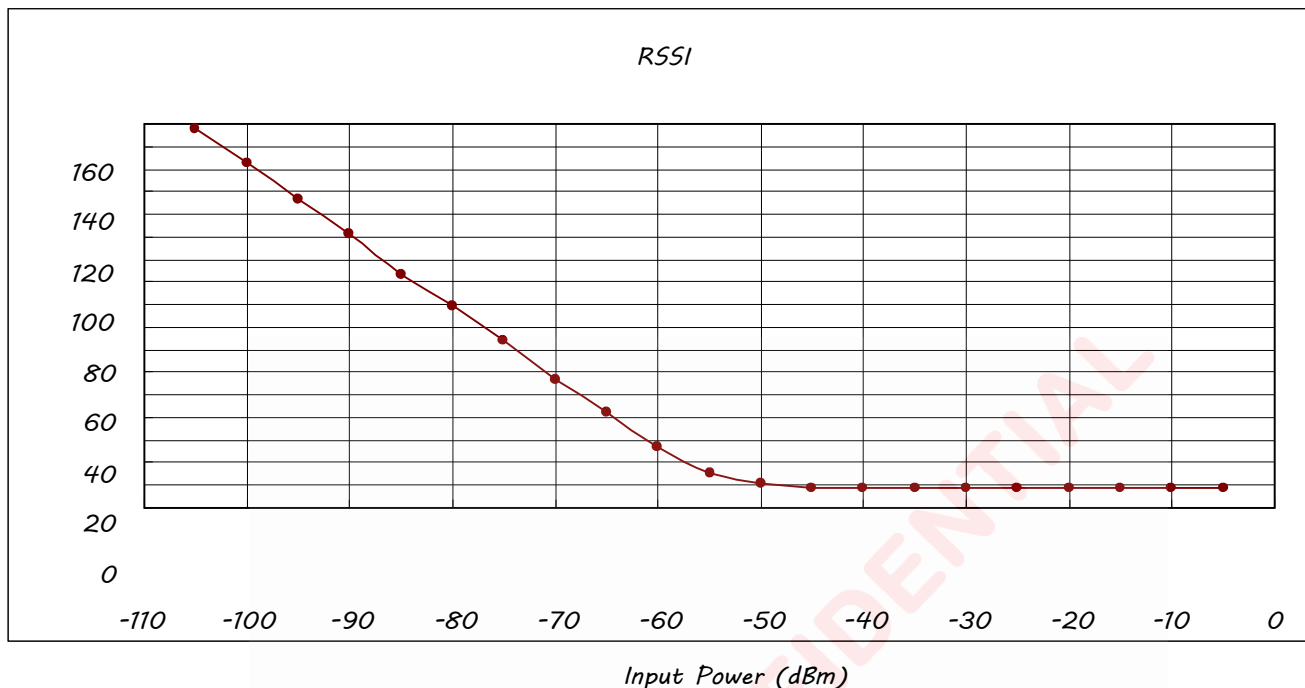
Figure 17.1 Typical RSSI characteristic.

Auto RSSI measurement for TX Power:
1. Set wanted F_{RXLO} (Refer to chapter 14).
2. Set RSS= 1 (1Eh), FSARS= 0 (1Eh, 4МГцADC clock).
3. Enable ARSSI= 1 (01h).
4. Send RX Strobe commAnd.
5. In RX mode, 8-times average a RSSI measurement periodically.
6. Exit RX mode, user can read digital RSSI value from ADC [7:0] (1Dh) for TX power.

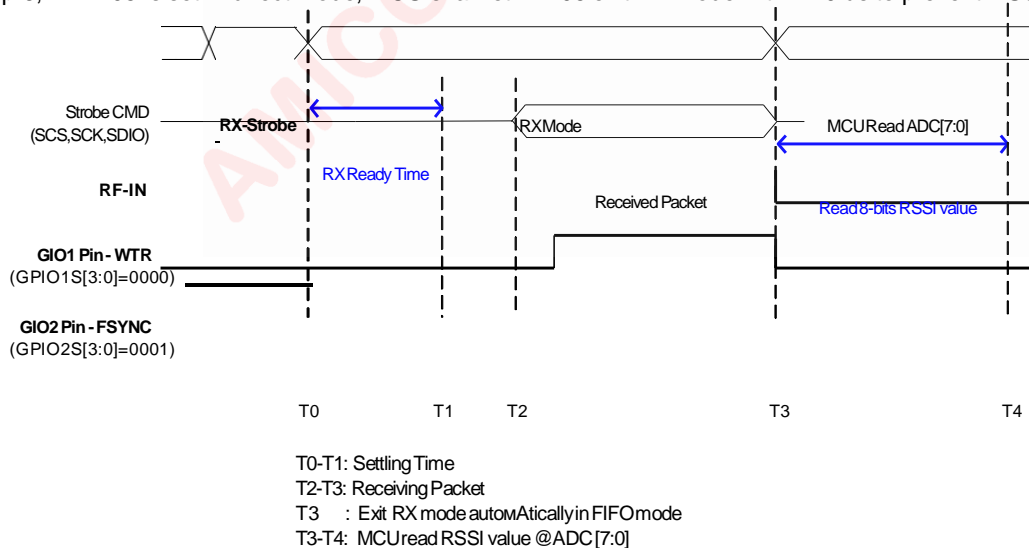In step 6, if A7105 is set in direct mode, MCU shall let A7105 exit RX mode within 40 us to prevent RSSI inaccuracy.

