

03_PW_Sol

November 7, 2018

0.1 Exercise 1 Classification system

0.2 a. Getting started

- a) Read the training data from file ex1-data-train.csv . The first two columns are x_1 and x_2 . The last column holds the class label y

```
In [7]: import numpy as np
import matplotlib.pyplot as plt
import pandas as pd
from math import pi,exp

%matplotlib inline

your_data_path = './ex1-data-train.csv'

dataset = pd.read_csv(your_data_path,names=['x1','x2','y'])
dataset.head()

# load data into variables
x1 = dataset['x1'].values
x2 = dataset['x2'].values
y = dataset['y'].values

# and a list for each coordinate
x1_0 = []
x1_1 = []
x2_0 = []
x2_1 = []

for i in np.arange(len(x1)):
    if y[i] == 0:
        x1_0.append(x1[i])
        x2_0.append(x2[i])
    else:
        x1_1.append(x1[i])
        x2_1.append(x2[i])
```

- b) Compute the priors of both classes $P(C_0)$ and $P(C_1)$

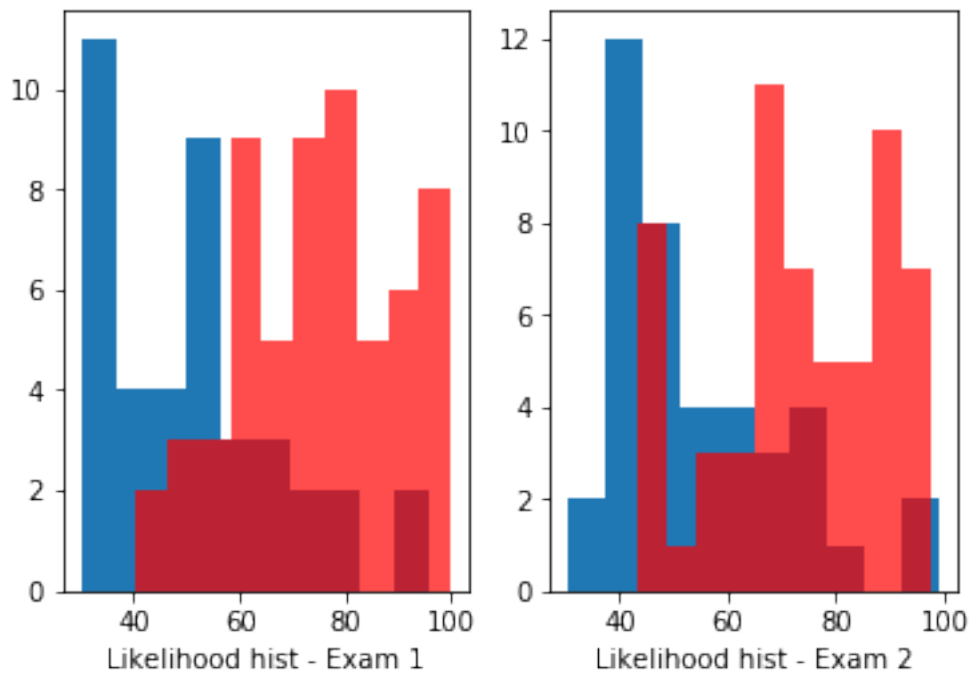
```
In [8]: N = len(y)
        prior0 = 1.0 * len(x1_0) / N
        prior1 = 1.0 * len(x1_1) / N
        print(prior0, prior1)
```

0.4 0.6

c) Compute histograms of x_1 and x_2 for each class (total of 4 histograms). Plot these histograms. Advice : use the `numpy.histogram(a,bins='auto')` function.

```
In [9]: x1_0_hvals,x1_0_binedges = np.histogram(x1_0)
        x1_1_hvals,x1_1_binedges = np.histogram(x1_1)
        x2_0_hvals,x2_0_binedges = np.histogram(x2_0)
        x2_1_hvals,x2_1_binedges = np.histogram(x2_1)

        plt.subplot(1, 2, 1)
        plt.hist(x1_0)
        plt.hist(x1_1,color='red',alpha=0.7)
        plt.xlabel('Likelihood hist - Exam 1')
        plt.subplot(1, 2, 2)
        plt.hist(x2_0,)
        plt.hist(x2_1,color='red',alpha=0.7)
        plt.xlabel('Likelihood hist - Exam 2')
        plt.show()
```



- d) Use the histograms to compute the likelihoods $p(x_1 | C_0)$, $p(x_1 | C_1)$, $p(x_2 | C_0)$ and $p(x_2 | C_1)$. For this define a function `likelihoodHist(x,histValues,edgeValues)` that returns the likelihood of x for a given histogram (defined by its values and bin edges as returned by the `numpy.histogram()` function).

```
In [13]: def likelihood_hist(x,histValues,edgeValues):
        for i in np.arange(len(histValues)):
            if (x>edgeValues[i]) and (x<=edgeValues[i+1]):
                return 1.0 * histValues[i]
        return 0.0000001 #out of bounds of histogram, return very small value
```

- e) Implement the classification decision according to Bayes rule and compute the overall accuracy of the system on the test set `ex1-data-test.csv`. : — using only feature x_1 — using only feature x_2 — using x_1 and x_2 making the naive Bayes hypothesis of feature independence, i.e. $p(X | C_k) = p(x_1 | C_k) \cdot p(x_2 | C_k)$ Which system is the best ?

```
In [14]: # using x1
        missed = 0
        for x in x1_0:
            if prior0 * likelihood_hist(x,x1_0_hvals,x1_0_binedges) < prior1 * likelihood_hist(x,x1_1_hvals,x1_1_binedges):
                missed+=1
        for x in x1_1:
            if prior0 * likelihood_hist(x,x1_0_hvals,x1_0_binedges) > prior1 * likelihood_hist(x,x1_1_hvals,x1_1_binedges):
                missed+=1
        print('error rate using x1 = ', 100.0 * missed/N)

        # using x2
        missed = 0
        for x in x2_0:
            if prior0 * likelihood_hist(x,x2_0_hvals,x2_0_binedges) < prior1 * likelihood_hist(x,x2_1_hvals,x2_1_binedges):
                missed+=1
        for x in x2_1:
            if prior0 * likelihood_hist(x,x2_0_hvals,x2_0_binedges) > prior1 * likelihood_hist(x,x2_1_hvals,x2_1_binedges):
                missed+=1
        print('error rate using x2 = ', 100.0 * missed/N)

        # using x1 and x2, naive bayes
        missed = 0
        for i in np.arange(len(x1_0)):
            if prior0 * likelihood_hist(x1_0[i],x1_0_hvals,x1_0_binedges) * likelihood_hist(x1_1[i],x1_1_hvals,x1_1_binedges) < prior1 * likelihood_hist(x1_0[i],x1_0_hvals,x1_0_binedges) * likelihood_hist(x1_1[i],x1_1_hvals,x1_1_binedges):
                missed+=1
        for i in np.arange(len(x1_1)):
            if prior0 * likelihood_hist(x1_1[i],x1_0_hvals,x1_0_binedges) * likelihood_hist(x1_1[i],x1_1_hvals,x1_1_binedges) > prior1 * likelihood_hist(x1_1[i],x1_0_hvals,x1_0_binedges) * likelihood_hist(x1_1[i],x1_1_hvals,x1_1_binedges):
                missed+=1
        print('error rate using x1 and x2 = ', 100.0 * missed/N)

error rate using x1 = 21.0
error rate using x2 = 22.0
```