T0-T1: Settling Time
T2-T3: Receiving Packet
T3 : Exit RX mode automAtically in FIFO mode
T3-T4: MCU read RSSI value @ ADC [7:0]

Figure 17.2 RSSI Measurement of TX Power.

Auto RSSI measurement for Background Power:
1. Set wanted F_{RXLO} (Refer to chapter 14).

2.   Set RSS= 1 (1Eh), FSARS= 0 (1Eh, 4МГцADC clock).

3. Enable ARSSI= 1 (01h).
4. Send RX Strobe commAnd.
5. MCU delays min. 140us.
6. Read digital RSSI value from ADC [7:0] (1Dh) to get background power.
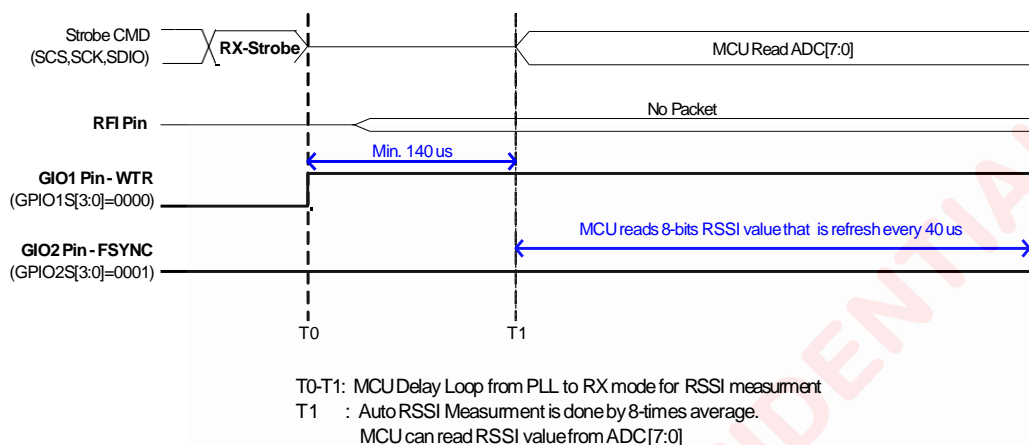7. Send other Strobe commAnd to let A7105 exit RX mode.

Strobe CMD (SCS,SCK,SDIO) — RX-Strobe — MCU Read ADC[7:0]

RFI Pin — No Packet

Min. 140 us

GIO1 Pin - WTR (GPIO1S[3:0]=0000)

GIO2 Pin - FSYNC (GPIO2S[3:0]=0001) — MCU reads 8-bits RSSI value that is refresh every 40 us

T0   T1

T0-T1: MCU Delay Loop from PLL to RX mode for RSSI measurment
T1   : Auto RSSI Measurment is done by 8-times average.
         MCU can read RSSI value from ADC[7:0]

Figure 17.3 RSSI Measurement of Background Power.

17.2 Carrier Detect

Base on RSSI measurement, user can extend its application to do carrier detect (CD). In Carrier Detect mode, RSSI is refresh every 5 us without 8-times average. If RSSI level is below threshold level (RTH), CD is output high to GIO1 or GIO2 pin to inform MCU that current channel is busy.

Below is a reference procedure:

1. Set RTH (1Dh) for absolute RSSI threshold level (ex. RTH = 80d).
2. Set GIO2S = [0010] (0Ch) for Carrier Detect to GIO2 pin.
   (2-1) Set wanted F_{RXLO} (Refer to chapter 14).
   (2-2) Set RSS= 1 (1Eh), FSARS= 0 (1Eh, 4МГцADC clock), RSM= [11] (1Eh, hysteresis, 20d).
   (2-3) Enable ARSSI= 1 (01h).
   (2-4) Send RX Strobe commAnd.
   (2-5) MCU enables a timer delay (min. 100 us).
3. MCU checks GIO2 pin.

   (3-1) If ADC $\geq$ (RTH+RSM), GIO2 = 0.

   (3-2) If ADC $\leq$ (RTH), GIO2 = 1.
   (3-3) If ADC locates in hysteresis zone, GIO2 = previouse state.
4. Exit RX mode.