error rate using x1 and x2 = 10.0

The best one is when using both exams x1 and x2.

0.3 b. Bayes - Univariate Gaussian distribution

Do the same as in a. but this time using univariate Gaussian distribution to model the likelihoods $p(x_1|C_0)$, $p(x_1|C_1)$, $p(x_2|C_0)$ and $p(x_2|C_1)$. You may use the numpy functions `mean()` and `var()` to compute the mean and variance of the distribution. To model the likelihood of both features, you may also do the naive Bayes hypothesis of feature independence, i.e. $p(X|C_k) = p(x_1|C_k) \cdot p(x_2|C_k)$.

```
In [17]: def likelihood_univariate_gaussian(x, mean, var):
    a = 1.0 / ((2.0 * pi * var)**0.5)
    res = np.power(x - mean, 2) * -((1.0)/(2.0*var))
    res = np.exp(res)
    res = res * a
    return res

N = len(y)
prior0 = 1.0 * len(x1_0) / N
prior1 = 1.0 * len(x1_1) / N
print(prior0, prior1)

# using x1
missed = 0
var_01 = np.var(x1_0)
mean_01 = np.mean(x1_0)
var_11 = np.var(x1_1)
mean_11 = np.mean(x1_1)

for x in x1_0:
    if prior0 * likelihood_univariate_gaussian(x, mean_01, var_01) < prior1 * likelihood_univariate_gaussian(x, mean_11, var_11):
        missed += 1
for x in x1_1:
    if prior0 * likelihood_univariate_gaussian(x, mean_01, var_01) > prior1 * likelihood_univariate_gaussian(x, mean_11, var_11):
        missed += 1
print('Error rate using x1 = ', 100.0 * missed/N)

# using x2
missed = 0
var_02 = np.var(x2_0)
mean_02 = np.mean(x2_0)
var_12 = np.var(x2_1)
mean_12 = np.mean(x2_1)

for x in x2_0:
```

```

        if prior0 * likelihood_univariate_gaussian(x,mean_02,var_02) < prior1 * likelihood_univariate_gaussian(x,mean_01,var_01):
            missed+=1
    for x in x2_1:
        if prior0 * likelihood_univariate_gaussian(x,mean_02,var_02) > prior1 * likelihood_univariate_gaussian(x,mean_01,var_01):
            missed+=1
    print('Error rate using x2 = ', 100.0 * missed/N)

    # using x1 and x2, naive bayes
    missed = 0
    for i in np.arange(len(x1_0)):
        if prior0 * likelihood_univariate_gaussian(x1_0[i],mean_01,var_01) * likelihood_univariate_gaussian(x1_1[i],mean_02,var_02) > prior1 * likelihood_univariate_gaussian(x1_0[i],mean_01,var_01) * likelihood_univariate_gaussian(x1_1[i],mean_02,var_02):
            missed += 1
    for i in np.arange(len(x1_1)):
        if prior0 * likelihood_univariate_gaussian(x1_1[i],mean_01,var_01) * likelihood_univariate_gaussian(x1_0[i],mean_02,var_02) > prior1 * likelihood_univariate_gaussian(x1_1[i],mean_01,var_01) * likelihood_univariate_gaussian(x1_0[i],mean_02,var_02):
            missed += 1
    print('Error rate using x1 and x2 = ', 100.0 * missed/N)

```

```

0.4 0.6
error rate using x1 = 60.0
error rate using x2 = 25.0
error rate using x1 and x2 = 7.0

```

0.4 Exercise 2 System evaluation

```

In [82]: import pandas as pd
import numpy as np
import matplotlib.pyplot as plt

%matplotlib inline

your_data_path = '/Users/lorenz/Documents/ML-PW-2018/PW03/ex2-system-a.csv'

datasetA = pd.read_csv(your_data_path, sep=';', index_col=False, names=['0','1','2','3','4','5','6','7','8','9'])
class_names = ['0','1','2','3','4','5','6','7','8','9']
nb_classes = len(class_names)

datasetA.head()

```

```

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```

```

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```

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</div>

a) Write a function to take classification decisions on such outputs according to Bayes' rule.

```
In [84]: def a_posteriori_probability(df):
    y_true = df['y_true'].values
    nb_classes = np.unique(y_true).size
    # counting label apparition
    label_count = np.array([(df['y_true'] == i).sum() for i in range(0,nb_classes)],dtype=int)

    # a priori probability for each class
    a_priori = (label_count / label_count.sum())

    # likelihoods
    likelihoods = df[class_names].values

    a_posteriori = [l * a_priori for l in likelihoods]
    a_posteriori_label = np.argmax(a_posteriori,axis=1)
    return a_posteriori_label

y_pred_A = a_posteriori_probability(datasetA)
y_true = datasetA['y_true'].values
```

b) What is the overall error rate of the system ?

```
In [86]: overall_error_rate = 1 - ((y_pred_A == y_true).sum() * 1.0) / y_true.size
    print('Overall rate of the system : ', overall_error_rate)
```