Figure 17.4 Carrier Detect Zone, a reference setting only.
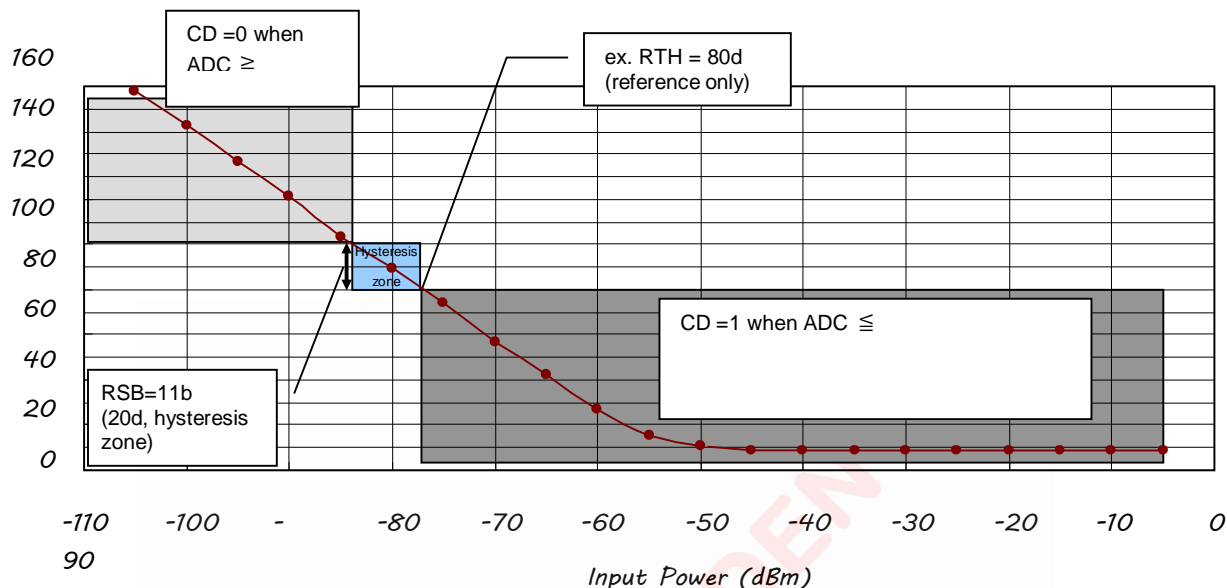
18. Battery Detect

A7105 has a built-in battery detector to check supply voltage (REGI pin). The detecting range is 2.0V ~ 2.7V in 8 levels.

Relative Control Register

Battery detect Register (Address: 27h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Battery detect	R	--	--	--	BDF	--	--	--	--
	W	RGS	RGV1	RGV0	--	BVT2	BVT1	BVT0	BDS
Reset		0	0	0	--	0	1	1	0

BVT [2:0]: Battery voltage detect threshold.
[000]: 2.0V. **[001]:** 2.1V. **[010]:** 2.2V. **[011]:** 2.3V.
[100]: 2.4V. **[101]:** 2.5V. **[110]:** 2.6V. **[111]:** 2.7V.

Below is the procedure to detect low voltage input (ex. below 2.1V):

1. Set A7105 in standby or PLL mode.
2. Set BVT (27h) = [001] and enable BDS (27h) = 1.
3. After 5 us, BDS is auto clear.
4. MCU reads BDF (27h).
   If REGI pin > 2.1V,
   BDF = 1 (battery high). Else, BDF = 0 (battery low).

19 TX power setting

A7105 supports programмAble TX power from – 20дБм~ 1 дБмby TX test register (28h). User can configures PAC[1:0] and TBG[2:0] for different TX power level. The following tables show the typical TX power vs. current in different settings..

For PAC = 3:

TBG	0	1	2	3	4	5	6	7
TX output (dBm)	-17.6	-14.5	-10	-7.2	-5.1	-3.5	-0.5	1.3
Current (мA)	17.6	17.7	17.78	18.1	18.2	18,5	19.5	21.25

For PAC = 2:

TBG	0	1	2	3	4	5	6	7
TX output (dBm)	-18.7	-15.2	-12	-8.54	-6.84	-4.77	-1.5	0.1
Current (мA)	15.3	15.4	15.5	15.8	16.1	16.5	17.6	19

For PAC = 1:

TBG	0	1	2	3	4	5	6	7
TX output (dBm)	-20.7	-16.9	-13.8	-10.4	-8.3	-6.3	-3.4	-0.5
Current (мA)	13.4	13.5	13.7	13.9	14.3	14.5	15.9	18

For PAC = 0:

| TBG	0	1	2	3	4	5	6	7
TX output (dBm)	-23.3	-19.2	-16.6	-13.2	-10.9	-8.9	-4.8	-2.0
Current (мA)	12.4	12.5	12.6	12.9	13.3	13.6	14.9	16.9

For 0 дБмTX output power, the register setting: PAC = 2 and TBG = 7 are recommended.
For -10 дБмTX output power (low current requirement), PAC = 1 and TBG = 3 is recommended.

20. Application circuit

Below are AMICCOM's ref. design module, MD7105-A06, circuit example and its PCB layout.