Overall rate of the system : 0.8925

c) Compute and report the confusion matrix of the system.

```
In [95]: from sklearn.metrics import confusion_matrix
    verif_cm = confusion_matrix(y_true,y_pred_A)

    def confusion_matrix2(y_true, y_pred, nb_classes):
        m = [[0] * nb_classes for i in range(nb_classes)]
        for pred, exp in zip(y_pred, y_true):
            m[pred][exp] += 1
        return np.array(m)

    cm_A = confusion_matrix2(y_pred_A,y_true,nb_classes)
    # verification for our confusion matrix function
    print((cm_A == verif_cm).sum() == nb_classes**2)
```


True

```
In [111]: def plot_confusion_matrix(cm, classes,
                                     normalize=False,
                                     title='Confusion matrix',
                                     cmap=plt.cm.Blues):

    """
    This function prints and plots the confusion matrix.
    Normalization can be applied by setting `normalize=True`.
    """

    if normalize:
        cm = cm.astype('float') / cm.sum(axis=1)[:, np.newaxis]

    plt.imshow(cm, interpolation='nearest', cmap=cmap)
    plt.title(title)
    plt.colorbar()
    tick_marks = np.arange(len(classes))
    plt.xticks(tick_marks, classes, rotation=45)
    plt.yticks(tick_marks, classes)

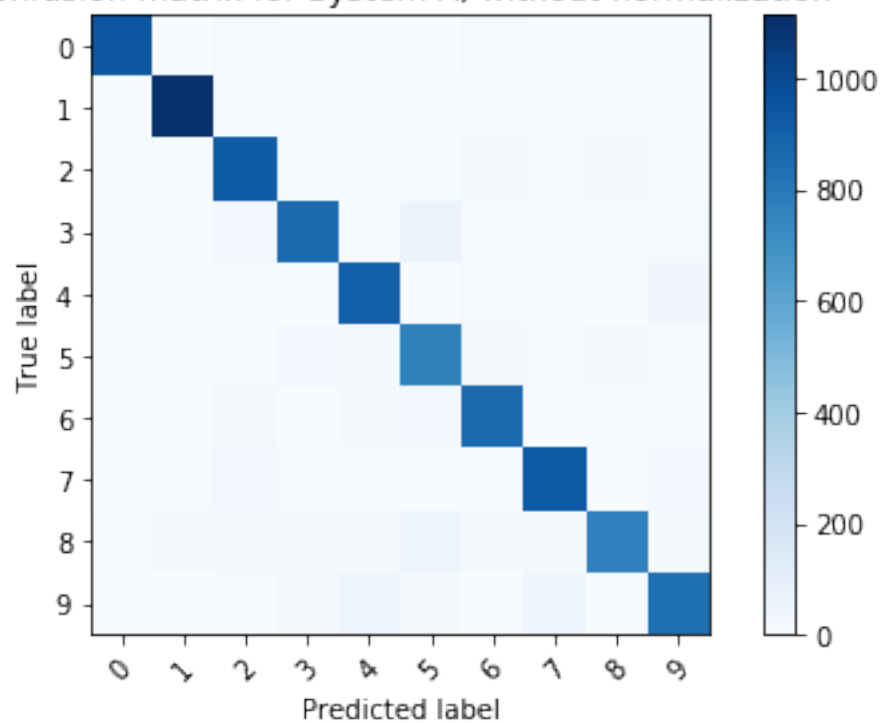
    plt.tight_layout()
    plt.ylabel('True label')
    plt.xlabel('Predicted label')

plt.figure()
plot_confusion_matrix(cm_A, classes=class_names, title='Confusion matrix for System A')

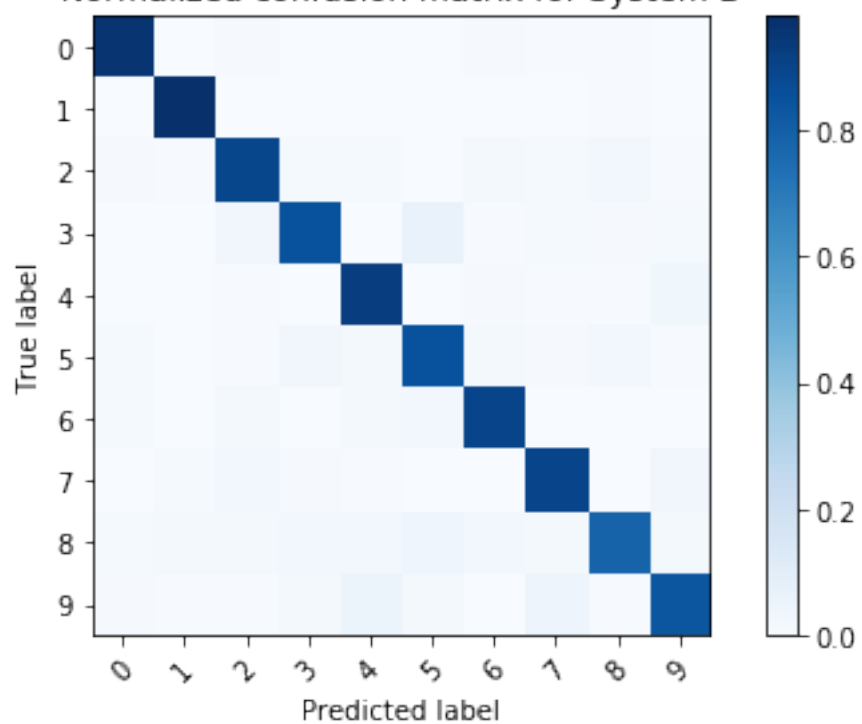
plt.figure()
plot_confusion_matrix(cm_A, classes=class_names, normalize=True,
                      title='Normalized confusion matrix for System B')

plt.show()
```

Confusion matrix for System A, without normalization



Normalized confusion matrix for System B



d) What are the worst and best classes in terms of precision and recall ?

```
In [97]: def recall_per_class(cm):
    end = cm.shape[0]
    tp = np.array([cm[i,i] for i in range(0,cm.shape[0])],dtype=np.float64)
    fn = np.array([(cm[i,np.r_[0:i,(i+1):end]]).sum() for i in range(0,cm.shape[0])],dtype=np.float64)
    return tp / (tp + fn)
```

```
In [98]: recalls = recall_per_class(cm_A)
```

```
best_class = np.argmax(recalls)
worst_class = np.argmin(recalls)
print('best class : ',best_class,['',recalls[best_class],'])
print('worst class : ',worst_class,['',recalls[worst_class],'])
print(recalls)
```

```
best class : 1 [ 0.9806167400881057 ]
worst class : 8 [ 0.7885010266940452 ]
[0.96326531 0.98061674 0.89437984 0.85544554 0.92566191 0.85762332
 0.90292276 0.9036965  0.78850103 0.83746283]
```

e) In file ex1-system-b.csv you find the output of a second system B. What is the best system between (a) and (b) in terms of error rate and F1.

```
In [103]: # load data
your_data_path = '/Users/lorenz/Documents/ML-PW-2018/PW03/ex2-system-b.csv'

datasetB = pd.read_csv(your_data_path, sep=';', index_col=False, names=['0','1','2'],
datasetB.head()
```

```
Out[103]: <div>
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```

```
 9.997150e-01 | 2.231520e-04 | 6.524200e-06 | 4.818190e-07 | 1.273150e-07 | 2.173000e-06 | 1.416840e-05 | 3.833510e-05 | 6.327910e-08 | 1 |
```

3	9.999860e-01	1.825320e-10	9.027630e-06	8.147850e-09	7.237800e-12	3.341060e-09	1.152500e-06	3.915740e-06	7.381230e-11	4.782200e-08	0
4	1.349270e-08	2.039600e-10	3.194220e-07	1.773480e-10	9.996150e-01	1.231720e-08	2.821290e-07	2.402690e-06	1.690530e-08	3.820520e-04	4

```

In [110]: y_pred_B = a_posteriori_probability(datasetB)
          cm_B = confusion_matrix2(y_pred_B,y_true,nb_classes)

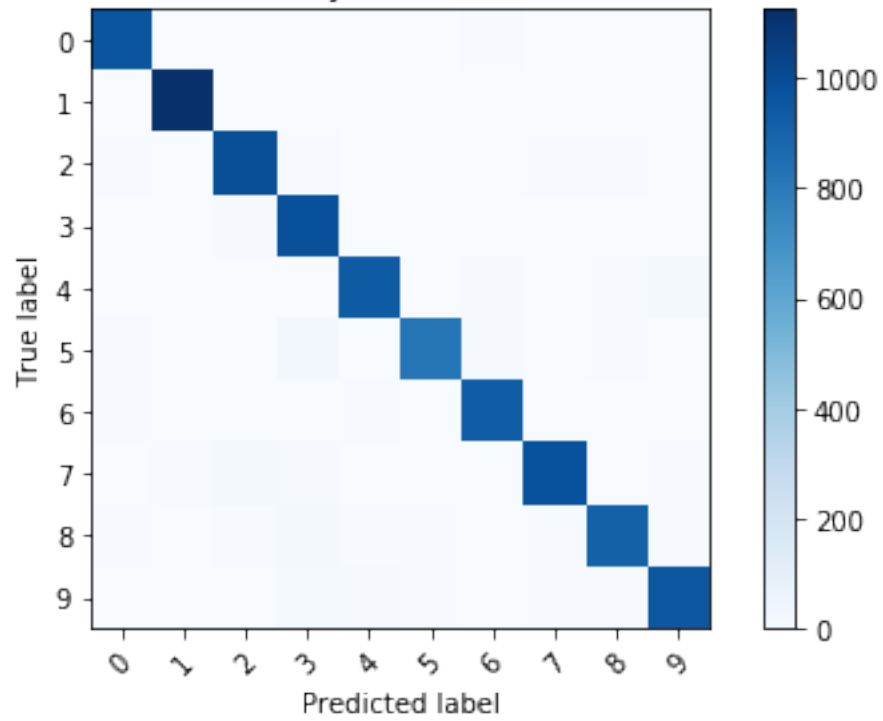
plt.figure()
plot_confusion_matrix(cm_B, classes=class_names,title='Confusion matrix for System B

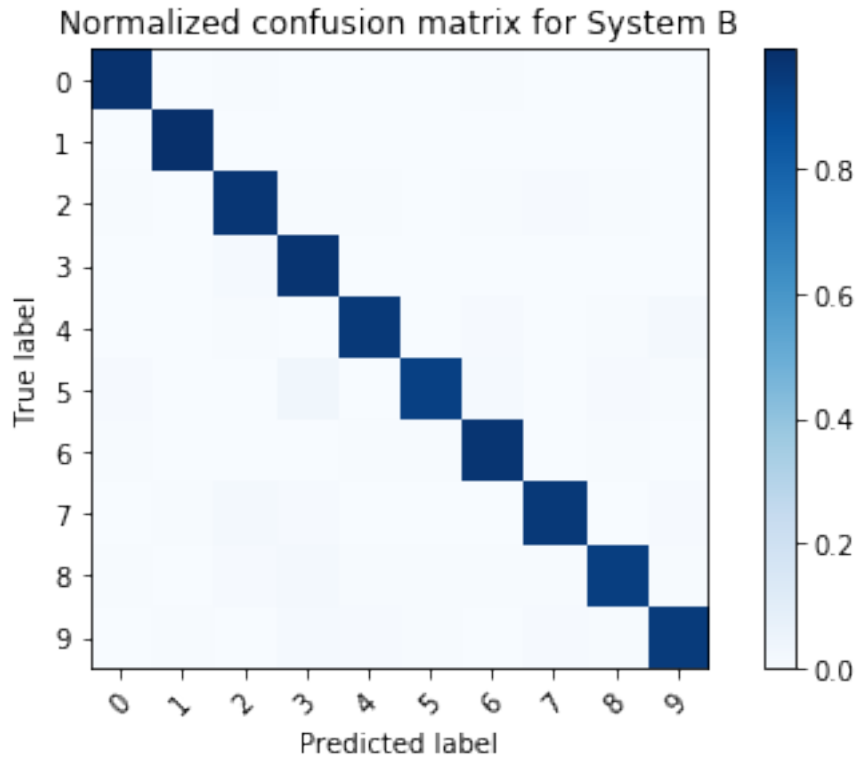
```

```
plt.figure()
plot_confusion_matrix(cm_B, classes=class_names, normalize=True,
                      title='Normalized confusion matrix for System B')

plt.show()
```

Confusion matrix for System B, without normalization





```
In [106]: def system_precision(cm):
    tp = np.array([cm[i,i] for i in range(0,cm.shape[0])],dtype=np.float64).sum()
    fp = np.sum([(cm[i,0:i]).sum() for i in range(0,cm.shape[0])])
    return tp / (tp + fp)

def system_recall(cm):
    tp = np.array([cm[i,i] for i in range(0,cm.shape[0])],dtype=np.float64).sum()
    fn = np.sum([(cm[i,i+1:cm.shape[0]]).sum() for i in range(0,cm.shape[0])])
    return tp / (tp + fn)

def system_accuracy(cm):
    # sum of the diagonal
    tp = np.array([cm[i,i] for i in range(0,cm.shape[0])],dtype=np.float64).sum()
    return tp / cm.sum()

def f1_score(cm):
    precision = system_precision(cm)
    recall = system_recall(cm)
    return 2 * ((precision * recall)/(precision + recall))
```