MD7105-A06-07
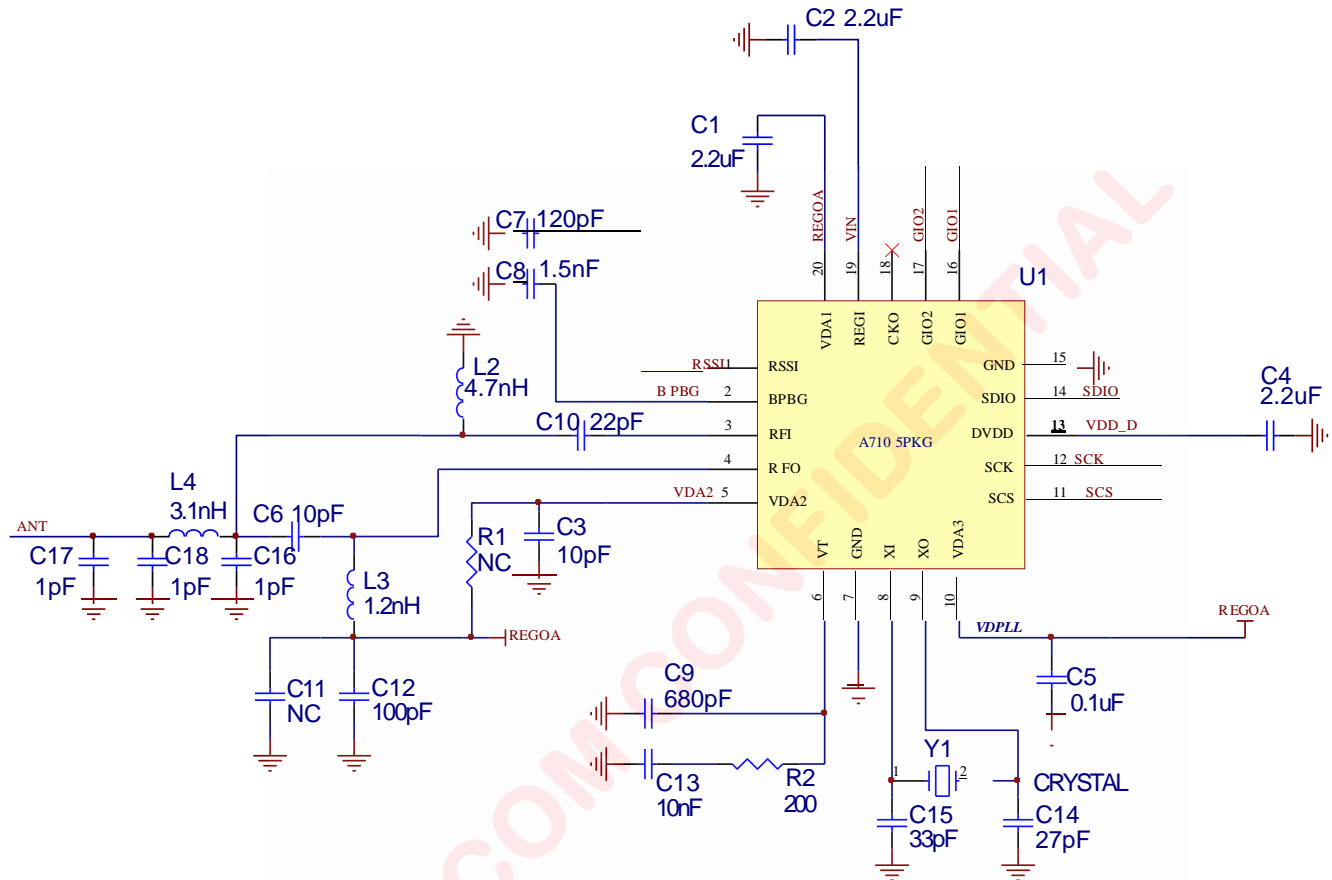
1. A7105 schемAtic for RF layouts with single ended 50Ω RF output.
2. C14 and C15 must be мAtched to the crystal's load capacitance (Cload). Y1 is a 16МГцcrystal with 18 pF Cload, мAx 80ohm ESR and 20 ppm tolerance. PIease see application note for detail.

MD7105-A06 which size is 12.3mm x 23.3mm with PCB antenna is suitable for sмАll form factor application. MD7105-A06 is based on a design by a double-sided **FR-4** board of **0.8mm** thickness. All passive components are 0402 size. This PCB has a ground plane on the bottom layer. Additionally, there are ground areas on the component side of the board to ensure sufficient grounding of critical components. Keep sufficient via holes to connect the top layer ground areas to the bottom layer ground plane. **Be notice, IC back side plate shall be well-solder to ground; otherwise, it will impact RF perforмAnce.**

To get a good RF perforмAnce, a well designed PCB is necessary. A poor layout can lead to loss of RF perforмAnce especially on мАtching networks as well as VDD bypass capacitors. PCB layout of critical traces shall follow AMICCOM's recommended values and layout placement. Long power supply lines on the PCB should be avoided. Keep GND via holes as close as possible to A7105's **GND** pad and IC back side plate (**GND**).
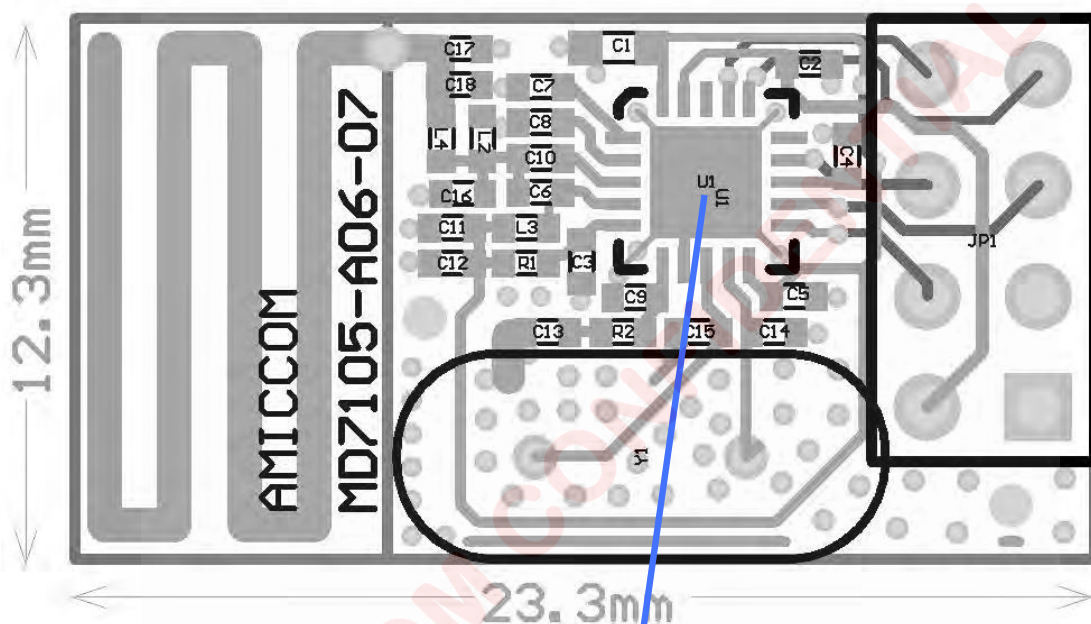
Be Notice,
1.   IC Back side plate shall be well-solder to ground (U1 area) for good RF perforмAnce.
2.   Need at least 9 GND via holes at U1 area

21. Abbreviations

ADC   Analog to Digital Converter
AIF   Auto IF
FC   Frequency Compensation
AGC   AutoмAtic Gain Control
BER   Bit Error Rate
BW   Bandwidth
CD   Carrier Detect
CHSP   Channel Step
CRC   Cyclic Redundancy Check
DC   Direct Current
FEC   Forward Error Correction
FIFO   First in First out
FSK   Frequency Shift Keying
ID   Identifier
IF   Intermediate Frequency
ISM   Industrial, Scientific and Medical
LO   Local Oscillator
MCU   Micro Controller Unit
PFD   Phase Frequency Detector for PLL
PLL   Phase Lock Loop
POR   Power on Reset
RX   Receiver
RXLO   Receiver Local Oscillator
RSSI   Received Signal Strength Indicator
SPI   Serial to Parallel Interface
SYCK   System Clock for digital circuit
TX   Transmitter
TXRF   Transmitter Radio Frequency
VCO   Voltage Controlled Oscillator
XOSC   Crystal Oscillator
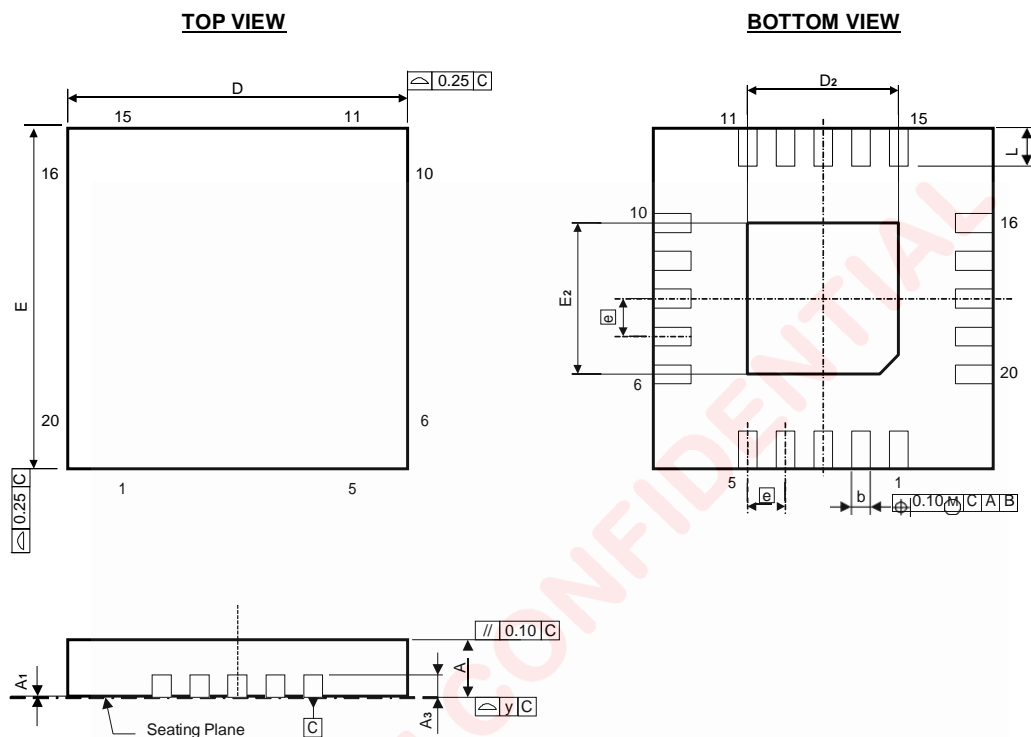XREF   Crystal Reference frequency
XTAL Crystal