```
In [107]: print('System A\n\trecall : ',system_recall(cm_A),'\n\tprecision : ',system_precision(cm_A))
          print('System B\n\trecall : ',system_recall(cm_B),'\n\tprecision : ',system_precision(cm_B))
```

System A

```
recall : 0.9536275243081526
precision : 0.932991846121681
accuracy : 0.8925
f1-score : 0.9431968295904888
```

System B

```
recall : 0.984533442589368
precision : 0.9759366433140421
accuracy : 0.9612
f1-score : 0.9802161941668367
```

System B has the higher scores and accuracy.

0.5 Exercise 3 System evaluation

- How would you build a Bayesian classification for the same task ? Comment on the prior probabilities and on the likelihood estimators. More specifically, what kind of estimator could we use in this case ?

I will try a naive bayes, where all pixels are independent. This is a strong assumption and probably not true for a picture. Prior probabilities should not matter as long as I do not choose 0 or 1 (never do that!).

- Optional : implement it and report performance !

```
In [94]: import pandas as pd
import numpy as np
import os
from scipy.stats import multivariate_normal as MVN

your_data_path = '/Users/lorenz/Documents/ML-PW-2018/PW03/mnist/'

def load_MNIST(ROOT):
    '''load all of mnist
    training set first'''
    Xtr = []
    train = pd.read_csv(os.path.join(ROOT, 'mnist_train.csv'))
    X = np.array(train.drop('label', axis=1))
    Ytr = np.array(train['label'])
    # With this for-loop we give the data a shape of the actual image (28x28)
    # instead of the shape in file (1x784)
    for row in X:
        Xtr.append(row.reshape(28,28))
    # load test set second
    Xte = []
```



```

test = pd.read_csv(os.path.join(ROOT, 'mnist_test.csv'))
X = np.array(test.drop('label', axis=1))
Yte = np.array(test['label'])
# same reshaping
for row in X:
    Xte.append(row.reshape(28,28))

return np.array(Xtr), np.array(Ytr), np.array(Xte), np.array(Yte)

In [95]: X_train, y_train, X_test, y_test = load_MNIST(your_data_path)

In [207]: def calculate_mean_and_var(X, Y, s = 0.0001):
    labels = set(Y)
    gaussians = {}
    prior = {}
    for label in labels:
        x = X[Y == label]
        gaussians[label] = {'mean': x.mean(axis=0),
                            'var': x.var(axis=0) + s,
                            }
        prior[label] = float(len(Y[Y == key]) / len(Y))

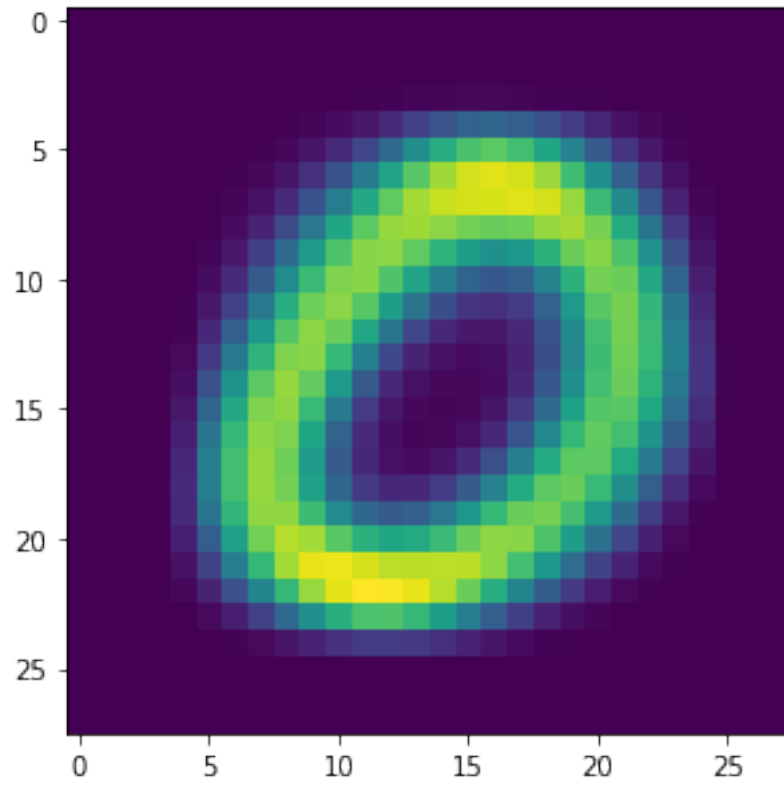
    return gaussians, prior

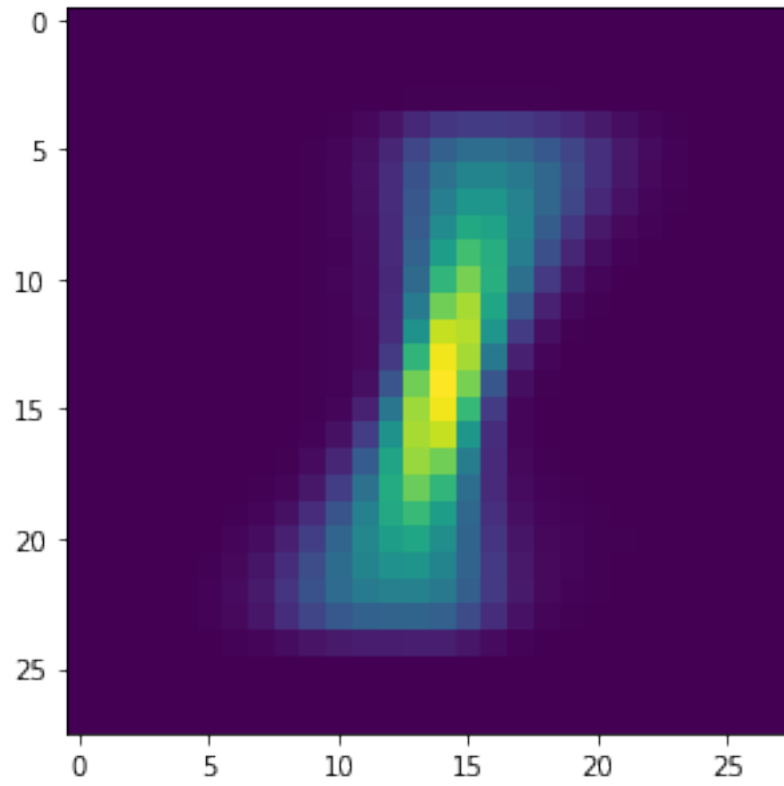
class_gaussians, count_prior = calculate_mean_and_var(X_train, y_train)