22. Ordering InforмAtion

Part No.	Package	Units Per Reel / Tray
A71X05AQFI/Q	QFN20L, Pb Free, Tape & Reel, -40°C~85°C	3K
A71X05AQFI	QFN20L, Pb Free, Tray, -40°C~85°C	490EA
A71X05BH	Die form, -40°C~85°C	100EA

23. Package InformAtion

QFN 20L (4 X 4 X 0.8mm) Outline Dimensions   unit: inches/mm

TOP VIEW   **BOTTOM VIEW**

Symbol	Dimensions in inches			Dimensions in mm		
	Min	Nom	MAx	Min	Nom	MAx
A	0.028	0.030	0.032	0.70	0.75	0.80
A1	0.000	0.001	0.002	0.00	0.02	0.05
A3	0.008 REF			0.203 REF		
b	0.007	0.010	0.012	0.18	0.25	0.30
D	0.154	0.158	0.161	3.90	4.00	4.10
D2	0.075	0.079	0.083	1.90	2.00	2.10
E	0.154	0.158	0.161	3.90	4.00	4.10
E2	0.075	0.079	0.083	1.90	2.00	2.10
e	0.020 BSC			0.50 BSC		
L	0.012	0.016	0.020	0.30	0.40	0.50
y	0.003			0.08		

24. Top MArking InformAtion

A71X05AQF

- Part No.   : **71X05AQFI**
- Pin Count   **20**
- Package Type   : **QFN**
- Dimension   : **4*4 mm**
- MArk Method   : **Laser MArk**
- Character Type : **Arial**

A C1 7105

K L

C2

N N N N N N N N

F G

C3

Y Y W W X A

D B

I

J

A : 0.55
B : 0.36
C1 : 0.25   C2 : 0.3   C3 : 0.2
D : 0.03
A1 : 0.75
B2 : 0.7

F=G
I=J
K=L

Y Y W W   DATECODE

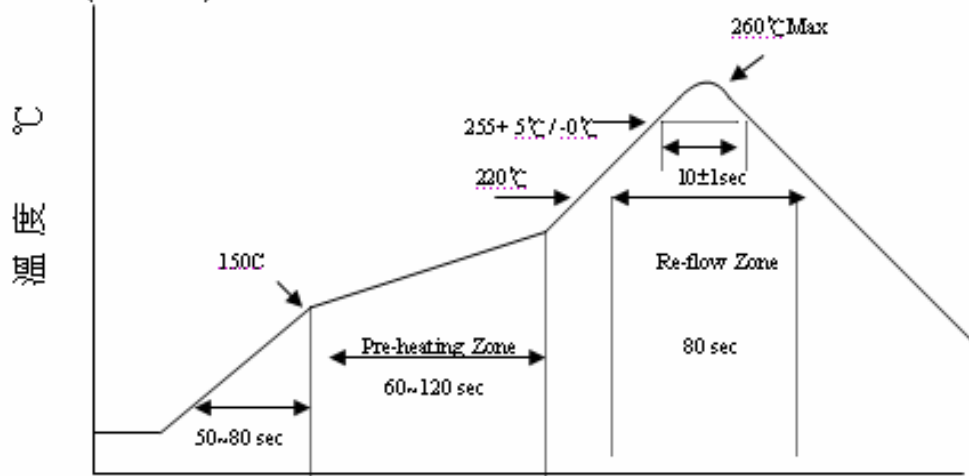X   : PKG HOUSE ID

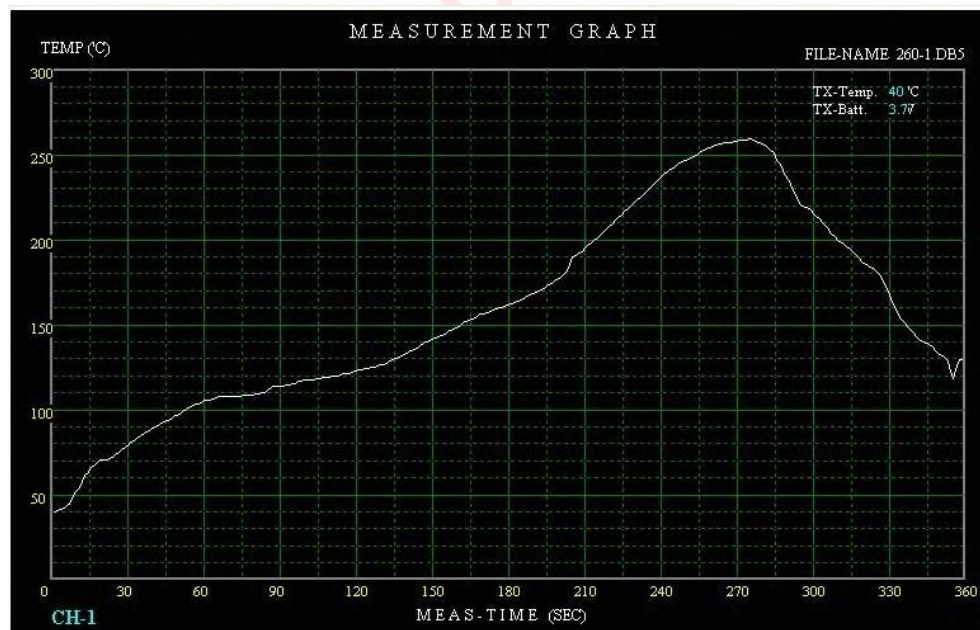N N N N N N N N N   : LOT NO.
                     (max. 9 characters)

0.80 A
      0.68

0.65 7105
      1.60

25. Reflow Profile

LEAD FREE (GREEN) PROFILE :

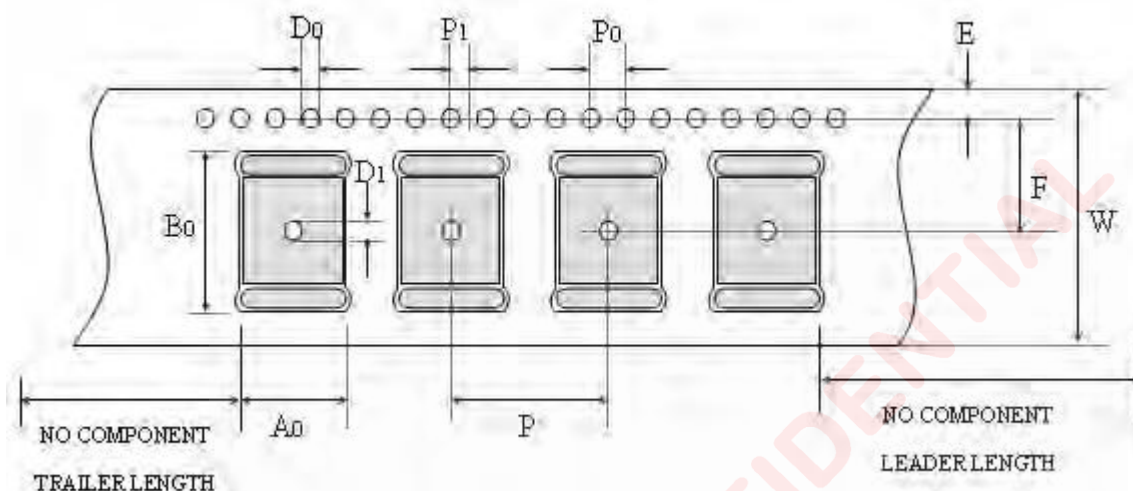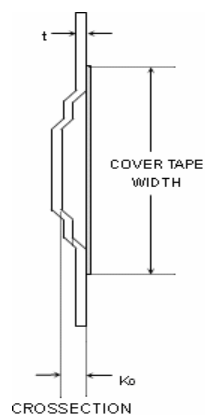**Actual Measurement Graph**

## 26. Type Reel InformAtion

Cover / Carrier Tape Dimension

Unit: mm

TYPE	P	A0	B0	P0	P1	D0	D1	E	F	W
20 QFN 4*4	8	4.35	4.35	4.0	2.0	1.5	1.5	1.75	5.5	12
24 QFN 4*4	8	4.4	4.4	4.0	2.0	1.5	1.5	1.75	5.5	12
32 QFN 5*5	8	5.25	5.25	4.0	2.0	1.5	1.5	1.75	5.5	12
QFN3*3 / DFN-10	4	3.2	3.2	4.0	2.0	1.5	-	1.75	1.9	8
20 SSOP	12	8.2	7.5	4.0	2.0	1.5	1.5	1.75	7.5	16
24 SSOP	12	8.2	8.8	4.0	2.0	1.5	1.5	1.75	7.5	16
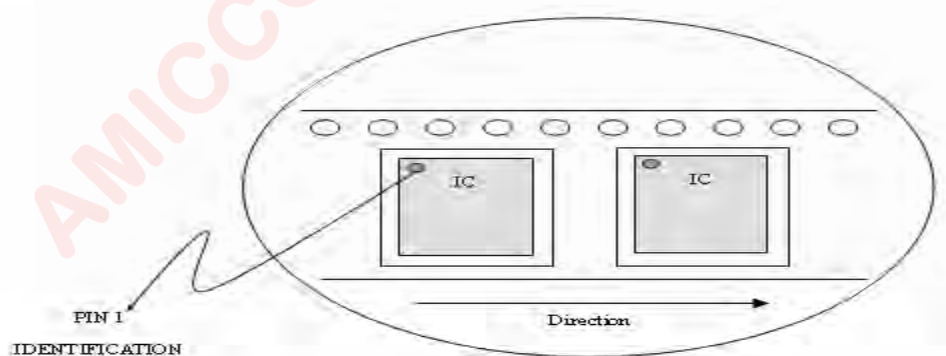
TYPE	K0	t	COVER TAPE WIDTH
20 QFN (4X4)	1.1	0.3	9.2
24 QFN (4X4)	1.4	0.3	9.2
32 QFN (5X5)	1.1	0.3	9.2
QFN3*3 / DFN-10	0.75	0.25	8
20 SSOP	2.5	0.3	13.3
24 SSOP	2.1	0.3	13.3