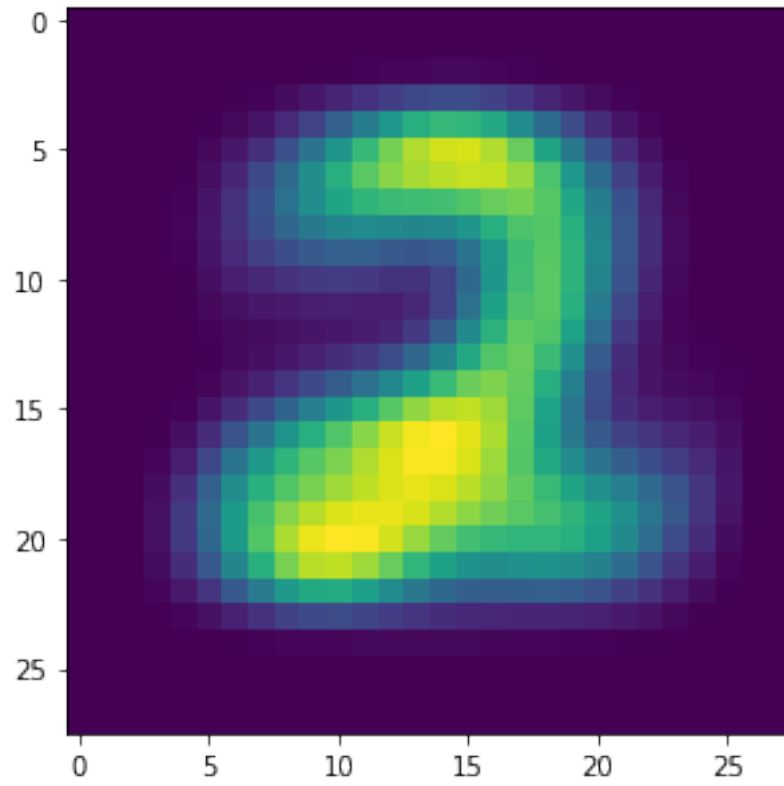
In [196]: import matplotlib.pyplot as plt
%matplotlib inline
plt.rcParams['figure.figsize'] = (5.0, 5.0)

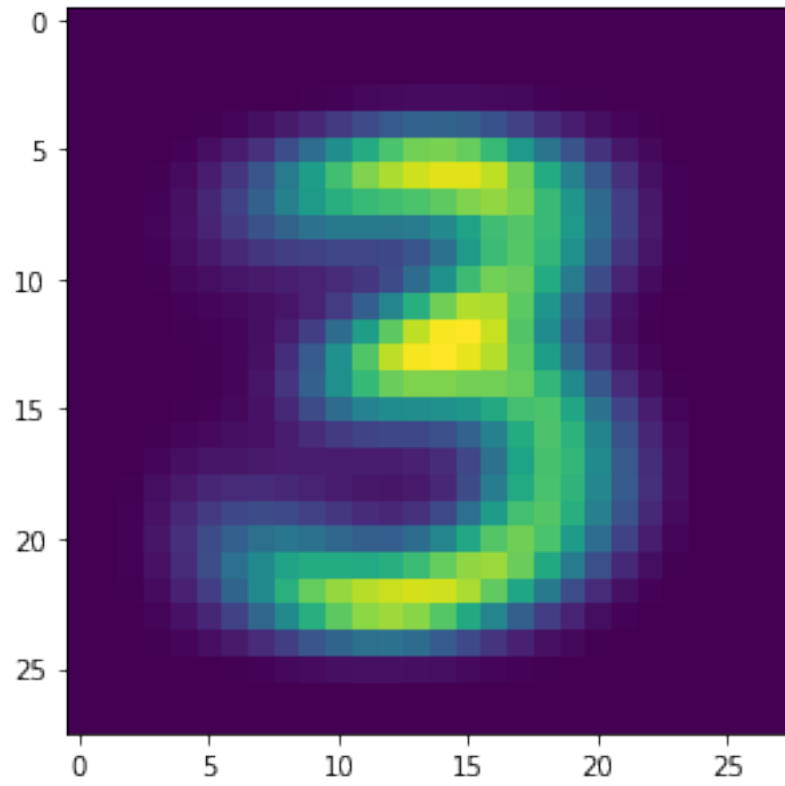
# lets have a look at what the "mean" of the numbers look like
for key in class_gaussians:
    plt.imshow(class_gaussians[key]['mean'].astype('uint8'))
    plt.show()