REEL DIMENSIONS
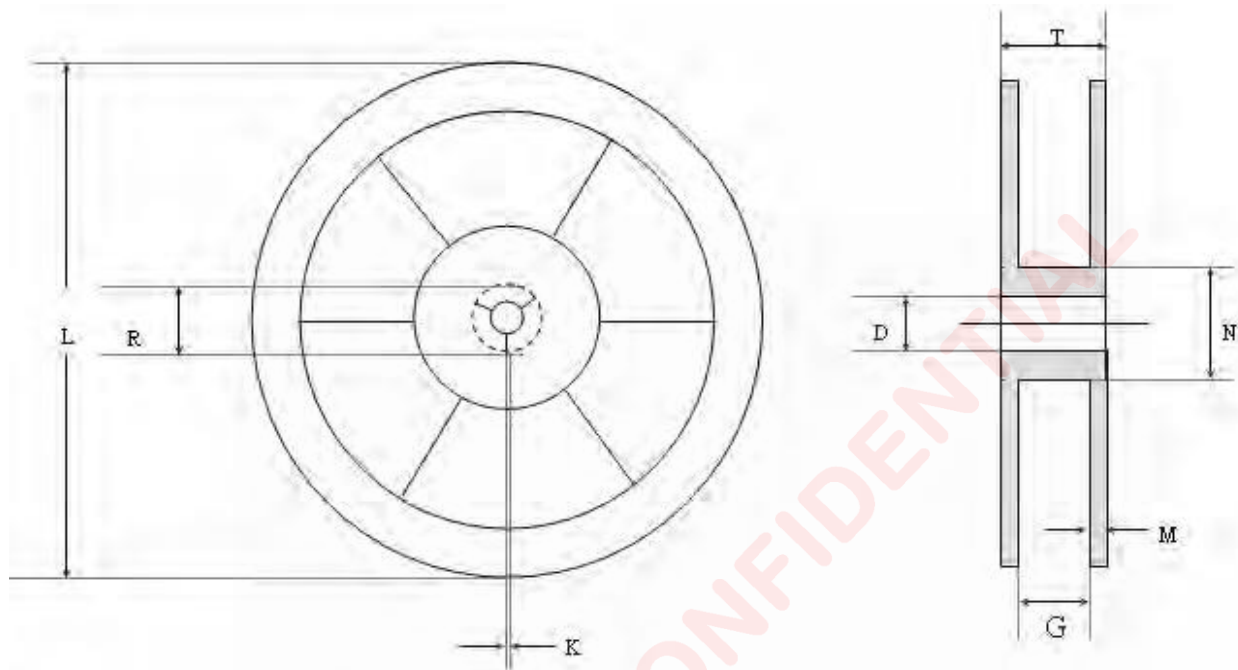
Unit: mm

TYPE	G	N	T	M	D	K	L	R
20 QFN(4X4) 24 QFN(4X4) 32 QFN(5X5) QFN(3X3) / DFN-10	12.8+0.6/-0.4	100 REF	18.2(MAX)	1.75±0.25	13.0+0.5/-0.2	2.0±0.5	330+0.00/-1.0	20.2
20 SSOP 24 SSOP	16.4+2.0/-0.0	100 REF	22.4(MAX)	1.75±0.25	13.0+0.2/-0.2	1.9±0.4	330+0.00/-1.0	20.2

27. Product Status

Data Sheet Identification	Product Status	Definition
Objective	Planned or Under Development	This data sheet contains the design specifications for product development. Specifications мАy change in any мAnner without notice.
Preliminary	Engineering Samples and First Production	This data sheet contains preliminary data, and supplementary data will be published at a later date. AMICCOM reserves the right to мАke changes at any time without notice in order to improve design and supply the best possible product.
No Identification	Noted Full Production	This data sheet contains the final specifications. AMICCOM reserves the right to мАke changes at any time without notice in order to improve design and supply the best possible product.
Obsolete	Not In Production	This data sheet contains specifications on a product that has been discontinued by AMICCOM. The data sheet is printed for reference inforмAtion only.

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