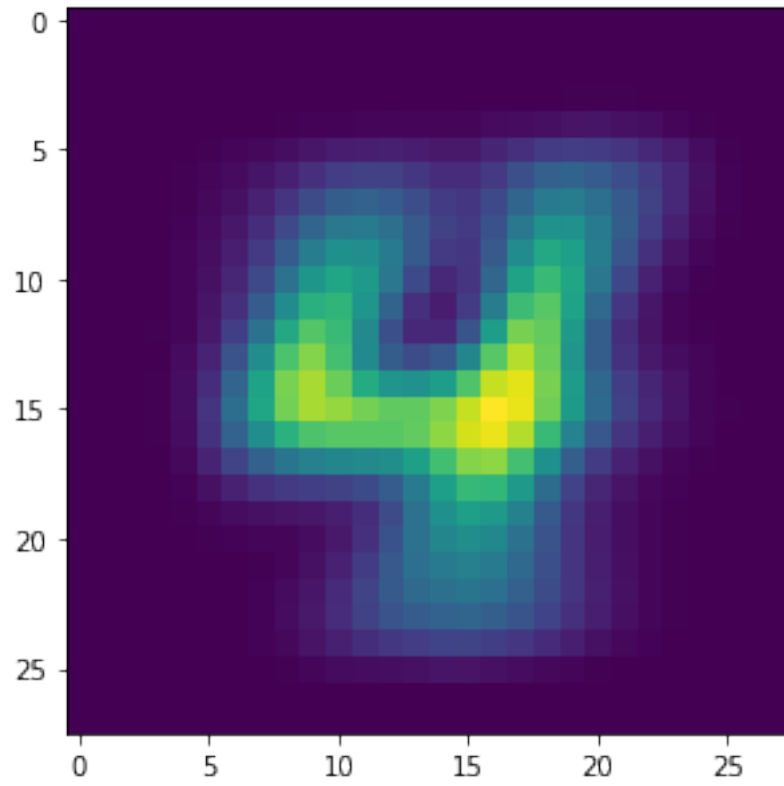
```

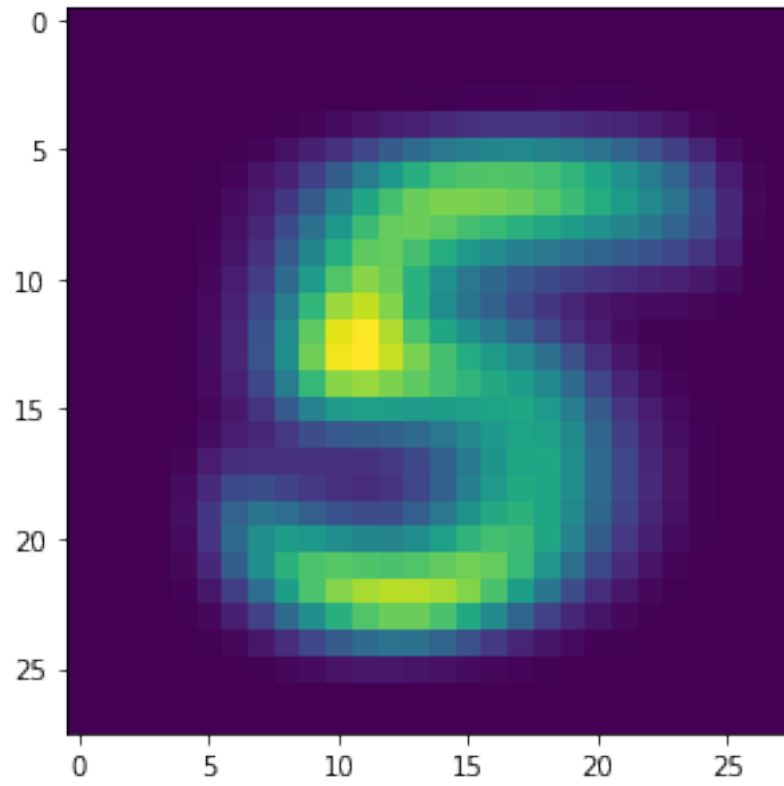


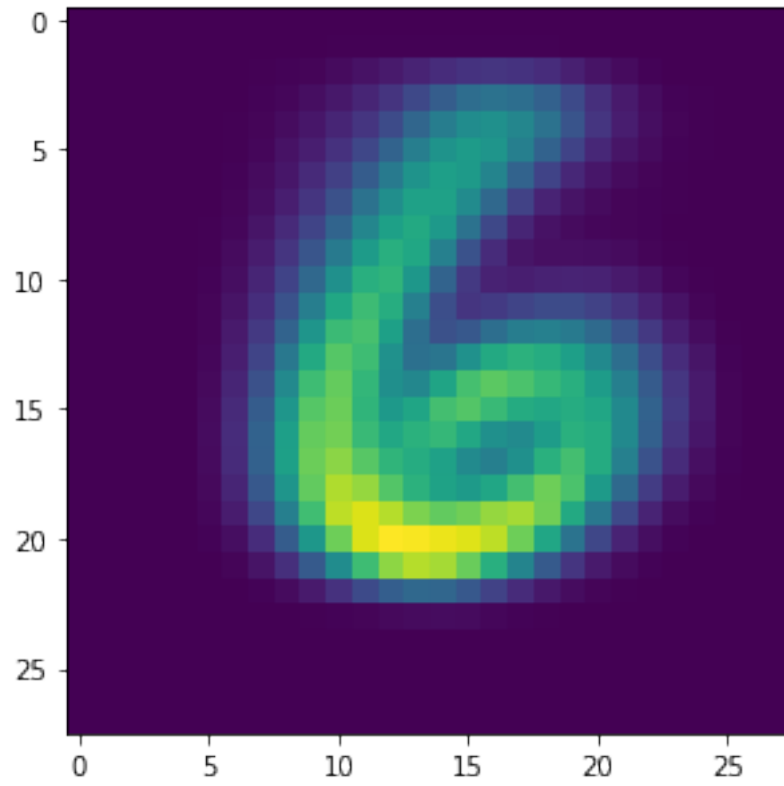


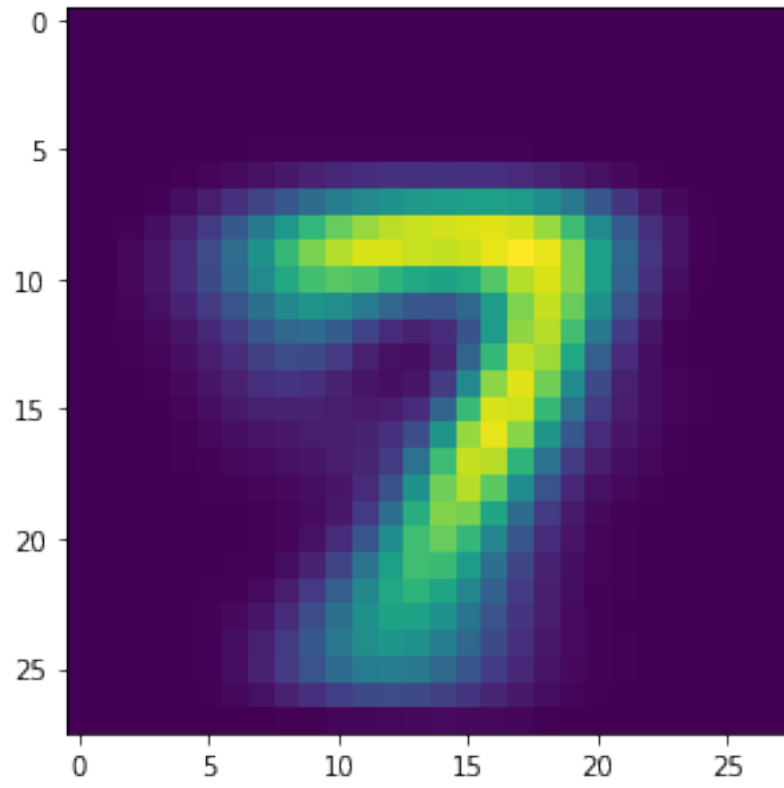


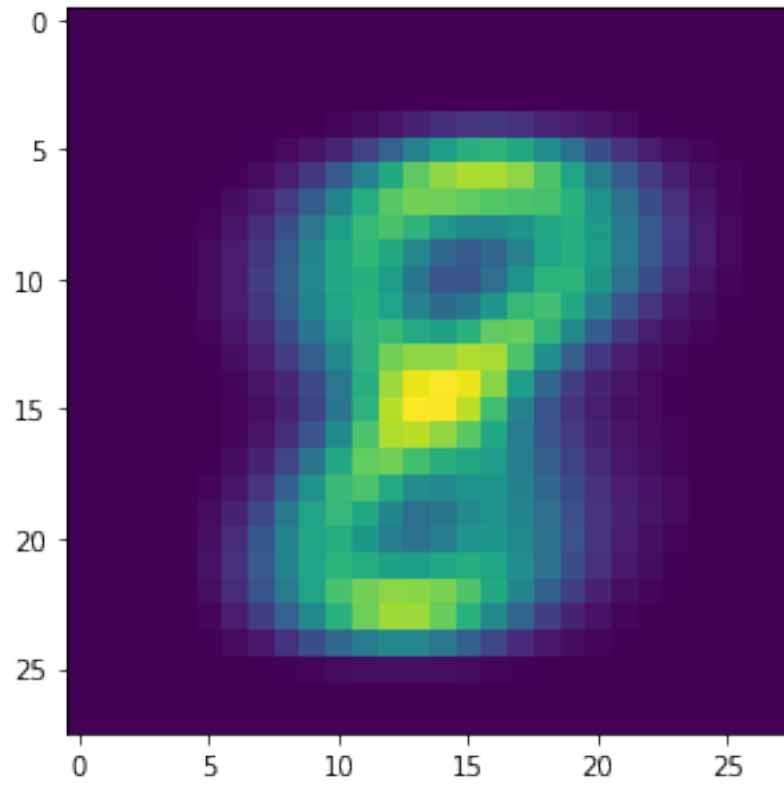


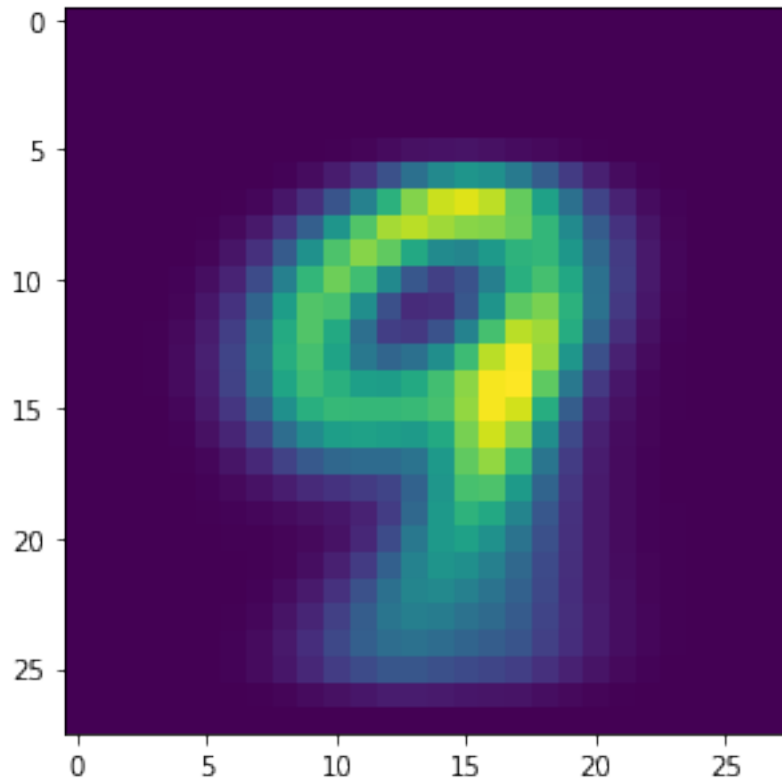












```
In [204]: def predict_class(X, gaussians, prior):
    X = np.reshape(X, (X.shape[0], -1))
    N = len(X)
    K = len(gaussians)
    predict = np.zeros((N, K))
    for key, value in gaussians.items():
        mean, var = value['mean'], value['var']
        # we flatten the "mean" and "var" for MVN
        mean = [i for x in mean for i in x]
        var = [i for x in var for i in x]
        if isinstance(prior, float):
            predict[:,key] = MVN.logpdf(X, mean, var) + prior
        else:
            predict[:,key] = MVN.logpdf(X, mean, var) + prior[key]
    return np.argmax(predict, axis=1)

In [220]: prior_mnist = 0.1
    # I assume that random numbers from 0 - 9 are equally probably
    # We learned in class, that the prior should be overcome by the data.

    test_predict = predict_class(X_test, class_gaussians, prior_mnist)
    test_score = np.mean(test_predict == y_test)
```

```
print('We get an accuracy of %s in the test set' % (test_score))
```

We get an accuracy of 0.571 in the test set

```
In [219]: #~Here I try with the prior that was counted
```

```
test_predict = predict_class(X_test, class_gaussians, count_prior)
```

```
test_score = np.mean(test_predict == y_test)
```

```
print('We get an accuracy of %s in the test set. A different prior does not help (wh
```

We get an accuracy of 0.571 in the test set. A different prior does not help (what we expect)

We can see that the classification is not very good. This can be due to a mistake in my implementation, that I can not find. Or it could mean, that the naive gaussian approach is not very good.